



Regularizations

Deep Neural Networks
Session 10
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2 Agenda

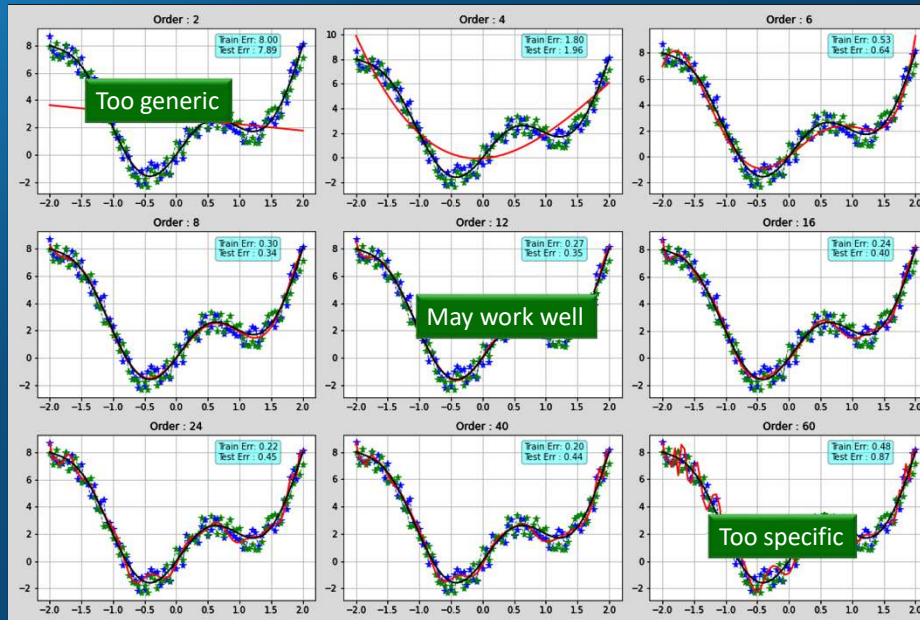
- L-1, L-2
- Dropout
- Early Stopping
- Augmentation

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Under-fitting vs. Over-fitting



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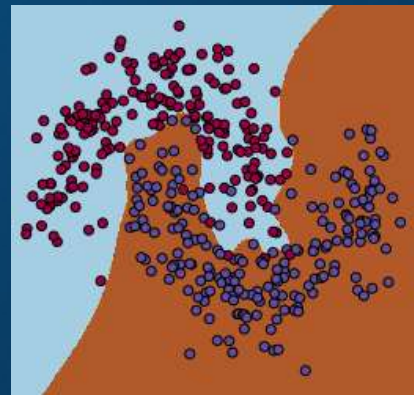
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Regularization

- ❑ Regularization helps in avoiding over fitting by penalizing the coefficients
- ❑ In deep learning, it actually penalizes the weight matrices of the nodes
- ❑ Different Regularization Techniques in Deep Learning
 - ❖ L1 regularization
 - ❖ L2 regularizations
 - ❖ Dropouts
 - ❖ Early stopping
 - ❖ Data Augmentation

Most Libraries have tunable hyper-parameters!



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Weights vs. Bias

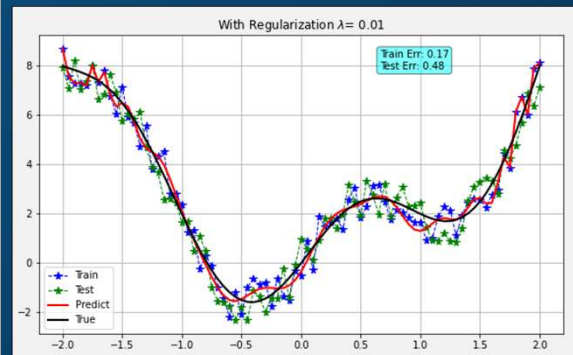
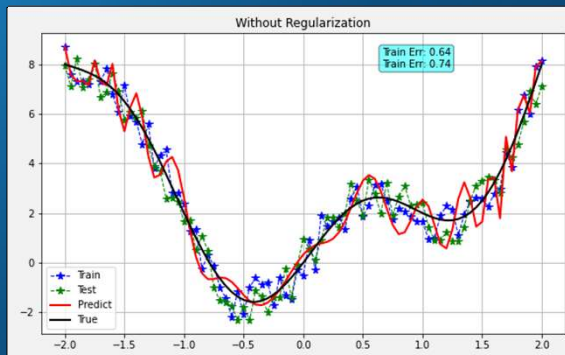
- ❑ For neural networks, we typically choose to use a parameter norm penalty Ω that penalizes only the weights at each layer and leaves the biases un-regularized.
- ❑ The biases typically require less data to fit accurately than the weights.
- ❑ Fitting the weight will requires observing both (fan_in and fan_out) layer in a variety of conditions.
- ❑ Each bias controls only a single layer.
- ❑ This means that we do not induce too much variance by leaving the biases un-regularized.
- ❑ Also, regularizing the bias parameters can introduce a significant amount of under fitting.

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Effect of L2 Regularization



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Theory – Logistic Regression – L1 & L2

- Idea is to minimize Cost Function

$$\diamond J(W, b) = \frac{1}{m} * \sum \ell(a, y)$$

$$\diamond = -\frac{1}{m} \{y * \log(a) + (1-y) * \log(1-a)\}$$

- A term is added to Cost function $\frac{\lambda}{2 * m} \cdot \|W\|_2^2$

$$J(W, b) = \frac{1}{m} * \sum \ell(a, y) + \frac{\lambda}{2 * m} \cdot \|W\|_2^2$$

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Theory – Logistic Regression – L1 & L2

$$\square J(W, b) = \frac{1}{m} * \sum \ell(a, y) + \frac{\lambda}{2 * m} \cdot \|W\|_2^2 + \frac{\lambda}{2 * m} \cdot b^2$$

- ✦ This is referred as L2 regularization
- ✦ **Regularization hyperparameter λ :** It is another parameter we tune...

$$\square \|W\|_2^2 = \sum_{j=1}^n w_j^2 = W^T \cdot W$$

- Here, we are using Euclidean Norm or L2 Norm

- Compared to W, bias b has fewer dimensions, hence, it is generally not considered

- If you add for b, $(\frac{\lambda}{2 * m} \cdot b^2)$... that's ok too

- ✦ Although its effect will be minimal,
- ✦ Better to leave it alone.

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Theory – Logistic Regression – L1 & L2

□ Sometimes L1 too is used

$$□ J(W, b) = \frac{1}{m} * (\sum \ell(a, y)) + \frac{\lambda}{2 * m} * \|W\|_1$$

□ Differentiation of $\frac{\lambda}{2 * m} * \|W\|_1 = \frac{\lambda}{2 * m} \text{sign}(W)$

❖ Will be infinitely small and will have smaller impact on gradient descent

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Neural Network – Frobenius Norm

□ In neural network, we have different layers with different weights

□ So we look at its cumulative effect over all layers

□ Hence the Cost function

$$❖ J(W, b) = J(W[1], b[1], W[2], b[2], W[3], b[3] \dots)$$

$$❖ J(W, b) = \frac{1}{m} * (\sum \ell(a, y)) + \frac{\lambda}{2 * m} * \sum_{l=1}^L \sum (w_{i,j})^2$$

$$❖ J(W, b) = \frac{1}{m} * \sum \{y * \log(a) + (1-y) * \log(1-a)\} + \frac{\lambda}{2 * m} * \sum_{l=1}^L \|W[l]\|^2$$

$$❖ \text{Where } \|W[l]\|_F^2 = \sum_{i=1}^{n^{[l-1]}} \sum_{j=1}^{n^{[l]}} (w_{ij}^{[l]})^2$$

➤ W is $(n^{[l-1]}, n^{[l]})$ dimensional matrix

□ It is called *Frobenius norm* of a matrix

□ Also the *Frobenius norm* defined as the square root of the sum of the absolute squares of its elements

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Frobenius Norm of a Vector

$$\square \|A\|_F = \sqrt{\sum (a_{ij})^2}$$

i.e.

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \sqrt{(1^2 + 2^2 + 3^2 + 4^2 + 5^2 + 6^2 + 7^2 + 8^2 + 9^2)}$$

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Updates to weights

□ Earlier

$$\diamond \partial W^{[l]} = X \cdot \partial z$$

$$\diamond \text{ And } W^{[l]} = W^{[l]} - \alpha \cdot \partial W^{[l]}$$

✦ For Regularization we add an extra term at the end

$$\diamond \partial W^{[l]} = X \cdot \partial z + \frac{\lambda}{m} \cdot W^{[l]}$$

Mathematically, we can show that it is still a valid definition of $\partial W^{[l]}$

$$\diamond W^{[l]} = W^{[l]} - \alpha \cdot [X \cdot \partial z + \frac{\lambda}{m} \cdot W^{[l]}]$$

$$\diamond W^{[l]} = (1 - \frac{\alpha \cdot \lambda}{m}) \cdot W^{[l]} - \alpha \cdot X \cdot \partial z$$

Weight Decay

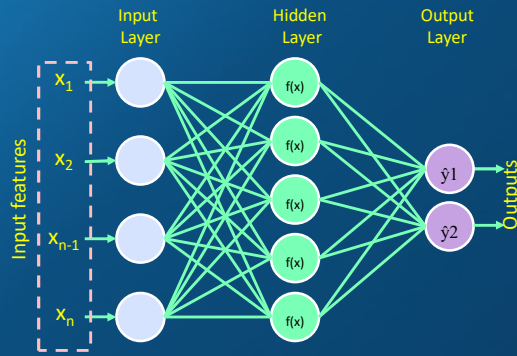
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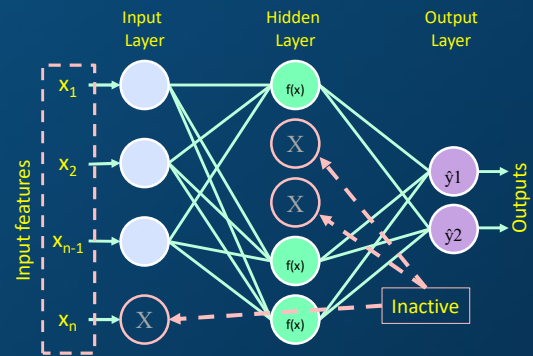
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Regularization : Dropout

Original



With Dropout



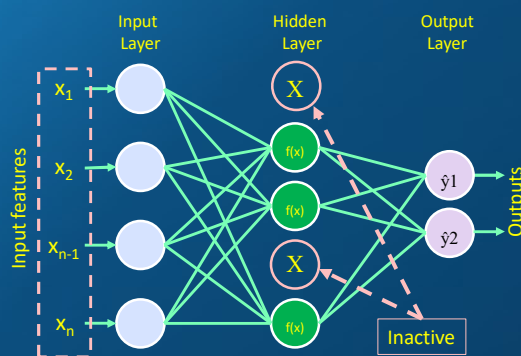
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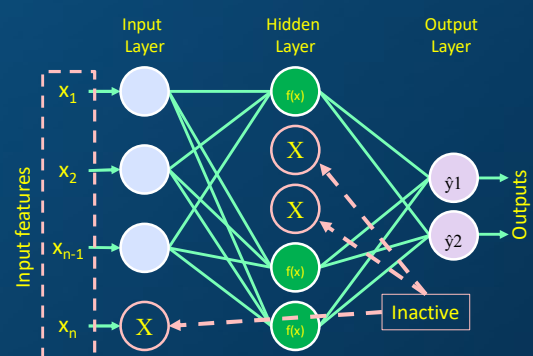
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Regularization : Dropout

Iteration 1



Iteration 2



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Regularization : Early Stopping

- ❑ How long to train the model?
- ❑ Duration of training → under – fit or over – fit
- ❑ Train the model to the point where its performance on test set is best!
- ❑ Very simple and very effective

How:

- ❑ Train the model and monitor performance
- ❑ Save weight every time the performance improves
- ❑ Stop training if performance has not improved for N epochs
- ❑ It's the last parameter to tune
 - ❖ Repeated early stopping may lead to over-fitting the validation set
 - ❖ Example : K-fold

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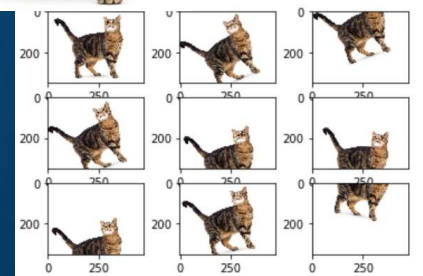
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Regularization : Data Augmentation

- ❑ Where limited data is available for training the model (when is it not!)
- ❑ Very effective in image identification
- ❑ Most libraries have Image Generators (parameter driven)
 - ❖ Horizontal and Vertical Shift
 - ❖ Horizontal and Vertical Flip
 - ❖ Random Rotation
 - ❖ Random Brightness / Contrast
 - ❖ Random Zoom
 - ❖ Random Noise



<https://towardsdatascience.com/image-augmentation-for-deep-learning-histogram-equalization-a71387f609b2>



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Reflect...

- ❑ What is the purpose of dropout in deep neural networks?
 - ❖ A) To add noise to the input data
 - ❖ B) To randomly drop neurons during training to prevent overfitting
 - ❖ C) To increase the learning rate
 - ❖ D) To increase the model complexity

❑ Answer: B

- ❑ What is the primary purpose of regularization in deep neural networks?
 - ❖ A) To increase computational efficiency
 - ❖ B) To prevent overfitting
 - ❖ C) To speed up convergence during training
 - ❖ D) To increase the model's capacity

❑ Answer: B) To prevent overfitting

- ❑ Which type of regularization adds a penalty term to the loss function based on the absolute values of the weights?
 - ❖ A) L1 Regularization
 - ❖ B) L2 Regularization
 - ❖ C) Dropout
 - ❖ D) Batch Normalization

❑ Answer: A) L1 Regularization

- ❑ How does dropout regularization work?
 - ❖ A) It penalizes large weights in the network
 - ❖ B) It introduces noise to the input data during training
 - ❖ C) It randomly removes neurons during training
 - ❖ D) It normalizes the input features

❑ Answer: C) It randomly removes neurons during training

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Reflect...

- ❑ Which regularization technique is commonly applied to prevent exploding gradients during training?
 - ❖ A) Dropout
 - ❖ B) Batch Normalization
 - ❖ C) L2 Regularization
 - ❖ D) Data Augmentation

❑ Answer: B) Batch Normalization

- ❑ What is the role of early stopping as a form of regularization?

❑ Answer Choices:

- ❖ A) To speed up the training process
- ❖ B) To prevent the model from fitting the training data too closely
- ❖ C) To add noise to the input data
- ❖ D) To stop the training process when the model performance on a validation set plateaus or degrades

❑ Answer: D) To stop the training process when the model performance on a validation set plateaus or degrades

- ❑ Which regularization method penalizes the squared values of the weights in the network?
 - ❖ A) Dropout
 - ❖ B) L1 Regularization
 - ❖ C) L2 Regularization
 - ❖ D) Batch Normalization

❑ Answer: C) L2 Regularization

- ❑ What is the trade-off associated with increasing the strength of regularization in a deep neural network?

- ❖ A) Increased risk of overfitting
- ❖ B) Increased risk of underfitting
- ❖ C) Slower convergence during training
- ❖ D) Improved model generalization

❑ Answer: B) Increased risk of underfitting

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Reflect...

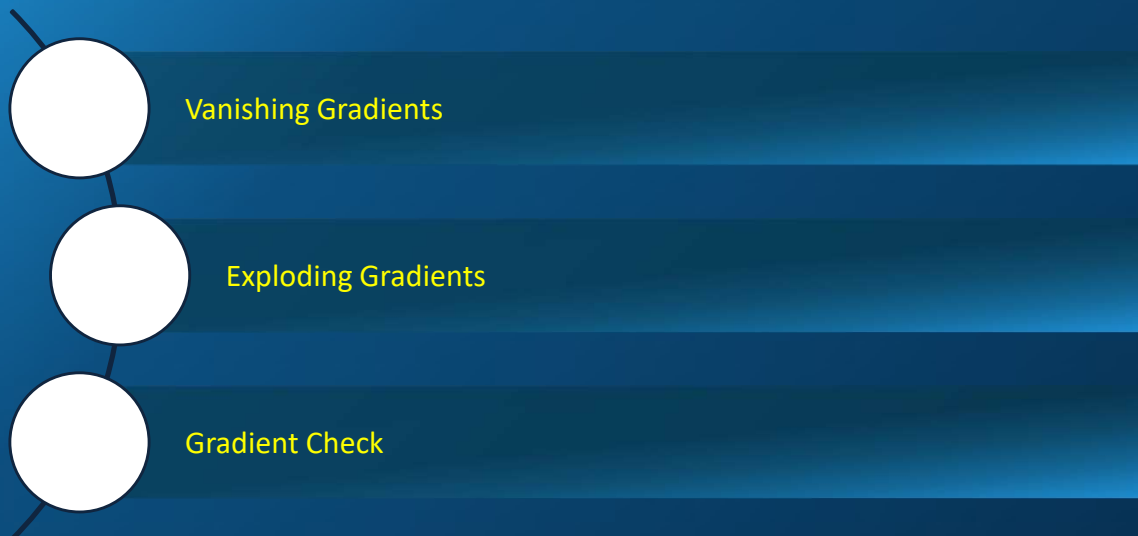
- ❑ In the context of regularization, what does the term "lambda" typically represent?
 - ❖ A) Learning rate
 - ❖ B) Regularization strength
 - ❖ C) Number of hidden layers
 - ❖ D) Batch size
- ❑ Answer: B) Regularization strength
- ❑ Which regularization technique is particularly useful for handling sequences and time-series data in deep learning?
 - ❖ A) L1 Regularization
 - ❖ B) Data Augmentation
 - ❖ C) Recurrent Dropout
 - ❖ D) Batch Normalization
- ❑ Correct Answer: C) Recurrent Dropout
- ❑ What is the purpose of data augmentation as a regularization technique?
 - ❖ A) To add noise to the input data
 - ❖ B) To increase the model's capacity
 - ❖ C) To generate more training samples by applying random transformations to the existing data
 - ❖ D) To decrease the learning rate during training
- ❑ Answer: C) To generate more training samples by applying random transformations to the existing data

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Next Session...



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