Mixed Hybrid Finite Element Eddington Acceleration of Discrete Ordinates Source Iteration

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Mathematics and Computation

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Overview

- 1. Motivation
- 2. Source Iteration Background
- 3. Eddington Acceleration
- 4. Results
- 5. Conclusions

Motivation

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Radiation Hydrodynamics

- Describes the effects of emission, absorption, scattering on fluid momentum and energy
- Required in high energy density laboratory experiments (NIF, Z Machine) and astrophysics

Mixed Hybrid Finite Element Method (MHFEM) hydrodynamics

Problems

- MHFEM and first-order form of transport are incompatible ⇒ can't use linear acceleration scheme
- Radiation transport is expensive

Goal

Develop a transport algorithm that

- 1. Accelerates Discrete Ordinates Source Iteration
- Bridges Linear Discontinuous Galerkin (LDG) transport and MHFEM multiphysics

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Source Iteration Background

Boltzmann Equation

Steady-state, mono-energetic, istropically-scattering, fixed-source Linear Boltzmann Equation in 1D slab geometry:

$$\mu \frac{\partial \psi}{\partial x}(x,\mu) + \Sigma_t(x)\psi(x,\mu) = \frac{\Sigma_s(x)}{2} \int_{-1}^1 \psi(x,\mu')d\mu' + \frac{Q(x)}{2}$$

 $\mu=\cos\theta$ the cosine of the angle of flight θ relative to the x-axis $\Sigma_t(x)$, $\Sigma_s(x)$ total and scattering macroscopic cross sections Q(x) the isotropic fixed-source $\psi(x,\mu)$ the angular flux

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Integro-differential equation

Discrete Ordinates (S_N) Angular Discretization

Compute angular flux on N discrete angles

$$\psi(x,\mu) \xrightarrow{\mathsf{S}_N} \begin{cases} \psi_1(x), & \mu = \mu_1 \\ \psi_2(x), & \mu = \mu_2 \\ \vdots \\ \psi_N, & \mu = \mu_N \end{cases}$$

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 μ_1 , μ_2 , ..., μ_N defined by N-point Gauss Quadrature Rule

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 $\mu_1,\ \mu_2,\ \dots,\ \mu_N$ defined by N-point Gauss Quadrature Rule Integrate order 2N-1 polynomials exactly with

$$\phi(x) = \int_{-1}^{1} \psi(x, \mu) d\mu \xrightarrow{S_N} \sum_{n=1}^{N} w_n \psi_n(x)$$

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S_N Equations

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$$\mu_n \frac{\mathrm{d}\psi_n}{\mathrm{d}x}(x) + \Sigma_t(x)\psi_n(x) = \frac{\Sigma_s(x)}{2}\phi(x) + \frac{Q(x)}{2}, \ 1 \le n \le N$$
$$\phi(x) = \sum_{n=1}^N w_n \psi_n(x)$$

N coupled, ordinary differential equations

All coupling in scattering term

Source Iteration

Decouple by lagging scattering term

$$\mu_n \frac{d\psi_n^{\ell+1}}{dx}(x) + \Sigma_t(x)\psi_n^{\ell+1}(x) = \frac{\Sigma_s(x)}{2}\phi^{\ell}(x) + \frac{Q(x)}{2}, 1 \le n \le N$$

N independent, first-order, ordinary differential equations

Solve each equation with well-known sweeping process

Source Iteration

- 1. Given previous estimate for $\phi^\ell(x),$ solve for $\psi_n^{\ell+1}$
- 2. Compute $\phi^{\ell+1}(x) = \sum_{n=1}^{N} w_n \psi_n^{\ell+1}(x)$
- 3. Update scattering term with $\phi^{\ell+1}(x)$ and repeat until:

$$\frac{\|\phi^{\ell+1}(x)-\phi^{\ell}(x)\|}{\|\phi^{\ell+1}(x)\|}<\epsilon$$

6

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Slow to converge in optically thick systems with minimal losses to absorption and leakage

Radiation Hydrodynamics problems often contain highly diffusive regions

 S_N is too expensive in these regions

Need an acceleration scheme that rapidly increases the rate of convergence of source iteration

Eddington Acceleration

Take moments of Boltzmann equation until have enough equations for the number of unknowns

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Zeroth Moment: integrate over all angles

$$\int_{-1}^{1} \mu \frac{d\psi}{dx}(x,\mu) d\mu + \int_{-1}^{1} \Sigma_{t}(x)\psi(x,\mu) d\mu = \int_{-1}^{1} \frac{\Sigma_{s}(x)}{2} \phi(x) d\mu + \int_{-1}^{1} \frac{Q(x)}{2} d\mu$$

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Use
$$J(x) = \int_{-1}^{1} \mu \psi(x, \mu) \, d\mu$$
, $\phi(x) = \int_{-1}^{1} \psi(x, \mu) \, d\mu$

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1 equation, 2 unknowns

$$\int_{-1}^1 \mu^2 \frac{\mathrm{d} \psi}{\mathrm{d} x}(x,\mu) \, \mathrm{d} \mu + \int_{-1}^1 \mu \Sigma_t(x) \psi(x,\mu) \, \mathrm{d} \mu \ = \ \int_{-1}^1 \mu \frac{\Sigma_s(x)}{2} \phi(x) \, \mathrm{d} \mu + \int_{-1}^1 \mu \frac{Q(x)}{2} \, \mathrm{d} \mu$$

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Rearrange derivative

$$\frac{\mathrm{d}}{\mathrm{d}x} \int_{-1}^{1} \mu^2 \psi(x,\mu) \,\mathrm{d}\mu$$

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Multiply and divide by $\int_{-1}^{1} \psi(x,\mu) d\mu$

$$\frac{d}{dx} \int_{-1}^{1} \psi(x,\mu) d\mu \frac{\int_{-1}^{1} \mu^{2} \psi(x,\mu) d\mu}{\int_{-1}^{1} \psi(x,\mu) d\mu}$$

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Eddington Factor

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Angular flux weighted average of μ^2

Moment Equations

$$\frac{\mathrm{d}}{\mathrm{d}x}J(x) + \Sigma_a(x)\phi(x) = Q(x) \tag{Zeroth Moment}$$

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Numerically: use S_N to compute estimate of $\langle \mu^2 \rangle(x)$, Moment Equations to find $\phi(x)$

Eddington Acceleration

Eddington Acceleration

- 1. Given the previous estimate for the scalar flux, $\phi^\ell(x)$, solve for $\psi_n^{\ell+1/2}(x)$
- 2. Compute $\langle \mu^2 \rangle^{\ell+1/2}(x)$
- 3. Solve the Moment Equations for $\phi^{\ell+1}(x)$ using $\langle \mu^2 \rangle^{\ell+1/2}(x)$
- 4. Update the scalar flux estimate with $\phi^{\ell+1}(x)$ and repeat the iteration process until the scalar flux converges

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Acceleration occurs because

- 1. Angular shape of the angular flux converges quickly \Rightarrow Eddington factor quickly converges
- 2. Moment Equations model all scattering at once \Rightarrow dependence on source iterations to introduce scattering information is reduced

Produces 2 solutions (S_N and Moment)

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Downside: Which solution is correct?

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Relaxes consistent differencing requirements important in linear acceleration

Transport can be LDG and Moment can be MHFEM

Moment Equations are conservative and relatively inexpensive to solve

Downside: Which solution is correct?

Difference between S_N and Moment solutions can be used as a measure of mesh convergence

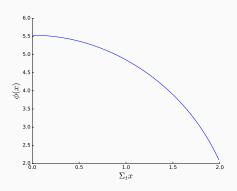
Results

Test Problem

 S_8 in 1D slab geometry

Lumped Linear Discontinuous Galerkin transport

Mixed Hybrid Finite Element Method Moment



Scale cross sections, source

$$\Sigma_t \to \Sigma_t/\epsilon$$

$$\Sigma_a \to \epsilon \Sigma_a$$

$$Q \to \epsilon Q$$

System becomes diffusive as $\epsilon \to 0$

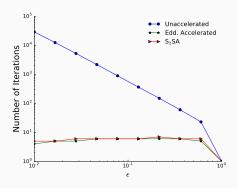
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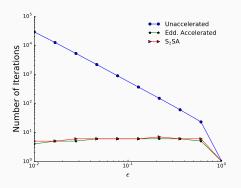
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Survives diffusion limit

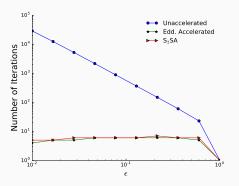
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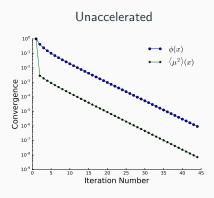
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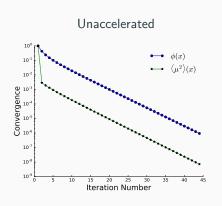
Survives diffusion limit

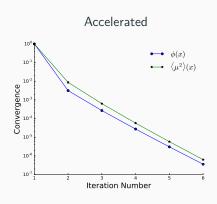
Performs similarly to consistently differenced, linear acceleration (S2SA)

Convergence Rate Comparison

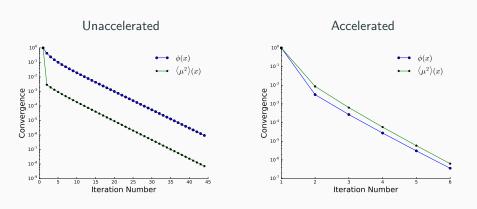


Convergence Rate Comparison





Convergence Rate Comparison



Fast rate of convergence of $\langle \mu^2 \rangle(x)$ is transfered to $\phi(x)$

Set Q(x) to force solution to

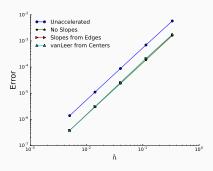
$$\phi(x) = \sin\left(\frac{\pi x}{x_b}\right)$$

Compare numerical results to MMS solution as cell width is decreased

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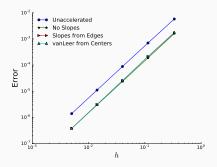
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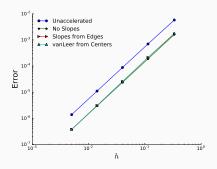


Data reconstruction: recover linear representation from MHFEM $\phi(x)$

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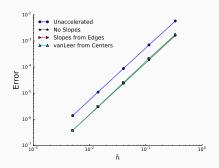
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All second order as expected

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Compare numerical results to MMS solution as cell width is decreased



Data reconstruction: recover linear representation from MHFEM $\phi(x)$

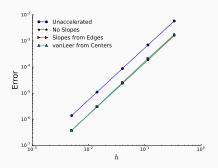
All second order as expected

Eddington Acceleration did not effect the order of accuracy of lumped LDG

Set Q(x) to force solution to

$$\phi(x) = \sin\left(\frac{\pi x}{x_b}\right)$$

Compare numerical results to MMS solution as cell width is decreased



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All slope recovery methods have similar accuracy

Compare

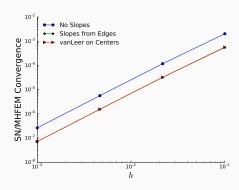
$$\frac{\|\phi_{\mathsf{S}_N}(x) - \phi_{\mathsf{Moment}}(x)\|}{\|\phi_{\mathsf{Moment}}(x)\|}$$

 $\text{as }h\to 0$

Compare

$$\frac{\|\phi_{\mathsf{S}_N}(x) - \phi_{\mathsf{Moment}}(x)\|}{\|\phi_{\mathsf{Moment}}(x)\|}$$

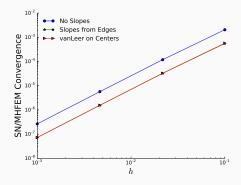
 $\text{as }h\to 0$



Compare

$$\frac{\|\phi_{\mathsf{S}_N}(x) - \phi_{\mathsf{Moment}}(x)\|}{\|\phi_{\mathsf{Moment}}(x)\|}$$

as $h \to 0$

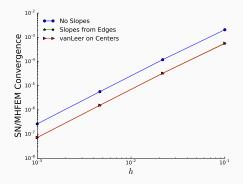


 S_{N} and Moment solutions converge as mesh is refined

Compare

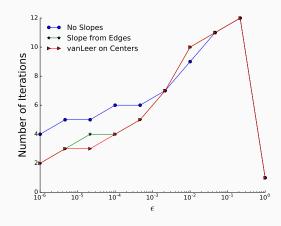
$$\frac{\|\phi_{\mathsf{S}_N}(x) - \phi_{\mathsf{Moment}}(x)\|}{\|\phi_{\mathsf{Moment}}(x)\|}$$

as $h \to 0$

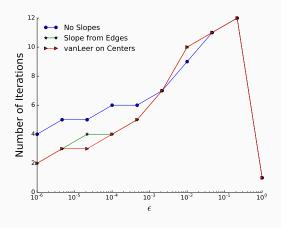


 S_N and Moment solutions converge as mesh is refined Slope recovery effects solution convergence but not accuracy

Data Reconstruction Diffusion Limit

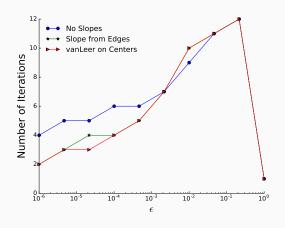


Data Reconstruction Diffusion Limit



All data reconstruction methods survived diffusion limit

Data Reconstruction Diffusion Limit



All data reconstruction methods survived diffusion limit

Eddington Acceleration is externely robust

Conclusions

Summary

Conclusions

- Scheme successfully accelerated source iteration in 1D slab geometry
- Eddington Acceleration is uniquely suited for radiation hydrodynamics
 - Transport and acceleration steps can be differenced with different methods
 - Reduces expense of source iteration
 - Provides inexpensive, conservative solution
- Showed MHFEM/LLDG pairing is robust

Summary

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- Scheme successfully accelerated source iteration in 1D slab geometry
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Future Work

- Add temperature for radiative transfer
- Higher dimensions
- Develop an efficient rad hydro algorithm that makes use of the inexpensive Moment solution in multiphysics iterations

References

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Data Reconstruction Methods

MHFEM $\phi(x)$ is piecewise constant with discontinuous cell edges $(\phi_{i-1/2},\,\phi_i,\,\phi_{i+1/2})$

LLDG is linear discontinuous $(\phi_{i,L}, \phi_{i,R})$

Need a way to recover slope information when S_N scattering term is updated with MHFEM $\phi(x)$

No Slopes:

$$\phi_{i,L/R} = \phi_{i\mp 1/2}^*$$

Slopes from Edges:

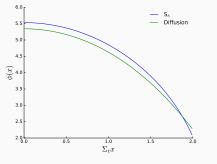
$$\phi_{i,L/R} = \phi_i^* \mp \frac{1}{2} \left(\phi_{i+1/2}^* - \phi_{i-1/2}^* \right)$$

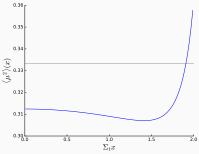
vanLeer on Centers:

$$\phi_{i,L/R} = \phi_i^* \mp \frac{1}{4} \xi_{\text{vanLeer}} \left[\left(\phi_{i+1}^* - \phi_i^* \right) + \left(\phi_i^* - \phi_{i-1}^* \right) \right]$$

S₈ v. Diffusion

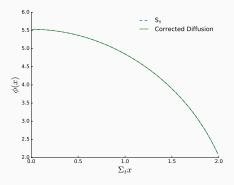
Small system \Rightarrow diffusion not expected to be accurate





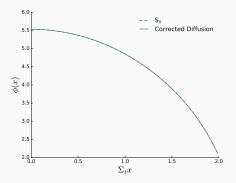
S₈ v. Drift Diffusion

Use $\langle \mu^2 \rangle(x)$ from S₈ in Moment Equations



S₈ v. Drift Diffusion

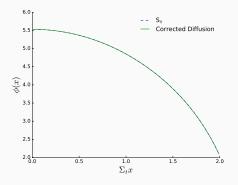
Use $\langle \mu^2 \rangle(x)$ from S₈ in Moment Equations



Moment Equations and S_N match!

S₈ v. Drift Diffusion

Use $\langle \mu^2 \rangle(x)$ from S₈ in Moment Equations



Moment Equations and S_N match!

Requires knowledge of angular flux