

Recap : Error Analysis

Error = True value - Approx. value

$$e = f(x) - \tilde{f}(x)$$

$$e = x - \tilde{x}$$

Relative error

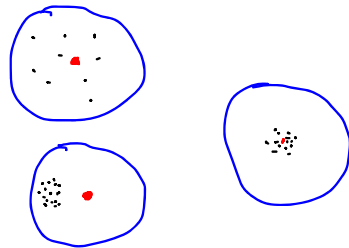
$$e_r = \frac{f(x) - \tilde{f}(x)}{f(x)} \quad f(x) \neq 0$$

$$e_r = \frac{x - \tilde{x}}{x} \quad x \neq 0$$

True value is almost never known

Accuracy

Precision



1. Approximate value of error

Example - For iterative algorithms

ε = Current approximation - Previous approx.

$$\varepsilon_r = \frac{\text{Current approx} - \text{Previous approx.}}{\text{Current approx}}$$

2. Determine error bound

$$E \geq e$$

Truncation error

Taylor Series

$$f(x_{i+1}) = f(x_i) + (x_{i+1} - x_i) f'(x_i)$$

$$+ \frac{(x_{i+1} - x_i)^2}{2!} f''(x_i) +$$

$$+ \dots + \frac{(x_{i+1} - x_i)^n}{n!} f^{(n)}(x_i)$$

$$+ R$$

$$R = \frac{(x_{i+1} - x_i)^{n+1}}{(n+1)!} f^{(n+1)}(\xi)$$
$$x_i \leq \xi \leq x_{i+1}$$

Example

$$x_0 = 0 \quad f(x_0) = 1.2$$
$$x = 1 \quad f(x) = 0.2$$
$$f(x) = -0.1x^4 - 0.15x^3 - 0.5x^2 - 0.25x + 1.2$$

Zeroth order

$$\tilde{f}(x_{i+1}) = f(x_i) = 1.2$$

$$e = 0.2 - 1.2 = -1.0$$

$$R = \frac{(x_{i+1} - x_i)}{1!} f'(\xi)$$

$$f(x) = -0.4x^3 - 0.45x^2 - x - 0.25$$

$$E \geq |R|$$

$$E = 2.1$$

First order

$$f(x_{i+1}) = 0.95$$

$$e = 0.2 - 0.95 = -0.75$$

$$R = \frac{(x_{i+1} - x_i)^2}{2!} f''(\xi)$$

$$f''(x) = -1.2x^2 - 0.9x - 1$$

$$E = 1.55$$

$$e_q = 0.95 - 1.2 = -0.25$$

Order	$\tilde{f}(x_{i+1})$	$ e $	E	$ e_q $
0	1.2	1.0	2.1	—
1 st	0.95	0.75	1.55	0.25
2 nd	0.45	0.25	0.55	0.50
3 rd	0.30	0.10	0.10	0.15
4 th	0.20	0.0	0.0	0.10

Data error

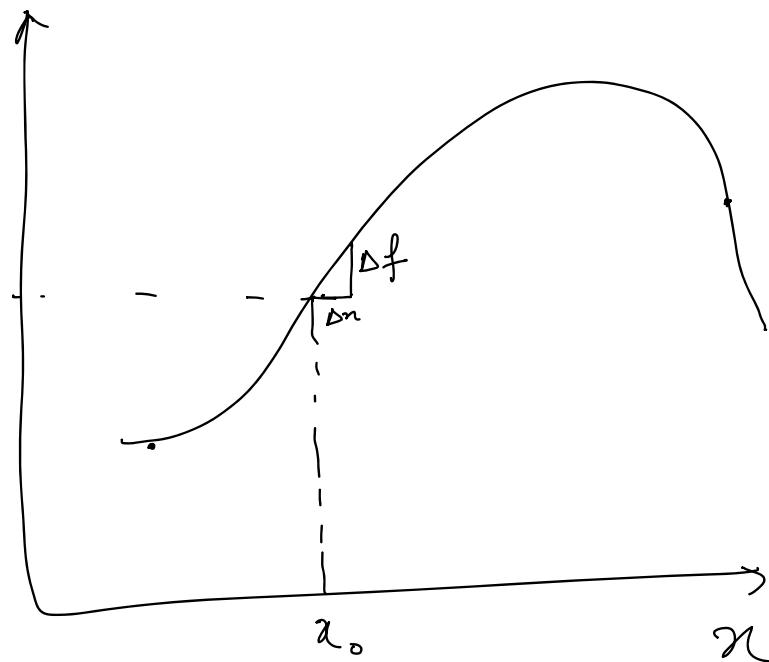
$$f(x + \Delta x) - f(x) = \Delta x f'(x) + \frac{\Delta x^2}{2!} f''(x) + \dots$$

propagation

First order error

$$f(x + \Delta x) - f(x) \approx \Delta x f'(x)$$

$f(x)$
 $f(x_0)$



$$\frac{\Delta f}{\Delta x} = f'(x)$$

$$\Delta f = \Delta x f'(x)$$

Example

$$g = \frac{2H}{t^2}$$

$$\Delta g \approx \left| \Delta t \frac{\partial g}{\partial t} \right| + \left| \Delta H \frac{\partial g}{\partial H} \right|$$

$$\Delta g \approx \left| \Delta t \frac{4H}{t^3} \right| + \left| \Delta H \frac{2}{H^2} \right|$$

$$H = 660 \pm 0.01 \text{ m}$$

$$t = 11.65 \pm 0.01 \text{ s}$$

$$\Delta g = 0.01 \times 1.67 + 0.01 \times 0.00147$$

$$= 0.016995 \text{ m/s}^2$$

Round-off error

Number representation

Integer — unsigned, signed ^{0, 1, 2} ^{-1, -2, 1, 2, 0}

Fixed-point — $\pi = 3.14$

Floating-point $\frac{1}{\sqrt{2}} = 0.71$

Floating point numbers

$$x = \pm m b^p$$

m - mantissa

b - base — 10

p - exponent

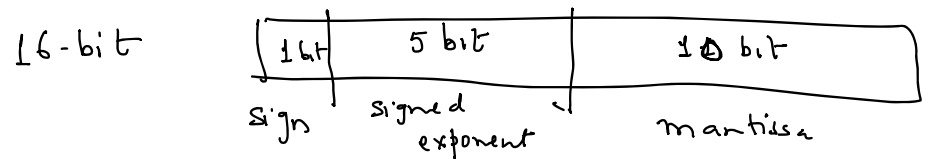
$$\boxed{} \times 10^{384}$$

Example

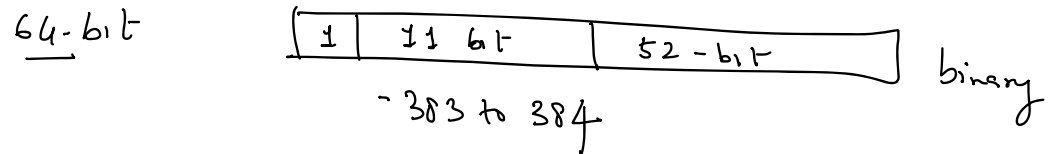
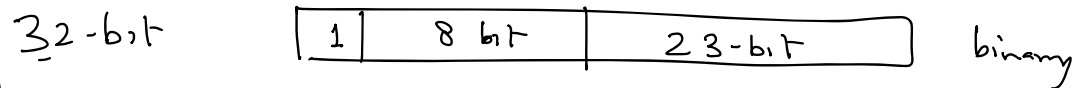
$$\pi = 0.314 \times 10^1$$

$$1/\sqrt{2} = 0.707 \times 10^0$$

To store floating point numbers, a "computer word" is divided into 3 parts



IEEE 754 technical standard



System - Decimal

3 decimal places - mantissa

1 place - exponent

$d \rightarrow p$

$$x = \pm 0. \underbrace{ddd}_m \underbrace{10}_b$$

Mantissa $\rightarrow \frac{1}{b} \leq m < 1$

Decimal minimum 0.100

maximum 0.999

Binary minimum $2^{-1} = 0.5$

maximum $2^{-1} + 2^{-2} + 2^{-3}$

3 - important properties

1. Maximum positive value

$$x_{\max} = 0.999 \times 10^9$$

$$x_{\min} = -0.999 \times 10^9$$

Overflow error

2. Hole near zero

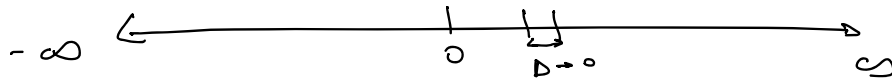
$$\left. \begin{array}{l} 0.000 \times 10^{-9} \\ 0.100 \times 10^{-9} \\ 0.101 \times 10^{-9} \end{array} \right\} \begin{array}{l} 10^{-9} \\ \\ -10^{-12} \end{array}$$

$$0.102 \times 10^{-9}$$

3. Interval between numbers increase

$$\begin{array}{rcl}
 0.998 \times 10^3 & \uparrow & 1 \\
 0.999 \times 10^3 & \uparrow & 2 \\
 0.100 \times 10^4 & \uparrow & 3 \\
 0.101 \times 10^4 & \uparrow & 10
 \end{array}$$

Mathematics



Computer

