EXPERIMENT 3-2 LAB REPORT

ECEN 5517 (Spring 2017)
Power electronics and Photovoltaic Power Systems Laboratory

3/10/2017

TEAM MUSE

Maneesh Kumar Singh Vivek Sankaranarayanan

Objectives

The objectives of this experiment are:

- To design and interface a sensor circuitry to measure battery voltage and current
- To design and test an MPPT algorithm that extracts maximum power from solar panel

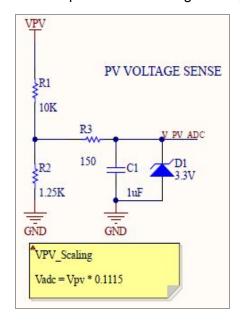
Experimental data

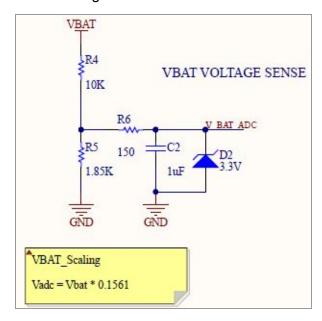
Equipments used

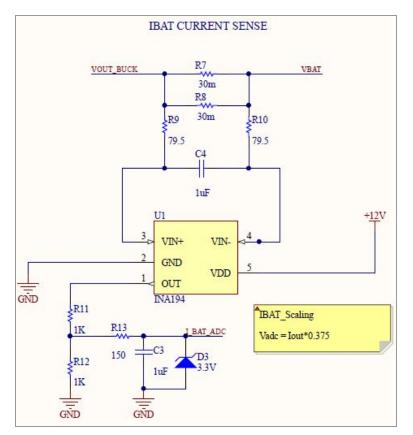
Power	Measurement
Power Supply: 30V-5A Dual Power Supply Rheostat: 0 -15.5 Ohms SQ85-P Solar panel	Meters: FLUKE 45 Oscilloscope

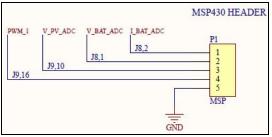
Sensor circuitry and schematics

3 sensors were designed: **Battery voltage**, **Battery current** and **Panel voltage**The complete Buck sensing circuitry with expressions for adc voltages is shown below:









ADC Input voltage Expressions

PV VOLTAGE

R1 = 10 KOhms, R2 = 1.25 KOhms Vadc = Vpv * 1.25/11= Vpv * 0.1111

VBAT VOLTAGE

R1 = 10 KOhms, R2 = 1.85 KOhms Vadc = Vpv * 1.85/11.85 = Vbat * 0.1561

IBAT CURRENT

Sense Resistor = 10 mOhms, R_filt = 79.5 Ohms; C_filt = 1uF, Rdiv = 1K, INA194_gain = 49 Vadc = Ibat*0.245

- The actual gain observed was much less than this, because two 20mOhm shunt resistors were connected in parallel. Since the connection was not made exactly at Kelvin point of the resistors, the actual resistance was somewhat lower than 10 mOhm
- The actual gain observed was Vadc = Ibat*0.125

ADC Measurements

An internal reference of 12V was used for adc conversions

Panel voltage sensing

Meter mea	surements	MSP430 ADC i	neasurements	
V_panel (V)	V_adc (V)	ADC Counts V_adc (V)		Error (%)
8.9	0.9537	391	0.954	0.01
10.22	1.0952	445	1.086	0.368
16.92	1.812	751	1.833	0.84
17.17	1.8394	755	1.843	0.144
17.78	1.893	770	1.879	0.56

Battery Voltage (Tested by connecting load resistor at the output of the buck)

Meter mea	surements	MSP430 ADC I	ISP430 ADC measurements	
V_battery (V)	V_adc (V)	ADC Counts V_adc (V)		Error (%)
5.406	0.8246	339	0.8284	0.152
7.44	1.1349	463	1.1314	0.14
9.552	1.457	581	1.4198	1.488
12.722	1.9406	711	1.7375	2.153
13.038	1.988	719	1.757	2.327

Battery Current (Tested by connecting load resistor at the output of the buck)

Meter mea	surements	MSP430 ADC measurements		
I_battery (A)	V_adc (V)	ADC Counts V_adc (V)		Error (%)
1.347	0.1683	55	0.1344	1.356
2.292	0.2865	97	0.2370	1.98
3.152	0.394	119	0.2908	4.128
5.121	0.6401	217	0.5303	4.392
6.337	0.7921	275	0.6720	4.804

- There are a few points where the adc error is quite high, especially in battery voltage and current. This could have been calibrated to obtain more accurate readings, but accuracy is not required for the MPPT algorithm
- It's enough if the ADC results are monotonic i.e, adc readings increase as power increases since MPPT requires only the direction of power
- Also, in the version of MPPT that has been implemented, accurate panel measurement is required, which as seen from the readings meets the requirements

Design and Evaluation of MPPT

ALGORITHM

- The central part of our MPPT algorithm is the input voltage Proportional_Integral (PI) loop
- Since the panel MPP voltage is almost constant (it changes with temperature but not irradiation), it is enough if the panel voltage (input voltage of the buck) be regulated at this voltage. Panel will then be operating at Maximum Power Point for irradiation changes
- Once every 5 minutes an MPPT sweep is performed, that sweeps the input voltage from 14V to 18V. Power at each point is calculated and stored in a buffer. From this buffer, the max operating point is determined and then the panel is regulated to this input voltage.

EVALUATION AND TESTING PROCESS

The MPPT algorithm was designed and tested in following steps:

- 1. Sensing circuitry design and testing
- 2. Input Voltage Proportional-Integral loop design and testing
- 3. MPPT development and testing
- 4. MPPT final performance evaluation with solar panel

Each step is briefly described below

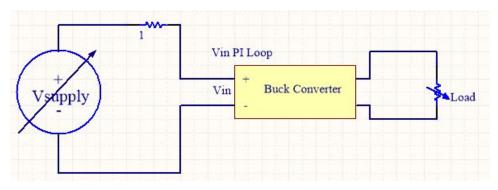
SENSING CIRCUITRY AND DESIGN

Sensing circuitry was designed and tested as per section 1. Results are shown in section of this report.

INPUT VOLTAGE PI LOOP TESTING

In this step, a PI loop was designed that regulates the input voltage to a particular set point. Panel operation was emulated by connecting a 1 Ohm resistor in series with input source. The test setup is shown below:

Setup for PI loop and MPPT initial testing



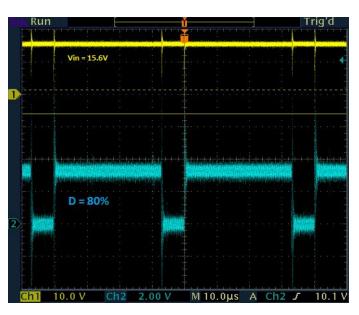
MPPT DEVELOPMENT AND TESTING

In this stage, the MPPT sweep algorithm was implemented and tested in the same setup shown above. An MPPT sweep is performed every 5 minutes that sweeps Vin from 14V to 18V and settles at the highest power point till the next sweep is performed

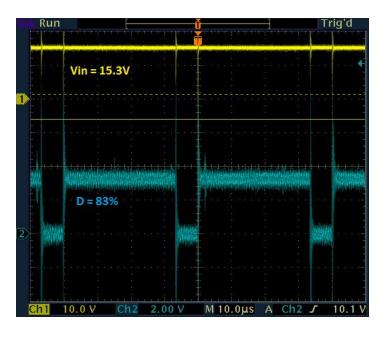
MPPT FINAL EVALUATION AND TESTING

Finally, the Buck converter was tested with solar panel and battery. The results of this step are presented in the following sections

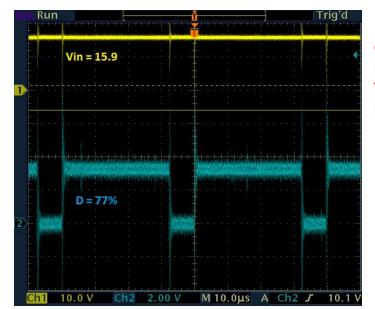
MPPT WAVEFORMS AROUND OPERATING POINT



Operation at MPP D = 0.8 Vpv = 15.6V Pin = 78.01W



Operation below MPP D = 0.83 Vpv = 15.3V Pin = 76.43W



Operation below MPP

D = 0.77

Vpv = 15.9V

Pin = 77.10W

MPPT MEASUREMENTS

The table below gives the result of one MPPT sweep from 14 to 18V in steps of 0.2V

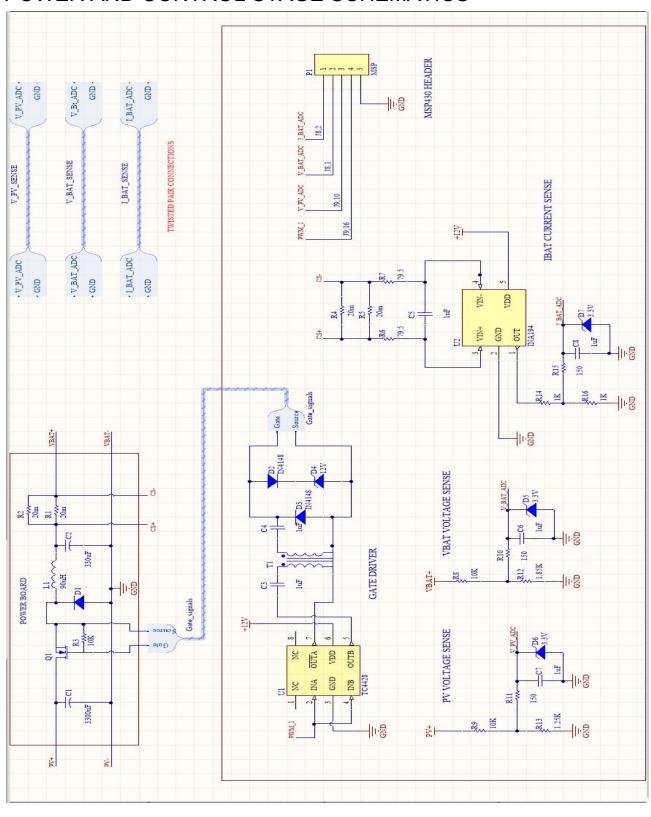
- The entire Vpv sweep was performed once every 5 minutes
- Each step of the sweep was performed every 3 seconds

MPPT sweep readings

Vpv (V)	lpv (A)	Ppv (W)	Vbat (V)	lbat (A)	Pbat (W)	Efficiency
14.0	5.210	72.940	12.891	5.381	69.366	0.951
14.2	5.200	73.840	12.891	5.447	70.222	0.951
14.4	5.150	74.160	12.900	5.490	70.823	0.955
14.6	5.136	74.986	12.901	5.551	71.611	0.955
14.8	5.110	75.628	12.910	5.594	72.225	0.955
15.0	5.080	76.200	12.915	5.641	72.847	0.956
15.2	5.050	76.760	12.921	5.709	73.766	0.961
15.4	5.016	77.246	12.921	5.745	74.234	0.961
15.6	5.000	78.000	13.939	5.378	74.958	0.961
15.8	4.900	77.420	12.930	5.742	74.246	0.959
16.0	4.830	77.280	12.925	5.734	74.112	0.959
16.2	4.690	75.978	12.913	5.637	72.787	0.958
16.4	4.572	74.981	12.910	5.564	71.832	0.958
16.6	4.446	73.804	12.900	5.452	70.335	0.953
16.8	4.331	72.761	12.900	5.353	69.050	0.949
17.0	4.210	71.570	12.891	5.291	68.206	0.953
17.2	4.109	70.675	12.890	5.225	67.353	0.953
17.4	3.994	69.496	12.884	5.130	66.090	0.951
17.6	3.809	67.038	12.873	4.932	63.485	0.947
17.8	3.691	65.700	12.860	4.848	62.349	0.949
18.0	3.548	63.864	12.850	4.697	60.351	0.945

- From the above sweep, max power (P_{mpp}) of **78W** was achieved at V_{pv} = **15.6 V.** The algorithm successfully identified this operating point and settled to this value on completion of a sweep.
- Also efficiency at all operating points was measured and peak efficiency of 96.1% was obtained

POWER AND CONTROL STAGE SCHEMATICS



PEAK EFFICIENCY

Converter efficiency at different operating points have been tabulated in the previous section. The peak efficiency reading is reproduced here for reference.

Vpv (V)	lpv (A)	Ppv (W)	Vbat (V)	lbat (A)	Pbat (W)	Efficiency
15.6	5.000	78.000	13.939	5.378	74.958	0.961

DIRECT ENERGY TRANSFER IN UNSHADED CONDITIONS

Vpv (V)	lpv (A)	Ppv (W)
13.01	5.27	68.56

Only **68.56 W** of power was extracted when Direct energy transfer was used to charge the battery. Compared to this the buck converter yielded **78 W** of power which is 13.7% increase in extraction

DIRECT ENERGY TRANSFER IN SHADED CONDITIONS

4 cells were shaded and power was measured in both approaches

DIRECT ENERGY TRANSFER			ВІ	JCK CONVERTE	R
Vpv (V)	lpv (A)	Ppv (W)	Vpv (V) Ipv (A) Ppv (W		
12.535	0.522	6.543	15.59	0.525	8.18

- The Buck converter approach performs better than Direct Energy transfer even when the panels are shaded.
- Even then, both approaches yield suboptimal extraction from panel. When 4 cells are shaded only 18 cells of the panel conduct and Vmpp drops to 8V. Since buck converter cannot operate with input voltage less than output voltage, the converter fails to operate at maximum power.
- One approach to extract maximum power even during shaded conditions would be to replace the Buck with a SEPIC. SEPIC can both boost and buck voltages. This will ensure maximum power point operation in both shaded and unshaded conditions.

CONCLUSION

- An MPPT algorithm was designed that periodically sweeps the panel voltage to find the operating voltage at which the panel must be regulated to yield maximum power.
- The performance of the above algorithm was evaluated under different irradiations and was found to have satisfactory peak power tracking.