

Span : Does $\{v_1, v_2, \dots, v_t\}$

#elements = t

$$\begin{matrix} (\mathbb{R}^3), \mathbb{R}^2, \mathbb{R}^{n \times n}, \mathbb{P} \\ \left[\begin{matrix} a \\ b \\ c \end{matrix} \right], \left[\begin{matrix} a \\ b \\ \vdots \\ d \end{matrix} \right] \end{matrix} \xrightarrow{\text{span}} V ? \quad \xrightarrow{\sim} \text{Span} \{v_1, v_2, \dots, v_t\} = V$$

→ Can we generate all vectors in V
as a linear comb. of these vectors?

$$r_1 v_1 + r_2 v_2 + \dots + r_t v_t = \text{a typical vector in } V$$

system of linear equations

if this system
has a solution for r_1, r_2, \dots, r_t
(without any restrictions) $\Rightarrow \checkmark$

→ if the system may not have a solution $\Rightarrow \times$

$t < \dim(V) \Rightarrow$ The set can not span V.

$t = \dim(V) \Rightarrow$ a square system $\det \neq 0 \Rightarrow \checkmark \quad \det = 0 \Rightarrow \times$

$t > \dim(V) \Rightarrow$ may or may not span V → solve the system.

Linear

Independence

#elements = t

$$c_1 v_1 + c_2 v_2 + \dots + c_t v_t = \vec{0}_V$$

a system of linear equations

$\vec{0}_V$ in the set $\Rightarrow \times$
if the vectors can be written as a linear comb. $\Rightarrow \times$

$c_1 = c_2 = \dots = c_t = 0 \rightarrow$ trivial soln. $\Rightarrow \checkmark$
is the only soln.

inf. many soln. case $\Rightarrow \times$

$t < \dim(V) \Rightarrow$ may or may not be lin. indep. → solve the system.

$t = \dim(V) \Rightarrow$ square system $\det \neq 0 \Rightarrow \checkmark \quad \det = 0 \Rightarrow \times$

$t > \dim(V) \Rightarrow$ the set can not be lin. independent \times

BASIS

$\{v_1, v_2, \dots, v_t\}$

span + lin. indep.

$\underline{t = \dim(V)}, \det \neq 0$

Dimension

$$2v_1 + 3v_2 + \dots + 5v_4 = \text{Halil}$$

$$-1v_1 + 4v_2 + \dots + 0v_6 = \text{Cihan F.}$$

standard bases

$$\begin{bmatrix} a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix} + \dots + c \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$\dim(\mathbb{R}^3) = 3 \quad \mathbb{R}^3 \quad \text{standard bases} \quad \left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}}_{e_3} \right\} = E \quad \left[\begin{array}{c} a \\ b \\ c \end{array} \right] = a \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

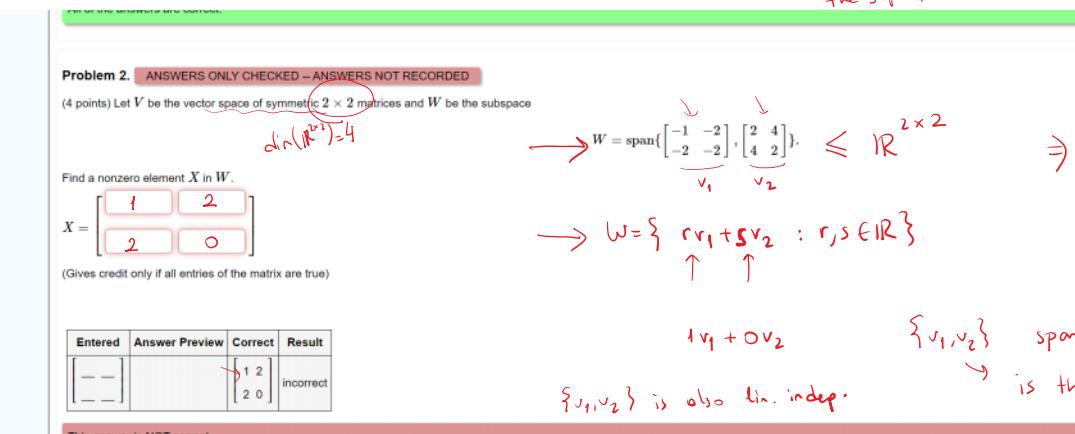
$$\dim(\mathbb{R}^2) = 2 \quad \mathbb{R}^2 \quad \left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{e_2} \right\} = E$$

$$\dim(\mathbb{R}^{2 \times 2}) = 4 \quad \mathbb{R}^{2 \times 2} \quad \left\{ \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}}_{e_1}, \underbrace{\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}}_{e_2}, \underbrace{\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}}_{e_3}, \underbrace{\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}}_{e_4} \right\} = E$$

$$\dim(P_3) = 3 \quad P_3 \quad \{1, x, x^2\} \quad ax^2 + bx + c$$

Finding a Basis for Subspaces

any subspace dimension \leq dimension of the superspace



Problem 2. ANSWERS ONLY CHECKED - ANSWERS NOT RECORDED

(4 points) Let V be the vector space of symmetric 2×2 matrices and W be the subspace $\dim(W) = 4$

Find a nonzero element X in W .

$X = \begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$

(Gives credit only if all entries of the matrix are true)

Entered	Answer Preview	Correct	Result
$\begin{bmatrix} \quad & \quad \\ \quad & \quad \end{bmatrix}$	$\begin{bmatrix} 1 & 2 \\ 2 & 0 \end{bmatrix}$	incorrect	

This answer is NOT correct.

$W = \{rv_1 + sv_2 : r, s \in \mathbb{R}\}$

$v_1 = \begin{bmatrix} -1 & -2 \\ -2 & -2 \end{bmatrix}$, $v_2 = \begin{bmatrix} 2 & 4 \\ 4 & 2 \end{bmatrix}$

$W = \{rv_1 + sv_2 : r, s \in \mathbb{R}\}$

$1v_1 + 0v_2$ $\{v_1, v_2\}$ spans W

$\{v_1, v_2\}$ is also lin. indep. \rightarrow is this a basis W ? \checkmark

! if you're given 2 vectors (whatever vector space you're in), the only possible linear combination \rightarrow scalar multiple.



$$S = \left\{ r \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + s \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} + t \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix} : r, s, t \in \mathbb{R} \right\}, \text{ Find a basis for } S. \dim(S)=?$$

(S is a subspace of \mathbb{R}^3)

$$= \text{span} \left\{ \underbrace{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}_{v_1}, \underbrace{\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}}_{v_2}, \underbrace{\begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}}_{v_3} \right\}$$

$\{v_1, v_2, v_3\}$ already spans S .

$v_3 = v_1 + v_2 \rightarrow$ we don't need v_3 . $\{v_1, v_2, v_3\}$ is not linearly indep.

$\{v_1, v_2\}$ is a linearly independent.
still spans S .

$$\text{A basis for } S = \{v_1, v_2\}$$

A basis for $S = \{v_1, v_2\}$

$$\dim(S) = 2$$

$$\mathbb{R}^2 \not\subseteq \mathbb{R}^3$$

\checkmark

$$v_1 = 1+x \quad v_2 = x^2 \quad v_3 = 2x^2 - 3$$

$$\in \mathbb{P}_4$$

$$\mathbb{P}_2 \leq \mathbb{P}_3 \leq \mathbb{P}_4$$

$$S = \text{Span}\{v_1, v_2, v_3\} \quad \text{Find a basis for } S. \quad \dim(S) = ?$$

$\{v_1, v_2, v_3\}$ spans S . Is $\{v_1, v_2, v_3\}$ lin. independent?

(*)

$$c_1 v_1 + c_2 v_2 + c_3 v_3 = 0 + 0x + 0x^2 + 0x^3 \rightarrow 0_{\mathbb{P}_4}$$

$$c_1(1+x) + c_2(x^2) + c_3(2x^2 - 3) = 0 + 0x + 0x^2 + 0x^3 \rightarrow 0_{\mathbb{P}_4}$$

$$\Rightarrow c_1 - 3c_3 = 0 \Rightarrow c_3 = 0$$

$$c_1 = 0 \leftarrow$$

$$c_2 + 2c_3 = 0 \rightarrow \Rightarrow c_2 = 0$$

$$0 = 0$$

$c_1 = c_2 = c_3 = 0$ is the only solution of the system.

$\Rightarrow \{v_1, v_2, v_3\}$ is a linearly independent set.

(**) \Rightarrow

(*) + (**) $\Rightarrow \{v_1, v_2, v_3\}$ is a basis for S .

$$\dim(S) = 3$$

Change of Bases

\mathbb{R}^3
any vector
in this
space

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} = E$$

we fix the order

$$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} \right\} \rightarrow \begin{array}{l} \text{is a basis} \\ \text{for } \mathbb{R}^3 \end{array}$$

span ✓ even. indep. ✓

$$\begin{vmatrix} 1 & -1 & 0 \\ 2 & 0 & 0 \\ 3 & 1 & 4 \end{vmatrix} = -2 \begin{vmatrix} -1 & 0 \\ 1 & 4 \end{vmatrix} + 0 + 0 = 8 \neq 0$$

$$\checkmark \quad Ay_{\text{seg1}} = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix} \in \mathbb{R}^3$$

$$v = \begin{bmatrix} v \\ E \end{bmatrix} \quad v = [v]_E$$

$$Ay_{\text{seg1}} = 5e_1 + 8e_2 + 3e_3$$

$$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \end{bmatrix} \right\}$$

Assume that you want to find r_1, r_2, r_3

$[v]_F \rightarrow$
coordinates of v with respect to the basis

$$F = \{v_1, v_2, v_3\}$$

$$r_1 \cdot 1 + r_2 \cdot (-1) + r_3 \cdot 0 = 5$$

$$F = \left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 4 \\ 1 \end{bmatrix} \right\}$$

Assume that you want to find r_1, r_2, r_3

$$r_1 v_1 + r_2 v_2 + r_3 v_3 = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix} \Rightarrow r_1 \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} + r_2 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 2 \end{bmatrix} + r_3 \begin{bmatrix} 0 \\ 0 \\ 4 \\ 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix}$$

$A \times b$

$$\begin{aligned} r_1 - r_2 + 0r_3 &= 5 \\ 2r_1 + 0r_2 + 0r_3 &= 8 \\ 3r_1 + 1r_2 + 4r_3 &= 3 \end{aligned} \quad \Rightarrow \quad \left[\begin{array}{ccc|c} 1 & -1 & 0 & 5 \\ 2 & 0 & 0 & 8 \\ 3 & 1 & 4 & 3 \end{array} \right] \xrightarrow{\text{Row operations}} \underbrace{\left[\begin{array}{ccc|c} 1 & -1 & 0 & 5 \\ 2 & 0 & 0 & 8 \\ 3 & 1 & 4 & 3 \end{array} \right]}_{F} \left[\begin{array}{c} r_1 \\ r_2 \\ r_3 \end{array} \right] = \begin{bmatrix} 5 \\ 8 \\ 3 \end{bmatrix}$$

$$\beta = \{v_1, v_2, v_3\}$$

$$\begin{aligned} F[v]_F &= \checkmark \\ I &\quad ? \\ F^{-1} F[v]_F &= (F^{-1}) \checkmark \end{aligned}$$

B, C two ordered basis for V

(we don't know $v \in V$)

Knowing B, C , and $[v]_B \Rightarrow$ how can we find $[v]_C = ?$

$$\cancel{v} = \cancel{B[v]_B} = \cancel{C[v]_C} = \underline{\underline{\dots}}$$

$$\Rightarrow \cancel{C^{-1} B} [v]_B = \cancel{C^{-1} C} [v]_C = [v]_C \checkmark$$

This matrix is called as the transition matrix from B to C .

$$\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

We're in \mathbb{R}^2 ,

$$B = \left\{ \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 4 \end{bmatrix} \right\}$$

$$C = \left\{ \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

$$\det B = 12 - 10 = 2 \neq 0 \checkmark$$

$$\det C = -2 - 0 = -2 \neq 0 \checkmark$$

$$\text{Halil} = v = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$$

B and C are two ordered basis in \mathbb{R}^2 .

$$v = B[v]_B = C[v]_C = \dots$$

$$[v]_B = B^{-1} v = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix} \begin{bmatrix} 4 \\ 6 \end{bmatrix} = \begin{bmatrix} -7 \\ 5 \end{bmatrix} \rightarrow \begin{array}{l} \text{coordinates of Halil} \\ \text{wrt the basis } B. \end{array}$$

Short way
to find
 A^{-1}

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$B = \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix}$$

$$B^{-1} = \begin{bmatrix} 4/2 & -5/2 \\ -2/2 & 3/2 \end{bmatrix} = \begin{bmatrix} 2 & -5/2 \\ -1 & 3/2 \end{bmatrix}$$

$$1 + 2 = 3$$

Short way to find 2x2 inverses

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\det(B) = 2$$

$$-7 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 5 \begin{bmatrix} 5 \\ 4 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix} \rightarrow \text{Hatalı} \checkmark$$

-21 + 15
-14 + 20

E)

$$B = \left\{ \underbrace{\begin{bmatrix} 3 \\ 2 \end{bmatrix}}, \underbrace{\begin{bmatrix} 5 \\ 4 \end{bmatrix}} \right\}$$

$$\det = 12 - 10 = 2 \neq 0 \checkmark$$

$$C = \left\{ \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 2 \end{bmatrix} \right\}$$

$$\det C = -2 - 0 = -2 \neq 0 \checkmark$$

$$[v]_B = \begin{bmatrix} -7 \\ 5 \end{bmatrix}$$

a) Find the transition matrix from B to C.

$$B[v]_B = C[v]_C ?$$

$$[v]_C = (C^{-1}B)[v]_B$$

b) $[v]_C = ?$

a)

$$C = \begin{bmatrix} -1 & 5 \\ 0 & 2 \end{bmatrix} \quad C^{-1} = \begin{bmatrix} 2/2 & -5/2 \\ 0/2 & 1/2 \end{bmatrix} = \begin{bmatrix} -1 & 5/2 \\ 0 & 1/2 \end{bmatrix}$$

$$\det C = -2$$

$$C^{-1}B = \begin{bmatrix} -1 & 5/2 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 2 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix}$$

0+1 0+2

the transition matrix from B to C.

b)

$$[v]_C = (C^{-1}B)[v]_B = \begin{bmatrix} 2 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -7 \\ 5 \end{bmatrix} = \begin{bmatrix} 11 \\ 3 \end{bmatrix} = [v]_C$$

(to check:

$$11 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 5 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix} \rightarrow \text{Hatalı} \checkmark$$

-11 + 15
0 + 6

7. Given

$$v_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, v_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, S = \begin{bmatrix} 3 & 5 \\ 1 & -2 \end{bmatrix} \xrightarrow{\text{from } B \text{ to } C} = (C^{-1}B) \checkmark$$

find vectors w_1 and w_2 so that S will be the transition matrix from $\{w_1, w_2\}$ to $\{v_1, v_2\}$.

$$\begin{matrix} B \\ ? \end{matrix} \quad \begin{matrix} C \\ \checkmark \end{matrix}$$

$$C = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix} \right\}$$

$$C = \begin{bmatrix} 1 & 2 \\ 2 & 3 \end{bmatrix}$$

$$C(C^{-1}B) = B$$

I S

$$\begin{bmatrix} 1 & 2 \end{bmatrix} \begin{bmatrix} 3 & 5 \\ 1 & -2 \end{bmatrix} = \begin{bmatrix} 5 & 1 \end{bmatrix} \rightarrow R = \left\{ \begin{bmatrix} 5 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 \\ 9 \end{pmatrix} \rightarrow B = \left\{ \begin{pmatrix} 5 \\ 9 \end{pmatrix}, \begin{pmatrix} 1 \\ 4 \end{pmatrix} \right\}$$

\downarrow
 w_1 w_2

8. Given

$$\underline{\mathbf{v}_1 = \begin{pmatrix} 2 \\ 6 \end{pmatrix}}, \quad \underline{\mathbf{v}_2 = \begin{pmatrix} 1 \\ 4 \end{pmatrix}}, \quad \underline{S = \begin{pmatrix} 4 & 1 \\ 2 & 1 \end{pmatrix}}$$

$$B = \begin{pmatrix} 2 & 1 \\ 6 & 4 \end{pmatrix} \quad \det B = 8 - 6 = 2$$

find vectors \mathbf{u}_1 and \mathbf{u}_2 so that S will be the transition matrix from $\{\mathbf{v}_1, \mathbf{v}_2\}$ to $\{\mathbf{u}_1, \mathbf{u}_2\}$.

(B) \checkmark (C) \checkmark ?

$$B^{-1} = \begin{pmatrix} u_{12} & -1_{12} \\ -6_{12} & 2_{12} \end{pmatrix}$$

$$C^{-1}B \quad \checkmark$$

$$B \quad \checkmark$$

$$C = ?$$

$$B^{-1} = \begin{pmatrix} 2 & -1/2 \\ -3 & 1 \end{pmatrix}$$

$$\text{Find } B^{-1}.$$

$$\underbrace{(C^{-1}B)}_{I} B^{-1} = C^{-1} \Rightarrow (C^{-1})^{-1} = C$$

$$C^{-1} = \underbrace{C^{-1}B}_{S} B^{-1} = \begin{pmatrix} 4 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ -3 \end{pmatrix} \begin{pmatrix} -1/2 \\ 1 \end{pmatrix} = \begin{pmatrix} 5 & -1 \\ 1 & 0 \end{pmatrix} \quad \det C^{-1} = 0 - (-1) = 1$$

$$C = \begin{pmatrix} 0 & 1 \\ -1 & 5 \end{pmatrix} \quad \checkmark \quad \Rightarrow \quad C = \left\{ \underbrace{\begin{pmatrix} 0 \\ -1 \end{pmatrix}}_{u_1}, \underbrace{\begin{pmatrix} 1 \\ 5 \end{pmatrix}}_{u_2} \right\}$$