# MODEL QUESTION PAPER EMBEDDED SYSTEM AND REAL TIME OPERATING SYSTEM (5131)

[Maximum Marks: 75] [Time: 3 Hours]

### **PART-A**

## I. Answer *all* the following questions in one word or one sentence. Each question carries 'one' mark.

 $(9 \times 1 = 9 \text{ Marks})$ 

		Module Outcome C	ognitive ievei
1.	The data type in AVR C that takes a value in the range 0 to 255 is	M2.01	U
2.	is used by the CPU to point to the address of the next instruction to	M1.03	U
	be executed.	1,11,00	
3.	Write the AVR C statement to set port B to function as output.	M2.02	A
4.	register is used for setting the modes of operation of a timer.	M2.06	A
5.	Give the instruction used to enable and clear interrupts globally.	M2.08	A
6.	In reading the columns of a keyboard matrix, if no key is pressed we should get all values as	M3.01	R
7.	LM34 is a	M3.02	R
8.	Name different types real time Operating System	M4.02	R
9.	Define Process.	M4.03	R

#### **PART-B**

### II. Answer any eight questions from the following. Each question carries 'three' marks.

(8 x 3 = 24 Marks)
Module Outcome Cognitive level

1.	Differentiate microprocessor and microcontroller	M1.01	U
2.	Explain about real time embedded systems. Also give its classification.	M4.02	U
3.	Write about AVR Status Register and specify the function of each bit in the status register	M1.03	U
4.	Write an AVR C program to toggle only PORTB.4 bit continuously with a delay.	M2.02	A
5.	Draw TIFR register and mention the function of each bit.	M2.05	U
6.	Compare and Contrast interrupt and polling.	M2.07	U
7.	Draw the block diagram of interfacing LM34 temperature sensor with ATMega32.	M3.02	U
8.	Explain ADC and its major characteristics.	M3.02	R
9.	Explain the structure of a process in operating system.	M4.03	U
10.	Explain the role of device drivers in embedded operating systems.	M4.07	U

PART-C Answer all questions. Each question carries *'seven'* marks

(6 x 7 = 42 Marks)
Module Outcome Cognitive level

		Module Outcome Co	ognitive level
III.	Write the different criteria for choosing a microcontroller.	M1.01	U
	OR		
IV.	Describe the basic block diagram of AVR microcontroller.	M1.03	U
V.	Toggle all the bits of Port B 200 times using delay function	M2.02	A
	(_dealy_ms).		
VI.	OR	M2.03	A
٧ 1.	Write an AVR C program to send out the value 44H serially one bit at a time via port C, pin 3. The MSB should go out first.	1112.03	$\Pi$
	a time via port C, pin 3. The MSB should go out first.		
VII.	Describe the purpose of ISR and explain the steps in executing an Interrupt.	M2.07	U
	OR		
VIII.		M2.05	U
V 111.	Describe about the registers associated with AVR timer.	W12.03	O
IX.	Explain the interfacing keyboard with AVR with the help of diagram.	M3.01	U
171.		1413.01	O
	OR		
X.	Describe the interfacing of temperature sensor LM34 to AVR.	M3.02	U
	beserve the intertueing of temperature sensor Eivis 1 to 11 vic.		
XI.	Explain the features of General Purpose Operating System (GPOS)	M4.02	U
	and Real Time Operating System (RTOS)		
	OR		
XII.	Explain any four functionalities of real time operating system.	M4.01	U
	Explain any four functionalities of fear time operating system.		
XIII.	Outline the key concepts of Task, Process and threads	M4.03	U
	OR		
XIV.	Explain the functional requirements for choosing RTOS.	M4.08	U
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