

HumanActivityRecognition

This project is to build a model that predicts the human activities such as Walking, Walking_Upstairs, Walking_Downstairs, Sitting, Standing or Laying.

This dataset is collected from 30 persons(referred as subjects in this dataset), performing different activities with a smartphone to their waists. The data is recorded with the help of sensors (accelerometer and Gyroscope) in that smartphone. This experiment was video recorded to label the data manually.

How data was recorded

By using the sensors(Gyroscope and accelerometer) in a smartphone, they have captured '3-axial linear acceleration'($tAcc-XYZ$) from accelerometer and '3-axial angular velocity' ($tGyro-XYZ$) from Gyroscope with several variations.

prefix 't' in those metrics denotes time.

suffix 'XYZ' represents 3-axial signals in X , Y, and Z directions.

Feature names

1. These sensor signals are preprocessed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.
2. From Each window, a feature vector was obtained by calculating variables from the time and frequency domain.

In our dataset, each datapoint represents a window with different readings

3. The acceleration signal was separated into Body and Gravity acceleration signals(***tBodyAcc-XYZ*** and ***tGravityAcc-XYZ***) using some low pass filter with corner frequency of 0.3Hz.
4. After that, the body linear acceleration and angular velocity were derived in time to obtain *jerk signals* (***tBodyAccJerk-XYZ*** and ***tBodyGyroJerk-XYZ***).
5. The magnitude of these 3-dimensional signals were calculated using the Euclidian norm. These magnitudes are represented as features with names like ***tBodyAccMag***, ***tGravityAccMag***, ***tBodyAccJerkMag***, ***tBodyGyroMag*** and ***tBodyGyroJerkMag***.
6. Finally, We've got frequency domain signals from some of the available signals by applying a FFT (Fast Fourier Transform). These signals obtained were labeled with **prefix 'f'** just like original signals with **prefix 't'**. These signals are labeled as ***fBodyAcc-XYZ***, ***fBodyGyroMag*** etc.,.
7. These are the signals that we got so far.
 - tBodyAcc-XYZ
 - tGravityAcc-XYZ
 - tBodyAccJerk-XYZ
 - tBodyGyro-XYZ
 - tBodyGyroJerk-XYZ
 - tBodyAccMag
 - tGravityAccMag
 - tBodyAccJerkMag
 - tBodyGyroMag
 - tBodyGyroJerkMag
 - fBodyAcc-XYZ
 - fBodyAccJerk-XYZ
 - fBodyGyro-XYZ
 - fBodyAccMag
 - fBodyAccJerkMag
 - fBodyGyroMag

- fBodyGyroJerkMag
8. We can estimate some set of variables from the above signals. ie., We will estimate the following properties on each and every signal that we recorded so far.
- **mean()**: Mean value
 - **std()**: Standard deviation
 - **mad()**: Median absolute deviation
 - **max()**: Largest value in array
 - **min()**: Smallest value in array
 - **sma()**: Signal magnitude area
 - **energy()**: Energy measure. Sum of the squares divided by the number of values.
 - **iqr()**: Interquartile range
 - **entropy()**: Signal entropy
 - **arCoeff()**: Autorregresion coefficients with Burg order equal to 4
 - **correlation()**: correlation coefficient between two signals
 - **maxInds()**: index of the frequency component with largest magnitude
 - **meanFreq()**: Weighted average of the frequency components to obtain a mean frequency
 - **skewness()**: skewness of the frequency domain signal
 - **kurtosis()**: kurtosis of the frequency domain signal
 - **bandsEnergy()**: Energy of a frequency interval within the 64 bins of the FFT of each window.
 - **angle()**: Angle between to vectors.
9. We can obtain some other vectors by taking the average of signals in a single window sample. These are used on the angle() variable`
- gravityMean
 - tBodyAccMean
 - tBodyAccJerkMean
 - tBodyGyroMean
 - tBodyGyroJerkMean

Y_Labels(Encoded)

- In the dataset, Y_labels are represented as numbers from 1 to 6 as their identifiers.
 - WALKING as **1**
 - WALKING_UPSTAIRS as **2**
 - WALKING_DOWNSTAIRS as **3**
 - SITTING as **4**
 - STANDING as **5**
 - LAYING as **6**

Train and test data were saperated

- The readings from **70%** of the volunteers were taken as **trianing data** and remaining **30%** subjects recordings were taken for **test data**

Data

- All the data is present in 'UCI_HAR_dataset/' folder in present working directory.
 - Feature names are present in 'UCI_HAR_dataset/features.txt'
 - **Train Data**
 - 'UCI_HAR_dataset/train/X_train.txt'
 - 'UCI_HAR_dataset/train/subject_train.txt'
 - 'UCI_HAR_dataset/train/y_train.txt'
 - **Test Data**
 - 'UCI_HAR_dataset/test/X_test.txt'
 - 'UCI_HAR_dataset/test/subject_test.txt'
 - 'UCI_HAR_dataset/test/y_test.txt'

Data Size :

27 MB

Quick overview of the dataset :

- Accelerometer and Gyroscope readings are taken from 30 volunteers(referred as subjects) while performing the following 6 Activities.
 1. Walking
 2. WalkingUpstairs
 3. WalkingDownstairs
 4. Standing
 5. Sitting
 6. Lying.
- Readings are divided into a window of 2.56 seconds with 50% overlapping.
- Accelerometer readings are divided into gravity acceleration and body acceleration readings, which has x,y and z components each.
- Gyroscope readings are the measure of angular velocities which has x,y and z components.
- Jerk signals are calculated for BodyAcceleration readings.
- Fourier Transforms are made on the above time readings to obtain frequency readings.
- Now, on all the base signal readings., mean, max, mad, sma, arcoefficient, engerybands,entropy etc., are calculated for each window.
- We get a feature vector of 561 features and these features are given in the dataset.
- Each window of readings is a datapoint of 561 features.

Problem Framework

- 30 subjects(volunteers) data is randomly split to 70%(21) test and 30%(7) train data.
- Each datapoint corresponds one of the 6 Activities.

Problem Statement

- Given a new datapoint we have to predict the Activity

```
In [0]: import numpy as np
import pandas as pd

# get the features from the file features.txt
features = list()
with open('UCI_HAR_Dataset/features.txt') as f:
    features = [line.split()[1] for line in f.readlines()]
print('No of Features: {}'.format(len(features)))
```

Obtain the train data

```
In [0]: # get the data from txt files to pandas dataframe
X_train = pd.read_csv('UCI_HAR_dataset/train/X_train.txt', delim_whitespace=True, header=None, names=features)

# add subject column to the dataframe
X_train['subject'] = pd.read_csv('UCI_HAR_dataset/train/subject_train.txt', header=None, squeeze=True)

y_train = pd.read_csv('UCI_HAR_dataset/train/y_train.txt', names=['Activity'], squeeze=True)
y_train_labels = y_train.map({1: 'WALKING', 2: 'WALKING_UPSTAIRS', 3: 'WALKING_DOWNSTAIRS',
                                4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})

# put all columns in a single dataframe
train = X_train
train['Activity'] = y_train
train['ActivityName'] = y_train_labels
train.sample()
```

```
In [0]: train.shape
```

```
Out[0]: (7352, 564)
```

Obtain the test data

```
In [0]: # get the data from txt files to pandas dataframe
X_test = pd.read_csv('UCI_HAR_dataset/test/X_test.txt', delim_whitespace=True, header=None, names=features)

# add subject column to the dataframe
X_test['subject'] = pd.read_csv('UCI_HAR_dataset/test/subject_test.txt', header=None, squeeze=True)

# get y labels from the txt file
y_test = pd.read_csv('UCI_HAR_dataset/test/y_test.txt', names=['Activity'], squeeze=True)
y_test_labels = y_test.map({1: 'WALKING', 2: 'WALKING_UPSTAIRS', 3: 'WALKING_DOWNSTAIRS', \
                             4: 'SITTING', 5: 'STANDING', 6: 'LAYING'})

# put all columns in a single dataframe
test = X_test
test['Activity'] = y_test
test['ActivityName'] = y_test_labels
test.sample()
```

```
D:\installed\Anaconda3\lib\site-packages\pandas\io\parsers.py:678: UserWarning: Duplicate names specified. This will raise an error in the future.
    return _read(filepath_or_buffer, kwds)
```

Out[0]:

	tBodyAcc-mean()-X	tBodyAcc-mean()-Y	tBodyAcc-mean()-Z	tBodyAcc-std()-X	tBodyAcc-std()-Y	tBodyAcc-std()-Z	tBodyAcc-mad()-X
2261	0.279196	-0.018261	-0.103376	-0.996955	-0.982959	-0.988239	-0.9972

1 rows × 564 columns

```
In [0]: test.shape
```

```
Out[0]: (2947, 564)
```

Data Cleaning

1. Check for Duplicates

```
In [0]: print('No of duplicates in train: {}'.format(sum(train.duplicated())))  
        print('No of duplicates in test : {}'.format(sum(test.duplicated())))
```

```
No of duplicates in train: 0  
No of duplicates in test : 0
```

2. Checking for NaN/null values

```
In [0]: print('We have {} NaN/Null values in train'.format(train.isnull().values.  
        s.sum()))  
        print('We have {} NaN/Null values in test'.format(test.isnull().values.  
        sum()))
```

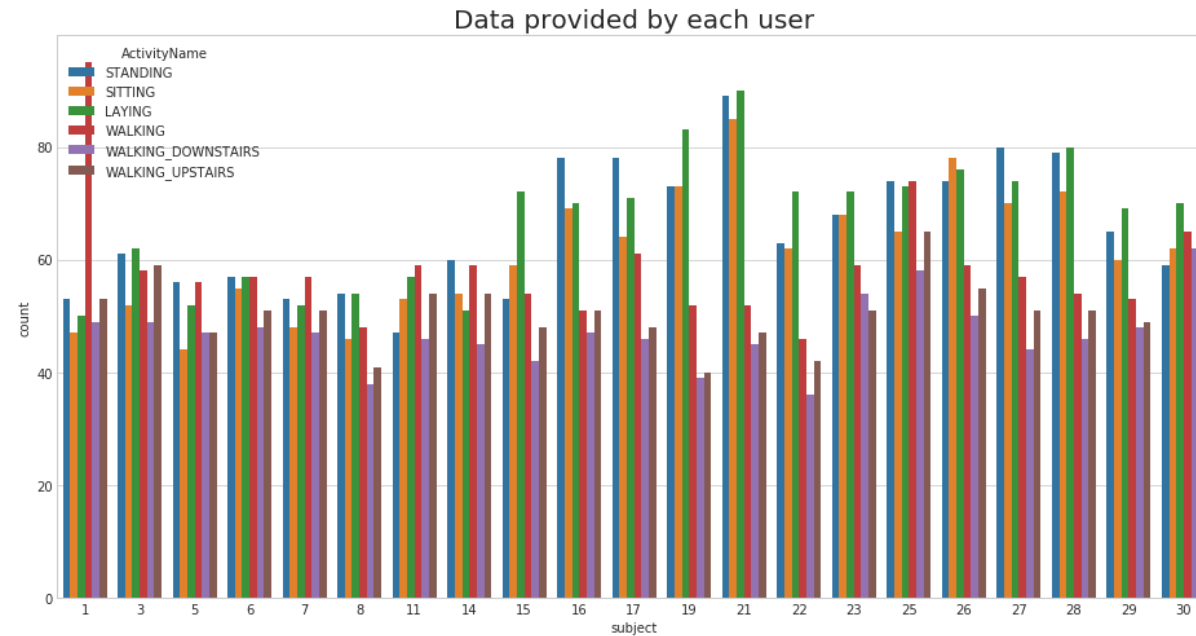
3. Check for data imbalance

```
In [0]: import matplotlib.pyplot as plt  
        import seaborn as sns
```



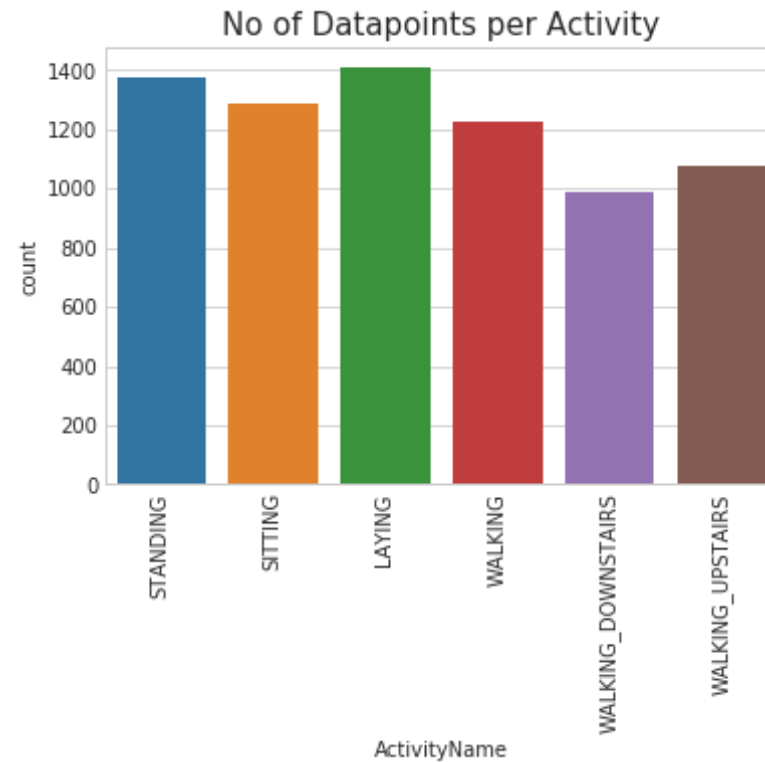
```
sns.set_style('whitegrid')
plt.rcParams['font.family'] = 'Dejavu Sans'
```

```
In [0]: plt.figure(figsize=(16,8))
plt.title('Data provided by each user', fontsize=20)
sns.countplot(x='subject',hue='ActivityName', data = train)
plt.show()
```



We have got almost same number of reading from all the subjects

```
In [0]: plt.title('No of Datapoints per Activity', fontsize=15)
sns.countplot(train.ActivityName)
plt.xticks(rotation=90)
plt.show()
```



Observation

Our data is well balanced (almost)

4. Changing feature names

```
In [0]: columns = train.columns

# Removing '()' from column names
columns = columns.str.replace('[()]', '')
```

```
columns = columns.str.replace('[-]', '')
columns = columns.str.replace('[,]', '')

train.columns = columns
test.columns = columns

test.columns
```

```
Out[0]: Index(['tBodyAccmeanX', 'tBodyAccmeanY', 'tBodyAccmeanZ', 'tBodyAccstdX',
              'tBodyAccstdY', 'tBodyAccstdZ', 'tBodyAccmadX', 'tBodyAccmadY',
              'tBodyAccmadZ', 'tBodyAccmaxX',
              ...
              'angletBodyAccMeangravity', 'angletBodyAccJerkMeangravityMean',
              'angletBodyGyroMeangravityMean', 'angletBodyGyroJerkMeangravityM
              ean',
              'angleXgravityMean', 'angleYgravityMean', 'angleZgravityMean',
              'subject', 'Activity', 'ActivityName'],
              dtype='object', length=564)
```

5. Save this dataframe in a csv files

```
In [0]: train.to_csv('UCI_HAR_Dataset/csv_files/train.csv', index=False)
        test.to_csv('UCI_HAR_Dataset/csv_files/test.csv', index=False)
```

Exploratory Data Analysis

"Without domain knowledge EDA has no meaning, without EDA a problem has no soul."

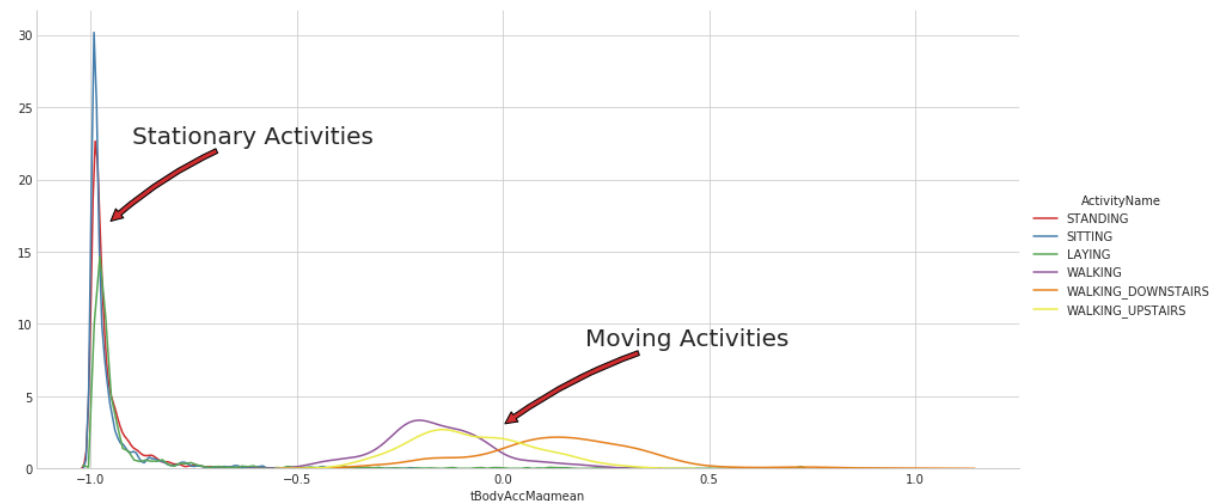
1. Featuring Engineering from Domain Knowledge

- Static and Dynamic Activities

- In static activities (sit, stand, lie down) motion information will not be very useful.
- In the dynamic activities (Walking, WalkingUpstairs, WalkingDownstairs) motion info will be significant.

2. Stationary and Moving activities are completely different

```
In [0]: sns.set_palette("Set1", desat=0.80)
facetgrid = sns.FacetGrid(train, hue='ActivityName', size=6, aspect=2)
facetgrid.map(sns.distplot, 'tBodyAccMagmean', hist=False)\
    .add_legend()
plt.annotate("Stationary Activities", xy=(-0.956,17), xytext=(-0.9, 23),
    size=20,\
        va='center', ha='left',\
        arrowprops=dict(arrowstyle="simple",connectionstyle="arc3,r
ad=0.1"))
plt.annotate("Moving Activities", xy=(0,3), xytext=(0.2, 9), size=20,\
        va='center', ha='left',\
        arrowprops=dict(arrowstyle="simple",connectionstyle="arc3,r
ad=0.1"))
plt.show()
```



```

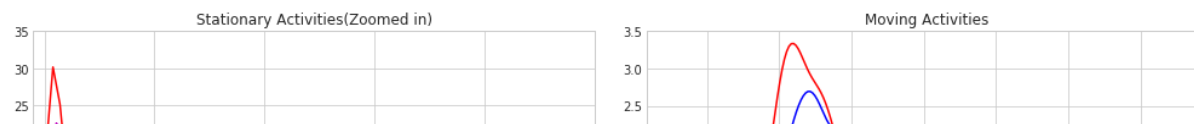
In [0]: # for plotting purposes taking datapoints of each activity to a different dataframe
df1 = train[train['Activity']==1]
df2 = train[train['Activity']==2]
df3 = train[train['Activity']==3]
df4 = train[train['Activity']==4]
df5 = train[train['Activity']==5]
df6 = train[train['Activity']==6]

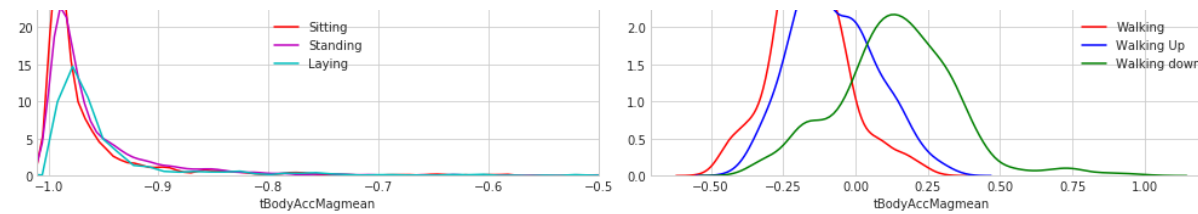
plt.figure(figsize=(14,7))
plt.subplot(2,2,1)
plt.title('Stationary Activities(Zoomed in)')
sns.distplot(df4['tBodyAccMagmean'],color = 'r',hist = False, label = 'Sitting')
sns.distplot(df5['tBodyAccMagmean'],color = 'm',hist = False,label = 'Standing')
sns.distplot(df6['tBodyAccMagmean'],color = 'c',hist = False, label = 'Laying')
plt.axis([-1.01, -0.5, 0, 35])
plt.legend(loc='center')

plt.subplot(2,2,2)
plt.title('Moving Activities')
sns.distplot(df1['tBodyAccMagmean'],color = 'red',hist = False, label = 'Walking')
sns.distplot(df2['tBodyAccMagmean'],color = 'blue',hist = False,label = 'Walking Up')
sns.distplot(df3['tBodyAccMagmean'],color = 'green',hist = False, label = 'Walking down')
plt.legend(loc='center right')

plt.tight_layout()
plt.show()

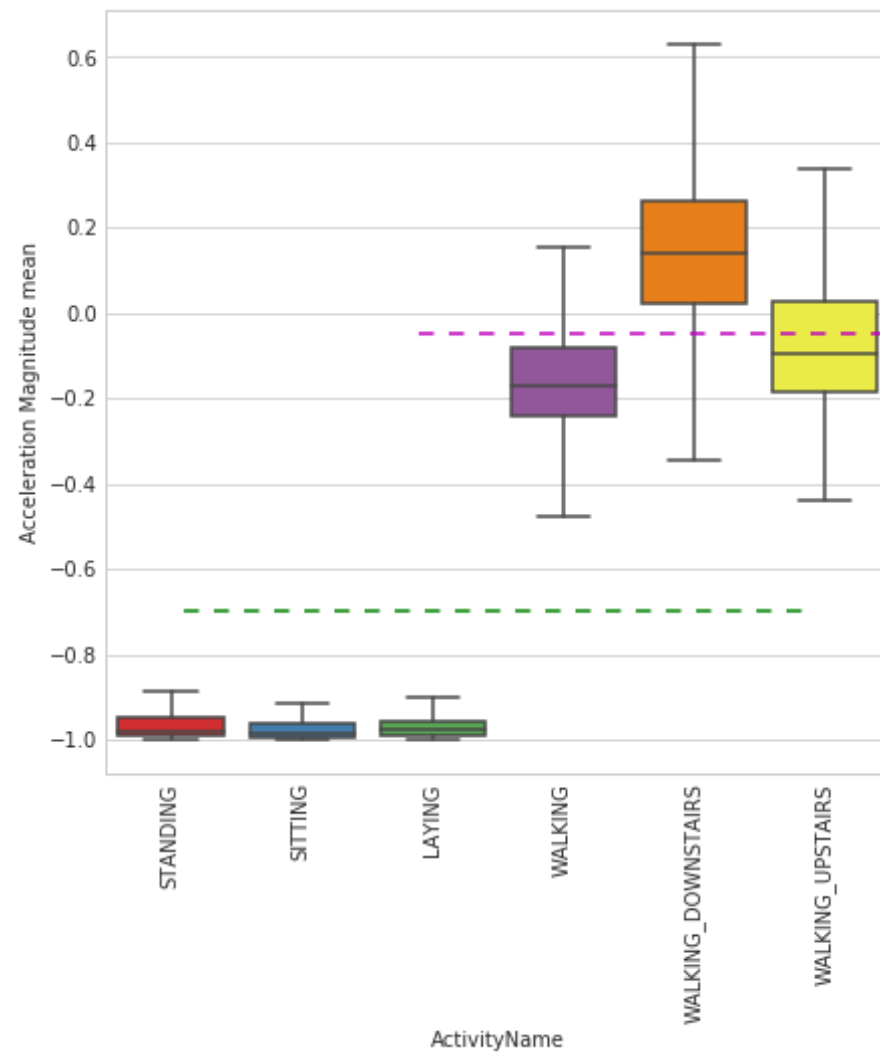
```





3. Magnitude of an acceleration can saperate it well

```
In [0]: plt.figure(figsize=(7,7))
sns.boxplot(x='ActivityName', y='tBodyAccMagmean', data=train, showfliers=False, saturation=1)
plt.ylabel('Acceleration Magnitude mean')
plt.axhline(y=-0.7, xmin=0.1, xmax=0.9, dashes=(5,5), c='g')
plt.axhline(y=-0.05, xmin=0.4, dashes=(5,5), c='m')
plt.xticks(rotation=90)
plt.show()
```



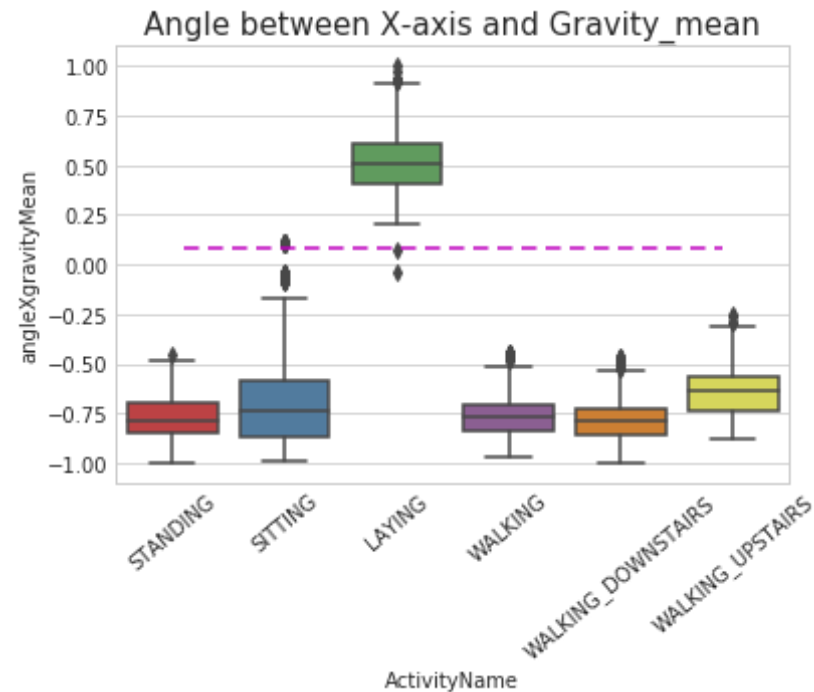
Observations:

- If tAccMean is < -0.8 then the Activities are either Standing or Sitting or Laying.
- If tAccMean is > -0.6 then the Activities are either Walking or WalkingDownstairs or WalkingUpstairs.
- If tAccMean > 0.0 then the Activity is WalkingDownstairs.

- We can classify 75% the Activity labels with some errors.

4. Position of GravityAccelerationComponents also matters

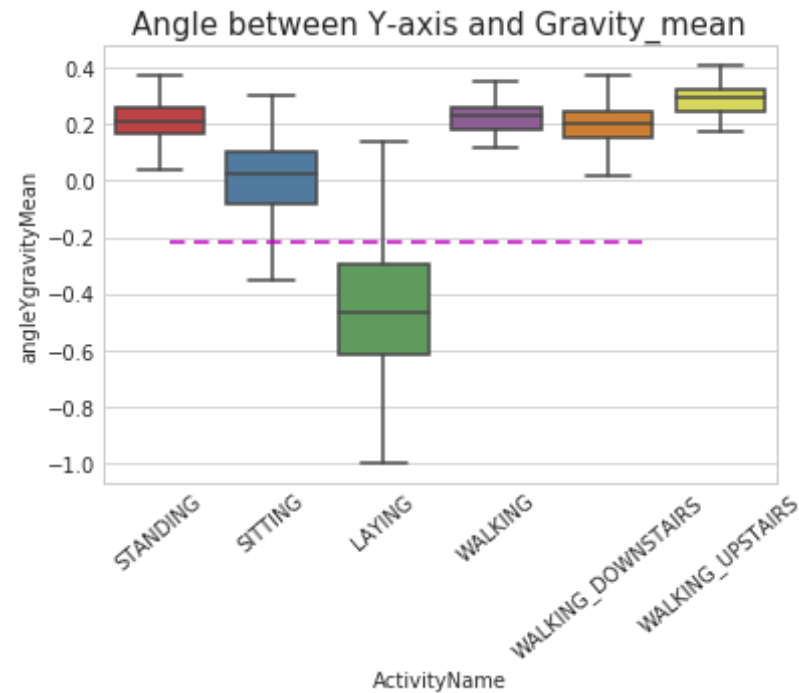
```
In [0]: sns.boxplot(x='ActivityName', y='angleXgravityMean', data=train)
plt.axhline(y=0.08, xmin=0.1, xmax=0.9, c='m', dashes=(5,3))
plt.title('Angle between X-axis and Gravity_mean', fontsize=15)
plt.xticks(rotation = 40)
plt.show()
```



Observations:

- If $\text{angleXgravityMean} > 0$ then Activity is Laying.
- We can classify all datapoints belonging to Laying activity with just a single if else statement.


```
In [0]: sns.boxplot(x='ActivityName', y='angleYgravityMean', data = train, show
fliers=False)
plt.title('Angle between Y-axis and Gravity_mean', fontsize=15)
plt.xticks(rotation = 40)
plt.axhline(y=-0.22, xmin=0.1, xmax=0.8, dashes=(5,3), c='m')
plt.show()
```



Apply t-sne on the data

```
In [0]: import numpy as np
from sklearn.manifold import TSNE
import matplotlib.pyplot as plt
import seaborn as sns
```

```

In [0]: # performs t-sne with different perplexity values and their respective plots..

def perform_tsne(X_data, y_data, perplexities, n_iter=1000, img_name_prefix='t-sne'):

    for index,perplexity in enumerate(perplexities):
        # perform t-sne
        print('\nperforming tsne with perplexity {} and with {} iterations at max'.format(perplexity, n_iter))
        X_reduced = TSNE(verbose=2, perplexity=perplexity).fit_transform(X_data)
        print('Done..')

        # prepare the data for seaborn
        print('Creating plot for this t-sne visualization..')
        df = pd.DataFrame({'x':X_reduced[:,0], 'y':X_reduced[:,1], 'label':y_data})

        # draw the plot in appropriate place in the grid
        sns.lmplot(data=df, x='x', y='y', hue='label', fit_reg=False, size=8,\
                    palette="Set1",markers=['^','v','s','o', '1','2'])
        plt.title("perplexity : {} and max_iter : {}".format(perplexity, n_iter))
        img_name = img_name_prefix + '_perp_{}_iter_{}.png'.format(perplexity, n_iter)
        print('saving this plot as image in present working directory...')
        plt.savefig(img_name)
        plt.show()
        print('Done')

```

```

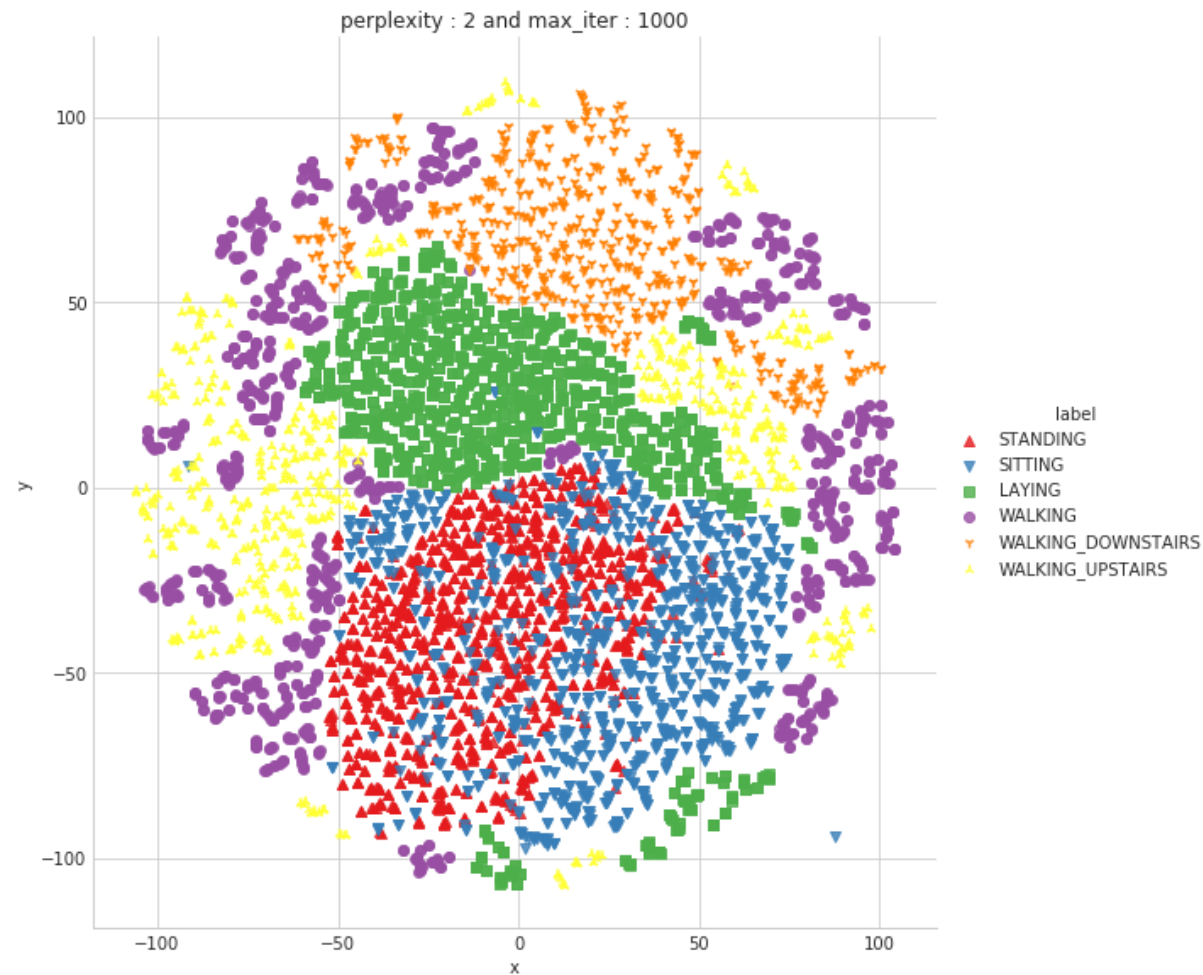
In [0]: X_pre_tsne = train.drop(['subject', 'Activity','ActivityName'], axis=1)
y_pre_tsne = train['ActivityName']
perform_tsne(X_data = X_pre_tsne,y_data=y_pre_tsne, perplexities =[2,5,10,20,50])

```

performing tsne with perplexity 2 and with 1000 iterations at max

```
[t-SNE] Computing 7 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.426s...
[t-SNE] Computed neighbors for 7352 samples in 72.001s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.635855
[t-SNE] Computed conditional probabilities in 0.071s
[t-SNE] Iteration 50: error = 124.8017578, gradient norm = 0.0253939 (50 iterations in 16.625s)
[t-SNE] Iteration 100: error = 107.2019501, gradient norm = 0.0284782 (50 iterations in 9.735s)
[t-SNE] Iteration 150: error = 100.9872894, gradient norm = 0.0185151 (50 iterations in 5.346s)
[t-SNE] Iteration 200: error = 97.6054382, gradient norm = 0.0142084 (50 iterations in 7.013s)
[t-SNE] Iteration 250: error = 95.3084183, gradient norm = 0.0132592 (50 iterations in 5.703s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 95.308418
[t-SNE] Iteration 300: error = 4.1209540, gradient norm = 0.0015668 (50 iterations in 7.156s)
[t-SNE] Iteration 350: error = 3.2113254, gradient norm = 0.0009953 (50 iterations in 8.022s)
[t-SNE] Iteration 400: error = 2.7819963, gradient norm = 0.0007203 (50 iterations in 9.419s)
[t-SNE] Iteration 450: error = 2.5178111, gradient norm = 0.0005655 (50 iterations in 9.370s)
[t-SNE] Iteration 500: error = 2.3341548, gradient norm = 0.0004804 (50 iterations in 7.681s)
[t-SNE] Iteration 550: error = 2.1961622, gradient norm = 0.0004183 (50 iterations in 7.097s)
[t-SNE] Iteration 600: error = 2.0867445, gradient norm = 0.0003664 (50 iterations in 9.274s)
```

```
[t-SNE] Iteration 650: error = 1.9967778, gradient norm = 0.0003279 (50
iterations in 7.697s)
[t-SNE] Iteration 700: error = 1.9210005, gradient norm = 0.0002984 (50
iterations in 8.174s)
[t-SNE] Iteration 750: error = 1.8558111, gradient norm = 0.0002776 (50
iterations in 9.747s)
[t-SNE] Iteration 800: error = 1.7989457, gradient norm = 0.0002569 (50
iterations in 8.687s)
[t-SNE] Iteration 850: error = 1.7490212, gradient norm = 0.0002394 (50
iterations in 8.407s)
[t-SNE] Iteration 900: error = 1.7043383, gradient norm = 0.0002224 (50
iterations in 8.351s)
[t-SNE] Iteration 950: error = 1.6641431, gradient norm = 0.0002098 (50
iterations in 7.841s)
[t-SNE] Iteration 1000: error = 1.6279151, gradient norm = 0.0001989 (5
0 iterations in 5.623s)
[t-SNE] Error after 1000 iterations: 1.627915
Done..
Creating plot for this t-sne visualization..
saving this plot as image in present working directory...
```

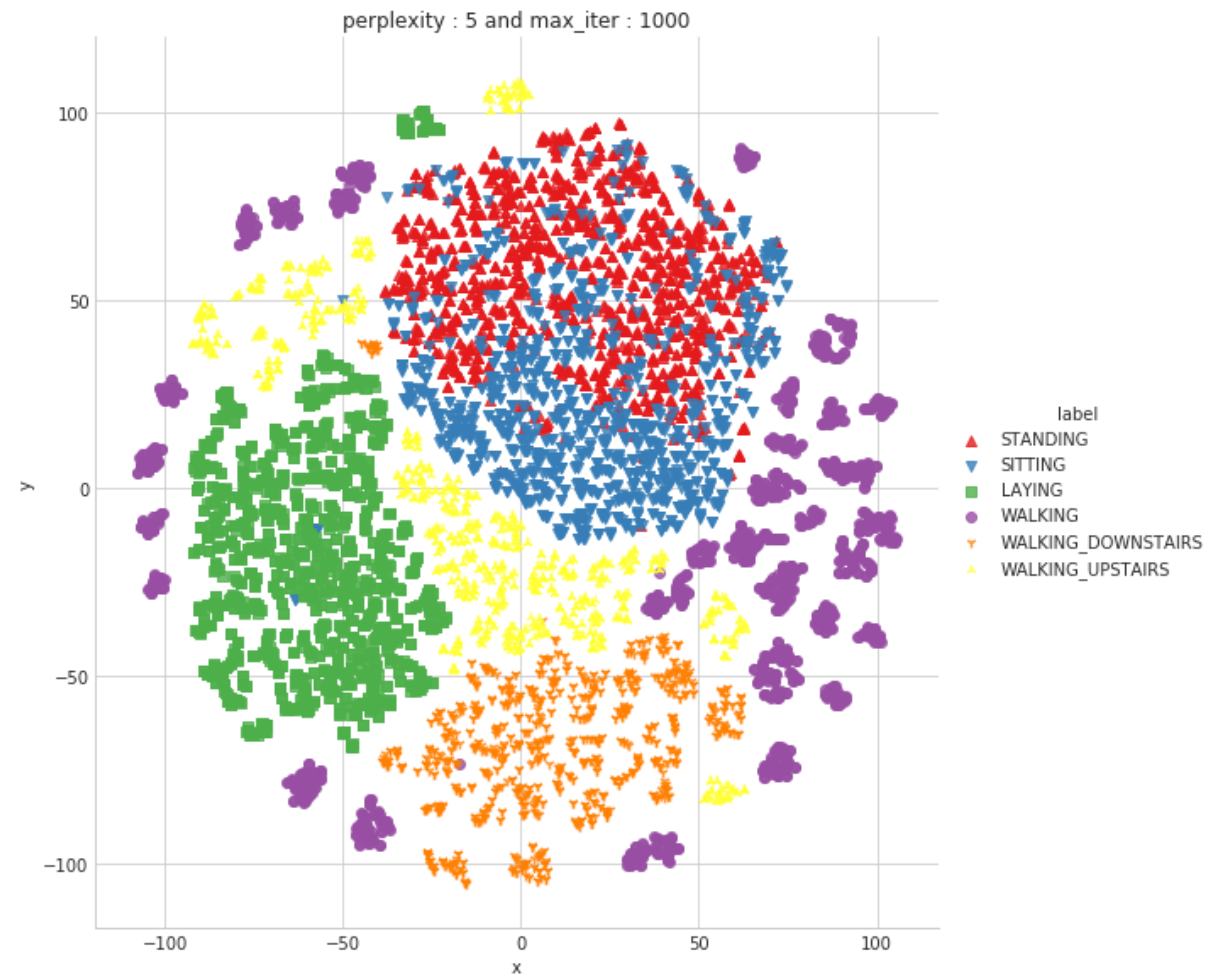


Done

```
performing tsne with perplexity 5 and with 1000 iterations at max
[t-SNE] Computing 16 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.263s...
[t-SNE] Computed neighbors for 7352 samples in 48.983s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
```

```
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 0.961265
[t-SNE] Computed conditional probabilities in 0.122s
[t-SNE] Iteration 50: error = 114.1862640, gradient norm = 0.0184120 (50 iterations in 55.655s)
[t-SNE] Iteration 100: error = 97.6535568, gradient norm = 0.0174309 (50 iterations in 12.580s)
[t-SNE] Iteration 150: error = 93.1900101, gradient norm = 0.0101048 (50 iterations in 9.180s)
[t-SNE] Iteration 200: error = 91.2315445, gradient norm = 0.0074560 (50 iterations in 10.340s)
[t-SNE] Iteration 250: error = 90.0714417, gradient norm = 0.0057667 (50 iterations in 9.458s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 90.071442
[t-SNE] Iteration 300: error = 3.5796804, gradient norm = 0.0014691 (50 iterations in 8.718s)
[t-SNE] Iteration 350: error = 2.8173938, gradient norm = 0.0007508 (50 iterations in 10.180s)
[t-SNE] Iteration 400: error = 2.4344938, gradient norm = 0.0005251 (50 iterations in 10.506s)
[t-SNE] Iteration 450: error = 2.2156141, gradient norm = 0.0004069 (50 iterations in 10.072s)
[t-SNE] Iteration 500: error = 2.0703306, gradient norm = 0.0003340 (50 iterations in 10.511s)
[t-SNE] Iteration 550: error = 1.9646366, gradient norm = 0.0002816 (50 iterations in 9.792s)
[t-SNE] Iteration 600: error = 1.8835558, gradient norm = 0.0002471 (50 iterations in 9.098s)
[t-SNE] Iteration 650: error = 1.8184001, gradient norm = 0.0002184 (50 iterations in 8.656s)
[t-SNE] Iteration 700: error = 1.7647167, gradient norm = 0.0001961 (50 iterations in 9.063s)
[t-SNE] Iteration 750: error = 1.7193680, gradient norm = 0.0001796 (50 iterations in 9.754s)
```

```
[t-SNE] Iteration 800: error = 1.6803776, gradient norm = 0.0001655 (50
iterations in 9.540s)
[t-SNE] Iteration 850: error = 1.6465144, gradient norm = 0.0001538 (50
iterations in 9.953s)
[t-SNE] Iteration 900: error = 1.6166563, gradient norm = 0.0001421 (50
iterations in 10.270s)
[t-SNE] Iteration 950: error = 1.5901035, gradient norm = 0.0001335 (50
iterations in 6.609s)
[t-SNE] Iteration 1000: error = 1.5664237, gradient norm = 0.0001257 (5
0 iterations in 8.553s)
[t-SNE] Error after 1000 iterations: 1.566424
Done..
Creating plot for this t-sne visualization..
saving this plot as image in present working directory...
```



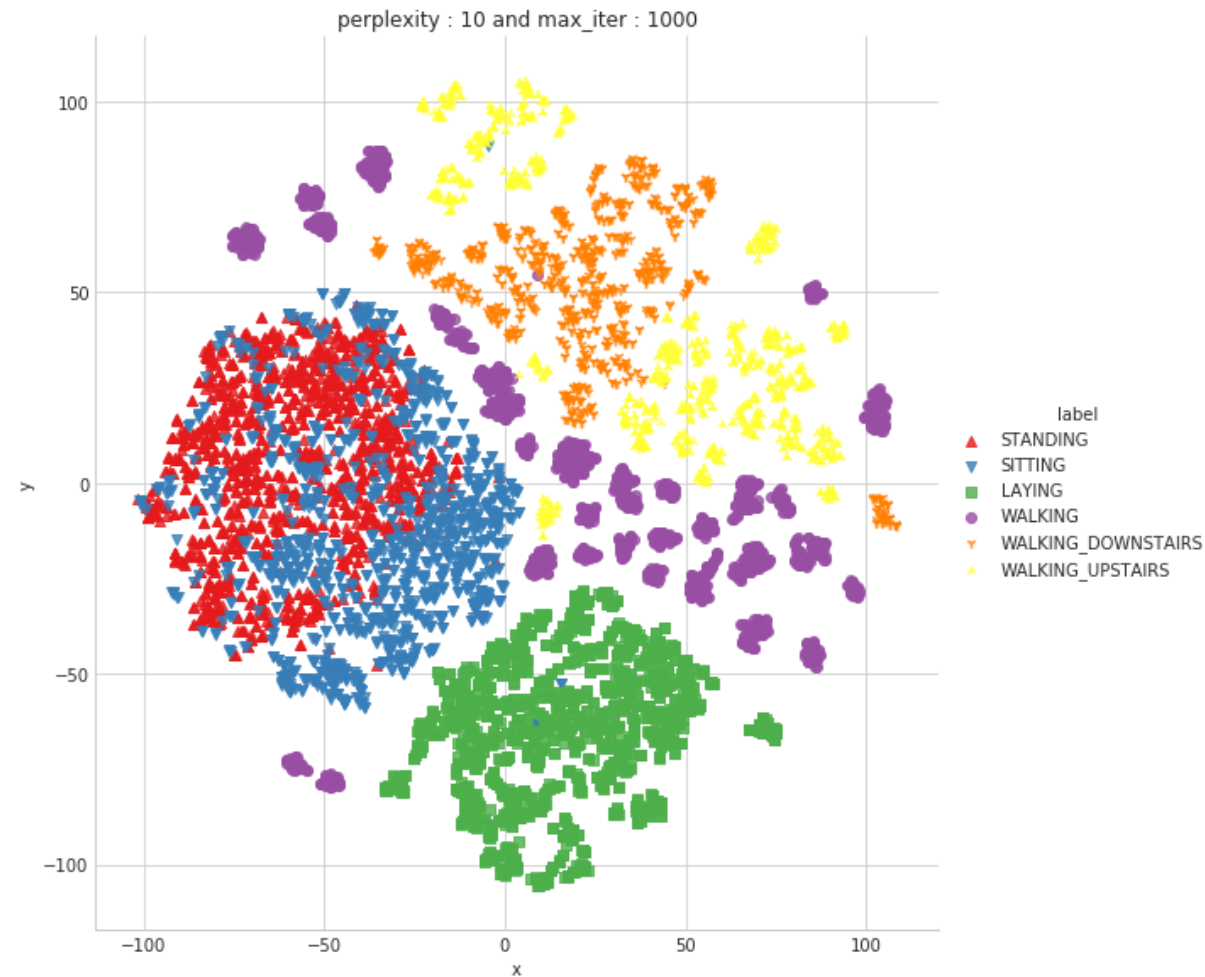
Done

```
performing tsne with perplexity 10 and with 1000 iterations at max
[t-SNE] Computing 31 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.410s...
[t-SNE] Computed neighbors for 7352 samples in 64.801s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
```



```
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.133828
[t-SNE] Computed conditional probabilities in 0.214s
[t-SNE] Iteration 50: error = 106.0169220, gradient norm = 0.0194293 (50 iterations in 24.550s)
[t-SNE] Iteration 100: error = 90.3036194, gradient norm = 0.0097653 (50 iterations in 11.936s)
[t-SNE] Iteration 150: error = 87.3132935, gradient norm = 0.0053059 (50 iterations in 11.246s)
[t-SNE] Iteration 200: error = 86.1169128, gradient norm = 0.0035844 (50 iterations in 11.864s)
[t-SNE] Iteration 250: error = 85.4133606, gradient norm = 0.0029100 (50 iterations in 11.944s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 85.413361
[t-SNE] Iteration 300: error = 3.1394315, gradient norm = 0.0013976 (50 iterations in 11.742s)
[t-SNE] Iteration 350: error = 2.4929206, gradient norm = 0.0006466 (50 iterations in 11.627s)
[t-SNE] Iteration 400: error = 2.1733041, gradient norm = 0.0004230 (50 iterations in 11.846s)
[t-SNE] Iteration 450: error = 1.9884514, gradient norm = 0.0003124 (50 iterations in 11.405s)
[t-SNE] Iteration 500: error = 1.8702440, gradient norm = 0.0002514 (50 iterations in 11.320s)
[t-SNE] Iteration 550: error = 1.7870129, gradient norm = 0.0002107 (50 iterations in 12.009s)
[t-SNE] Iteration 600: error = 1.7246909, gradient norm = 0.0001824 (50 iterations in 10.632s)
[t-SNE] Iteration 650: error = 1.6758548, gradient norm = 0.0001590 (50 iterations in 11.270s)
[t-SNE] Iteration 700: error = 1.6361949, gradient norm = 0.0001451 (50 iterations in 12.072s)
[t-SNE] Iteration 750: error = 1.6034756, gradient norm = 0.0001305 (50 iterations in 11.607s)
```

```
[t-SNE] Iteration 800: error = 1.5761518, gradient norm = 0.0001188 (50
iterations in 9.409s)
[t-SNE] Iteration 850: error = 1.5527289, gradient norm = 0.0001113 (50
iterations in 8.309s)
[t-SNE] Iteration 900: error = 1.5328671, gradient norm = 0.0001021 (50
iterations in 9.433s)
[t-SNE] Iteration 950: error = 1.5152045, gradient norm = 0.0000974 (50
iterations in 11.488s)
[t-SNE] Iteration 1000: error = 1.4999681, gradient norm = 0.0000933 (5
0 iterations in 10.593s)
[t-SNE] Error after 1000 iterations: 1.499968
Done..
Creating plot for this t-sne visualization..
saving this plot as image in present working directory...
```



Done

```
performing tsne with perplexity 20 and with 1000 iterations at max
[t-SNE] Computing 61 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.425s...
[t-SNE] Computed neighbors for 7352 samples in 61.792s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
```

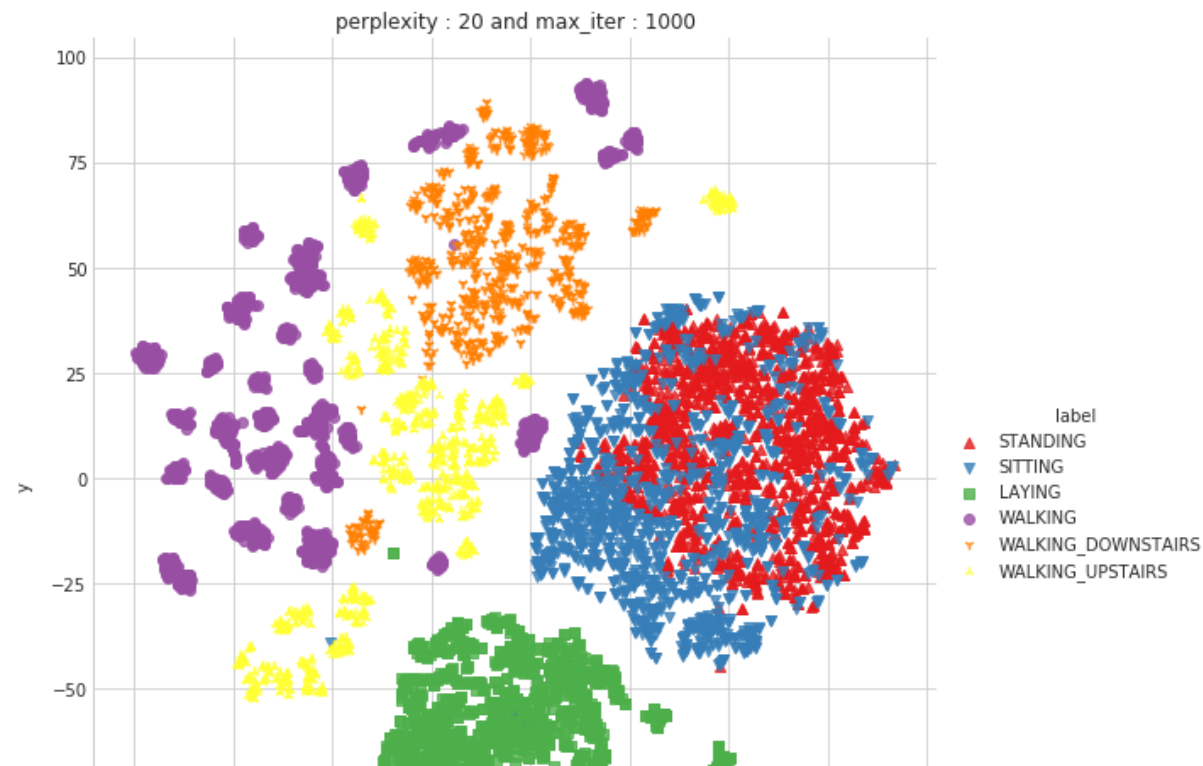
```

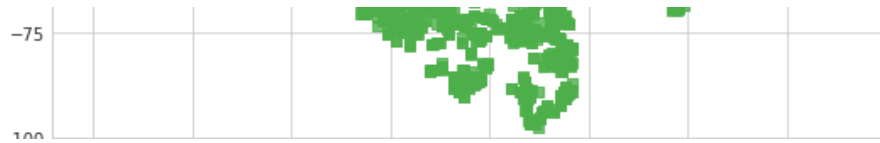
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.274335
[t-SNE] Computed conditional probabilities in 0.355s
[t-SNE] Iteration 50: error = 97.5202179, gradient norm = 0.0223863 (50
iterations in 21.168s)
[t-SNE] Iteration 100: error = 83.9500732, gradient norm = 0.0059110 (5
0 iterations in 17.306s)
[t-SNE] Iteration 150: error = 81.8804779, gradient norm = 0.0035797 (5
0 iterations in 14.258s)
[t-SNE] Iteration 200: error = 81.1615143, gradient norm = 0.0022536 (5
0 iterations in 14.130s)
[t-SNE] Iteration 250: error = 80.7704086, gradient norm = 0.0018108 (5
0 iterations in 15.340s)

[t-SNE] KL divergence after 250 iterations with early exaggeration: 80.
770409
[t-SNE] Iteration 300: error = 2.6957574, gradient norm = 0.0012993 (50
iterations in 13.605s)
[t-SNE] Iteration 350: error = 2.1637220, gradient norm = 0.0005765 (50
iterations in 13.248s)
[t-SNE] Iteration 400: error = 1.9143614, gradient norm = 0.0003474 (50
iterations in 14.774s)
[t-SNE] Iteration 450: error = 1.7684202, gradient norm = 0.0002458 (50
iterations in 15.502s)
[t-SNE] Iteration 500: error = 1.6744757, gradient norm = 0.0001923 (50
iterations in 14.808s)
[t-SNE] Iteration 550: error = 1.6101606, gradient norm = 0.0001575 (50
iterations in 14.043s)
[t-SNE] Iteration 600: error = 1.5641028, gradient norm = 0.0001344 (50
iterations in 15.769s)
[t-SNE] Iteration 650: error = 1.5291905, gradient norm = 0.0001182 (50
iterations in 15.834s)
[t-SNE] Iteration 700: error = 1.5024391, gradient norm = 0.0001055 (50
iterations in 15.398s)
[t-SNE] Iteration 750: error = 1.4809053, gradient norm = 0.0000965 (50
iterations in 14.594s)
[t-SNE] Iteration 800: error = 1.4631850, gradient norm = 0.0000884 (50

```

```
[t-SNE] Iteration 800: error = 1.4051859, gradient norm = 0.0000884 (50
iterations in 15.025s)
[t-SNE] Iteration 850: error = 1.4486470, gradient norm = 0.0000832 (50
iterations in 14.060s)
[t-SNE] Iteration 900: error = 1.4367288, gradient norm = 0.0000804 (50
iterations in 12.389s)
[t-SNE] Iteration 950: error = 1.4270191, gradient norm = 0.0000761 (50
iterations in 10.392s)
[t-SNE] Iteration 1000: error = 1.4189968, gradient norm = 0.0000787 (5
0 iterations in 12.355s)
[t-SNE] Error after 1000 iterations: 1.418997
Done..
Creating plot for this t-sne visualization..
saving this plot as image in present working directory...
```



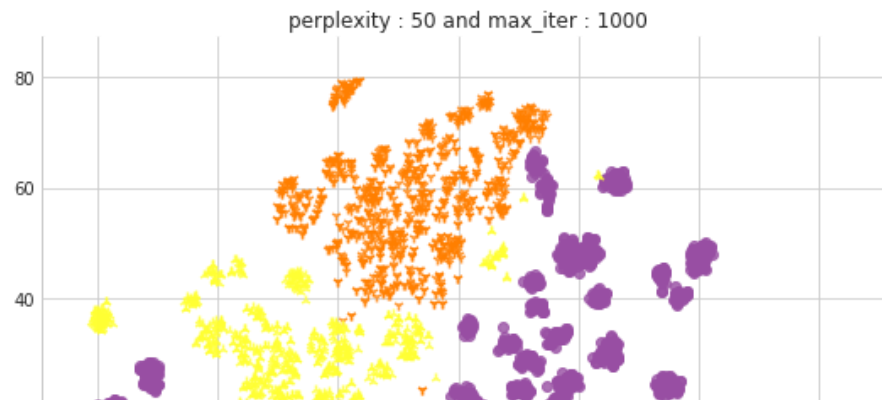


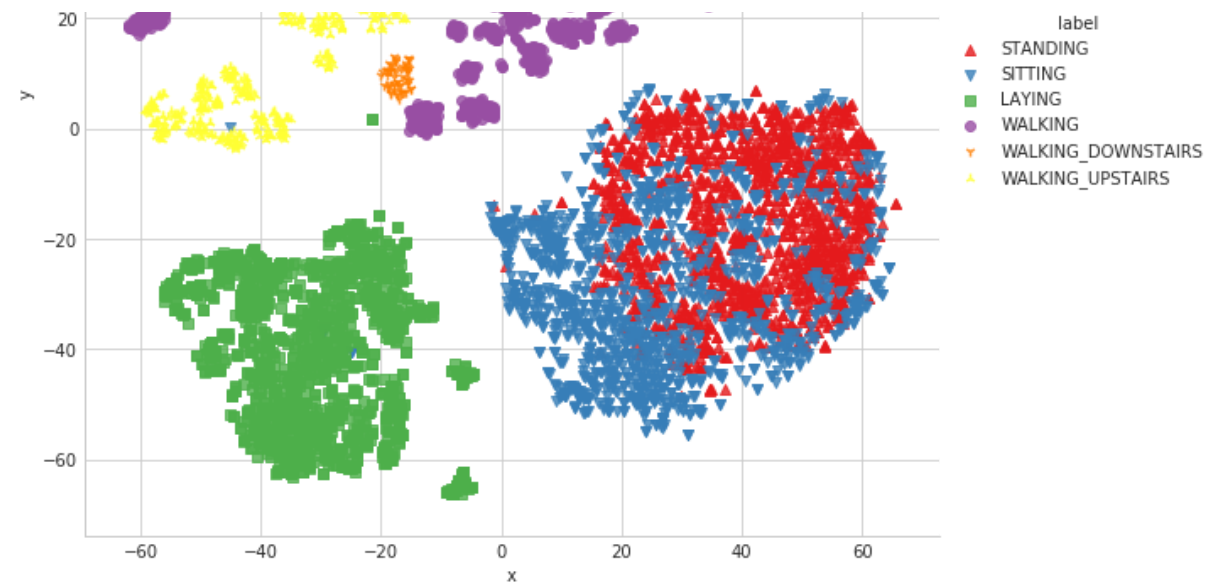
Done

```
performing tsne with perplexity 50 and with 1000 iterations at max
[t-SNE] Computing 151 nearest neighbors...
[t-SNE] Indexed 7352 samples in 0.376s...
[t-SNE] Computed neighbors for 7352 samples in 73.164s...
[t-SNE] Computed conditional probabilities for sample 1000 / 7352
[t-SNE] Computed conditional probabilities for sample 2000 / 7352
[t-SNE] Computed conditional probabilities for sample 3000 / 7352
[t-SNE] Computed conditional probabilities for sample 4000 / 7352
[t-SNE] Computed conditional probabilities for sample 5000 / 7352
[t-SNE] Computed conditional probabilities for sample 6000 / 7352
[t-SNE] Computed conditional probabilities for sample 7000 / 7352
[t-SNE] Computed conditional probabilities for sample 7352 / 7352
[t-SNE] Mean sigma: 1.437672
[t-SNE] Computed conditional probabilities in 0.844s
[t-SNE] Iteration 50: error = 86.1525574, gradient norm = 0.0242986 (50
iterations in 36.249s)
[t-SNE] Iteration 100: error = 75.9874649, gradient norm = 0.0061005 (5
0 iterations in 30.453s)
[t-SNE] Iteration 150: error = 74.7072296, gradient norm = 0.0024708 (5
0 iterations in 28.461s)
[t-SNE] Iteration 200: error = 74.2736282, gradient norm = 0.0018644 (5
0 iterations in 27.735s)
[t-SNE] Iteration 250: error = 74.0722427, gradient norm = 0.0014078 (5
0 iterations in 26.835s)
[t-SNE] KL divergence after 250 iterations with early exaggeration: 74.
072243
[t-SNE] Iteration 300: error = 2.1539080, gradient norm = 0.0011796 (50
iterations in 25.445s)
[t-SNE] Iteration 350: error = 1.7567128, gradient norm = 0.0004845 (50
iterations in 21.282s)
[t-SNE] Iteration 400: error = 1.5888531, gradient norm = 0.0002798 (50
iterations in 21.015s)
[t-SNE] Iteration 450: error = 1.4956820, gradient norm = 0.0001894 (50
iterations in 23.332s)
```

```
iterations in 23.552s)
[t-SNE] Iteration 500: error = 1.4359720, gradient norm = 0.0001420 (50
iterations in 23.083s)
[t-SNE] Iteration 550: error = 1.3947564, gradient norm = 0.0001117 (50
iterations in 19.626s)
[t-SNE] Iteration 600: error = 1.3653858, gradient norm = 0.0000949 (50
iterations in 22.752s)
[t-SNE] Iteration 650: error = 1.3441534, gradient norm = 0.0000814 (50
iterations in 23.972s)
[t-SNE] Iteration 700: error = 1.3284039, gradient norm = 0.0000742 (50
iterations in 20.636s)
[t-SNE] Iteration 750: error = 1.3171139, gradient norm = 0.0000700 (50
iterations in 20.407s)
[t-SNE] Iteration 800: error = 1.3085558, gradient norm = 0.0000657 (50
iterations in 24.951s)
[t-SNE] Iteration 850: error = 1.3017821, gradient norm = 0.0000603 (50
iterations in 24.719s)

[t-SNE] Iteration 900: error = 1.2962619, gradient norm = 0.0000586 (50
iterations in 24.500s)
[t-SNE] Iteration 950: error = 1.2914882, gradient norm = 0.0000573 (50
iterations in 24.132s)
[t-SNE] Iteration 1000: error = 1.2874244, gradient norm = 0.0000546 (5
0 iterations in 22.840s)
[t-SNE] Error after 1000 iterations: 1.287424
Done..
Creating plot for this t-sne visualization..
saving this plot as image in present working directory...
```





Done

```
In [0]: import numpy as np  
import pandas as pd
```

Obtain the train and test data

```
In [0]: train = pd.read_csv('UCI_HAR_dataset/csv_files/train.csv')  
test = pd.read_csv('UCI_HAR_dataset/csv_files/test.csv')  
print(train.shape, test.shape)
```


(7352, 564) (2947, 564)

In [0]: train.head(3)

Out[0]:

	tBodyAccmeanX	tBodyAccmeanY	tBodyAccmeanZ	tBodyAccstdX	tBodyAccstdY	tB
0	0.288585	-0.020294	-0.132905	-0.995279	-0.983111	-0.
1	0.278419	-0.016411	-0.123520	-0.998245	-0.975300	-0.
2	0.279653	-0.019467	-0.113462	-0.995380	-0.967187	-0.

3 rows × 564 columns

```
In [0]: # get X_train and y_train from csv files
X_train = train.drop(['subject', 'Activity', 'ActivityName'], axis=1)
y_train = train.ActivityName
```

```
In [0]: # get X_test and y_test from test csv file
X_test = test.drop(['subject', 'Activity', 'ActivityName'], axis=1)
y_test = test.ActivityName
```

```
In [0]: print('X_train and y_train : ({}, {})'.format(X_train.shape, y_train.shape))
print('X_test and y_test : ({}, {})'.format(X_test.shape, y_test.shape))
```

```
X_train and y_train : ((7352, 561), (7352,))
X_test and y_test : ((2947, 561), (2947,))
```

Let's model with our data

Labels that are useful in plotting confusion matrix

```
In [0]: labels=['LAYING', 'SITTING', 'STANDING', 'WALKING', 'WALKING_DOWNSTAIRS',  
              'WALKING_UPSTAIRS']
```

Function to plot the confusion matrix

```
In [0]: import itertools  
import numpy as np  
import matplotlib.pyplot as plt  
from sklearn.metrics import confusion_matrix  
plt.rcParams["font.family"] = 'DejaVu Sans'  
  
def plot_confusion_matrix(cm, classes,  
                          normalize=False,  
                          title='Confusion matrix',  
                          cmap=plt.cm.Blues):  
    if normalize:  
        cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]  
  
    plt.imshow(cm, interpolation='nearest', cmap=cmap)  
    plt.title(title)  
    plt.colorbar()  
    tick_marks = np.arange(len(classes))  
    plt.xticks(tick_marks, classes, rotation=90)  
    plt.yticks(tick_marks, classes)  
  
    fmt = '.2f' if normalize else 'd'  
    thresh = cm.max() / 2.  
    for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):  
        plt.text(j, i, format(cm[i, j], fmt),  
                 horizontalalignment="center",  
                 color="white" if cm[i, j] > thresh else "black")
```

```
plt.tight_layout()
plt.ylabel('True label')
plt.xlabel('Predicted label')
```

Generic function to run any model specified

```
In [0]: from datetime import datetime
def perform_model(model, X_train, y_train, X_test, y_test, class_labels
, cm_normalize=True, \
                print_cm=True, cm_cmap=plt.cm.Greens):

    # to store results at various phases
    results = dict()

    # time at which model starts training
    train_start_time = datetime.now()
    print('training the model..')
    model.fit(X_train, y_train)
    print('Done \n \n')
    train_end_time = datetime.now()
    results['training_time'] = train_end_time - train_start_time
    print('training_time(HH:MM:SS.ms) - {}'.format(results['trainin
g_time']))

    # predict test data
    print('Predicting test data')
    test_start_time = datetime.now()
    y_pred = model.predict(X_test)
    test_end_time = datetime.now()
    print('Done \n \n')
    results['testing_time'] = test_end_time - test_start_time
    print('testing_time(HH:MM:SS.ms) - {}'.format(results['testing_
time']))
    results['predicted'] = y_pred
```

```

# calculate overall accuracy of the model
accuracy = metrics.accuracy_score(y_true=y_test, y_pred=y_pred)
# store accuracy in results
results['accuracy'] = accuracy
print('-----')
print('|         Accuracy         |')
print('-----')
print('\n    {}\n\n'.format(accuracy))

# confusion matrix
cm = metrics.confusion_matrix(y_test, y_pred)
results['confusion_matrix'] = cm
if print_cm:
    print('-----')
    print('| Confusion Matrix |')
    print('-----')
    print('\n {}'.format(cm))

# plot confusion matrix
plt.figure(figsize=(8,8))
plt.grid(b=False)
plot_confusion_matrix(cm, classes=class_labels, normalize=True, title='Normalized confusion matrix', cmap = cm_cmap)
plt.show()

# get classification report
print('-----')
print('| Classification Report |')
print('-----')
classification_report = metrics.classification_report(y_test, y_pred)

# store report in results
results['classification_report'] = classification_report
print(classification_report)

# add the trained model to the results
results['model'] = model

```

```
return results
```

Method to print the gridsearch Attributes

```
In [0]: def print_grid_search_attributes(model):
        # Estimator that gave highest score among all the estimators formed
        in GridSearch
        print('-----')
        print('|           Best Estimator           |')
        print('-----')
        print('\n\t{}\n'.format(model.best_estimator_))

        # parameters that gave best results while performing grid search
        print('-----')
        print('|           Best parameters           |')
        print('-----')
        print('\tParameters of best estimator : \n\n\t{}\n'.format(model.be
st_params_))

        # number of cross validation splits
        print('-----')
        print('|   No of CrossValidation sets   |')
        print('-----')
        print('\n\tTotal numbre of cross validation sets: {}\n'.format(mode
l.n_splits_))

        # Average cross validated score of the best estimator, from the Gri
d Search
        print('-----')
        print('|           Best Score           |')
        print('-----')
        print('\n\tAverage Cross Validate scores of best estimator : \n\n\t
{}\n'.format(model.best_score_))
```

1. Logistic Regression with Grid Search

```
In [0]: from sklearn import linear_model
        from sklearn import metrics

        from sklearn.model_selection import GridSearchCV
```

```
In [0]: # start Grid search
        parameters = {'C':[0.01, 0.1, 1, 10, 20, 30], 'penalty':['l2','l1']}
        log_reg = linear_model.LogisticRegression()
        log_reg_grid = GridSearchCV(log_reg, param_grid=parameters, cv=3, verbose=1, n_jobs=-1)
        log_reg_grid_results = perform_model(log_reg_grid, X_train, y_train, X_test, y_test, class_labels=labels)
```

training the model..

Fitting 3 folds for each of 12 candidates, totalling 36 fits

[Parallel(n_jobs=-1)]: Done 36 out of 36 | elapsed: 1.2min finished

Done

training_time(HH:MM:SS.ms) - 0:01:25.843810

Predicting test data

Done

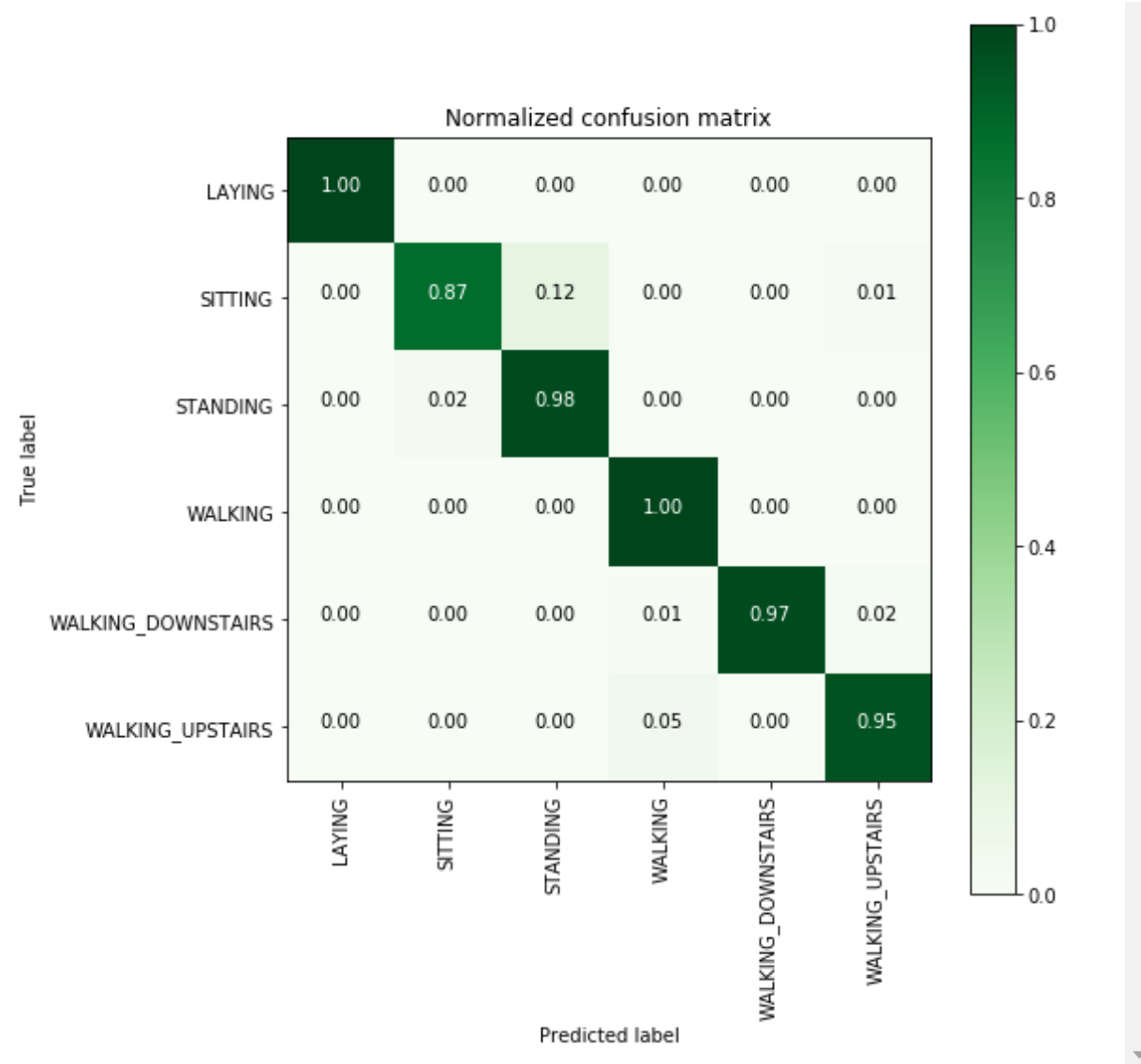
```
testing time(HH:MM:SS:ms) - 0:00:00.009192
```

```
-----  
|      Accuracy      |  
-----
```

```
0.9626739056667798
```

```
-----  
| Confusion Matrix |  
-----
```

```
[[537  0  0  0  0  0]  
[  1 428 58  0  0  4]  
[  0 12 519  1  0  0]  
[  0  0  0 495  1  0]  
[  0  0  0  3 409  8]  
[  0  0  0 22  0 449]]
```

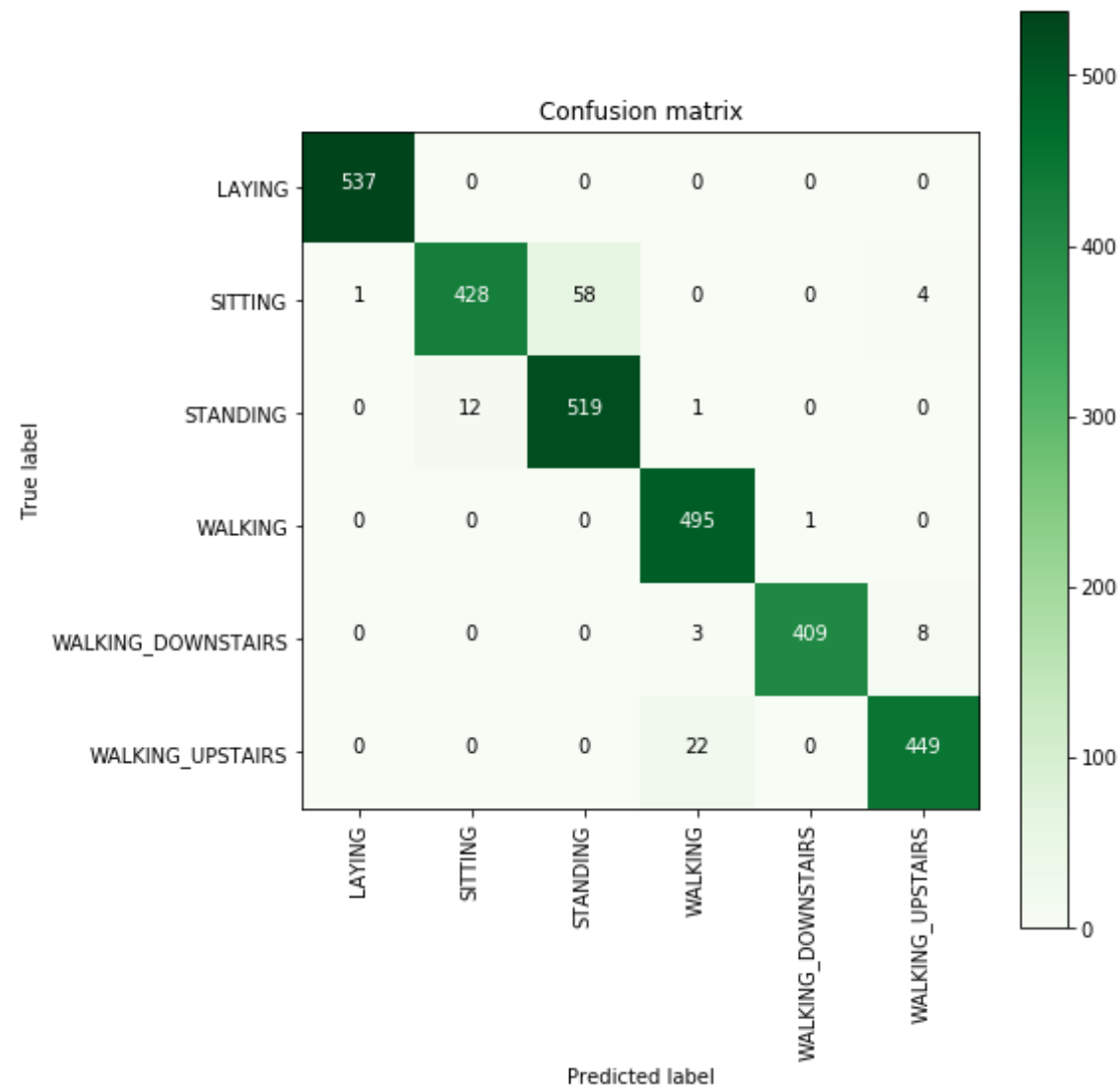


Classification Report

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537

SITTING	0.97	0.87	0.92	491
STANDING	0.90	0.98	0.94	532
WALKING	0.95	1.00	0.97	496
WALKING_DOWNSTAIRS	1.00	0.97	0.99	420
WALKING_UPSTAIRS	0.97	0.95	0.96	471
avg / total	0.96	0.96	0.96	2947

```
In [0]: plt.figure(figsize=(8,8))
plt.grid(b=False)
plot_confusion_matrix(log_reg_grid_results['confusion_matrix'], classes
=labels, cmap=plt.cm.Greens, )
plt.show()
```



```
In [0]: # observe the attributes of the model
print_grid_search_attributes(log_reg_grid_results['model'])
```

```
-----
| Best Estimator |
```

```

-----
        LogisticRegression(C=30, class_weight=None, dual=False, fit_int
ercept=True,
        intercept_scaling=1, max_iter=100, multi_class='ovr', n_jobs=
1,
        penalty='l2', random_state=None, solver='liblinear', tol=0.00
01,
        verbose=0, warm_start=False)

-----
|      Best parameters      |
-----
Parameters of best estimator :

{'C': 30, 'penalty': 'l2'}

-----
| No of CrossValidation sets |
-----

Total nombre of cross validation sets: 3

-----
|      Best Score      |
-----

Average Cross Validate scores of best estimator :

0.9461371055495104

```

2. Linear SVC with GridSearch

```
In [0]: from sklearn.svm import LinearSVC
```

```
In [0]: parameters = {'C':[0.125, 0.5, 1, 2, 8, 16]}
```

```
lr_svc = LinearSVC(tol=0.00005)
lr_svc_grid = GridSearchCV(lr_svc, param_grid=parameters, n_jobs=-1, verbose=1)
lr_svc_grid_results = perform_model(lr_svc_grid, X_train, y_train, X_test, y_test, class_labels=labels)
```

training the model..

Fitting 3 folds for each of 6 candidates, totalling 18 fits

[Parallel(n_jobs=-1)]: Done 18 out of 18 | elapsed: 24.9s finished

Done

training_time(HH:MM:SS.ms) - 0:00:32.951942

Predicting test data

Done

testing time(HH:MM:SS.ms) - 0:00:00.012182

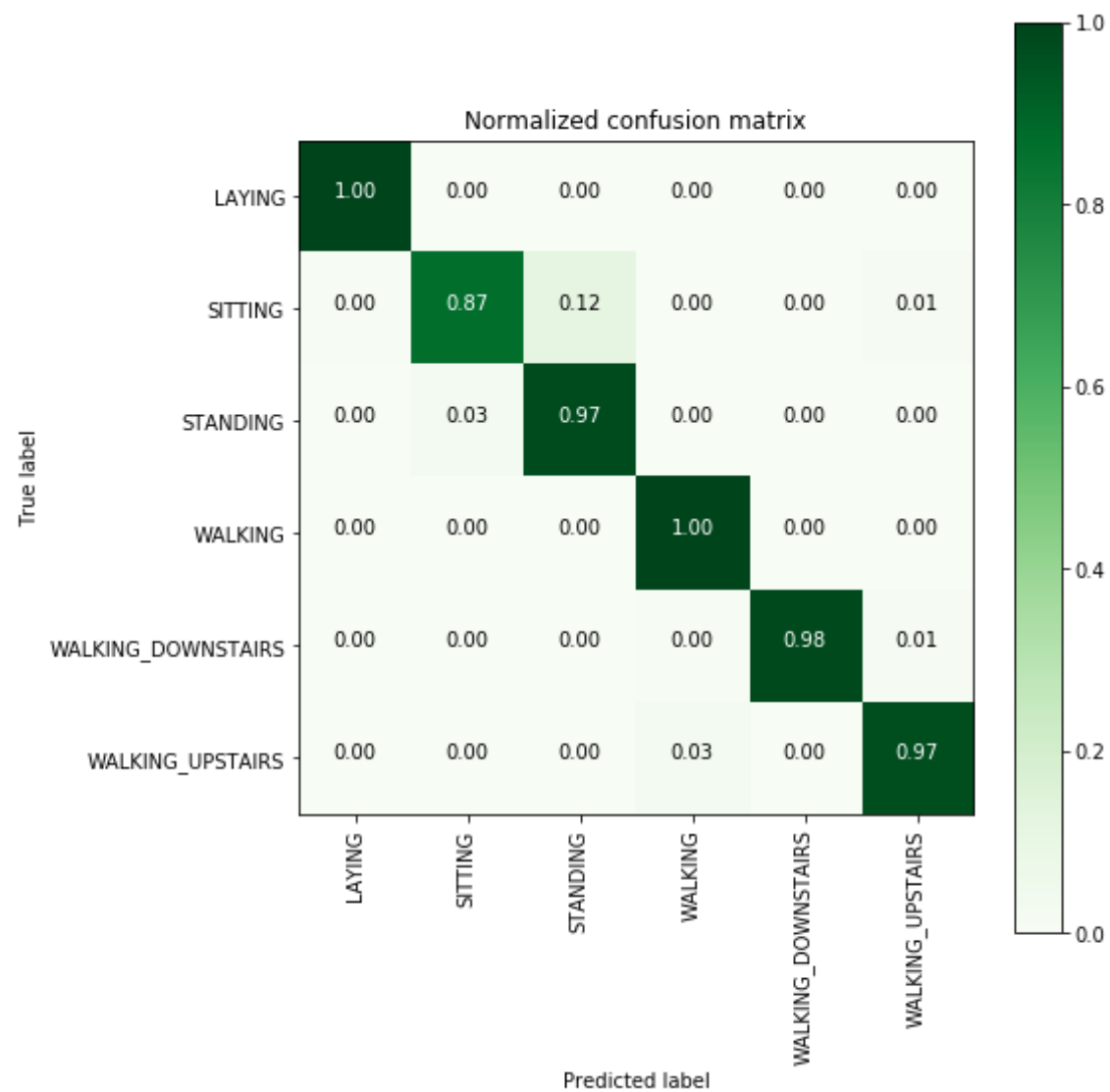
Accuracy

0.9660671869697998

Confusion Matrix

```
[[537  0  0  0  0  0]
 [ 2 426 58  0  0  5]
 [ 0 14 518  0  0  0]
 [ 0  0  0 495  0  1]
```

```
[ 0  0  0  2 413  5]
[ 0  0  0  12  1 458]]
```



| Classification Report |

precision recall f1-score support

	precision	recall	f1 score	support
LAYING	1.00	1.00	1.00	537
SITTING	0.97	0.87	0.92	491
STANDING	0.90	0.97	0.94	532
WALKING	0.97	1.00	0.99	496
WALKING_DOWNSTAIRS	1.00	0.98	0.99	420
WALKING_UPSTAIRS	0.98	0.97	0.97	471
avg / total	0.97	0.97	0.97	2947

```
In [0]: print_grid_search_attributes(lr_svc_grid_results['model'])
```

```
-----
|      Best Estimator      |
-----

      LinearSVC(C=8, class_weight=None, dual=True, fit_intercept=True,
e,
      intercept_scaling=1, loss='squared_hinge', max_iter=1000,
      multi_class='ovr', penalty='l2', random_state=None, tol=5e-05,
      verbose=0)

-----
|      Best parameters      |
-----

      Parameters of best estimator :

      {'C': 8}

-----
|      No of CrossValidation sets      |
-----

      Total nombre of cross validation sets: 3

-----
|      Best Score      |
-----
```

Average Cross Validate scores of best estimator :
0.9465451577801959

We can choose **Logistic regression** or **Linear SVC** or **rbf SVM**.

3. Kernel SVM with GridSearch

```
In [0]: from sklearn.svm import SVC
parameters = {'C':[2,8,16],\
              'gamma': [ 0.0078125, 0.125, 2]}
rbf_svm = SVC(kernel='rbf')
rbf_svm_grid = GridSearchCV(rbf_svm,param_grid=parameters, n_jobs=-1)
rbf_svm_grid_results = perform_model(rbf_svm_grid, X_train, y_train, X_
test, y_test, class_labels=labels)
```

training the model..
Done

training_time(HH:MM:SS.ms) - 0:05:46.182889

Predicting test data
Done

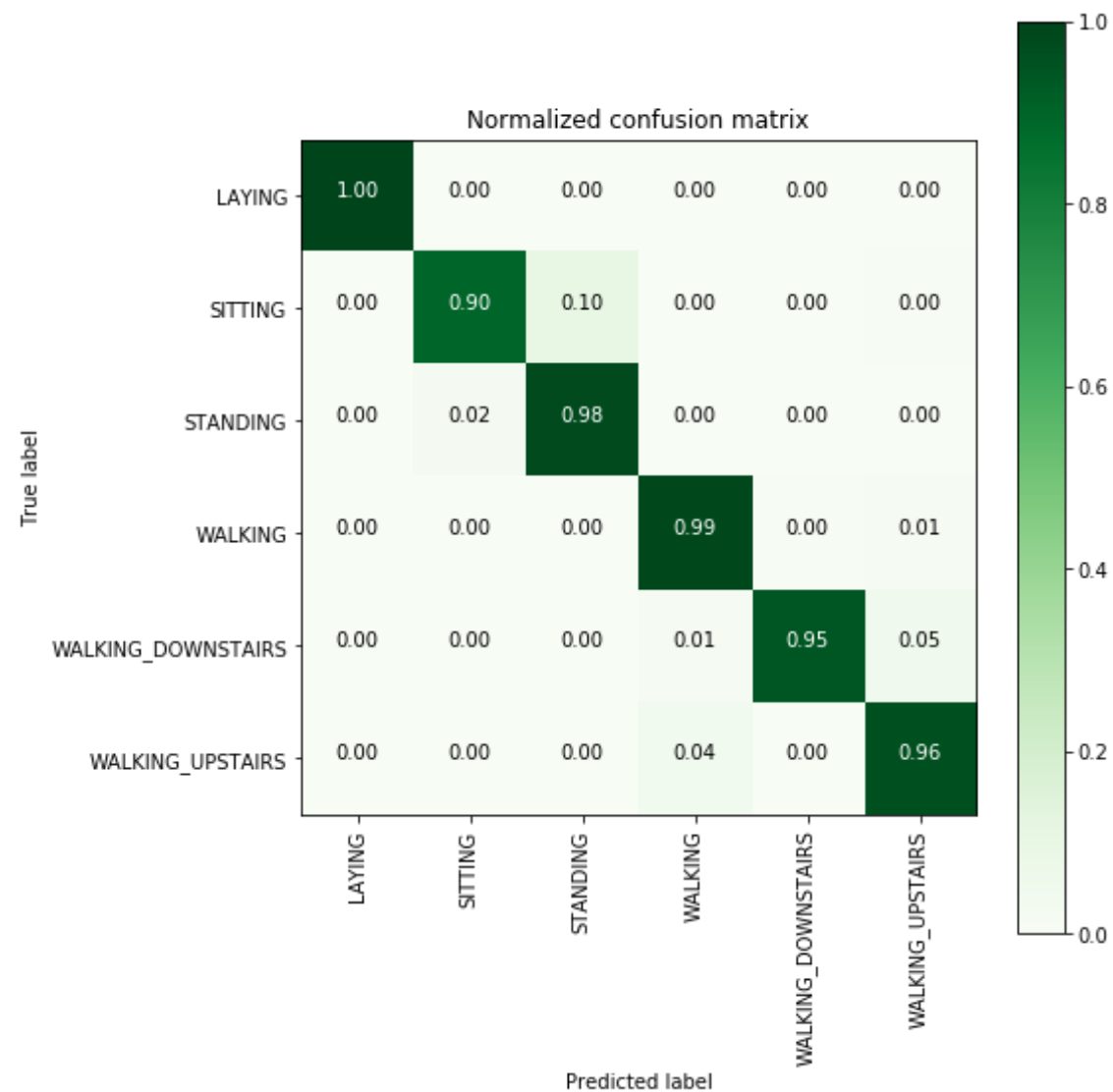
testing time(HH:MM:SS.ms) - 0:00:05.221285

| Accuracy |

0.9626739056667798

Confusion Matrix

```
[[537  0  0  0  0  0]
 [  0 441 48  0  0  2]
 [  0 12 520  0  0  0]
 [  0  0  0 489  2  5]
 [  0  0  0  4 397 19]
 [  0  0  0 17  1 453]]
```

Classification Report

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537

SITTING	0.97	0.90	0.93	491
STANDING	0.92	0.98	0.95	532
WALKING	0.96	0.99	0.97	496
WALKING_DOWNSTAIRS	0.99	0.95	0.97	420
WALKING_UPSTAIRS	0.95	0.96	0.95	471
avg / total	0.96	0.96	0.96	2947

```
In [0]: print_grid_search_attributes(rbf_svm_grid_results['model'])
```

```
-----
|      Best Estimator      |
|-----|
```

```

      SVC(C=16, cache_size=200, class_weight=None, coef0=0.0,
      decision_function_shape='ovr', degree=3, gamma=0.0078125, kernel='rb
f',
      max_iter=-1, probability=False, random_state=None, shrinking=True,
      tol=0.001, verbose=False)

```

```
-----
|    Best parameters      |
|-----|
```

```
Parameters of best estimator :
```

```
{'C': 16, 'gamma': 0.0078125}
```

```
-----
| No of CrossValidation sets |
|-----|
```

```
Total numbere of cross validation sets: 3
```

```
-----
|      Best Score        |
|-----|
```

```
Average Cross Validate scores of best estimator :
```

0.9440968443960827

4. Decision Trees with GridSearchCV

```
In [0]: from sklearn.tree import DecisionTreeClassifier
parameters = {'max_depth':np.arange(3,10,2)}
dt = DecisionTreeClassifier()
dt_grid = GridSearchCV(dt,param_grid=parameters, n_jobs=-1)
dt_grid_results = perform_model(dt_grid, X_train, y_train, X_test, y_test, class_labels=labels)
print_grid_search_attributes(dt_grid_results['model'])
```

training the model..

Done

training_time(HH:MM:SS.ms) - 0:00:19.476858

Predicting test data

Done

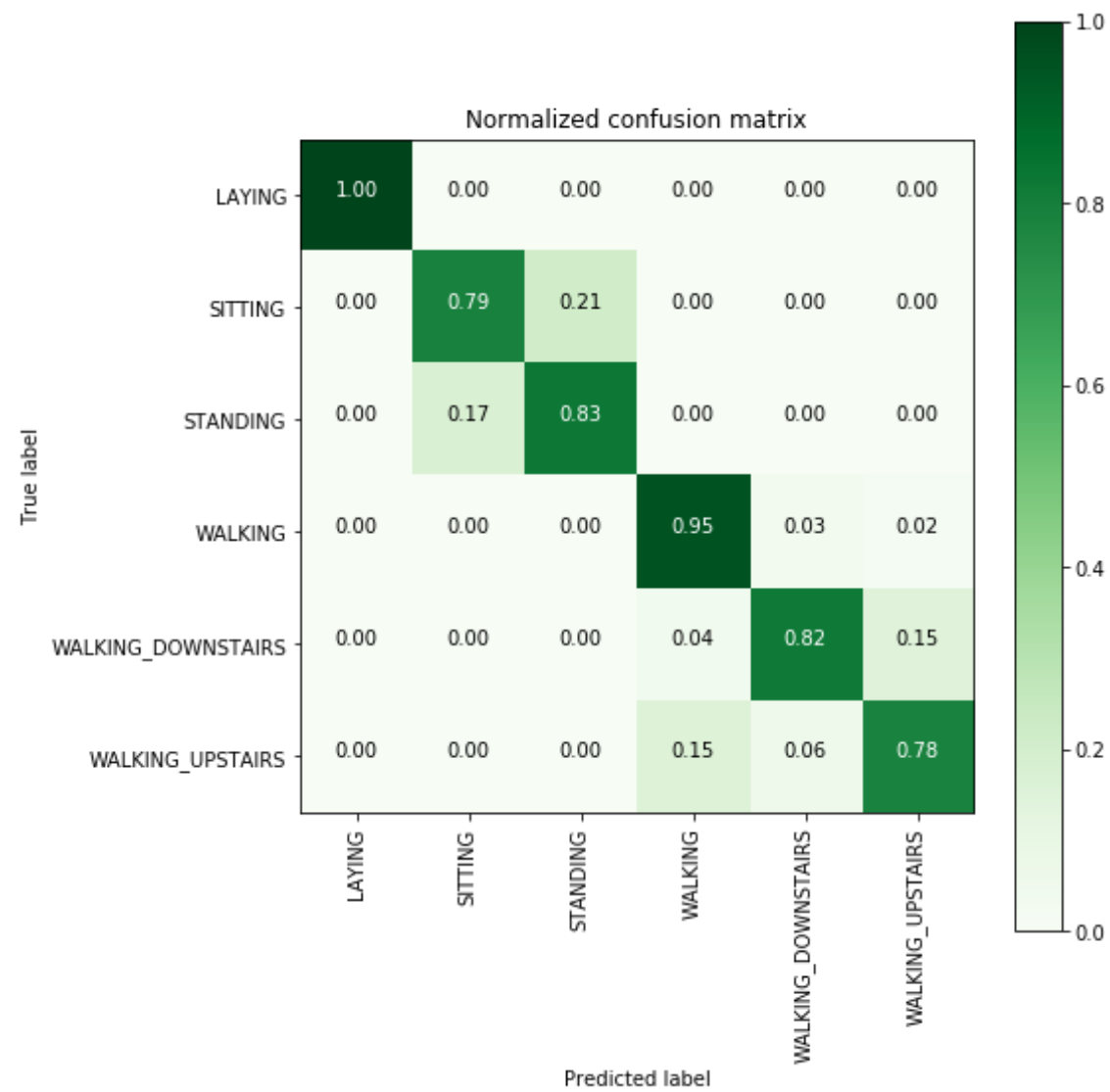
testing time(HH:MM:SS.ms) - 0:00:00.012858

```
-----
|      Accuracy      |
|-----|
```

0.8642687478791992

```
-----
| Confusion Matrix |
```

```
-----  
[[537  0  0  0  0  0]  
[  0 386 105  0  0  0]  
[  0  93 439  0  0  0]  
[  0  0  0 472 16  8]  
[  0  0  0 15 344 61]  
[  0  0  0 73 29 369]]
```



Classification Report

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537

SITTING	0.81	0.79	0.80	491
STANDING	0.81	0.83	0.82	532
WALKING	0.84	0.95	0.89	496
WALKING_DOWNSTAIRS	0.88	0.82	0.85	420
WALKING_UPSTAIRS	0.84	0.78	0.81	471
avg / total	0.86	0.86	0.86	2947

```
-----
|      Best Estimator      |
|-----|
```

```
DecisionTreeClassifier(class_weight=None, criterion='gini', m
ax_depth=7,
                        max_features=None, max_leaf_nodes=None,
                        min_impurity_decrease=0.0, min_impurity_split=None,
                        min_samples_leaf=1, min_samples_split=2,
                        min_weight_fraction_leaf=0.0, presort=False, random_state
=None,
                        splitter='best')
```

```
-----
|    Best parameters      |
|-----|
```

Parameters of best estimator :

```
{'max_depth': 7}
```

```
-----
|  No of CrossValidation sets  |
|-----|
```

Total number of cross validation sets: 3

```
-----
|      Best Score        |
|-----|
```

Average Cross Validate scores of best estimator :

0.8369151251360174

5. Random Forest Classifier with GridSearch

```
In [0]: from sklearn.ensemble import RandomForestClassifier
params = {'n_estimators': np.arange(10,201,20), 'max_depth':np.arange(3,15,2)}
rfc = RandomForestClassifier()
rfc_grid = GridSearchCV(rfc, param_grid=params, n_jobs=-1)
rfc_grid_results = perform_model(rfc_grid, X_train, y_train, X_test, y_test, class_labels=labels)
print_grid_search_attributes(rfc_grid_results['model'])
```

training the model..

Done

training_time(HH:MM:SS.ms) - 0:06:22.775270

Predicting test data

Done

testing time(HH:MM:SS.ms) - 0:00:00.025937

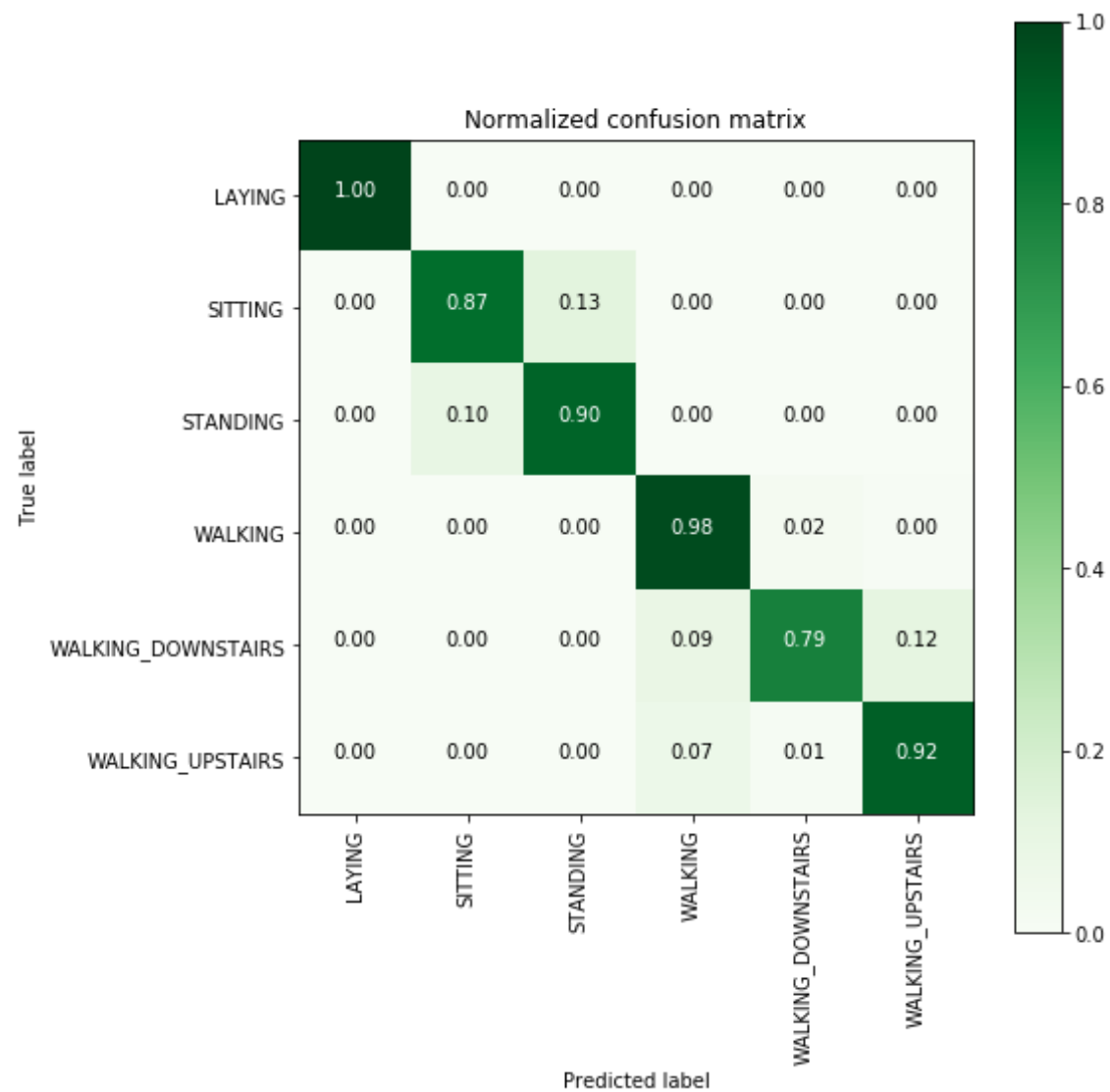
```
-----
|      Accuracy      |
-----
```

0.9131319986426875

```
-----
```

| Confusion Matrix |

```
[[537  0  0  0  0  0]
 [  0 427 64  0  0  0]
 [  0 52 480  0  0  0]
 [  0  0  0 484 10  2]
 [  0  0  0 38 332 50]
 [  0  0  0 34  6 431]]
```

Classification Report

precision recall f1-score support

LAYING 1.00 1.00 1.00 527

LAYING	1.00	1.00	1.00	537
SITTING	0.89	0.87	0.88	491
STANDING	0.88	0.90	0.89	532
WALKING	0.87	0.98	0.92	496
WALKING_DOWNSTAIRS	0.95	0.79	0.86	420
WALKING_UPSTAIRS	0.89	0.92	0.90	471
avg / total	0.92	0.91	0.91	2947

```
-----
| Best Estimator |
-----
```

```
RandomForestClassifier(bootstrap=True, class_weight=None, criterion='gini',
                        max_depth=7, max_features='auto', max_leaf_nodes=None,
                        min_impurity_decrease=0.0, min_impurity_split=None,
                        min_samples_leaf=1, min_samples_split=2,
                        min_weight_fraction_leaf=0.0, n_estimators=70, n_jobs=1,
                        oob_score=False, random_state=None, verbose=0,
                        warm_start=False)
```

```
-----
| Best parameters |
-----
```

Parameters of best estimator :

```
{'max_depth': 7, 'n_estimators': 70}
```

```
-----
| No of CrossValidation sets |
-----
```

Total number of cross validation sets: 3

```
-----
| Best Score |
-----
```

Average Cross Validation score of best estimator :

Average cross validate scores of best estimator :

0.9141730141458106

6. Gradient Boosted Decision Trees With GridSearch

```
In [0]: from sklearn.ensemble import GradientBoostingClassifier
param_grid = {'max_depth': np.arange(5,8,1), \
              'n_estimators': np.arange(130,170,10)}
gbdt = GradientBoostingClassifier()
gbdt_grid = GridSearchCV(gbdt, param_grid=param_grid, n_jobs=-1)
gbdt_grid_results = perform_model(gbdt_grid, X_train, y_train, X_test,
y_test, class_labels=labels)
print_grid_search_attributes(gbdt_grid_results['model'])
```

training the model..

Done

training_time(HH:MM:SS.ms) - 0:28:03.653432

Predicting test data

Done

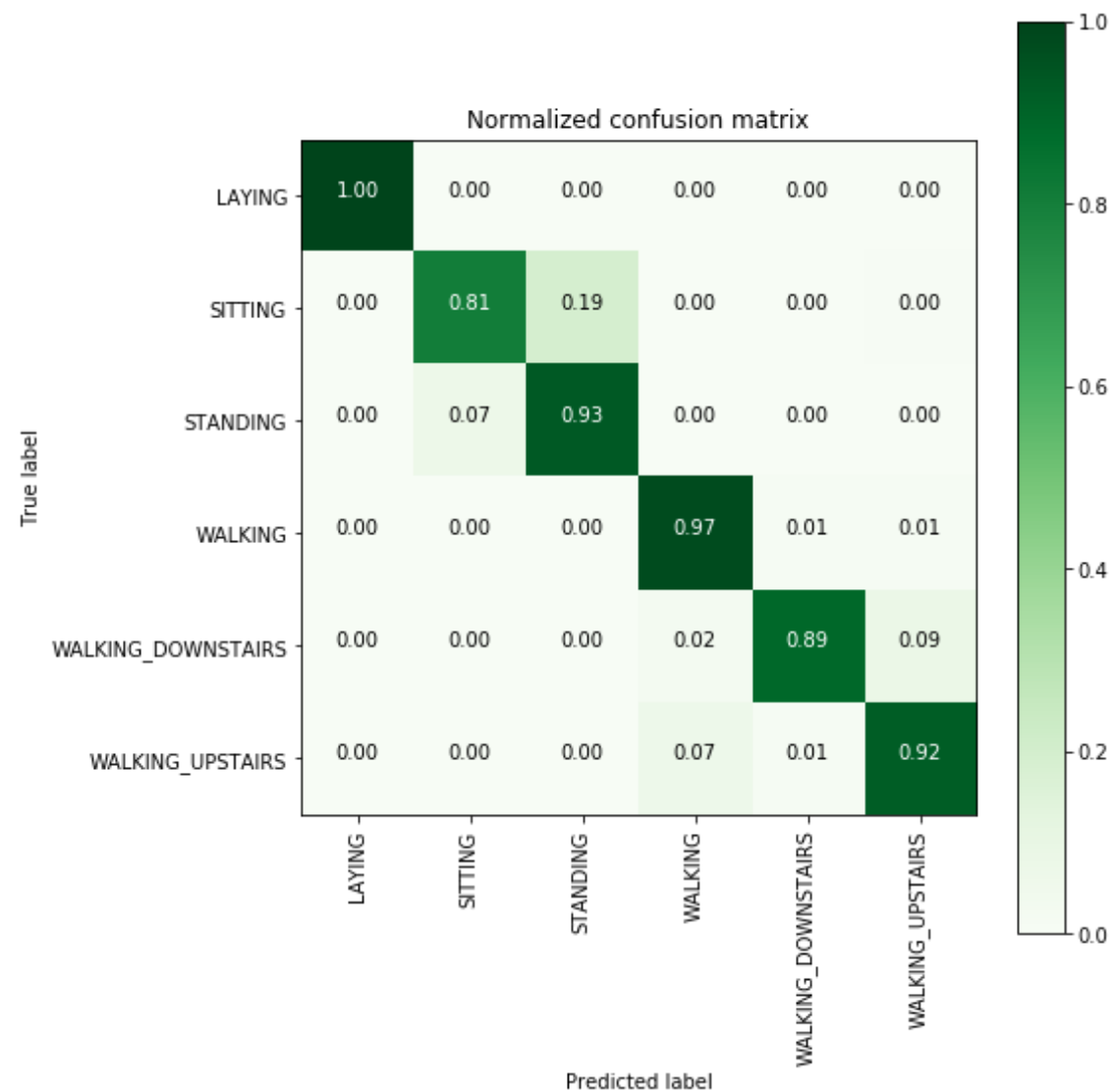
testing time(HH:MM:SS.ms) - 0:00:00.058843

```
-----
|      Accuracy      |
-----
```

0.9222938581608415

Confusion Matrix

```
[[537  0  0  0  0  0]
 [  0 396 93  0  0  2]
 [  0 37 495  0  0  0]
 [  0  0  0 483  7  6]
 [  0  0  0 10 374 36]
 [  0  1  0 31  6 433]]
```



Classification Report

	precision	recall	f1-score	support
LAYING	1.00	1.00	1.00	537

SITTING	0.91	0.81	0.86	491
STANDING	0.84	0.93	0.88	532
WALKING	0.92	0.97	0.95	496
WALKING_DOWNSTAIRS	0.97	0.89	0.93	420
WALKING_UPSTAIRS	0.91	0.92	0.91	471
avg / total	0.92	0.92	0.92	2947

```
-----
| Best Estimator |
-----
```

```
GradientBoostingClassifier(criterion='friedman_mse', init=None,
learning_rate=0.1, loss='deviance', max_depth=5,
max_features=None, max_leaf_nodes=None,
min_impurity_decrease=0.0, min_impurity_split=None,
min_samples_leaf=1, min_samples_split=2,
min_weight_fraction_leaf=0.0, n_estimators=140,
presort='auto', random_state=None, subsample=1.0, verbose
=0,
warm_start=False)
```

```
-----
| Best parameters |
-----
```

Parameters of best estimator :

```
{'max_depth': 5, 'n_estimators': 140}
```

```
-----
| No of CrossValidation sets |
-----
```

Total numbere of cross validation sets: 3

```
-----
| Best Score |
-----
```

Average Cross Validate scores of best estimator :

0.904379760609358

```
In [0]: import pandas as pd
import numpy as np
```

```
In [0]: # Activities are the class labels
# It is a 6 class classification
ACTIVITIES = {
    0: 'WALKING',
    1: 'WALKING_UPSTAIRS',
    2: 'WALKING_DOWNSTAIRS',
    3: 'SITTING',
    4: 'STANDING',
    5: 'LAYING',
}

# Utility function to print the confusion matrix
def confusion_matrix(Y_true, Y_pred):
    Y_true = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_true, axis=1)
    ])
    Y_pred = pd.Series([ACTIVITIES[y] for y in np.argmax(Y_pred, axis=1)
    ])

    return pd.crosstab(Y_true, Y_pred, rownames=['True'], colnames=['Pred'])
```

Data

```
In [0]: # Data directory
DATADIR = 'UCI_HAR_Dataset'
```

```
In [0]: # Raw data signals
```

```

# Signals are from Accelerometer and Gyroscope
# The signals are in x,y,z directions
# Sensor signals are filtered to have only body acceleration
# excluding the acceleration due to gravity
# Triaxial acceleration from the accelerometer is total acceleration
SIGNALS = [
    "body_acc_x",
    "body_acc_y",
    "body_acc_z",
    "body_gyro_x",
    "body_gyro_y",
    "body_gyro_z",
    "total_acc_x",
    "total_acc_y",
    "total_acc_z"
]

```

```

In [0]: # Utility function to read the data from csv file
def _read_csv(filename):
    return pd.read_csv(filename, delim_whitespace=True, header=None)

# Utility function to load the load
def load_signals(subset):
    signals_data = []

    for signal in SIGNALS:
        filename = f'UCI_HAR_Dataset/{subset}/Inertial Signals/{signal}_{subset}.txt'
        signals_data.append(
            _read_csv(filename).as_matrix()
        )

    # Transpose is used to change the dimensionality of the output,
    # aggregating the signals by combination of sample/timestep.
    # Resultant shape is (7352 train/2947 test samples, 128 timesteps,
    9 signals)
    return np.transpose(signals_data, (1, 2, 0))

```



```
In [0]: def load_y(subset):  
        """  
        The objective that we are trying to predict is a integer, from 1 to  
        6,  
        that represents a human activity. We return a binary representation  
        of  
        every sample objective as a 6 bits vector using One Hot Encoding  
        (https://pandas.pydata.org/pandas-docs/stable/generated/pandas.get\_  
        dummies.html)  
        """  
        filename = f'UCI_HAR_Dataset/{subset}/y_{subset}.txt'  
        y = _read_csv(filename)[0]  
  
        return pd.get_dummies(y).as_matrix()
```

```
In [0]: def load_data():  
        """  
        Obtain the dataset from multiple files.  
        Returns: X_train, X_test, y_train, y_test  
        """  
        X_train, X_test = load_signals('train'), load_signals('test')  
        y_train, y_test = load_y('train'), load_y('test')  
  
        return X_train, X_test, y_train, y_test
```

```
In [0]: import pandas as pd  
        import numpy as np
```

```
In [0]: # Importing tensorflow  
        np.random.seed(42)  
        import tensorflow as tf  
        tf.set_random_seed(42)
```

```
In [0]: # Configuring a session  
        session_conf = tf.ConfigProto(  
            intra_op_parallelism_threads=1,  
            inter_op_parallelism_threads=1  
        )
```

```
In [0]: # Import Keras
from keras import backend as K
sess = tf.Session(graph=tf.get_default_graph(), config=session_conf)
K.set_session(sess)
```

Using TensorFlow backend.

```
In [0]: # Importing libraries
from keras.models import Sequential
from keras.layers import LSTM
from keras.layers.core import Dense, Dropout
```

```
In [0]: # Initializing parameters
epochs = 25
batch_size = 16
n_hidden = [30, 50]
```

```
In [0]: # Utility function to count the number of classes
def _count_classes(y):
    return len(set([tuple(category) for category in y]))
```

```
In [0]: # Loading the train and test data
X_train, X_test, Y_train, Y_test = load_data()
```

```
In [0]: # Install the PyDrive wrapper & import libraries.
# This only needs to be done once per notebook.
!pip install -U -q PyDrive
from pydrive.auth import GoogleAuth
from pydrive.drive import GoogleDrive
from google.colab import auth
from oauth2client.client import GoogleCredentials

# Authenticate and create the PyDrive client.
# This only needs to be done once per notebook.
auth.authenticate_user()
gauth = GoogleAuth()
```

```

gauth.credentials = GoogleCredentials.get_application_default()
drive = GoogleDrive(gauth)

# Download a file based on its file ID.
#
# A file ID looks like: laggVyWshwcyP6kEI-y_W3P8D26sz
listed = drive.ListFile().GetList()
for file in listed:
    print('title {}, id {}'.format(file['title'], file['id']))

```

```

In [0]: download = drive.CreateFile({'id': '1YJG5KLOCG-AbqGd470DcByPMejsz-lTR'
})
download.GetContentFile('X_TEST.pkl')
#https://drive.google.com/open?id=1YJG5KLOCG-AbqGd470DcByPMejsz-lTR

```

```

In [0]: download = drive.CreateFile({'id': '1Qq8eUm6jJDjpi6MSkGL_9rZny3EllyBr'
})
download.GetContentFile('X_TRAIN.pkl')
#https://drive.google.com/open?id=1Qq8eUm6jJDjpi6MSkGL_9rZny3EllyBr

```

```

In [0]: download = drive.CreateFile({'id': '1drmq9jDPfw-EfeYfwU0gavSp4Uzeyhiu'
})
download.GetContentFile('Y_TEST.pkl')
#https://drive.google.com/open?id=1drmq9jDPfw-EfeYfwU0gavSp4Uzeyhiu

```

```

In [0]: download = drive.CreateFile({'id': '1tVKv9b_SGPu-c7ScdZTtMrL8Dr0z6Sez'
})
download.GetContentFile('Y_TRAIN.pkl')
#https://drive.google.com/open?id=1tVKv9b_SGPu-c7ScdZTtMrL8Dr0z6Sez

```

```

In [0]: import pickle

###Extract from file
with open("X_TRAIN.pkl","rb") as f:
    X_train = pickle.load(f)

###Extract from file

```

```
with open("X_TEST.pkl","rb") as f:
    X_test = pickle.load(f)

###Extract from file
with open("Y_TEST.pkl","rb") as f:
    Y_test = pickle.load(f)

###Extract from file
with open("Y_TRAIN.pkl","rb") as f:
    Y_train = pickle.load(f)
```

```
In [0]: timesteps = len(X_train[0])
input_dim = len(X_train[0][0])
n_classes = 6

print(timesteps)
print(input_dim)
print(len(X_train))
```

```
128
9
7352
```

```
In [0]: for i in n_hidden:
        print(i)
```

```
30
50
```

- Defining the Architecture of LSTM

DEEP LEARNING

N-HIDDEN=30,50

```
In [0]: for i in n_hidden: #(30 and 50)
        # Initiailizing the sequential model
        model = Sequential()
        # Configuring the parameters
        model.add(LSTM(i, input_shape=(timesteps, input_dim)))
        # Adding a dropout layer
        model.add(Dropout(0.5))
        # Adding a dense output layer with sigmoid activation
        model.add(Dense(n_classes, activation='sigmoid'))
        model.summary()

        # Compiling the model
        model.compile(loss='categorical_crossentropy',
                      optimizer='rmsprop',
                      metrics=['accuracy'])

        # Training the model
        model.fit(X_train,
                  Y_train,
                  batch_size=batch_size,
                  validation_data=(X_test, Y_test),
                  epochs=epochs)

        # Confusion Matrix
        print(confusion_matrix(Y_test, model.predict(X_test)))

        score = model.evaluate(X_test, Y_test)

        list=[]
        list.append(score)
        print(list)
```

WARNING: Logging before flag parsing goes to stderr.
W0903 06:18:22.929164 139936869062528 deprecation_wrapper.py:119] From
/usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The name tf.get_default_graph is deprecated. Please use tf.compat.v1.get_default_graph instead.

```
W0903 06:18:22.940048 139936869062528 deprecation_wrapper.py:119] From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:541: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.
```

```
W0903 06:18:22.951153 139936869062528 deprecation_wrapper.py:119] From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4432: The name tf.random_uniform is deprecated. Please use tf.random.uniform instead.
```

```
W0903 06:18:23.384014 139936869062528 deprecation_wrapper.py:119] From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:148: The name tf.placeholder_with_default is deprecated. Please use tf.compat.v1.placeholder_with_default instead.
```

```
W0903 06:18:23.391802 139936869062528 deprecation.py:506] From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3733: calling dropout (from tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.
```

Instructions for updating:

Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.

```
W0903 06:18:23.421131 139936869062528 deprecation_wrapper.py:119] From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.
```

```
W0903 06:18:23.438022 139936869062528 deprecation_wrapper.py:119] From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3576: The name tf.log is deprecated. Please use tf.math.log instead.
```

```
W0903 06:18:23.554906 139936869062528 deprecation.py:323] From /usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/math_grad.py:1250: add_dispatch_support.<locals>.wrapper (from tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.
```

Instructions for updating:

Use `tf.where` in 2.0, which has the same broadcast rule as `np.where`

Model: "sequential_1"

Layer (type)	Output Shape	Param #
lstm_1 (LSTM)	(None, 30)	4800
dropout_1 (Dropout)	(None, 30)	0
dense_1 (Dense)	(None, 6)	186

Total params: 4,986

Trainable params: 4,986

Non-trainable params: 0

Train on 7352 samples, validate on 2947 samples

Epoch 1/25

7352/7352 [=====] - 93s 13ms/step - loss: 1.30

72 - acc: 0.4499 - val_loss: 1.0075 - val_acc: 0.5182

Epoch 2/25

7352/7352 [=====] - 90s 12ms/step - loss: 0.92

83 - acc: 0.5471 - val_loss: 0.8425 - val_acc: 0.6067

Epoch 3/25

7352/7352 [=====] - 90s 12ms/step - loss: 0.79

73 - acc: 0.6023 - val_loss: 0.7585 - val_acc: 0.6281

Epoch 4/25

7352/7352 [=====] - 91s 12ms/step - loss: 0.74

05 - acc: 0.6748 - val_loss: 0.7687 - val_acc: 0.6783

Epoch 5/25

7352/7352 [=====] - 90s 12ms/step - loss: 0.63

90 - acc: 0.7380 - val_loss: 0.5709 - val_acc: 0.7323

Epoch 6/25

7352/7352 [=====] - 90s 12ms/step - loss: 0.54

27 - acc: 0.7726 - val_loss: 0.5818 - val_acc: 0.7435

Epoch 7/25

7352/7352 [=====] - 91s 12ms/step - loss: 0.48

31 - acc: 0.8016 - val_loss: 0.5420 - val_acc: 0.7631

Epoch 8/25

7352/7352 [=====] - 91s 12ms/step - loss: 0.43

```
96 - acc: 0.8464 - val_loss: 0.5268 - val_acc: 0.8314
Epoch 9/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.40
18 - acc: 0.8760 - val_loss: 0.5084 - val_acc: 0.8453
Epoch 10/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.33
74 - acc: 0.9067 - val_loss: 0.4317 - val_acc: 0.8622
Epoch 11/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.29
90 - acc: 0.9120 - val_loss: 0.3753 - val_acc: 0.8795
Epoch 12/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.27
79 - acc: 0.9170 - val_loss: 0.3683 - val_acc: 0.8826
Epoch 13/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.26
52 - acc: 0.9203 - val_loss: 0.3991 - val_acc: 0.8829
Epoch 14/25
7352/7352 [=====] - 92s 12ms/step - loss: 0.24
42 - acc: 0.9249 - val_loss: 0.3788 - val_acc: 0.8921
Epoch 15/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.23
86 - acc: 0.9267 - val_loss: 0.5145 - val_acc: 0.8711
Epoch 16/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.22
55 - acc: 0.9298 - val_loss: 0.3603 - val_acc: 0.8924
Epoch 17/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.20
58 - acc: 0.9370 - val_loss: 0.3801 - val_acc: 0.8904
Epoch 18/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.20
29 - acc: 0.9336 - val_loss: 0.4204 - val_acc: 0.8901
Epoch 19/25
7352/7352 [=====] - 90s 12ms/step - loss: 0.21
54 - acc: 0.9334 - val_loss: 0.5807 - val_acc: 0.8643
Epoch 20/25
7352/7352 [=====] - 90s 12ms/step - loss: 0.19
18 - acc: 0.9388 - val_loss: 0.4082 - val_acc: 0.9016
Epoch 21/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.18
```



```

10 - acc: 0.9425 - val_loss: 0.4189 - val_acc: 0.8975
Epoch 22/25
7352/7352 [=====] - 90s 12ms/step - loss: 0.20
48 - acc: 0.9421 - val_loss: 0.4531 - val_acc: 0.8982
Epoch 23/25
7352/7352 [=====] - 90s 12ms/step - loss: 0.19
14 - acc: 0.9362 - val_loss: 0.3639 - val_acc: 0.9009
Epoch 24/25
7352/7352 [=====] - 91s 12ms/step - loss: 0.16
85 - acc: 0.9437 - val_loss: 0.3534 - val_acc: 0.9016
Epoch 25/25
7352/7352 [=====] - 90s 12ms/step - loss: 0.18
16 - acc: 0.9440 - val_loss: 0.3404 - val_acc: 0.9043

```

```

-----
NameError                                Traceback (most recent call l
ast)
<ipython-input-29-106868b458e9> in <module>()
    23
    24     # Confusion Matrix
----> 25     print(confusion_matrix(Y_test, model.predict(X_test)))
    26
    27     score = model.evaluate(X_test, Y_test)

NameError: name 'confusion_matrix' is not defined

```

BATCH SIZE=20, H_HIDDEN=50

```

In [0]: batch_size = [20]

# Initiliazing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(50, input_shape=(timesteps, input_dim)))
# Adding a dropout layer

```

```

model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()
# Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='rmsprop',
              metrics=['accuracy'])

for i in batch_size:
    # Training the model
    model.fit(X_train,
              Y_train,
              batch_size=i,
              validation_data=(X_test, Y_test),
              epochs=30)

    # Confusion Matrix
    print(confusion_matrix(Y_test, model.predict(X_test)))

    score = model.evaluate(X_test, Y_test)

    list=[]
    list.append(score)
    print(list)

```

Layer (type)	Output Shape	Param #
lstm_8 (LSTM)	(None, 50)	12000
dropout_7 (Dropout)	(None, 50)	0
dense_7 (Dense)	(None, 6)	306
Total params: 12,306		
Trainable params: 12,306		
Non-trainable params: 0		
Train on 7352 samples, validate on 2947 samples		

```
Epoch 1/30
7352/7352 [=====] - 74s 10ms/step - loss: 1.34
31 - acc: 0.4056 - val_loss: 1.1828 - val_acc: 0.5049
Epoch 2/30
7352/7352 [=====] - 72s 10ms/step - loss: 1.00
37 - acc: 0.5652 - val_loss: 0.9445 - val_acc: 0.6468
Epoch 3/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.79
32 - acc: 0.6574 - val_loss: 0.8565 - val_acc: 0.6804
Epoch 4/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.65
49 - acc: 0.7248 - val_loss: 0.7232 - val_acc: 0.7143
Epoch 5/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.59
74 - acc: 0.7520 - val_loss: 0.7075 - val_acc: 0.6926
Epoch 6/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.53
72 - acc: 0.7968 - val_loss: 0.6315 - val_acc: 0.7845
Epoch 7/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.49
87 - acc: 0.8502 - val_loss: 0.5195 - val_acc: 0.8300
Epoch 8/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.34
65 - acc: 0.8938 - val_loss: 0.4937 - val_acc: 0.8476
Epoch 9/30
7352/7352 [=====] - 73s 10ms/step - loss: 0.30
41 - acc: 0.9063 - val_loss: 0.5530 - val_acc: 0.8354
Epoch 10/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.28
69 - acc: 0.9095 - val_loss: 0.6340 - val_acc: 0.8565
Epoch 11/30
7352/7352 [=====] - 71s 10ms/step - loss: 0.24
49 - acc: 0.9196 - val_loss: 0.4410 - val_acc: 0.8629
Epoch 12/30
7352/7352 [=====] - 71s 10ms/step - loss: 0.22
28 - acc: 0.9241 - val_loss: 0.9497 - val_acc: 0.7577
Epoch 13/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.21
95 - acc: 0.9263 - val_loss: 0.3575 - val_acc: 0.8839
```

```
Epoch 14/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.18
33 - acc: 0.9374 - val_loss: 0.3619 - val_acc: 0.9006
Epoch 15/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.19
32 - acc: 0.9363 - val_loss: 0.5092 - val_acc: 0.8907
Epoch 16/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.17
46 - acc: 0.9407 - val_loss: 0.4385 - val_acc: 0.8965
Epoch 17/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.16
80 - acc: 0.9412 - val_loss: 0.3242 - val_acc: 0.9030
Epoch 18/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.17
16 - acc: 0.9399 - val_loss: 0.4171 - val_acc: 0.9040
Epoch 19/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.17
39 - acc: 0.9415 - val_loss: 0.4158 - val_acc: 0.8955
Epoch 20/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.16
57 - acc: 0.9403 - val_loss: 1.0578 - val_acc: 0.8331
Epoch 21/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.13
81 - acc: 0.9461 - val_loss: 0.4731 - val_acc: 0.9030
Epoch 22/30
7352/7352 [=====] - 73s 10ms/step - loss: 0.14
00 - acc: 0.9508 - val_loss: 0.4512 - val_acc: 0.8979
Epoch 23/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.14
77 - acc: 0.9455 - val_loss: 0.4751 - val_acc: 0.9009
Epoch 24/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.14
80 - acc: 0.9498 - val_loss: 0.5375 - val_acc: 0.8931
Epoch 25/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.16
46 - acc: 0.9448 - val_loss: 0.3878 - val_acc: 0.9125
Epoch 26/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.14
66 - acc: 0.9478 - val_loss: 0.4435 - val_acc: 0.9023
```

```

Epoch 27/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.13
26 - acc: 0.9512 - val_loss: 0.4770 - val_acc: 0.8975
Epoch 28/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.15
91 - acc: 0.9490 - val_loss: 0.3613 - val_acc: 0.9108
Epoch 29/30
7352/7352 [=====] - 72s 10ms/step - loss: 0.15
19 - acc: 0.9426 - val_loss: 0.3667 - val_acc: 0.9118
Epoch 30/30
7352/7352 [=====] - 73s 10ms/step - loss: 0.13
74 - acc: 0.9520 - val_loss: 0.5077 - val_acc: 0.9043
Pred          LAYING  SITTING  ...  WALKING_DOWNSTAIRS  WALKING_U
PSTAIRS
True          ...

LAYING          535          0  ...          0
  2
SITTING          5        398  ...          0
  3
STANDING          0        106  ...          0
  0
WALKING          0          0  ...        33
  1
WALKING_DOWNSTAIRS  0          0  ...        419
  0
WALKING_UPSTAIRS    2          0  ...          6
429

[6 rows x 6 columns]
2947/2947 [=====] - 6s 2ms/step
[[0.5076741776222898, 0.9043094672548354]]

```

bias_initializer='zeros' AND N_HIDDEN=50

```

In [0]: for i in n_hidden: #50
        # Initiliazing the sequential model

```

```

model = Sequential()
# Configuring the parameters
model.add(LSTM(i, input_shape=(timesteps, input_dim)))
# Adding a dropout layer
model.add(Dropout(0.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid', bias_initializer='zeros'))
model.summary()

# Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='rmsprop',
              metrics=['accuracy'])

# Training the model
model.fit(X_train,
          Y_train,
          batch_size=batch_size,
          validation_data=(X_test, Y_test),
          epochs=epochs)

# Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))

score = model.evaluate(X_test, Y_test)

list=[]
list.append(score)
print(list)

```

Layer (type)	Output Shape	Param #
lstm_2 (LSTM)	(None, 30)	4800
dropout_2 (Dropout)	(None, 30)	0
dense_1 (Dense)	(None, 6)	186

Total params: 4,986
Trainable params: 4,986
Non-trainable params: 0

WARNING:tensorflow:From D:\python\lib\site-packages\tensorflow\python\ops\math_ops.py:3066: to_int32 (from tensorflow.python.ops.math_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.cast instead.

Train on 7352 samples, validate on 2947 samples

Epoch 1/25

7352/7352 [=====] - 59s 8ms/step - loss: 1.4098 - acc: 0.3658 - val_loss: 1.3462 - val_acc: 0.3848

Epoch 2/25

7352/7352 [=====] - 53s 7ms/step - loss: 1.1654 - acc: 0.4667 - val_loss: 1.1091 - val_acc: 0.4282

Epoch 3/25

7352/7352 [=====] - 55s 7ms/step - loss: 1.0362 - acc: 0.5080 - val_loss: 1.0004 - val_acc: 0.5114

Epoch 4/25

7352/7352 [=====] - 54s 7ms/step - loss: 0.8950 - acc: 0.5977 - val_loss: 0.9265 - val_acc: 0.5847

Epoch 5/25

7352/7352 [=====] - 55s 7ms/step - loss: 0.8338 - acc: 0.6235 - val_loss: 0.8451 - val_acc: 0.6060

Epoch 6/25

7352/7352 [=====] - 52s 7ms/step - loss: 0.7162 - acc: 0.6532 - val_loss: 0.8258 - val_acc: 0.5925

Epoch 7/25

7352/7352 [=====] - 51s 7ms/step - loss: 0.6668 - acc: 0.6736 - val_loss: 0.7662 - val_acc: 0.5969

Epoch 8/25

7352/7352 [=====] - 50s 7ms/step - loss: 0.6115 - acc: 0.7193 - val_loss: 0.6973 - val_acc: 0.6804

Epoch 9/25

7352/7352 [=====] - 50s 7ms/step - loss: 0.5873 - acc: 0.7844 - val_loss: 0.6832 - val_acc: 0.7886

Epoch 10/25

7352/7352 [=====] - 51s 7ms/step - loss: 0.582

```
5 - acc: 0.8044 - val_loss: 0.7368 - val_acc: 0.7455
Epoch 11/25
7352/7352 [=====] - 52s 7ms/step - loss: 0.513
3 - acc: 0.8414 - val_loss: 0.7064 - val_acc: 0.7852
Epoch 12/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.449
4 - acc: 0.8628 - val_loss: 0.7961 - val_acc: 0.7720
Epoch 13/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.414
7 - acc: 0.8717 - val_loss: 0.5192 - val_acc: 0.8402
Epoch 14/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.366
0 - acc: 0.8977 - val_loss: 0.4593 - val_acc: 0.8599
Epoch 15/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.341
6 - acc: 0.9074 - val_loss: 0.5251 - val_acc: 0.8497
Epoch 16/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.350
0 - acc: 0.8983 - val_loss: 0.4581 - val_acc: 0.8656
Epoch 17/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.285
3 - acc: 0.9180 - val_loss: 0.5698 - val_acc: 0.8351
Epoch 18/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.283
8 - acc: 0.9170 - val_loss: 0.6899 - val_acc: 0.8490
Epoch 19/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.283
3 - acc: 0.9151 - val_loss: 0.4440 - val_acc: 0.8731
Epoch 20/25
7352/7352 [=====] - 50s 7ms/step - loss: 0.222
8 - acc: 0.9305 - val_loss: 0.3845 - val_acc: 0.8765
Epoch 21/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.237
0 - acc: 0.9358 - val_loss: 0.4509 - val_acc: 0.8551
Epoch 22/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.321
6 - acc: 0.9086 - val_loss: 0.4348 - val_acc: 0.8775
Epoch 23/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.324
```



```

9 - acc: 0.9123 - val_loss: 0.5224 - val_acc: 0.8405
Epoch 24/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.253
0 - acc: 0.9274 - val_loss: 0.4417 - val_acc: 0.8863
Epoch 25/25
7352/7352 [=====] - 49s 7ms/step - loss: 0.281
4 - acc: 0.9170 - val_loss: 0.4307 - val_acc: 0.8785
Pred          LAYING  SITTING  STANDING  WALKING  WALKING_DOWNSTA
IRS \
True

LAYING          510          0          0          0
0
SITTING          0        395          92          0
0
STANDING          0        109         419          4
0
WALKING          0          2          2        463
13
WALKING_DOWNSTAIRS  0          3          0          9
399
WALKING_UPSTAIRS   0          3          4         59
2

Pred          WALKING_UPSTAIRS
True
LAYING          27
SITTING          4
STANDING          0
WALKING          16
WALKING_DOWNSTAIRS  9
WALKING_UPSTAIRS   403
2947/2947 [=====] - 2s 753us/step
[[0.4306884481576987, 0.8785205293518833]]

```

Layer (type)	Output Shape	Param #
lstm_3 (LSTM)	(None, 50)	12000

dropout_3 (Dropout)	(None, 50)	0
dense_2 (Dense)	(None, 6)	306

```

Total params: 12,306
Trainable params: 12,306
Non-trainable params: 0

```

```

Train on 7352 samples, validate on 2947 samples
Epoch 1/25
7352/7352 [=====] - 60s 8ms/step - loss: 1.327
4 - acc: 0.4211 - val_loss: 1.6261 - val_acc: 0.3756
Epoch 2/25
7352/7352 [=====] - 70s 9ms/step - loss: 0.986
7 - acc: 0.5717 - val_loss: 0.9573 - val_acc: 0.5650
Epoch 3/25
7352/7352 [=====] - 59s 8ms/step - loss: 0.751
0 - acc: 0.6778 - val_loss: 0.7629 - val_acc: 0.6709
Epoch 4/25
7352/7352 [=====] - 59s 8ms/step - loss: 0.627
3 - acc: 0.7360 - val_loss: 0.6046 - val_acc: 0.7648
Epoch 5/25
7352/7352 [=====] - 61s 8ms/step - loss: 0.527
2 - acc: 0.7750 - val_loss: 0.5351 - val_acc: 0.7520
Epoch 6/25
7352/7352 [=====] - 59s 8ms/step - loss: 0.476
5 - acc: 0.7982 - val_loss: 0.5932 - val_acc: 0.7689
Epoch 7/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.453
5 - acc: 0.8288 - val_loss: 0.4325 - val_acc: 0.8483
Epoch 8/25
7352/7352 [=====] - 59s 8ms/step - loss: 0.367
4 - acc: 0.8868 - val_loss: 0.3828 - val_acc: 0.8717
Epoch 9/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.270
8 - acc: 0.9104 - val_loss: 0.4445 - val_acc: 0.8768
Epoch 10/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.244
7 - acc: 0.9206 - val_loss: 0.3423 - val_acc: 0.8873

```

```
Epoch 11/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.222
6 - acc: 0.9272 - val_loss: 0.2954 - val_acc: 0.9060
Epoch 12/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.192
0 - acc: 0.9317 - val_loss: 0.3025 - val_acc: 0.8945
Epoch 13/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.211
0 - acc: 0.9332 - val_loss: 0.3361 - val_acc: 0.8795
Epoch 14/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.171
0 - acc: 0.9393 - val_loss: 0.2092 - val_acc: 0.9175
Epoch 15/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.182
3 - acc: 0.9362 - val_loss: 0.2753 - val_acc: 0.9043
Epoch 16/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.164
7 - acc: 0.9414 - val_loss: 0.3146 - val_acc: 0.8996
Epoch 17/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.153
2 - acc: 0.9444 - val_loss: 0.2999 - val_acc: 0.9074
Epoch 18/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.168
7 - acc: 0.9440 - val_loss: 0.3796 - val_acc: 0.9141
Epoch 19/25
7352/7352 [=====] - 55s 7ms/step - loss: 0.155
2 - acc: 0.9460 - val_loss: 0.5702 - val_acc: 0.8941
Epoch 20/25
7352/7352 [=====] - 55s 8ms/step - loss: 0.153
2 - acc: 0.9472 - val_loss: 0.3448 - val_acc: 0.9158
Epoch 21/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.163
6 - acc: 0.9438 - val_loss: 0.3222 - val_acc: 0.9138
Epoch 22/25
7352/7352 [=====] - 55s 7ms/step - loss: 0.160
2 - acc: 0.9448 - val_loss: 0.2972 - val_acc: 0.9148
Epoch 23/25
7352/7352 [=====] - 55s 8ms/step - loss: 0.153
1 - acc: 0.9450 - val_loss: 0.4835 - val_acc: 0.8948
```

```

Epoch 24/25
7352/7352 [=====] - 55s 8ms/step - loss: 0.139
3 - acc: 0.9494 - val_loss: 0.3466 - val_acc: 0.9226
Epoch 25/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.162
9 - acc: 0.9445 - val_loss: 0.2939 - val_acc: 0.9209
Pred          LAYING  SITTING  STANDING  WALKING  WALKING_DOWNSTA
IRS \
True

LAYING          537          0          0          0
0
SITTING          6        403          81          0
0
STANDING          0         92        440          0
0
WALKING          0          0          0        470
4
WALKING_DOWNSTAIRS  0          0          0          4
403
WALKING_UPSTAIRS   0          0          1          8
1

Pred          WALKING_UPSTAIRS
True
LAYING          0
SITTING          1
STANDING          0
WALKING          22
WALKING_DOWNSTAIRS 13
WALKING_UPSTAIRS  461
2947/2947 [=====] - 3s 861us/step
[[0.2939286813193747, 0.9209365456396336]]

```

**N_HIDDEN=50 AND
glorot_normal_INITIALIZER**

```
In [0]: for i in n_hidden: #50
        # Initiliazing the sequential model
        model = Sequential()
        # Configuring the parameters
        model.add(LSTM(i, input_shape=(timesteps, input_dim)))
        # Adding a dropout layer
        model.add(Dropout(0.5))
        # Adding a dense output layer with sigmoid activation
        model.add(Dense(n_classes, activation='sigmoid', kernel_initializer=
tf.keras.initializers.glorot_normal(seed=None)))
        model.summary()

        # Compiling the model
        model.compile(loss='categorical_crossentropy',
                      optimizer='rmsprop',
                      metrics=['accuracy'])

        # Training the model
        model.fit(X_train,
                  Y_train,
                  batch_size=batch_size,
                  validation_data=(X_test, Y_test),
                  epochs=epochs)

        # Confusion Matrix
        print(confusion_matrix(Y_test, model.predict(X_test)))

        score = model.evaluate(X_test, Y_test)

        list=[]
        list.append(score)
        print(list)
```

Layer (type)	Output Shape	Param #
lstm_7 (LSTM)	(None, 50)	12000
dropout_7 (Dropout)	(None, 50)	0

dense_4 (Dense)	(None, 6)	306
-----------------	-----------	-----

```

Total params: 12,306
Trainable params: 12,306
Non-trainable params: 0

```

WARNING:tensorflow:From D:\python\lib\site-packages\tensorflow\python\ops\math_ops.py:3066: to_int32 (from tensorflow.python.ops.math_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.cast instead.

Train on 7352 samples, validate on 2947 samples

Epoch 1/25

7352/7352 [=====] - 78s 11ms/step - loss: 1.2063 - acc: 0.4955 - val_loss: 1.0278 - val_acc: 0.5816

Epoch 2/25

7352/7352 [=====] - 56s 8ms/step - loss: 0.8347 - acc: 0.6310 - val_loss: 0.8318 - val_acc: 0.6081

Epoch 3/25

7352/7352 [=====] - 57s 8ms/step - loss: 0.7443 - acc: 0.6522 - val_loss: 0.7702 - val_acc: 0.6288

Epoch 4/25

7352/7352 [=====] - 58s 8ms/step - loss: 0.6688 - acc: 0.6997 - val_loss: 0.7439 - val_acc: 0.7167

Epoch 5/25

7352/7352 [=====] - 58s 8ms/step - loss: 0.5747 - acc: 0.7598 - val_loss: 0.5803 - val_acc: 0.7676

Epoch 6/25

7352/7352 [=====] - 57s 8ms/step - loss: 0.4927 - acc: 0.7964 - val_loss: 0.6355 - val_acc: 0.7621

Epoch 7/25

7352/7352 [=====] - 57s 8ms/step - loss: 0.4232 - acc: 0.8377 - val_loss: 0.5341 - val_acc: 0.8117

Epoch 8/25

7352/7352 [=====] - 60s 8ms/step - loss: 0.3566 - acc: 0.8868 - val_loss: 0.4469 - val_acc: 0.8588

Epoch 9/25

7352/7352 [=====] - 56s 8ms/step - loss: 0.2766 - acc: 0.9166 - val_loss: 0.6427 - val_acc: 0.8422

```

6 - acc: 0.9166 - val_loss: 0.6427 - val_acc: 0.8432
Epoch 10/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.243
1 - acc: 0.9230 - val_loss: 0.4285 - val_acc: 0.8585
Epoch 11/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.238
3 - acc: 0.9259 - val_loss: 0.4382 - val_acc: 0.8731
Epoch 12/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.214
1 - acc: 0.9347 - val_loss: 0.3263 - val_acc: 0.8924
Epoch 13/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.212
6 - acc: 0.9308 - val_loss: 0.4035 - val_acc: 0.8901
Epoch 14/25
7352/7352 [=====] - 56s 8ms/step - loss: 0.223
2 - acc: 0.9336 - val_loss: 0.3298 - val_acc: 0.8938
Epoch 15/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.215
9 - acc: 0.9323 - val_loss: 0.4234 - val_acc: 0.8850
Epoch 16/25
7352/7352 [=====] - 60s 8ms/step - loss: 0.197
4 - acc: 0.9343 - val_loss: 0.3042 - val_acc: 0.8975
Epoch 17/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.169
1 - acc: 0.9397 - val_loss: 0.3703 - val_acc: 0.8795
Epoch 18/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.181
2 - acc: 0.9395 - val_loss: 0.3291 - val_acc: 0.8911
Epoch 19/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.164
4 - acc: 0.9445 - val_loss: 0.3480 - val_acc: 0.8887
Epoch 20/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.154
0 - acc: 0.9427 - val_loss: 0.3574 - val_acc: 0.9135
Epoch 21/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.153
7 - acc: 0.9455 - val_loss: 0.4280 - val_acc: 0.9033
Epoch 22/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.162
2 - acc: 0.9452 - val_loss: 0.3307 - val_acc: 0.9026

```

```

3 - acc: 0.9453 - val_loss: 0.3307 - val_acc: 0.9026
Epoch 23/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.151
0 - acc: 0.9460 - val_loss: 0.4289 - val_acc: 0.8853
Epoch 24/25
7352/7352 [=====] - 57s 8ms/step - loss: 0.145
3 - acc: 0.9478 - val_loss: 0.4368 - val_acc: 0.8975
Epoch 25/25
7352/7352 [=====] - 58s 8ms/step - loss: 0.154
2 - acc: 0.9470 - val_loss: 0.4257 - val_acc: 0.9074
Pred          LAYING  SITTING  STANDING  WALKING  WALKING_DOWNSTA
IRS \
True

LAYING          510          0          27          0
0
SITTING          0         368         120          1
0
STANDING          0          57         473          2
0
WALKING          0          0          0         453
32
WALKING_DOWNSTAIRS  0          0          0          4
414
WALKING_UPSTAIRS   0          0          0         11
4

Pred          WALKING_UPSTAIRS
True
LAYING          0
SITTING          2
STANDING          0
WALKING         11
WALKING_DOWNSTAIRS  2
WALKING_UPSTAIRS  456
2947/2947 [=====] - 3s 1ms/step
[[0.4256824295249125, 0.9073634204275535]]

```


LSTM WITH 2-LAYERS

```
In [0]: # Initiailizing the sequential model
model = Sequential()
# Configuring the parameters
model.add(LSTM(50, return_sequences=True, input_shape=(timesteps, input_
dim)))
# Adding a dropout layer
model.add(Dropout(.5))
model.add(LSTM(50))
model.add(Dropout(.5))
# Adding a dense output layer with sigmoid activation
model.add(Dense(n_classes, activation='sigmoid'))
model.summary()

# Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='rmsprop',
              metrics=['accuracy'])

# Training the model
model.fit(X_train,
          Y_train,
          batch_size=batch_size,
          validation_data=(X_test, Y_test),
          epochs=epochs)

# Confusion Matrix
print(confusion_matrix(Y_test, model.predict(X_test)))

score = model.evaluate(X_test, Y_test)

list=[]
list.append(score)
print(list)
```

Layer (type)	Output Shape	Param #
lstm_16 (LSTM)	(None, 128, 50)	12000
dropout_9 (Dropout)	(None, 128, 50)	0
lstm_17 (LSTM)	(None, 50)	20200
dropout_10 (Dropout)	(None, 50)	0
dense_2 (Dense)	(None, 6)	306

Total params: 32,506
 Trainable params: 32,506
 Non-trainable params: 0

Layer (type)	Output Shape	Param #
lstm_16 (LSTM)	(None, 128, 50)	12000
dropout_9 (Dropout)	(None, 128, 50)	0
lstm_17 (LSTM)	(None, 50)	20200
dropout_10 (Dropout)	(None, 50)	0
dense_2 (Dense)	(None, 6)	306

Total params: 32,506
 Trainable params: 32,506
 Non-trainable params: 0

Train on 7352 samples, validate on 2947 samples
 Epoch 1/25
 Train on 7352 samples, validate on 2947 samples
 Epoch 1/25
 7352/7352 [=====] - 236s 32ms/step - loss: 1.1
 162 - acc: 0.5326 - val_loss: 0.9879 - val_acc: 0.6023

```
7352/7352 [=====] - 236s 32ms/step - loss: 1.1
162 - acc: 0.5326 - val_loss: 0.9879 - val_acc: 0.6023
Epoch 2/25
Epoch 2/25
7352/7352 [=====] - 147s 20ms/step - loss: 0.8
107 - acc: 0.6485 - val_loss: 0.8378 - val_acc: 0.6040
7352/7352 [=====] - 147s 20ms/step - loss: 0.8
107 - acc: 0.6485 - val_loss: 0.8378 - val_acc: 0.6040
Epoch 3/25
Epoch 3/25
7352/7352 [=====] - 149s 20ms/step - loss: 0.6
691 - acc: 0.6957 - val_loss: 0.6748 - val_acc: 0.7441
7352/7352 [=====] - 149s 20ms/step - loss: 0.6
691 - acc: 0.6957 - val_loss: 0.6748 - val_acc: 0.7441
Epoch 4/25
Epoch 4/25
7352/7352 [=====] - 160s 22ms/step - loss: 0.5
420 - acc: 0.7731 - val_loss: 0.6125 - val_acc: 0.7981
7352/7352 [=====] - 160s 22ms/step - loss: 0.5
420 - acc: 0.7731 - val_loss: 0.6125 - val_acc: 0.7981
Epoch 5/25
Epoch 5/25
7352/7352 [=====] - 146s 20ms/step - loss: 0.3
740 - acc: 0.8758 - val_loss: 0.6913 - val_acc: 0.7981
7352/7352 [=====] - 146s 20ms/step - loss: 0.3
740 - acc: 0.8758 - val_loss: 0.6913 - val_acc: 0.7981
Epoch 6/25
Epoch 6/25
7352/7352 [=====] - 152s 21ms/step - loss: 0.2
496 - acc: 0.9240 - val_loss: 0.6027 - val_acc: 0.8643
7352/7352 [=====] - 152s 21ms/step - loss: 0.2
496 - acc: 0.9240 - val_loss: 0.6027 - val_acc: 0.8643
Epoch 7/25
Epoch 7/25
7352/7352 [=====] - 154s 21ms/step - loss: 0.2
250 - acc: 0.9310 - val_loss: 0.3931 - val_acc: 0.8965
7352/7352 [=====] - 154s 21ms/step - loss: 0.2
250 - acc: 0.9310 - val_loss: 0.3931 - val_acc: 0.8965
Epoch 8/25
```

```
Epoch 8/25
7352/7352 [=====] - 152s 21ms/step - loss: 0.1
856 - acc: 0.9376 - val_loss: 0.3672 - val_acc: 0.8904
7352/7352 [=====] - 152s 21ms/step - loss: 0.1
856 - acc: 0.9376 - val_loss: 0.3672 - val_acc: 0.8904
Epoch 9/25
Epoch 9/25
7352/7352 [=====] - 144s 20ms/step - loss: 0.1
922 - acc: 0.9353 - val_loss: 0.4644 - val_acc: 0.8775
7352/7352 [=====] - 144s 20ms/step - loss: 0.1
922 - acc: 0.9353 - val_loss: 0.4644 - val_acc: 0.8775
Epoch 10/25
Epoch 10/25
7352/7352 [=====] - 141s 19ms/step - loss: 0.1
834 - acc: 0.9353 - val_loss: 0.4322 - val_acc: 0.8809
7352/7352 [=====] - 141s 19ms/step - loss: 0.1
834 - acc: 0.9353 - val_loss: 0.4322 - val_acc: 0.8809
Epoch 11/25
Epoch 11/25
7352/7352 [=====] - 143s 20ms/step - loss: 0.1
639 - acc: 0.9421 - val_loss: 0.3816 - val_acc: 0.8955
7352/7352 [=====] - 143s 20ms/step - loss: 0.1
639 - acc: 0.9421 - val_loss: 0.3816 - val_acc: 0.8955
Epoch 12/25
Epoch 12/25
7352/7352 [=====] - 146s 20ms/step - loss: 0.1
558 - acc: 0.9501 - val_loss: 0.3931 - val_acc: 0.9002
7352/7352 [=====] - 146s 20ms/step - loss: 0.1
558 - acc: 0.9501 - val_loss: 0.3931 - val_acc: 0.9002
Epoch 13/25
Epoch 13/25
7352/7352 [=====] - 148s 20ms/step - loss: 0.1
516 - acc: 0.9497 - val_loss: 0.3951 - val_acc: 0.9009
7352/7352 [=====] - 148s 20ms/step - loss: 0.1
516 - acc: 0.9497 - val_loss: 0.3951 - val_acc: 0.9009
Epoch 14/25
Epoch 14/25
7352/7352 [=====] - 152s 21ms/step - loss: 0.1
467 - acc: 0.9479 - val_loss: 0.5332 - val_acc: 0.8816
```

```
7352/7352 [=====] - 152s 21ms/step - loss: 0.1
467 - acc: 0.9479 - val_loss: 0.5332 - val_acc: 0.8816
Epoch 15/25
Epoch 15/25
7352/7352 [=====] - 149s 20ms/step - loss: 0.1
440 - acc: 0.9490 - val_loss: 0.4251 - val_acc: 0.8955
7352/7352 [=====] - 149s 20ms/step - loss: 0.1
440 - acc: 0.9490 - val_loss: 0.4251 - val_acc: 0.8955
Epoch 16/25
Epoch 16/25
7352/7352 [=====] - 158s 21ms/step - loss: 0.1
683 - acc: 0.9456 - val_loss: 0.4568 - val_acc: 0.9016
7352/7352 [=====] - 158s 21ms/step - loss: 0.1
683 - acc: 0.9456 - val_loss: 0.4568 - val_acc: 0.9016
Epoch 17/25
Epoch 17/25
7352/7352 [=====] - 142s 19ms/step - loss: 0.1
586 - acc: 0.9467 - val_loss: 0.3375 - val_acc: 0.8948
7352/7352 [=====] - 142s 19ms/step - loss: 0.1
586 - acc: 0.9467 - val_loss: 0.3375 - val_acc: 0.8948
Epoch 18/25
Epoch 18/25
7352/7352 [=====] - 147s 20ms/step - loss: 0.1
600 - acc: 0.9506 - val_loss: 0.6291 - val_acc: 0.8901
7352/7352 [=====] - 147s 20ms/step - loss: 0.1
600 - acc: 0.9506 - val_loss: 0.6291 - val_acc: 0.8901
Epoch 19/25
Epoch 19/25
7352/7352 [=====] - 157s 21ms/step - loss: 0.1
359 - acc: 0.9509 - val_loss: 0.4796 - val_acc: 0.9080
7352/7352 [=====] - 157s 21ms/step - loss: 0.1
359 - acc: 0.9509 - val_loss: 0.4796 - val_acc: 0.9080
Epoch 20/25
Epoch 20/25
7352/7352 [=====] - 166s 23ms/step - loss: 0.1
481 - acc: 0.9475 - val_loss: 0.3207 - val_acc: 0.9162
7352/7352 [=====] - 166s 23ms/step - loss: 0.1
481 - acc: 0.9475 - val_loss: 0.3207 - val_acc: 0.9162
Epoch 21/25
```

```

Epoch 21/25
7352/7352 [=====] - 155s 21ms/step - loss: 0.1
410 - acc: 0.9499 - val_loss: 0.3656 - val_acc: 0.9070
7352/7352 [=====] - 155s 21ms/step - loss: 0.1
410 - acc: 0.9499 - val_loss: 0.3656 - val_acc: 0.9070
Epoch 22/25
Epoch 22/25
7352/7352 [=====] - 137s 19ms/step - loss: 0.1
356 - acc: 0.9504 - val_loss: 0.4651 - val_acc: 0.9033
7352/7352 [=====] - 137s 19ms/step - loss: 0.1
356 - acc: 0.9504 - val_loss: 0.4651 - val_acc: 0.9033
Epoch 23/25
Epoch 23/25
7352/7352 [=====] - 153s 21ms/step - loss: 0.1
428 - acc: 0.9494 - val_loss: 0.4361 - val_acc: 0.8962
7352/7352 [=====] - 153s 21ms/step - loss: 0.1
428 - acc: 0.9494 - val_loss: 0.4361 - val_acc: 0.8962
Epoch 24/25
Epoch 24/25
7352/7352 [=====] - 155s 21ms/step - loss: 0.1
389 - acc: 0.9512 - val_loss: 0.3655 - val_acc: 0.9118
7352/7352 [=====] - 155s 21ms/step - loss: 0.1
389 - acc: 0.9512 - val_loss: 0.3655 - val_acc: 0.9118
Epoch 25/25
Epoch 25/25
7352/7352 [=====] - 168s 23ms/step - loss: 0.1
382 - acc: 0.9513 - val_loss: 0.3222 - val_acc: 0.9141
7352/7352 [=====] - 168s 23ms/step - loss: 0.1
382 - acc: 0.9513 - val_loss: 0.3222 - val_acc: 0.9141
Pred          LAYING  SITTING  STANDING  WALKING  WALKING_DOWNSTA
IRS \
True

LAYING          509          0          27          0
  1
SITTING          1        380        108          0
  1
STANDING          0         62        470          0
  0

```

WALKING	0	1	1	484
5				
WALKING_DOWNSTAIRS	0	0	0	3
407				
WALKING_UPSTAIRS	0	1	2	10
14				

Pred WALKING_UPSTAIRS

True

LAYING	0
SITTING	1
STANDING	0
WALKING	5
WALKING_DOWNSTAIRS	10
WALKING_UPSTAIRS	444

32/2947 [.....] - ETA: 8sPred

LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS	\
True					

LAYING	509	0	27	0
1				
SITTING	1	380	108	0
1				
STANDING	0	62	470	0
0				
WALKING	0	1	1	484
5				
WALKING_DOWNSTAIRS	0	0	0	3
407				
WALKING_UPSTAIRS	0	1	2	10
14				

Pred WALKING_UPSTAIRS

True

LAYING	0
SITTING	1
STANDING	0
WALKING	5
WALKING_DOWNSTAIRS	10

```
WALKING_UPSTAIRS                                444
2947/2947 [=====] - 12s 4ms/step
2947/2947 [=====] - 12s 4ms/step
[[0.32220571241385143, 0.9141499830335935]]
[[0.32220571241385143, 0.9141499830335935]]
```

CNN

```
In [0]: # Initiliazing the sequential model
model = Sequential()
model.add(Conv1D(filters=300, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))
model.add(MaxPooling1D(pool_size=15))
#model.add(Conv1D(filters=70, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))

#model.add(MaxPooling1D(pool_size=9))
#model.add(Dropout(0.7))
#Configuring the parameters
#model.add(LSTM(50, input_shape=(timesteps, input_dim)))
#model.add(Dropout(0.6))
# Adding a dropout layer
# Adding a dense output layer with sigmoid activation
model.add(Flatten())
model.add(Dense(n_classes, activation='sigmoid'))

model.summary()
```

Layer (type)	Output Shape	Param #
conv1d_22 (Conv1D)	(None, 128, 300)	40800
max_pooling1d_21 (MaxPooling)	(None, 8, 300)	0
flatten_21 (Flatten)	(None, 2400)	0


```
dense_21 (Dense)                (None, 6)                14406
=====
Total params: 55,206
Trainable params: 55,206
Non-trainable params: 0
```

```
In [0]: # Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='adamax',
              metrics=['accuracy'])
```

```
In [0]: # Training the model
model.fit(X_train,
          Y_train,
          batch_size=10,
          validation_data=(X_test, Y_test),
          epochs=50)
```

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/50
7352/7352 [=====] - 4s 542us/step - loss: 1.22
71 - acc: 0.4486 - val_loss: 0.5731 - val_acc: 0.8517
Epoch 2/50
7352/7352 [=====] - 3s 390us/step - loss: 0.25
75 - acc: 0.9233 - val_loss: 0.3177 - val_acc: 0.9006
Epoch 3/50
7352/7352 [=====] - 3s 387us/step - loss: 0.16
82 - acc: 0.9421 - val_loss: 0.2805 - val_acc: 0.9067
Epoch 4/50
7352/7352 [=====] - 3s 388us/step - loss: 0.14
23 - acc: 0.9449 - val_loss: 0.2365 - val_acc: 0.9108
Epoch 5/50
7352/7352 [=====] - 3s 390us/step - loss: 0.13
57 - acc: 0.9465 - val_loss: 0.2707 - val_acc: 0.8979
Epoch 6/50
7352/7352 [=====] - 3s 388us/step - loss: 0.12
68 - acc: 0.9494 - val_loss: 0.2305 - val_acc: 0.9257
Epoch 7/50
```

```
7352/7352 [=====] - 3s 386us/step - loss: 0.12
26 - acc: 0.9484 - val_loss: 0.2421 - val_acc: 0.9125
Epoch 8/50
7352/7352 [=====] - 3s 392us/step - loss: 0.12
13 - acc: 0.9467 - val_loss: 0.2568 - val_acc: 0.9175
Epoch 9/50
7352/7352 [=====] - 3s 393us/step - loss: 0.11
66 - acc: 0.9506 - val_loss: 0.2266 - val_acc: 0.9206
Epoch 10/50
7352/7352 [=====] - 3s 390us/step - loss: 0.11
50 - acc: 0.9494 - val_loss: 0.2331 - val_acc: 0.9203
Epoch 11/50
7352/7352 [=====] - 3s 390us/step - loss: 0.11
41 - acc: 0.9478 - val_loss: 0.2182 - val_acc: 0.9247
Epoch 12/50
7352/7352 [=====] - 3s 384us/step - loss: 0.11
15 - acc: 0.9490 - val_loss: 0.2190 - val_acc: 0.9216
Epoch 13/50
7352/7352 [=====] - 3s 390us/step - loss: 0.11
19 - acc: 0.9490 - val_loss: 0.2322 - val_acc: 0.9199
Epoch 14/50
7352/7352 [=====] - 3s 408us/step - loss: 0.10
92 - acc: 0.9498 - val_loss: 0.2107 - val_acc: 0.9294
Epoch 15/50
7352/7352 [=====] - 3s 409us/step - loss: 0.10
82 - acc: 0.9505 - val_loss: 0.2201 - val_acc: 0.9199
Epoch 16/50
7352/7352 [=====] - 3s 411us/step - loss: 0.10
91 - acc: 0.9478 - val_loss: 0.2086 - val_acc: 0.9226
Epoch 17/50
7352/7352 [=====] - 3s 403us/step - loss: 0.10
57 - acc: 0.9484 - val_loss: 0.2032 - val_acc: 0.9301
Epoch 18/50
7352/7352 [=====] - 3s 388us/step - loss: 0.10
51 - acc: 0.9529 - val_loss: 0.2072 - val_acc: 0.9203
Epoch 19/50
7352/7352 [=====] - 3s 385us/step - loss: 0.10
08 - acc: 0.9531 - val_loss: 0.2413 - val_acc: 0.9281
Epoch 20/50
```

```
7352/7352 [=====] - 3s 386us/step - loss: 0.10
28 - acc: 0.9557 - val_loss: 0.2084 - val_acc: 0.9277
Epoch 21/50
7352/7352 [=====] - 3s 386us/step - loss: 0.10
29 - acc: 0.9531 - val_loss: 0.1996 - val_acc: 0.9287
Epoch 22/50
7352/7352 [=====] - 3s 386us/step - loss: 0.10
03 - acc: 0.9540 - val_loss: 0.2049 - val_acc: 0.9237
Epoch 23/50
7352/7352 [=====] - 3s 384us/step - loss: 0.09
84 - acc: 0.9547 - val_loss: 0.2078 - val_acc: 0.9226
Epoch 24/50
7352/7352 [=====] - 3s 387us/step - loss: 0.09
93 - acc: 0.9558 - val_loss: 0.2227 - val_acc: 0.9230
Epoch 25/50
7352/7352 [=====] - 3s 384us/step - loss: 0.09
68 - acc: 0.9566 - val_loss: 0.2097 - val_acc: 0.9179
Epoch 26/50
7352/7352 [=====] - 3s 384us/step - loss: 0.09
53 - acc: 0.9547 - val_loss: 0.2080 - val_acc: 0.9274
Epoch 27/50
7352/7352 [=====] - 3s 387us/step - loss: 0.09
56 - acc: 0.9569 - val_loss: 0.1902 - val_acc: 0.9301
Epoch 28/50
7352/7352 [=====] - 3s 389us/step - loss: 0.09
47 - acc: 0.9565 - val_loss: 0.2011 - val_acc: 0.9260
Epoch 29/50
7352/7352 [=====] - 3s 387us/step - loss: 0.09
33 - acc: 0.9573 - val_loss: 0.2121 - val_acc: 0.9216
Epoch 30/50
7352/7352 [=====] - 3s 388us/step - loss: 0.09
17 - acc: 0.9570 - val_loss: 0.2003 - val_acc: 0.9216
Epoch 31/50
7352/7352 [=====] - 3s 392us/step - loss: 0.09
07 - acc: 0.9589 - val_loss: 0.2169 - val_acc: 0.9189
Epoch 32/50
7352/7352 [=====] - 3s 388us/step - loss: 0.08
84 - acc: 0.9603 - val_loss: 0.1968 - val_acc: 0.9257
Epoch 33/50
```

```
7352/7352 [=====] - 3s 386us/step - loss: 0.08
79 - acc: 0.9603 - val_loss: 0.2100 - val_acc: 0.9264
Epoch 34/50
7352/7352 [=====] - 3s 387us/step - loss: 0.08
67 - acc: 0.9604 - val_loss: 0.2015 - val_acc: 0.9230
Epoch 35/50
7352/7352 [=====] - 3s 389us/step - loss: 0.08
52 - acc: 0.9611 - val_loss: 0.1967 - val_acc: 0.9260
Epoch 36/50
7352/7352 [=====] - 3s 391us/step - loss: 0.08
34 - acc: 0.9610 - val_loss: 0.1905 - val_acc: 0.9267
Epoch 37/50
7352/7352 [=====] - 3s 389us/step - loss: 0.08
44 - acc: 0.9612 - val_loss: 0.1909 - val_acc: 0.9253
Epoch 38/50
7352/7352 [=====] - 3s 388us/step - loss: 0.07
99 - acc: 0.9629 - val_loss: 0.2035 - val_acc: 0.9223
Epoch 39/50
7352/7352 [=====] - 3s 390us/step - loss: 0.07
96 - acc: 0.9633 - val_loss: 0.1967 - val_acc: 0.9328
Epoch 40/50
7352/7352 [=====] - 3s 390us/step - loss: 0.07
92 - acc: 0.9645 - val_loss: 0.2069 - val_acc: 0.9223
Epoch 41/50
7352/7352 [=====] - 3s 385us/step - loss: 0.07
73 - acc: 0.9656 - val_loss: 0.2352 - val_acc: 0.9203
Epoch 42/50
7352/7352 [=====] - 3s 390us/step - loss: 0.07
76 - acc: 0.9631 - val_loss: 0.1964 - val_acc: 0.9294
Epoch 43/50
7352/7352 [=====] - 3s 385us/step - loss: 0.07
43 - acc: 0.9675 - val_loss: 0.2191 - val_acc: 0.9203
Epoch 44/50
7352/7352 [=====] - 3s 385us/step - loss: 0.07
47 - acc: 0.9664 - val_loss: 0.1891 - val_acc: 0.9355
Epoch 45/50
7352/7352 [=====] - 3s 386us/step - loss: 0.07
16 - acc: 0.9664 - val_loss: 0.2050 - val_acc: 0.9253
Epoch 46/50
```

```

7352/7352 [=====] - 3s 389us/step - loss: 0.07
33 - acc: 0.9656 - val_loss: 0.2120 - val_acc: 0.9277
Epoch 47/50
7352/7352 [=====] - 3s 385us/step - loss: 0.07
04 - acc: 0.9682 - val_loss: 0.1898 - val_acc: 0.9308
Epoch 48/50
7352/7352 [=====] - 3s 385us/step - loss: 0.06
96 - acc: 0.9678 - val_loss: 0.1956 - val_acc: 0.9294
Epoch 49/50
7352/7352 [=====] - 3s 388us/step - loss: 0.06
75 - acc: 0.9682 - val_loss: 0.1868 - val_acc: 0.9277
Epoch 50/50
7352/7352 [=====] - 3s 389us/step - loss: 0.06
82 - acc: 0.9699 - val_loss: 0.1671 - val_acc: 0.9433

```

Out[0]: <keras.callbacks.History at 0x7fa9b4cecba8>

```

In [0]: # Confusion Matrix
# print(confusion_matrix(Y_test, model.predict(X_test)))
conf = pd.DataFrame(confusion_matrix(Y_test, model.predict(X_test)))
conf

```

Out[0]:

	Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTA
True						
LAYING		534	0	0	0	0
SITTING		0	420	67	2	0
STANDING		0	52	480	0	0
WALKING		0	0	0	492	1
WALKING_DOWNSTAIRS		0	0	0	1	406
WALKING_UPSTAIRS		0	12	0	1	10

```

In [0]: score = model.evaluate(X_test, Y_test)

```

2947/2947 [=====] - 0s 77us/step

In [0]: score

Out[0]: [0.16710662225743034, 0.9433322022395657]

In [0]: score_train = model.evaluate(X_train, Y_train)
score_train

7352/7352 [=====] - 1s 96us/step

Out[0]: [0.06354207507458427, 0.9729325353645266]

2- layers of CNN

```
In [0]: # Initiliazing the sequential model
model = Sequential()
model.add(Conv1D(filters=300, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))
model.add(MaxPooling1D(pool_size=15))
model.add(Conv1D(filters=70, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))
#model.add(MaxPooling1D(pool_size=9))
#model.add(Dropout(0.7))
#Configuring the parameters
#model.add(LSTM(50, input_shape=(timesteps, input_dim)))
#model.add(Dropout(0.6))
# Adding a dropout layer
# Adding a dense output layer with sigmoid activation
model.add(Flatten())
model.add(Dense(n_classes, activation='sigmoid'))

model.summary()
```

Layer (type)	Output Shape	Param #
--------------	--------------	---------

conv1d_25 (Conv1D)	(None, 128, 300)	40800
max_pooling1d_24 (MaxPooling)	(None, 8, 300)	0
conv1d_26 (Conv1D)	(None, 8, 70)	315070
flatten_22 (Flatten)	(None, 560)	0
dense_22 (Dense)	(None, 6)	3366
=====		
Total params: 359,236		
Trainable params: 359,236		
Non-trainable params: 0		
=====		

```
In [0]: # Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='adamax',
              metrics=['accuracy'])
```

```
In [0]: # Training the model
model.fit(X_train,
          Y_train,
          batch_size=10,
          validation_data=(X_test, Y_test),
          epochs=50)
```

```
Train on 7352 samples, validate on 2947 samples
Epoch 1/50
7352/7352 [=====] - 5s 630us/step - loss: 1.30
05 - acc: 0.3883 - val_loss: 0.8273 - val_acc: 0.6753
Epoch 2/50
7352/7352 [=====] - 3s 446us/step - loss: 0.46
85 - acc: 0.8134 - val_loss: 0.4067 - val_acc: 0.8677
Epoch 3/50
7352/7352 [=====] - 3s 452us/step - loss: 0.19
04 - acc: 0.9312 - val_loss: 0.2962 - val_acc: 0.8958
Epoch 4/50
7352/7352 [=====] - 3s 454us/step - loss: 0.16
```

```
20 - acc: 0.9353 - val_loss: 0.4242 - val_acc: 0.8273
Epoch 5/50
7352/7352 [=====] - 3s 449us/step - loss: 0.14
03 - acc: 0.9438 - val_loss: 0.2267 - val_acc: 0.9074
Epoch 6/50
7352/7352 [=====] - 3s 452us/step - loss: 0.13
18 - acc: 0.9461 - val_loss: 0.2307 - val_acc: 0.9135
Epoch 7/50
7352/7352 [=====] - 3s 447us/step - loss: 0.12
42 - acc: 0.9508 - val_loss: 0.2210 - val_acc: 0.9063
Epoch 8/50
7352/7352 [=====] - 3s 450us/step - loss: 0.12
30 - acc: 0.9493 - val_loss: 0.2101 - val_acc: 0.9108
Epoch 9/50
7352/7352 [=====] - 3s 446us/step - loss: 0.11
68 - acc: 0.9506 - val_loss: 0.2306 - val_acc: 0.9087
Epoch 10/50
7352/7352 [=====] - 3s 449us/step - loss: 0.11
41 - acc: 0.9533 - val_loss: 0.2078 - val_acc: 0.9141
Epoch 11/50
7352/7352 [=====] - 3s 449us/step - loss: 0.11
29 - acc: 0.9535 - val_loss: 0.2381 - val_acc: 0.9084
Epoch 12/50
7352/7352 [=====] - 3s 448us/step - loss: 0.11
20 - acc: 0.9532 - val_loss: 0.2005 - val_acc: 0.9209
Epoch 13/50
7352/7352 [=====] - 3s 453us/step - loss: 0.10
88 - acc: 0.9525 - val_loss: 0.2118 - val_acc: 0.9162
Epoch 14/50
7352/7352 [=====] - 3s 450us/step - loss: 0.10
81 - acc: 0.9539 - val_loss: 0.2998 - val_acc: 0.9043
Epoch 15/50
7352/7352 [=====] - 3s 448us/step - loss: 0.10
51 - acc: 0.9553 - val_loss: 0.1967 - val_acc: 0.9267
Epoch 16/50
7352/7352 [=====] - 3s 450us/step - loss: 0.10
29 - acc: 0.9567 - val_loss: 0.2115 - val_acc: 0.9192
Epoch 17/50
7352/7352 [=====] - 3s 452us/step - loss: 0.10
```



```
25 - acc: 0.9570 - val_loss: 0.2075 - val_acc: 0.9199
Epoch 18/50
7352/7352 [=====] - 3s 449us/step - loss: 0.10
07 - acc: 0.9562 - val_loss: 0.2361 - val_acc: 0.9186
Epoch 19/50
7352/7352 [=====] - 3s 450us/step - loss: 0.09
95 - acc: 0.9547 - val_loss: 0.2167 - val_acc: 0.9223
Epoch 20/50
7352/7352 [=====] - 3s 451us/step - loss: 0.09
62 - acc: 0.9563 - val_loss: 0.2410 - val_acc: 0.9135
Epoch 21/50
7352/7352 [=====] - 3s 447us/step - loss: 0.09
57 - acc: 0.9577 - val_loss: 0.2287 - val_acc: 0.9128
Epoch 22/50
7352/7352 [=====] - 3s 448us/step - loss: 0.09
26 - acc: 0.9597 - val_loss: 0.2431 - val_acc: 0.9141
Epoch 23/50
7352/7352 [=====] - 3s 447us/step - loss: 0.09
08 - acc: 0.9603 - val_loss: 0.2083 - val_acc: 0.9325
Epoch 24/50
7352/7352 [=====] - 3s 451us/step - loss: 0.09
00 - acc: 0.9606 - val_loss: 0.2402 - val_acc: 0.9182
Epoch 25/50
7352/7352 [=====] - 3s 449us/step - loss: 0.08
65 - acc: 0.9595 - val_loss: 0.2466 - val_acc: 0.9162
Epoch 26/50
7352/7352 [=====] - 3s 448us/step - loss: 0.08
42 - acc: 0.9629 - val_loss: 0.2298 - val_acc: 0.9182
Epoch 27/50
7352/7352 [=====] - 3s 450us/step - loss: 0.08
54 - acc: 0.9631 - val_loss: 0.2572 - val_acc: 0.9169
Epoch 28/50
7352/7352 [=====] - 3s 447us/step - loss: 0.08
08 - acc: 0.9604 - val_loss: 0.2706 - val_acc: 0.9189
Epoch 29/50
7352/7352 [=====] - 3s 448us/step - loss: 0.07
85 - acc: 0.9644 - val_loss: 0.2323 - val_acc: 0.9169
Epoch 30/50
7352/7352 [=====] - 3s 454us/step - loss: 0.07
```

```
77 - acc: 0.9622 - val_loss: 0.2699 - val_acc: 0.9179
Epoch 31/50
7352/7352 [=====] - 3s 451us/step - loss: 0.07
50 - acc: 0.9650 - val_loss: 0.2286 - val_acc: 0.9291
Epoch 32/50
7352/7352 [=====] - 3s 449us/step - loss: 0.07
57 - acc: 0.9635 - val_loss: 0.2430 - val_acc: 0.9230
Epoch 33/50
7352/7352 [=====] - 3s 453us/step - loss: 0.07
46 - acc: 0.9630 - val_loss: 0.2714 - val_acc: 0.9097
Epoch 34/50
7352/7352 [=====] - 3s 452us/step - loss: 0.07
14 - acc: 0.9674 - val_loss: 0.2597 - val_acc: 0.9206
Epoch 35/50
7352/7352 [=====] - 3s 446us/step - loss: 0.06
86 - acc: 0.9689 - val_loss: 0.2425 - val_acc: 0.9311
Epoch 36/50
7352/7352 [=====] - 3s 451us/step - loss: 0.06
69 - acc: 0.9680 - val_loss: 0.2777 - val_acc: 0.9141
Epoch 37/50
7352/7352 [=====] - 3s 447us/step - loss: 0.06
71 - acc: 0.9689 - val_loss: 0.2681 - val_acc: 0.9260
Epoch 38/50
7352/7352 [=====] - 3s 448us/step - loss: 0.06
43 - acc: 0.9708 - val_loss: 0.2755 - val_acc: 0.9230
Epoch 39/50
7352/7352 [=====] - 3s 452us/step - loss: 0.06
26 - acc: 0.9709 - val_loss: 0.2591 - val_acc: 0.9304
Epoch 40/50
7352/7352 [=====] - 3s 447us/step - loss: 0.06
20 - acc: 0.9721 - val_loss: 0.2838 - val_acc: 0.9213
Epoch 41/50
7352/7352 [=====] - 3s 448us/step - loss: 0.06
08 - acc: 0.9713 - val_loss: 0.3815 - val_acc: 0.8989
Epoch 42/50
7352/7352 [=====] - 3s 453us/step - loss: 0.05
78 - acc: 0.9713 - val_loss: 0.2855 - val_acc: 0.9253
Epoch 43/50
7352/7352 [=====] - 3s 456us/step - loss: 0.05
```

```

83 - acc: 0.9717 - val_loss: 0.2754 - val_acc: 0.9325
Epoch 44/50
7352/7352 [=====] - 3s 450us/step - loss: 0.05
67 - acc: 0.9744 - val_loss: 0.2670 - val_acc: 0.9226
Epoch 45/50
7352/7352 [=====] - 3s 444us/step - loss: 0.05
58 - acc: 0.9750 - val_loss: 0.2887 - val_acc: 0.9277
Epoch 46/50
7352/7352 [=====] - 3s 447us/step - loss: 0.05
41 - acc: 0.9710 - val_loss: 0.3079 - val_acc: 0.9226
Epoch 47/50
7352/7352 [=====] - 3s 451us/step - loss: 0.05
23 - acc: 0.9770 - val_loss: 0.2853 - val_acc: 0.9257
Epoch 48/50
7352/7352 [=====] - 3s 444us/step - loss: 0.05
31 - acc: 0.9763 - val_loss: 0.3183 - val_acc: 0.9186
Epoch 49/50
7352/7352 [=====] - 3s 448us/step - loss: 0.05
06 - acc: 0.9752 - val_loss: 0.3276 - val_acc: 0.9230
Epoch 50/50
7352/7352 [=====] - 3s 445us/step - loss: 0.05
07 - acc: 0.9777 - val_loss: 0.3183 - val_acc: 0.9216

```

Out[0]: <keras.callbacks.History at 0x7fa9b45c8240>

```

In [0]: score = model.evaluate(X_test, Y_test)
        print(score)

        score_train = model.evaluate(X_train, Y_train)
        print(score_train)

2947/2947 [=====] - 0s 89us/step
[0.3449924494941751, 0.9192399049881235]
7352/7352 [=====] - 1s 85us/step
[0.045094185050339956, 0.9767410228509249]

```

```

In [0]: # Confusion Matrix
        # print(confusion_matrix(Y_test, model.predict(X_test)))

```

```
conf = pd.DataFrame(confusion_matrix(Y_test, model.predict(X_test)))
conf
```

Out[0]:

	Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTA
True						
LAYING		510	0	0	0	0
SITTING		0	395	94	0	0
STANDING		0	70	461	1	0
WALKING		0	0	0	480	7
WALKING_DOWNSTAIRS		0	0	0	4	411
WALKING_UPSTAIRS		0	0	0	0	19

CNN + LSTM

```
In [0]: # Initiliazing the sequential model
model = Sequential()
model.add(Conv1D(filters=300, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))
model.add(MaxPooling1D(pool_size=15))
#model.add(Conv1D(filters=70, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))

#model.add(MaxPooling1D(pool_size=9))
#model.add(Dropout(0.7))
#Configuring the parameters
model.add(LSTM(50, input_shape=(timesteps, input_dim)))
model.add(Dropout(0.6))
# Adding a dropout layer
# Adding a dense output layer with sigmoid activation
#model.add(Flatten())
```

```

model.add(Dense(n_classes, activation='sigmoid'))

model.summary()

# Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='adamax',
              metrics=['accuracy'])

# Training the model
model.fit(X_train,
          Y_train,
          batch_size=10,
          validation_data=(X_test, Y_test),
          epochs=50)

score = model.evaluate(X_test, Y_test)
print(score)

score_train = model.evaluate(X_train, Y_train)
print(score_train)

# Confusion Matrix
# print(confusion_matrix(Y_test, model.predict(X_test)))
conf = pd.DataFrame(confusion_matrix(Y_test, model.predict(X_test)))
conf

```

W0616 07:39:34.822537 140374351411072 nn_ops.py:4224] Large dropout rate: 0.6 (>0.5). In TensorFlow 2.x, dropout() uses dropout rate instead of keep_prob. Please ensure that this is intended.

Layer (type)	Output Shape	Param #
conv1d_40 (Conv1D)	(None, 128, 300)	40800
max_pooling1d_33 (MaxPooling)	(None, 8, 300)	0
lstm_8 (LSTM)	(None, 50)	70200

dense_5 (Dense)	(None, 50)	70200
dropout_5 (Dropout)	(None, 50)	0
dense_27 (Dense)	(None, 6)	306

Total params: 111,306
 Trainable params: 111,306
 Non-trainable params: 0

Train on 7352 samples, validate on 2947 samples
 Epoch 1/50
 7352/7352 [=====] - 15s 2ms/step - loss: 1.1337 - acc: 0.5303 - val_loss: 0.7919 - val_acc: 0.6546
 Epoch 2/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.7844 - acc: 0.6234 - val_loss: 0.7166 - val_acc: 0.7204
 Epoch 3/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.7039 - acc: 0.6748 - val_loss: 0.6864 - val_acc: 0.6834
 Epoch 4/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.6499 - acc: 0.7133 - val_loss: 0.5547 - val_acc: 0.7662
 Epoch 5/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.5801 - acc: 0.7447 - val_loss: 0.4997 - val_acc: 0.7611
 Epoch 6/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.4755 - acc: 0.7920 - val_loss: 0.4990 - val_acc: 0.7516
 Epoch 7/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.4192 - acc: 0.8221 - val_loss: 0.4501 - val_acc: 0.7713
 Epoch 8/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.3697 - acc: 0.8555 - val_loss: 0.3573 - val_acc: 0.8941
 Epoch 9/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.3152 - acc: 0.8881 - val_loss: 0.3059 - val_acc: 0.8975
 Epoch 10/50
 7352/7352 [=====] - 13s 2ms/step - loss: 0.258

```
6 - acc: 0.9246 - val_loss: 0.2724 - val_acc: 0.9094
Epoch 11/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.250
3 - acc: 0.9240 - val_loss: 0.2439 - val_acc: 0.9111
Epoch 12/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.227
7 - acc: 0.9317 - val_loss: 0.2399 - val_acc: 0.9145
Epoch 13/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.214
2 - acc: 0.9361 - val_loss: 0.2215 - val_acc: 0.9196
Epoch 14/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.201
0 - acc: 0.9366 - val_loss: 0.2228 - val_acc: 0.9216
Epoch 15/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.185
8 - acc: 0.9402 - val_loss: 0.3012 - val_acc: 0.8955
Epoch 16/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.181
3 - acc: 0.9433 - val_loss: 0.2351 - val_acc: 0.9237
Epoch 17/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.178
5 - acc: 0.9441 - val_loss: 0.2208 - val_acc: 0.9155
Epoch 18/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.168
6 - acc: 0.9410 - val_loss: 0.2250 - val_acc: 0.9291
Epoch 19/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.172
5 - acc: 0.9408 - val_loss: 0.2275 - val_acc: 0.9260
Epoch 20/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.168
1 - acc: 0.9430 - val_loss: 0.2231 - val_acc: 0.9196
Epoch 21/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.159
0 - acc: 0.9433 - val_loss: 0.2180 - val_acc: 0.9240
Epoch 22/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.147
4 - acc: 0.9474 - val_loss: 0.3544 - val_acc: 0.8816
Epoch 23/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.160
```

```
5 - acc: 0.9456 - val_loss: 0.2234 - val_acc: 0.9209
Epoch 24/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.144
8 - acc: 0.9494 - val_loss: 0.2287 - val_acc: 0.9223
Epoch 25/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.149
9 - acc: 0.9491 - val_loss: 0.2094 - val_acc: 0.9233
Epoch 26/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.151
0 - acc: 0.9471 - val_loss: 0.2226 - val_acc: 0.9267
Epoch 27/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.151
7 - acc: 0.9495 - val_loss: 0.2131 - val_acc: 0.9260
Epoch 28/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.146
4 - acc: 0.9436 - val_loss: 0.2201 - val_acc: 0.9213
Epoch 29/50
7352/7352 [=====] - 14s 2ms/step - loss: 0.143
8 - acc: 0.9490 - val_loss: 0.2058 - val_acc: 0.9250
Epoch 30/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.139
8 - acc: 0.9494 - val_loss: 0.2356 - val_acc: 0.9270
Epoch 31/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.137
4 - acc: 0.9490 - val_loss: 0.2204 - val_acc: 0.9250
Epoch 32/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.133
4 - acc: 0.9505 - val_loss: 0.2372 - val_acc: 0.9220
Epoch 33/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.139
0 - acc: 0.9468 - val_loss: 0.2412 - val_acc: 0.9247
Epoch 34/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.140
2 - acc: 0.9487 - val_loss: 0.2264 - val_acc: 0.9253
Epoch 35/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.134
6 - acc: 0.9501 - val_loss: 0.2530 - val_acc: 0.9162
Epoch 36/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.135
```



```
4 - acc: 0.9501 - val_loss: 0.2319 - val_acc: 0.9179
Epoch 37/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.134
9 - acc: 0.9508 - val_loss: 0.2315 - val_acc: 0.9257
Epoch 38/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.130
6 - acc: 0.9532 - val_loss: 0.2304 - val_acc: 0.9274
Epoch 39/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.137
6 - acc: 0.9508 - val_loss: 0.2402 - val_acc: 0.9298
Epoch 40/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.133
3 - acc: 0.9493 - val_loss: 0.2290 - val_acc: 0.9270
Epoch 41/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.125
5 - acc: 0.9513 - val_loss: 0.2715 - val_acc: 0.9186
Epoch 42/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.129
1 - acc: 0.9535 - val_loss: 0.2591 - val_acc: 0.9152
Epoch 43/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.130
0 - acc: 0.9524 - val_loss: 0.2332 - val_acc: 0.9287
Epoch 44/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.129
8 - acc: 0.9544 - val_loss: 0.2711 - val_acc: 0.9216
Epoch 45/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.128
3 - acc: 0.9506 - val_loss: 0.2492 - val_acc: 0.9169
Epoch 46/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.126
4 - acc: 0.9508 - val_loss: 0.2511 - val_acc: 0.9226
Epoch 47/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.123
8 - acc: 0.9521 - val_loss: 0.2565 - val_acc: 0.9213
Epoch 48/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.134
6 - acc: 0.9520 - val_loss: 0.2876 - val_acc: 0.9165
Epoch 49/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.125
```

```

7 - acc: 0.9529 - val_loss: 0.2678 - val_acc: 0.9121
Epoch 50/50
7352/7352 [=====] - 13s 2ms/step - loss: 0.121
2 - acc: 0.9529 - val_loss: 0.2423 - val_acc: 0.9277
2947/2947 [=====] - 1s 207us/step
[0.24233421574737116, 0.9277231082456736]
7352/7352 [=====] - 1s 203us/step
[0.09086589647518013, 0.9604189336235038]

```

Out[0]:

	Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTA
	True					
LAYING		534	0	0	0	0
SITTING		0	401	88	0	0
STANDING		0	82	446	0	0
WALKING		0	0	0	491	5
WALKING_DOWNSTAIRS		0	0	0	0	412
WALKING_UPSTAIRS		0	0	0	0	21

2 CNN layers, 3 Pooling layers and one Dropout layer

```

In [0]: # Initiliazing the sequential model
model = Sequential()
model.add(Conv1D(filters=200, kernel_size=15, padding='same', activation='sigmoid', input_shape=(timesteps, input_dim)))
model.add(MaxPooling1D(pool_size=15))
model.add(MaxPooling1D(pool_size=2))
model.add(Conv1D(filters=100, kernel_size=15, padding='same', activation='sigmoid'))

```

```

model.add(MaxPooling1D(pool_size=2))
model.add(Dropout(0.4))
model.add(Flatten())
model.add(Dense(n_classes, activation='sigmoid', kernel_initializer='gl
orot_normal'))
model.summary()

```

Layer (type)	Output Shape	Param #
conv1d_9 (Conv1D)	(None, 128, 200)	27200
max_pooling1d_15 (MaxPooling)	(None, 8, 200)	0
max_pooling1d_16 (MaxPooling)	(None, 4, 200)	0
conv1d_10 (Conv1D)	(None, 4, 100)	300100
max_pooling1d_17 (MaxPooling)	(None, 2, 100)	0
dropout_2 (Dropout)	(None, 2, 100)	0
flatten_6 (Flatten)	(None, 200)	0
dense_6 (Dense)	(None, 6)	1206
Total params: 328,506		
Trainable params: 328,506		
Non-trainable params: 0		

```

In [0]: # Compiling the model
model.compile(loss='categorical_crossentropy',
              optimizer='adamax',
              metrics=['accuracy'])

```

```

In [0]: # Training the model
history = model.fit(X_train,
                    Y_train,

```

```
batch_size=50,  
validation_data=(X_test, Y_test),  
epochs=300)
```

Train on 7352 samples, validate on 2947 samples

Epoch 1/300

7352/7352 [=====] - 1s 190us/step - loss: 1.44

82 - acc: 0.3702 - val_loss: 1.0487 - val_acc: 0.6620

Epoch 2/300

7352/7352 [=====] - 1s 120us/step - loss: 0.73

33 - acc: 0.7153 - val_loss: 0.6046 - val_acc: 0.8358

Epoch 3/300

7352/7352 [=====] - 1s 118us/step - loss: 0.43

40 - acc: 0.8398 - val_loss: 0.4747 - val_acc: 0.8619

Epoch 4/300

7352/7352 [=====] - 1s 120us/step - loss: 0.30

98 - acc: 0.9023 - val_loss: 0.3850 - val_acc: 0.8911

Epoch 5/300

7352/7352 [=====] - 1s 122us/step - loss: 0.22

76 - acc: 0.9285 - val_loss: 0.3341 - val_acc: 0.8904

Epoch 6/300

7352/7352 [=====] - 1s 122us/step - loss: 0.18

48 - acc: 0.9387 - val_loss: 0.2959 - val_acc: 0.8911

Epoch 7/300

7352/7352 [=====] - 1s 120us/step - loss: 0.16

74 - acc: 0.9411 - val_loss: 0.2790 - val_acc: 0.8948

Epoch 8/300

7352/7352 [=====] - 1s 120us/step - loss: 0.15

80 - acc: 0.9400 - val_loss: 0.2723 - val_acc: 0.9077

Epoch 9/300

7352/7352 [=====] - 1s 121us/step - loss: 0.14

57 - acc: 0.9433 - val_loss: 0.2694 - val_acc: 0.9006

Epoch 10/300

7352/7352 [=====] - 1s 121us/step - loss: 0.13

85 - acc: 0.9475 - val_loss: 0.2576 - val_acc: 0.9128

Epoch 11/300

7352/7352 [=====] - 1s 118us/step - loss: 0.13

51 - acc: 0.9478 - val_loss: 0.2488 - val_acc: 0.9046

Epoch 12/300

7352/7352 [=====] - 1s 118us/step - loss: 0.12

```
77 - acc: 0.9506 - val_loss: 0.2521 - val_acc: 0.9046
Epoch 13/300
7352/7352 [=====] - 1s 119us/step - loss: 0.12
60 - acc: 0.9505 - val_loss: 0.2557 - val_acc: 0.9074
Epoch 14/300
7352/7352 [=====] - 1s 120us/step - loss: 0.12
35 - acc: 0.9508 - val_loss: 0.2537 - val_acc: 0.9067
Epoch 15/300
7352/7352 [=====] - 1s 121us/step - loss: 0.12
08 - acc: 0.9512 - val_loss: 0.2324 - val_acc: 0.9118
Epoch 16/300
7352/7352 [=====] - 1s 120us/step - loss: 0.11
73 - acc: 0.9527 - val_loss: 0.2330 - val_acc: 0.9087
Epoch 17/300
7352/7352 [=====] - 1s 120us/step - loss: 0.11
71 - acc: 0.9527 - val_loss: 0.2274 - val_acc: 0.9141
Epoch 18/300
7352/7352 [=====] - 1s 119us/step - loss: 0.11
61 - acc: 0.9516 - val_loss: 0.2248 - val_acc: 0.9121
Epoch 19/300
7352/7352 [=====] - 1s 122us/step - loss: 0.11
55 - acc: 0.9517 - val_loss: 0.2345 - val_acc: 0.9094
Epoch 20/300
7352/7352 [=====] - 1s 122us/step - loss: 0.11
81 - acc: 0.9482 - val_loss: 0.2249 - val_acc: 0.9192
Epoch 21/300
7352/7352 [=====] - 1s 123us/step - loss: 0.11
44 - acc: 0.9510 - val_loss: 0.2154 - val_acc: 0.9172
Epoch 22/300
7352/7352 [=====] - 1s 122us/step - loss: 0.10
98 - acc: 0.9551 - val_loss: 0.2205 - val_acc: 0.9206
Epoch 23/300
7352/7352 [=====] - 1s 122us/step - loss: 0.10
89 - acc: 0.9553 - val_loss: 0.2304 - val_acc: 0.9135
Epoch 24/300
7352/7352 [=====] - 1s 122us/step - loss: 0.10
96 - acc: 0.9539 - val_loss: 0.2208 - val_acc: 0.9203
Epoch 25/300
7352/7352 [=====] - 1s 120us/step - loss: 0.10
```

```
57 - acc: 0.9535 - val_loss: 0.2108 - val_acc: 0.9189
Epoch 26/300
7352/7352 [=====] - 1s 121us/step - loss: 0.10
79 - acc: 0.9540 - val_loss: 0.2128 - val_acc: 0.9233
Epoch 27/300
7352/7352 [=====] - 1s 122us/step - loss: 0.10
63 - acc: 0.9535 - val_loss: 0.2110 - val_acc: 0.9155
Epoch 28/300
7352/7352 [=====] - 1s 121us/step - loss: 0.10
43 - acc: 0.9562 - val_loss: 0.2033 - val_acc: 0.9230
Epoch 29/300
7352/7352 [=====] - 1s 123us/step - loss: 0.10
44 - acc: 0.9558 - val_loss: 0.1967 - val_acc: 0.9206
Epoch 30/300
7352/7352 [=====] - 1s 121us/step - loss: 0.10
22 - acc: 0.9569 - val_loss: 0.2094 - val_acc: 0.9192
Epoch 31/300
7352/7352 [=====] - 1s 120us/step - loss: 0.10
36 - acc: 0.9557 - val_loss: 0.2120 - val_acc: 0.9213
Epoch 32/300
7352/7352 [=====] - 1s 119us/step - loss: 0.10
19 - acc: 0.9548 - val_loss: 0.1923 - val_acc: 0.9270
Epoch 33/300
7352/7352 [=====] - 1s 118us/step - loss: 0.10
17 - acc: 0.9592 - val_loss: 0.1928 - val_acc: 0.9277
Epoch 34/300
7352/7352 [=====] - 1s 121us/step - loss: 0.09
88 - acc: 0.9577 - val_loss: 0.1858 - val_acc: 0.9287
Epoch 35/300
7352/7352 [=====] - 1s 121us/step - loss: 0.10
14 - acc: 0.9570 - val_loss: 0.1860 - val_acc: 0.9267
Epoch 36/300
7352/7352 [=====] - 1s 120us/step - loss: 0.09
78 - acc: 0.9592 - val_loss: 0.1929 - val_acc: 0.9294
Epoch 37/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
83 - acc: 0.9565 - val_loss: 0.1856 - val_acc: 0.9270
Epoch 38/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
```

```
85 - acc: 0.9587 - val_loss: 0.1882 - val_acc: 0.9253
Epoch 39/300
7352/7352 [=====] - 1s 121us/step - loss: 0.09
77 - acc: 0.9588 - val_loss: 0.1853 - val_acc: 0.9267
Epoch 40/300
7352/7352 [=====] - 1s 117us/step - loss: 0.09
53 - acc: 0.9596 - val_loss: 0.2141 - val_acc: 0.9253
Epoch 41/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
80 - acc: 0.9580 - val_loss: 0.1916 - val_acc: 0.9216
Epoch 42/300
7352/7352 [=====] - 1s 121us/step - loss: 0.09
72 - acc: 0.9589 - val_loss: 0.1927 - val_acc: 0.9291
Epoch 43/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
85 - acc: 0.9589 - val_loss: 0.1854 - val_acc: 0.9270
Epoch 44/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
71 - acc: 0.9610 - val_loss: 0.1956 - val_acc: 0.9274
Epoch 45/300
7352/7352 [=====] - 1s 120us/step - loss: 0.09
44 - acc: 0.9614 - val_loss: 0.1949 - val_acc: 0.9393
Epoch 46/300
7352/7352 [=====] - 1s 120us/step - loss: 0.09
33 - acc: 0.9606 - val_loss: 0.2004 - val_acc: 0.9189
Epoch 47/300
7352/7352 [=====] - 1s 118us/step - loss: 0.09
47 - acc: 0.9601 - val_loss: 0.1835 - val_acc: 0.9287
Epoch 48/300
7352/7352 [=====] - 1s 121us/step - loss: 0.09
26 - acc: 0.9582 - val_loss: 0.1806 - val_acc: 0.9277
Epoch 49/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
99 - acc: 0.9626 - val_loss: 0.1836 - val_acc: 0.9308
Epoch 50/300
7352/7352 [=====] - 1s 119us/step - loss: 0.09
00 - acc: 0.9629 - val_loss: 0.1881 - val_acc: 0.9270
Epoch 51/300
7352/7352 [=====] - 1s 119us/step - loss: 0.08
```

```
90 - acc: 0.9608 - val_loss: 0.1803 - val_acc: 0.9281
Epoch 52/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
95 - acc: 0.9627 - val_loss: 0.1770 - val_acc: 0.9277
Epoch 53/300
7352/7352 [=====] - 1s 122us/step - loss: 0.08
73 - acc: 0.9630 - val_loss: 0.1745 - val_acc: 0.9294
Epoch 54/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
70 - acc: 0.9629 - val_loss: 0.1714 - val_acc: 0.9308
Epoch 55/300
7352/7352 [=====] - 1s 122us/step - loss: 0.08
79 - acc: 0.9625 - val_loss: 0.1877 - val_acc: 0.9253
Epoch 56/300
7352/7352 [=====] - 1s 121us/step - loss: 0.08
71 - acc: 0.9631 - val_loss: 0.1645 - val_acc: 0.9308
Epoch 57/300
7352/7352 [=====] - 1s 118us/step - loss: 0.08
79 - acc: 0.9619 - val_loss: 0.1709 - val_acc: 0.9308
Epoch 58/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
73 - acc: 0.9623 - val_loss: 0.1725 - val_acc: 0.9308
Epoch 59/300
7352/7352 [=====] - 1s 121us/step - loss: 0.08
62 - acc: 0.9611 - val_loss: 0.1810 - val_acc: 0.9267
Epoch 60/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
63 - acc: 0.9641 - val_loss: 0.1858 - val_acc: 0.9264
Epoch 61/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
48 - acc: 0.9645 - val_loss: 0.1649 - val_acc: 0.9308
Epoch 62/300
7352/7352 [=====] - 1s 118us/step - loss: 0.08
45 - acc: 0.9648 - val_loss: 0.1807 - val_acc: 0.9284
Epoch 63/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
32 - acc: 0.9663 - val_loss: 0.1642 - val_acc: 0.9382
Epoch 64/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
```



```
27 - acc: 0.9635 - val_loss: 0.1722 - val_acc: 0.9304
Epoch 65/300
7352/7352 [=====] - 1s 118us/step - loss: 0.08
20 - acc: 0.9642 - val_loss: 0.1737 - val_acc: 0.9410
Epoch 66/300
7352/7352 [=====] - 1s 119us/step - loss: 0.08
60 - acc: 0.9649 - val_loss: 0.1742 - val_acc: 0.9308
Epoch 67/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
11 - acc: 0.9638 - val_loss: 0.1720 - val_acc: 0.9318
Epoch 68/300
7352/7352 [=====] - 1s 118us/step - loss: 0.08
03 - acc: 0.9650 - val_loss: 0.1692 - val_acc: 0.9301
Epoch 69/300
7352/7352 [=====] - 1s 119us/step - loss: 0.08
29 - acc: 0.9649 - val_loss: 0.1679 - val_acc: 0.9335
Epoch 70/300
7352/7352 [=====] - 1s 120us/step - loss: 0.08
08 - acc: 0.9665 - val_loss: 0.1683 - val_acc: 0.9321
Epoch 71/300
7352/7352 [=====] - 1s 119us/step - loss: 0.07
82 - acc: 0.9671 - val_loss: 0.1894 - val_acc: 0.9287
Epoch 72/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
72 - acc: 0.9694 - val_loss: 0.1833 - val_acc: 0.9345
Epoch 73/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
68 - acc: 0.9693 - val_loss: 0.1762 - val_acc: 0.9311
Epoch 74/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
59 - acc: 0.9687 - val_loss: 0.1863 - val_acc: 0.9294
Epoch 75/300
7352/7352 [=====] - 1s 122us/step - loss: 0.07
60 - acc: 0.9678 - val_loss: 0.1683 - val_acc: 0.9352
Epoch 76/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
51 - acc: 0.9691 - val_loss: 0.1723 - val_acc: 0.9423
Epoch 77/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
```

```
75 - acc: 0.9663 - val_loss: 0.1743 - val_acc: 0.9311
Epoch 78/300
7352/7352 [=====] - 1s 119us/step - loss: 0.07
87 - acc: 0.9679 - val_loss: 0.1868 - val_acc: 0.9270
Epoch 79/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
59 - acc: 0.9687 - val_loss: 0.1696 - val_acc: 0.9352
Epoch 80/300
7352/7352 [=====] - 1s 119us/step - loss: 0.07
53 - acc: 0.9676 - val_loss: 0.1640 - val_acc: 0.9348
Epoch 81/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
55 - acc: 0.9687 - val_loss: 0.1765 - val_acc: 0.9325
Epoch 82/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
56 - acc: 0.9693 - val_loss: 0.1847 - val_acc: 0.9287
Epoch 83/300
7352/7352 [=====] - 1s 118us/step - loss: 0.07
47 - acc: 0.9698 - val_loss: 0.1997 - val_acc: 0.9308
Epoch 84/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
42 - acc: 0.9697 - val_loss: 0.1743 - val_acc: 0.9365
Epoch 85/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
34 - acc: 0.9697 - val_loss: 0.1816 - val_acc: 0.9301
Epoch 86/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
45 - acc: 0.9691 - val_loss: 0.1794 - val_acc: 0.9345
Epoch 87/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
61 - acc: 0.9684 - val_loss: 0.1781 - val_acc: 0.9338
Epoch 88/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
33 - acc: 0.9694 - val_loss: 0.1774 - val_acc: 0.9342
Epoch 89/300
7352/7352 [=====] - 1s 123us/step - loss: 0.07
23 - acc: 0.9701 - val_loss: 0.1556 - val_acc: 0.9457
Epoch 90/300
7352/7352 [=====] - 1s 119us/step - loss: 0.07
```

```
14 - acc: 0.9702 - val_loss: 0.2043 - val_acc: 0.9230
Epoch 91/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
22 - acc: 0.9684 - val_loss: 0.1710 - val_acc: 0.9437
Epoch 92/300
7352/7352 [=====] - 1s 122us/step - loss: 0.06
92 - acc: 0.9716 - val_loss: 0.1755 - val_acc: 0.9396
Epoch 93/300
7352/7352 [=====] - 1s 120us/step - loss: 0.07
08 - acc: 0.9691 - val_loss: 0.1919 - val_acc: 0.9304
Epoch 94/300
7352/7352 [=====] - 1s 120us/step - loss: 0.06
61 - acc: 0.9733 - val_loss: 0.1737 - val_acc: 0.9427
Epoch 95/300
7352/7352 [=====] - 1s 122us/step - loss: 0.06
97 - acc: 0.9701 - val_loss: 0.1671 - val_acc: 0.9454
Epoch 96/300
7352/7352 [=====] - 1s 121us/step - loss: 0.07
07 - acc: 0.9729 - val_loss: 0.1900 - val_acc: 0.9348
Epoch 97/300
7352/7352 [=====] - 1s 121us/step - loss: 0.06
37 - acc: 0.9736 - val_loss: 0.1613 - val_acc: 0.9393
Epoch 98/300
7352/7352 [=====] - 1s 118us/step - loss: 0.06
62 - acc: 0.9717 - val_loss: 0.1860 - val_acc: 0.9362
Epoch 99/300
7352/7352 [=====] - 1s 122us/step - loss: 0.06
28 - acc: 0.9727 - val_loss: 0.2216 - val_acc: 0.9237
Epoch 100/300
7352/7352 [=====] - 1s 121us/step - loss: 0.06
66 - acc: 0.9721 - val_loss: 0.1643 - val_acc: 0.9423
Epoch 101/300
7352/7352 [=====] - 1s 121us/step - loss: 0.06
35 - acc: 0.9736 - val_loss: 0.1788 - val_acc: 0.9447
Epoch 102/300
7352/7352 [=====] - 1s 120us/step - loss: 0.06
72 - acc: 0.9716 - val_loss: 0.1733 - val_acc: 0.9467
Epoch 103/300
7352/7352 [=====] - 1s 121us/step - loss: 0.06
```

```
28 - acc: 0.9732 - val_loss: 0.1727 - val_acc: 0.9423
Epoch 104/300
7352/7352 [=====] - 1s 120us/step - loss: 0.06
16 - acc: 0.9733 - val_loss: 0.1731 - val_acc: 0.9406
Epoch 105/300
7352/7352 [=====] - 1s 119us/step - loss: 0.06
40 - acc: 0.9728 - val_loss: 0.1722 - val_acc: 0.9474
Epoch 106/300
7352/7352 [=====] - 1s 120us/step - loss: 0.06
16 - acc: 0.9737 - val_loss: 0.1770 - val_acc: 0.9416
Epoch 107/300
7352/7352 [=====] - 1s 119us/step - loss: 0.05
91 - acc: 0.9750 - val_loss: 0.1592 - val_acc: 0.9494
Epoch 108/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
91 - acc: 0.9744 - val_loss: 0.1596 - val_acc: 0.9494
Epoch 109/300
7352/7352 [=====] - 1s 119us/step - loss: 0.05
66 - acc: 0.9758 - val_loss: 0.1583 - val_acc: 0.9491
Epoch 110/300
7352/7352 [=====] - 1s 122us/step - loss: 0.05
87 - acc: 0.9759 - val_loss: 0.2098 - val_acc: 0.9291
Epoch 111/300
7352/7352 [=====] - 1s 123us/step - loss: 0.05
79 - acc: 0.9752 - val_loss: 0.1948 - val_acc: 0.9359
Epoch 112/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
61 - acc: 0.9767 - val_loss: 0.1789 - val_acc: 0.9403
Epoch 113/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
50 - acc: 0.9771 - val_loss: 0.1410 - val_acc: 0.9576
Epoch 114/300
7352/7352 [=====] - 1s 122us/step - loss: 0.05
51 - acc: 0.9786 - val_loss: 0.1447 - val_acc: 0.9583
Epoch 115/300
7352/7352 [=====] - 1s 122us/step - loss: 0.05
70 - acc: 0.9758 - val_loss: 0.1570 - val_acc: 0.9522
Epoch 116/300
7352/7352 [=====] - 1s 124us/step - loss: 0.05
```

```
88 - acc: 0.9755 - val_loss: 0.1693 - val_acc: 0.9528
Epoch 117/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
42 - acc: 0.9759 - val_loss: 0.1596 - val_acc: 0.9474
Epoch 118/300
7352/7352 [=====] - 1s 120us/step - loss: 0.05
07 - acc: 0.9786 - val_loss: 0.1767 - val_acc: 0.9481
Epoch 119/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
85 - acc: 0.9736 - val_loss: 0.1530 - val_acc: 0.9539
Epoch 120/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
38 - acc: 0.9786 - val_loss: 0.1826 - val_acc: 0.9321
Epoch 121/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
07 - acc: 0.9796 - val_loss: 0.1717 - val_acc: 0.9413
Epoch 122/300
7352/7352 [=====] - 1s 123us/step - loss: 0.05
24 - acc: 0.9793 - val_loss: 0.1558 - val_acc: 0.9549
Epoch 123/300
7352/7352 [=====] - 1s 121us/step - loss: 0.05
28 - acc: 0.9778 - val_loss: 0.1537 - val_acc: 0.9522
Epoch 124/300
7352/7352 [=====] - 1s 120us/step - loss: 0.05
20 - acc: 0.9782 - val_loss: 0.1523 - val_acc: 0.9542
Epoch 125/300
7352/7352 [=====] - 1s 120us/step - loss: 0.05
02 - acc: 0.9805 - val_loss: 0.1652 - val_acc: 0.9450
Epoch 126/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
84 - acc: 0.9805 - val_loss: 0.1638 - val_acc: 0.9508
Epoch 127/300
7352/7352 [=====] - 1s 118us/step - loss: 0.04
77 - acc: 0.9803 - val_loss: 0.2000 - val_acc: 0.9315
Epoch 128/300
7352/7352 [=====] - 1s 117us/step - loss: 0.04
75 - acc: 0.9800 - val_loss: 0.1583 - val_acc: 0.9484
Epoch 129/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
```

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88 - acc: 0.9799 - val_loss: 0.1812 - val_acc: 0.9437
Epoch 130/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
67 - acc: 0.9807 - val_loss: 0.1611 - val_acc: 0.9471
Epoch 131/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
39 - acc: 0.9814 - val_loss: 0.1604 - val_acc: 0.9593
Epoch 132/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
44 - acc: 0.9815 - val_loss: 0.1826 - val_acc: 0.9444
Epoch 133/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
37 - acc: 0.9829 - val_loss: 0.1566 - val_acc: 0.9566
Epoch 134/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
59 - acc: 0.9818 - val_loss: 0.1662 - val_acc: 0.9501
Epoch 135/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
34 - acc: 0.9823 - val_loss: 0.1521 - val_acc: 0.9511
Epoch 136/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
17 - acc: 0.9838 - val_loss: 0.1762 - val_acc: 0.9474
Epoch 137/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
29 - acc: 0.9823 - val_loss: 0.1675 - val_acc: 0.9454
Epoch 138/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
23 - acc: 0.9804 - val_loss: 0.1782 - val_acc: 0.9410
Epoch 139/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
36 - acc: 0.9818 - val_loss: 0.1713 - val_acc: 0.9450
Epoch 140/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
43 - acc: 0.9823 - val_loss: 0.1500 - val_acc: 0.9596
Epoch 141/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
04 - acc: 0.9844 - val_loss: 0.1755 - val_acc: 0.9444
Epoch 142/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
```

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01 - acc: 0.9837 - val_loss: 0.1591 - val_acc: 0.9552
Epoch 143/300
7352/7352 [=====] - 1s 121us/step - loss: 0.03
98 - acc: 0.9839 - val_loss: 0.1691 - val_acc: 0.9505
Epoch 144/300
7352/7352 [=====] - 1s 123us/step - loss: 0.03
85 - acc: 0.9853 - val_loss: 0.1688 - val_acc: 0.9498
Epoch 145/300
7352/7352 [=====] - 1s 128us/step - loss: 0.03
99 - acc: 0.9834 - val_loss: 0.1606 - val_acc: 0.9589
Epoch 146/300
7352/7352 [=====] - 1s 128us/step - loss: 0.03
91 - acc: 0.9837 - val_loss: 0.1628 - val_acc: 0.9572
Epoch 147/300
7352/7352 [=====] - 1s 128us/step - loss: 0.04
27 - acc: 0.9819 - val_loss: 0.1795 - val_acc: 0.9413
Epoch 148/300
7352/7352 [=====] - 1s 129us/step - loss: 0.04
07 - acc: 0.9826 - val_loss: 0.1626 - val_acc: 0.9471
Epoch 149/300
7352/7352 [=====] - 1s 130us/step - loss: 0.03
87 - acc: 0.9834 - val_loss: 0.1812 - val_acc: 0.9423
Epoch 150/300
7352/7352 [=====] - 1s 130us/step - loss: 0.03
98 - acc: 0.9833 - val_loss: 0.1361 - val_acc: 0.9684
Epoch 151/300
7352/7352 [=====] - 1s 129us/step - loss: 0.04
34 - acc: 0.9823 - val_loss: 0.1408 - val_acc: 0.9650
Epoch 152/300
7352/7352 [=====] - 1s 130us/step - loss: 0.04
35 - acc: 0.9841 - val_loss: 0.1928 - val_acc: 0.9457
Epoch 153/300
7352/7352 [=====] - 1s 127us/step - loss: 0.03
86 - acc: 0.9837 - val_loss: 0.1497 - val_acc: 0.9528
Epoch 154/300
7352/7352 [=====] - 1s 130us/step - loss: 0.04
34 - acc: 0.9814 - val_loss: 0.1892 - val_acc: 0.9413
Epoch 155/300
7352/7352 [=====] - 1s 126us/step - loss: 0.03
```

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80 - acc: 0.9844 - val_loss: 0.1413 - val_acc: 0.9532
Epoch 156/300
7352/7352 [=====] - 1s 122us/step - loss: 0.04
09 - acc: 0.9822 - val_loss: 0.1714 - val_acc: 0.9477
Epoch 157/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
12 - acc: 0.9826 - val_loss: 0.1800 - val_acc: 0.9416
Epoch 158/300
7352/7352 [=====] - 1s 121us/step - loss: 0.04
00 - acc: 0.9839 - val_loss: 0.1410 - val_acc: 0.9552
Epoch 159/300
7352/7352 [=====] - 1s 121us/step - loss: 0.03
98 - acc: 0.9829 - val_loss: 0.1648 - val_acc: 0.9511
Epoch 160/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
19 - acc: 0.9830 - val_loss: 0.1419 - val_acc: 0.9589
Epoch 161/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
90 - acc: 0.9856 - val_loss: 0.1490 - val_acc: 0.9545
Epoch 162/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
22 - acc: 0.9819 - val_loss: 0.1691 - val_acc: 0.9433
Epoch 163/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
64 - acc: 0.9846 - val_loss: 0.1446 - val_acc: 0.9525
Epoch 164/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
89 - acc: 0.9838 - val_loss: 0.1665 - val_acc: 0.9532
Epoch 165/300
7352/7352 [=====] - 1s 119us/step - loss: 0.04
00 - acc: 0.9835 - val_loss: 0.1467 - val_acc: 0.9505
Epoch 166/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
77 - acc: 0.9848 - val_loss: 0.1799 - val_acc: 0.9508
Epoch 167/300
7352/7352 [=====] - 1s 118us/step - loss: 0.03
45 - acc: 0.9867 - val_loss: 0.1827 - val_acc: 0.9460
Epoch 168/300
7352/7352 [=====] - 1s 117us/step - loss: 0.03
```



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57 - acc: 0.9849 - val_loss: 0.1955 - val_acc: 0.9437
Epoch 169/300
7352/7352 [=====] - 1s 120us/step - loss: 0.04
19 - acc: 0.9823 - val_loss: 0.1349 - val_acc: 0.9661
Epoch 170/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
57 - acc: 0.9837 - val_loss: 0.1567 - val_acc: 0.9539
Epoch 171/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
44 - acc: 0.9856 - val_loss: 0.1440 - val_acc: 0.9555
Epoch 172/300
7352/7352 [=====] - 1s 118us/step - loss: 0.03
65 - acc: 0.9859 - val_loss: 0.1647 - val_acc: 0.9511
Epoch 173/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
05 - acc: 0.9876 - val_loss: 0.1496 - val_acc: 0.9545
Epoch 174/300
7352/7352 [=====] - 1s 118us/step - loss: 0.03
06 - acc: 0.9882 - val_loss: 0.1655 - val_acc: 0.9491
Epoch 175/300
7352/7352 [=====] - 1s 117us/step - loss: 0.03
19 - acc: 0.9863 - val_loss: 0.1490 - val_acc: 0.9569
Epoch 176/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
24 - acc: 0.9876 - val_loss: 0.1596 - val_acc: 0.9545
Epoch 177/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
33 - acc: 0.9875 - val_loss: 0.1750 - val_acc: 0.9484
Epoch 178/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
33 - acc: 0.9869 - val_loss: 0.1745 - val_acc: 0.9471
Epoch 179/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
18 - acc: 0.9871 - val_loss: 0.1494 - val_acc: 0.9559
Epoch 180/300
7352/7352 [=====] - 1s 122us/step - loss: 0.03
38 - acc: 0.9846 - val_loss: 0.1533 - val_acc: 0.9542
Epoch 181/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
```

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44 - acc: 0.9856 - val_loss: 0.1579 - val_acc: 0.9562
Epoch 182/300
7352/7352 [=====] - 1s 117us/step - loss: 0.03
09 - acc: 0.9883 - val_loss: 0.1628 - val_acc: 0.9569
Epoch 183/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
00 - acc: 0.9879 - val_loss: 0.1408 - val_acc: 0.9637
Epoch 184/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
29 - acc: 0.9865 - val_loss: 0.1618 - val_acc: 0.9552
Epoch 185/300
7352/7352 [=====] - 1s 122us/step - loss: 0.03
02 - acc: 0.9884 - val_loss: 0.1454 - val_acc: 0.9630
Epoch 186/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
25 - acc: 0.9880 - val_loss: 0.2003 - val_acc: 0.9437
Epoch 187/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
47 - acc: 0.9857 - val_loss: 0.1314 - val_acc: 0.9647
Epoch 188/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
12 - acc: 0.9882 - val_loss: 0.1445 - val_acc: 0.9562
Epoch 189/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
14 - acc: 0.9883 - val_loss: 0.1448 - val_acc: 0.9576
Epoch 190/300
7352/7352 [=====] - 1s 121us/step - loss: 0.03
35 - acc: 0.9861 - val_loss: 0.1484 - val_acc: 0.9623
Epoch 191/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
32 - acc: 0.9867 - val_loss: 0.1533 - val_acc: 0.9555
Epoch 192/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
99 - acc: 0.9874 - val_loss: 0.1532 - val_acc: 0.9603
Epoch 193/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
24 - acc: 0.9869 - val_loss: 0.1917 - val_acc: 0.9444
Epoch 194/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
```

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96 - acc: 0.9874 - val_loss: 0.1574 - val_acc: 0.9593
Epoch 195/300
7352/7352 [=====] - 1s 121us/step - loss: 0.03
30 - acc: 0.9878 - val_loss: 0.1492 - val_acc: 0.9555
Epoch 196/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
99 - acc: 0.9880 - val_loss: 0.1975 - val_acc: 0.9437
Epoch 197/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
21 - acc: 0.9867 - val_loss: 0.1507 - val_acc: 0.9589
Epoch 198/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
05 - acc: 0.9883 - val_loss: 0.1301 - val_acc: 0.9681
Epoch 199/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
04 - acc: 0.9886 - val_loss: 0.1579 - val_acc: 0.9569
Epoch 200/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
88 - acc: 0.9887 - val_loss: 0.1552 - val_acc: 0.9559
Epoch 201/300
7352/7352 [=====] - 1s 123us/step - loss: 0.02
76 - acc: 0.9902 - val_loss: 0.1434 - val_acc: 0.9617
Epoch 202/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
67 - acc: 0.9894 - val_loss: 0.1489 - val_acc: 0.9566
Epoch 203/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
78 - acc: 0.9891 - val_loss: 0.1476 - val_acc: 0.9600
Epoch 204/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
83 - acc: 0.9888 - val_loss: 0.1457 - val_acc: 0.9606
Epoch 205/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
91 - acc: 0.9872 - val_loss: 0.1512 - val_acc: 0.9589
Epoch 206/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
91 - acc: 0.9872 - val_loss: 0.1566 - val_acc: 0.9562
Epoch 207/300
7352/7352 [=====] - 1s 122us/step - loss: 0.03
```

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18 - acc: 0.9883 - val_loss: 0.1529 - val_acc: 0.9549
Epoch 208/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
56 - acc: 0.9901 - val_loss: 0.1348 - val_acc: 0.9695
Epoch 209/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
68 - acc: 0.9887 - val_loss: 0.1641 - val_acc: 0.9549
Epoch 210/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
64 - acc: 0.9908 - val_loss: 0.1391 - val_acc: 0.9654
Epoch 211/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
61 - acc: 0.9895 - val_loss: 0.1905 - val_acc: 0.9481
Epoch 212/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
80 - acc: 0.9891 - val_loss: 0.1465 - val_acc: 0.9623
Epoch 213/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
89 - acc: 0.9874 - val_loss: 0.2022 - val_acc: 0.9471
Epoch 214/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
96 - acc: 0.9883 - val_loss: 0.1316 - val_acc: 0.9671
Epoch 215/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
64 - acc: 0.9898 - val_loss: 0.1407 - val_acc: 0.9627
Epoch 216/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
34 - acc: 0.9879 - val_loss: 0.1389 - val_acc: 0.9644
Epoch 217/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
53 - acc: 0.9906 - val_loss: 0.1471 - val_acc: 0.9583
Epoch 218/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
70 - acc: 0.9895 - val_loss: 0.1554 - val_acc: 0.9569
Epoch 219/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
69 - acc: 0.9891 - val_loss: 0.1884 - val_acc: 0.9498
Epoch 220/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
```

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54 - acc: 0.9905 - val_loss: 0.2170 - val_acc: 0.9433
Epoch 221/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
28 - acc: 0.9865 - val_loss: 0.1481 - val_acc: 0.9617
Epoch 222/300
7352/7352 [=====] - 1s 120us/step - loss: 0.03
16 - acc: 0.9887 - val_loss: 0.1462 - val_acc: 0.9606
Epoch 223/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
32 - acc: 0.9910 - val_loss: 0.1544 - val_acc: 0.9562
Epoch 224/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
27 - acc: 0.9920 - val_loss: 0.1722 - val_acc: 0.9542
Epoch 225/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
57 - acc: 0.9898 - val_loss: 0.1466 - val_acc: 0.9593
Epoch 226/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
29 - acc: 0.9897 - val_loss: 0.1970 - val_acc: 0.9494
Epoch 227/300
7352/7352 [=====] - 1s 119us/step - loss: 0.03
02 - acc: 0.9888 - val_loss: 0.2200 - val_acc: 0.9444
Epoch 228/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
16 - acc: 0.9908 - val_loss: 0.1580 - val_acc: 0.9603
Epoch 229/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
72 - acc: 0.9893 - val_loss: 0.1449 - val_acc: 0.9613
Epoch 230/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
76 - acc: 0.9880 - val_loss: 0.1358 - val_acc: 0.9623
Epoch 231/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
60 - acc: 0.9893 - val_loss: 0.2007 - val_acc: 0.9464
Epoch 232/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
50 - acc: 0.9912 - val_loss: 0.1836 - val_acc: 0.9511
Epoch 233/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
```

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58 - acc: 0.9902 - val_loss: 0.1514 - val_acc: 0.9617
Epoch 234/300
7352/7352 [=====] - 1s 118us/step - loss: 0.02
54 - acc: 0.9908 - val_loss: 0.1947 - val_acc: 0.9477
Epoch 235/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
41 - acc: 0.9899 - val_loss: 0.1514 - val_acc: 0.9613
Epoch 236/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
45 - acc: 0.9898 - val_loss: 0.1556 - val_acc: 0.9620
Epoch 237/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
46 - acc: 0.9901 - val_loss: 0.1289 - val_acc: 0.9678
Epoch 238/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
24 - acc: 0.9918 - val_loss: 0.1678 - val_acc: 0.9549
Epoch 239/300
7352/7352 [=====] - 1s 118us/step - loss: 0.02
07 - acc: 0.9918 - val_loss: 0.1581 - val_acc: 0.9593
Epoch 240/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
02 - acc: 0.9924 - val_loss: 0.1624 - val_acc: 0.9593
Epoch 241/300
7352/7352 [=====] - 1s 116us/step - loss: 0.01
93 - acc: 0.9918 - val_loss: 0.1576 - val_acc: 0.9610
Epoch 242/300
7352/7352 [=====] - 1s 119us/step - loss: 0.01
96 - acc: 0.9929 - val_loss: 0.1844 - val_acc: 0.9545
Epoch 243/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
24 - acc: 0.9910 - val_loss: 0.1409 - val_acc: 0.9637
Epoch 244/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
07 - acc: 0.9921 - val_loss: 0.1601 - val_acc: 0.9572
Epoch 245/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
34 - acc: 0.9908 - val_loss: 0.1599 - val_acc: 0.9586
Epoch 246/300
7352/7352 [=====] - 1s 121us/step - loss: 0.01
```

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89 - acc: 0.9924 - val_loss: 0.1617 - val_acc: 0.9583
Epoch 247/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
92 - acc: 0.9936 - val_loss: 0.2374 - val_acc: 0.9444
Epoch 248/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
32 - acc: 0.9909 - val_loss: 0.1369 - val_acc: 0.9667
Epoch 249/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
01 - acc: 0.9916 - val_loss: 0.1641 - val_acc: 0.9579
Epoch 250/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
16 - acc: 0.9913 - val_loss: 0.1720 - val_acc: 0.9562
Epoch 251/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
01 - acc: 0.9928 - val_loss: 0.1703 - val_acc: 0.9603
Epoch 252/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
19 - acc: 0.9912 - val_loss: 0.1875 - val_acc: 0.9555
Epoch 253/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
22 - acc: 0.9918 - val_loss: 0.1905 - val_acc: 0.9508
Epoch 254/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
93 - acc: 0.9924 - val_loss: 0.2275 - val_acc: 0.9464
Epoch 255/300
7352/7352 [=====] - 1s 118us/step - loss: 0.02
05 - acc: 0.9927 - val_loss: 0.1790 - val_acc: 0.9562
Epoch 256/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
11 - acc: 0.9920 - val_loss: 0.1437 - val_acc: 0.9637
Epoch 257/300
7352/7352 [=====] - 1s 122us/step - loss: 0.02
21 - acc: 0.9916 - val_loss: 0.1537 - val_acc: 0.9661
Epoch 258/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
20 - acc: 0.9913 - val_loss: 0.1390 - val_acc: 0.9650
Epoch 259/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
```

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06 - acc: 0.9912 - val_loss: 0.1675 - val_acc: 0.9562
Epoch 260/300
7352/7352 [=====] - 1s 121us/step - loss: 0.02
00 - acc: 0.9932 - val_loss: 0.1735 - val_acc: 0.9600
Epoch 261/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
78 - acc: 0.9893 - val_loss: 0.1580 - val_acc: 0.9623
Epoch 262/300
7352/7352 [=====] - 1s 117us/step - loss: 0.01
92 - acc: 0.9928 - val_loss: 0.1700 - val_acc: 0.9566
Epoch 263/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
02 - acc: 0.9918 - val_loss: 0.1703 - val_acc: 0.9617
Epoch 264/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
69 - acc: 0.9931 - val_loss: 0.1742 - val_acc: 0.9579
Epoch 265/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
05 - acc: 0.9918 - val_loss: 0.1898 - val_acc: 0.9528
Epoch 266/300
7352/7352 [=====] - 1s 119us/step - loss: 0.01
65 - acc: 0.9937 - val_loss: 0.1540 - val_acc: 0.9620
Epoch 267/300
7352/7352 [=====] - 1s 119us/step - loss: 0.01
90 - acc: 0.9932 - val_loss: 0.1674 - val_acc: 0.9603
Epoch 268/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
28 - acc: 0.9901 - val_loss: 0.2336 - val_acc: 0.9454
Epoch 269/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
08 - acc: 0.9921 - val_loss: 0.1613 - val_acc: 0.9600
Epoch 270/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
99 - acc: 0.9921 - val_loss: 0.2037 - val_acc: 0.9474
Epoch 271/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
01 - acc: 0.9920 - val_loss: 0.1571 - val_acc: 0.9596
Epoch 272/300
7352/7352 [=====] - 1s 124us/step - loss: 0.01
```



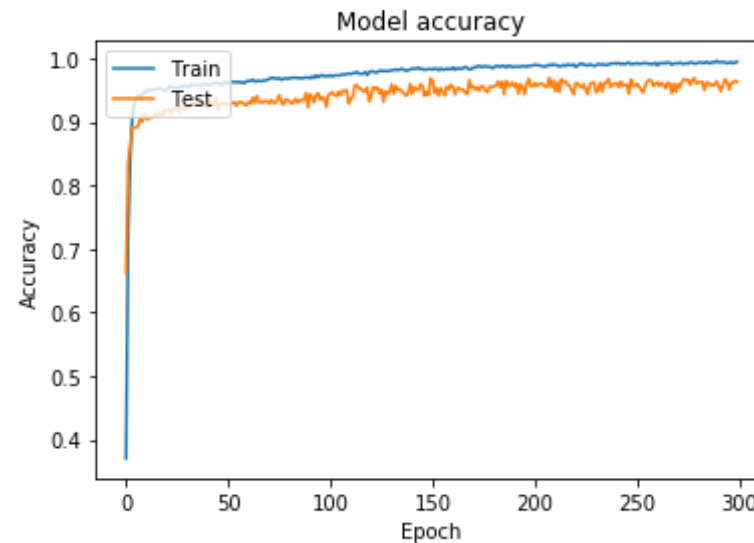
```
69 - acc: 0.9935 - val_loss: 0.2013 - val_acc: 0.9545
Epoch 273/300
7352/7352 [=====] - 1s 124us/step - loss: 0.02
04 - acc: 0.9916 - val_loss: 0.1543 - val_acc: 0.9627
Epoch 274/300
7352/7352 [=====] - 1s 125us/step - loss: 0.02
13 - acc: 0.9914 - val_loss: 0.1377 - val_acc: 0.9674
Epoch 275/300
7352/7352 [=====] - 1s 127us/step - loss: 0.02
13 - acc: 0.9924 - val_loss: 0.1419 - val_acc: 0.9654
Epoch 276/300
7352/7352 [=====] - 1s 126us/step - loss: 0.01
94 - acc: 0.9917 - val_loss: 0.1406 - val_acc: 0.9664
Epoch 277/300
7352/7352 [=====] - 1s 124us/step - loss: 0.01
58 - acc: 0.9939 - val_loss: 0.1931 - val_acc: 0.9586
Epoch 278/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
67 - acc: 0.9935 - val_loss: 0.1506 - val_acc: 0.9654
Epoch 279/300
7352/7352 [=====] - 1s 119us/step - loss: 0.02
02 - acc: 0.9917 - val_loss: 0.1365 - val_acc: 0.9691
Epoch 280/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
90 - acc: 0.9920 - val_loss: 0.1658 - val_acc: 0.9606
Epoch 281/300
7352/7352 [=====] - 1s 119us/step - loss: 0.01
78 - acc: 0.9933 - val_loss: 0.1570 - val_acc: 0.9620
Epoch 282/300
7352/7352 [=====] - 1s 119us/step - loss: 0.01
62 - acc: 0.9940 - val_loss: 0.1546 - val_acc: 0.9627
Epoch 283/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
75 - acc: 0.9929 - val_loss: 0.1720 - val_acc: 0.9627
Epoch 284/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
73 - acc: 0.9927 - val_loss: 0.2060 - val_acc: 0.9498
Epoch 285/300
7352/7352 [=====] - 1s 121us/step - loss: 0.01
```

```
54 - acc: 0.9947 - val_loss: 0.1514 - val_acc: 0.9617
Epoch 286/300
7352/7352 [=====] - 1s 124us/step - loss: 0.01
66 - acc: 0.9928 - val_loss: 0.1656 - val_acc: 0.9617
Epoch 287/300
7352/7352 [=====] - 1s 120us/step - loss: 0.02
07 - acc: 0.9920 - val_loss: 0.1736 - val_acc: 0.9576
Epoch 288/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
55 - acc: 0.9947 - val_loss: 0.1548 - val_acc: 0.9589
Epoch 289/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
62 - acc: 0.9935 - val_loss: 0.1592 - val_acc: 0.9579
Epoch 290/300
7352/7352 [=====] - 1s 120us/step - loss: 0.01
25 - acc: 0.9962 - val_loss: 0.1570 - val_acc: 0.9637
Epoch 291/300
7352/7352 [=====] - 1s 124us/step - loss: 0.01
74 - acc: 0.9937 - val_loss: 0.1811 - val_acc: 0.9569
Epoch 292/300
7352/7352 [=====] - 1s 123us/step - loss: 0.01
54 - acc: 0.9944 - val_loss: 0.2292 - val_acc: 0.9481
Epoch 293/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
59 - acc: 0.9939 - val_loss: 0.1810 - val_acc: 0.9572
Epoch 294/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
54 - acc: 0.9940 - val_loss: 0.1417 - val_acc: 0.9671
Epoch 295/300
7352/7352 [=====] - 1s 121us/step - loss: 0.01
69 - acc: 0.9924 - val_loss: 0.1630 - val_acc: 0.9634
Epoch 296/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
82 - acc: 0.9931 - val_loss: 0.2041 - val_acc: 0.9511
Epoch 297/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
55 - acc: 0.9943 - val_loss: 0.1862 - val_acc: 0.9610
Epoch 298/300
7352/7352 [=====] - 1s 123us/step - loss: 0.01
```

```
84 - acc: 0.9922 - val_loss: 0.1728 - val_acc: 0.9613
Epoch 299/300
7352/7352 [=====] - 1s 121us/step - loss: 0.01
50 - acc: 0.9933 - val_loss: 0.1495 - val_acc: 0.9647
Epoch 300/300
7352/7352 [=====] - 1s 122us/step - loss: 0.01
43 - acc: 0.9947 - val_loss: 0.1655 - val_acc: 0.9630
```

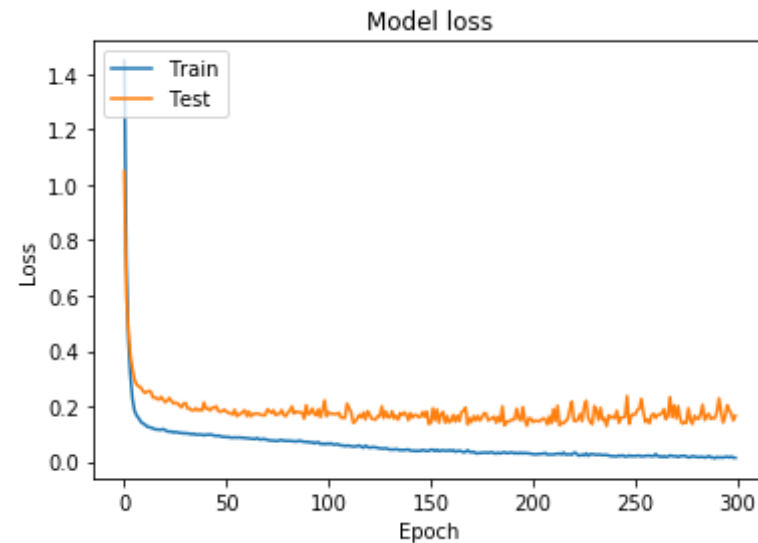
```
In [0]: import matplotlib.pyplot as plt

# Plot training & validation accuracy values
plt.plot(history.history['acc'])
plt.plot(history.history['val_acc'])
plt.title('Model accuracy')
plt.ylabel('Accuracy')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
In [0]: # Plot training & validation loss values
plt.plot(history.history['loss'])
```

```
plt.plot(history.history['val_loss'])
plt.title('Model loss')
plt.ylabel('Loss')
plt.xlabel('Epoch')
plt.legend(['Train', 'Test'], loc='upper left')
plt.show()
```



```
In [0]: # Confusion Matrix
# print(confusion_matrix(Y_test, model.predict(X_test)))
conf = pd.DataFrame(confusion_matrix(Y_test, model.predict(X_test)))
conf
```

Out[0]:

	Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTA
True						
LAYING		537	0	0	0	0
SITTING		0	438	53	0	0
STANDING		0	9	523	0	0

	Pred	LAYING	SITTING	STANDING	WALKING	WALKING_DOWNSTAIRS
	True					
WALKING		0	3	0	480	13
WALKING_DOWNSTAIRS		0	0	0	0	405
WALKING_UPSTAIRS		0	2	0	0	14

```
In [0]: score = model.evaluate(X_test, Y_test)
```

```
2947/2947 [=====] - 0s 79us/step
```

```
In [0]: score
```

```
Out[0]: [0.1655390887501719, 0.9630132337970818]
```

```
In [0]: score_train = model.evaluate(X_train, Y_train)
score_train
```

```
7352/7352 [=====] - 1s 74us/step
```

```
Out[0]: [0.008311180752592058, 0.9970076169749728]
```

7. Comparing all ML models

```
In [0]: print('\n
print('
print('Logistic Regression : {:.04}%
_results['accuracy'] * 100,\
Accuracy      Error')
-----
 {:.04}%'.format(log_reg_grid
_results['accuracy'] * 100,\
100-(log_reg_grid_res
_results['accuracy'] * 100)))

print('Linear SVC
_results['accuracy'] * 100,\
Accuracy      Error')
-----
 {:.04}%'.format(lr_svc_grid
_results['accuracy'] * 100,\
100-(lr_svc_gri
```

```

d_results['accuracy'] * 100)))

print('rbf SVM classifier : {:.04}%      {:.04}% '.format(rbf_svm_grid
_results['accuracy'] * 100,\
                                                             100-(rbf_svm_
grid_results['accuracy'] * 100)))

print('DecisionTree      : {:.04}%      {:.04}% '.format(dt_grid_resu
lts['accuracy'] * 100,\
                                                             100-(dt_grid_re
sults['accuracy'] * 100)))

print('Random Forest     : {:.04}%      {:.04}% '.format(rfc_grid_res
ults['accuracy'] * 100,\
                                                             100-(rfc_gri
d_results['accuracy'] * 100)))
print('GradientBoosting DT : {:.04}%      {:.04}% '.format(rfc_grid_res
ults['accuracy'] * 100,\
                                                             100-(rfc_grid_r
esults['accuracy'] * 100)))

```

	Accuracy	Error
	-----	-----
Logistic Regression	: 96.27%	3.733%
Linear SVC	: 96.61%	3.393%
rbf SVM classifier	: 96.27%	3.733%
DecisionTree	: 86.43%	13.57%
Random Forest	: 91.31%	8.687%
GradientBoosting DT	: 91.31%	8.687%

We can choose **Logistic regression** or **Linear SVC** or **rbf SVM**.

Conclusion :

This project is to build a model that predicts the human activities such as Walking, Walking_Upstairs, Walking_Downstairs, Sitting, Standing or Laying.

These sensor signals are preprocessed by applying noise filters and then sampled in fixed-width windows(sliding windows) of 2.56 seconds each with 50% overlap. ie., each window has 128 readings.

- Jerk signals are calculated for BodyAcceleration readings.
- Fourier Transforms are made on the above time readings to obtain frequency readings.
- Now, on all the base signal readings., mean, max, mad, sma, arcoefficient, engerybands,entropy etc., are calculated for each window.
- We get a feature vector of 561 features and these features are given in the dataset.
- Each window of readings is a datapoint of 561 features.

Splited the data

Removed dublicates

Removed nan values

This is balanced dataset

Performed EDA

Stationary and Moving activities are completely different

Magnitude of an acceleration can saperate it well

Position of GravityAccelerationComponants also matters

Apply t-sne on the data

Let's model with our data

Linear SVC with GridSearch

Logistic Regression

Gradient Boosted

Decision Trees With GridSearch

Random Forest Classifier with GridSearch

Decision Trees with GridSearchCV

Kernel SVM with GridSearch

Deep learning

LSTM for n_hidden layer-30

- 0.8934509670851714

LSTM for n_hidden layer-50

- 0.9277231082456736

LSTM for n_hidden layer-50 using bias_initializer='zeros'

- 0.9209365456396336

LSTM for 2-layers

- 0.9141499830335935

LSTM for n_hidden layer-50 using glorot_initializer-

- 0.909365456396336

CNN with 300 units and kernel size and max-pool-15=

-0.9433322022395657

2 layers of CNN with 300 units and kernel size and max-pool
-15= -0.9192399049881235

CNN + LSTM-
0.9277231082456736

2 CNN layers + 3 Pooling layers + one Dropout layer
0.9630132337970818