

Estimating Mutual Information from Average Classification Error

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Abstract

Multivariate pattern analyses approaches in neuroimaging are fundamentally concerned with investigating the quantity and type of information processed by various regions of the human brain; typically, estimates of classification accuracy are used to quantify information. While a extensive and powerful library of methods can be applied to train and assess classifiers, it is not always clear how to use the resulting measures of classification performance to draw scientific conclusions: e.g. for the purpose of evaluating redundancy between brain regions. An additional confound for interpreting classification performance is the dependence of the error rate on the number and choice of distinct classes obtained for the classification task. In contrast, mutual information is a quantity which is in principle defined independently of the experimental design, and has ideal properties for comparative analyses. One obstacle to wider use of mutual information is the difficulty of estimating mutual information in high-dimensional neuroimaging data. We propose a new estimator of mutual information based on the concept of "average Bayes error." By assuming that the classes obtained in the data are drawn randomly from a continuous population, we find that the expected Bayes error converges to a function of the mutual information in a high-dimensional limit. We demonstrate the utility of our approach in simulated and real-data examples.

1 Introduction

A fundamental challenge of computational neuroscience is to understand how information about the external world is processed and represented in the brain. Each individual neuron aggregates the incoming information into a single sequence of spikes—an output which is too simplistic by itself to capture the full complexity of sensory input. Only by combining the signals from massive ensembles of neurons is it possible to reconstruct our complex representation of the world. Nevertheless, neurons form hierarchies of specialization within neural circuits, which are further organized in various specialized regions of the brain. It remains a key question to understand the division of labor at the macroscale level of organization in the brain. To answer whether or not a particular brain region receives information about a given stimulus, it suffices to demonstrate a systematic dependence between brain activity in that region and stimulus features. For a recording of a single neuron responding to varying stimuli, the noisy channel model at the basis of Shanon’s information theory was a natural fit. But as new technologies for recording of the brain developed, the resulting increase in the number of channels and often indirect measurements necessitate new approaches for summarizing and inferring measures of information in the brain.

An influential model to describe how much of the input information can be extracted from the output channels is Shannon’s mutual information, defined as

$$I(X; Y) = \int p(x, y) \log \frac{p(x, y)}{p(x)p(y)} dx dy$$

where X is the input channel and Y is the output channel. A leading metaphor is that of a noisy communications channel; the mutual information describes the rate at which Y can communicate bits from X . This framework is well-suited for summarizing the properties of a single neuron coding external stimulus information; indeed, experiments studying the properties of a single or a small number of neurons often make use of the concept of mutual information in summarizing or interpreting their results (Quiroga 2009). However, estimating mutual information for multiple channels require large and over-parameterized generative models. For instance, one can tractably estimate mutual information by assuming a multivariate Gaussian model: however, this approach essentially assumes a linear relationship between the input and output, and hence fails to quantify nonlinear dependencies. As the complexity of stimuli and the number of output channels increases, these

models are hard or impossible to estimate without gross over-fitting. A new way to measure the information in the ensemble was needed.

Machine learning algorithms showed a way forward: in the seminal work by Haxby (2001) proposed to quantify the information in multiple channels by measuring how well the stimulus can be identified from the brain responses, in what is known as “multivariate pattern analysis” (MVPA). To demonstrate that a particular brain region responds to a certain type of sensory information, one employs supervised learning to build a classifier that classifies the stimulus class from the brain activation in that region. Classifiers that achieve above-chance classification accuracy indicate that information from the stimulus is represented in the brain region. In principle, one could just as well test the statistical hypothesis that the Fisher information or mutual information between the stimulus and the activation patterns is nonzero. But in practice, the machine learning approach enjoys several advantages: First, it is invariant to the parametric representation of the stimulus space, and is opportunistic in the parameterization of the response space. This is an important quality for naturalistic stimulus-spaces, such as faces or natural images. Second, it scales better with the dimensionality of both the stimulus space and the responses space, because a slimmer discriminative model can be used rather than a fully generative model.

Nevertheless, classification error is problematic for quantifying the strength of the relation between stimulus and outputs due to its arbitrary scale and strong dependence on experimental choices. Classification accuracy depends on the particular choice of stimuli exemplars employed in the study and the number of partitions used to define the classes for the classification task. The difficulty of the classification task depends on the number of classes defined: high classification accuracy can be achieved relatively easily by using a coarse partition of stimuli exemplars into classes. In a meta-analysis on visual decoding, Coutanche et al (2016) quantified the strength of a classification study using the formula

$$\text{decoding strength} = \frac{\text{accuracy} - \text{chance}}{\text{chance}}.$$

Such an approach may compensate for the differences in accuracy due purely to choice of number of classes defined; however, no theory is provided to justify the formula. In contrast, mutual information has ideal properties for the quantitatively comparing information between different studies, or between different brain regions, subjects, featurization models, or modalities.

Not only is the mutual information defined independently of the arbitrary definition of stimulus classes (albeit still dependent on an implied distribution over stimuli), it is even meaningful to discuss the difference between the mutual information measured for one system and the mutual information for a second system.

Hence, a popular approach which combines the strengths of the machine learning approach and the advantages of the information theoretic approach is to obtain a lower bound on the mutual information by using the confusion matrix of a classifier. This is the most popular approach for estimating mutual information in neuroimaging studies, but suffers from known shortcomings (Gastpar 2010, Quiroga 2009).

The idea of linking classification performance to mutual information dates back to the beginnings of information theory: Shannon’s original motivation was to characterize the minimum achievable error probability of a noisy communication channel. More explicitly, Fano’s inequality provides a lower bound on mutual information in relation to the optimal prediction error, or Bayes error. Fano’s inequality can be further refined to obtain a tighter lower bound on mutual information (Tebbe and Dwyer 1968.) However, all approaches to date can only obtain a lower bound on the mutual information from classification error. In practice, the bound obtained may be a vast underestimate.

In this paper, we propose a new way to link classification performance to the implied mutual information. To create this link we need to overcome the arbitrary choice of exemplars, and the arbitrary number of classes K . Towards this end, we define a notion of K -class *average Bayes error* which is uniquely defined for any given stimulus distribution and stochastic mapping from stimulus to response. The K -class average Bayes error is simply the expectation of the Bayes error (the classification error of the optimal classifier) when K stimuli exemplars are drawn i.i.d. from the stimulus distribution, and treated as distinct classes. Hence the average Bayes error can in principle be estimated if the appropriate randomization is employed for designing the experiment.

Our main theoretical contribution is the derivation of an asymptotic relationship between the K -class average Bayes error and the mutual information. Although the K -class average Bayes error is defined independently of the particular choice of stimuli, the quantity still depends on the choice of number of classes, K . Mutual information provides a quantification of information that does not depend on K , allowing more flexible comparisons

and easier interpretation. Our method allows estimates of the K -class Bayes error to be translated into estimate of the mutual information, and this resulting estimator of mutual information will be asymptotically independent of the choice of number of classes K .

2 Framework

The following simplified model captures the essence of many neuroimaging studies. Let \mathcal{X} be a space of stimuli, represented by q -dimensional vectors. In the design stage of the experiment, a set of k stimuli exemplars $\{x^{(1)}, \dots, x^{(k)}\}$ are selected, and then one specifies a T -length sequence of stimuli $(x^{(i_1)}, \dots, x^{(i_T)})$ to be presented to the subject. In the execution of the experiment, an activation pattern, or *response* y^t is obtained for each of the stimuli presentations $x^{(i_t)}$. Generally y^t is a p -dimensional vector, representing activity levels of p disjoint brain regions. To simplify, assume that each of the k stimuli is presented a total of r times in the sequence; further assume that the responses to each stimulus presentation are conditionally independent, hence the ordering of the sequence does not matter. Henceforth we can let $y^{(i),j}$ denote the response to the j th presentation of the stimulus $x^{(i)}$.

While in many studies, the stimuli exemplars $x^{(1)}, \dots, x^{(k)}$ are chosen somewhat arbitrarily, more types of inferences can be drawn if randomization is employed to choose the stimuli. Based on this distinction, we discuss two types of experimental designs:

1. *Fixed stimuli design.* The exemplars $x^{(1)}, \dots, x^{(k)}$ are treated as fixed.
2. *Randomized stimuli design.* The experimenter first specifies a space of stimuli \mathcal{X} and a probability distribution $p(x)$ over that space. Then, k exemplars are drawn i.i.d. from that space,

$$X^{(1)}, \dots, X^{(k)} \stackrel{iid}{\sim} p(x).$$

As we will discuss, the randomized stimuli design allows the possibility of *generalizing* beyond the chosen exemplars; i.e. drawing inferences about the entire joint distribution $p(x, y)$.

2.1 Fixed stimuli design

We begin by describing a fixed stimuli design, and the types of inferences that can be made using machine learning tools.

Let $\mathcal{X} \subset \mathbb{R}^q$ and $\mathcal{Y} \subset \mathbb{R}^p$; For every $x \in \mathcal{X}$, let $p_x(y)$ be a probability density on \mathcal{Y} . Take a subset $\{x_1, \dots, x_k\} \subset \mathcal{X}$. Let Y_i^j be a random vector distributed according to density $p_{x_i}(y)$; and let Y_i^j be conditionally independent given $\{x_1, \dots, x_k\}$ for $i = 1, \dots, k$ and $j = 1, \dots, r$.

In MVPA, one carries out a classification task to assess whether y contains information about x . Formally, a classification rule is any (possibly stochastic) mapping $f : \mathcal{Y} \rightarrow \{1, \dots, k\}$. The *generalization error* of the classification rule for classes x_1, \dots, x_k is

$$e_{gen}(f) = \frac{1}{k} \sum_{i=1}^k \Pr[f(Y) \neq i | X = x_i].$$

A trivial classification rule which outputs the result of a k -sided die roll for all inputs y would achieve a generalization error of $e_{gen} = \frac{k-1}{k}$. Conversely, even a single counterexample with $e_{gen} < \frac{k-1}{k}$ is indicative that y contains nonzero information about x . Hence, in order to demonstrate that y is informative of x , one tests the null hypothesis

$$H_0 : e_{gen}(f) = \frac{k-1}{k}.$$

Rejecting the null hypothesis for a given classification rule f can be taken as evidence that y is informative of x . In the discussion thus far, “information” refers to an informal, intuitive notion.

The classifier is a functional which maps a set of observations to a classification rule,

$$\mathcal{F} : \{(x_1, y_1), \dots, (x_m, y_m)\} \mapsto f(\cdot);$$

informally, a classifier is an algorithm which “learns” a classification rule from data. For a valid test of H_0 , either the data-splitting approach or the cross-validation approach can be used. In the data-splitting approach, one creates a *training set* consisting of r_1 repeats per class,

$$\{(x_1, y_1^1), \dots, (x_1, y_1^{r_1}), \dots, (x_m, y_m^1), \dots, (x_m, y_m^{r_1})\}$$

and a *test set* consisting of the remaining $r_2 = r - r_1$ repeats.

$$\{(x_1, y_1^{r_1+1}), \dots, (x_1, y_1^r), \dots, (x_m, y_m^{r_1+1}), \dots, (x_m, y_m^r)\}.$$

In the cross-validation approach, one applies the data-splitting approach multiple times, with different training and test partitions, and aggregates the results. We further discuss the cross-validation approach in section X.

In the data-splitting approach, one obtains the classification rule f by applying the classifier to the training data,

$$f = \mathcal{F}(\{(x_1, y_1^1), \dots, (x_1, y_1^{r_1}), \dots, (x_m, y_m^1), \dots, (x_m, y_m^{r_m})\})$$

The test statistic of interest is the test error, defined as

$$e_{test} = \frac{1}{kr_2} \sum_{i=1}^k \sum_{j=r_1+1}^r \mathbf{I}(f(y_i^j) \neq i).$$

Due to the conditional independence of the training set and test set, e_{test} is an unbiased estimate of e_{gen} . Hence various approaches can be used to obtain a threshold c_α such that $\Pr[e_{test} < c_\alpha] \leq \alpha$ holds (approximately) under the null hypothesis. These approaches include permutation tests, tests based on a universal variance bound, or the generalized likelihood ratio test. Regardless of the procedure used to derive the threshold c_α , The hypothesis H_0 is rejected at level α if $e_{test} < c_\alpha$.

While tests of the generalization error suffice to establish the presence of information, the generalization error is less satisfactory as a measure of the information between X and Y , because e_{gen} depends on the classification rule f obtained—but since the performance of the classifier may vary depending on the choice of model (k -nearest neighbors, SVM, etc.) and the choice of tuning parameters, the quantity e_{gen} is therefore not uniquely defined. To resolve the ill-definedness of the generalization error, we define the Bayes error, which is simply the *optimal* generalization error

$$e_{Bayes} = \min_f e_{gen}(f).$$

Due to Bayes' theorem, the optimal classification rule f^* which achieves the Bayes error can be given explicitly: it is the maximum a posteriori (MAP) rule

$$f^*(y) = \operatorname{argmax}_{i=1}^k p(y|x_i).$$

However, it is not possible to construct this rule in practice since the joint distribution is unknown. Instead, in many cases, a reasonable approach is to try a variety of classifiers, producing rules f_1, \dots, f_m , and taking the best

generalization error as an estimate of the Bayes error. We give more details of this approach in the Discussion.

This way one can draw inferences about information between the fixed ensemble x_1, \dots, x_k and the brain regions being examined. But in many cases it is desired to generalize the results to other stimuli that were not included in the experiment. In order to do this, a randomized design is needed.

2.2 Randomized stimuli design

In a randomized design, we specify a distribution $p(x)$ on \mathcal{X} , and require that the stimulus x_1, \dots, x_k are drawn iid from this distribution. Defining the joint distribution of the stimulus X and the response Y as

$$p(x, y) = p(x)p(y|x),$$

one can also define the mutual information

$$I(X; Y) = \int p(x, y) \log \frac{p(x, y)}{p(x)p(y)} dx dy$$

Unlike in the case of fixed design, it becomes possible to infer functionals of $p(x, y)$, such as $I(X; Y)$, from the data. In other words, beyond merely testing for the existence of information, the additional assumption of randomization allows us to estimate the mutual information. While the fixed design setup allowed qualitative tests of information, the randomized design enables, in addition, a quantitative estimation approach, which in turn allows for a richer set of comparisons to be made from the data: which region has the most information about the stimulus? how redundant is the information in region A compared to region B?

Methodologies for estimating mutual information under the assumption of randomization have been studied in (Borst 1999), (Nelken 2005) and most notably (Gastpar 2010); the latter studies the problem under an identical setup to ours. In addition to these approaches, one can obtain a lower bound on the information using the mutual information of the confusion matrix (Treves et al), (Quiroga 2009). In the following section, we present our methodology for inferring mutual information under the randomized stimuli design setting,

Before presenting our approach, we first define the notion of average Bayes error, which is fundamental to our approach. The motivation for defining

average Bayes error is the fact that the quantity e_{Bayes} is not a parameter of the joint distribution $p(x, y)$, but rather depends on the specific exemplars x_1, \dots, x_k selected; hence, one may write $e_{Bayes}(x_1, \dots, x_k)$ to emphasize this dependence. The *average* Bayes error, on the other hand, is defined uniquely for any joint distribution,

$$e_{ABE,k} = \mathbf{E}[e_{Bayes}(X_1, \dots, X_k)],$$

where X_1, \dots, X_K are drawn i.i.d. from $p(x)$. Supposing that an unbiased estimator for Bayes error exists, \hat{e}_{Bayes} , then \hat{e}_{Bayes} will also be unbiased for $e_{ABE,k}$ under the randomization assumption. It turns out that under certain conditions, the average Bayes error can be well-approximated as a monotonically decreasing function of the mutual information, and vice-versa.

3 Asymptotic Theory

Our goal in this section is to establish a relationship between the mutual information $I(X; Y)$ and the k -class average Bayes error, $e_{ABE,k}$. In short, we will identify a function π_k (which depends on k),

$$e_{ABE,k} \approx \pi_k(\sqrt{2I(X; Y)})$$

and that this approximation becomes accurate under a limit where $I(X; Y)$ is small relative to the dimensionality of X , and under the condition that the components of X are approximately independent. Formal conditions are given in the proof statement.

The function π_k is given by

$$\pi_k(c) = 1 - \int_{\mathbb{R}} \phi(z - c) \Phi(z)^{k-1} dz.$$

Figure 1 displays the plot of π_k for several values of k . For all values of k , $\pi_k(\mu)$ is monotonically decreasing in μ , and tends to zero as $\mu \rightarrow \infty$. This should not be surprising, because if $I(X; Y)$ is large, then the average Bayes error should be small. Another fact, which can be verified through a simple calculation, is that

$$\pi_k(0) = 1 - \frac{1}{k}.$$

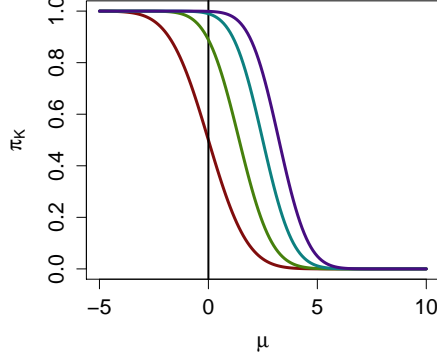


Figure 1: The function $pi_k(\mu)$, for $k = \{2, 9, 99, 999\}$ (left to right)

This should also not be surprising, since if $I(X; Y) = 0$, then it should not be possible to obtain a classification rule which is better than guessing at random, which is only correct with probability $1/k$.

First, let us rewrite $e_{ABE,k}$ in terms of the joint density $p(x, y)$. Recall that the Bayes rule is

$$e_{Bayes}(x_1, \dots, x_k) = \frac{1}{k} \sum_{i=1}^k \Pr[\hat{X}(Y) \neq x_i | X = x_i].$$

In turn, the Bayes classification rule is given in terms of the conditional density:

$$\hat{X}(y) = \operatorname{argmax}_{x \in \{x_1, \dots, x_k\}} p(y|x).$$

Therefore, we obtain

$$e_{Bayes}(x_1, \dots, x_k) = \frac{1}{k} \sum_{i=1}^k \Pr[p(Y|x_i) \leq \max_{j \neq i} p(Y|x_j) | X = x_i].$$

In turn the average Bayes error can be written as

$$e_{ABE,k} = \mathbf{E}[e_{Bayes}(X_1, \dots, X_k)] \tag{1}$$

$$= \frac{1}{k} \sum_{i=1}^k \mathbf{E}[\Pr[p(Y|x_i) \leq \max_{j \neq i} p(Y|x_j) | X = x_i]] \tag{2}$$

$$= \mathbf{E}[\Pr[p(Y|x_1) \leq \max_{j \neq 1} p(Y|x_j) | X = x_1]] \tag{3}$$

$$= \Pr[p(Y|X_1) \leq \max_{j \neq 1} p(Y|X_j) | X = X_1]. \tag{4}$$

Defining $Z_i = \log p(Y|X_i) - \log p(Y|X_1)$, where $Y \sim p(y|X_1)$. The we obtain

$$e_{ABE} = \Pr[Z_1 < \max_{j>1} Z_j].$$

Our proof uses the assumption that Z_1, \dots, Z_k are asymptotically multivariate normal. Supposing that Z_1, \dots, Z_k are indeed asymptotically normal, the following lemma allows us to obtain a formula for the misclassification rate.

Lemma 1. *Suppose (Z_1, Z_2, \dots, Z_k) are jointly multivariate normal, with $\mathbf{E}[Z_1 - Z_i] = \alpha$, $\text{Var}(Z_1) = \beta$, $\text{Cov}(Z_1, Z_i) = \gamma$, $\text{Var}(Z_i) = \delta$, and $\text{Cov}(Z_i, Z_j) = \epsilon$ for all $i, j = 2, \dots, k$, such that $\beta + \epsilon - 2\gamma > 0$. Then, letting*

$$\mu = \frac{\mathbf{E}[Z_1 - Z_i]}{\sqrt{\frac{1}{2} \text{Var}(Z_i - Z_j)}} = \frac{\alpha}{\sqrt{\delta - \epsilon}},$$

$$\nu^2 = \frac{\text{Cov}(Z_1 - Z_i, Z_1 - Z_j)}{\frac{1}{2} \text{Var}(Z_i - Z_j)} = \frac{\beta + \epsilon - 2\gamma}{\delta - \epsilon},$$

we have

$$\begin{aligned} \Pr[Z_1 < \max_{i=2}^k Z_i] &= \Pr[W < M_{k-1}] \\ &= 1 - \int \frac{1}{\sqrt{2\pi\nu^2}} e^{-\frac{(w-\mu)^2}{2\nu^2}} \Phi(w)^{k-1} dw, \end{aligned}$$

where $W \sim N(\mu, \nu^2)$ and M_{k-1} is the maximum of $k-1$ independent standard normal variates, which are independent of W .

Proof. We can construct independent normal variates G_1, G_2, \dots, G_k such that

$$\begin{aligned} G_1 &\sim N(0, \beta + \epsilon - 2\gamma) \\ G_i &\sim N(0, \delta - \epsilon) \text{ for } i > 1 \end{aligned}$$

such that

$$Z_1 - Z_i = \alpha + G_1 + G_i \text{ for } i > 1.$$

Hence

$$\begin{aligned}
\Pr[Z_1 < \max_{i=2}^k Z_i] &= \Pr[\min_{i>1} Z_1 - Z_i < 0]. \\
&= \Pr[\min_{i=2}^k G_1 + G_i + \alpha < 0] \\
&= \Pr[\min_{i=2}^k G_i < -\alpha - G_1] \\
&= \Pr[\min_{i=2}^k \frac{G_i}{\sqrt{\delta - \epsilon}} < -\frac{\alpha - G_1}{\sqrt{\delta - \epsilon}}].
\end{aligned}$$

Since $\frac{G_i}{\sqrt{\delta - \epsilon}}$ are iid standard normal variates, and since $-\frac{\alpha - G_1}{\sqrt{\delta - \epsilon}} \sim N(\mu, \nu^2)$ for μ and ν^2 given in the statement of the Lemma, the proof is completed via a straightforward computation. \square

To see why the assumption that Z_1, \dots, Z_k are multivariate normal might be justified, suppose that X and Y have the same dimensionality d , and that joint density factorizes as

$$p(x_j, y) = \prod_{i=1}^d p_i(x_{j,i}, y_i)$$

where $x_{j,i}, y_i$ are the components of x_j and y . Then,

$$Z_i = \sum_{m=1}^d \log p_m(y_m | x_{m,i}) - \log p_m(y_m | x_{m,1})$$

where $x_{i,j}$ is the i th component of x_j . The d terms $\log p_m(y_m | x_{m,i}) - \log p_m(y_m | x_{m,1})$ are independent across the indices m , but dependent between the $i = 1, \dots, k$. Therefore, the multivariate central limit theorem can be applied to conclude that the vector (Z_1, \dots, Z_k) can be scaled to converge to a multivariate normal distribution. Now, since the average Bayes error $e_{ABE,k}$ is a continuous functional of the joint distribution $p(x, y)$, it follows that $e_{ABE,k}$ converges to a functional of the limiting mean and covariance of (Z_1, \dots, Z_k) , assuming that the limits exist. In our theorem, we assume a specific regime where these limits exist as a consequence. While the componentwise independence condition is not a realistic assumption, the key property of multivariate normality of (Z_1, \dots, Z_k) holds under more general conditions, and appears reasonable in practice.

The second component of our theorem is to manipulate the expression of the mutual information $I(X; Y)$. The differential mutual information is defined as

$$I(X; Y) = \int p(x, y) \log \frac{p(x, y)}{p(x)p(y)} dx dy.$$

The key manipulation we employ is to approximate the logarithmic term by the Taylor expansion

$$\log \frac{p(x, y)}{p(x)p(y)} \approx \frac{p(x, y) - p(x)p(y)}{p(x)p(y)} - \left(\frac{p(x, y) - p(x)p(y)}{p(x)p(y)} \right)^2 + \dots$$

The approximation is accurate if $I(X; Y)$ is small—or rather, small relative to the dimensionality within the asymptotic sequence. We state the theorem for the regime where $I(X; Y)$ is fixed, while the dimensionality of X increases.

3.1 Technical section

We formally state the assumptions and theorem in this section. The less technically inclined reader may skip the section in order to continue to the proposed methodology for estimating mutual information, and results.

The asymptotic regime we consider is one where the dimension of X goes to infinity. This means that we have to consider a sequence of joint distributions $(X^{[d]}, Y^{[d]})$ indexed by the dimension d .

Fix integer $k \geq 2$. Let $p^{[d]}(x, y)$ be a sequence of probability density functions, where x is of dimension $p^{[d]}$ and y is of dimension $q^{[d]}$. Let $p^{[d]}(x)$ and $p^{[d]}(y)$ denote the marginal densities, and let

$$p^{[d]}(y|x) = p^{[d]}(x, y)/p^{[d]}(x).$$

Let $(X^{([d], i)}, Y^{([d], i)})$ be iid random variates from $p^{[d]}(x, y)$ for $i = 1, \dots, k$; we will suppress the superscripts $[d]$ and/or (i) when convenient. Recall the definitions of entropy,

$$H(X) = - \int p(x) \log p(x) dx,$$

and mutual information

$$I(X; Y) = \int p(x, y) \log \frac{p(x, y)}{p(x)p(y)} dx dy.$$

Furthermore, define the K -class average Bayes error as

$$e_{ABE,k} = \Pr[p(Y^{(1)}|X^{(1)}) < \max_{i=2}^k p(Y^{(1)}|X^{(i)})].$$

Define

$$u^{[d]}(x, y) = \log p^{[d]}(x, y) - \log p^{[d]}(x) - \log p^{[d]}(y),$$

and define

$$\ell_{ij}^{[d]} = \log p(y^{(i)}|x^{(j)}).$$

We now give the theorem and its proof.

Theorem 1. Let $p^{[d]}(x, y)$ be a sequence of joint densities for $d = 1, 2, \dots$ as given above. Further assume that

- A1. $\lim_{d \rightarrow \infty} I(X^{[d]}; Y^{[d]}) = \iota < \infty$.
- A2. There exists a sequence of scaling constants $a_{ij}^{[d]}$ and $b_{ij}^{[d]}$ such that the random vector $(a_{ij}\ell_{ij}^{[d]} + b_{ij}^{[d]})_{i,j=1,\dots,k}$ converges in distribution to a multivariate normal distribution.
- A3. There exists a sequence of scaling constants $a^{[d]}, b^{[d]}$ such that

$$a^{[d]}u(X^{(1)}, Y^{(2)}) + b^{[d]}$$

converges in distribution to a univariate normal distribution.

- A4. For all $i \neq k$,

$$\lim_{d \rightarrow \infty} \text{Cov}[u(X^{(i)}, Y^{(j)}), u(X^{(k)}, Y^{(j)})] = 0.$$

Then for $e_{ABE,k}$ as defined above, we have

$$\lim_{d \rightarrow \infty} e_{ABE,k} = \pi_k(\sqrt{2\iota})$$

where

$$\pi_k(c) = 1 - \int_{\mathbb{R}} \phi(z - c) \Phi(z)^{k-1} dz$$

where ϕ and Φ are the standard normal density function and cumulative distribution function, respectively.

Proof.

For $i = 2, \dots, k$, define

$$Z_i = \log p(Y^{(1)}|X^{(i)}) - \log p(Y^{(1)}|X^{(1)}).$$

Then, we claim that $\vec{Z} = (Z_2, \dots, Z_k)$ converges in distribution to

$$\vec{Z} \sim N \left(-2\iota, \begin{bmatrix} 4\iota & 2\iota & \cdots & 2\iota \\ 2\iota & 4\iota & \cdots & 2\iota \\ \vdots & \vdots & \ddots & \vdots \\ 2\iota & 2\iota & \cdots & 4\iota \end{bmatrix} \right).$$

Combining the claim with the lemma (stated below this proof) yields the desired result.

To prove the claim, it suffices to derive the limiting moments

$$\mathbf{E}[Z_i] \rightarrow -2\iota,$$

$$\text{Var}[Z_i] \rightarrow 4\iota,$$

$$\text{Cov}[Z_i, Z_j] \rightarrow 2\iota,$$

for $i \neq j$, since then assumption A2 implies the existence of a multivariate normal limiting distribution with the given moments.

Before deriving the limiting moments, note the following identities. Let $X' = X^{(2)}$ and $Y = Y^{(1)}$.

$$\mathbf{E}[e^{u(X', Y)}] = \int p(x)p(y)e^{u(x, y)}dxdy = \int p(x, y)dxdy = 1.$$

Therefore, from assumption A3 and the formula for gaussian exponential moments, we have

$$\lim_{d \rightarrow \infty} \mathbf{E}[u(X', Y)] - \frac{1}{2} \text{Var}[u(X', Y)] = 0.$$

Let $\sigma^2 = \lim_{d \rightarrow \infty} \text{Var}[u(X', Y)]$. Meanwhile, by applying assumption A2,

$$\begin{aligned} \lim_{d \rightarrow \infty} I(X; Y) &= \lim_{d \rightarrow \infty} \int p(x, y)u(x, y)dxdy = \lim_{d \rightarrow \infty} \int p(x)p(y)e^{u(x, y)}u(x, y)dxdy \\ &= \lim_{d \rightarrow \infty} \mathbf{E}[e^{u(X, Y')}u(X, Y')] \\ &= \int_{\mathbb{R}} e^z z \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(z+\sigma^2/2)^2}{2\sigma^2}} dz \quad (\text{applying A2}) \\ &= \int_{\mathbb{R}} z \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(z-\sigma^2/2)^2}{2\sigma^2}} dz \\ &= \frac{1}{2}\sigma^2. \end{aligned}$$

Therefore,

$$\sigma^2 = 2\iota,$$

and

$$\lim_{d \rightarrow \infty} \mathbf{E}[u(X', Y)] = -\iota.$$

Once again by applying A2, we get

$$\begin{aligned} \lim_{d \rightarrow \infty} \text{Var}[u(X, Y)] &= \lim_{d \rightarrow \infty} \int (u(x, y) - \iota)^2 p(x, y) dx dy \\ &= \lim_{d \rightarrow \infty} \int (u(x, y) - \iota)^2 e^{u(x, y)} p(x) p(y) dx dy \\ &= \lim_{d \rightarrow \infty} \mathbf{E}[(u(X', Y) - \iota)^2 e^{u(X', Y)}] \\ &= \int (z - \iota)^2 e^z \frac{1}{\sqrt{4\pi\iota}} e^{-\frac{(z+\iota)^2}{4\iota}} dz \quad (\text{applying A2}) \\ &= \int (z - \iota)^2 \frac{1}{\sqrt{4\pi\iota}} e^{-\frac{(z-\iota)^2}{4\iota}} dz \\ &= 2\iota. \end{aligned}$$

We now proceed to derive the limiting moments. We have

$$\begin{aligned} \lim_{d \rightarrow \infty} \mathbf{E}[Z] &= \lim_{d \rightarrow \infty} \mathbf{E}[\log p(Y|X') - \log p(Y|X)] \\ &= \lim_{d \rightarrow \infty} \mathbf{E}[u(X', Y) - u(X, Y)] = -2\iota. \end{aligned}$$

Also,

$$\begin{aligned} \lim_{d \rightarrow \infty} \text{Var}[Z] &= \lim_{d \rightarrow \infty} \text{Var}[u(X', Y) - u(X, Y)] \\ &= \lim_{d \rightarrow \infty} \text{Var}[u(X', Y)] + \text{Var}[u(X, Y)] \quad (\text{using assumption A4}) \\ &= 4\iota, \end{aligned}$$

and similarly

$$\begin{aligned} \lim_{d \rightarrow \infty} \text{Cov}[Z_i, Z_j] &= \lim_{d \rightarrow \infty} \text{Var}[u(X, Y)] \quad (\text{using assumption A4}) \\ &= 2\iota. \end{aligned}$$

This concludes the proof. \square .

Assumptions A1-A4 are satisfied in a variety of natural models. One example is a multivariate Gaussian model where

$$X \sim N(0, \Sigma_d)$$

$$E \sim N(0, \Sigma_e)$$

$$Y = X + E$$

where Σ_d and Σ_e are $d \times d$ covariance matrices, and where X and E are independent. Then, if $d\Sigma_d$ and Σ_e have limiting spectra H and G respectively, the joint densities $p(x, y)$ for $d = 1, \dots$, satisfy assumptions A1 - A4.

We can also construct a family of densities satisfying A1 - A4, which we call an *exponential family sequence model* since each joint distribution in the sequence is a member of an exponential family. A given exponential family sequence model is specified by choice of a base carrier function $b(x, y)$ and base sufficient statistic $t(x, y)$, with the property that carrier function factorizes as

$$b(x, y) = b_x(x)b_y(y)$$

for marginal densities b_x and b_y . Note that the dimensions of x and y in the base carrier function are arbitrary; let p denote the dimension of x and q the dimension of y for the base carrier function. Next, one specifies a sequence of scalar parameters $\kappa_1, \kappa_2, \dots$ such that

$$\lim_{d \rightarrow \infty} d\kappa_d = c < \infty.$$

for some constant c . For the d th element of the sequence, $X^{[d]}$ is a pd -dimensional vector, which can be partitioned into blocks

$$X^{[d]} = (X_1^{[d]}, \dots, X_d^{[d]})$$

where each $X_i^{[d]}$ is p -dimensional. Similarly, $Y^{[d]}$ is partitioned into $Y_i^{[d]}$ for $i = 1, \dots, d$. The density of $(X^{[d]}, Y^{[d]})$ is given by

$$p^{[d]}(x^{[d]}, y^{[d]}) = Z_d^{-1} \left(\prod_{i=1}^d b(x_i^{[d]}, y_i^{[d]}) \right) \exp \left[\kappa_d \sum_{i=1}^d t(x_i^{[d]}, y_i^{[d]}) \right],$$

where Z_d is a normalizing constant. Hence $p^{[d]}$ can be recognized as the member of an exponential family with carrier measure

$$\left(\prod_{i=1}^d b(x_i^{[d]}, y_i^{[d]}) \right)$$

and sufficient statistic

$$\sum_{i=1}^d t(x_i^{[d]}, y_i^{[d]}).$$

One example of such an exponential family sequence model is a multivariate Gaussian model with limiting spectra $H = \delta_1$ and $G = \delta_1$, but scaled so that the marginal variance of the components of X and Y are equal to one. This corresponds to a exponential family sequence model with

$$b_x(x) = b_y(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

and

$$t(x, y) = xy.$$

Another example is a multivariate logistic regression model, given by

$$X \sim N(0, I)$$

$$Y_i \sim \text{Bernoulli}(e^{\beta X_i} / (1 + e^{\beta X_i}))$$

This corresponds to an exponential family sequence model with

$$b_x(x) = \frac{1}{\sqrt{2\pi}} e^{-x^2/2}$$

$$b_y(y) = \frac{1}{2} \text{ for } y = \{0, 1\},$$

and

$$t(x, y) = x\delta_1(y) - x\delta_0(y).$$

The multivariate logistic regression model (and multivariate Poisson regression model) are especially suitable for modeling neural spike count data; we simulate data from such a multivariate logistic regression model in section X.

3.2 Inference for mutual information

In the previous section, we showed that

$$\lim_{d \rightarrow \infty} e_{ABE,k} = \pi_k(\sqrt{2I(X; Y)}),$$

where $e_{ABE,k}$ is the k -class average Bayes error, in an asymptotic regime where $I(X^{[d]}; Y^{[d]})$ is fixed while the dimensionality of X increases. Since π_k is invertible for all $k = 2, \dots$, a converse relationship

$$\lim_{d \rightarrow \infty} I(X^{[d]}; Y^{[d]}) = \frac{1}{2}(\pi_k^{-1}(\eta))^2$$

also holds in the same regime. We formally state the result, and a few consequences, as follows.

Corollary 1. Let $p^{[d]}(x, y)$ be a sequence of joint densities for $d = 1, 2, \dots$ as given above. Further assume assumptions A2 - A4 and also

$$\text{A1'}. \lim_{d \rightarrow \infty} e_{ABE,k} = \eta < \infty.$$

Then

i.

$$\lim_{d \rightarrow \infty} I(X^{[d]}; Y^{[d]}) = \frac{1}{2}(\pi_k^{-1}(e_{ABE}))^2.$$

ii. If $[\underline{e}, \bar{e}]$ is a $1 - \alpha$ confidence interval for $e_{ABE,k}$, then

$$\left[\frac{1}{2}(\pi_k^{-1}(\bar{e}))^2, \frac{1}{2}(\pi_k^{-1}(\underline{e}))^2 \right]$$

is asymptotically a $1 - \alpha$ confidence interval of $I(X; Y)$: that is,

$$\lim_{d \rightarrow \infty} \Pr \left[I(X^{[d]}; Y^{[d]}) \in \left[\frac{1}{2}(\pi_k^{-1}(\underline{e}))^2, \frac{1}{2}(\pi_k^{-1}(\bar{e}))^2 \right] \right] = 1 - \alpha.$$

iii. If \hat{e} is a $O(1/\sqrt{n})$ -consistent estimator for $e_{ABE,k}$, and $\lim_{d \rightarrow \infty} e_{ABE,k} > 0$, then $\frac{1}{2}(\pi_k^{-1}(\hat{e}))^2$ is a $O(1/\sqrt{n})$ -consistent estimator for $I(X; Y)$.

Proof.

(i) Let $\{\iota_1, \dots\}$ be a collection of limiting points of $I(X^{[d]}; Y^{[d]})$. By Theorem 1, each of the corresponding subsequences has $e_{ABE,k}$ converging to $\pi_k(\sqrt{2\iota_i})$. However, by assumption A1', $e_{ABE,k}$ converges to η in all subsequences. Therefore,

$$\iota_1 = \iota_2 = \dots = \frac{1}{2}(\pi_k^{-1}(\eta))^2,$$

implying the corollary.

The proof of (ii) follows from continuity of probability, while the proof of (iii) follows from application of the delta method. \square

Corollary 1 therefore suggests methods for obtaining confidence intervals and point estimates for $I(X; Y)$. To get a confidence interval for $I(X; Y)$, first find a confidence interval for the average Bayes error $e_{ABE,k}$; then obtain the confidence interval for $I(X; Y)$ as

$$[\frac{1}{2}(\pi_k^{-1}(\bar{e}))^2, \frac{1}{2}(\pi_k^{-1}(\underline{e}))^2].$$

To obtain a point estimate for $I(X; Y)$, Corollary 1 suggests

$$\hat{I}(X; Y) = \frac{1}{2}(\pi_k^{-1}(\hat{e}))^2.$$

However, this procedure for obtaining point estimates can be easily seen to have suboptimal mean-squared risk in finite samples. Suppose that the estimator for average Bayes error has bias

$$\mathbf{E}[\hat{e}] - e_{ABC,k} = \mu$$

and variance

$$\text{Var}[\hat{e}] = \sigma^2,$$

and assume that μ is $O(1/\sqrt{n})$ while σ^2 is $O(1/n)$. Let $f(e) = \frac{1}{2}(\pi_k^{-1}(e))^2$. We know that

$$\lim_{e \rightarrow 0} f(e) = \infty,$$

and also that

$$\lim_{e \rightarrow 0} f'(e) = -\infty,$$

$$\lim_{e \rightarrow 0} f''(e) = \infty.$$

Meanwhile, from the delta method we have

$$\mathbf{E}[\hat{I}] = \mathbf{E}[f(\hat{e})] = I(X; Y) + \mu f'(e_{ABC,k}) + \frac{1}{2}\sigma^2 f''(e_{ABC,k}),$$

and

$$\text{Var}[\hat{I}] = \dots$$

[to be continued. Task: propose a better estimator in mean-squared error.]

4 Results

4.1 Simulation

Multiple-response logistic regression model

$$X \sim N(0, I_p)$$

$$Y \in \{0, 1\}^q$$

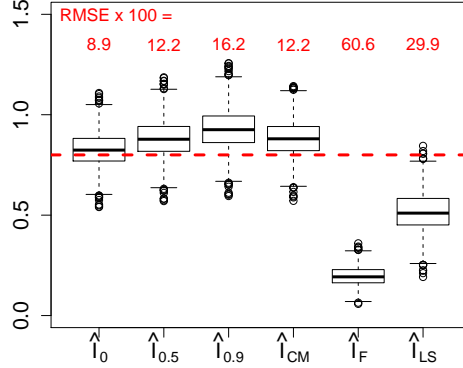
$$Y_i|X = x \sim \text{Bernoulli}(x^T B_i)$$

where B is a $p \times q$ matrix.

Methods.

- Nonparametric: \hat{I}_0 naive estimator, \hat{I}_α anthropic correction.
- ML-based: \hat{I}_{CM} confusion matrix, \hat{I}_F Fano, \hat{I}_{LS} low-SNR method.

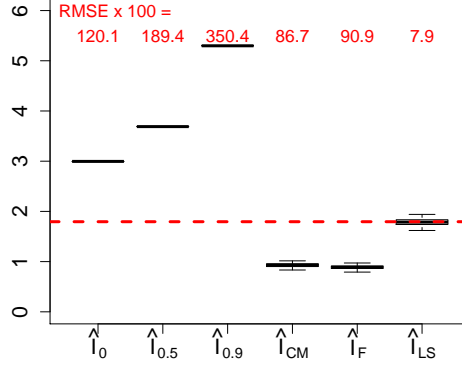
Sampling distribution of \hat{I} for $\{p = 3, B = \frac{4}{\sqrt{3}}I_3, K = 20, r = 40\}$.
True parameter $I(X; Y) = 0.800$ (*dotted line.*)



Naïve estimator performs best! \hat{I}_{LS} not effective.

Sampling distribution of \hat{I} for $\{p = 50, B = \frac{4}{\sqrt{50}}I_{50}, K = 20, r = 8000\}$.

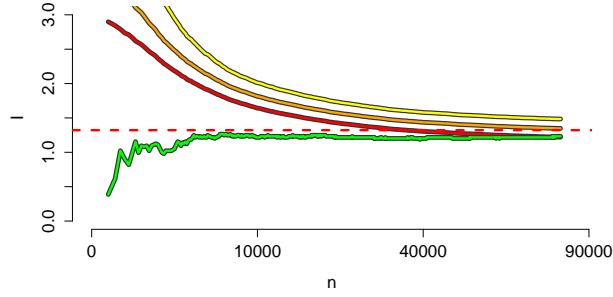
True parameter $I(X; Y) = 1.794$ (*dashed line.*)



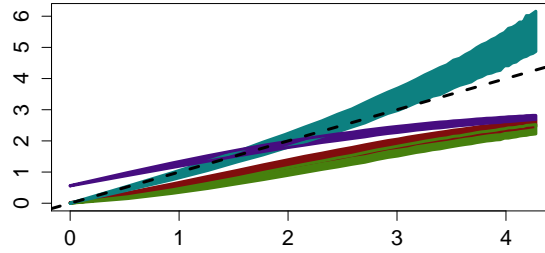
Non-parametric methods extremely biased.

Estimation path of \hat{I}_{LS} and \hat{I}_α as n ranges from 10 to 8000.

$\{p = 10, B = \frac{4}{\sqrt{10}}I_{10}, K = 20\}$. True parameter $I(X;Y) = 1.322$ (*dashed line.*)



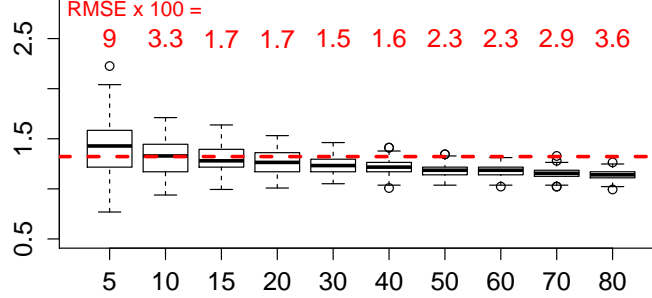
Estimated \hat{I} vs true I .



Sampling distribution of \hat{I}_{LS} for $\{p = 10, B = \frac{4}{\sqrt{10}}I_{10}, N = 80000\}$,

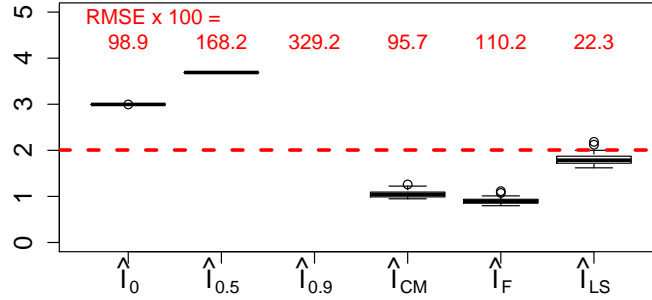
and $K = \{5, 10, 15, 20, \dots, 80\}, r = N/k$.

True parameter $I(X;Y) = 1.322$ (*dashed line.*)



Decreasing variance as K increases. Bias at large and small K .
 $p = 20$ and $q = 40$, entries of B are iid $N(0, 0.025)$.
 $K = 20$, $r = 8000$, true $I(X; Y) = 1.86$ (*dashed line.*)

Sampling distribution of \hat{I} .



4.2 Application to data

Kay et al. employed a randomized stimuli design in their 2008 paper, “Identifying Natural Images from Human Brain Activity.” The experiment was designed in order to investigate how visual information from natural images is encoded in the V1 through V3 brain regions. The stimulus space, \mathcal{X} , consists of 128×128 -pixel grayscale photographs. The response data consists of BOLD response in regions V1, V2, and V3 from a single subject. The raw time series were processed to yield a single averaged response vector $y^{(i)}$ for each stimulus $x^{(i)}$, for $i = 1, \dots, 1870$. The dimensionality of $y^{(i)}$ varies depending on which regions of interest we are discussing, and whether we consider a subset of the voxels in those regions. Let v denote the dimensionality (number of voxels) of y .

Let $x^{(i)}$ denote the native 128×128 -pixel representation of the image (i.e. a 16384-dimensional vector with entries between 0 and 1.) In the study, Kay et

al. parameterized the raw stimuli $x^{(i)}$ using a library of Gabor wavelet filters, g_1, \dots, g_{10921} , where each filter is a nonlinear mapping

$$g_j : \mathcal{X} \rightarrow \mathbb{R}.$$

Also let \vec{g} denote the vector-valued function

$$\vec{g}(x) = (g_1(x), \dots, g_{10921}(x)).$$

Using a *training* subset of the stimulus-response pairs (x_i, y_i) , $i = 1, \dots, 1750$, Kay et al. fit a regularized linear model

$$y^{(i)} \approx B^T \vec{g}(x^{(i)})$$

where B is a $10921 \times v$ -dimensional matrix, which is to be fit to the data. The resulting model is used to obtain predictions $\hat{y}^{(i)}$ for the remaining validation subset, $i = 1751, \dots, 1870$, by

$$\hat{y}^{(i)} = B^T \vec{g}(x^{(i)}).$$

Kay et al. introduced the novel idea of assessing the accuracy of these predictions using a *classification*-based metric, rather than a usual metric for prediction error such as mean-squared error. One treats the 120 validation stimuli $x_{1751}, \dots, x_{1870}$ as distinct classes. Next, for each $i = 1751, \dots, 1870$, one predicts the class of $y^{(i)}$, by correlating the observed $y^{(i)}$ with the predictions $\hat{y}^{(j)}$. In other words, let f be the mapping from the observed response to the predicted class: f is given by

$$f(y) = \operatorname{argmax}_{j=1751}^{1870} \operatorname{Cor}(y, \hat{y}^{(j)}).$$

The test error is

$$e_{\text{test}} = \frac{1}{120} \sum_{i=1751}^{1870} I(i \neq f(y^{(i)})).$$

While differing from a conventional classification task, the Kay et al. *identification* task can also be treated using our framework. An *identification rule* (as opposed to a classification rule) is defined by a function f which takes arguments $\{y, x^{(1)}, \dots, x^{(k)}\}$ where k can be any positive integer. The function f returns an integer from 1 to k ,

$$f(y, x^{(1)}, \dots, x^{(k)}) \in \{1, \dots, k\}.$$

The generalization error for the identification task is defined as

$$e_{\text{gen}}(f) = \Pr[f(Y, x^{(1)}, \dots, x^{(k)}) \neq i | Y \sim p(y|x^{(i)})].$$

5 Discussion

Since the Bayes error is the large-sample limit of the achieved classification error, a promising approach is to perform classification using differently sized subsamples of the training data, producing a plot of classification error versus sample size—a “learning curve.” One can then extrapolate the learning curve to estimate the Bayes error (Cortes et al. 1994.) However, much work remains to develop rigorous methodology for estimating Bayes error, and so we leave this first issue for future work.

We should keep in mind that the definition of mutual information depends on the specific class of stimulus that is of interest in the experiment. The Bayes error itself depends on the choices made by the experimenter in regards to the stimuli exemplar chosen in the experiment, and the decision of how to partition those exemplars in the classification task. For example, Nishimoto et al classified segments of a movie clips based on activation patterns, but the definition of the classification task, and the achievable classification performance, depends not only on the particular movie clips used in the experiment, but also the choice of time interval used to define discrete classes: defining each class to be a 1sec segment of movie results in more distinct classes and lower classification accuracy than defining each class to be a 4sec segment of movie. The Bayes error, and any estimate of mutual information based on the Bayes error, would therefore be necessarily dependent on the experimental parameters.

Estimating e_{Bayes} is much more difficult in practice than estimating e_{gen} ; however, nonparametric estimators of e_{Bayes} have been proposed in the literature. Cover (1969) first noted that the leave-one-out error of 1-nearest neighbor, e_{1nn} , asymptotically bounds the Bayes error in the sense that

$$\frac{1}{2}\mathbf{E}[e_{1nn}] \leq e_{Bayes} \leq \mathbf{E}[e_{1nn}].$$

Later, Fukunaga and Kessel (1971) and Fralick and Scott (1971) both proposed a consistent estimator of e_{Bayes} using the test error from kernel density estimation-based classifiers. Fukunaga and Hostetler 1975 improved on the density estimation approach by estimating the generalization error directly, rather than using empirical test error (hence reducing variance.)

Nevertheless, the convergence rates of nonparametric methods of Bayes risk estimation are too slow to provide much assurance for their use in high-dimensional problems. On the other hand, the empirical success of supervised learning approaches seems to justify a certain optimism that at least one of the popular black-box methods (random forests, neural networks, kernel SVM) can come close to the Bayes error rate within realistic sample sizes. Methods such as random forests and neural networks are known to have *universal approximation* properties

that guarantee consistent recovery of the classification rule, given that the model complexity is scaled at an appropriate rate as the sample size increases; but methods such as kernel SVM have much more restrictive function classes and therefore have no guarantee of being able to recover the Bayes error. Yet, it is seen in many learning tasks that the test error is very similar for very different classification methods, some universal and some non-universal, suggesting that the true signal lies in a low-complexity function class which can be adequately approximated using a variety of methods. Empirical evidence for these phenomenon are collected in studies on the learning curves of classifiers, beginning with Cortes 1994, and applied to specific applications by Figueroa et al. 2012, Beleites et al. 2013. We leave further discussion of Bayes error estimation for future work; in the theoretical portion of the current paper, we will simply leave unspecified the method used to estimate Bayes error, and in our simulation and real data examples, we will use an ad hoc approach for estimating Bayes error from test error for the purpose of demonstrating our method.

6 Conclusions

- We derive a relationship between average Bayes error (ABE) and mutual information (MI), motivating a novel estimator \hat{I}_{LS} .
- Theory based on high dimensional, low SNR limit, where

$$\text{ABE} \leftrightarrow \text{MI}.$$

- In ideal settings for supervised learning, ABE can be estimated effectively and \hat{I}_{LS} can recover MI at much lower sample sizes than nonparametric methods.
- In simulations, \hat{I}_{LS} works better than Fano’s inequality or the confusion matrix approach.

7 References

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