

```
then SAVE Click
                                                                                   en Servo_04 PositionChanged
                                                                                                                                                call BluetoothGlient1 - .SendText
                                                                                  thumbPosition
                                                                                                                                                                        text SAVE . Text .
                                                                                    call Bluetooth@lient1 . SendText
                                                                                                                                                 set Positions . Text . to Positions . Text . + 1
when BluetoothList AfterPicking
                                                                                                           text i join 54
 call BluetoothClient1 - .Connect
                                                                                                                       get thumbPosition
                              address BluetoothList - Selection -
                                                                                                                                                hen RUN Click
      set BluetoothList . Elements . to BluetoothClient1 . AddressesAndNames .
                                                                                                                                                set RUN . BackgroundColor to
                                                                                                                                                 O I RUN Text - FAUSE
hen Clock1 Timer
                                                                                                                                                  then call BluetoothClient1 .. SendText
  BluetoothClient1 | IsConnected
                                                                                                                                                                             text ( RUN ... Text ...
  then set Connected . Text to Connected when BluetoothList . Before Picking
                                                                                                                                                      set (RUN ... Text ... to RUN ...
       set Connected . TextColor to
                                               set BluetoothList . Elements to BluetoothClient1 . AddressesAndNames .
                                                                                                                                                  else if RUN . Text . F. RUN .
  BluetoothClient1 - IsConnected -
                                                                                                                                                  then call BluetoothClient1 - SendText
  then set Connected . Text to Disconnected
                                                                                                                                                                             text RUN - Text -
      set Connected . TextColor to
                                                                                                                                                      set RUN . Text . to PAUSE
                                                                                  hen Servo_03 . PositionChanged
en Disconnect - Click
                                                                                                                                                  RESET - .Click
                                                                                 thumbPosition
  call BluetoothClient1 .Disconnect
                                                                                                                                                 call BluetoothClient1 - SendText
                                                                                   call BluetoothClient1 ... SendText
                                                                                                                                                                        text RESET Text
                                                                                                          text i join s3
                                                                                                                                                 set (RUN ... Text ... to RUN)
                                                                                                                       get thumbPosition +
hen BluetoothClient1 BluetoothErro
                                                                                                                                                 set Positions . Text + to 0
functionName message
                                                                                 then Servo_02 .PositionChange
                                                                                                                                                 set RUN . BackgroundColor to I
call Bluetooth Client1 Disconnect
                                                                                 thumbPosition
   if not BluetoothClient1 - . IsConnected -
                                                                                   call BluetoothC entil ... SendText
  then set Connected . Text . to Disconnected
                                                                                                          text join 52
       set Connected . TextColor to
                                                                                                                       get thumbPosition -
                                                                                                                                               when Speed PositionChange
                                                                                                                                                thumbPosition
                                                                                 when Servo_01 PositionChanged
                                                                                                                                               call BluetoothClient1 ... SendText
                                                                                 thumbPosition
                                                                                                                                                                         text i join ss .
                                                                                   call BluetoothGlient1: SendText
                                                                                                                                                                                    get thumbPosition •
                                                                                                          text 🔯 join 🔭 🚮 🔭
                                                                                                                       get thumbPosition -
```

Show Warnings







