

Satisfaction, Validity, and State Updates

CS 536: Science of Programming, Fall 2021

1. Say u and v stand for variables (possibly the same variable) and α and β are values (possibly equal). When is $\sigma[u \mapsto \alpha][v \mapsto \beta] = \sigma[v \mapsto \beta][u \mapsto \alpha]$? Hint: There are four cases because maybe $u \equiv v$ and maybe $\alpha = \beta$.
2. Let $\sigma(b) = (7, 5, 12, 16)$. Assume out-of-bound indexes cause runtime errors.
 - a. Does $\sigma \models \exists k . 0 \leq k \wedge k+1 < \text{size}(b) \wedge b[k] < b[k+1]$? If so, what was your witness value for k ?
 - b. Does $\sigma \models \exists k . 0 < k-1 \wedge k+1 < \text{size}(b) \wedge b[k-1] < b[k] < b[k+1]$? If so, what was your witness value for k ?
 - c. Does $\sigma \models \forall k . 0 \leq k < 4 \rightarrow b[k] > 0$?
 - d. If $\sigma(k) = -5$, then does $\sigma \models \exists k . b[k] > 0$?
3. For each of the situations below, fill in the blanks to describe when the situation holds.

Fill in $\underline{\quad}_1$ with “some”, “every”, or “this”

Fill in $\underline{\quad}_2$ with “some” or “every”

Fill in $\underline{\quad}_3$ with “ $\sigma(x)$ must be undefined”, “ $\sigma(x)$ must be defined and $\sigma \models p$ ”, or “nothing of $\sigma(x)$ ”

Fill in $\underline{\quad}_4$ with “ $\models p$ ” or “ $\not\models p$ ”

- a. $\sigma \models (\exists x \in U. p)$ iff for $\underline{\quad}_1$ state σ and $\underline{\quad}_2 \alpha \in U$, $\sigma[x \mapsto \alpha] \underline{\quad}_4$
- b. $\sigma \models (\forall x \in U. p)$ iff for $\underline{\quad}_1$ state σ and $\underline{\quad}_2 \alpha \in U$, $\sigma[x \mapsto \alpha] \underline{\quad}_4$
- c. $\sigma \models (\exists x \in U. p)$ requires $\underline{\quad}_3$.
- d. $\sigma \models (\forall x \in U. p)$ requires $\underline{\quad}_3$.
- e. $\sigma \not\models (\exists x \in U. p)$ iff for $\underline{\quad}_1$ state σ for $\underline{\quad}_2 \alpha \in U$, $\sigma[x \mapsto \alpha] \underline{\quad}_4$
- f. $\sigma \not\models (\forall x \in U. p)$ iff for $\underline{\quad}_1$ state σ for $\underline{\quad}_2 \alpha \in U$, $\sigma[x \mapsto \alpha] \underline{\quad}_4$
- g. $\not\models (\forall x \in U. p)$ iff for $\underline{\quad}_2$ state σ , we have $\sigma \underline{\quad}_4 (\forall x \in U. p)$.
- h. $\not\models (\exists x \in U. p)$ iff for $\underline{\quad}_2$ state σ , we have $\sigma \underline{\quad}_4 (\exists x \in U. p)$.
- i. $\not\models (\forall x \in U. p)$ iff for $\underline{\quad}_2$ state σ , and for $\underline{\quad}_2 \alpha \in U$, we have $\sigma[x \mapsto \alpha] \underline{\quad}_4$
- j. $\models (\exists x \in U . (\forall y \in V . p))$ iff for $\underline{\quad}_1$ state σ , for $\underline{\quad}_2 \alpha \in U$, and for $\underline{\quad}_2 \beta \in V$, we have $\sigma[x \mapsto \alpha][y \mapsto \beta] \underline{\quad}_4$
- k. $\not\models (\exists x \in U . (\forall y \in V . p))$ iff for $\underline{\quad}_1$ state σ , for $\underline{\quad}_2 \alpha \in U$, and for $\underline{\quad}_2 \beta \in V$, we have $\sigma[x \mapsto \alpha][y \mapsto \beta] [\models | \not\models \neg] p$.

- I. $\models (\forall x \in U . (\exists y \in V . p))$ iff for $\underline{\quad}_1$ state σ , for $\underline{\quad}_2 \alpha \in U$, and for $\underline{\quad}_2 \beta \in V$, we have $\sigma[x \mapsto \alpha][y \mapsto \beta] \underline{\quad}_4$
- m. $\not\models (\forall x \in U . (\exists y \in V . p))$ iff for $\underline{\quad}_1$ state σ , for $\underline{\quad}_2 \alpha \in U$, and for $\underline{\quad}_2 \beta \in V$, we have $\sigma[x \mapsto \alpha][y \mapsto \beta] \underline{\quad}_4$
4. Let $p \equiv \exists y . \forall x . f(x) > y$, and let $q \equiv \forall x . \exists y . f(x) > y$. (As usual, assume a domain of \mathbb{Z} .)
- Is it the case that (regardless of the definition of f), if p is valid then so is q ? If so, explain why. If not, give a definition of $f(x)$ and show $\models p$ but $\not\models q$.
 - (The converse.) Is it the case that (regardless of the definition of f), if q is valid then so is p ? If so, explain why. If not, give a definition of $f(x)$ and show $\models q$ but $\not\models p$.

CS 536: Solution to Activity 4 (Satisfaction, Validity, and State Updates)

1. $\sigma[u \mapsto \alpha][v \mapsto \beta] = \sigma[v \mapsto \beta][u \mapsto \alpha]$ iff $u \not\equiv v$ or ($u \equiv v$ and) $\alpha = \beta$. Another way to phrase this is ($\alpha = \beta$ or $u \not\equiv v$)
2. (Quantified statements over arrays) Let $\sigma(b) = (7, 5, 12, 16)$.
 - a. Yes, $\sigma \models \exists k. 0 \leq k \wedge k+1 < \text{size}(b) \wedge b[k] < b[k+1]$ with 1 and 2 as possible witnesses for k .
 - b. Yes, $\sigma \models \exists k. 0 \leq k-1 \wedge k+1 < \text{size}(b) \wedge b[k-1] < b[k] < b[k+1]$ with 2 as the only witness that works.
 - c. Yes, $\sigma \models \forall k. b[k] > 0$
 - d. Yes, if $\sigma(k) = -5$, we still have $\sigma \models \exists k. b[k] > 0$, with witnesses 0, 1, 2, 3. The key is that for σ to satisfy the existential with witness call it α , then we need $\sigma[k \mapsto \alpha] \models b[k] > 0$, which doesn't depend on $\sigma(k)$ because the update of σ uses $k = \alpha$, not $k = \text{whatever } \sigma(k) \text{ happens to be}$. Here's a step-by-step explanation (this is way too much detail for appearing on a test):

$\sigma[k \mapsto \alpha] \models b[k] >$
 iff $\sigma[k \mapsto \alpha](b[k]) > \sigma[k \mapsto \alpha](0)$ defn state \models relational test
 iff $(\sigma[k \mapsto \alpha](b))(\sigma[k \mapsto \alpha](k)) > 0$ the value of 0 is zero
 iff $(\sigma(b))(\sigma[k \mapsto \alpha](k)) > 0$ $\sigma[k \mapsto \alpha](b) = \sigma(b)$ because $b \not\equiv k$
 iff $(\sigma(b))(\alpha) > 0$ $\sigma[k \mapsto \alpha](k) = \alpha$
 iff 7, 5, 12, or 16 > 0 depending on $\alpha = 0, 1, 2, \text{ or } 3$

3. (Validity/invalidity of quantified predicates)

- a. this σ , some α , $\models p$
- b. this σ , every α , $\models p$
- c. nothing of $\sigma(x)$
- d. nothing of $\sigma(x)$
- e. this σ , every α , $\not\models p$
- f. this σ , some α , $\not\models p$
- g. some σ , $\not\models \forall x \in U. p$
- h. some σ , every α , $\not\models p$
- i. some σ , some α , $\not\models p$
- j. every σ , some α , every β , $\models p$
- k. some σ , every α , some β , $\not\models p$
- l. every σ , every α , some β , $\models p$
- m. some σ , some α , every β , $\not\models p$

4. ($\exists \forall$ predicates versus $\forall \exists$ predicates, specifically $p \equiv \exists y . \forall x . f(x) > y$, and $q \equiv \forall x . \exists y . f(x) > y$)

- The relation does hold: $\models p$ implies $\models q$. The short explanation is that for each value α for x , we need to find a value β for y that satisfies the body, but p says that there's a value that works for every α , so we can use that value for β . In more detail, assume p is valid: for every state σ , there is some value β where for every value α , $\sigma[y \mapsto \beta][x \mapsto \alpha] \models f(x) > y$. To show that q is valid, take an arbitrary state τ with value α for x . We need a witness value for the $\exists y$; using p with τ for σ , we get a β for the $\exists y$ of p and use that as the witness for the $\exists y$ in q . So then we need $\tau[x \mapsto \alpha][y \mapsto \beta] \models f(x) > y$. Substituting σ for τ and swapping the order of the updates, we need $\sigma[y \mapsto \beta][x \mapsto \alpha] \models f(x) > y$. But that's exactly what p provided.
- The relation does not hold: We can have $\models q$ but $\not\models p$. The easiest example is $f(x) = x$, then validity of p would require us to find an integer value for y that is $>$ every possible integer value of x , but no such value exists.

As an aside, you can use an arbitrary predicate over x and y instead of $f(x) > y$ as the body of the $\exists \forall$ and $\forall \exists$ predicates. I use $f(x) > y$ here just because it's nice and concrete.