Feedback analysis and compensator design example: RWE
Investigation of an opensator lead compensator 9/10/12

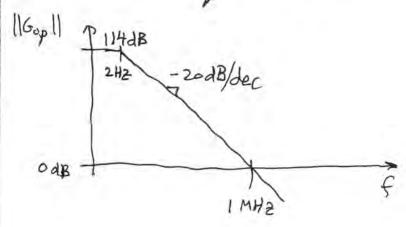
CITCUIT

Lecture hate
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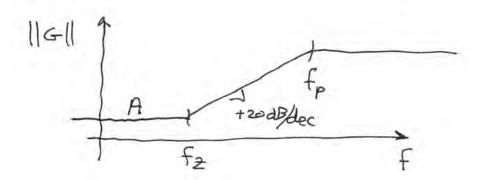
The op amp in the parts kit (ALD 2702) is a cmos rail-to-rail input op amp with 1 MHz gain-bandwidth product.

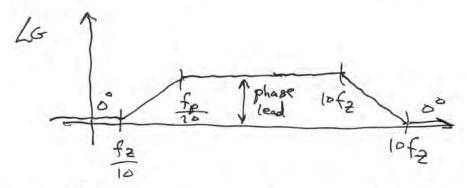
$$G_{op}(s) = G_o \frac{1}{1 + \frac{5}{\omega_{op}}}$$
 $f_{op} = \frac{\omega_{op}}{2\pi} = 2 + 12$
 $G_o = 5 \cdot 10^5 \Rightarrow 114 dB$

The gain at 1 MHZ is $(5.10^{5}) \frac{1}{11/4 \frac{j^{2\pi/2^{6}}}{2\pi.2}} = \frac{5.10^{5}}{5.10^{5}} = 1$



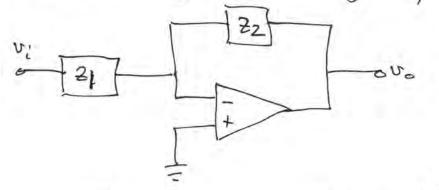
Let's consider a lead compensator (PD) having a transfer function $G(s) = A \frac{1 + \frac{5}{\omega_2}}{1 + \frac{5}{\omega_D}}$





Such circuits are sometimes added to feedback loop compensators, to improve phase margin.

A realization using an inverting amplifier:



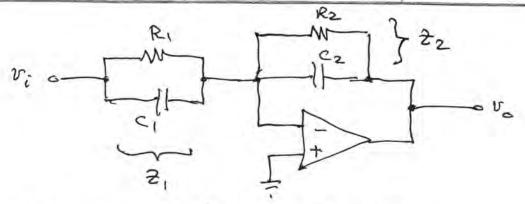
$$G(S) = -\frac{2z}{2} = \frac{U_0}{V_i}$$

$$(Hus also adds a minus sign)$$

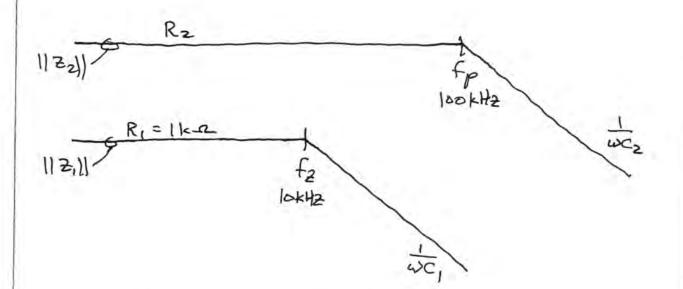
(this also adds a minus sign)

Sp = 100 KHZ

TAMBALOT



Let's choose (arbitrarily) R, = 1 K-12 Then Z, and Zz should be!



- @ we want dc gain A = 10At dc, $2_1 = R_1$ and $2_2 = R_2$ so $A = \frac{R_2}{R_1}$ \Rightarrow need $R_2 = 10$ kD
- (b) we want $f_z = 10 \text{ kHz}$ at f_z , $R_1 = \frac{1}{2\pi f_z C_1}$ so $C_1 = \frac{1}{2\pi f_z R_1}$ $= \frac{1}{2\pi (10 \text{ kHz})(1 \text{ k.s.})}$ $= 0.016 \mu\text{F}$

© we want
$$f_p = 100 \text{ kHz}$$
at f_p , $R_z = \frac{1}{2\pi f_p C_z}$

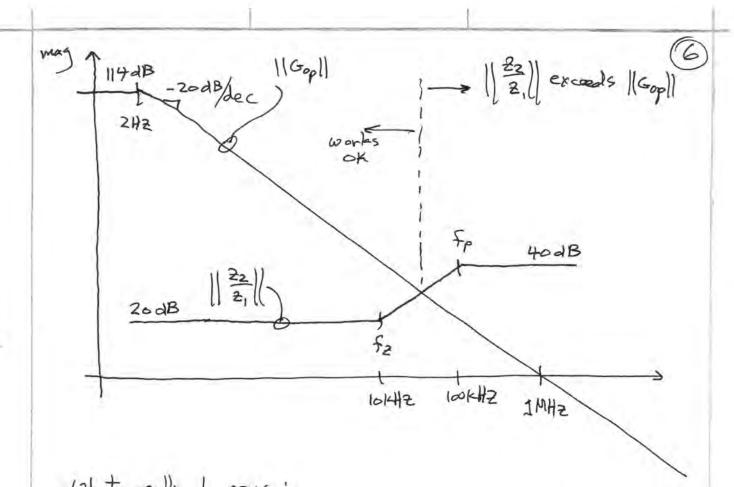
$$= \frac{1}{2\pi (100 \text{ kHz})(10 \text{ k.s.})}$$

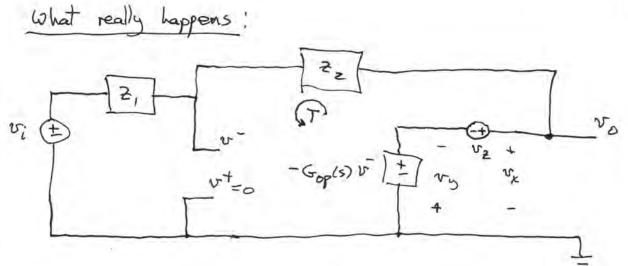
$$= 160 pF$$

$$v_i = \frac{1}{100 \text{ k.s.}}$$

$$V_0 = \frac{1}{100 \text{ k.s.}}$$

A problem with this design! we are trying to obtain more gain than the op amp is capable of producing. The formula $G(S) = -\frac{22}{2}$ is true for ideal op amps with $G_{qp} \rightarrow \infty$ (i.e., for Kall sufficiently large). But at high frequency, Gop rolls off.





To find loop gain (or measure loop gain):

inject a voltage V_2 at output of op amp

given V_X , find V_3 . Loop gain is $T(5) = \frac{v_3}{v_x}$ with $v_i = 0$.

Analysis: with $v_i = 0$, $v_i = \frac{z_1}{z_1 + z_2}$ v_i and $v_i = \frac{z_1}{z_1 + z_2}$ v_i $v_i = \frac{z_1}{z_1 + z_2}$ v_i

$$G(S) = \frac{v_o}{v_i} = \left(-\frac{22}{21}\right) \left(\frac{T}{1+T}\right)$$
ideal effect of
gain finite Gap

Construct loop gain:
$$\frac{2}{2,+2z} = \frac{1}{1+\frac{2z}{2,}}$$

Since $||z_2|| >> ||z_1||$ everwhere, this is approximately

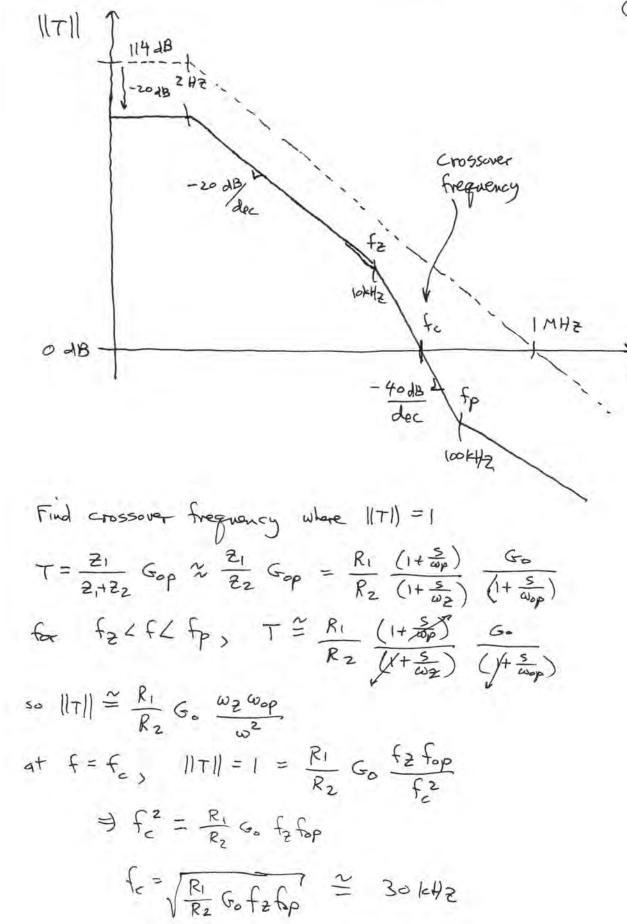
$$\frac{1}{1 + \frac{22}{2}} = \frac{2}{22}$$
 which is (ideal gain)

$$\left\| \frac{2_{1}}{2_{2}} \right\|$$

$$\frac{-20dB}{R_{2}} \frac{R_{1}}{R_{2}}$$

$$f_{p} \frac{C_{2}}{C_{1}}$$

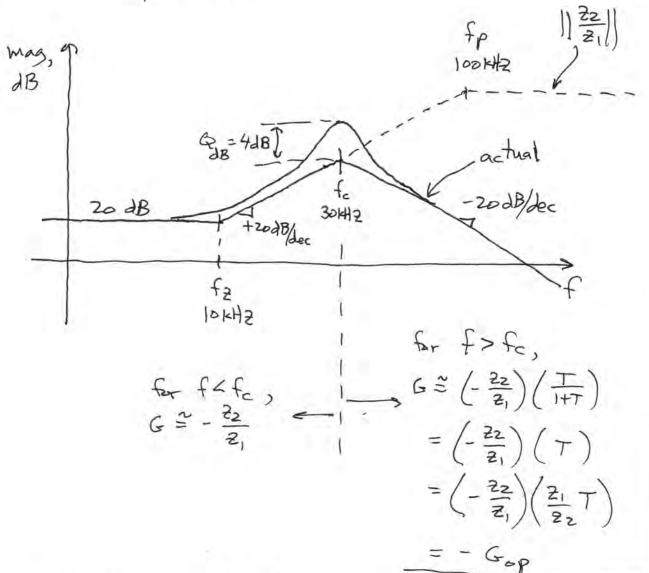
So
$$T = \frac{z_1}{z_2}$$
 Gop is decreased relative to Gop



What is the phase margin? LT at f=fc is -90° from the pole at for = 2HZ from the pole at fz and zero at fp: See textbook Fig. 9.16 or Eq. (9.34). The result is $-\tan^2\left(\frac{\sqrt{10}-\sqrt{0.1}}{2}\right)=-55^\circ$ So LT = -90°-55° = - 145° at fc phase margin = 180° + 1 = 350 From textbook Fig. 9.13, this leads to closed-loop Q of 1,57 => 4 dB construction of I+T 1 1+1 $\frac{T}{1+T} \cong \begin{cases} 1, & ||T|| \gg 1 \\ T, & ||T|| \geq 1 \end{cases}$ 0 dB 30KHZ

100 KH2

Actual transfer function



So the actual transfer function follows the ideal value $\left(-\frac{22}{21}\right)$ as long as $\|Gop\| >> \|\frac{22}{81}\|$. But when $\|Gop\| \leq \|\frac{22}{81}\|$ then the actual transfer function follows $\left(-Gop\right)$ instead.