

Graph Positional Autoencoders as Self-supervised Learners

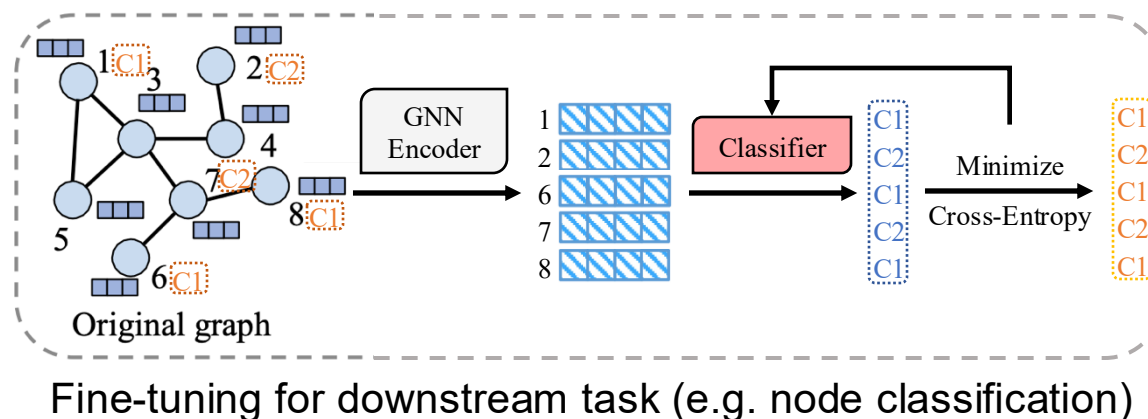
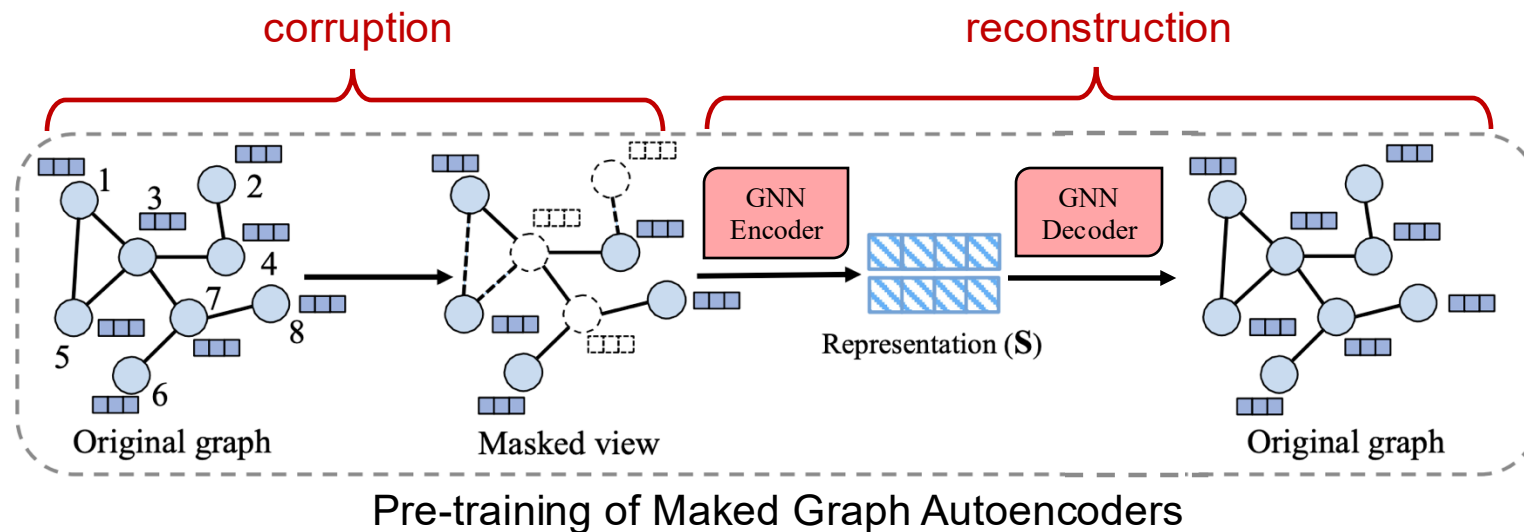
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1 Background Masked Graph Autoencoders

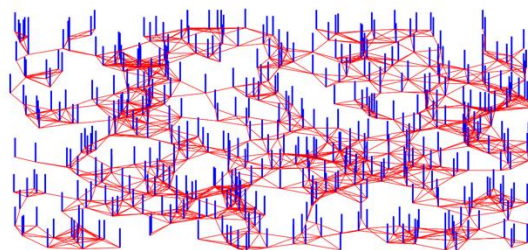
Maked Graph Autoencoders (Masked GAEs) follow a corruption-reconstruction framework, which learns graph representations by recovering the missing information of the incomplete input graphs.



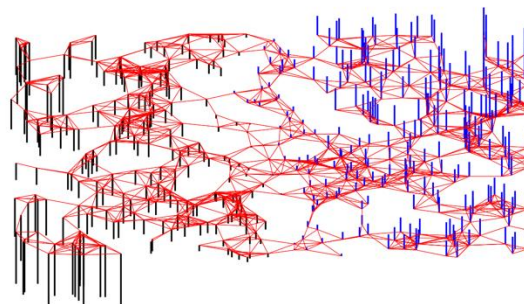
1 Background Frequency Bases in Graphs

- Eigenvectors of the graph Laplacian represent different frequencies, acting as frequency bases in the spectral domain.

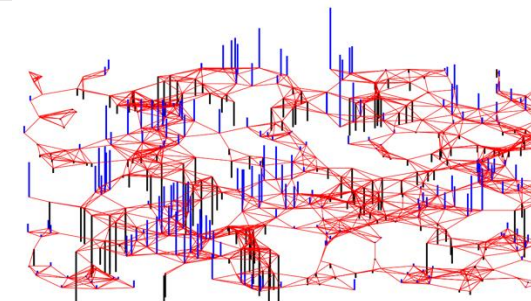
Given eigen-decomposition $Lu_k = \lambda_k u_k$ with $u_k^\top u_k = 1$, we have $u_k^\top Lu_k = u_k^\top \lambda_k u_k = \lambda_k$. Since $u_k^\top Lu_k = \sum_{(i,j) \in \mathcal{E}} (u_{i,k} - u_{j,k})^2$, we obtain $\sum_{(i,j) \in \mathcal{E}} (u_{i,k} - u_{j,k})^2 = \lambda_k$. Therefore, λ_k reflects the frequency magnitude of u_k over the graph.



u_0



u_1

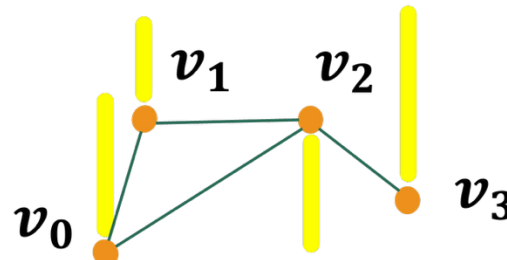


u_{50}

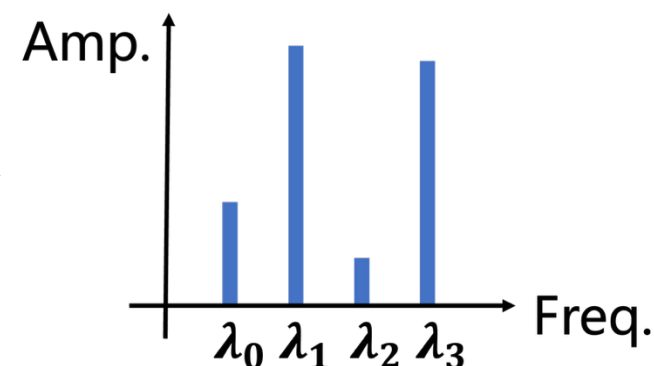
frequency bases

u_0
u_1
u_2
u_3

\mathbf{X}



$\mathbf{U}^\top \mathbf{X}$

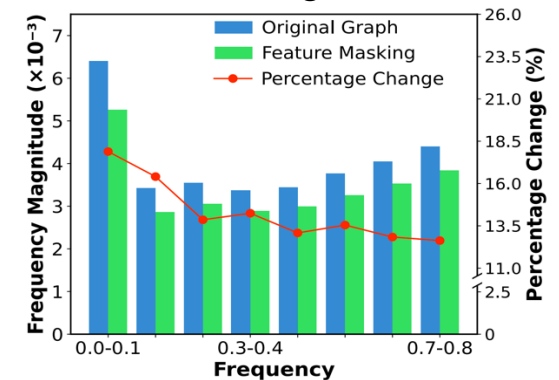


- Limitations of existing methods:

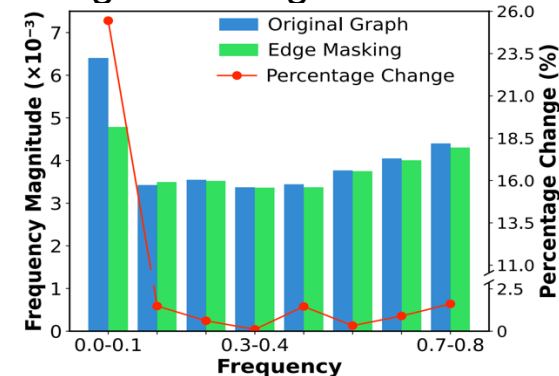
Existing masked GAEs tend to focus on reconstructing low-frequency information of graphs while overlooking high-frequency information.

Model	Corruption			Reconstruction		
	Feature	Edge	Position	Feature	Edge	Other
GraphMAE [18]	✓	-	-	✓	-	-
StructMAE [32]	✓	-	-	✓	-	-
AUG-MAE [59]	✓	-	-	✓	-	-
S2GAE [50]	-	✓	-	-	✓	-
SeeGera [30]	✓	✓	-	✓	✓	-
Bandana [77]	-	✓	-	-	✓	-
MaskGAE [28]	-	✓	-	✓	-	Degree
GiGaMAE [45]	✓	✓	-	-	-	Latent
GraphPAE	✓	-	✓	✓	-	Position

Node Masking: $U^T X$ vs $U^T X'$



Edge Masking: $U^T X$ vs $U'^T X$

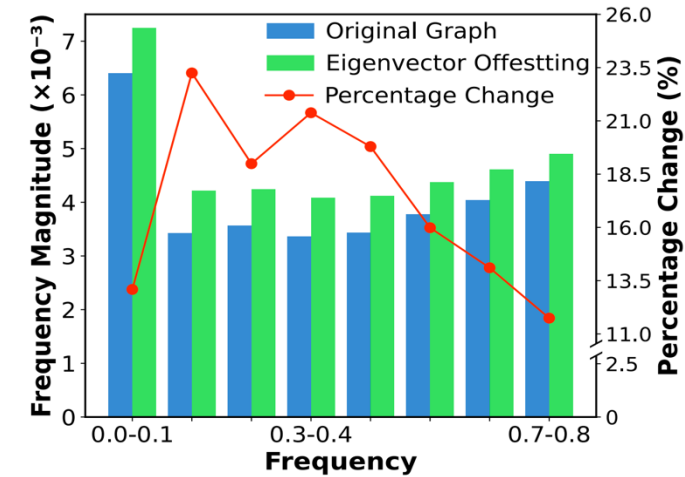


- How can we design the corruption and reconstruction objectives to exploit the diverse frequency information?

3 Inspired by Spectral Theory

- The eigenvectors of graph Laplacian correspond to different frequencies in the graph signal processing.
- Directly perturbing eigenvectors can explicitly corrupt corresponding frequency information in the graph.

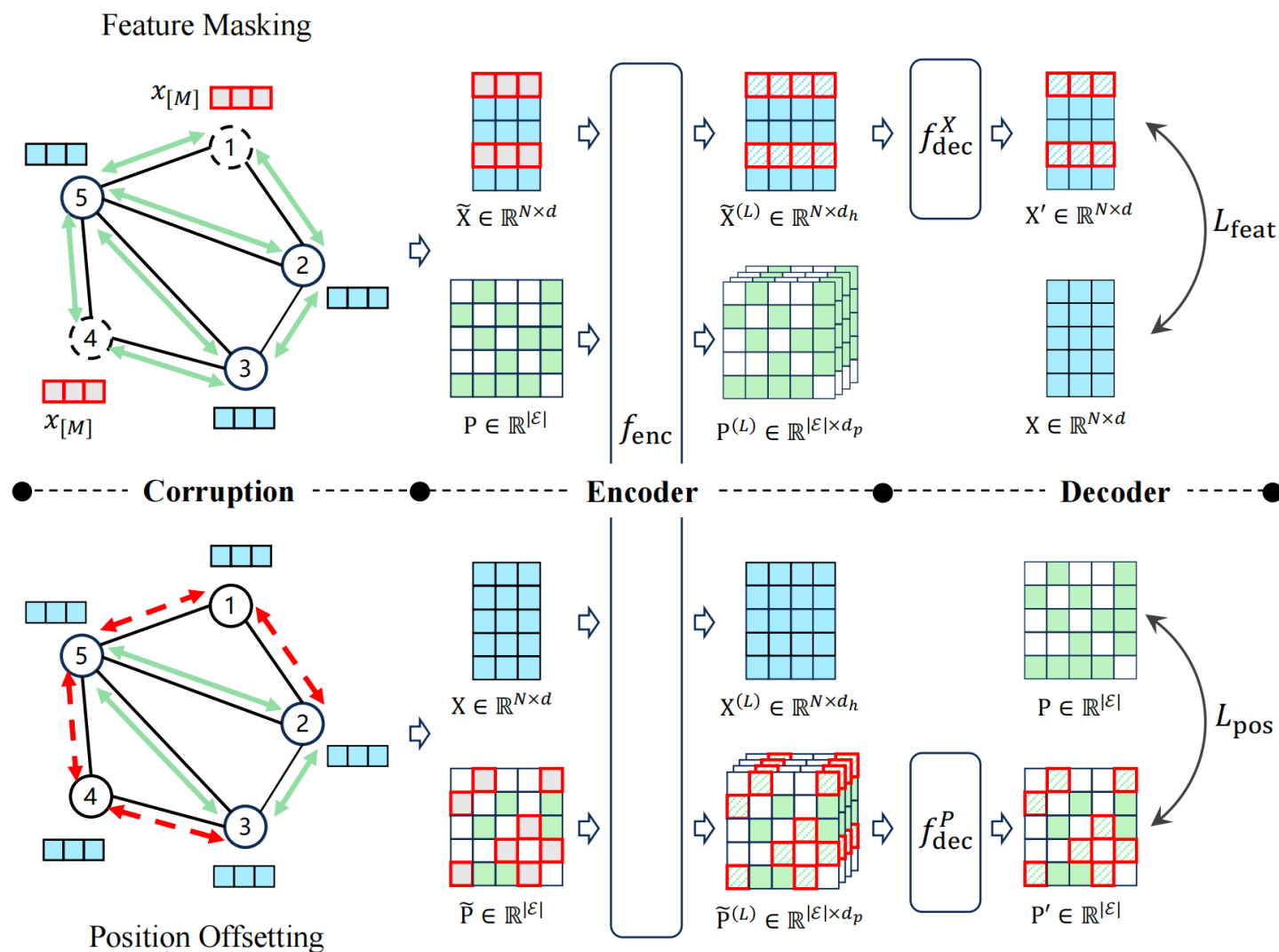
Eigenvector offsetting: $U^T X$ vs $U'^T X$



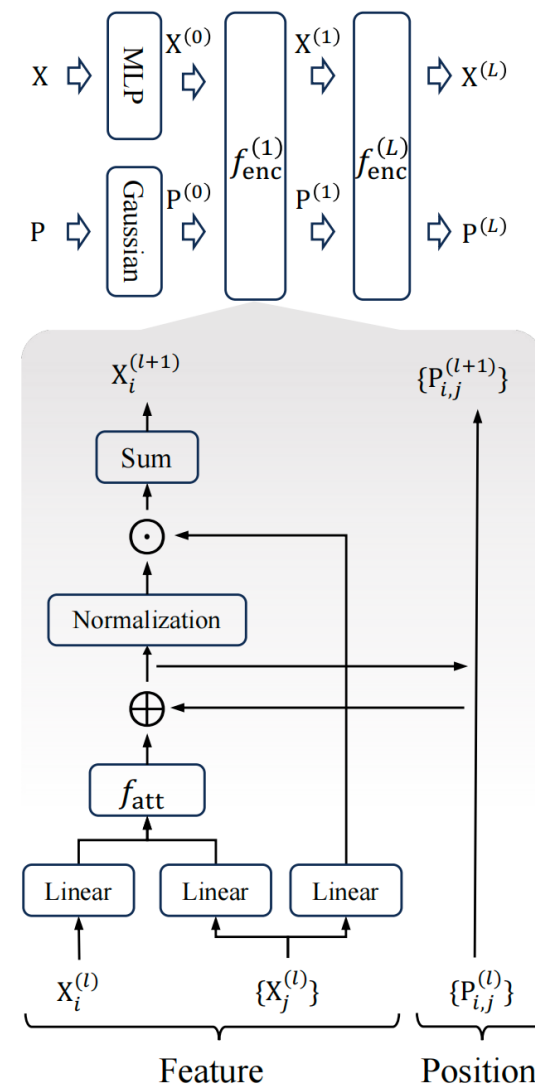
Incorporating eigenvector corruption-reconstruction into masked GAEs.

- Two main challenge of reconstructing the eigenvectors:
 - ✓ GNN Expressivity: Eigenvectors represent global structural patterns, which cannot be easily approximated by GNNs, whose expressiveness is bounded by the 1-WL test.
 - ✓ Eigenvector Ambiguity: Eigenvectors suffer from sign- and basis- ambiguity issues. Directly reconstructing eigenvectors leads to non-unique solutions, thereby affecting the robustness of GAEs.

4 GraphPAE Overall Framework



(a) Overall pipeline of GraphPAE.



(b) Encoder of GraphPAE

- Feature Masking.

Randomly sampling a subset of nodes $\tilde{\mathcal{V}} \subset \mathcal{V}$ and reset their features. The corrupted feature matrix $\tilde{\mathbf{X}}$ is defined as:

$$\tilde{\mathbf{X}}_i = \begin{cases} \mathbf{x}_{[M]}, & \text{if } v_i \in \tilde{\mathcal{V}} \\ \mathbf{X}_i, & \text{if } v_i \notin \tilde{\mathcal{V}} \end{cases}$$

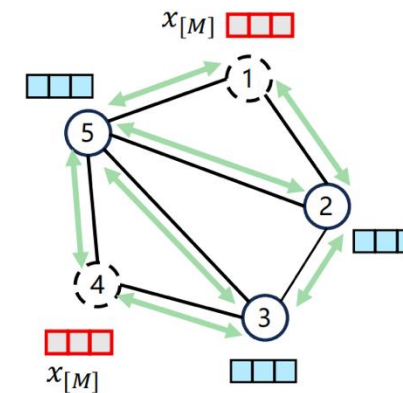
- Position Offsetting.

Adding random offsets to node position:

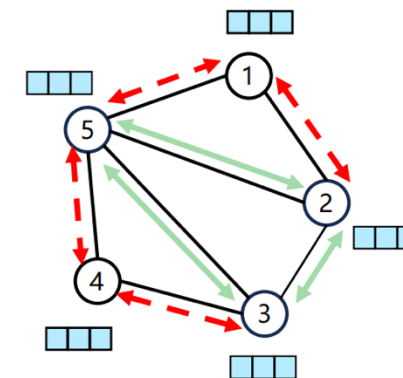
$$\tilde{\mathbf{U}}_i = \begin{cases} \mathbf{U}_i + \delta, & \text{if } v_i \in \tilde{\mathcal{V}} \\ \mathbf{U}_i, & \text{if } v_i \notin \tilde{\mathcal{V}} \end{cases} \quad \delta \in \mathbb{R}^K \text{ is sampled from } \mathcal{U}(-\mu_p, \mu_p)$$

- Relative Positional Encoding.

$$\mathbf{P}_{i,j} = \begin{cases} \|\mathbf{U}_i - \mathbf{U}_j\|_2, & \text{if } \mathbf{A}_{i,j} = 1 \\ 0, & \text{otherwise} \end{cases}$$



Feature Masking



Position Offsetting

- Overall formulation.

$$\mathbf{X}_i^{(l+1)}, \mathbf{P}_i^{(l+1)} = f_{\text{enc}}^{(l+1)} \left(\mathbf{X}_i^{(l)}, \{\mathbf{X}_j^{(l)}\}_{j \in \mathcal{N}_i}, \mathbf{P}_i^{(l)} \right)$$

$$\mathbf{P}_{i,j}^{(0)} = \text{MLP} \left([G(\mathbf{P}_{i,j}; \mu_1, \sigma), \dots, G(\mathbf{P}_{i,j}; \mu_d, \sigma)] \right) \quad \mathbf{X}_i^{(0)} = \text{MLP}(\mathbf{X}_i).$$

$$G(\mathbf{P}_{i,j}; \mu_k, \sigma) = \exp \left(-(\mathbf{P}_{i,j} - \mu_k)^2 / 2\sigma^2 \right)$$

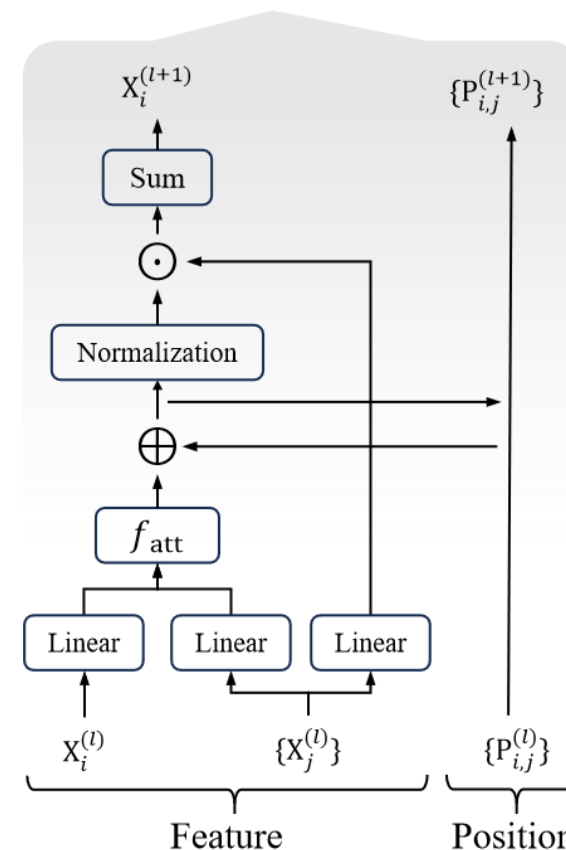
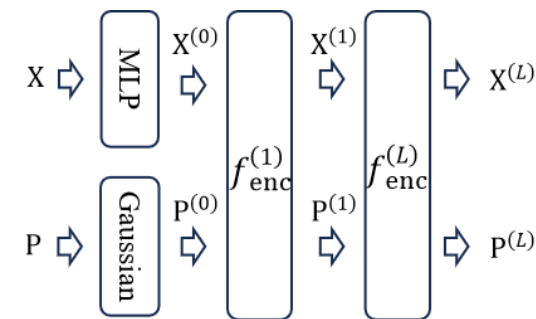
- Feature Path: PE-enhanced MPNNs.

$$\alpha_{i,j}^{(l)} = f_{\text{att}}(\mathbf{X}_i^{(l)}, \mathbf{X}_j^{(l)}), \quad \alpha_{i,j}^{(l)} \in \mathbb{R}^d,$$

$$\mathbf{X}_i^{(l+1)} = \sum_{j \in \mathcal{N}_i} \left(\alpha_{i,j}^{(l)} + \mathbf{P}_{i,j}^{(l)} \right) \odot \text{MLP}(\mathbf{X}_j^{(l)}),$$

- Position Path: Refine Node Positions.

$$\mathbf{P}_{i,j}^{(l+1)} = \alpha_{i,j}^{(l)} + \mathbf{P}_{i,j}^{(l)}.$$



- Feature Reconstruction.

$$\mathbf{X}'_i = f_{\text{dec}}^X \left(\tilde{\mathbf{X}}_i^{(L)} \right),$$

$$\mathcal{L}_{\text{feat}} = \frac{1}{|\tilde{\mathcal{V}}|} \sum_{v_i \in \tilde{\mathcal{V}}} \left(1 - \frac{\mathbf{X}_i^T \mathbf{X}'_i}{\|\mathbf{X}_i\| \cdot \|\mathbf{X}'_i\|} \right)^\gamma,$$

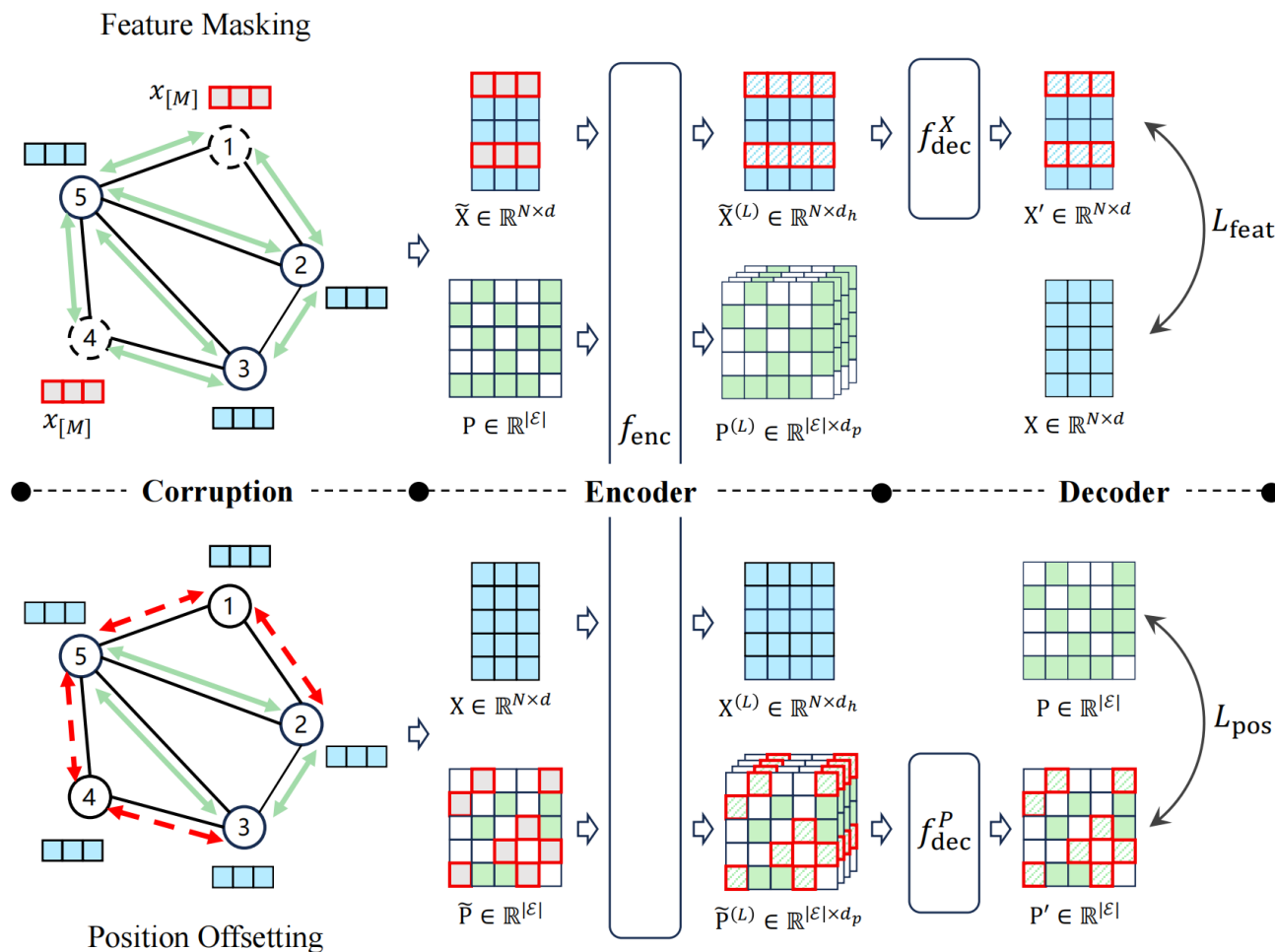
- Position Reconstruction.

$$\mathbf{P}'_{i,j} = f_{\text{dec}}^P \left(\tilde{\mathbf{P}}_{i,j}^{(L)} \right)$$

$$\mathcal{L}_{\text{pos}}^{i,j} = \begin{cases} \frac{(\mathbf{P}'_{i,j} - \mathbf{P}_{i,j})^2}{2}, & \text{if } |\mathbf{P}'_{i,j} - \mathbf{P}_{i,j}| < 1 \\ |\mathbf{P}'_{i,j} - \mathbf{P}_{i,j}| - \frac{1}{2}, & \text{otherwise} \end{cases}$$

$$\mathcal{L}_{\text{pos}} = \frac{1}{\sum_{v_i \in \tilde{\mathcal{V}}} |\mathcal{N}_i|} \sum_{v_i \in \tilde{\mathcal{V}}, j \in \mathcal{N}_i} \mathcal{L}_{\text{pos}}^{i,j}$$

- Overall Loss Function. $\mathcal{L} = \mathcal{L}_{\text{feat}} + \alpha \mathcal{L}_{\text{pos}}$



5 Experiments Performance of Node Classification



Dataset	Small Graphs				Large Graphs	
	BlogCatalog	Chameleon	Squirrel	Actor	arXiv-year	Penn94
Supervised	80.52±2.10	80.02±0.87	71.91±1.03	33.93±2.47	46.02±0.26	81.53±0.55
DGI	72.07±0.16	43.83±0.14	34.56±0.10	27.98±0.09	-	-
BGRL	79.74±0.46	61.24±1.07	43.24±0.52	26.61±0.57	<u>41.43±0.04</u>	63.31±0.49
MVGRL	63.24±0.94	73.19±0.42	60.09±0.44	34.64±0.20	-	-
CCA-SSG	74.00±0.28	75.00±0.75	61.58±1.98	27.79±0.58	40.78±0.01	62.63±0.20
Sp ² GCL	72.73±0.46	78.88±1.04	62.61±0.87	<u>34.70±0.92</u>	39.09±0.02	68.80±0.45
VGAE	60.47±1.84	62.32±1.90	42.50±1.35	31.57±0.75	36.39±0.21	55.31±0.28
GraphMAE	79.90±1.13	<u>79.50±0.57</u>	61.13±0.60	32.15±1.33	40.30±0.04	67.97±0.21
GraphMAE2	77.34±0.12	<u>79.13±0.19</u>	<u>70.27±0.88</u>	34.48±0.26	38.97±0.03	67.86±0.42
MaskGAE	73.10±0.08	74.50±0.87	68.53±0.44	33.44±0.34	40.59±0.04	63.84±0.03
S2GAE	75.76±0.43	60.24±0.37	68.60±0.56	26.17±0.38	40.32±0.12	<u>70.24±0.09</u>
AUG-MAE	<u>82.03±0.69</u>	70.10±1.88	62.57±0.67	33.42±0.38	37.10±0.13	69.90±0.43
GraphPAE	85.76±1.22	80.51±1.25	72.05±1.40	38.55±1.35	41.85±0.04	71.79±0.37

Table 1. Node classification results of different graph self-supervised learning.

5 Experiments Performance of Graph Prediction



Task	Regression (Metric: RMSE ↓)			Classification (Metric: ROC-AUC% ↑)			
Dataset	molesol	molipo	molreesolv	molbase	molbbbp	molclintox	moltoxc21
Supervised	1.173±0.057	0.757±0.018	2.755±0.349	80.42±0.96	68.17±1.48	88.14±2.51	74.91±0.51
InfoGraph	1.344±0.178	1.005±0.023	10.005±8.147	73.64±3.64	66.33±2.79	64.50±5.32	69.74±0.57
GraphCL	1.272±0.089	0.910±0.016	7.679±2.748	73.32±2.70	68.22±2.19	74.92±4.42	72.40±1.07
MVGRL	1.433±0.145	0.962±0.036	9.024±1.982	74.88±1.43	67.24±3.19	73.84±2.75	70.48±0.83
JOAO	1.285±0.121	0.865±0.032	5.131±0.782	74.43±1.94	67.62±1.29	71.28±4.12	71.38±0.92
Sp ² GCL	1.235±0.119	<u>0.835±0.026</u>	4.144±0.573	78.76±1.43	68.72±1.53	80.88±3.86	73.06±0.75
GraphMAE	<u>1.050±0.034</u>	0.850±0.022	2.740±0.233	79.14±1.31	66.55±1.78	80.56±5.55	73.84±0.58
GraphMAE2	1.225±0.081	0.885±0.019	2.913±0.293	<u>80.74±1.53</u>	67.67±1.44	75.75±3.65	72.93±0.69
StructMAE	1.499±0.043	1.089±0.002	2.568±0.262	77.75±0.42	65.66±1.16	79.42±4.56	71.13±0.61
AUG-MAE	1.248±0.026	0.917±0.013	<u>2.395±0.158</u>	78.54±2.49	67.05±0.63	<u>82.66±1.98</u>	<u>74.33±0.07</u>
GraphPAE	1.015±0.045	0.810±0.018	2.058±0.188	81.11±1.24	<u>68.56±0.71</u>	82.69±3.39	74.46±0.54

Table 2. Graph regression and classification results of different graph self-supervised learning on OGB datasets.

Exp No.	Corrupt Info.		Recon Info.		Dual-Path	Node-level		Graph-level		
	Feature	Position	Feature	Position		Blog (\uparrow)	Squirrel (\uparrow)	Bace (\uparrow)	Bbbp (\uparrow)	Freesolv (\downarrow)
a	✓	✓	✓			82.8 \pm 1.7	66.4 \pm 1.6	78.4 \pm 1.2	66.4 \pm 1.7	2.79 \pm 0.40
b	✓	✓	✓	✓		83.5 \pm 1.0	68.5 \pm 0.9	78.9 \pm 2.1	66.8 \pm 0.6	2.44 \pm 0.36
c	✓		✓		✓	84.6 \pm 1.6	71.3 \pm 0.9	79.4 \pm 3.4	67.7 \pm 0.9	2.20 \pm 0.14
d	✓	✓	✓	✓	✓	85.8\pm1.2	72.1\pm1.4	81.1\pm1.2	68.6\pm0.7	2.06\pm0.19

Table 3. Ablation studies of position reconstruction and framework design.

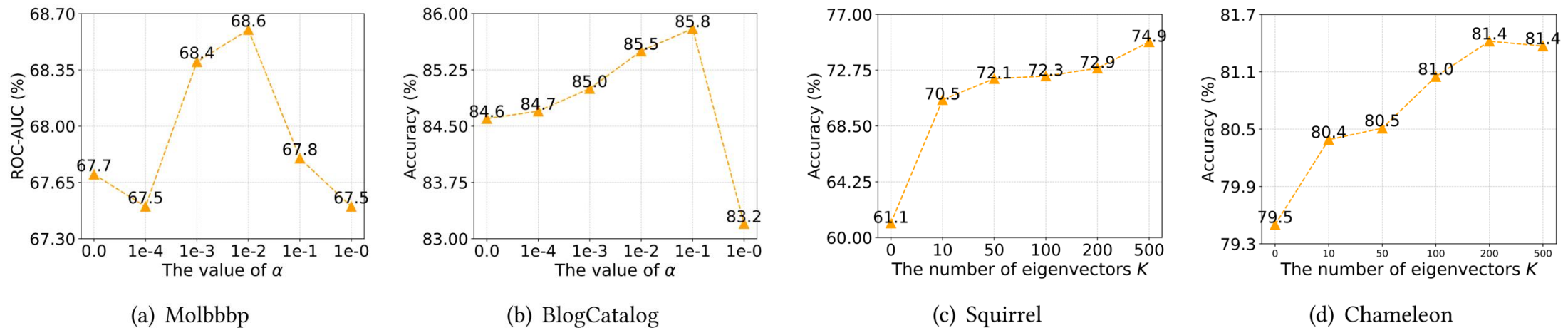


Figure 1: Influence of loss weight \mathcal{L}_{pos} and the number of eigenvectors K .



Paper



Code

Thanks

Q&A



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