# Mixed Hybrid Finite Element Method Eddington Acceleration of Discrete Ordinates Source Iteration

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Mathematics and Computation

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# **Overview**

- 1. Motivation
- 2. Source Iteration Background
- 3. Eddington Acceleration
- 4. Results
- 5. Conclusions

# Motivation

#### Motivation

#### Radiation Hydrodynamics

- Propogate thermal radiation through fluid
- Model effects of thermal radiation on fluid momentum and energy
- Required in high energy density laboratory physics and astrophysics

#### Efficient methods developed independently

- Mixed Hybrid Finite Element Method (MHFEM) for hydrodynamics
- Linear Discontinuous Galerkin (LDG) for transport

Need hydrodynamics and transport to be spatially discretized with the same method

- Interpolating between spatial grids introduces noise
- Matching grids between methods is not always possible in higher dimensions

#### Goal

Develop an acceleration scheme that

- Robustly reduces the number of source iterations in Discrete Ordinates calculations
- 2. Is compatible with MHFEM multiphysics

Show that MHFEM can be used to accelerate lumped LDG radiation transport

**Source Iteration Background** 

# **Boltzmann Equation**

Steady-state, mono-energetic, istropically-scattering, fixed-source Linear Boltzmann Equation in 1D slab geometry:

$$\mu \frac{\partial \psi}{\partial x}(x,\mu) + \Sigma_t(x)\psi(x,\mu) = \frac{\Sigma_s(x)}{2} \int_{-1}^1 \psi(x,\mu')d\mu' + \frac{Q(x)}{2}$$

 $\mu=\cos\theta$  the cosine of the angle of flight  $\theta$  relative to the x-axis  $\Sigma_t(x)$ ,  $\Sigma_s(x)$  total and scattering macroscopic cross sections Q(x) the isotropic fixed-source  $\psi(x,\mu)$  the angular flux

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### Integro-differential equation

# Discrete Ordinates $(S_N)$ Angular Discretization

Compute angular flux on N discrete angles

$$\psi(x,\mu) \xrightarrow{\mathsf{S}_N} \begin{cases} \psi_1(x), & \mu = \mu_1 \\ \psi_2(x), & \mu = \mu_2 \\ \vdots \\ \psi_N, & \mu = \mu_N \end{cases}$$

 $\mu_1,\ \mu_2,\ \dots,\ \mu_N$  defined by N-point Gauss Quadrature Rule Integrate order 2N-1 polynomials exactly with

$$\phi(x) = \int_{-1}^{1} \psi(x, \mu) d\mu \xrightarrow{S_N} \sum_{n=1}^{N} w_n \psi_n(x)$$

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# $S_N$ Equations

$$\mu_n \frac{\mathrm{d}\psi_n}{\mathrm{d}x}(x) + \Sigma_t(x)\psi_n(x) = \frac{\Sigma_s(x)}{2}\phi(x) + \frac{Q(x)}{2}, \ 1 \le n \le N$$
$$\phi(x) = \sum_{n=1}^N w_n \psi_n(x)$$

# N coupled, ordinary differential equations

All coupling in scattering term

#### Source Iteration

Decouple by lagging scattering term

$$\mu_n \frac{d\psi_n^{\ell+1}}{dx}(x) + \Sigma_t(x)\psi_n^{\ell+1}(x) = \frac{\Sigma_s(x)}{2}\phi^{\ell}(x) + \frac{Q(x)}{2}, 1 \le n \le N$$

### N independent, first-order, ordinary differential equations

Solve each equation with well-known sweeping process

#### **Source Iteration**

- 1. Given previous estimate for  $\phi^\ell(x),$  solve for  $\psi_n^{\ell+1}$
- 2. Compute  $\phi^{\ell+1}(x) = \sum_{n=1}^{N} w_n \psi_n^{\ell+1}(x)$
- 3. Update scattering term with  $\phi^{\ell+1}(x)$  and repeat until:

$$\frac{\|\phi^{\ell+1}(x) - \phi^{\ell}(x)\|}{\|\phi^{\ell+1}(x)\|} < \epsilon$$

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If 
$$\phi^0(x) = 0$$

$$\mu_n \frac{d\psi_n^1}{dx}(x) + \Sigma_t(x)\psi_n^1(x) = \frac{\Sigma_s(x)}{2}\phi^0(x) + \frac{Q(x)}{2}, 1 \le n \le N$$

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- $\phi^1(x)$  is the uncollided flux
- $\phi^2(x)$  is uncollided and once collided flux
- $\phi^\ell(x)$  is the scalar flux of particles that have undergone at most  $\ell-1$  collisions

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Slow to converge in optically thick systems with minimal losses to absorption and leakage

**Eddington Acceleration** 

# **Zeroth Angular Moment**

#### Boltzmann Equation

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Integrate over all angles

$$\int_{-1}^{1} \mu \frac{d\psi}{dx}(x,\mu) d\mu + \int_{-1}^{1} \Sigma_{t}(x)\psi(x,\mu) d\mu = \int_{-1}^{1} \frac{\Sigma_{s}(x)}{2} \phi(x) d\mu + \int_{-1}^{1} \frac{Q(x)}{2} d\mu$$

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Use 
$$J(x) = \int_{-1}^{1} \mu \psi(x, \mu) \, d\mu$$
,  $\phi(x) = \int_{-1}^{1} \psi(x, \mu) \, d\mu$ 

#### **Zeroth Angular Moment**

$$\frac{\mathrm{d}}{\mathrm{d}x}J(x) + \Sigma_a(x)\phi(x) = Q(x)$$

Multiply by  $\mu$  and integrate

$$\int_{-1}^{1} \mu^{2} \frac{\mathrm{d}\psi}{\mathrm{d}x}(x,\mu) \,\mathrm{d}\mu + \int_{-1}^{1} \mu \Sigma_{t}(x)\psi(x,\mu) \,\mathrm{d}\mu \ = \ \int_{-1}^{1} \mu \frac{\Sigma_{s}(x)}{2} \phi(x) \,\mathrm{d}\mu + \int_{-1}^{1} \mu \frac{Q(x)}{2} \,\mathrm{d}\mu$$

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$$\int_{-1}^1 \mu^2 \frac{\mathrm{d} \psi}{\mathrm{d} x}(x,\mu) \, \mathrm{d} \mu + \underbrace{\int_{-1}^1 \mu \Sigma_t(x) \psi(x,\mu) \, \mathrm{d} \mu}_{\Sigma_t(x)J(x)} = \int_{-1}^1 \mu \frac{\Sigma_s(x)}{2} \phi(x) \, \mathrm{d} \mu + \int_{-1}^1 \mu \frac{Q(x)}{2} \, \mathrm{d} \mu$$

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#### Multiply by $\mu$ and integrate

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Rearrange derivative

$$\frac{\mathrm{d}}{\mathrm{d}x} \int_{-1}^{1} \mu^2 \psi(x,\mu) \,\mathrm{d}\mu$$

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Multiply and divide by  $\int_{-1}^{1} \psi(x,\mu) d\mu$ 

$$\frac{\mathrm{d}}{\mathrm{d}x} \int_{-1}^{1} \psi(x,\mu) \,\mathrm{d}\mu \frac{\int_{-1}^{1} \mu^{2} \psi(x,\mu) \,\mathrm{d}\mu}{\int_{-1}^{1} \psi(x,\mu) \,\mathrm{d}\mu}$$

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**Eddington Factor** 

$$\langle \mu^2 \rangle(x) = \frac{\int_{-1}^1 \mu^2 \psi(x, \mu) \, d\mu}{\int_{-1}^1 \psi(x, \mu) \, d\mu}$$

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Shape function

# **Moment Equations**

$$\frac{\mathrm{d}}{\mathrm{d}x}J(x) + \Sigma_a(x)\phi(x) = Q(x) \tag{Zeroth Moment}$$

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 (Zeroth Moment)

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Solve First Moment for J(x)

$$J(x) = -\frac{1}{\Sigma_t(x)} \frac{\mathrm{d}}{\mathrm{d}x} \langle \mu^2 \rangle(x) \phi(x)$$

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Combine Zero and First Moments ⇒ Drift Diffusion Equation

$$-\frac{\mathrm{d}}{\mathrm{d}x}\frac{1}{\Sigma_t(x)}\frac{\mathrm{d}}{\mathrm{d}x}\langle\mu^2\rangle(x)\phi(x) + \Sigma_a(x)\phi(x) = Q(x)$$

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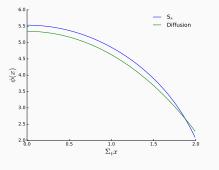
$$-\frac{\mathrm{d}}{\mathrm{d}x}\frac{1}{\Sigma_t(x)}\frac{\mathrm{d}}{\mathrm{d}x}\langle\mu^2\rangle(x)\phi(x) + \Sigma_a(x)\phi(x) = Q(x)$$

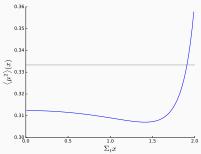
Fick's Law: set 
$$\langle \mu^2 \rangle(x) = \frac{1}{3}$$

$$J(x) = -\frac{1}{3\Sigma_t(x)} \frac{\mathrm{d}}{\mathrm{d}x} \phi(x)$$

# S<sub>8</sub> v. Diffusion

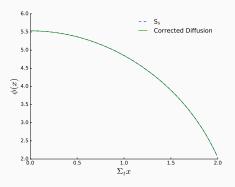
Small system  $\Rightarrow$  diffusion not expected to be accurate





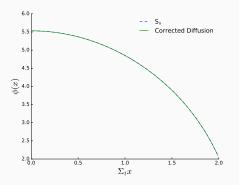
# S<sub>8</sub> v. Drift Diffusion

Use  $\langle \mu^2 \rangle(x)$  from S<sub>8</sub> in Moment Equations



# S<sub>8</sub> v. Drift Diffusion

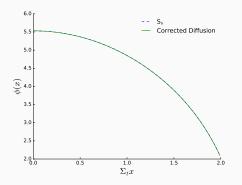
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Drift Diffusion and  $S_N$  match!

## S<sub>8</sub> v. Drift Diffusion

Use  $\langle \mu^2 \rangle(x)$  from S<sub>8</sub> in Moment Equations



Drift Diffusion and  $S_N$  match!

Requires knowledge of angular flux  $\,$ 

## **Eddington Acceleration**

Use  $S_N$  to compute  $\langle \mu^2 \rangle(x)$  and Moment Equations to find  $\phi(x)$ 

#### **Eddington Acceleration**

- 1. Given the previous estimate for the scalar flux,  $\phi^\ell(x)$ , solve for  $\psi_n^{\ell+1/2}(x)$
- 2. Compute  $\langle \mu^2 \rangle^{\ell+1/2}(x)$
- 3. Solve the Moment Equations for  $\phi^{\ell+1}(x)$  using  $\langle \mu^2 \rangle^{\ell+1/2}(x)$
- 4. Update the scalar flux estimate with  $\phi^{\ell+1}(x)$  and repeat the iteration process until the scalar flux converges

#### Acceleration occurs due to:

- 1. Angular shape of the angular flux converges quickly  $\Rightarrow$  Eddington factor quickly converges
- 2. Solution to moment equations models all scattering events at once
- 3. Dependence on source iterations to introduce scattering information is reduced

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#### **Benefits**

- 1. No need for consistent differencing  $\Rightarrow$  transport can be LDG and acceleration can be MHFEM
- 2. Accelerates source iterations
- Moment Equations are conservative and relatively inexpensive compared to transport sweep
- 4. Difference between  $S_N$  and Moment solution can be used as a measure of spatial truncation error (measure of mesh convergence)

# Results

Scale cross sections, source

$$\Sigma_t \to \Sigma_t/\epsilon$$

$$\Sigma_a \to \epsilon \Sigma_a$$

$$Q \to \epsilon Q$$

System becomes diffusive as  $\epsilon \to 0$ 

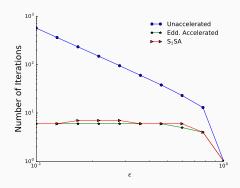
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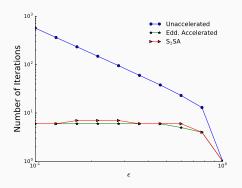
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Accelerates source iteration, survives diffusion limit

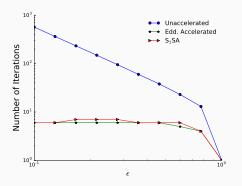
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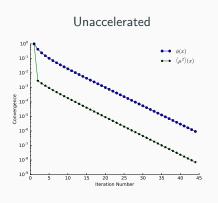
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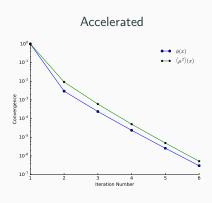


Accelerates source iteration, survives diffusion limit

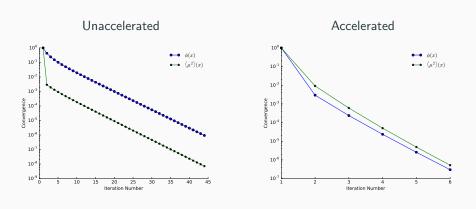
Performs similarly to consistently differenced, linear acceleration (S2SA)

# **Convergence Rate Comparison**





# **Convergence Rate Comparison**



Fast rate of convergence of  $\langle \mu^2 \rangle(x)$  is transfered to  $\phi(x)$ 

# **Solution Convergence**

Compare

$$\frac{\|\phi_{\mathsf{S}_N}(x) - \phi_{\mathsf{Moment}}(x)\|}{\|\phi_{\mathsf{Moment}}(x)\|}$$

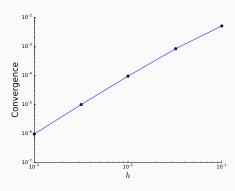
 $\text{ as } h \to 0$ 

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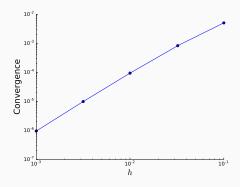


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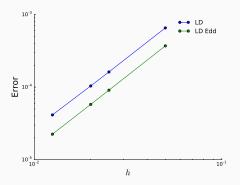


 $\mathsf{S}_N$  and Moment solutions converge

# Method of Manufactured Solutions Order of Accuracy

Set source term to force solution to

$$\phi(x) = \sin\left(\frac{\pi x}{x_b}\right)$$



Both second order accurate

# Conclusions

### **Summary**

#### Conclusions

- Scheme successfully accelerated source iteration in 1D slab geometry
- Inherently compatible with rad-hydro multiphysics
  - Transport and acceleration steps can be discretized with arbitrarily different methods
  - Avoids consistency issues
  - Provides less expensive, conservative solution
- Proved Mixed Hybrid Finite Element Method can be used to accelerate lumped Linear Discontinuous Galerkin transport

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#### Future Work

- Develop a rad-hydro algorithm
  - Make use of inexpensive Moment solution in multiphysics iterations
- Add discretization in energy
- Higher dimensions
- Anisotropic scattering
- Implement LDG basis functions in MHFEM

#### References

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