

## Homework 2: Due at class on March 18

1. Show that an open ball  $B_n = \{x \in \mathbb{R}^n \mid |x| < 1\}$  is diffeomorphic to  $\mathbb{R}^n$  by constructing a smooth bijection map.
2. Let  $(x, y)$  be the Cartesian coordinate of  $\mathbb{R}^2$  and  $(r, \theta)$  be the polar coordinate of  $\mathbb{R}^2$ . Write a vector field  $X$  in terms of the Cartesian coordinate that generate a flow  $\varphi_t : \mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} .$$

This is the rotation in  $\mathbb{R}^2$ . In addition, draw the schematic picture of the vector field  $X$ .

3. Write down vector fields that generate the rotation along  $x$ -,  $y$ -,  $z$ -axis in  $\mathbb{R}^3$ . Find the commutation relations of these vector fields. Compare the theory of angular momenta in quantum mechanics.
4. Let  $e$  be the identity element of  $SO(3)$ . Show that the tangent space  $T_e SO(3)$  at  $e$  is spanned by tangent vectors of curves in  $SO(3)$

$$\exp(tJ_i) = 1 + tJ_i + \frac{1}{2}(tJ_i)^2 + \dots$$

at  $t = 0$  where  $J_i$  ( $i = x, y, z$ ) are defined by

$$J_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad J_y = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{pmatrix} \quad J_z = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} .$$

Let us define the commutator by  $[X, Y] = XY - YX$ . Then, show that

$$[J_x, J_y] = J_z, \quad [J_y, J_z] = J_x, \quad [J_z, J_x] = J_y .$$

5. Show that the tangent space  $T_e SU(2)$  is spanned by  $i\sigma_x, i\sigma_y$  and  $i\sigma_z$  (the Pauli matrices by  $i$ ).
6. Show that  $\mathbb{R}P^n$  is non-orientable for even  $n$ . In addition, construct an example of unorientable manifolds except the Möbius strip and even-dimensional real projective space.