

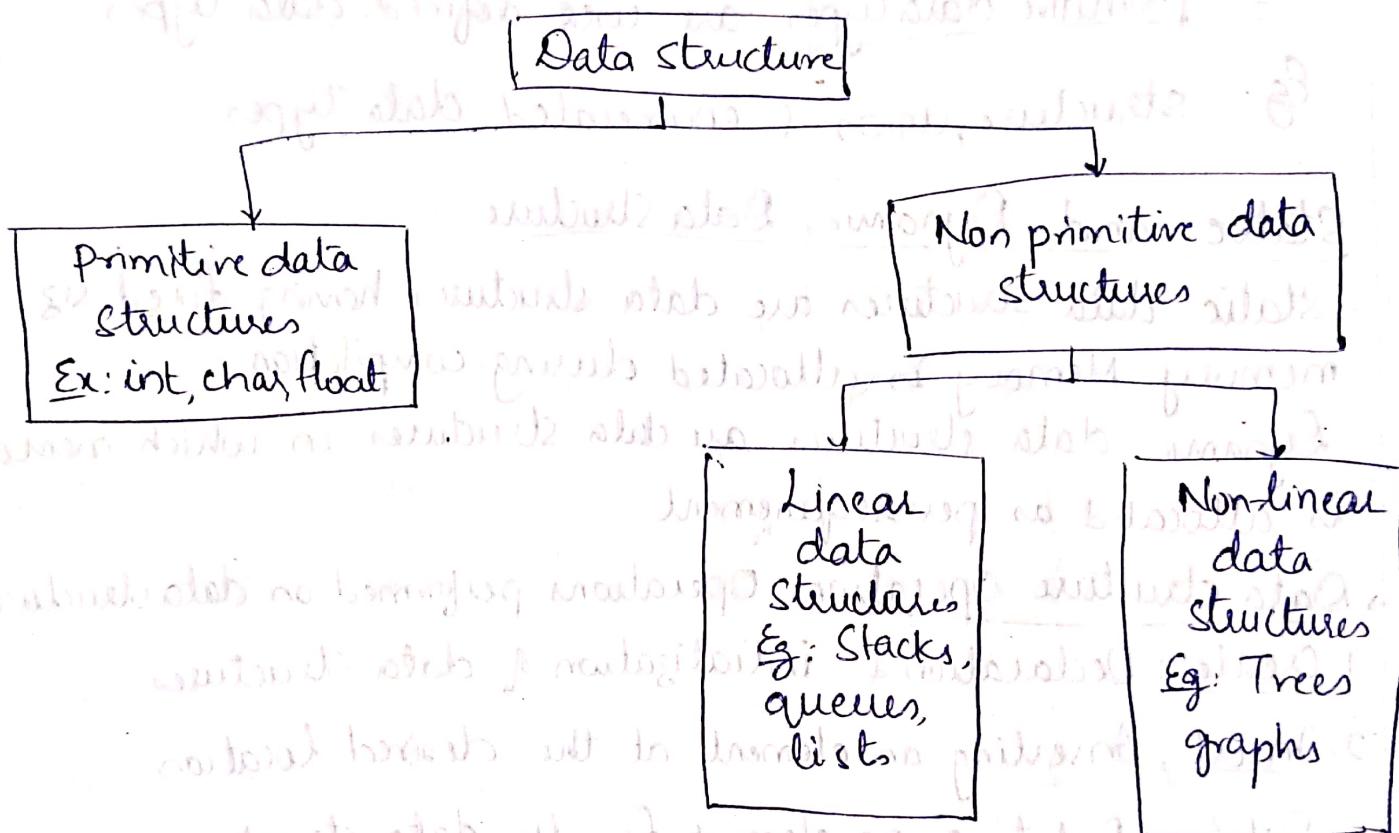
MODULE - 1

Introduction

Data Structure is a collection of set of elements and various operations that can be performed on these elements.

→ Classification of Data Structures

Data structures can be divided into 2 basic types as shown below



- Linear data structures are the data structures in which data is arranged in a list or in a straight sequence.
Eg. Arrays, lists.
- Non-linear data structures are those in which data may be arranged in hierarchical manner.
Eg: Trees, graphs.

Primitive and Non primitive data structures

- Primitive data types are the fundamental data types.
 - The non primitive data types can be built using primitive data types
- Eg: int, float, double, char

Non-primitive data-types are user defined data types

Eg: structure, union & enumerated data types.

Static and Dynamic Data Structure

Static data structures are data structures having fixed size memory. Memory is allocated during compilation

Dynamic data structures are data structures in which memory is allocated as per requirement

Data structure Operations: Operations performed on data structures

1. Create: Declaration & initialization of data structures
2. Insert: Inserting an element at the desired location
3. Delete: Deleting an element from the data structure
4. Searching: Searching of a key element from the data structure means finding the location of key element.
5. Sorting: Arranging the elements in a specific order (ascending or descending)
6. Reversing: Changing the order of data structure
7. Merging: Combining 2 data structures together to form a single data structure.
8. Traversal: Visiting each element of the data structure

Data Structures: Data structure is the organization of data in primary memory.

Types: stacks

queues

trees

Linked Lists

Pointers and Dynamic Memory Allocation

Pointers

A pointer is an address of memory as well.

Two operators used with the pointers are & and *

& the address operator

→ the dereferencing operator (value at the address)

A variable which holds the address of another variable or a memory location is called a pointer variable.

Declarations

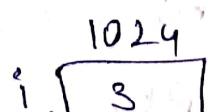
```
int i,*pi;
```

i is an integer variable

pi is a pointer variable

Initialization

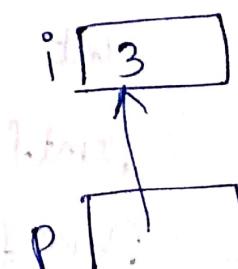
```
i=3;
```



```
pi=&i;
```



(or)



Pi holds the address of variable i.

Data can be accessed using pointer variable with the use of '*' operator.

for eg.:

```
int *pa;
```

```
int a=10;
```

```
pa = &a;
```

```
printf ("%d %d \n", *pa, a); output: 10 10
```

Here a or *pa or *&a refers to the data 10

stored using variable a at the base address.

Operations on pointers

1) Arithmetic operations such as addition, subtraction, multiplication and division can be performed using pointers.

Eg: #include <stdio.h>

```
void main()
```

```
{ int a=10, b=20;
```

```
int *pa=&a, *pb=&b;
```

```
int x = *pa + *pb;
```

```
int y = *pa - *pb;
```

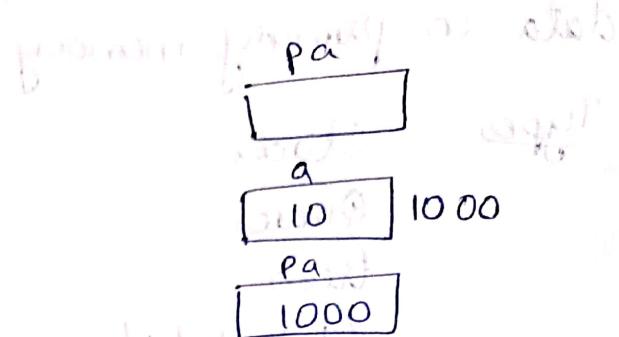
```
int z = *pa * *pb; i.
```

```
printf ("%d %d \n", *pa, *pb, x);
```

```
printf ("%d - %d \n", *pa, *pb, y);
```

```
printf ("%d * %d \n", *pa, *pb, z);
```

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The output for the above program is

$$10 + 20 = 30$$

$$10 - 20 = -10$$

$$10 * 20 = 200$$

2) Two pointers can be compared

If pa & pb are 2 pointers

$pa < pb$, $pa > pb$, $pa == pb$, $pa != pb$ are allowed

3) Copying 1 pointer to another pointer is allowed.

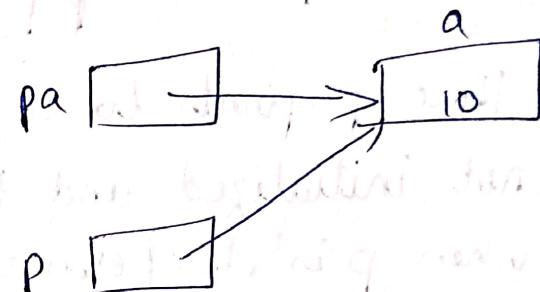
Eg:

`int a = 10;`

`int *pa = &a;`

`int *p;`

`p = pa;`



NULL pointer is a special pointer that points to '0' (nowhere) in memory.

`int *p; p = NULL;`

`P [NULL]`

NULL pointer variable does not point to any part of the memory.

Pointers can be dangerous

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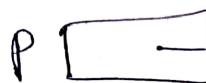
If a pointer is not initialized to NULL or any other legitimate object, it is likely to access an area of memory that is out of range of our program or it may contain a pointer reference to an illegitimate object.

- This may lead to serious errors.

Eg: int *p;
int a = 10;
p = &a;

printf("%d", *p); // Output = 10

printf("%d", *(p-1)); // accessing memory which
is out of range

Eg: int *p; p  JUNK address

Here p points to an invalid address as it is not initialized and this may crash the program when p is dereferenced.

- Dereferencing a NULL pointer may return 0 in some computers or may return data in location 0 producing serious errors.

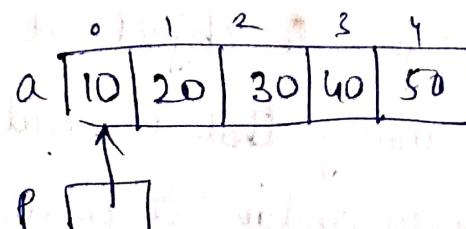
Pointers to Arrays Size of int and size of pointer are same. A valid integer may be interpreted as a pointer, causing errors.

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- Pointers can be used to hold the address of an array element and the complete array elements can be accessed using pointer

- int a[5] = {10, 20, 30, 40, 50};
int *p;

p = a; // or p = &a[0]



`printf("%d", *p); // Output: 10`

`P = p + 3; // P = &a[3]`

`printf("%d", *p); // Output: 40`

`P--;`

`printf("%d", *p); // Output: 30`

`p = &a[4];`

`printf("%d", *p); // Output: 50`

Good understanding

- In the above example `p=a`; stores the address of the first element in the array a in p ie `&a[0]`.

`*p` displays the value at the address pointed by p ie, 10

- `P` value is then changed to `p=p+3` (and hence it points to the element 3 spaces to the right of the current position, ie, p has the value `&a[3]`)

- decrementing p points it to the previous location.

- `p = &a[u]` assigns the address of `a[u]` to p.

Memory allocation

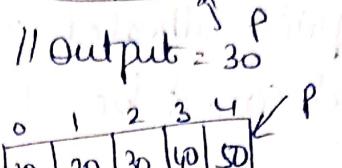
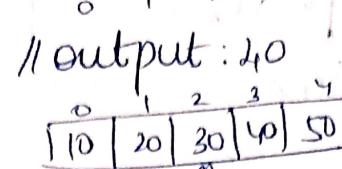
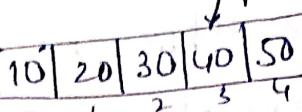
Memory Allocation

Techniques

Static allocation

Dynamic allocation

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Static Allocation

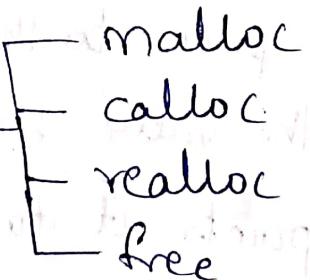
- 1) Memory is allocated during compilation i.e., compile time.
- 2) Memory space allocated is fixed and cannot be altered.
- 3) Eg. User declarations and definitions
Eg: int a;

Dynamic Allocation

- 1) Memory is allocated during execution i.e., run time.
- 2) Memory allocated can be increased or reduced during execution.
- 3) Memory allocated using predefined functions like malloc(), calloc(), realloc() and free().

Dynamic Memory Allocation is the process of allocating memory space during execution time (i.e., runtime).

Functions



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- 1) malloc: Allocates memory of required size.

Syntax: datatype * p;

P = (datatype *) malloc (size);

p is a pointer variable of type datatype.

datatype can be int, float, char, void or user defined.

Size - number of bytes to be allocated.
malloc function returns the first byte of allocated space if memory is allocated successfully else it returns NULL. malloc does not initialize the memory.

2) calloc

Syntax datatype *p;
 $p = (\text{datatype} *) \text{calloc}(n, \text{size});$

n - number of blocks to be allocated

size - number of bytes in each block

calloc allocates n blocks of memory where each block is of specified size. calloc initializes the memory allocated to 0s. ~~to set the size of~~

3) realloc

realloc changes the size of the memory allocated using malloc() or calloc()

realloc can extend or delete the allocated memory at the end of the block.

P points to a block of previously allocated memory either using malloc() or calloc()

size - new size of block.

free

free(.) function is used to deallocate the block of memory which is allocated by using the function malloc(.) or calloc(.)

free(p);

P pointer to memory block previously allocated
Macro to allocate memory for one or more items of any datatype using malloc

```
#define MALLOC(p,n,type)
```

```
p=(type*)malloc(n*sizeof(type));
```

```
if(p==NULL)
```

```
{ printf("Insufficient memory\n");
```

```
exit(0);
```

```
y
```

Array

- An array is a consecutive set of memory locations. It is a set of pairs <index, value> such that each index that is defined has a value associated with it.
- An array is a series of entities or a sequence of entities of the same type
- An array is a data structure

An array of integers

10 20 30 40 50

An array of real numbers

35.6 20.8 50.7 63.5 80.2 11.12

An array of characters

Hello world

- To store an array of integers in memory, we have to first create an array and store the integers in that array. as shown below

int a[6] = {33, 46, 82, -50, 40, 7};

- The above declaration int a[6] allocates 6 blocks of memory and stores the integers in those blocks.
- It is diagrammatically represented as

33	46	82	-50	40	7
a(0)	a(1)	a(2)	a(3)	a(4)	a(5)

Array size = number of blocks * size of each block

$$= 6 * 2$$

$$= 12 \text{ bytes}$$

An array can be initialized directly as shown above or using a forloop

Always in C

array declaration

datatype name[size];

Eg: int list[5], *plist[5];

declares 2 arrays each containing 5 elements.

- The first array defines five integers
- Second array defines five pointers to integers.
- Arrays start at index 0. list[0], list[1], ... list[4] are the names of the five array elements, each of which contains an integer value
- The compiler allocates five consecutive memory locations each large enough to hold a single integer
- The address of the first element list[0] is called the base address.
- Memory address of list[i] is $\alpha + i * \text{sizeof(int)}$ where α is base address.
- In the above example, list is a pointer to list[0].

list + i equals & list[i]

* (list + i) equals list[i]

Consider the following initialization statement

int a[5] = {10, 11, 12, 13, 14}

Compiler allocates memory locations and stores the values as shown below

a[0]	10	1000	&a[0]
a[1]	11	1004	&a[1]
a[2]	12	1008	&a[2]
a[3]	13	1012	&a[3]
a[4]	14	1016	&a[4]

↑ ↑
Accessing values Accessing address
value of a is the base address i.e., 1000

$$\&a[0] \text{ or } a+0 = 1000$$

$$\&a[1] \text{ or } a+1 = 1004$$

$$\&a[2] \text{ or } a+2 = 1008$$

$$\&a[4] \text{ or } a+4 = 1016$$

$$*\&a[0] \text{ or } *(a+0) \text{ or } a[0] = 10$$

$$*\&a[1] \text{ or } *(a+1) \text{ or } a[1] = 11$$

$$*\&a[4] \text{ or } *(a+4) \text{ or } a[4] = 14$$

↓

$*\&a[i] \text{ or } *(a+i) \text{ or } *(i+a) \text{ or } a[i] \text{ or } i[a]$

gives value of ith item.

Base address $a = 1000$ i.e. $\&a[0]$.

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$a[0]$	$\boxed{}$	$1000 = 1000 + 4 * 0$
$a[1]$	$\boxed{}$	$1004 = 1000 + 4 * 1$
$a[2]$	$\boxed{}$	$1008 = 1000 + 4 * 2$
$a[3]$	$\boxed{}$	$1012 = 1000 + 4 * 3$
$a[4]$	$\boxed{}$	$1016 = 1000 + 4 * 4$
		\uparrow \uparrow $\leftarrow i$ base address sizeof(int)

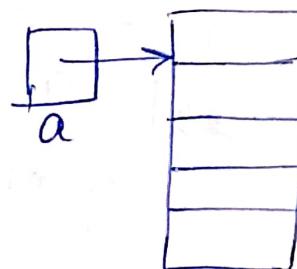
$$\boxed{\text{address of } a[i] = \alpha + \text{sizeof(int)} * i}$$

Pictorial representations

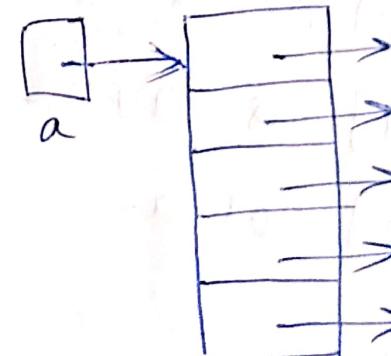
$\text{int } *a;$



$\text{int } a[5]$



$\text{int } *a[5]$



Function to display array elements using pointers

```
Void display (int *ptr, int n)
{
    int i;
    printf ("Array contents");
    for (i=0; i<n; i++)
        printf ("%d", *(ptr+i));
}
```

Dynamically Allocated Arrays

Memory for array can be allocated dynamically during run time using `malloc` as shown below.

```
int *p, n, i;
printf ("Enter the number of elements");
scanf ("%d", &n);
int *p = (int *) malloc (n * sizeof (int));
```

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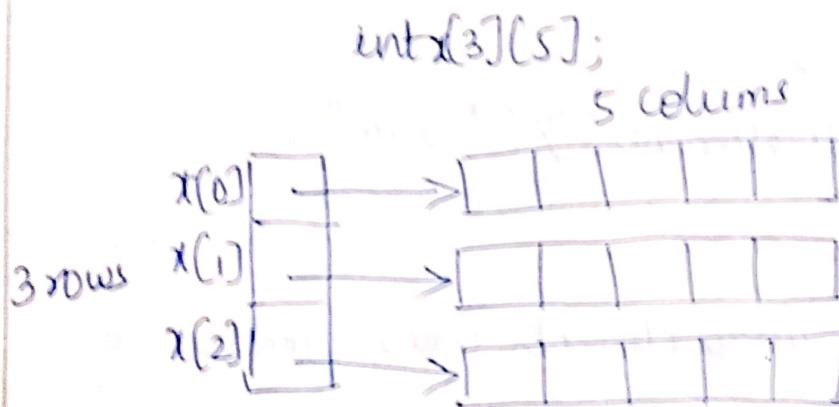
```

p = malloc (n * sizeof (int));
printf ("Enter elements");
for (i = 0; i < n; i++)
    scanf ("%d", &p[i]);

```

Two-dimensional arrays

Two-dimensional array can be represented as



Arrays of arrays representation

- C finds the element $x[i][j]$ by first accessing the pointer in $x[i]$.
- This pointer gives the address of zeroth element of row i of the array.
- Address of j^{th} element of row i is found by adding $j * \text{sizeof(int)}$ to this pointer.
- Memory can be allocated dynamically for a two-dimensional array as shown below.

```

int **p;
p = makearray (5, 10);

```

Pointers & arrays

(8.1) slides

Eg1: `int num[5] = { 23, 34, 45, 56, 6 };`

(if $\&num[0] = \text{main} + 3$) Flowchart

23	34	45	56	6
1001	1003	1005	1007	1009

→ array elements
→ addresses

main()

{

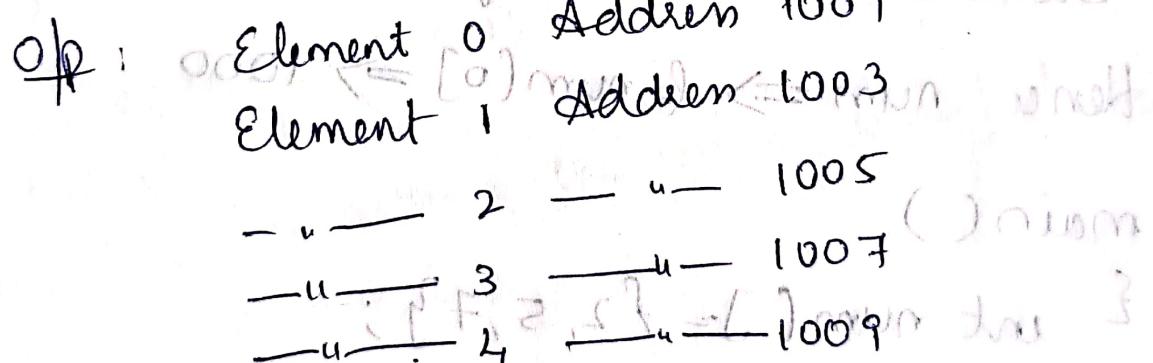
`int num[5] = { 23, 34, 45, 56, 6 };`

`int i=0; /* initial value of i */`

`while (i < 5)`

{ `printf("Element %d Address %u", i, &num[i])`

`i++;`



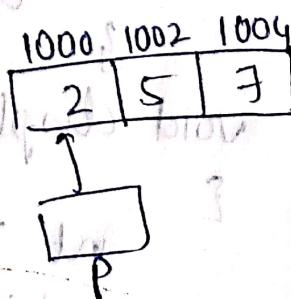
(E. min) possible : (E. [0] max) possible

Eg2: main()

{ `int num[] = { 2, 5, 7 }; num`

`int *p;`

`p = num; or p = &num[0]`



```

while (i < 3)
{
    printf ("Address = %u, &num[i]);
```

printf ("Element = %d", *p);

i++;

p++;

}

}

Op Address = 1000 Element = 2

Address = 1002 Element = 5

Address = 1004 Element = 7

Name of the array holds the address of the first element in the array

Hence num \Rightarrow &num[0] \Rightarrow 1000

Eg3: main()

{ int num[] = {2, 5, 7}; }

display (&num[0], 3); //display(num, 3);

void display (int *j, int n)

{

int i=1;

while (i <= n)

{

printf ("Element = %d", *j);

} i++; j++;

Sparse Matrices

A sparse matrix is a matrix that contains many zero entries.

Eg. $\begin{matrix} & \text{col} \\ \text{row} & \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 5 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 2 & -5 & 0 \\ 2 & 2 & 0 & 0 & 0 & 0 \\ 3 & 3 & 2 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \end{matrix}$

$$\left(\begin{matrix} & \text{col} \\ \text{row} & \begin{bmatrix} 0 & 1 & 2 & 3 & 4 & 5 \\ 0 & 5 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 2 & -5 & 0 \\ 2 & 2 & 0 & 0 & 0 & 0 \\ 3 & 3 & 2 & 0 & 0 & 0 \\ 4 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \right) \quad \text{Matrix } A$$

We can use an array of triples $\langle \text{row}, \text{col}, \text{value} \rangle$ to represent a sparse matrix as shown below

	row	col	value
a[0]	0	5	9
[1]	0	0	5
[2]	0	4	1
[3]	1	2	2
[4]	1	2	-5
[5]	1	F	11
[6]	2	0	2
[7]	2	5	15
[8]	3	1	2
M.D.I.E.R([9])	3	2	1

Structure for triple format

```
typedef struct
{
    int row;
    int col;
    int value;
}Triple;
```

```
Triple a[20];
```

a[0].row contains the number of rows, a[0].col contains the number of columns and a[0].value contains the total number of nonzero entries. Other positions store the triples representing nonzero entries. row index is in the field 'row' column index in the field 'col' and value is in the field 'value'

Program to read a sparse matrix and convert it to triple format

```
#include <stdio.h> //Insert the structure for triple format;
```

```
void main()
```

```
{ int a[10][10], m, n, i, j, k=1;
```

```
Triple ta[10];
```

```
printf("Enter the order of the sparse matrix\n");
```

```
scanf("%d %d", &m, &n);
```

```
ta[0].row = m;
```

```
ta[0].col = n;
```

```
printf("Enter elements into the sparse matrix\n");
```

```
for (i=0; i<m; i++)
```

```
{ for (j=0; j<n; j++)
```

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```
scanf("%d", &a[i][j]);
```

```
if(a[i][j] != 0)
```

```
{
```

```
ta[k].value = a[i][j];
```

```
ta[k].row = i;
```

```
ta[k].col = j;
```

```
k++;
```

```
} // end of if
```

```
} // inner for loop closed
```

```
} // outer for loop closed
```

```
ta[0].value = k-1;
```

```
printf("Matrix A\n");
```

```
for(i=0; i<m; i++)
```

```
{
```

```
for(j=0; j<n; j++)
```

```
{
```

```
printf("%d\t", a[i][j]);
```

```
}
```

```
printf("\n");
```

```
}
```

```
printf("Triple format of matrix a");
```

```
printf("Row \t Col \t value \t");
```

```
for(i=0; i<k; i++)
```

```
{
```

```
printf("%d\t%d\t%d\n", ta[i].row, ta[i].col,
```

```
ta[i].value);
```

```
}
```

```
(else ignore all other elements)
```

```
}
```

Transpose of a sparse matrix in triple format

```
void transpose(Triple a[], Triple b[])
```

```
{
```

```
    int n, j, i, curb;
```

```
    n = a[0].value;
```

```
    b[0].row = a[0].col;
```

```
    b[0].col = a[0].row;
```

```
    b[0].value = n;
```

```
    if (n > 0)
```

```
{
```

```
    curb = 1;
```

```
    for (i = 0; i < a[0].col; i++)
```

```
        for (j = 1; j <= n; j++)
```

```
            if (a[j].col == i)
```

```
{
```

```
                b[curb].row = a[j].col;
```

```
                b[curb].col = a[j].row;
```

```
                b[curb].value = a[j].value;
```

```
                curb++;
```

```
}
```

```
}
```

Sparse format transpose
work with col row, need to make a 2D array of
int size n * n all the initial value will be zero or -1

Polynomials using arrays

A polynomial is a sum of terms, where each term has a form $a x^e$ where x is the variable, a is the coefficient and e is the exponent.

Eg:

$$A(x) = 3x^{20} + 2x^5 + 4$$

$$B(x) = x^4 + 10x^3 + 3x^2 + 1$$

The largest exponent of a polynomial is called its degree.

M.D.I.E.I.B
R022370097, T22A



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```

Polynomial representation (using structs)
typedef struct {
    int coef;
    int expon;
} poly;
poly pa[MAX];

```

Consider 2 polynomials A and B given in the example
 These 2 polynomials can be stored in the array pa
 as shown below

	startA	finishA	startB	finishB	avail							
coeff	3	2	4	1	10	3	1					
pa	20	5	0	4	3	2	0					
	0	1	2	3	4	5	6	7	8	9	10	11

The index of the first term of A and B is given by startA and startB respectively. finishA and finishB give the index of the last term of A and B.

The index of the next free location in the array is given by avail.

Here startA=0, finishA=2, startB=3, finishB=6, avail=7.

Polynomial addition

```

void poly-add (int startA, int finishA, int startB, int finishB)
{
    int sum;
    startD = avail;
    while (startA <= finishA && startB <= finishB)
    {

```

```
if (pa[startA].expon < pa[startB].expon)
{
    pa[avail].expon = pa[startB].expon;
    pa[avail].coef = pa[startB].coef;
    avail++;
    startB++;
}
else if (pa[startA].expon > pa[startB].expon)
{
    pa[avail].expon = pa[startA].expon;
    pa[avail].coef = pa[startA].coef;
    avail++;
    startA++;
}
```

} else

```
{ sum = pa[startA].coef + pa[startB].coef;
```

if (sum != 0)

```
    pa[avail].expon = pa[startA].expon;
```

```
    pa[avail].coef = sum;
```

avail++;

startA++;

startB++;

}

for (; startA <= finishA; startA++)

```
{ pa[avail].expon = pa[startA].expon;
```

```
    pa[avail].coef = pa[startA].coef;
```

(startB) avail++; \Rightarrow A test 2 starts

}

for(; startB <= finishB ; startB++)

{

pa(avail).expon = pa(startB).expon;

pa(avail).coeff = pa(startB).coeff;

avail++;

}

finishD = avail;

avail++;

}

The above function adds the 2 polynomials A and B are the result is stored in the array starting at position startD and ending at finishD as shown below

StartA	FinishA	StartB	FinishB	StartD	FinishD	avail
3	2	4	1	10	3	5
20	5	0	4	3	2	0

$$A(x) = 3x^{20} + 2x^5 + 4$$

$$B(x) = x^4 + 10x^3 + 3x^2 + 1$$

$$\text{sum } D(x) = 3x^{20} + 2x^5 + x^4 + 10x^3 + 3x^2 + 5$$

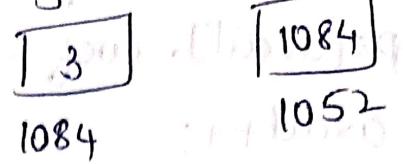
Pointer examples

i) main()

```

    {
        int j=3, *i;
        i = &j;
    }

```



printf("Address of i=%u, Address of j=%u",
&i, &j);

printf("Value of i=%u", i);

printf("Value of j using pointer variable is
%u", *i);

printf("Value of j=%u", *(&j));

Address	Address	Address	Address	Address	Address	Address	Address	Address	Address
i	j	i	j	i	j	i	j	i	j
1052	1084	1052	1084	1052	1084	1052	1084	1052	1084
Value of i = 1084									
Address of i = 1052, Address of j = 1084									

value of j using pointer variable is 3

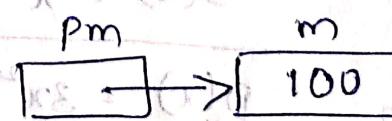
value of j = 3

ii) main()

```

    {
        int m=122, *pm;
        pm = &m;
        *pm = 100;
    }

```



Output

value of m = 100

printf("Value of m=%u", *pm);

Output

Element = 2
Element = 5
Element = 7

Array of pointers

void main()

{

int * arr[4];

int i=3, j=5, k=8, l=7; m;

arr[0] = &i;

arr[1] = &j;

arr[2] = &k;

arr[3] = &l;

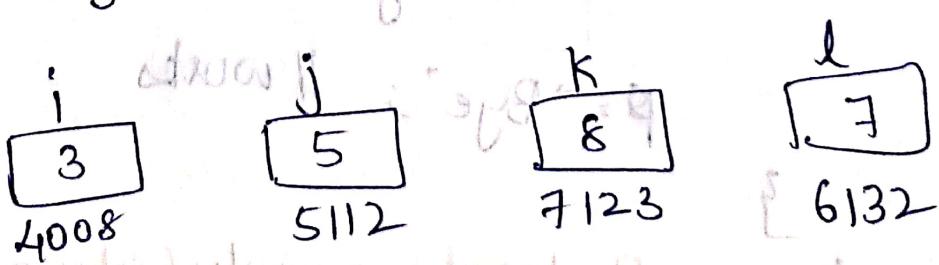
for (m=0; m<3; m++)

printf("%d", *(arr[m]));

3

output:

3 5 8



arr[0] arr[1] arr[2] arr[3]

arr	4008	5112	7123	6132
	7602	7604	7606	7608

Pointer to pointer

A variable containing the address of a pointer variable is called pointer to a pointer.

Eg. int p; integer variable

int *p1; pointer

int **p2; pointer to pointer

p1 = &p;

p2 = &p1;



Pointers and Strings

We cannot assign a string to another string but a char pointer can be assigned to another char pointer.

Eg: main()

```
char str1[] = "Hello";
```

```
char str2[10];
```

```
char *s = "How are you";
```

```
char *q;
```

```
str2 = str1; // error
```

```
q = s // works
```

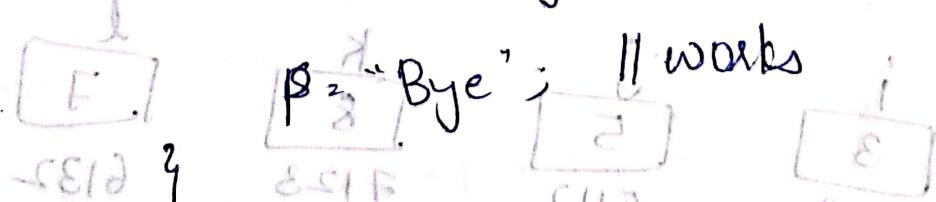
- Once a string is defined it cannot be initialized to another set of characters

Eg: void main()

```
char str1[] = "Hello";
```

```
char *p = "Hello";
```

```
str1 = "Bye"; // error
```


P = "Bye"; // works

Pointer types: Pointer to a pointer (refer previous page)

1. Dangling pointer: pointer containing an invalid address
2. NULL pointer: Pointer initialized to NULL & not pointing anywhere in memory
3. Void pointer: Can point to any datatype.

- Various primitive data types in C are
 - int - integer data type
 - float - floating point data type
 - char - character data type
 - double - double precision floating point data type
 - void - null data type
- Other data types that can be derived from the basic data types are called derived data types. Various derived data types are
 - Arrays
 - Pointers
 - Enumerated
 - Structures
 - Unions

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→ Type definition

- typedef keyword allows the programmer to create a new data type name for an already existing data type.
- The purpose of typedef is to redefine the name of an existing data type.
- General syntax of typedef is

```
typedef   datatype   new_name1, new_name2... ;  

         ↑           ↑  

    keyword   Existing   user-defined  

              datatype   data types  

                  (int, float...)   (marks, amount...)
```

Eg: `typedef int MARKS;`

Here we are creating a new name "MARKS" for the existing data type `int`. `MARKS` is called user-defined data type

The new data type names that are defined by the user using already existing data types are called user-defined data types.

Ex 1: `typedef int MARKS;`
`MARKS sub1, sub2, sub3;`

Ex 2: `typedef int BIGARRAY[1000] //user-defined data type`
`BIGARRAY a; //a is an array of 1000 integers`

Ex 3: `typedef char STRING[80] //user defined data type`
`STRING s; //s is an array of 80 characters.`

-Program to compute simple interest using various typedef definition

```
#include <stdio.h>
typedef float AMOUNT;           //typedef definitions
typedef float TIME;
typedef float RATE;
void main()
{
    AMOUNT p, si;
    TIME t;
    RATE r;
    printf("Enter p, t and r");
    scanf("%f %f %f", &p, &t, &r);
    si = (p * t * r) / 100;
    printf("SI = %.f \n", si);
```

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AMOUNT, TIME and RATE are user-defined data types

Advantages of typedef

- Provides a meaningful way of declaring the variables
- Increases the readability of the program
- Helps us to understand the source code and saves time and energy spent in understanding the program.

Structures

Def: A structure is a collection of one or more variables of same data type or dissimilar data types grouped together under a single name. Structure allows to group data of different data types.

Eg: Student information to be grouped may consist of

- Name of the student
- University marks
- USN.

General syntax of a structure

```
struct tagname
{
    type1 member1;
    type2 member2;
    :
};
```

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Example

```
struct student
{
    char name[10];
    int usn;
    float marks;
};
```

struct is the keyword used to define a structure. The tagname is used as shorthand for declarations. The variables in

a structure such as member1, member2, ... declared within braces are called members of the structure. The members can be of any data type such as int, char, float etc. There should be semicolon at the end of closing brace.

→ Structure definition/declaration

A structure can be declared using three different ways

- 1) Tagged structures
- 2) Structure without tag
- 3) Typedefined structures

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1) Tagged structure

In structure definition, the keyword struct can be followed by an identifier. This identifier is called tag name. The structure definition associated with a tag name is called tagged structure.

* Structure definition */

Syntax

```
struct tag_name
{
    type1 member1;
    type2 member2;
    :
};
```

Example

```
struct student
{
    char name[10];
    int usn;
    float marks;
};
```

- struct is the keyword
- student is the name of the structure. It is also called tag name.
- struct student represents the data type. It is called a derived datatype.
- Memory is allocated for structure only when the variables are declared.

Structure variables are declared as shown below

Syntax:

```
struct tagname variable-list;
```

Example

```
struct student s1, s2; // structure declaration */
```

s1 and s2 are variables of type struct student.

- Once the variables are declared memory is allocated for s1 & s2

Number of bytes allocated for variable s1 is

10 bytes for name	} Size of structure student 10+2+4= 16 bytes.
2 bytes for usn	
4 bytes for marks	

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2) Structure without tag

The structure definition without tag name is called structure without tag.

Syntax

```
struct
```

```
{
```

```
type1 member1;
```

```
type2 member2;
```

```
:
```

```
} variablelist;
```

Example

```
struct
```

```
{
```

```
char name[10];
```

```
int usn;
```

```
float marks;
```

```
} s1, s2;
```

In the absence of tag name, variables must be declared immediately after the right brace as shown above

3) Type defined structure

The structure definition associated with keyword `typedef` is called type defined structure.

Syntax

```
typedef struct  
{  
    type1 member1;  
    type2 member2;  
    ...  
}; TYPE-ID;
```

Example

```
typedef struct  
{  
    char name[10];  
    int usn;  
    float marks;  
}; STUDENT;
```

- `typedef` and `struct` are keywords
- The closing brace must end with type definition name.
In the example, `STUDENT` is the new data type using which variables can be declared as shown below

Syntax: TYPE-ID V1, V2, ..., Vn;
 ↓

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Example: STUDENT S1, S2;

Here, student is tagname and STUDENT is the user-defined data type.

→ Structure Initialization

The syntax of initializing structure variables is shown below

struct tag-name variable = {V1, V2, ..., Vn};

Examples

```
struct student  
{  
    char name[10];  
    int usn;  
    float marks;  
}; a = {"abc", 1, 20};
```

↓
values for members



Variable a has values name = "abc", salary = 1 and marks = 20.

The variable a can also be initialized as shown below

```
struct student
{
    char name[10];
    int usn;
    int marks;
};
```

```
struct student a = {"abc", 1, 20};
```

Initialization during structure declaration with more than one variable

```
struct student
{
    char name[10];
    int usn;
    int marks;
} a, b = {"xyz", 2, 24};
```

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Here, a is not initialized and only b is initialized.

```
> struct student
{
    char name[10];
    int usn;
    int marks;
} a = {"abc", 1, 20}, b = {"xyz", 2, 24};
```

Here both a and b are initialized

> Partial initialization

```
struct student a = {"abc", 1};
```

Here only name and usn of variable a are initialized.

→ Accessing structures

A member of a structure can be accessed by specifying the variable name followed by a dot, followed by the member name

Syntax: variable.member

To access the member name of variable a, we specify a.name

Program to display various members of a structure:

```
#include<stdio.h>

typedef struct
{
    char name[10];
    int usn;
    float marks;
} STUDENT;

Void main()
{
    STUDENT a;
    printf(" Enter student details");
    scanf(" %s %d %.f", a.name, &a.usn, &a.marks);
    printf(" The student details are");
    printf(" Name: %s", a.name);
    printf(" Usn: %d", a.usn);
    printf(" Marks: %.f", a.marks);
    getch();
}
```

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Unions: A union is similar to a structure which is also a collection of data items of similar or dissimilar data types. The data items are called fields or members. All the members of the union share the same memory space. Hence all members have same addresses. Only one member is active at any point during execution.

General format / syntax

Union tagname

{

type1 member1;

type2 member2;

}

Eg: `typedef union`

{

`int i;`

`float f;`

`char c;`

}

item x; → declaration of variable of type item.

The compiler reserves memory whose size is that of the largest member. In the above example `float` is the largest datatype of the members of the union. Hence, $\text{size of (float)} = 4$ bytes of memory is reserved for the variable x.

```

#include <stdio.h>
Void main()
{
    typedef union
    {
        int marks;
        char grade;
        float percentage;
    } STUDENT;
    STUDENT x;
    x.marks = 100;
    printf ("Marks : %d \n", x.marks);
    x.grade = 'A';
    printf ("Grade : %c \n", x.grade);
    x.percentage = 99.5;
    printf ("Percentage : %f \n", x.percentage);
}

```

Output

Marks : 100

Grade : A

Percentage : 99.5.

After statement `x.marks=100`, the member `marks` will hold the value `100` and other members should not access the data. If accessed, it will be treated as garbage value.

Difference between structure and union

Structure	Union
1. The keyword struct is used to define a structure.	1. The keyword union is used to define a union.
2. For a structure variable, the compiler allocates the memory for each member. The size of structure is equal to the sum of sizes of its members.	2. For a union variable, the compiler allocates the memory by considering the size of the largest member. So, size of union is equal to the size of largest member.
3. Altering the value of any member will not affect the other members of the structure.	3. Altering the value of any of the members will alter other member values.
4. The address of each member will be in ascending order. The memory for each member starts at different offset values.	4. The address is same for all the members of a union. Every member begins at offset zero.
5. Individual members can be accessed at any time since separate memory is reserved for each member.	5. Only one member can be accessed at a time since memory is shared by each member.
Eg: struct student { char name[10]; int usn; };	Eg: union student { char name[10]; int usn;

Self-referential Structures

A self-referential structure is one in which one or more of its components is a pointer to itself.

Eg: `typedef struct {`

`int data;`

`struct list *link;`

`list,`

`data is an integer, link is a pointer to a list structure.`

`Value of link is either the address in memory of an instance of list or the null pointer.`

`list item1, item2, item3;`

`item1.data = 10;`

`item2.data = 20;`

`item3.data = 30;`

`item1.link = item2.link = item3.link = NULL;`

`item1.link = &item2;`

`item2.link = &item3;`

10	2000
----	------

20	1048
----	------

30	NULL
----	------

1000

2000

1048

