

Mixed Hybrid Finite Element Method

Eddington Acceleration of Discrete Ordinates

Source Iteration

ANS Student Conference

Mathematics and Computation

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NUCLEAR ENGINEERING
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1. Motivation
2. Source Iteration Background
3. Eddington Acceleration
4. Results
5. Conclusions

Motivation

Motivation

Radiation Hydrodynamics

- Propagate thermal radiation through fluid
- Model effect of thermal radiation on fluid momentum and energy
- Required in high energy density laboratory physics (NIF, Z Machine) and astrophysics

Efficient methods developed independently

- Mixed Hybrid Finite Element Method (MHFEM) for hydrodynamics
- Linear Discontinuous Galerkin (LDG) for transport

Need hydrodynamics and transport to be spatially discretized with the same method

- Interpolating between spatial grids introduces noise
- Matching grids between methods is not always possible in higher dimensions

Goal

Develop an acceleration scheme that

1. Robustly reduces the number of source iterations in Discrete Ordinates calculations
2. Is compatible with MHFEM multiphysics

Show that MHFEM can be used to accelerate lumped LDG radiation transport

Source Iteration Background

Boltzmann Equation

Steady-state, mono-energetic, isotropically-scattering, fixed-source Linear Boltzmann Equation in 1D slab geometry:

$$\mu \frac{\partial \psi}{\partial x}(x, \mu) + \Sigma_t(x) \psi(x, \mu) = \frac{\Sigma_s(x)}{2} \int_{-1}^1 \psi(x, \mu') d\mu' + \frac{Q(x)}{2}$$

$\mu = \cos \theta$ the cosine of the angle of flight θ relative to the x -axis

$\Sigma_t(x)$, $\Sigma_s(x)$ total and scattering macroscopic cross sections

$Q(x)$ the isotropic fixed-source

$\psi(x, \mu)$ the angular flux

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Integro-differential equation

Discrete Ordinates (S_N) Angular Discretization

Compute angular flux on N discrete angles

$$\psi(x, \mu) \xrightarrow{S_N} \begin{cases} \psi_1(x), & \mu = \mu_1 \\ \psi_2(x), & \mu = \mu_2 \\ \vdots \\ \psi_N, & \mu = \mu_N \end{cases}$$

$\mu_1, \mu_2, \dots, \mu_N$ defined by N -point Gauss Quadrature Rule

Integrate order $2N - 1$ polynomials exactly with

$$\phi(x) = \int_{-1}^1 \psi(x, \mu) d\mu \xrightarrow{S_N} \sum_{n=1}^N w_n \psi_n(x)$$

$$\mu_n \frac{d\psi_n}{dx}(x) + \Sigma_t(x)\psi_n(x) = \frac{\Sigma_s(x)}{2}\phi(x) + \frac{Q(x)}{2}, 1 \leq n \leq N$$

$$\phi(x) = \sum_{n=1}^N w_n \psi_n(x)$$

N coupled, ordinary differential equations

All coupling in scattering term

Source Iteration

Decouple by lagging scattering term

$$\mu_n \frac{d\psi_n^{\ell+1}}{dx}(x) + \Sigma_t(x)\psi_n^{\ell+1}(x) = \frac{\Sigma_s(x)}{2}\phi^\ell(x) + \frac{Q(x)}{2}, 1 \leq n \leq N$$

N independent, first-order, ordinary differential equations

Solve each equation with well-known sweeping process

Source Iteration

1. Given previous estimate for $\phi^\ell(x)$, solve for $\psi_n^{\ell+1}$
2. Compute $\phi^{\ell+1}(x) = \sum_{n=1}^N w_n \psi_n^{\ell+1}(x)$
3. Update scattering term with $\phi^{\ell+1}(x)$ and repeat until:

$$\frac{\|\phi^{\ell+1}(x) - \phi^\ell(x)\|}{\|\phi^{\ell+1}(x)\|} < \epsilon$$

Need For Acceleration in Source Iteration

Convergence rate is linked to the number of collisions in a particle's lifetime

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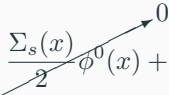
If $\phi^0(x) = 0$

$$\mu_n \frac{d\psi_n^1}{dx}(x) + \Sigma_t(x)\psi_n^1(x) = \frac{\Sigma_s(x)}{2}\phi^0(x) + \frac{Q(x)}{2}, 1 \leq n \leq N$$

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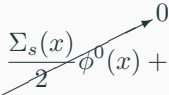
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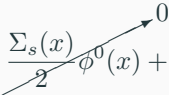
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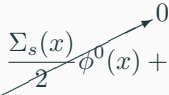
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$\phi^2(x)$ is uncollided and once collided flux

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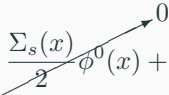
$\phi^2(x)$ is uncollided and once collided flux

$\phi^\ell(x)$ is the scalar flux of particles that have undergone at most $\ell - 1$ collisions

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Slow to converge in optically thick systems with minimal losses to absorption and leakage

Eddington Acceleration

Zeroth Angular Moment

Boltzmann Equation

$$\mu \frac{d\psi}{dx}(x, \mu) + \Sigma_t(x)\psi(x, \mu) = \frac{\Sigma_s(x)}{2}\phi(x) + \frac{Q(x)}{2}$$

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Integrate over all angles

$$\int_{-1}^1 \mu \frac{d\psi}{dx}(x, \mu) d\mu + \int_{-1}^1 \Sigma_t(x)\psi(x, \mu) d\mu = \int_{-1}^1 \frac{\Sigma_s(x)}{2}\phi(x) d\mu + \int_{-1}^1 \frac{Q(x)}{2} d\mu$$

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Use $J(x) = \int_{-1}^1 \mu\psi(x, \mu) d\mu$, $\phi(x) = \int_{-1}^1 \psi(x, \mu) d\mu$

Zeroth Angular Moment

$$\frac{d}{dx}J(x) + \Sigma_a(x)\phi(x) = Q(x)$$

First Angular Moment

Multiply by μ and integrate

$$\int_{-1}^1 \mu^2 \frac{d\psi}{dx}(x, \mu) d\mu + \int_{-1}^1 \mu \Sigma_t(x) \psi(x, \mu) d\mu = \int_{-1}^1 \mu \frac{\Sigma_s(x)}{2} \phi(x) d\mu + \int_{-1}^1 \mu \frac{Q(x)}{2} d\mu$$

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$$\int_{-1}^1 \mu^2 \frac{d\psi}{dx}(x, \mu) d\mu + \underbrace{\int_{-1}^1 \mu \Sigma_t(x) \psi(x, \mu) d\mu}_{\Sigma_t(x) J(x)} = \int_{-1}^1 \mu \frac{\Sigma_s(x)}{2} \phi(x) d\mu + \int_{-1}^1 \mu \frac{Q(x)}{2} d\mu$$

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Eddington Factor

Rearrange derivative

$$\frac{d}{dx} \int_{-1}^1 \mu^2 \psi(x, \mu) d\mu$$

Eddington Factor

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$$\frac{d}{dx} \int_{-1}^1 \mu^2 \psi(x, \mu) d\mu$$

Multiply and divide by $\int_{-1}^1 \psi(x, \mu) d\mu$

$$\frac{d}{dx} \int_{-1}^1 \psi(x, \mu) d\mu \frac{\int_{-1}^1 \mu^2 \psi(x, \mu) d\mu}{\int_{-1}^1 \psi(x, \mu) d\mu}$$

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$$\langle \mu^2 \rangle(x) = \frac{\int_{-1}^1 \mu^2 \psi(x, \mu) d\mu}{\int_{-1}^1 \psi(x, \mu) d\mu}$$

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Shape function

Moment Equations

Moment Equations

$$\frac{d}{dx}J(x) + \Sigma_a(x)\phi(x) = Q(x) \quad (\text{Zeroth Moment})$$

$$\frac{d}{dx}\langle\mu^2\rangle(x)\phi(x) + \Sigma_t(x)J(x) = 0 \quad (\text{First Moment})$$

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Solve First Moment for $J(x)$

$$J(x) = -\frac{1}{\Sigma_t(x)} \frac{d}{dx} \langle\mu^2\rangle(x)\phi(x)$$

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Combine Zero and First Moments \Rightarrow Drift Diffusion Equation

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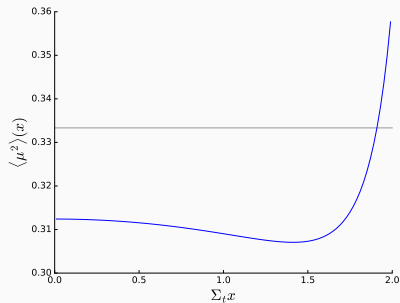
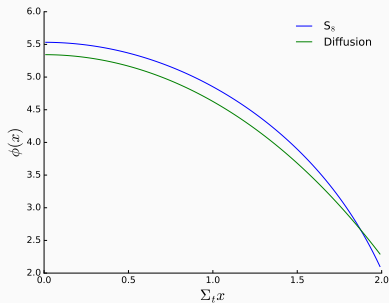
$$-\frac{d}{dx} \frac{1}{\Sigma_t(x)} \frac{d}{dx} \langle \mu^2 \rangle(x) \phi(x) + \Sigma_a(x) \phi(x) = Q(x)$$

Recover Diffusion Equation by setting $\langle \mu^2 \rangle(x) = \frac{1}{3}$

$$J(x) = -\frac{1}{3\Sigma_t(x)} \frac{d}{dx} \phi(x)$$

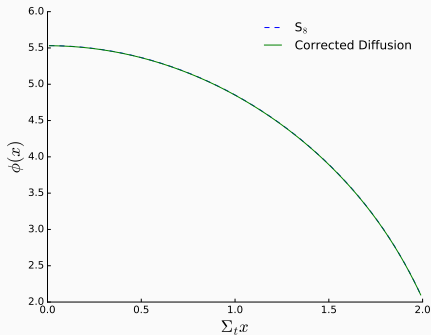
S_8 v. Diffusion

Small system \Rightarrow diffusion not expected to be accurate



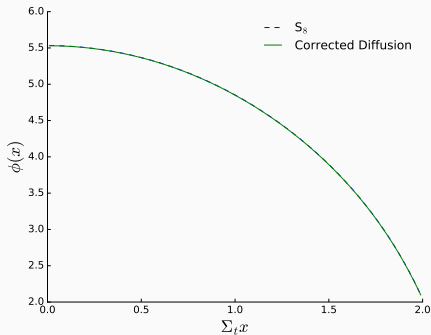
S_8 v. Drift Diffusion

Use $\langle \mu^2 \rangle(x)$ from S_8 in Moment Equations



S_8 v. Drift Diffusion

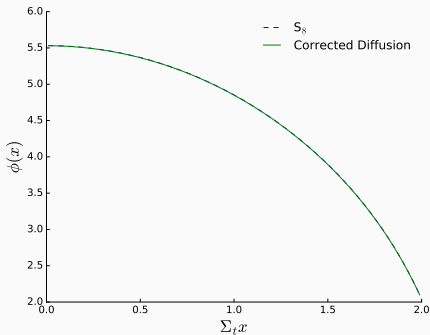
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Moment Equations and S_N match!

S_8 v. Drift Diffusion

Use $\langle \mu^2 \rangle(x)$ from S_8 in Moment Equations



Moment Equations and S_N match!

Requires knowledge of angular flux

Use S_N to compute $\langle \mu^2 \rangle(x)$ and Moment Equations to find $\phi(x)$

Eddington Acceleration

1. Given the previous estimate for the scalar flux, $\phi^\ell(x)$, solve for $\psi_n^{\ell+1/2}(x)$
2. Compute $\langle \mu^2 \rangle^{\ell+1/2}(x)$
3. Solve the Moment Equations for $\phi^{\ell+1}(x)$ using $\langle \mu^2 \rangle^{\ell+1/2}(x)$
4. Update the scalar flux estimate with $\phi^{\ell+1}(x)$ and repeat the iteration process until the scalar flux converges

Eddington Acceleration Properties

Acceleration occurs due to:

1. Angular shape of the angular flux converges quickly \Rightarrow Eddington factor quickly converges
2. Solution to moment equations models all scattering events at once
3. Dependence on source iterations to introduce scattering information is reduced

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Benefits

1. No need for consistent differencing \Rightarrow transport can be LDG and acceleration can be MHFEM
2. Accelerates source iterations
3. Moment Equations are conservative and relatively inexpensive compared to transport sweep
4. Difference between S_N and Moment solution can be used as a measure of spatial truncation error (measure of mesh convergence)

Results

Diffusion Limit

Scale cross sections, source

$$\Sigma_t \rightarrow \Sigma_t/\epsilon$$

$$\Sigma_a \rightarrow \epsilon \Sigma_a$$

$$Q \rightarrow \epsilon Q$$

System becomes diffusive as $\epsilon \rightarrow 0$

Diffusion Limit

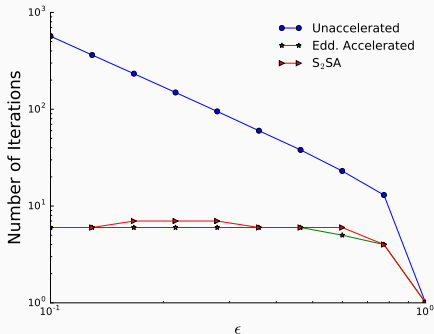
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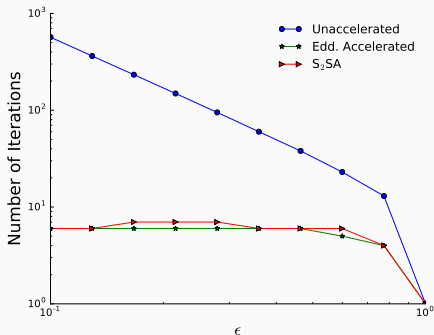
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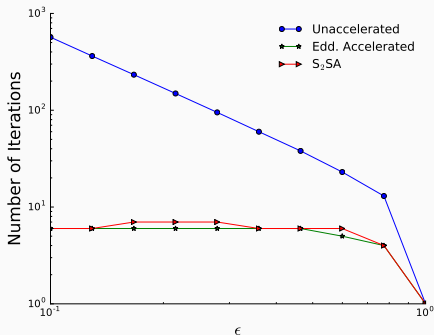
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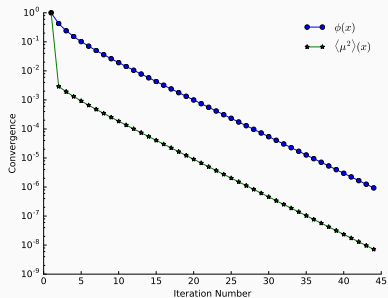


Accelerates source iteration, survives diffusion limit

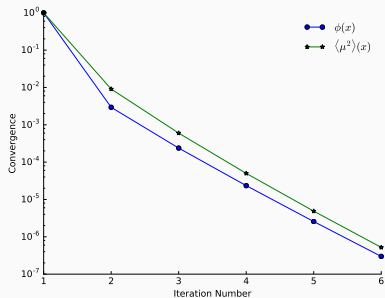
Performs similarly to consistently differenced, linear acceleration (S_2SA)

Convergence Rate Comparison

Unaccelerated

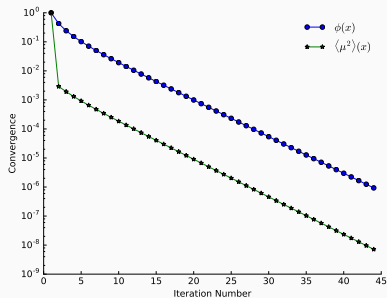


Accelerated

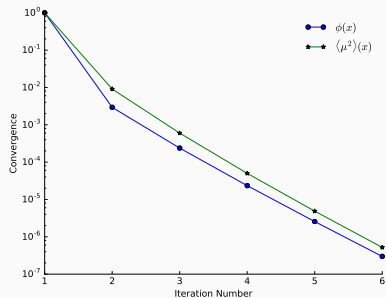


Convergence Rate Comparison

Unaccelerated



Accelerated



Fast rate of convergence of $\langle \mu^2 \rangle(x)$ is transferred to $\phi(x)$

Solution Convergence

Compare

$$\frac{\|\phi_{S_N}(x) - \phi_{\text{Moment}}(x)\|}{\|\phi_{\text{Moment}}(x)\|}$$

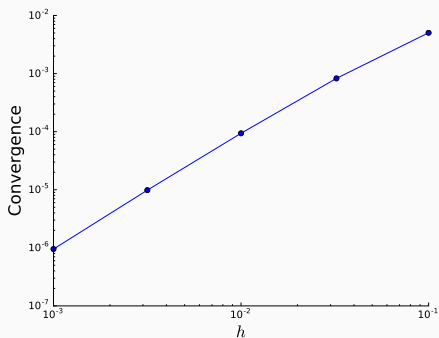
as $h \rightarrow 0$

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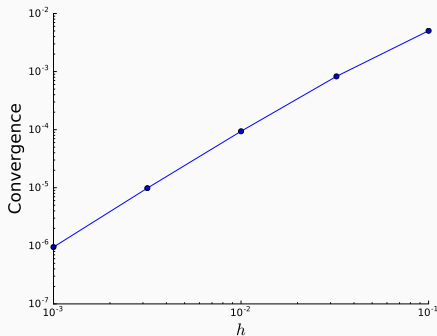


Solution Convergence

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$$\frac{\|\phi_{S_N}(x) - \phi_{\text{Moment}}(x)\|}{\|\phi_{\text{Moment}}(x)\|}$$

as $h \rightarrow 0$



S_N and Moment solutions converge as mesh is refined

Method of Manufactured Solutions Order of Accuracy

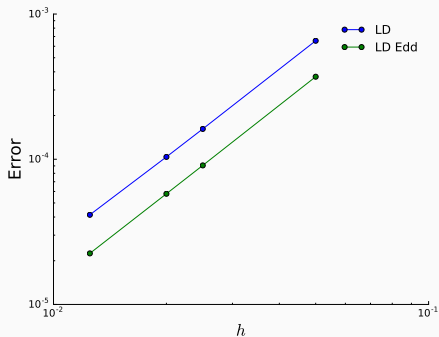
Set source term to force solution to

$$\phi(x) = \sin\left(\frac{\pi x}{x_b}\right)$$

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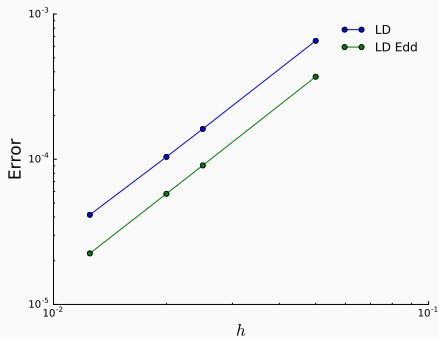
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Method of Manufactured Solutions Order of Accuracy

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Both second order accurate

Conclusions

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- Inherently compatible with rad-hydro multiphysics
 - Transport and acceleration steps can be discretized with arbitrarily different methods
 - Avoids consistency issues
 - Provides less expensive, conservative solution
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Summary

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- Inherently compatible with rad-hydro multiphysics
 - Transport and acceleration steps can be discretized with arbitrarily different methods
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Future Work

- Develop a rad-hydro algorithm
 - Make use of inexpensive Moment solution in multiphysics iterations
- Add discretization in energy
- Higher dimensions
- Anisotropic scattering
- Implement LDG basis functions in MHFEM

References

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Questions?