1 Stokes flow in a triply periodic domain

We want to solve the Stokes equations,

$$\eta \nabla^2 \boldsymbol{u} - \nabla p = -\boldsymbol{f},\tag{1.1}$$

$$\nabla \cdot \boldsymbol{u} = 0, \tag{1.2}$$

on a periodic domain $\Omega := (x, y, z) \in [0, L_x] \times [0, L_y] \times [0, L_z]$ subject to periodic boundary conditions. Here, the velocity $\mathbf{u} = \begin{pmatrix} u & v & w \end{pmatrix}^T$, and $\mathbf{f} = \begin{pmatrix} f & g & h \end{pmatrix}^T$ are smeared δ -function sources representing particles with an effective hydrodynamic radius of R_h . Taking the divergence of Eq. 1.1 and using Eq. 1.2, we find the pressure p satisfies a Poisson equation

$$\nabla^2 p = -\nabla \cdot \mathbf{f} \tag{1.3}$$

Then, taking the Fourier transform of Eq. 1.3 and using Fourier derivative symbols, we find

$$\hat{p} = -\frac{i\mathbf{k} \cdot \hat{\mathbf{f}}}{k^2},\tag{1.4}$$

where $\mathbf{k} = \begin{pmatrix} k_x & k_y & k_z \end{pmatrix}^T$ is the vector of wave numbers in x, y and $z, k^2 = ||\mathbf{k}||^2$, and $\hat{\cdot}$ denotes the Fourier transform. Now, if take the Fourier transform of Eq. 1.1 and use Eq. 1.4, we find that

$$\hat{u} = \frac{1}{\eta k^2} \left(\hat{f} + \frac{ik_x}{k^2} \left(ik_x \hat{f} + ik_y \hat{g} + ik_z \hat{h} \right) \right), \tag{1.5}$$

$$\hat{v} = \frac{1}{nk^2} \left(\hat{g} + \frac{ik_y}{k^2} \left(ik_x \hat{f} + ik_y \hat{g} + ik_z \hat{h} \right) \right), \tag{1.6}$$

$$\hat{w} = \frac{1}{nk^2} \left(\hat{h} + \frac{ik_z}{k^2} \left(ik_x \hat{f} + ik_y \hat{g} + ik_z \hat{h} \right) \right). \tag{1.7}$$

The above equations hold for $k \neq 0$. Since the net force on the unit cell must be 0, we accept 0 as the solution for the k = 0 mode of the fluid velocity.

In our uniform discretization, $k_i = \frac{2\pi j}{L_i}$, $j = -\frac{N_i}{2}, \dots, \frac{N_i}{2} - 1$, with N_i the number of points in direction i = x, y, z, and L_i the length. The source term \boldsymbol{f} consists of monopole and dipole terms with "exponential of a semicircle" (ES) kernel [1] envelopes Δ ;

$$\Delta(z; \alpha, \beta) = \frac{1}{\int_{-\alpha}^{\alpha} e^{\beta(\sqrt{1 - (\frac{z}{\alpha})^2} - 1)} dz} \begin{cases} e^{\beta(\sqrt{1 - (\frac{z}{\alpha})^2} - 1)}, & |\frac{z}{\alpha}| \le 1\\ 0, & \text{otherwise.} \end{cases}$$
(1.8)

Here, $\alpha = w_i h_i/2$, where h_i is the grid spacing in direction i, w_i is the number of points to which we spread in that direction, and we've normalized the kernel so that integrating it over its support gives 1. The monopole term Δ_f represents the force exerted by particles on the fluid, while Δ_{τ} relates to external torques τ on the particles, given in [2] as

$$f(x) = \sum_{k=1}^{M} f(y_k) \Delta_f(x - y_k) + \frac{1}{2} \nabla \times (\tau(y_k) \Delta_\tau(x - y_k)), \qquad (1.9)$$

where y_k is the position of particle k. Once we've solved for the fluid velocity u, we can obtain the linear and angular velocities of the particles through

$$V(x) = \int_{\Omega} u(y) \Delta_f(y - x) dy = J_f U, \qquad (1.10)$$

$$\mathbf{\Omega}(\mathbf{x}) = \frac{1}{2} \int_{\Omega} (\nabla \times \mathbf{u}(\mathbf{y})) \Delta_{\tau}(\mathbf{y} - \mathbf{x}) d\mathbf{y} = \frac{1}{2} \mathbf{J}_{\tau}(\nabla \times \mathbf{U}). \tag{1.11}$$

1.1 Validation (translation-only)

Here, we will validate the efficacy of our method and implementation in computing particle velocities against Hasimoto's correction to Stokes drag law for cubic lattices of spheres [3], given by

$$\frac{F}{\eta V} = \frac{6\pi R_h}{1 - 2.8373(R_h/L) + 4.19(R_h/L)^3 - 27.4(R_h/L)^6 + \text{h.o.t}},$$
(1.12)

where F is the force on the particle and V is its velocity in one direction. We place a force of $\begin{pmatrix} 1 & 0 & 0 \end{pmatrix}$ on a particle of radius $R_h = 1.5539$ (this corresponds to ES kernel settings $w = 6, \beta = 1.714, h = 1$) located randomly in the unit cell $[0, L]^3$. After spreading the force on the particle to the grid with the first term in Eq. 1.9, solving Eq. 1.1 and interpolating the velocity on the particles with Eq. 1.10, we evaluate agreement with Eq. 1.12. The results, collected over several random placements of the particle and lattice lengths, are shown in the following figure.

2 A note on memory layout

Data on the grid are stored so that the fastest index is $l=0,\cdots, \text{dof}$, followed by $i=0,\cdots, N_x$, then $j=0,\cdots,N_y$, and with $k=0,\cdots,N_z$ the slowest. This means that the Grid member fG is such that fG(k,j,i,l) = fG[1 + dof * (i + Nx * (j + Ny * k))]. The reason for this has to do with parallelization and vectorization in the underlying spreading algorithm, where it's better if x and y vary faster than z. However, this isn't necessarily true for the solve stage.

In the Python interface, when we execute

the returned variable fG has been marshalled into a flat numpy array. If it makes sense (based on the solver) to copy the memory layout to a new one, say in reverse order, one can use

Then, the fG variable will be indexed in memory like fG[1,i,j,k] with k the fastest index.

References

- [1] Alex H. Barnett, Jeremy F. Magland, and Ludvig af Klinteberg. A parallel non-uniform fast fourier transform library based on an "exponential of semicircle" kernel, 2018.
- [2] Sune Lomholt and Martin Maxey. Force-coupling method for particulate two-phase flow: Stokes flow. *Journal of Computational Physics*, 184:381–405, 01 2003.
- [3] H. Hasimoto. On the periodic fundamental solutions of the stokes equations and their application to viscous flow past a cubic array of spheres. *Journal of Fluid Mechanics*, 5(2):317328, 1959.