

Init

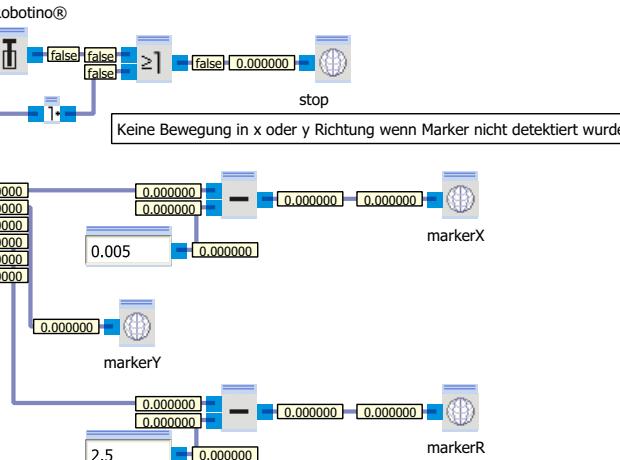
Main program

Bildverarbeitung

Robotino®

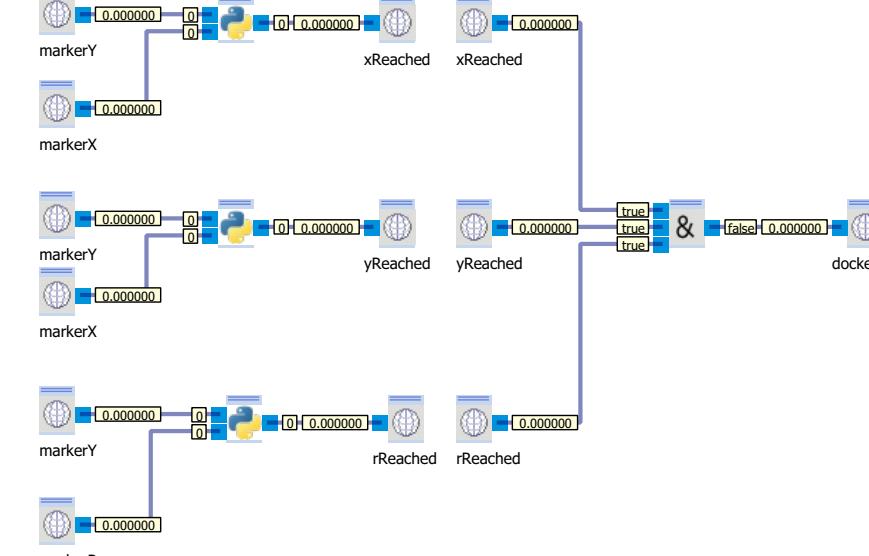
Camera RGBD

Marker detection

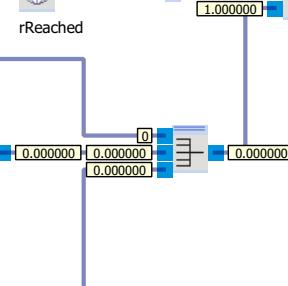
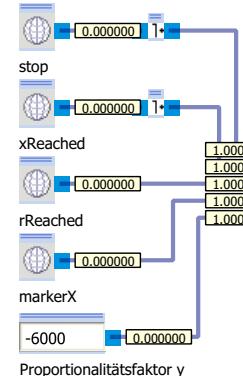
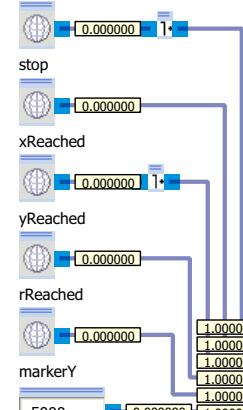


Positionsüberprüfung

Übergangsbedingung

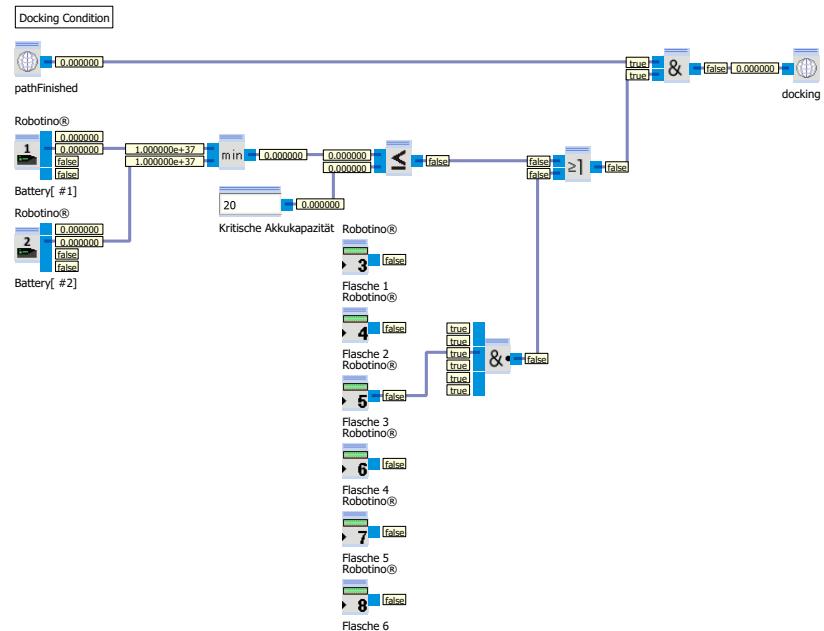
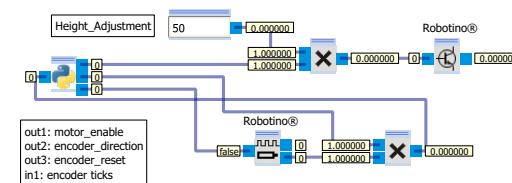
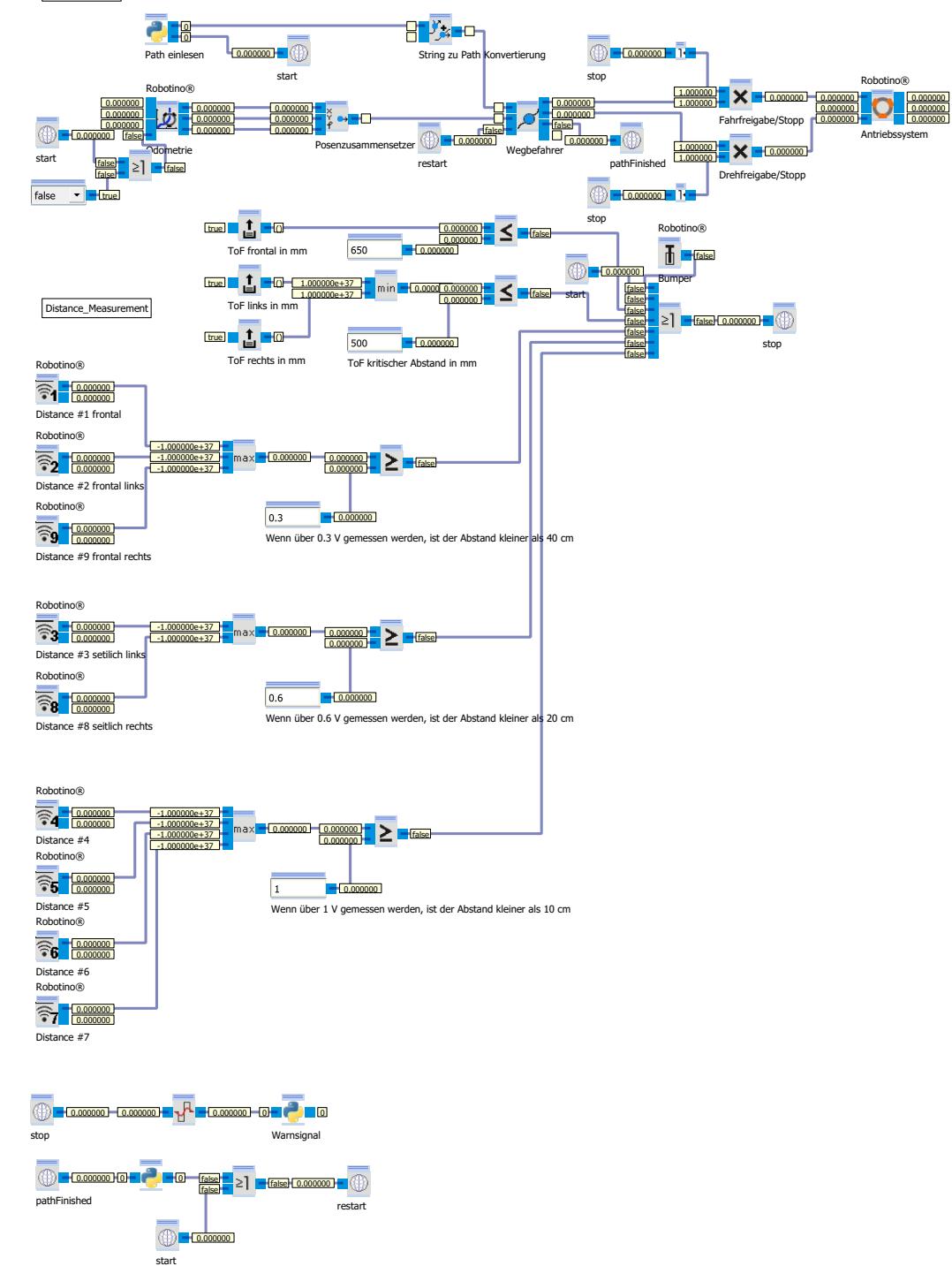


Motorregelung

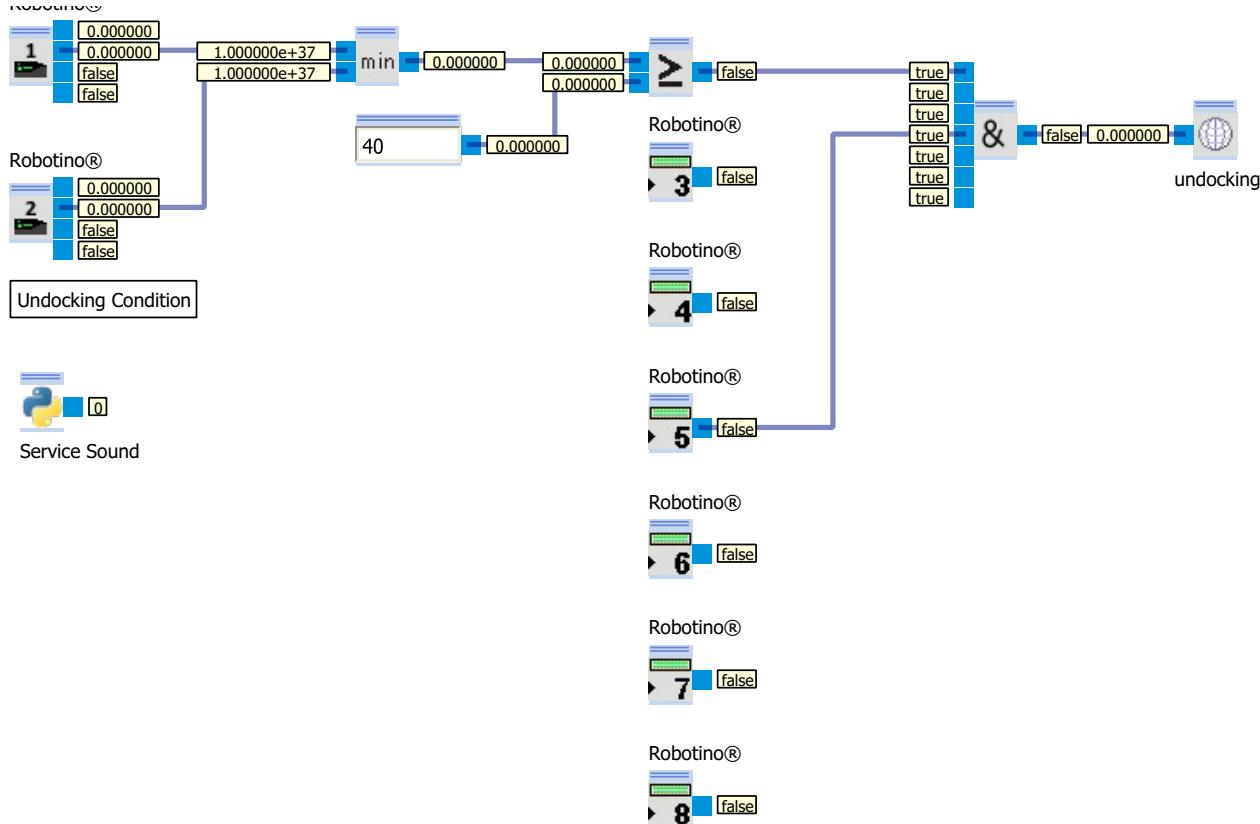


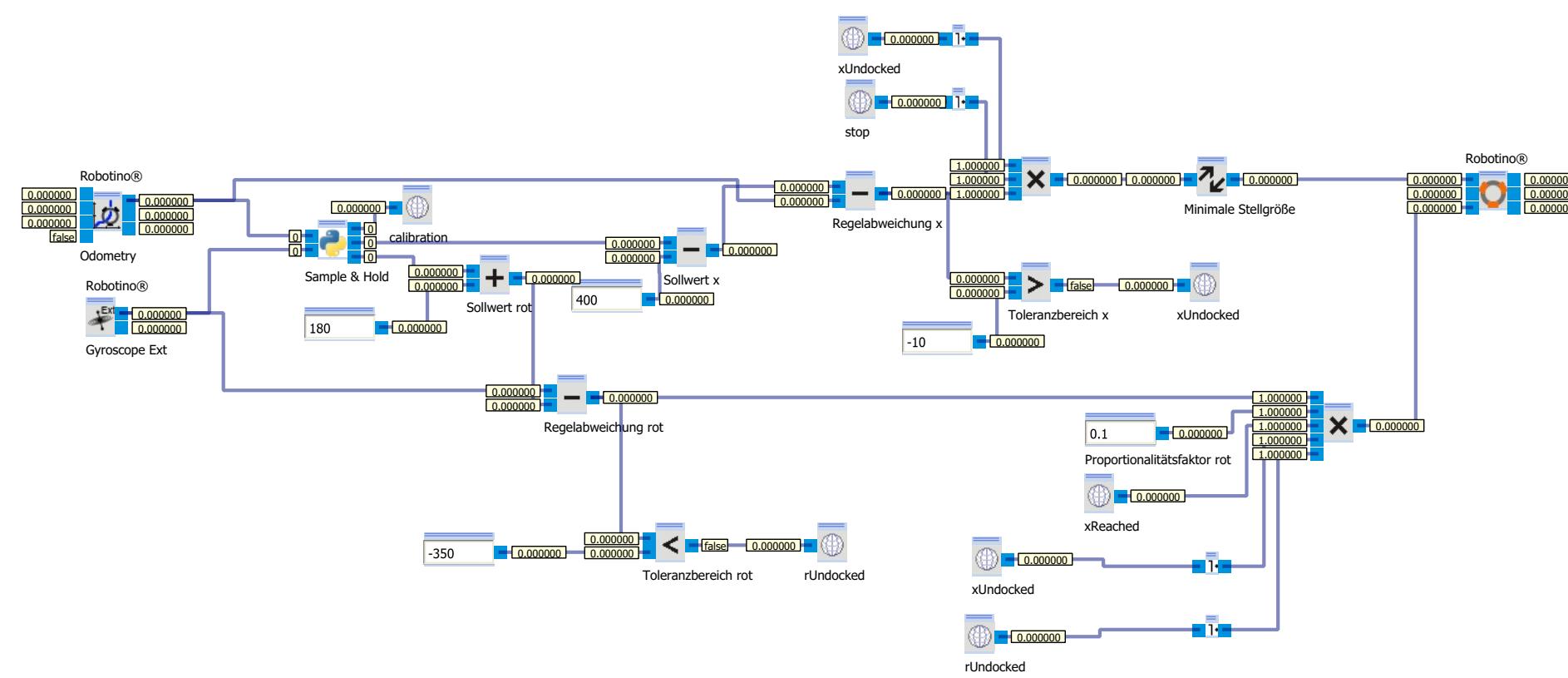
Wenn Marker nicht detektiert -> drehe bis detektiert

Route_Following

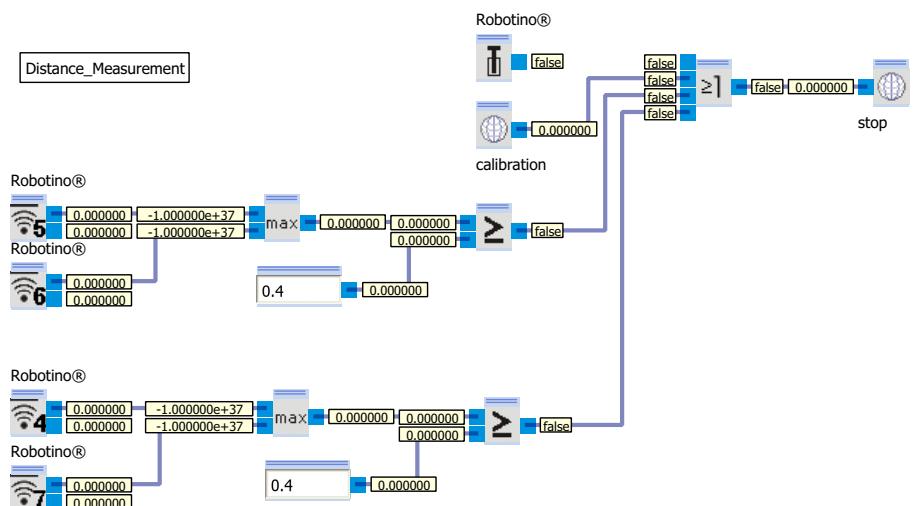


Route_Following





Distance_Measurement



Undocking