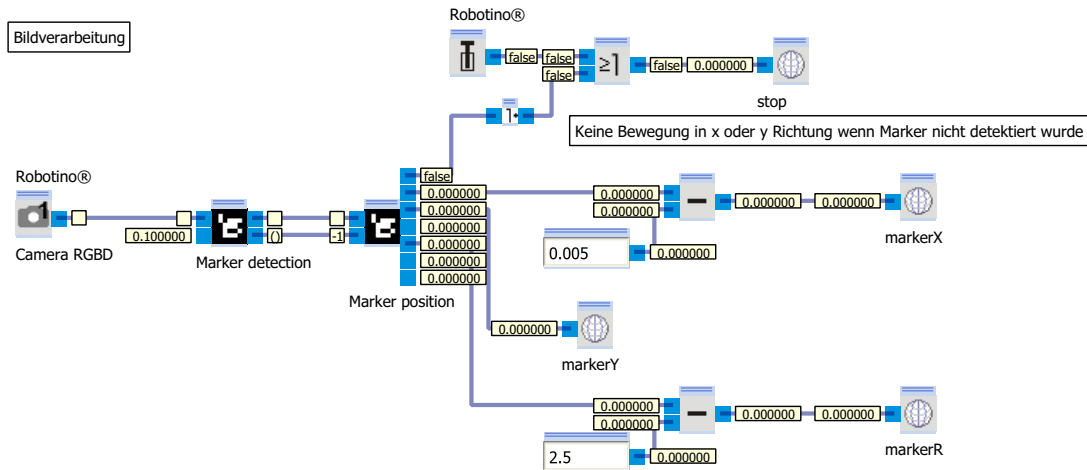
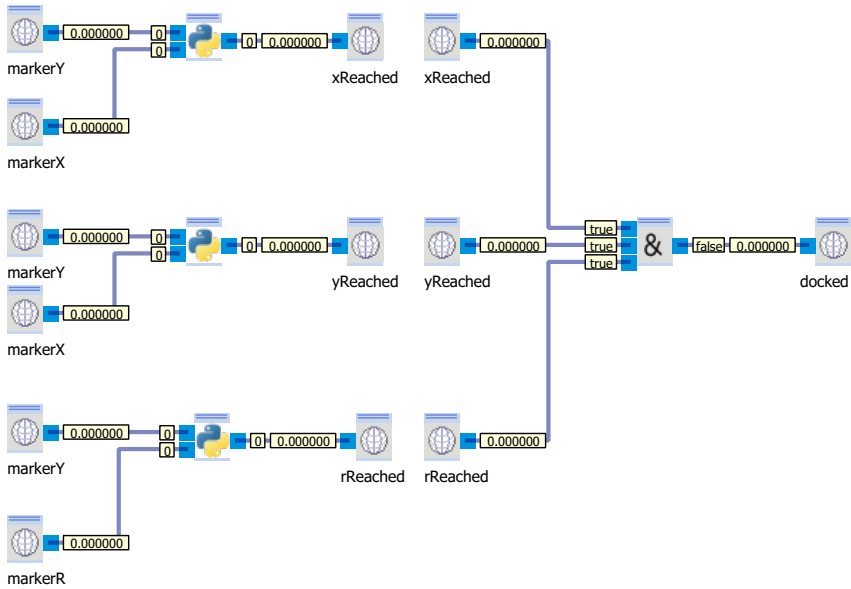


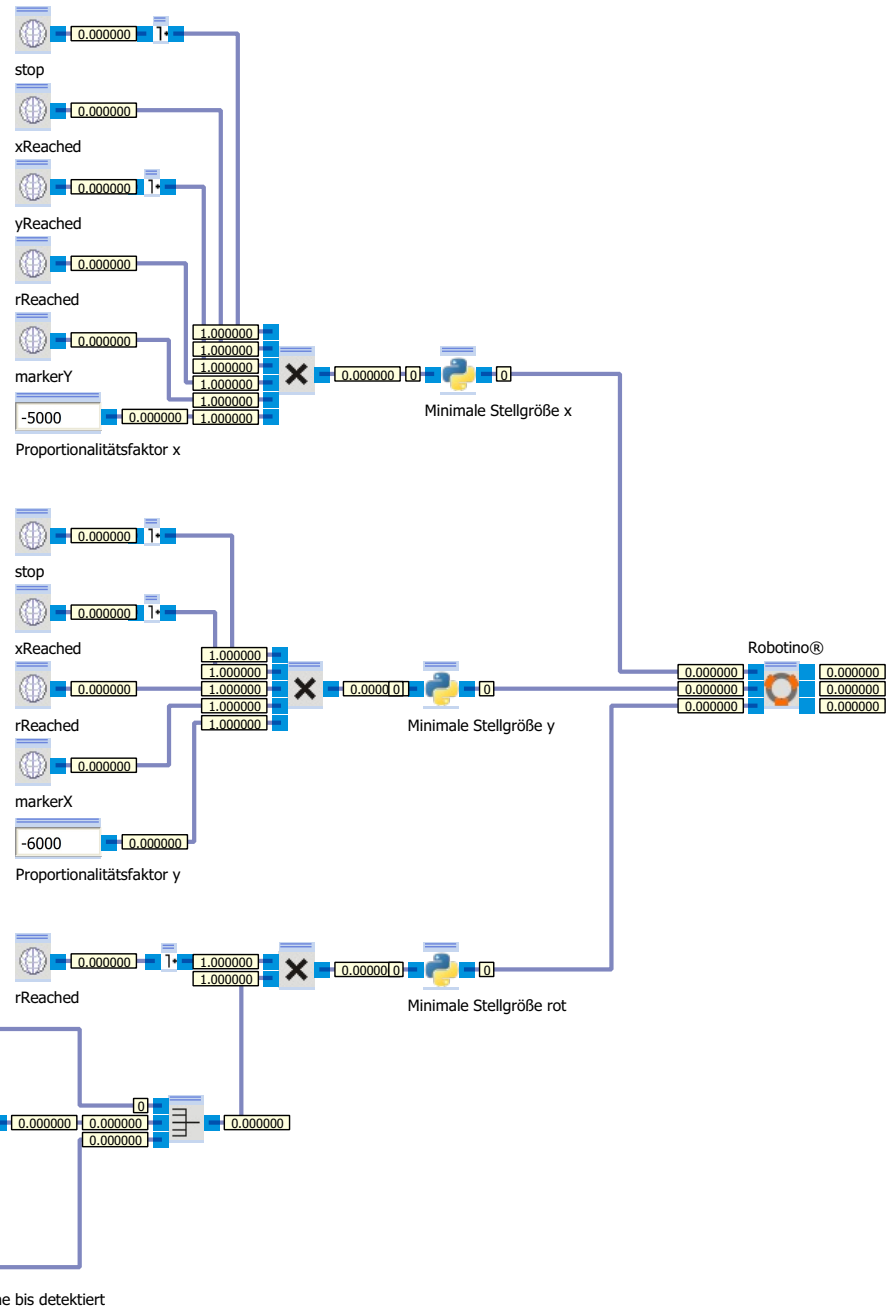
## Bildverarbeitung



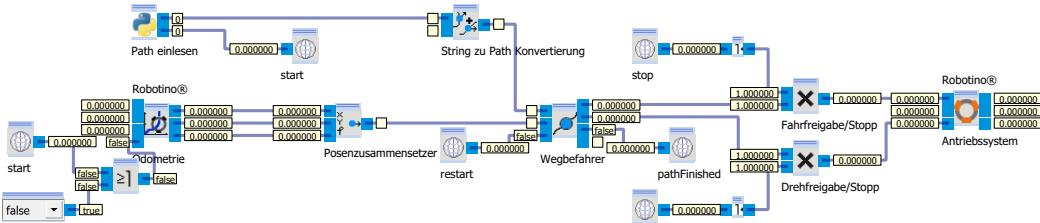
## Positionsüberprüfung



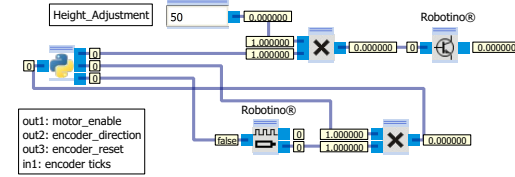
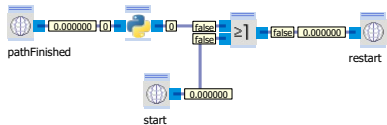
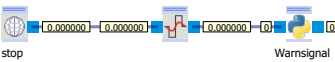
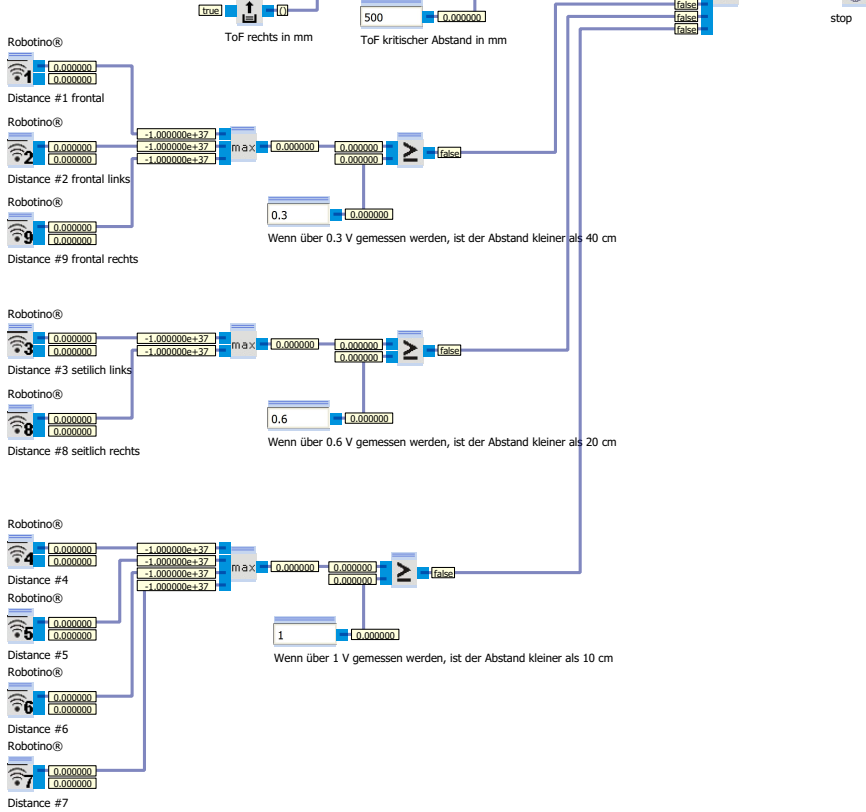
## Motorregelung



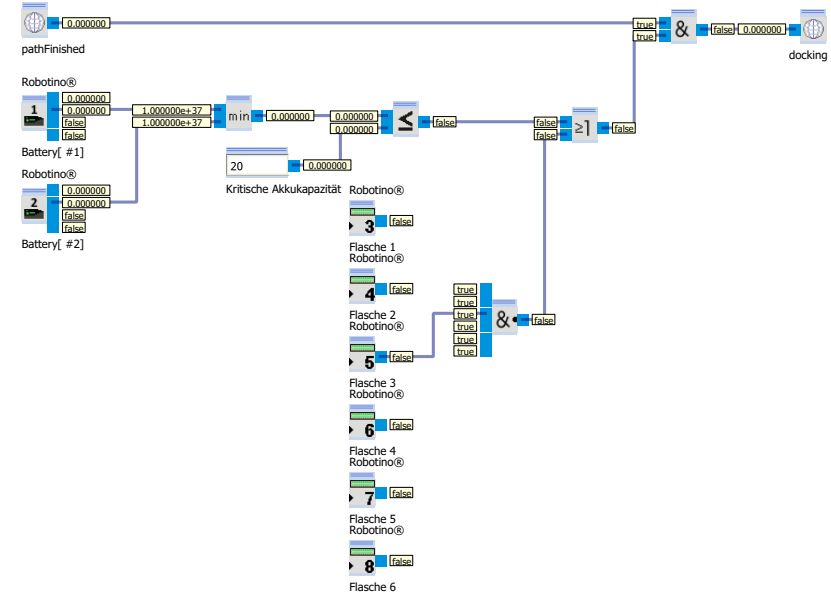
## Route\_Following

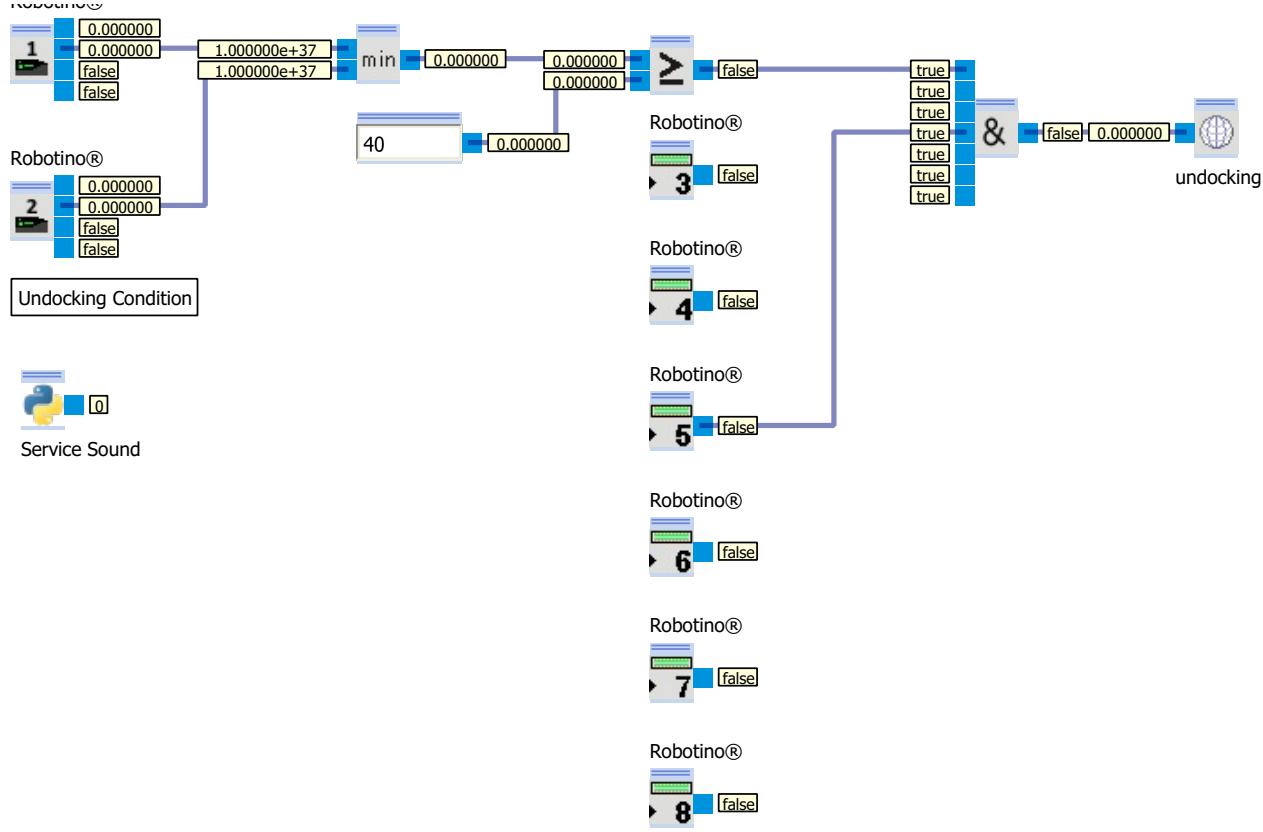


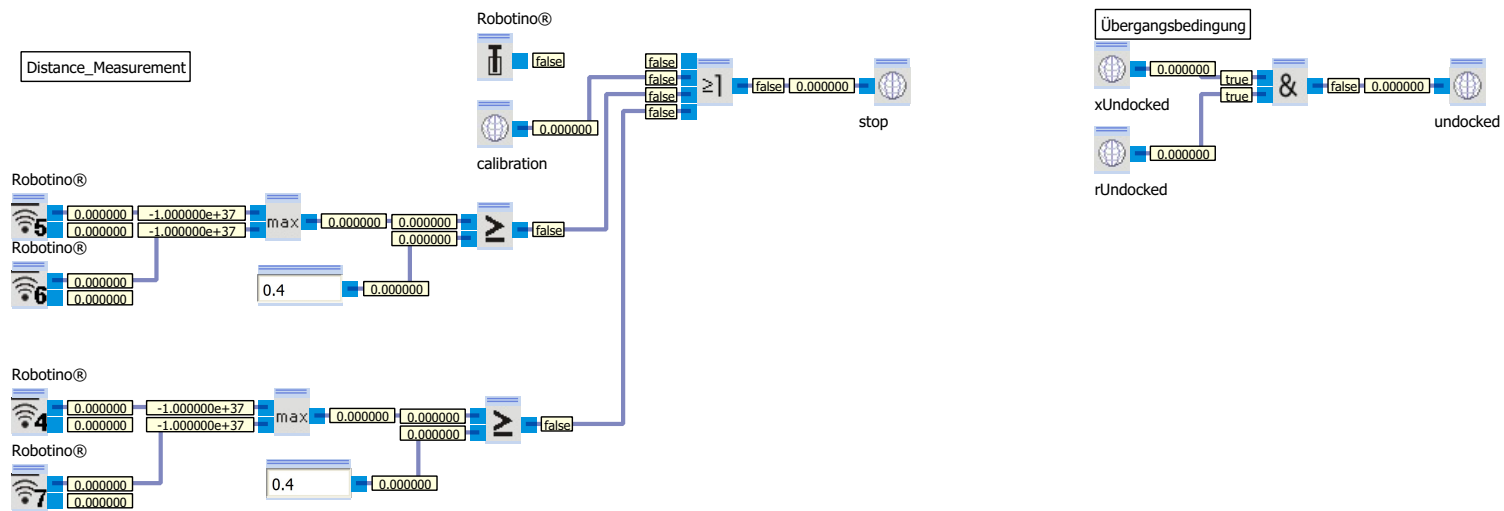
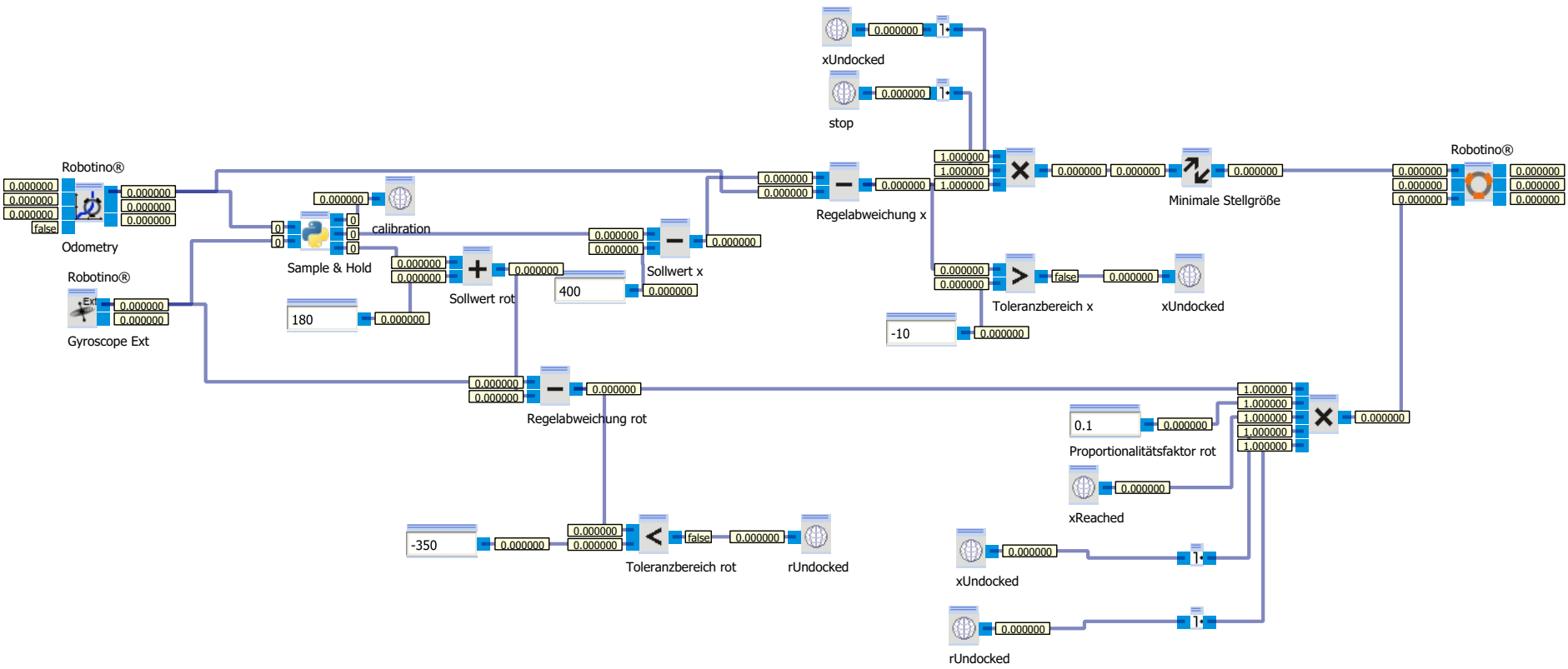
## Distance\_Measurement



## Docking Condition







Undocking