Estimating mutual information for high-dimensional sparse relationships

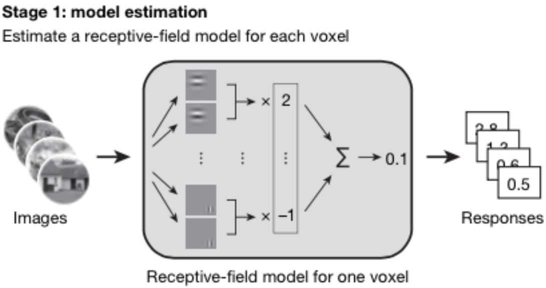
Charles Zheng

Stanford University

January 23, 2017

(Joint work with Yuval Benjamini, Hebrew University.)

Introduction



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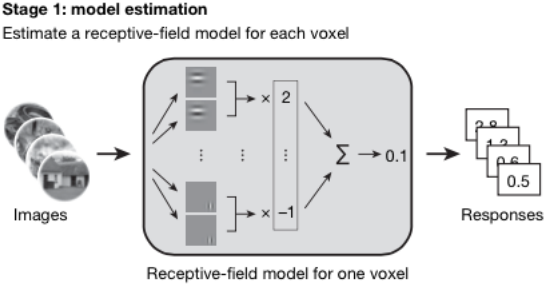
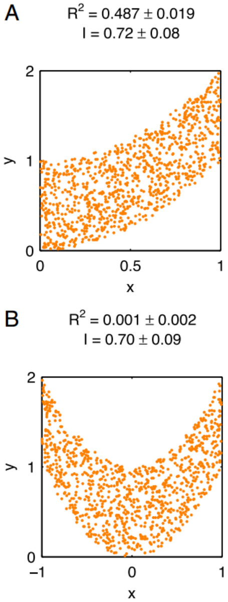


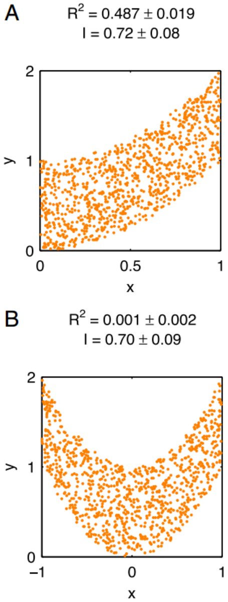
- Much of my work has been inspired by use of machine learning in encoding/decoding models in fMRI (Kay et al. 2008, Nishimoto et al. 2011)
- E.g.: Extrapolating classification accuracy curves (Z., Achanta, and Benjamini 2016)



Mutual information $I(\vec{X}; \vec{Y})$

- measures dependence between two random vectors, $\vec{X}$ and $\vec{Y}$

This talk



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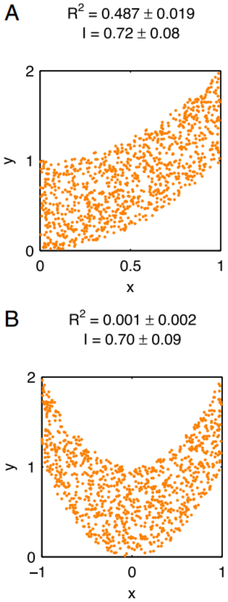

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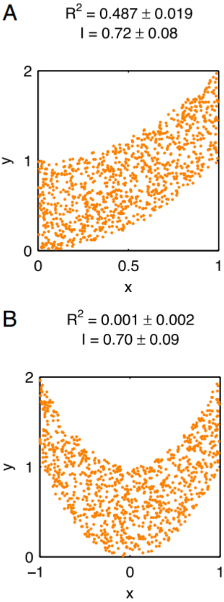

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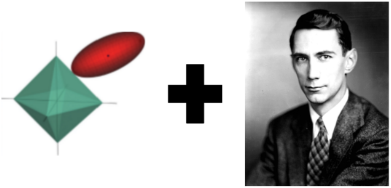
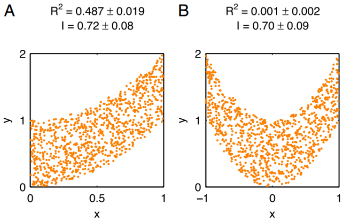
We combine *machine learning* (sparse estimation) with *information theory* to obtain better estimates of $I(\vec{X}; \vec{Y})$



Mutual information $I(X;Y)$



Introduced in Shannon's 1948 paper, "A mathematical theory of communication"

$$I(X;Y) = \int \log\left(\frac{p(x,y)}{p(x)p(y)}\right) p(x,y)dxdy$$

Image credit Kinney et al. 2014.

Applications of $I(X; Y)$

Mutual information has since been applied to many areas outside of information theory

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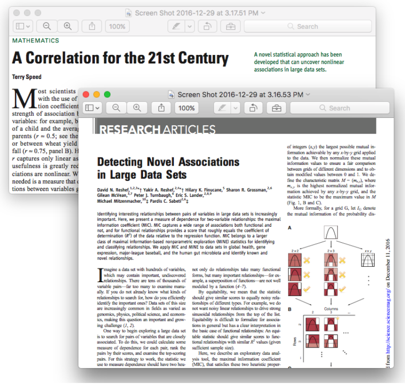
Applications [edit]

In many applications, one wants to maximize mutual information (thus

- In search engine technology, mutual information between phrases
- In telecommunications, the channel capacity is equal to the mutua
- Discriminative training procedures for hidden Markov models have
- RNA secondary structure prediction from a multiple sequence alig
- Phylogenetic profiling prediction from pairwise present and disapp
- Mutual information has been used as a criterion for feature selecti the minimum redundancy feature selection.
- Mutual information is used in determining the similarity of two diffe
- Mutual information of words is often used as a significance functio words; rather, one counts instances where 2 words occur adjacen another, goes up with N.
- Mutual information is used in medical imaging for image registratic reference image, this image is deformed until the mutual informati
- Detection of phase synchronization in time series analysis
- In the infomax method for neural-net and other machine learning,

Engineering, biology, computer science, physics, medicine

Comparing $I(X;Y)$ with Pearson correlation



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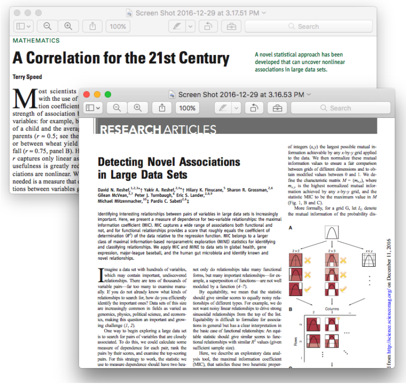

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- Only mutual information (and derived quantities) measures dependence directly

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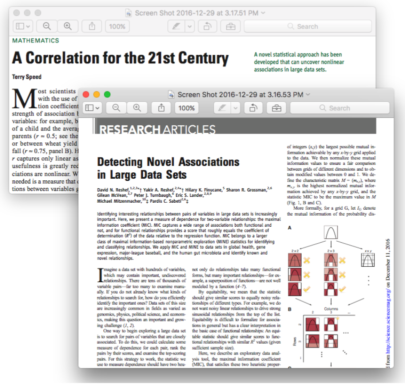

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How to estimate $I(X;Y)$

Suppose we observe pairs $(X_i, Y_i)_{i=1}^n$ iid from density $p(x, y)$

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- Kernel density estimate approaches estimate $p(x,y)$ (Beirlant et al. 2001, Ivanov and Rozhkova 1981)
- Nearest neighbor estimators rely on distance-based computations (Mnatsakanov et al. 2008, Goria et al. 2005, Singh et. al. 2003)

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Suppose we observe pairs $(X_i, Y_i)_{i=1}^n$ iid from density $p(x,y)$

- **Plug-in estimate**:

$$\hat{I}(X;Y) = \int \log\left(\frac{\hat{p}(x,y)}{\hat{p}(x)\hat{p}(y)}\right)\hat{p}(x,y)dxdy$$

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Problems in high dimensions

- Density estimation is known to have *exponential complexity* with respect to dimensionality.
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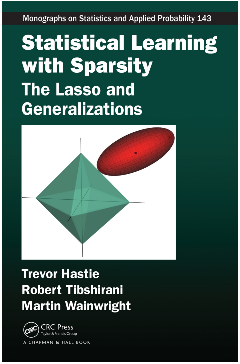
- One approach is to assume joint multivariate normality of X, Y, but this reduces mutual information to a linear statistic.
- Other approaches: binning (Bialek et al. 1991, Paninski 2003), confusion matrix of a classifier (Treves 1997, Quiroga et al. 2009)

New idea: Use sparsity!



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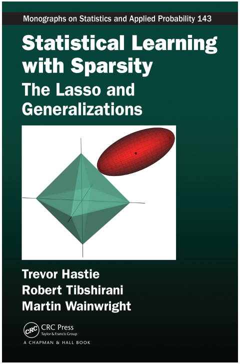

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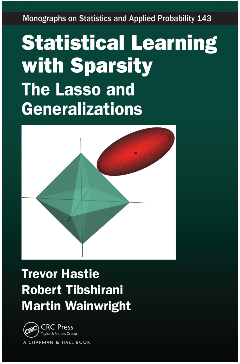


- *Sparsity* refers to existence of low-dimensional structure hidden in high-dimensional data.
- E.g. suppose X is 100-dimensional but Y is only a function of (X_5, X_9).
- Can we exploit sparsity to obtain a good estimate of $I(X; Y)$ even under low sample sizes?

Our proposal

Suppose we observe pairs $(X_i, Y_i)_{i=1}^n$ iid from density $p(x, y)$.

1. Estimate a (sparse) regression model for $\mathbf{E}[\vec{Y}|\vec{X}]$.
2. Assess the *prediction accuracy* of the model using *identification risk*
3. Use the identification risk to obtain a lower bound for the mutual information $I(X; Y)$

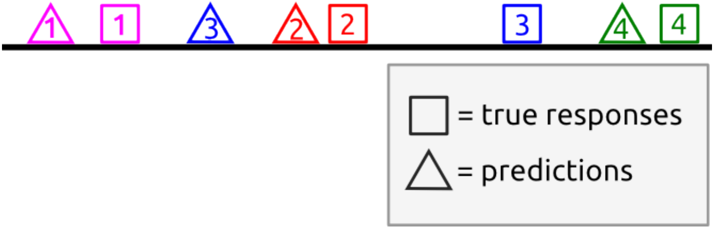
Multiple-response regression

- Pairs $(x_i, y_i)_{i=1}^n$, where X is p-dimensional and Y is q-dimensional.
- Data matrices $\boldsymbol{X}_{n\times p}$, $\boldsymbol{Y}_{n\times q}$.
- For each column of Y, fit sparse model $Y^{(i)} \approx X^T\beta^{(i)} + \epsilon$, e.g. by using elastic net (Zou 2008),

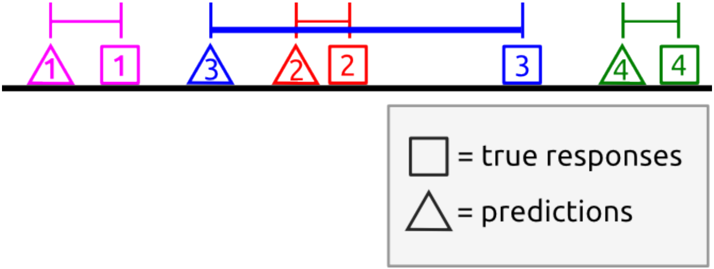
$$\hat{\beta}^{(i)} = \text{argmin}_\beta ||\boldsymbol{X}^T\beta^{(i)} - Y^{(i)}||^2 + \lambda_2||\beta^{(i)}||_2^2 + \lambda_1||\beta^{(i)}||_1$$

- Or, fit a *random forest* model for each column of Y (Breiman 2001)

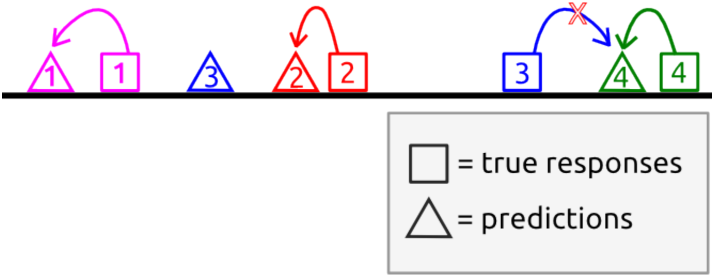
Regression vs Identification loss



Mean-squared error



Identification loss



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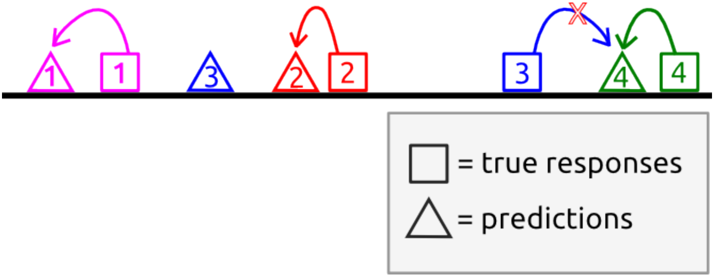

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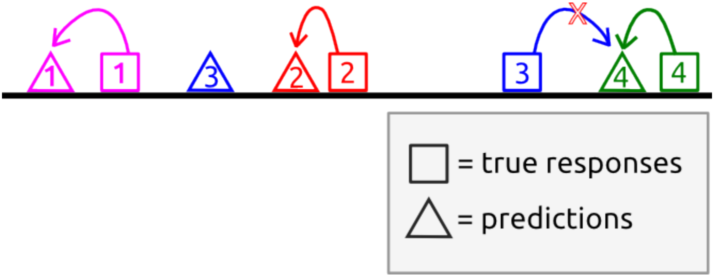


- First used by Kay et al. (2008) to compare accuracy of center-surround model of V1 versus Gabor filter model of V1.
- We are the first to explore theoretical properties of the loss (e.g. connection to mutual information)

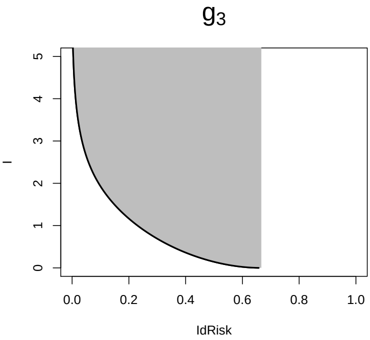
Identification loss and mutual information

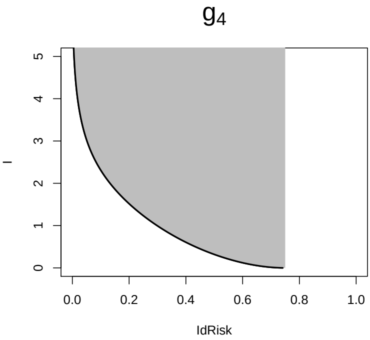
- Define the identification risk as the expected identification loss

$$\text{IdRisk}_k = \mathbf{E}[\text{IdLoss}_k]$$

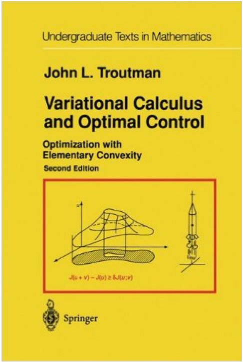
- **Theorem.** (Z., Benjamini 2017) There exists a function g_k such that

$$I(X;Y) \geq g_k(\text{IdRisk}_k).$$

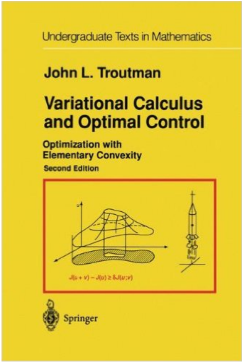




Proof details



- Variational calculus allows optimization of *functionals*.



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- Mutual information is a functional of $p(x, y)$.

$$\mathrm{I}[p(x,y)] = \mathbf{E}\left[\log \frac{p(X,Y)}{p(X)p(Y)}\right].$$

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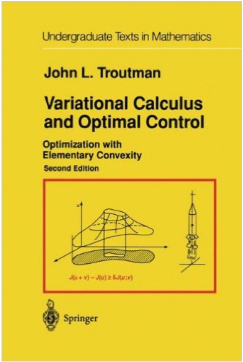

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- Identification risk is *lower-bounded* by another functional–the *Bayes risk*.

$$\text{BayesRisk}_k[p(x, y)] = 1 - \mathbf{E}[\max_{i=1}^{k} p(Y|X_i)].$$

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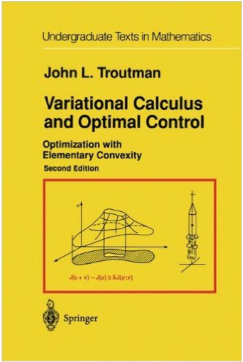

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$$\text{BayesRisk}_k[p(x,y)] = 1 - \mathbf{E}[\max_{i=1}^{k} p(Y|X_i)].$$

- $g_k(u)$ obtained by minimizing $\mathrm{I}[p(x,y)]$ subject to $\text{BayesRisk}_k[p(x,y)] \leq u$.

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1. Estimate a (sparse) regression model for $\mathbf{E}[\vec{Y}|\vec{X}]$.
2. Compute *identification loss*, IdLoss_k, using *leave-k-out*.
3. Estimate mutual information using

$$\hat{I}_{IdLoss}(X; Y) = g_k(\text{IdLoss}_k).$$

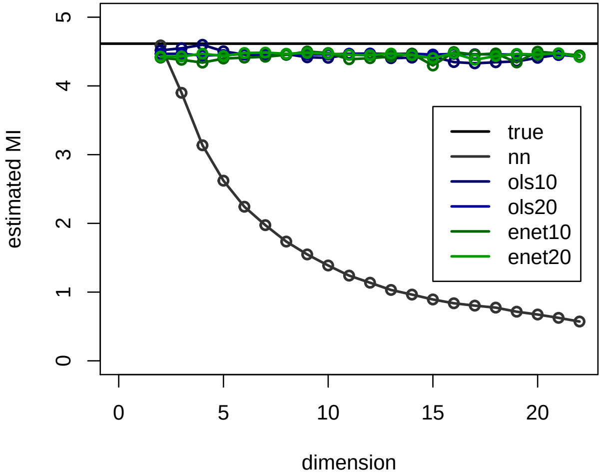
Section 2

Applications

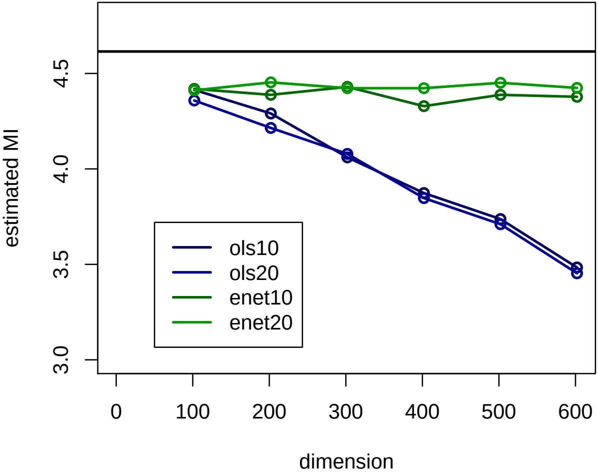
Simulation

- Generate data: $(Y_1, Y_2) = (X_1, X_2)^T B + \epsilon$ where B is a randomly generated coefficient matrix.
- Add extra noise dimensions $X_3, X_4, \ldots$.
- $n = 1000$.
- Compare Nearest-Neighbor estimator (Mnatsakov et al, 2008, implemented in `FNN`) with our method using OLS and elastic net (sparse).

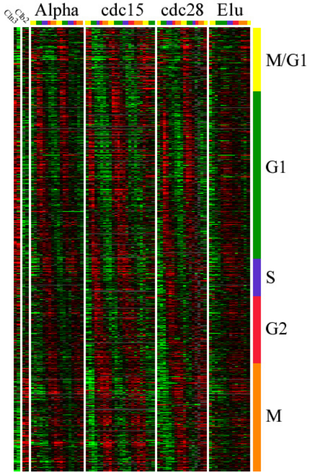
Simulation Results - I. low dimension



Simulation Results - III. high dimension



Application to gene expression time series



- Data from Spellman et al. 1998
- Expression levels of 6178 yeast genes during cell cycle
- Total 73 time points per gene

Groups of genes

Group	No. genes
unknown	396
cell cycle	27
DNA replication	27
transport	19
cytoskeleton	17
chromatin structure	16

Total 145 different categories (only top 6 shown).

Canonical correlations between time series

Top canonical correlation (Hotelling 1936)

	CC	DR	Tr	Cy	CS
CC		1	1	1	1
DR			1	0.99	0.99
Tr				0.99	0.98
Cy					0.98
CS					

CC = cell cycle, DR = DNA replication, Tr = transport,
Cy = cytoskeleton, CS = chromatin structure

Sparse canonical correlations between time series

Using sparse CCA* (Witten and Tibshirani 2009).

	CC	DR	Tr	Cy	CS
CC		0.96	0.87	0.92	0.94
DR			0.83	0.88	0.95
Tr				0.83	0.78
Cy					0.90
CS					

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*: using `CCApermute` in R package `PMA`

Information correlations between time series

Taking the max of $\hat{I}(X;Y)$ and $\hat{I}(Y;X)$.

	CC	DR	Tr	Cy	CS
CC		0.93	0.78	0.98	0.83
DR			0.85	0.91	0.92
Tr				0.72	0.71
Cy					0.93
CS					

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Invariance properties

- Transform data from each group with random rotation...

$$b\tilde{X} = \boldsymbol{X}E$$

$$b\tilde{Y} = \boldsymbol{X}F$$

with $E^T E = I$, $F^T F = I$.

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$$\text{CCA}(\boldsymbol{X}, \boldsymbol{Y}) = \text{CCA}(\tilde{bX}, \tilde{bY})$$

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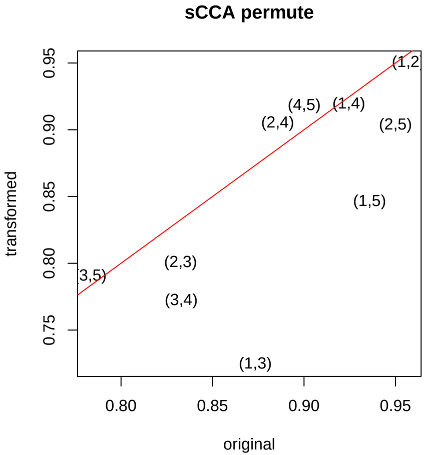
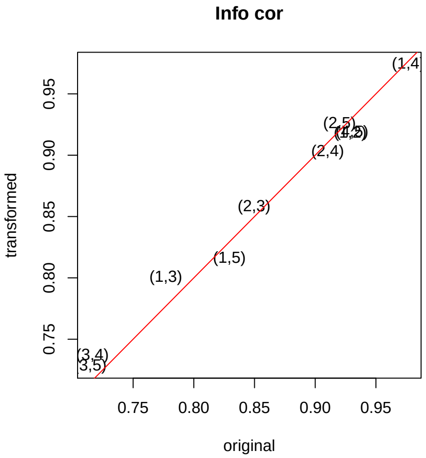
However, sparse CCA is not invariant.



Invariance properties

Our method, on the other hand, is *robust* to rotation.



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- Example application: measure of joint information between two tables which is robust to transformations.

Related work and future directions

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- Estimating quantities related to mutual information, such as *transfer information*, *stimulus-specific information* and *redundancy* (Borst and Theunissen 1999)

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- Estimating quantities related to mutual information, such as *transfer information*, *stimulus-specific information* and *redundancy* (Borst and Theunissen 1999)
- Inferring resting-state brain networks.

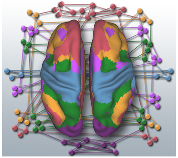

Image credit Simons Foundation

Section 3

The End

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