

# **Topological Semantics for Common Inductive Knowledge**

**Solving an inductive version of the coordinated attack problem**

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# Blockchains/Web3

- **Many on-chain applications rely on attestations from validators about off-chain data.**
- Example: Proof of Reserve for freezing wrapped coins whenever backing drops.
- **Consensus from validators drives on-chain actions.**
- Example: Validators must agree that there is sufficient collateral to unfreeze a wrapped coin.
- **False positives are often far worse than false negatives.**
- Example: Unfreezing a wrapped coin with insufficient collateral is worse than freezing the coin when there is sufficient collateral.

# Inductive Coordinated Attack

- Validators passively receive signals about backing and follow an exogenous asynchronous communication protocol.
- They each tolerate a fixed number of mind switches about whether there is eventually always (e.a.) sufficient collateral.
- Want to find an attestation protocol which satisfies:
  1. **Validity**- If backing always eventually (a.e.) drops then not a single validator converges on attesting that there is e.a. sufficient collateral.
  2. **Agreement**- Either all validators converge on attesting there is e.a. sufficient collateral or no validators converge on attesting there is e.a. sufficient collateral.
  3. **Nontriviality**- At least one execution where all validators converge on attesting there is e.a. sufficient collateral.
- If validators honestly follow such an attestation protocol we can (e.g. via majority vote) ensure a wrapped coin is eventually unfrozen forever whenever all validators correctly converge on attesting there is e.a. sufficient collateral.
- Moreover, we can increase/decrease threshold from simple majority to trade off false positives/false negatives and protect against greater/fewer dishonest validators who deviate from the attestation protocol.

# Notation

- $N$  is a set of agents and  $\Omega$  is a set of possible worlds.
- $\mathcal{E}_i$  is a topological basis over  $\Omega$ , representing possible information states of agent  $i \in N$ .
- $n_i$  denotes the maximum number of times agent  $i$  is willing to switch their mind after first saying Yes while limit deciding a proposition.
- $\mathcal{T}_i$  is the topology generated by  $\mathcal{E}_i$ .
- $\mathcal{E}_{i|w}$  denotes those information states in  $\mathcal{E}_i$  which contain  $w$ .

# Strategies

- Each agent  $i$ 's *strategy*  $s_i$  is an  $n_i$ -switching method  $m_i$  where:
  1. A *method* for agent  $i$  is a map  $m_i : \mathcal{E}_i \rightarrow \{\text{Yes}, ?\}$ .
  2. A *t-switching sequence* for  $m_i$  is a finite downward sequence  $E_0 \supseteq \dots \supseteq E_t$  of information states in  $\mathcal{E}_i$  such that  $m_i(E_{2k}) = \text{Yes}$  and  $m_i(E_{2k+1}) = ?$ .
  3. An  $n$ -switching method for  $i$  has no  $t$ -switching sequences for any  $t > n$ .
- We let  $\sigma_{s_i}(w)$  denote the output  $s_i$  converges to in world  $w$ .

# Protocols

- A protocol  $(s_i)_{i \in N}$  *satisfies validity for the proposition  $P$*  if  $\forall i \in N$  we have:

$$\sigma_{s_i}^{-1}(\text{Yes}) \subseteq P.$$

- Next, a protocol  $(s_i)_{i \in N}$  *satisfies agreement* if  $\forall i, j \in N$  we have:

$$\sigma_{s_i}^{-1}(\text{Yes}) = \sigma_{s_j}^{-1}(\text{Yes}).$$

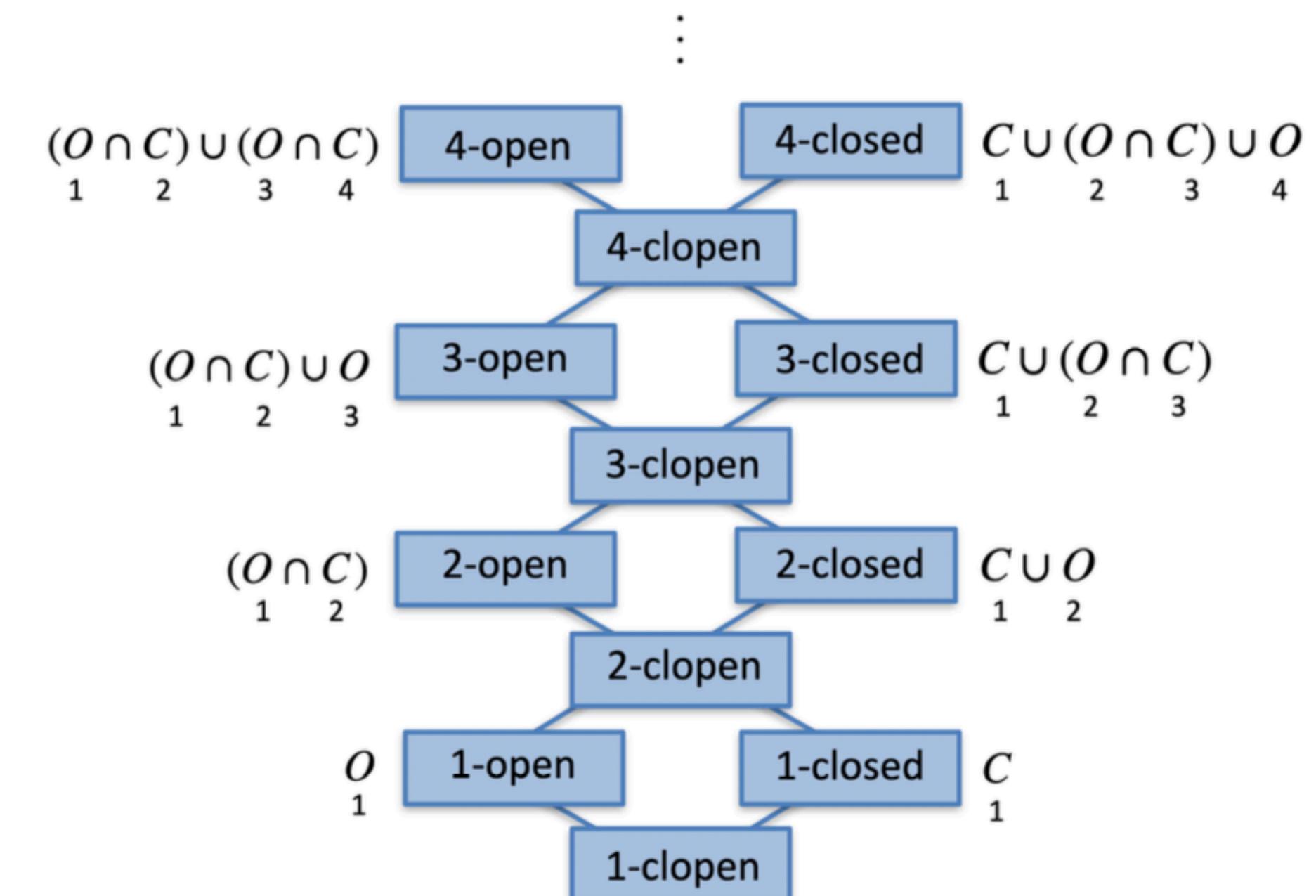
- Finally, a protocol  $(s_i)_{i \in N}$  *satisfies nontriviality* if we have:

$$\bigcap_{i \in N} \sigma_{s_i}^{-1}(\text{Yes}) \neq \emptyset.$$

- A protocol  $(s_i)_{i \in N}$  satisfying the above conditions *solves consensus for  $P$* .

# Topological Difference Hierarchy

- Fact: There exists a strategy  $s_i$  where  $\sigma_{s_i}^{-1}(\text{Yes}) = W$  iff  $W$  is  $(n_i + 1)$ -open in  $\mathcal{T}_i$ .
- If  $W$  is  $(n_i + 1)$ -open in  $\mathcal{T}_i$  it is easy to reconstruct the strategies  $s_i$  such that  $\sigma_{s_i}^{-1}(\text{Yes}) = W$ .
- Hence, if we can find the non-empty subsets of  $P$  which are  $(n_i + 1)$ -open in each  $\mathcal{T}_i$  then we can reconstruct the protocols which solve consensus for  $P$ .
- But how do we find these subsets?



# Topological Semantics

- $\text{Yes}_i^{n_i}(W|E)$ :  $i$  says Yes while limit deciding  $W$  in light of evidence  $E$ .
- $\mathbb{R}_i W$ :  $i$  has reason simpliciter to believe  $W$ .
- $\mathbb{I}_{i@W} P$ :  $W$  indicates to  $i$  that  $P$ .
- $\mathbb{B}_{i@W} P$ :  $i$  has  $W$  as reason to believe  $P$ .
- $\mathbb{E}_W P$ : everyone has  $W$  as reason to believe  $P$ .
- $\mathbb{G}_W P$ :  $W$  generates common inductive knowledge of  $P$ .
- $\mathbb{C}P$ :  $P$  is common inductive knowledge.

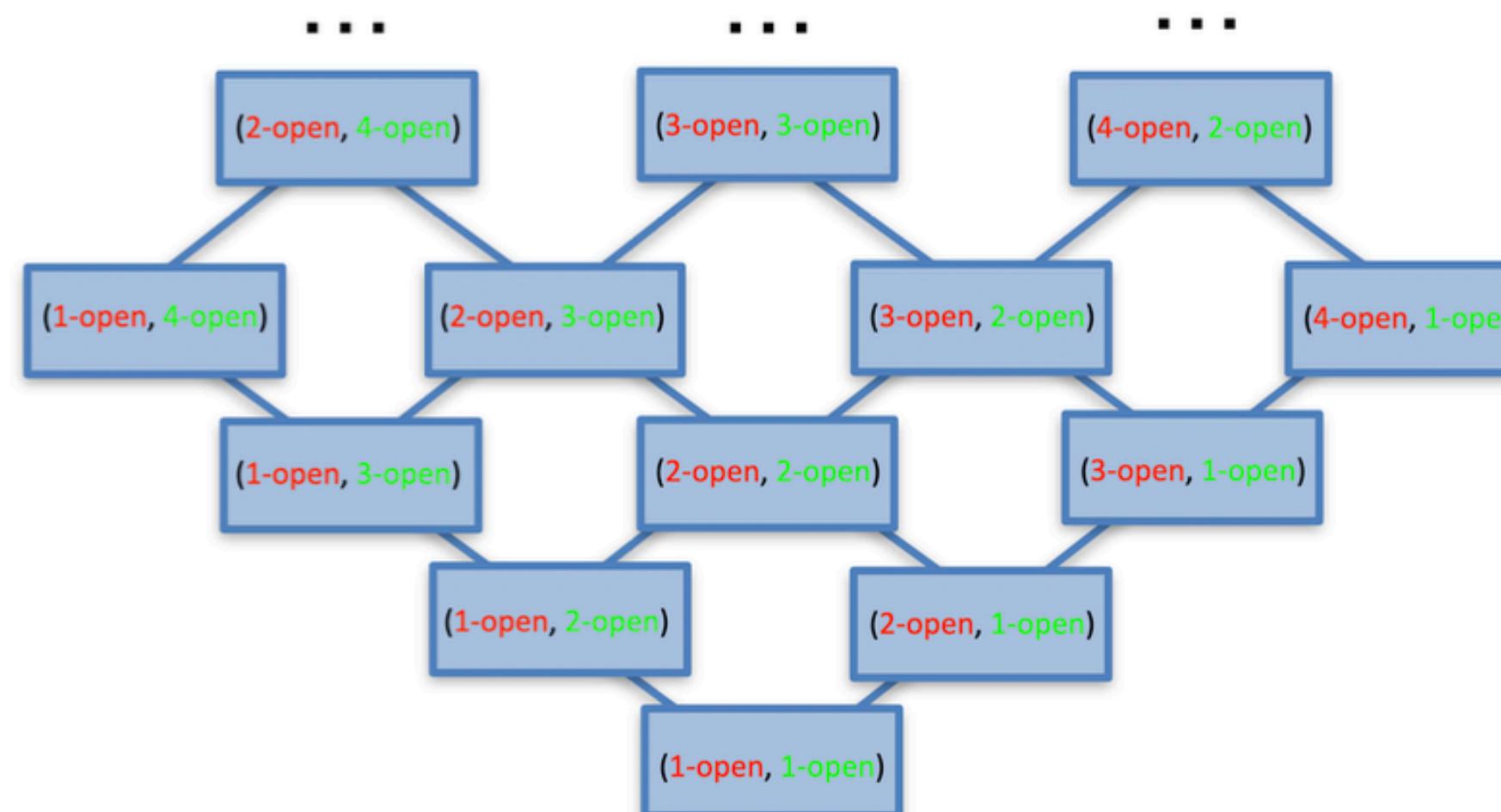
- $w \in \mathbb{R}_i W$  iff  $\exists E \in \mathcal{E}_{i|w}, \text{Yes}_i^{n_i}(W|E)$ .
- $w \in \mathbb{I}_{i@W} P$  iff  $\forall E \in \mathcal{E}_{i|w}, \text{Yes}_i^{n_i}(W|E) \rightarrow W \cap E \subseteq P$ .
- $w \in \mathbb{B}_{i@W} P$  iff  $w \in \mathbb{R}_i W \cap \mathbb{I}_{i@W} P$ .
- $w \in \mathbb{E}_W P$  iff  $w \in \cap_{i \in N} \mathbb{B}_{i@W} P$ .
- $w \in \mathbb{E}_W^1 P$  iff  $w \in \mathbb{E}_W P$ .
- $w \in \mathbb{E}_W^n P$  iff  $w \in \mathbb{E}_W \mathbb{E}_W^{n-1} P$ .
- $w \in \mathbb{G}_W P$  iff  $w \in \cap_{i \in \mathbb{N}^+} \mathbb{E}_W^n P$ .
- $w \in \mathbb{C}P$  iff  $\exists W \subseteq \Omega, w \in W \cap \mathbb{G}_W P$

# Results

- **Theorem 1:**  $W$  is a subset of  $P$  which is  $(n_i + 1)$ -open in each  $\mathcal{T}_i$  iff it is a fixed point of the map  $W \mapsto W \cap \mathbb{G}_W P$ . Further,  $\forall W \subseteq \Omega$ ,  $W \cap \mathbb{G}_W P$  is itself such a fixed point. This means:
  - A. The map  $W \mapsto W \cap \mathbb{G}_W P$  can be used to select any subset of  $P$  which is  $(n_i + 1)$ -open in each  $\mathcal{T}_i$ .
  - B.  $w \in \mathbb{C}P$  iff  $w$  is a world where agents can converge to attesting Yes in some protocol which solves consensus for  $P$ .

# Results

- **Theorem 2:** If  $\Omega$  is finite and each  $n_i$  is sufficiently high then  $\mathbb{C}P$  is invariant. To be clear:
  - Increasing  $n_i$  past a certain threshold does not change  $\mathbb{C}P$ .
  - There is some protocol solving consensus for  $P$  where agents converge to attesting 'yes' on  $\mathbb{C}P$ . This protocol is 'welfare-maximizing.'



# Future Work

- We are creating a logical language to reason precisely about common inductive knowledge.
  - Need to develop a sound and complete proof system for our semantics.
  - Will help prove and verify new theorems about our language.
- What kinds of consensus tasks are just inductive coordinated attack problems in disguise?
  - Might want to retemporalize possible worlds semantics back to states of affairs semantics (runs and systems).