



GraphPrompt: Unifying Pre-Training and Downstream Tasks for Graph Neural Networks

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Outline

- 1 .Motivation
- 2 .Challenges
- 3 .Proposed Model: GraphPrompt
- 4 .Experiment
- 5 .Conclusions

Motivation

Problem 1:

- task-specific labeled data is often difficult or costly to obtain

Problem 2:

- pre-training step aims to preserve various intrinsic graph properties
- fine-tuning step aims to reduce the downstream task loss

**GNNs' performance
heavily depends on labeled
data [1,2]**

Scarce of labeled data

**Pre-Training+Finetuning
[3,4]**

**Gap between pre-train
and downstream tasks[5]**

Pre-Training+Prompt

[1] Will Hamilton et.al. 2017. Inductive representation learning on large graphs. NIPS.

[2] Thomas N Kipf and Max Welling. 2017. Semi-supervised classification with graph convolutional networks. ICLR.

[3] Weihua Hu et.al. 2020. Strategies for Pre-training Graph Neural Networks. ICLR.

[4] Ziniu Hu et.al. 2020. GPT-GNN: Generative pre-training of graph neural networks. KDD.

[5] Pengfei Liu et.al. 2021. Pre-train, prompt, and predict: A systematic survey of prompting methods in natural language processing. ACM Computing Survey.

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Challenges

Challenges

- Different downstream tasks often have different objectives[6]
- Distinction between various downstream tasks

C1: How to unify pre-training with various downstream tasks on graph?

C2: How to design prompts on graphs?[7]

[6] Tom Brown, Benjamin Mann, Nick Ryder, Melanie Subbiah, Jared D Kaplan, Prafulla Dhariwal, Arvind Neelakantan, Pranav Shyam, Girish Sastry, Amanda Askell, et al. 2020. Language models are few-shot learners. NeurIPS.

[7] Mingchen Sun, Kaixiong Zhou, Xin He, Ying Wang, and Xin Wang. 2022. GPPT: Graph Pre-training and Prompt Tuning to Generalize Graph Neural Networks. SIGKDD

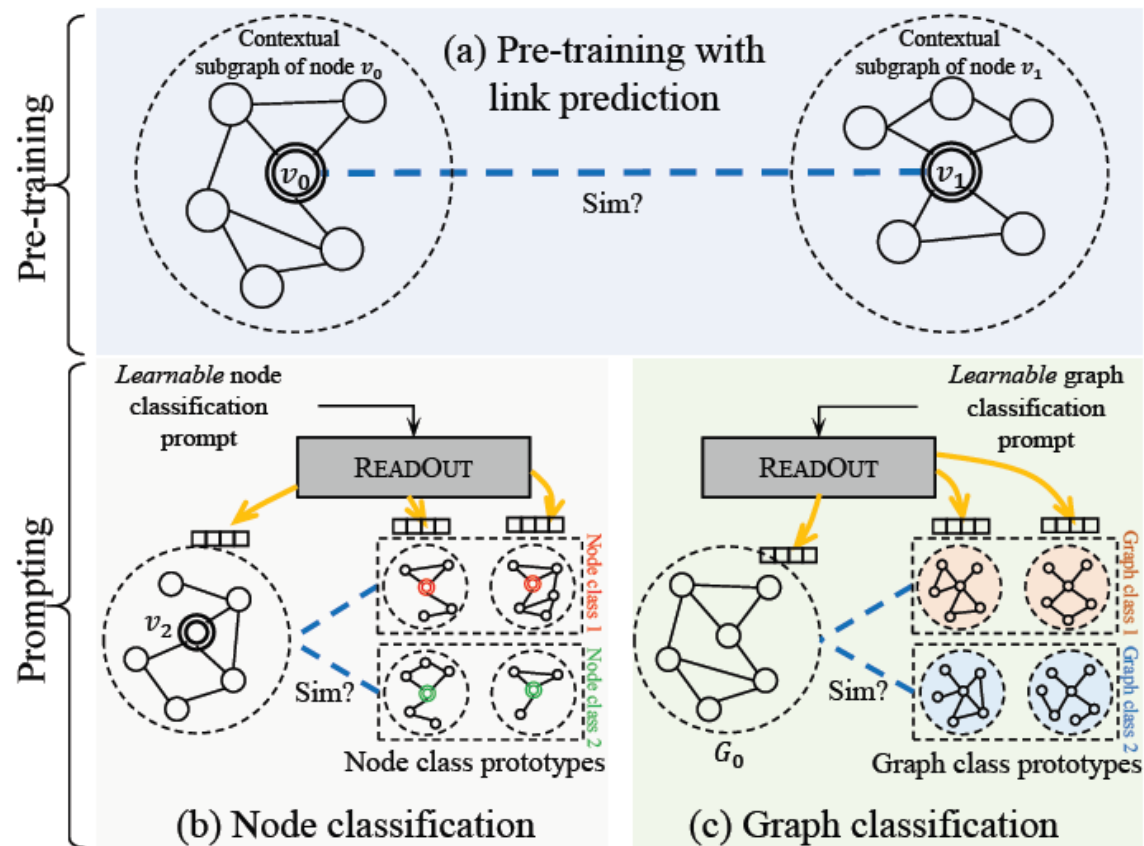


Figure 1: Illustration of the motivation. (a) Pre-training on graphs. (b/c) Downstream node/graph classification.

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Proposed Method: GraphPrompt

Unified task template

Link Prediction

$$\text{sim}(\mathbf{s}_v, \mathbf{s}_a) > \text{sim}(\mathbf{s}_v, \mathbf{s}_b)$$

Node Classification(NC)

$$\tilde{\mathbf{s}}_c = \frac{1}{k} \sum_{(v_i, l_i) \in D, l_i=c} \mathbf{s}_{v_i}$$

$$\ell_j = \arg \max_{c \in C} \text{sim}(\mathbf{s}_{v_j}, \tilde{\mathbf{s}}_c)$$

Graph Classification(GC)

$$\tilde{\mathbf{s}}_c = \frac{1}{k} \sum_{(G_i, L_i) \in \mathcal{D}, L_i=c} \mathbf{s}_{G_i}$$

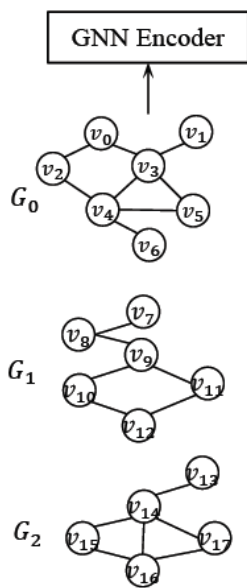
$$L_j = \arg \max_{c \in C} \text{sim}(\mathbf{s}_{G_j}, \tilde{\mathbf{s}}_c)$$

mean embedding of (sub)graphs
class label

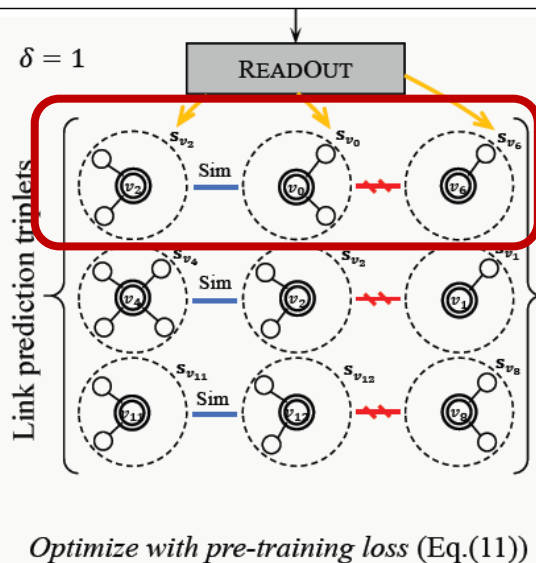
A Notation for NC and GC

$$y = \arg \max_{c \in Y} \text{sim}(\mathbf{s}_x, \tilde{\mathbf{s}}_c)$$

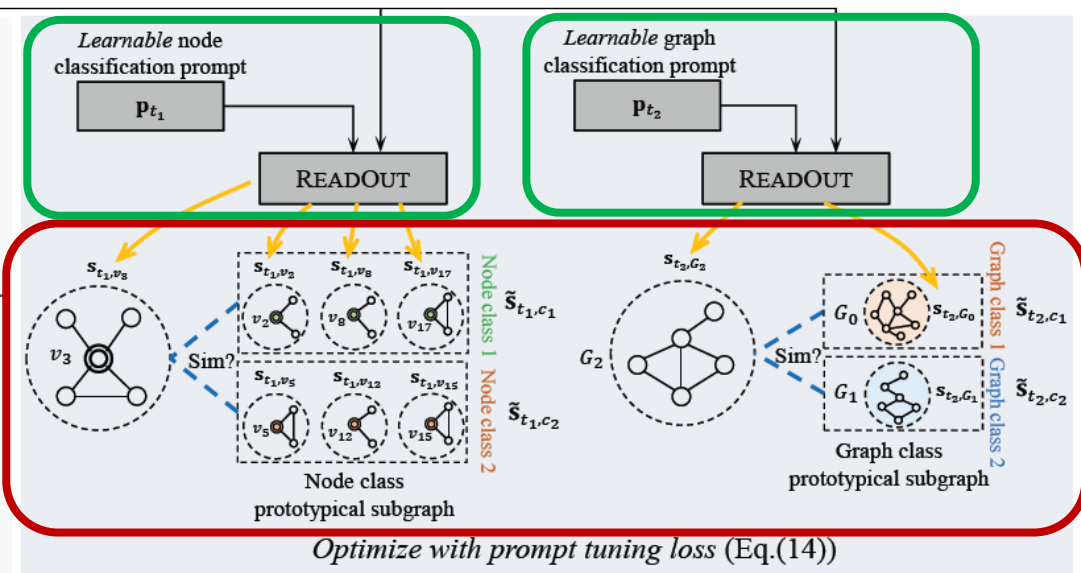
$$\mathbf{s}_x = \text{READOUT}(\{\mathbf{h}_v : v \in V(S_x)\})$$



(a) Toy graphs



(b) Pre-training



(c) Prompting for node classification (left) or graph classification (right)

Figure 2: Overall framework of GRAPH PROMPT.

Pre-Training Objective

$$\mathcal{L}_{\text{pre}}(\Theta) = - \sum_{(v,a,b) \in \mathcal{T}_{\text{pre}}} \ln \frac{\exp(\text{sim}(\mathbf{s}_v, \mathbf{s}_a)/\tau)}{\sum_{u \in \{a,b\}} \exp(\text{sim}(\mathbf{s}_v, \mathbf{s}_u)/\tau)}$$

Prompt Design

$$\mathbf{s}_{t,x} = \text{READOUT}(\{\mathbf{p}_t \odot \mathbf{h}_v : v \in V(S_x)\})$$

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Experiment

Node Classification and Graph Classification

Table 2: Accuracy evaluation on node classification.

All tabular results are in percent, with best **bolded** and runner-up underlined.

Methods	Flickr 50-shot	PROTEINS 1-shot	ENZYMES 1-shot
GCN	9.22 ± 9.49	59.60 ± 12.44	61.49 ± 12.87
GRAPHSAGE	13.52 ± 11.28	59.12 ± 12.14	61.81 ± 13.19
GAT	16.02 ± 12.72	58.14 ± 12.05	60.77 ± 13.21
GIN	10.18 ± 5.41	<u>60.53</u> ± 12.19	<u>63.81</u> ± 11.28
DGI	17.71 ± 1.09	54.92 ± 18.46	63.33 ± 18.13
GRAPHCL	18.37 ± 1.72	52.00 ± 15.83	58.73 ± 16.47
GPPT	<u>18.95</u> ± 1.92	50.83 ± 16.56	53.79 ± 17.46
GRAPHPROMPT	20.21 ± 11.52	63.03 ± 12.14	67.04 ± 11.48

Table 3: Accuracy evaluation on graph classification.

Methods	PROTEINS 5-shot	COX2 5-shot	ENZYMES 5-shot	BZR 5-shot
GCN	54.87 ± 11.20	51.37 ± 11.06	20.37 ± 5.24	56.16 ± 11.07
GRAPHSAGE	52.99 ± 10.57	52.87 ± 11.46	18.31 ± 6.22	57.23 ± 10.95
GAT	48.78 ± 18.46	51.20 ± 27.93	15.90 ± 4.13	53.19 ± 20.61
GIN	<u>58.17</u> ± 8.58	51.89 ± 8.71	20.34 ± 5.01	57.45 ± 10.54
INFOGRAPH	54.12 ± 8.20	54.04 ± 9.45	20.90 ± 3.32	57.57 ± 9.93
GRAPHCL	56.38 ± 7.24	<u>55.40</u> ± 12.04	<u>28.11</u> ± 4.00	<u>59.22</u> ± 7.42
GRAPHPROMPT	64.42 ± 4.37	59.21 ± 6.82	31.45 ± 4.32	61.63 ± 7.68

- GraphPrompt outperforms all baselines for both node classification task and graph classification task, which implies
 - GraphPrompt is able to narrow the gap between pre-training task and downstream tasks.
 - GraphPrompt could effectively derive the downstream tasks to exploit the pre-trained model in task-specific manner.

Experiment

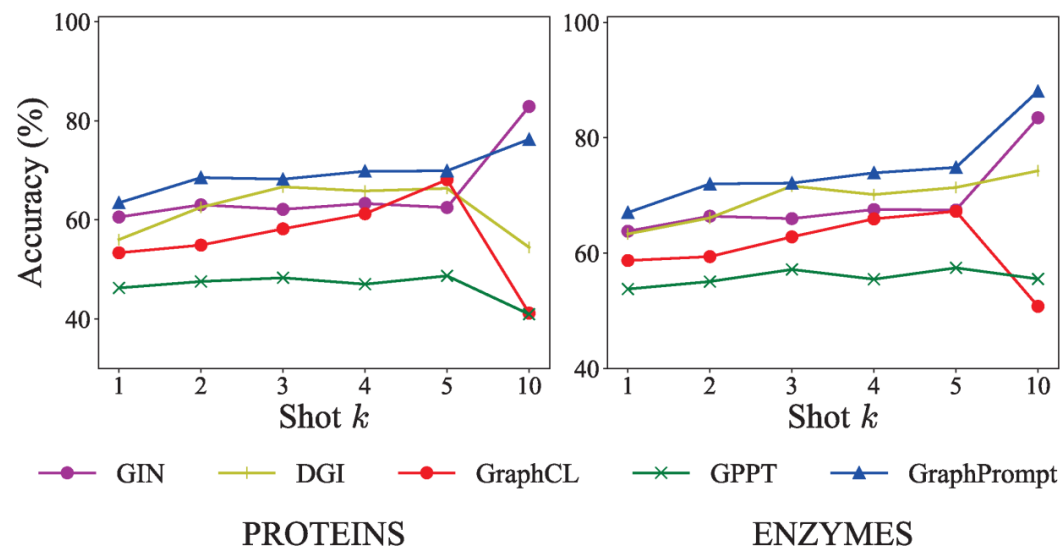


Figure 3: Impact of shots on few-shot node classification.

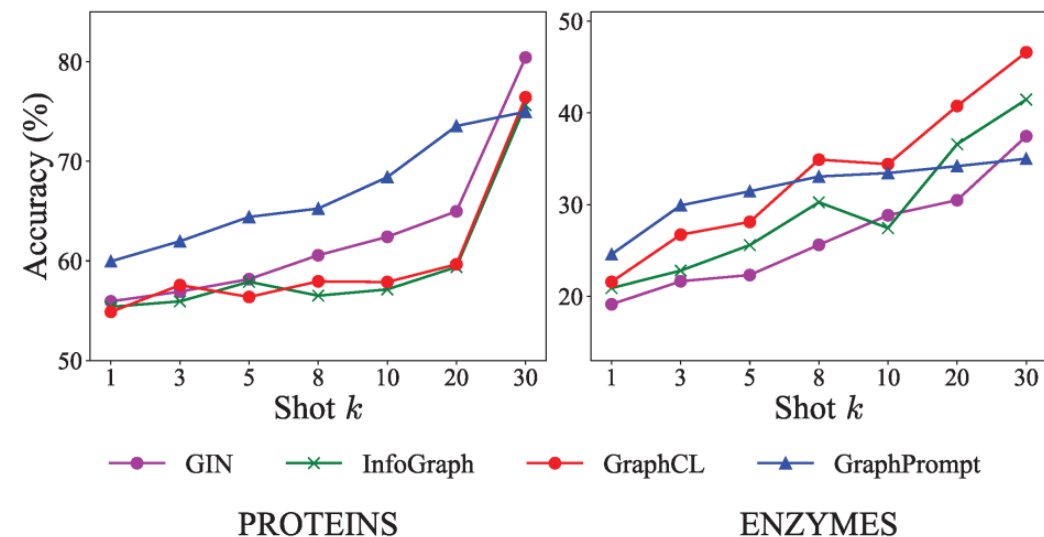


Figure 4: Impact of shots on few-shot graph classification.

- GraphPrompt consistently outperforms the baselines especially with lower shots
- For node classification task, 10 shot is sufficient for semi-supervised learning since graph is small
- For graph classification task, GraphPrompt can be surpassed by some baselines when given more shots

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Conclusions

- **Problem: Pretraining-Prompting**
 - Unify pre-training task and downstream tasks
 - Attain task-specific optima
- **Proposed-Model: GraphPrompt**
 - Unify upstream and downstream tasks via subgraph similarity
 - Using prompt vector to change the feature weights of each dimension of the node embedding to guide subgraph readout
- **Experiment**
 - GraphPrompt outperforms all baselines for both node classification task and graph classification task

Thanks!

Paper, data & code available at <https://xingtongyu.netlify.app/>

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