view_frames Result

Recorded at time: 1503375655.758

world

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

table

camera_frame

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

base

shoulder_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

upper_arm_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

forearm_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

wrist_1_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

wrist_2_link

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1503375655.682 (0.076 sec old)
Buffer length: 4.900 sec

wrist_3_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1503375655.758 sec old)
Buffer length: 0.000 sec

ee_link

tool0