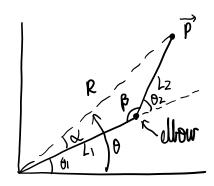
## Fourord Kinematics



$$\theta = \theta_1 + \alpha$$

$$\beta = \pi - \theta_2$$

$$R^2 = L_1^2 + L_2^2 - 2L_1L_2 \cos \beta$$

$$\frac{R}{\sin \beta} = \frac{L_2}{\sin \alpha}$$

$$\Rightarrow \cos \beta = \frac{R^2 - L_1^2 - L_2^2}{-2L_1L_2}$$

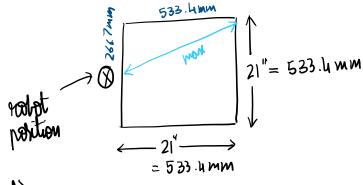
$$\lim_{X \to \infty} X = \frac{L_2 \lim_{R \to \infty} R}{R}$$

$$X = \lim_{R \to \infty} \left( \frac{L_2 \lim_{R \to \infty} R}{R} \right)$$

 $\beta = 665 \left( \frac{R^2 - L_1^2 - L_2^2}{-21112} \right)$ 

ellow = 
$$(L_1 \otimes \theta_1, L_1 \otimes \theta_1)$$
  
 $P = \text{ellow} + (L_2 \otimes (\theta_1 + \theta_2), L_2 \sin(\theta_1 + \theta_2))$   
 $\text{end} = (R_1 \otimes \theta_1)$ 

for a standard there board



$$\downarrow \qquad \qquad \downarrow_{l} = 298 \cdot 179 \text{ mm}, \qquad \downarrow_{z} = 298 \cdot 179 \text{ mm}$$

$$\Rightarrow \qquad \downarrow \qquad \qquad \downarrow_{l} = \downarrow_{l} + \downarrow_{z} = \downarrow_{l} \text{ man}$$

$$\Rightarrow \qquad \downarrow \qquad \qquad \downarrow_{l} = \downarrow_{l} \qquad \downarrow_{l} = \downarrow_{l} \otimes \downarrow_{$$

For my fusion model I had started with dimensions  $L_1 = 153 \text{ mm}$   $L_2 = 148 \text{ mm}$ from the model, when  $\theta_1 = 78.7^{\circ}$  and  $\theta_2 = 104.6^{\circ}$   $\Rightarrow R = 184 \text{ mm}$ on calculating of and  $\beta$ ,  $\beta = \alpha \delta^{-1} \left( \frac{184^2 - 153^2 - 14\delta^2}{-2(153)(148)} \right) = \alpha \delta^{-1} (0.2530) = 75.35^{\circ}$   $\alpha = \sin^{-1} \left( \frac{(148)(0.4675)}{(84)} \right) = \sin^{-1} (0.7782) = 51.10^{\circ}$ 

from the model,  $X = 50.97^{\circ}$ 

B= 76.384°