# Testing Quick Reference Handbooks in Flight Simulators

Anthony Berg (200871682) Supervisor: Dr Leo Freitas

13th May 2024

# **Preface**

## Abstract

This is an abstract.

### Declaration

I declare that this dissertation represents my own work except where otherwise stated.

## Acknowledgements

I would like to thank my supervisor Leo Freitas for supporting, guiding, and providing with areas of improvement for me throughout the project.

# Contents

| 1  | Intr          | roduction                     | 1  |  |
|----|---------------|-------------------------------|----|--|
|    | 1.1           | Scene                         | 1  |  |
|    | 1.2           | Motivation                    | 1  |  |
|    | 1.3           | Aim                           | 1  |  |
|    | 1.4           | Objectives                    | 1  |  |
| 2  | Background    |                               |    |  |
|    | 2.1           | Hypothesis                    | 3  |  |
|    | 2.2           | Safety in Aviation            | 3  |  |
|    |               | 2.2.1 History                 | 3  |  |
|    |               | 2.2.2 Checklists              | 3  |  |
|    | 2.3           | Formal Methods                | 3  |  |
|    |               | 2.3.1 History                 | 3  |  |
|    |               | 2.3.2 Application             | 3  |  |
|    | 2.4           | Solution Stack                | 3  |  |
|    |               | 2.4.1 Formal Model            | 4  |  |
|    |               | 2.4.2 Checklist Tester        | 4  |  |
|    |               | 2.4.3 Flight Simulator Plugin | 4  |  |
| 3  | Des           | sign/Implementation           | 5  |  |
|    | 3.1           | Components                    | 5  |  |
|    | 3.2           | Formal Method                 | 5  |  |
|    | 3.3           | Checklist Tester              | 6  |  |
|    | 0.0           | 3.3.1 Designing               | 6  |  |
|    | 3.4           | Scenarios                     | 6  |  |
|    | 3.5           | Decisions                     | 6  |  |
| 4  | Res           | sults                         | 8  |  |
|    | 4.1           | Problems Found                | 8  |  |
|    | 4.2           | LOC?                          | 8  |  |
|    | 4.3           | Reflection                    | 8  |  |
|    | 4.4           | Time Spent                    | 8  |  |
| 5  | Cor           | nclusion                      | 9  |  |
|    | 5.1           | Changes                       | 9  |  |
|    | 5.2           | Objectives                    | 9  |  |
|    | 5.3           | What Next                     | 9  |  |
| Δ  | For           | mal Model                     | 10 |  |
|    |               |                               |    |  |
| Re | References 18 |                               |    |  |

## Introduction

### 1.1 Scene

- Designing Emergency Checklists is difficult
- Procedures in checklists must be tested in simulators [1], which usually means trained pilots test it, as the tests need to work consistently [2] (making sure it's not lengthy, concise and gets critical procedures)
- · Checklists are usually carried out in high workload environments, especially emergency ones

#### 1.2 Motivation

- Testing procedures in checklists are often neglected [1]
- There are some checklists that may not be fit for certain scenarios e.g. ditching (water landing) checklist for US Airways Flight 1549 assumed at least one engine was running [3], but in this scenario, there were none
- Some checklists may make pilots 'stuck' not widely implemented, could be fixed with 'opt out' points. e.g. US Airways 1549, plane below 3000ft, could have skip to later in the checklist to something like turn on APU, otherwise plane will have limited control [3].
- Checklists may take too long to carry out Swissair 111

#### 1.3 Aim

The goal of this project is to test checklists in Quick Reference Handbooks (QRH) for flaws that could compromise the aircraft and making sure that the tests can be completed in a reasonable amount of time by pilots. It is also crucial to make sure that the tests are reproducible in the same flight conditions and a variety of flight conditions.

## 1.4 Objectives

- 1. Research current checklists that may be problematic and are testable in the QRH tester being made
- 2. Implement a formal model that runs through checklists, with the research gathered to produce an accurate test
  - (a) Understand the relative states of the aircraft that need to be captured
  - (b) Ensure that the results of the checklist procedures are consistent
- 3. Implement a QRH tester manager that
  - Runs the formal model and reacts to the output of the formal model

- Connect to a flight simulator to run actions from the formal model
- $\bullet$  Implement checklist procedures to be tested, run them, and get feedback on how well the procedure ran

# Background

## 2.1 Hypothesis

- Checklists can be tested in a simulated environment to find flaws in checklist for things like
  - Can be done in an amount of time that will not endanger aircraft
  - Provides reproducible results
  - Procedures will not endanger aircraft or crew further (Crew referring to Checklist Manifesto with the cargo door blowout)
- Results in being able to see where to improve checklists

## 2.2 Safety in Aviation

#### 2.2.1 History

• 70-80% of aviation accidents are attributed to human factors [4]

#### 2.2.2 Checklists

- Checklists have been shown to aid in minimising human errors [2]
- However, checklists can be misleading and compromise the safety of the aircraft due to them being either too confusing or taking too long to complete [1]
- That is why testing checklists are important to avoid these situations

#### 2.3 Formal Methods

#### 2.3.1 History

### 2.3.2 Application

#### 2.4 Solution Stack

- There would be around 3 main components to this tester
  - Formal Model
  - Flight Simulator plugin
  - Checklist Tester (to connect the formal model and flight simulator)
- As VDM-SL is being used, it uses VDMJ to parse the model [5]. This was a starting point for the tech stack, as VDMJ is also open source.
- VDMJ is written in Java [5], therefore to simplify implementing VDMJ into the Checklist Tester, it would be logical to use a Java virtual machine (JVM) language.

### 2.4.1 Formal Model

- There were a few ways of implementing the formal model into another application
- Some of these methods were provided by Overture [6]
  - RemoteControl interface
  - VDMTools API [7]
- However, both of these methods did not suit what was required as most of the documentation for RemoteControl was designed for the Overture Tool IDE. VDMTools may have handled the formal model differently
- The choice was to create a VDMJ wrapper, as the modules are available on Maven

#### 2.4.2 Checklist Tester

#### JVM Language

- There are multiple languages that are made for or support JVMs [8]
- Requirements for language
  - Be able to interact with Java code because of VDMJ
  - Have Graphical User Interface (GUI) libraries
  - Have good support (the more popular, the more resources available)
- The main contenders were Java and Kotlin [9]
- Kotlin [9] was the choice in the end as Google has been putting Kotlin first instead of Java. Kotlin also requires less boilerplate code (e.g. getters and setters) [10]

#### Graphical User Interface

- As the tester is going to include a UI, the language choice was still important
- There are a variety of GUI libraries to consider using
  - JavaFX [11]
  - Swing [12]
  - Compose Multiplatform [13]
- The decision was to use Compose Multiplatform in the end, due to time limitations and having prior experience in using Flutter [14]
- Compose Multiplatform has the ability to create a desktop application and a server, which
  would allow for leeway if a server would be needed

#### 2.4.3 Flight Simulator Plugin

- There are two main choices for flight simulators that can be used for professional simulation
  - X-Plane [15]
  - Prepar3D [16]
- X-Plane was the choice due to having better documentation for the SDK, and a variety of development libraries for the simulator itself
- For the plugin itself, there was already a solution developed by NASA, X-Plane Connect [17] that is more appropriate due to the time limitations and would be more likely to be reliable as it has been developed since 2015

# Design/Implementation

## 3.1 Components

Splitting up the project into multiple components has been useful for

- Aiding in planning to make the implementation more efficient
- Delegating specific work tasks
- Making the project modular, for example, allowing for a different simulator to be implemented with minimal need to refactor other parts of the codebase

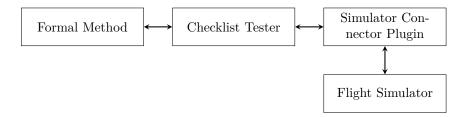


Figure 3.1: Abstract layout of components

Each of the components in Figure 3.1 will be covered in detail in this chapter.

### 3.2 Formal Method

- Formal modelling is the heart of the logic for testing checklists
- Formal model created using VDM-SL
- It allows to test that the checklists have been completed in a proper manner and that it is provable
- Model keeps track of
  - Aircraft state
  - Checklist state
- If an error were to occur in the model, this can be relayed that there was something wrong with running the test for the checklist, such as:
  - Procedure compromises integrity of aircraft
  - There is not enough time to complete the procedure
  - There is a contradiction with the steps of the checklist

#### 3.3 Checklist Tester

Brief overview of what it is supposed to do...

### 3.3.1 Designing

- Used Figma to create a design for the application
- Allows for implementing the front end to be faster because:
  - They act as a requirement for code
  - You do not forget what needs to be implemented
  - Keeps everything consistent
  - Allows to think about making parts of the GUI modular and what components can be reused
- Figma allows for plugins such as Material 3 colours and Material 3 components
- Figure 3.2 is the final design that will be used for the program

#### Limitations of Figma

- The Material 3 Components in Figma do not include features that are available in Jetpack Compose
- In this project, the 'Simulator Test' at the bottom of Figure 3.2 does not include a leading icon [18], and therefore had to be a trailing checkbox
- This was overcome by adding comments in Figma as a reminder of how the actual implementation should be like
- Another limitation is that in Figure 3.2, the title of the screen in the top app bar [19] is not centered, and that is because the auto layout feature in Figma allows for equal spacing, rather than having each in a set position

#### 3.4 Scenarios

- Use a Quick Reference Handbook (QRH) to find potential list of checklists to test
- Look at previous accident reports that had an incident related to checklists and test it with my tool to see if it will pick it up
- These previous accident reports can be good metrics to know what statistics to look out for

#### 3.5 Decisions

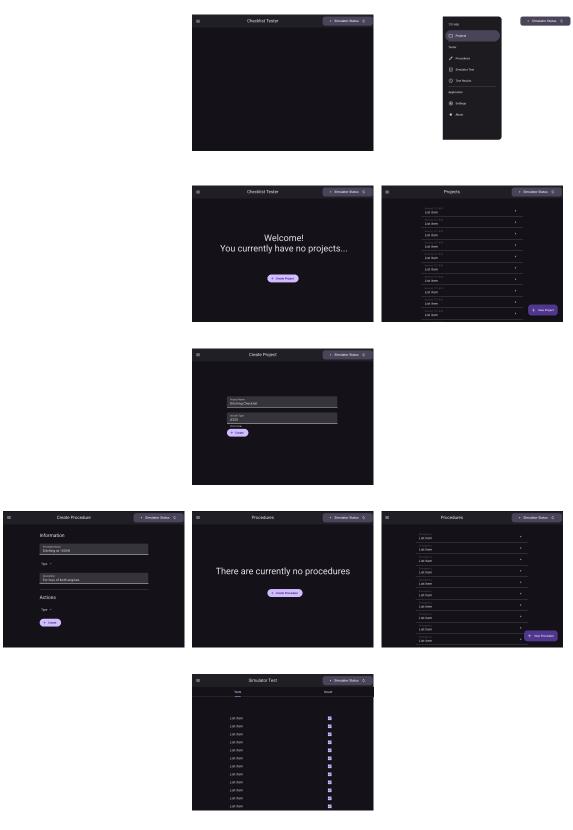


Figure 3.2: Design for the Checklist Connector GUI in Figma

# Results

- 4.1 Problems Found
- 4.2 LOC?
- 4.3 Reflection
- 4.4 Time Spent

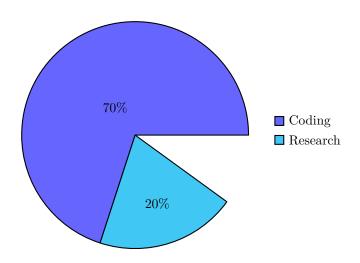


Figure 4.1: Time spent on sections of project

# Conclusion

- 5.1 Changes
- 5.2 Objectives
- 5.3 What Next

# Appendix A

## Formal Model

```
1 module Checklist
2 exports all
3 definitions
5 values
       -- Before Start Checklist
7
       -- Items in Aircraft
8
       -- Flight Deck... (can't check)
9
       fuel: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false)→
10
       pax_sign: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, →
           true));
       windows: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<ON>, →
11
           false));
12
       -- Preflight steps
       acol: ItemObject = mk_ItemObject(<SWITCH>, mk_Switch(<OFF>, false)→
13
14
       aircraft_panels: Items = {"Fuel⊔Pump" |-> fuel, "Passenger⊔Signs" →
15
           |-> pax_sign, "Windows" |-> windows, "AntiuCollisionuLights" →
           |-> acol};
16
17
       -- Checklist
18
       -- Flight Deck... (can't check)
       fuel_chkl: ChecklistItem = mk_ChecklistItem("Fuel_Pump", <SWITCH>,→
            <ON>, false);
20
       pax_sign_chkl: ChecklistItem = mk_ChecklistItem("Passenger_Signs",→
            <SWITCH>, <ON>, false);
21
       windows_chkl: ChecklistItem = mk_ChecklistItem("Windows", <SWITCH→</pre>
           >, < ON >, false);
22
       -- Preflight steps
23
       acol_chkl: ChecklistItem = mk_ChecklistItem("AntiuCollisionuLights→
           ", <SWITCH>, <ON>, false);
24
25
       before_start_procedure: Procedure = [fuel_chkl, pax_sign_chkl, →
           windows_chkl, acol_chkl];
26
27
       aircraft = mk_Aircraft(aircraft_panels, before_start_procedure);
28 types
29
       -- @doc The dataref name in X-Plane
30
       Dataref = seq1 of char;
31
32
       -- Aircraft
```

```
33
34
       -- Switches
35
       --@doc The state a switch can be in
36
       SwitchState = <OFF> | <MIDDLE> | <ON>;
37
38
           --@LF why have a type kist as a rename?
       ItemState = SwitchState; --@TODO | Button | ...
39
40
       --@doc A switch, with the possible states it can be in, and the \rightarrow
41
          state that it is in
42
       Switch ::
43
           position : SwitchState
44
           middlePosition : bool
45
           inv s ==
46
               (s.position = <MIDDLE> => s.middlePosition);
47
       -- Knob
48
49
       Knob ::
50
           position : nat
51
           --@LF how can a state be an int? perhaps a proper type (i..e. →
              subset of int range or a union?)
52
           states : set1 of nat
53
           inv k ==
54
               k.position in set k.states;
55
56
       Lever = nat
57
           inv t == t <= 100;
58
59
       Throttle ::
60
           thrust: Lever
61
           reverser: Lever
62
           inv t ==
63
               (t.reverser > 0 \iff t.thrust = 0);
64
65
       --@doc The type that the action of the button is
66
       ItemType = <SWITCH> | <KNOB> | <BUTTON> | <THROTTLE>;
67
68
       --@doc The unique switch/knob/etc of that aircraft
       ObjectType = Switch | Knob | Throttle;
69
70
       ItemObject ::
           type : ItemType
71
72
           object : ObjectType
73
           inv mk_ItemObject(type, object) ==
74
                   cases type:
                           <SWITCH> -> is_Switch(object),
75
76
                                   -> is_Knob(object),
                           <KNOB>
77
                           <THROTTLE>-> is_Throttle(object),
78
                            --<BUTTON> -> true
79
                           others -> true
80
                   end;
81
82
       --@doc Contains each ItemObject in the Aircraft, e.g. Fuel Pump →
          switch
83
       Items = map Dataref to ItemObject;
84
       85
           procedure
86
       Aircraft ::
```

```
87
             items : Items
 88
             procedure : Procedure
 89
             inv mk_Aircraft(i, p) ==
90
             ({ x.procedure | x in seq p } subset dom i);
91
92
         -- Checklist
93
94
         -- @doc Item of a checklist, e.g. Landing gear down
95
         ChecklistItem ::
             -- @LF again, empty string here doesn't make sense.
96
97
             procedure : Dataref
98
             type : ItemType
99
             --TODO Check is not only SwitchState
100
             check : SwitchState
101
             checked : bool;
102
103
         --@doc This is an item in the aircraft that complements the item \rightarrow
             in the procedure
104
         ItemAndChecklistItem ::
105
             item : ItemObject
106
             checklistItem: ChecklistItem
107
             inv i == i.item.type = i.checklistItem.type;
108
109
         -- @doc A section of a checklist, e.g. Landing Checklist
110
         --@LF shouldn't this be non-empty? What's the point to map a \rightarrow
             checklist name to an empty procedure? Yes.
111
         Procedure = seq1 of ChecklistItem
112
             inv p ==
113
                  --@LF the "trick" for "false not in set S" is neat. It 
ightarrow
                     forces a full evaluation, rather than short circuited →
                      (i.e. stops at first false).
114
                        I presume this was intended.
115
                  false not in set {
116
                      let first = p(x-1).checked, second = p(x).checked in
117
                               -- @LF boolean values don't need equality check
118
                           second => first--((first = true) and (second = \rightarrow
                              false))
119
                      | x in set {2,...,len p}};
120
121 functions
         -- PROCEDURES
122
123
         --@doc Finds the index of the next item in the procedure that \rightarrow
            needs to be completed
124
         procedure_next_item_index: Procedure -> nat1
125
         procedure_next_item_index(p) ==
126
             hd [ x | x in set \{1,\ldots,\text{len p}\} & not p(x).\text{checked }]-p(x).\rightarrow
                 checked = false]
127
         pre
128
             -- Checks procedure has not already been completed
129
             not procedure_completed(p)--procedure_completed(p) = false
130
         post
131
             -- Checks that the index of the item is the next one to be \rightarrow
                 completed
132
             --@LF your def is quite confusing (to me)
             --@LF how do you know that RESULT in inds p? Well, the \rightarrow
133
                 definition above okay.
134
                    but you can't know whether p(RESULT-1) will! What if \rightarrow
                 RESULT=1? p(RESULT-1)=p(0) which is invalid!
```

```
135
             (not p(RESULT).checked)
136
137
             (RESULT > 1 => p(RESULT-1).checked)
138
             --p(RESULT).checked = false
139
            --and if RESULT > 1 then
140
            -- p(RESULT-1).checked = true
141
            --else
142
            -- true
143
144
145
        -- --@doc Checks if all the procedures have been completed
146
        -- check_all_proc_completed: Checklist -> bool
147
        -- check_all_proc_completed(c) ==
148
               false not in set { procedure_completed(c(x)) | x in set \rightarrow
            {1,...,len c} };
149
        -- -- @doc Gives the index for the next procedure to complete
150
151
        -- next procedure: Checklist -> nat1
152
        -- next_procedure(c) ==
153
        -- hd [ x | x in set {1,...,len c} & not procedure_completed(c→
           (x))]
154
        -- post
155
               RESULT <= len c;
156
157
        --@doc Checks if the procedure has been completed
158
        procedure_completed: Procedure -> bool
159
        procedure_completed(p) ==
160
             false not in set { p(x).checked | x in set {1,...,len p} };
161
162
        --@doc Checks if the next item in the procedure has been completed
163
        check_proc_item_complete: Procedure * Aircraft -> bool
164
        check_proc_item_complete(p, a) ==
165
             --@LF here you have a nice lemma to prove: →
                procedure_next_item_index(p) in set inds p!
                      I think that's always true
166
167
            let procItem = p(procedure_next_item_index(p)),
168
                     --@LF here you can't tell whether this will be true? i→
                        .e. procItem.procedure in set dom a.items?
169
                 item = a.items(procItem.procedure) in
170
171
                 --TODO need to be able to check for different types of \rightarrow
                    Items
172
                 procItem.check = item.object.position
173
        pre
174
            procedure_completed(p) = false
             --@LF perhaps add
175
176
             --and
177
             --p(procedure_next_item_index(p)).procedure in set dom a.items→
178
179
180
        -- @doc Marks next item in procedure as complete
181
        mark_proc_item_complete: Procedure -> Procedure
182
        mark_proc_item_complete(p) ==
183
             let i = procedure_next_item_index(p), item = p(i) in
184
                 p ++ {i |-> complete_item(item)}
            pre
185
186
                 procedure_completed(p) = false;
```

```
187
188
         --@doc Completes an item in the procedure
        do_proc_item: ItemObject * ChecklistItem -> ItemAndChecklistItem
189
190
         do_proc_item(i, p) ==
191
             let objective = p.check,
192
                 checkckItem = complete_item(p) in
                 -- Checks if the item is in the objective desired by the \rightarrow
193
                     checklist
                 if check_item_in_position(i, objective) then
194
195
                      mk_ItemAndChecklistItem(i, checkckItem)
196
                 else
197
                     mk_ItemAndChecklistItem(move_item(i, p.check), ->
                         checkckItem)
198
        pre
199
             p.checked = false
200
         post
201
             -- Checks the item has been moved correctly
202
             check_item_in_position(RESULT.item, p.check);
203
204
         --@doc Completes a procedure step by step
205
         -- a = Aircraft
206
         complete_procedure: Aircraft -> Aircraft
207
         complete_procedure(a) ==
208
             let procedure = a.procedure in
209
                 mk_Aircraft(
210
                     a.items ++ { x.procedure |-> do_proc_item(a.items(x.→
                         procedure), x).item | x in seq procedure },
211
                      [ complete_item(x) | x in seq procedure ]
212
                 )
213
        pre
214
             not procedure_completed(a.procedure)
215
         post
216
             procedure_completed(RESULT.procedure);
217
218
         -- AIRCRAFT ITEMS
219
         --@doc Marks ChecklistItem as complete
220
         complete_item: ChecklistItem -> ChecklistItem
221
         complete_item(i) ==
222
             mk_ChecklistItem(i.procedure, i.type, i.check, true)
223
        pre
224
             i.checked = false;
225
226
         -- \mbox{@doc} Moves any type of Item
227
        move_item: ItemObject * ItemState -> ItemObject
228
        move_item(i, s) ==
229
             -- if is_Switch(i) then (implement later)
230
                 let switch: Switch = i.object in
231
                      if check_switch_onoff(switch) and (s <> <MIDDLE>) and \rightarrow
                         switch.middlePosition then
232
                          mk_ItemObject(i.type, move_switch(move_switch())
                             switch, <MIDDLE>), s))
233
                     else
234
                          mk_ItemObject(i.type, move_switch(switch, s))
235
        pre
236
             wf_item_itemstate(i, s)
237
             and not check_item_in_position(i, s);
238
             -- and wf_switch_move(i.object, s);
239
```

```
240
         --@doc Moves a specific switch in the aircraft
241
        move switch: Switch * SwitchState -> Switch
242
        move_switch(i, s) ==
243
             mk_Switch(s, i.middlePosition)
244
245
             wf_switch_move(i, s)
246
        post
247
             RESULT.position = s;
248
249
         --@doc Checks if the switch is in the on or off position
250
        check_switch_onoff: Switch -> bool
251
        check_switch_onoff(s) ==
252
             let position = s.position in
253
                 position = <OFF> or position = <ON>
254
        post
255
             -- Only one can be true at a time
             -- If the switch is in the middle position, then RESULT cannot→
256
                 be true
257
             -- If the switch is in the on/off position, then the RESULT \rightarrow
                will be true
258
             (s.position = <MIDDLE>) <> RESULT;
259
260
        --@doc Checks if the item is already in position for the desired \rightarrow
            state for that item
261
        check_item_in_position: ItemObject * ItemState -> bool
262
         check_item_in_position(i, s) ==
263
             -- if is_Switch(i) then (implement later)
264
                 i.object.position = s
265
        pre
266
             wf_item_itemstate(i,s);
267
268
        --@doc Checks if the Item.object is the same type for the \rightarrow
            ItemState
269
        wf_item_itemstate: ItemObject * ItemState -> bool
270
        wf_item_itemstate(i, s) ==
271
             (is_Switch(i.object) and is_SwitchState(s) and i.type = <+
                SWITCH>)
272
             --TODO check that the item has not already been completed \rightarrow
                before moving item
273
             --TODO add other types of Items
274
             ;
275
276
         -- @doc Checks if the move of the Switch is a valid
277
        wf_switch_move: Switch * SwitchState -> bool
278
        wf_switch_move(i, s) ==
279
             -- Checks that the switch not already in the desired state
280
             i.position <> s and
281
             -- The switch has to move one at a time
282
             -- Reasoning for this is that some switches cannot be moved in→
                 one quick move
283
             if i.middlePosition = true then
284
                 -- Checks moving the switch away from the middle position
285
                 (i.position = <MIDDLE> and s <> <MIDDLE>)
286
                 -- Checks moving the siwtch to the middle position
287
                 <> (check_switch_onoff(i) = true and s = <MIDDLE>)
288
289
                 check_switch_onoff(i) and s <> <MIDDLE>;
290
```

```
291
292 end Checklist
293
294 /*
295 //@LF always a good idea to run "qc" on your model. Here is its output→
                     . PO 21 and 22 show a problem.
296
           //@LF silly me, this was my encoding with the cases missing one \rightarrow
                     pattern :-). I can see yours has no issues. Good.
297
298 > qc
299 PO #1, PROVABLE by finite types in 0.002s
300 PO #2, PROVABLE by finite types in 0.0s
301 PO #3, PROVABLE by finite types in 0.0s
302 PO #4, PROVABLE by finite types in 0.0s
303\, PO #5, PROVABLE by finite types in 0.0s
304\, PO #6, PROVABLE by finite types in 0.0s
305 PO #7, PROVABLE by finite types in 0.0s
306\, PO #8, PROVABLE by finite types in 0.0s
307 PO #9, PROVABLE by finite types in 0.001s
308 PO #10, PROVABLE by finite types in 0.001s
309 PO #11, PROVABLE by direct (body is total) in 0.003s
310 PO #12, PROVABLE by witness s = mk_Switch(<MIDDLE>, true) in 0.001s
311 PO #13, PROVABLE by direct (body is total) in 0.001s
312 PO #14, PROVABLE by witness k = mk_Knob(1, [-2]) in 0.0s
313 PO #15, PROVABLE by direct (body is total) in 0.0s
314 PO #16, PROVABLE by witness t = 0 in 0.0s
315\, PO #17, PROVABLE by direct (body is total) in 0.001s
316 PO #18, PROVABLE by witness t = mk_Throttle(0, 0) in 0.001s
317\, PO #19, PROVABLE by direct (body is total) in 0.002s
318 PO #20, PROVABLE by witness i = mk_ItemObject(<KNOB>, mk_Knob(1, [-1])\rightarrow
                     ) in 0.002s
319 PO #21, FAILED in 0.002s: Counterexample: type = \langle BUTTON \rangle, object = \rightarrow
                     mk \ Knob(1, [-1])
         Causes Error 4004: No cases apply for <BUTTON> in 'Checklist' (formal/→
                     checklist.vdmsl) at line 119:13
321
322 ItemObject': utotal ufunction uobligation uin u'Checklist' u(formal / \rightarrow
                     checklist.vdmsl)_at_line_118:13
323 (forall_mk_ItemObject'(type, object):ItemObject'!_&
324 uuis_(inv_ItemObject'(mk_ItemObject'!(type,uobject)),ubool))
325
326 \quad \texttt{PO} \sqcup \texttt{\#22}, \sqcup \texttt{FAILED} \sqcup \texttt{by} \sqcup \texttt{direct} \sqcup \texttt{in} \sqcup \texttt{0.005s} : \sqcup \texttt{Counterexample} : \sqcup \texttt{type} \sqcup = \sqcup <\texttt{BUTTON} > \mathsf{Counterexample} : \sqcup \texttt{type} \sqcup = \sqcup <\mathsf{BUTTON} > \mathsf{Counterexample} : \sqcup \texttt{type} \sqcup = \sqcup <\mathsf{Counterexample} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} \sqcup = \sqcup <\mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup = \sqcup \mathsf{type} : \sqcup \mathsf{type} \sqcup \mathsf{type} : \sqcup \mathsf{type}
327 PO_#23,_PROVABLE_by_witness_type_=<KNOB>,_object_=\mk_Knob(1,_[-1])_\rightarrow \frac{1}{2}
                     in_{\sqcup}0.002s
328 PO_{\square}#24,_{\square}PROVABLE_{\square}by_{\square}direct_{\square}(body_{\square}is_{\square}total)_{\square}in_{\square}0.001s
329 \quad \text{PO}\_\#25, \_\text{PROVABLE}\_\texttt{by}\_\texttt{witness}\_\texttt{i}\_=\_\texttt{mk}\_\texttt{ItemAndChecklistItem}(\texttt{mk}\_\texttt{ItemObject} \rightarrow \texttt{mk}\_\texttt{Not})
                      (\langle KNOB \rangle, _{\sqcup}mk_Knob(1, _{\sqcup}[-1])), _{\sqcup}mk_ChecklistItem([], _{\sqcup}\langle KNOB \rangle, _{\sqcup}\langle MIDDLE \rangle, \rightarrow (AB, _{\sqcup})
                     _{\perp}true))_{\perp}in_{\perp}0.001s
330 \text{ PO}_{\square}#26, _{\square}MAYBE_{\square}in_{\square}0.003s
331 \text{ PO}_{\square}#27, _{\square}MAYBE_{\square}in_{\square}0.003s
332 \text{ PO}_{\square}#28, _{\square}MAYBE_{\square}in_{\square}0.002s
333 PO_#29, PROVABLE by witness p = [mk_ChecklistItem([], SUTTON>, <
                     MIDDLE>, utrue)] uin u 0.001s
334 PO<sub>\u00c4</sub>#30,\u00c4MAYBE\u10c1in\u00.002s
335 PO_{\square}#31,_{\square}MAYBE_{\square}in_{\square}0.001s
336 \quad PO_{\square}#32,_{\square}MAYBE_{\square}in_{\square}0.003s
337 PO_{\square}#33, _{\square}MAYBE_{\square}in_{\square}0.002s
338 PO_\#34,\\MAYBE\\in\\0.001s
```

```
PO_{\sqcup}#35,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.002s
        PO<sub>11</sub>#36, MAYBE, in, 0.009s
341
        PO_{\sqcup}#37, _{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.008s
342 PO_{\sqcup}#38,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.007s
343 PO_{\square}#39,_{\square}MAYBE_{\square}in_{\square}0.009s
344 \text{ PO}_{\square}#40, \squareMAYBE\squarein\square0.002s
345 \text{ PO}_{\square}#41, \squareMAYBE_{\square}in_{\square}0.001s
        P0 \sqcup #42, \sqcup MAYBE \sqcup in \sqcup 0.001s
346
347
        PO<sub>U</sub>#43, MAYBE in 0.002s
        PO_{\sqcup}#44,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.002s
348
349
        PO_{\sqcup}#45,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.003s
350
        P0 \sqcup #46, \sqcup MAYBE \sqcup in \sqcup 0.002s
351
        PO_{\sqcup}#47,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.002s
352 PO<sub>U</sub>#48, MAYBE in 0.001s
353 PO_{\square}#49,_{\square}MAYBE_{\square}in_{\square}0.001s
354~{\rm PO}_{\sqcup}#50,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.0s
355 \text{ PO}_{\square} #51, \text{MAYBE}_{\square} in_{\square} 0.0s
356 PO_#52, MAYBE_in_0.005s
357 POu#53,uPROVABLEubyutrivialupuinusetu(domuchecklist)uinu0.001s
358 PO_{\square}#54,_{\square}MAYBE_{\square}in_{\square}0.006s
359 \quad PO_{\square} #55, MAYBE_{\square} in_{\square} 0.0s
360 PO_{\sqcup}#56,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
361
        PO_{\sqcup}#57,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
362
        PO<sub>□</sub>#58, <sub>□</sub>MAYBE<sub>□</sub>in<sub>□</sub>0.001s
363
        PO_{\sqcup}#59, _{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
364
        PO_{\sqcup}#60,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
365~{\tt PO}_{\sqcup}#61,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
366 \quad PO_{\sqcup}#62,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.0s
367
        PO∪#63,∪PROVABLE∪by∪finiteutypesuinu0.001s
368 PO<sub>\u00e4</sub>#64,\u00e4PROVABLE\u00e4by\u00e4finite\u00e4types\u00e4in\u00e40.001s
369 PO_{\sqcup}#65,_{\sqcup}PROVABLE_{\sqcup}by_{\sqcup}finite_{\sqcup}types_{\sqcup}in_{\sqcup}0.001s
370~{\rm PO}_{\sqcup}#66,_{\sqcup}MAYBE_{\sqcup}in_{\sqcup}0.001s
371 >
372 */
```

## References

- [1] Immanuel Barshi, Robert Mauro, Asaf Degani et al. *Designing Flightdeck Procedures*. eng. Ames Research Center, Nov. 2016. URL: https://ntrs.nasa.gov/citations/20160013263.
- [2] Atul Gawande. The Checklist Manifesto: How To Get Things Right. Main Edition. Profile Books, July 2010. ISBN: 9781846683145.
- [3] National Transportation Safety Board. Loss of Thrust in Both Engines After Encountering a Flock of Birds and Subsequent Ditching on the Hudson River. Technical Report PB2010-910403. May 2010. URL: https://www.ntsb.gov/investigations/Pages/DCA09MA026.aspx.
- [4] William R. Knecht and Michael Lenz. Causes of General Aviation Weather-Related, Non-Fatal Incidents: Analysis Using NASA Aviation Safety Reporting System Data. Tech. rep. DOT/FAA/AM-10/13. FAA Office of Aerospace Medicine Civil Aerospace Medical Institute, Sept. 2010.
- [5] Nick Battle. VDMJ. URL: https://github.com/nickbattle/vdmj (visited on 21/04/2024).
- [6] Peter Gorm Larsen, Kenneth Lausdahl, Peter Jørgensen et al. Overture VDM-10 Tool Support: User Guide. TR-2010-02. Apr. 2013. Chap. 16, pp. 81-98. URL: https://raw.github.com/overturetool/documentation/editing/documentation/UserGuideOvertureIDE/OvertureIDEUserGuide.pdf.
- [7] Kyushu University. The VDM Toolbox API. Version 1.0. 2016. URL: https://github.com/vdmtools/vdmtools/raw/stable/doc/api-man/ApiMan\_a4E.pdf.
- [8] Raoul-Gabriel Urma. 'Alternative Languages for the JVM'. In: Java Magazine (July 2014). URL: https://www.oracle.com/technical-resources/articles/java/architect-languages.html (visited on 05/05/2024).
- [9] JetBrains s.r.o. Kotlin Programming Language. URL: https://kotlinlang.org/ (visited on 21/04/2024).
- [10] Google LLC. Kotlin and Android | Android Developers. URL: https://developer.android.com/kotlin (visited on 21/04/2024).
- [11] OpenJFX. JavaFX. URL: https://openjfx.io/ (visited on 21/04/2024).
- [12] FormDev Software GmbH. FlatLaf Flat Look and Feel / FormDev. URL: https://www.formdev.com/flatlaf/ (visited on 21/04/2024).
- [13] JetBrains s.r.o. Compose Multiplatform UI Framework | JetBrains | JetBrains: Developer Tools for Professionals and Teams. URL: https://www.jetbrains.com/lp/compose-multiplatform/ (visited on 21/04/2024).
- [14] Google LLC. Flutter Build apps for any screen. URL: https://flutter.dev/ (visited on 21/04/2024).
- [15] Laminar Research. X-Plane | The world's most advanced flight simulator. URL: https://www.x-plane.com/ (visited on 21/04/2024).
- [16] Lockheed Martin Corporation. Prepar3D Next Level Training. World class simulation. Be ahead of ready with Prepar3D. URL: https://www.prepar3d.com/ (visited on 21/04/2024).
- [17] NASA Ames Research Center Diagnostics and Prognostics Group. X-Plane Connect. URL: https://github.com/nasa/XPlaneConnect (visited on 21/04/2024).
- [18] Google LLC. Lists Material Design 3. URL: https://m3.material.io/components/lists/guidelines (visited on 13/05/2024).

REFERENCES REFERENCES

[19] Google LLC. Top app bar - Material Design 3. URL: https://m3.material.io/components/top-app-bar/guidelines (visited on 13/05/2024).

- [20] Barbara Burian. 'Design Guidance for Emergency and Abnormal Checklists in Aviation'. In: Proceedings of the Human Factors and Ergonomics Society Annual Meeting 50 (Oct. 2006). DOI: 10.1177/154193120605000123.
- [21] Quinn Kennedy, Joy Taylor, Daniel Heraldez et al. 'Intraindividual Variability in Basic Reaction Time Predicts Middle-Aged and Older Pilots' Flight Simulator Performance'. In: *The Journals of Gerontology: Series B* 68.4 (Oct. 2012), pp. 487–494. ISSN: 1079-5014. DOI: 10.1093/geronb/gbs090. eprint: https://academic.oup.com/psychsocgerontology/article-pdf/68/4/487/1520662/gbs090.pdf.
- [22] Civil Aviation Authority. Aircraft Emergencies: Considerations for air traffic controllers. CAP745. Mar. 2005. URL: https://www.caa.co.uk/cap745.
- [23] The Overture Project. The Vienna Development Method. URL: https://www.overturetool.org/method/ (visited on 23/02/2024).
- [24] Google LLC. Jetpack Compose UI App Development Toolkit Android Developers. URL: https://developer.android.com/develop/ui/compose (visited on 21/04/2024).