# Bi-Weekly Update

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### 1 Introduction

This is a section which outlines the fundamental formulas behind the "Delay Sum" (DAS) and "Pressure Matching" (PM) methods for sound localization.

#### 1.1 Math Fundamentals

The relationship between L sources and M control points is

$$\mathbf{p}(\omega) = \mathbf{Z}(\omega)\mathbf{q}(\omega)s(\omega) \tag{1}$$

where  $\mathbf{p}(\omega)$  are the sound pressure at the M control points,  $\mathbf{q}(\omega)$  is the vector of weights for the L sources,  $\mathbf{Z}(\omega)$  is the transfer matrix, and  $s(\omega)$  is set to 1 at each angular velocity  $\omega$ .

The transfer matrix  $\mathbf{Z}$  is

$$\mathbf{Z}_{M \times L}(\omega) = \begin{bmatrix} Z(\mathbf{x}_1, \mathbf{y}_1, \omega) & \dots & Z(\mathbf{x}_1, \mathbf{y}_L, \omega) \\ \vdots & \ddots & \vdots \\ Z(\mathbf{x}_M, \mathbf{y}_1, \omega) & \dots & Z(\mathbf{x}_M, \mathbf{y}_L, \omega) \end{bmatrix}$$
(2)

Where the transfer function is defined as

$$Z(\mathbf{x}_m, \mathbf{y}_{\ell}, \omega) = \frac{e^{-j\frac{\omega}{c}||\mathbf{x}_m - \mathbf{y}_{\ell}||}}{4\pi ||\mathbf{x}_m - \mathbf{y}_{\ell}||}$$
(3)

For simplicity's sake,  $\omega$  will be omitted in all further equations.

### 1.2 DAS

The equation that gives us the  $\mathbf{q}$  using the DAS method is

$$\mathbf{q}_{DAS} = \mathbf{\Gamma} \mathbf{z}_B^* \tag{4}$$

Where  $[\,\cdot\,]^*$  is the operation of complex conjugate. The vector  $\mathbf{z}_B$  is the transfer vector for the singular bright point and the matrix  $\Gamma$  is defined as

$$\mathbf{\Gamma} = \begin{bmatrix} \gamma_1 & 0 & \dots & 0 \\ 0 & \gamma_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \gamma_L \end{bmatrix}$$
 (5)

Where  $\gamma_{\ell} = \frac{16\pi^2 ||\mathbf{x}_B - \mathbf{y}_{\ell}||^2}{L}$ .

### 1.3 PM

The equation that allows us to derive  $\mathbf{q}$  using the PM method is

$$\min_{\mathbf{q}} J_{PM} = \min_{\mathbf{q}} (\mathbf{e}_{PM}^{H} \mathbf{e}_{PM} + \beta_{PM} E_{q})$$
 (6)

Where  $\mathbf{e}_{PM} = \hat{\mathbf{p}} - \mathbf{Z}\mathbf{q}$ . The Tikhonov regularization parameter  $\beta_{PM}$  is given by gradually increasing  $\beta_{PM}$  until this inequality is satisfied

$$E_{\mathbf{q}} = \mathbf{q}^H \mathbf{q} \le E_{max} \tag{7}$$

The final relationship used to calculate the vector  $\mathbf{q}_{PM}$  is

$$\mathbf{q}_{PM} = (\mathbf{Z}^H \mathbf{Z} + \beta_{PM} \mathbf{I})^{-1} \mathbf{Z}^H \hat{\mathbf{p}}$$
 (8)

## 2 Conclusion

From tinkering with the algorithms in a Jupyter notebook, I've elucidated some of the intricacies of the two algorithms. Notably:

- 1.  $\mathbf{q}_{DAS}$  is much, much faster to compute than  $\mathbf{q}_{PM}$
- 2. PM has much better directive performance than DAS

3. both algorithms perform better at higher frequencies and worse at lower frequencies  $\alpha$ 

The following images highlight points 2 and 3:



