<u>)</u> .					
	1 Algorithm	Program			
	Design time	Implementation time			
	Domain knowledge	Programmer			
	Any language even English and Maths	Programming language			
	Hardware and software independent	Hardware and operating system dependent			
	Analyze an algorithm	Testing of programs			
	2 Priori Analysis	Posterior Testing			
	Algorithm	Program			
	Independent of language	Language dependent			
	Hardware independent	Hardware dependent			
	Time and space function	watch time and bytes			
	3 Characteristics of algorithm				
	Zero or more inputs				
	Must generate atleast one output				
	Definiteness				
	Finiteness				
	Effectiveness				
	4 How to analyze an algorithm				
	Time				
	Space				
	Network consumtion : Data transfer amount				
	Power consumption				
	CPU registers				
	5 Frequency Count Method	Used for time snalysis of an algorithm			
	Assign 1 unit of time for each statement				
	For any repitition, calculate the frequency of repetition				
	for(i = 0; i < n; i++)> condition is checked for n+1 times	2n + 2 units of time ~ n+1 as we see condition i < n only for now			
	any statement within the loop will execute for n times				

variables used	nds upon number and kind of				
6 Algorithm : sum(A, n)					
Single for loop -					
Time complexity: O(N)					
Space complexity: O(N)					
7 Algorithm : Add(A, B,	1)	Sum of two square matrices of dimesions nXn			
Two nested for loops -					
Time complexity: O(N^2)				
Outer for loop executes	for N+1 times				
Inner for loop xecutes for	or N *(N+1) times				
Any statement within inr 1) times	ner for loop executes for (N + 1) * (N +				
Space complexity: O(N/	2)				
8 Algorithm : Multiply(A	B, n)				
Three nested for loops -					
Time complexity: O(N^3)				
Space complexity: O(N'	2)				
9 Different algorithm co	nditions				
For loops					
for(i = n; i > 0; i)		n+1 times			
for($i = 0$; $i < n$; $i = i + 2$)		n/2 times			
2 nested for loops where	e both i and j range from 0 to n	n^2 times			
2 nested for loops where	e j ranges from 0 to i	when i = 0; j loop repeats 0 times; when i = 1; j loop repeates 1 times; and so ontotal number of repetitions: $0 + 1 + 2 + 3 + 4 \dots + n = O(n^2)$			
p = 0; for(i = 1; p<= n; i+	$+){p = p + i;}$	$p = k(k+1)/2 \longrightarrow assuming that the loop exits when p is greater than n \longrightarrow k(k+1)/2 > n$	~ k^2 > n> O(root(n))		
for(i = 1; i < n; i = i *2)		will execute for 2 ^k times	O(logn)		
		Assume i >= n ; i = 2^k >= n			
		k = logn with base 2			

for(i = n; $i >= 1$; $i = i/2$)	i			
	n			
	n/2			
	n/2^2			
	n/2^3			
	n/2^k			
	Assume i < 1 => n / 2^k < 1	~ O(logn) with base 2		
for(i = 0; i * i < n; i++)	i*i < n			
	i*i > -n			
	i^2 = n> i = root(n)	~O(root(n))		
for(i = 0; i < n; i++) {}for(j = 0; j < n; j++){}	O(n)			
$p = 0$; for(i = 1; i < n; i*2){} for(j = 1; j < p; j*2){}	log n times for upper loop; lop p times for lower loop	~ O(log (logn))		
for(i = 0; i < n; i++) {for(j = 0; j < n; j*2){}}	Outer loop repeats n times; inner loop repeats logn times	~O(nlogn)		
for(i = 1; i < n; i = i*3)		~O(logn) with base 3		
While loops				
while vs. do while	do while will execute for minimum one time			
for and while are almost similar	do while will execute as long as the condition is true; for loop will execute until the condition is false			
a = 1;				
while(a < b){ a = a *2;}	1, 2, 2^2, 2^32^k repetitions	~O(logb) with base 2		
	assume $a > b$; $2^k > b ==> k = logb$ with base 2			
i = n; while(i > 1) {i = i/2;}		~O(logn) with base 2		
$i = 1; k = 1; while(k < n){k = k + i; i++;}$				
	i k			
	1			
	2 1 + 1			
	3 2 + 2			
	4 2 + 2 + 3			

		5 2 + 2 + 3 + 4	
	m	m(m + 1) /2	
	Assume, k >= n	m(m + 1)/ 2 >= n	~O(root(n))
	while(m != n) { if(m > n) m = m - n; else n = n - m;}		~O(n)
10	Types of time functions		
	O(1) constant		
	O(logn) logarithmic		
	O(n) linear		
	O(n^2) quadratic		
	O(n^3) cubic		
	O(2^n) exponential		
11	Order of complexity		
	1 < logn < root(n) < n < nlogn < n^2 < n^3 << 2^n < 3^n< n^n		
12	Asymptotic Notations		
	Representation of time omplexity in simple form which is understandable		
	Big O Notation - works as an upper bound	The function $f(n) = O(g(n))$ iff for all positive constants c and n_0 , such that $f(n) <= c * g$ (n) for all $n >= n_0$; here, $f(n) = O(n)$	e.g. 2n + 3 <= 10n; All those functions in time order complexity above n become upper bound; below n become lower bound and n is the average bound

	Big Omega Notation - works as a lower bound	The function $f(n) = Omega(g(n))$ iff for all positive constants c and n_0 , such that $f(n) >= c * g(n)$ for all $n >= n_0$; here, $f(n) = Omega(n)$	e.g. 2n + 3 >= 1n		
	Theta Notation - works as an average bound	The function $f(n) = \text{theta}(g(n))$ iff for all positive constants c1, c2 and n0 such that c1 * $g(n) <= f(n) <= c2 * g(n)$	e.g. f(n) 2n + 3; 1n <= 2n + 3 <= 5n		
	Most useful is theta notation, then why do we need the other two?	In case we are not able to get the average bound, then we point to its upper or lower bound			
	13 Examples for asymptotic notations				
а	f(n) = 2n^2 + 3n + 4				
	$2n^2 + 3n + 4 \le 2n^2 + 3n^2 + 4n^2$ i.e. $9n^2$	O(n^2)			
	2n^2 + 3n + 4 >= 1n^2	Omega(n^2)			
	1n^2 <= 2n^2 + 3n + 4 <= 9n^2	Theta(n^2)			
b	$f(n) = n^2 log n + n$				
	$n^2\log n \le n^2\log n + n \le 10n^2\log n$	O(n^2logn)			
		Omega(n^2logn)			
		Theta(n^2logn)			
С	f(n) = n!				
	1 <= 1*2*3*4*n-1*n <= n*n*n*n**n	O(n^n)			
		Omega(1)			
		Cannot find theta for n!			
d	f(n) = logn!	0(1) (1)			
	1 <= log(1*2*3*n) <= log(n*n*n*n*n)	O(logn^n)			
		Omega(1)			
		Cannot find theta for logn!			
	14 Properties of Asymptotic notations				
	General properties -				
	if $f(n)$ is $O(g(n))$ then $a*f(n)$ is $O(g(n))$				
	e.g. $f(n) = 2n^2 + 5$ is $O(n^2)$, then $7f(n)$ i.e. $14n^2 + 35$ is also $O(n^2)$	This would be true for both Omega and theta n as well			
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	Reflexive property -				
	If f(n) is given then f(n) is O(f(n))				
	e.g. $f(n) = n^2$ then $O(n^2)$	A function is an upper bound of itself			
		Similarly, a function is a lower bound of itself			
	Transitive property -				
	If $f(n)$ is $O(g(n))$ and $g(n)$ is $O(h(n))$ then $f(n)$ is $O(h(n))$				
	e.g. f(n) = n; g(n) = n^2 and h(n) = n^3	True for all notations			
	n is O(n^2) and n^2 is O(n^3) then n is O(n^3)				
	Symmetric property -				
	If f(n) is theta(g(n)) then g(n) is theta(f(n))	True for only theta(n)			
	e.g. $f(n) = n^2 g(n) = n^2$; $f(n) = theta(n^2)$ and $g(n) = theta(n^2)$				
	Transpose symmetric -	True for BigO and Omega notations			
	if $f(n) = O(g(n))$ then $g(n)$ is $Omega(f(n))$	True for Engle and emega netations			
	e.g. $f(n) = n$ and $g(n)$ is n^2 then n is $O(n^2)$ and n^2 is				
	Omega(n)				
	If $f(n) = O(g(n))$ and $f(n) = Omega(g(n))$ then $g(n) \le f(n) \le g$ (n) therefore $f(n) = theta(g(n))$				
	If $f(n) = O(g(n))$ and $d(n) = O(e(n))$ then $f(n) + d(n) = O(max(g(n), e(n)))$				
	e.g. $f(n)=n=O(n)$, $d(n)=n^2=O(n^2)$ then $f(n)+d(n)=n+n^2=O(n^2)$				
	If $f(n) = O(g(n))$ and $d(n) = O(e(n))$ then $f(n) * d(n) = O(g(n) * e(n))$				
15	Comparison of functions				
	First method is substituting values for n and comparing				
	Second method is applying log on both sides				
		Properties of log -			
	Example -	logab = loga + logb			
	$f(n) n^2logn; g(n) = n(logn)^10$	loga/b = loga - logb			
	Apply log	loga^b = bloga			

log(n^2log(n)); log(n(logn)^10)	a^(log_cb) = b^(log_ca)			
log(n^2) + loglogn; logn + loglog^10	a^b = n then b = log_an			
2logn + loglogn ; logn + 10loglogn				
here; 2logn is greater than logn and logn is a bigger term than loglogn				
so, first term is greater than the second one				
$f(n) = 3n^{(rootn)}; g(n) = 2^{(rootn log_2(n))}$				
Applying log				
3n(rootn); (n^rootn)log_2(2)				
3n(rootn); nrootn				
first term is greater than the second one value wise but asymptatically they are equal				
$f(n) = n^{(\log n)}; g(n) = 2^{(rootn)}$				
apply log,				
log(n^logn); log(2^rootn)				
logn*logn ; rootn (log_2(2))				
log^2n ; rootn				
canot judge, so apply log again				
2loglogn; 1/2logn				
loglogn is smaller than logn				
thus, second term is greater				
$f(n) = 2^{(logn)}; g(n) = n^{(rootn)}$				
logn*log_2(2); rootn*logn				
logn ; rootn*logn				
second term is greater				
f(n) = 2n; g(n) is 3n				
both are equal asymptotically				
$f(n) = 2^n; g(n) = 2^2(2n)$				
applying log				
log(2^n); log(2^2n)				
n; 2n	after applying log, do not cut coefficients			

	second function is greater			
16	Best, worst and average case analysis			
	Example -			
а	Linear search			
	A = {8, 6, 12, 5, 9, 7, 4, 3, 16, 18} key = 7			
	In linear search, it will start checking for the given key from left hand side			
	total in 6 comparisons, we would get our key			
	Best case - key element is present at first index			
	Best case time - 1 i.e. B(n) = O(1); Omega(1); Theta(1)			
	Worst case - key element is present at the last index			
	Worst case time - n i.e. W(n) = O(n); Omega(n); Theta(n)			
	Average case = all possible case time / no. of cases			
	average case analysis is very difficult for most of the cases			
	Here, average case time = $1 + 2 + 3 + n/2 = n(n+1)/2n = n+1/2$			
	A(n) = n+1/2			
b	Binary search tree			
	height = logn			
	time taken for a particular key is logn			
	Best case - element present in the root			
	Best case time - k i.e. B(n) = O(1); Omega(!); Theta(1)			
	Worst case - searching for a leaf element - depends upon the height of the tree			
	Worst case time - logn i.e. O(logn)			
	min w(n) = logn; max w(n) = n			
17	Disjoint sets			
	No common numbers between two sets - intersection is zero			
	Operations - find, union			
	Find - search or check membership			
	Union - Add an edge			
	Krisgal algorithm: If you take an edge and both the vertices belong to the same set, then there is a cycle in the graph			

Weighted union is used while adding edges and detectig cycle Collapsing find - process of directly linking node to a direct parent of a set is called collapsing find - reduces the time to find 18 Divide and conquer - Strategy 1 Strategy - an apprach for solving a problem If a problem cannot be solved, divide it into sub-problems and find a solution for each sub problem, combine the solutions. One point to note is that each sub problem should be similar to the original problem only. Recursive in nature Should have one method to combine the solutions of each sub problem	
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19 Problems under Divide and Conquer	
Binary search	
Finding maximum and minimum	
MergeSort	
QuickSort	
Strassen's matrix multiplication	
20 Recurrence relation 1: T(n) = T(n-1) + 1	
void test(int n)	
{	
if(n > 0){	
printf("%d",n);	
test(n-1)	
}	
}	
test(3)	
3. test(2)	
2. test(1)	
1 test(0)	

each print statement takes constant time 1 and there are n+ 1 calls made to the function. we can ignore the last call when it is not printing			
f(n) = n + 1 calls; $O(n)$			
T(n) = T(n-1) + 1; if we ignore if condition			
Let us solve this relation;			
if we know T(n-1), we can get T(n)			
T(n-1) = T(n-2) + 1			
T(n) = [T(n-2) + 1] + 1			
T(n) = T(n-3) + 3			
continue for k times			
T(n) = T(n-k) + k			
We would stop after k substitutions; now we need to find k			
Assume n - k = 0; therefore n = k			
T(n) = T(n-n) + n			
T(n) = T(0) + n			
T(n) = n + 1 i.e. theta(n)			
Recurrence relation 2: T(n) = T(n-1) + n (decreasing 21 function)			
void test(int n)	T(n)		
{			
if(n > 0)	1		
{			
for(i = 0; i <n; i++)<="" td=""><td>n+1</td><td></td><td></td></n;>	n+1		
{			
printf("%d", n);	n		
}			
test(n-1);	T(n-1)		
}			
}			
	T(n) = T(n-1) + 2n + 2 i.e. theta(n)		
we can also write $T(n) = T(n-1) + n$ for $n > 0$			
T(n) = 1 for $n = 0$			
T(n)	n time		
n T(n-1)	n-1 time		

	n-2 T(n-3)	n - 3 time			
	T(2)				
	2 T(1)	2 units of ti me			
	1 T(0)	1 unit of time			
	for T(0) it does nothing	0 unit of time			
	time taken -				
		0 + 1 + 2 ++ n-1 + n			
	theta(n^2)	T(n) = n(n+1)/2			
	T(n) = T(n-1) + n				
	T(n-1) = T(n-2) + n-1				
	thus, $T(n) = T(n-2) + (n-1) + n$	**remember, don't add the terms			
	T(n) = T(n-3) + (n-2) + (n-1) + n				
	T(n) = T(n-k) + (n-(k-1)) + (n-(k-2))+(n-1) + n	if we continue for k times			
	assume n - k = 0; n = k				
	Thus, $T(n) = T(n-n) + (n-n+1) + (n-n+2) + (n-1) + n$				
	T(n) = T(0) + n(n+1)/2				
	T(n) = 1 + n(n+1)/2	theta(n^2); this extra 1 is owing to the calls			
2	2 Recurrence relation 3: T(n) = T(n-1) + logn				
	void test(int n)	T(n)			
	{				
	if(n>0)				
	{				
	for(i = 1; i <n; i="i*2)</td"><td></td><td></td><td></td><td></td></n;>				
	{				
	printf("%d", i);	log n times			
	}				
	test(n-1);	T(n-1)			
	}				
	}				
	T(n) = T(n-1) + logn for n > 0				
	T(n) = 1 for n = 0				
	Solve using tree method,				

T(n)				
logn T(n-1)				
log(n-1) T(n-2)				
log(n-2) T(n-3)				
log2 T(!)				
log 1 T(0)				
logn + log(n-1) ++ log2 + log1				
log[n(n-1)(n-2)2.1] = log(n!)	there is no tight bound for this function but there is an upper bound for it			
O(nlogn)				
Solving using induction method.				
T(n) = T(n-1) + logn				
T(n) = T(n-2) + log(n-1) + log(n)				
T(n) = T(n-3) + log(n-2) + log(n-1) + logn				
T(n) = T(n-k) + logn + log(n-1) + log1				
Asume n-k = 0				
T(n) = T(0) + logn!				
T(n) = 1 + logn!				
O(nlogn)				
23 How to get the direct answer for a recurrence relation?				
T(n) = T(n-1) + 1	O(n)			
T(n) = T(n-1) + n	O(n^2)			
T(n) = T(n-1) + logn	O(nlogn)			
$T(n) = T(n-1) + n^2$	O(n^3)			
T(n) = T(n-2) + 1	O(n/2) ~ O(n)			
T(n) = T(n-100) + n	O(n^2)			
T(n) = 2T(n-1) + 1	???			
24 Recurrence relation 4: T(n) = 2T(n-1) + 1				
Test(int n)	T(n)			
{	'\''')			-

if(n > 0)	1		
{			
printf("%d", n);	1		
test(n-1);	T(n-1)		
test(n-1);	T(n-1)		
}			
}			
	T(n) = 2T(n-1) + 1		
T(n) = 2T(n-1) + 1 for $n > 0$			
T(n) = 1 for n = 0			
Solve using recursion tree method			
1 T(n-1) T(n-1)		2	
1 T(n-2) T(n-2)	1 T(n-2) T(n-2)	4	
1 T(n-3) T(n-3) 1 T(n-3) T(n-3)	1 T(n-3) T(n-3) 1 T(n-3) T(n-3)	8	
T(0). T(0)		2^k	
1 + 2 + 2 ² +2 ^k = 2 ^(k+1) - 1			
as, a + ar + ar^2ar^k = a(r^(k+1) - 1)/(r -1)			
Assume n - k = 0			
thus, 2^(n+1) - 1	O(2^n)		
Back substitution method			
T(n) = 2T(n-1) + 1			
T(n) = 4T(n-2) + 2 + 1			
T(n) = 8T(n-3) + 4 + 2 + 1			
$T(n) = 2^kT(n - k) + 2^k(k-1) + 2^k(k)2^3 + 2^2 + 1$			
Assume n - k = 0			
n = k			
$T(n) = 2^nT(0) + 1 + 2 + 2^2 + 2^n-1$			

25 Master theorem for decreasing funct	ion		
T(n) = T(n-1) + 1	O(n)		
T(n) = T(n-1) + n	O(n^2)		
T(n) = T(n-1) + logn	O(nlogn)		
T(n) = 2T(n-1) + 1	O(2 ⁿ)		
T(n) = 3T(n-1) + 1	O(3 ⁿ)		
T(n) = 2T(n-1) + n	O(n2^n)		
T(n) = 2T(n-2) + 1	O(2 ⁿ /2)		
T(n) = aT(n-b) + f(n)			
$a > 0$, $b > 0$ and $f(n) = O(n^k)$ where $k > 0$	·= 0		
if $a = 1$, $O(n^k+1)$ or $O(n^*f(n))$			
if $a > 1$, $O(n^k * a^n/b)$			
$if(a < 1) O(n^k) \text{ or } O(f(n))$			
26 Dividing functions			
test(int n)	T(n)		
{			
if(n > 1)			
{			
printf("%d", n);		1	
test(n/2)	T(n/2)		
}			
}			
T(n) = T(n/2) + 1 for $n > 1$			
T(n) = 1 for $n = 1$			
T(n)			
1 T(n/2)			
1 T(n/2^2)			
1 T(n/2^3)			
continue for k times			
1 T(n/2^k)			

assume , n/2^k = 1				
thus, we have taken k steps overall				
since, $n/2^k = 1 \Rightarrow k = logn$ with base 2	O(logn)			
Solving by substitution method				
T(n) = T(n/2) + 1				
$T(n) = T(n/2^2) + 2$				
$T(n) = T(n/2^3) + 3$				
$T(n) = T(n/2^k) + k$				
assume n/2^k = 1				
thus, k = logn with base 2				
$T(n) = T(1) + \log n$				
O(logn)				
27 Recurrence relation: T(n) = T(n/2) + n				
T(n) = T(n/2) + n for $n > 1$				
T(n) = 1 for n=1				
T(n)				
T(n/2) n				
T(n/2^2) n/2				
T(n/2^3) n/2^2				
T(n/2^k). n/2^(k-1)				
$T(n) = n + n/2 + n/2^2 + n/2^3 + n/2^k$				
$T(n) = n[1 + 1/2 + 1/2^2 + 1/2^3 + 1/2^k]$				
T(n) = n*1 = n				
O(n)				
Using substitution method				
T(n) = T(n/2) + n				
$T(n) = T(n/2^2) + n/2 + n$				

$T(n) = T(n/2^3) + n/2^2 + n/2 + n$			
$T(n) = T(n/2^k) + n/2^k-1+n/2^2 + n/2 + n$			
Assume n /2^k = 1			
k = logn with base 2			
$T(n) = T(1) + n[1/2^k-1+1/2^2+1]$			
$T(n) = 1 + 2n \sim O(n)$			
28 Recurrence Relation: T(n) = 2T(n/2) + n			
void test(int n)	T(n)		
{			
if(n > 1)			
{			
for(int i = 0; i <n; i++)<="" td=""><td></td><td></td><td></td></n;>			
{			
stmt	n		
}			
test(n/2);	T(n/2)		
test(n/2);	T(n/2)		
T(n) = 2T(n/2) + n for n > 1			
T(n) = 1 for $n = 1$			
Solve using recursion tree method,			
T(n)			
T(n/2). $T(n/2)$ n	n		
T(n/2^2) T(n/2^2) T(n/2^2) n/2	n		
$T(n/2^3)$.	n		
	n		
T(n/2^k)			
	n		
assume n / 2^k = 1			
k = logn with base 2			
$T(n) = nk \sim O(n\log n)$			

	Using backsubstitution method;			
	T(n) = 2T(n/2) + n			
	$T(n/2) = 2T(n/2^2) + n/2$			
	$T(n) = 2[2T(n/2^2) + n/2] + n$			
	$T(n) = 2^2T(n/2^2) + n + n$			
	$T(n) = 2^3T(n/2^3) + 3n$			
	continue for k times			
	$T(n) = 2^kT(n/2^k) + kn$			
	Asume $T(n/2^k) = T(1)$			
	k = logn with base 2			
	Thus, $T(n) = n + nlogn \sim O(nlogn)$			
29	Masters Theorem for dividing functions			
	T(n) = aT(n/b) + f(n)	loga with b		
	$a>=1$; $b>1$; $f(n)=theta(n^k* log^pn)$	k		
	case 1: if loga with base b > k then theta(n^(loga with base b))			
	case 2: if loga with base b = k then			
	if $p > -1$ theta($n^{klog^{(p+1)}n}$)			
	if $p = -1$ theta(n^kloglogn))			
	if $p < -1$ then theta(n^k)			
	case 3: if loga with base b < k			
	then, if $p \ge 0$, theta($n^k\log^p n$)			
	if $p < 0$, theta(n^k)			
	T(n) = 2T(n/2) + 1			
	a = 2			
	b = 2			
	$f(n) = theta(n^{(0)} * log n^{(0)})$			
	k = 0; p = 0			
	here, loga with base b > k			
	theta(n^1) where loga with base b is 1			
	T(n) = 4T(n/2) + n			
	log a with base b = 2			

k = 1			
p = 0			
this is an example of case 1			
theta(n^2)			
T(n) = 8T(n/2) + n			
log8 with base 2 = 3 > k = 1			
theta(n^3)			
T(n) = 9T(n/3) + 1			
loga with base b = 2 > k			
theta(n^2)			
$T(n) = 9T(n/3) + n^2$			
loga with base b = 2 = k	case 2		
theta(n^2)			
T(n) = 8T(n/2) + n			
theta(n^3)			
T(n) = 2T(n/2) + n			
loga with base $b = k = 1$; $p = 0$			
case 2			
theta(nlogn)			
$T(n) = 4T(n/2) + n^2$			
theta(n^2logn)			
$T(n) = 4T(n/2) + n^2 log n$			
theta(n^2logn^2)			
$T(n) = 8T(n/2) + n^3$			
theta(n^3logn)			
T(n) = 2T(n/2) + n/logn			
log a with base b = k = 1			

	p = -1			
	theta(nloglogn)			
	$T(n) = 2T(n/2) + n/logn^2$			
	p = -2			
	theta(n)			
	$T(n) = 2T(n/2) + n^2$			
	loga with base b < k			
	theta(n^2)			
	$T(n) = 2T(n/2) + n^2$			
	theta(n^2logn)			
	$T(n) = 2T(n/2) + n^3$			
	loga with base b < k			
	theta(n^3)			
30	T(n) = 2T(n/2) + 1			
	loga with base b = 1			
	k = 0			
	loga with base b > k			
	theta(n^1)			
	T(n) = 4T(n/2) + 1			
	loga with base b = 2			
	k = 0			
	theta(n^2)			
	T(n) = 4T(n/2) + n			
	loga with base b = 2			
	k = 1			
	theta(n^2)			
	$T(n) = 8T(n/2) + n^2$			
	loga with base b = 3			

k = 2			
theta(n^3)			
$T(n) = 16T(n/2) + n^2$			
loga with base b = 4			
k = 2			
theta(n^4)			
T(n) = T(n/2) + n			
log a with base b = 0			
k = 1			
theta(n)			
$T(n) = 2T(n/2) + n^2$			
loga with base b = 1			
k = 2			
theta(n^2)			
$T(n) = 2T(n/2) + n^2 log n$			
loga with base b = 1			
k = 2			
theta(n^2logn)			
$T(n) = 4T(n/2) + n^3\log^2 2n$			
loga with base b = 2			
k = 3			
theta(n^3log^2n)			
$T(n) = 2T(n/2) + n^2 / logn$			
log a with base b = 1			
k = 2			
theta(n^2)			
T(n) = T(n/2) + 1			
log a with base b = 0			
k = 0			

thet	ta(logn)			
T(n) = 2T(n/2) + n			
log	a with base b = 1			
k =	1			
p =	0			
thet	ta(nlogn)			
T(n) = 2T(n/2) + nlogn			
log	a with base b = 1			
k =	1			
p =	1			
thet	ta(nlog^2n)			
T(n)	$) = 4T(n/2) + n^2$			
log	a with base b = 2			
k =	2; p = 0			
thet	ta(n^2logn)			
T(n)	$= 4T(n/2) + (nlogn)^2$			
	a with base b = 2			
k =	2, p = 2			
thet	ta(n^2 log^3n)			
) = 2T(n/2) + n/logn			
	a with base b = 1			
k =	1; p = -1			
thet	ta(nloglogn)			
	$) = 2T(n/2) + n/log^2n$			
	a with base b = 1			
	1; p = -2			
thet	ta(n)			
	ot function Recurrence relation			
T(n)) = T(root(n) + 1) for n>2			

	T(n) = 1 for $n = 2$				
	T(n) = T(root(n)) + 1				
	$T(n) = T(n^{(1/2)}) + 1$ equation 1				
	using substitution				
	$T(n) = T(n^{(1/2^2)}) + 2$ equation 2				
	$T(n) = T(n^{(1/2^3)}) +3$ equation 3				
	$T(n) = T(n^{(1/2^k)}) + k$ equation 4				
	assume, n = 2 ⁿ m				
	$T(2^m) = T(2^m/2^k) + k$				
	assume T(2^(m/2^k)) = T(2)				
	thus, m/2 ^k = 1				
	m = 2^k				
	k = log m with base 2				
	substituting value of n				
	m = logn with base 2				
	therefore, k = loglogn with base 2				
	theta(loglogn with base 2)				
32	Binary Search Iterative Method				
	To perform binary search, the prerequisite is that the list must be in sorted order	A = {3, 6, 8, 12, 14, 17, 25, 29, 31, 36, 42, 47, 53, 55, 62}			
	we need two index pointers, one is low at the starting point and the other is high at the end point	I = 1, h = 15 (lowest and highest index); mid = 8			
	mid = low + high / 2 and we take the floor value	key value = 42; A[mid] = 29> key > A [mid]			
	the key value is on the right hand side as key value is greater than A[mid]				
	we will change low to mid + 1	I = 9, h = 15; mid = 9 + 15 / 2 = 12			
		A[mid] = 47 > key			
	we will change high to mid - 1 as key < A[mid]				
		h = 11, I = 9, mid = 10; A[mid] = 36			
		A[mid] < key			
	we will change low to mid + 1	I = 11; h = 11; mid = 11; A[mid] = 42			
	we can return the index as we have found the key value	A[mid] = key			

therefore, binary search looks faster than linear search. It just took 4 comparisons			
int BinSearch(A, n, key)			
{			
l = 1, h = n			
mid = I + h / 2 - take floor value			
while(I <= h){			
if(key == A[mid])			
{ return index i.e.element is found}			
else if(key < A[mid])			
{h= mid-1;}			
else {			
I = mid + 1;}			
}			
return 0;			
}			
Time taken for binary search = logn			
min time: O(1)			
max time: O(logn)			
avg time = add time for each element and divide by number of elements			
33 Binarysearch Recursive method			
Alogirthm RBinarySearch(I,h,key)	T(n)		
{			
if(l==h)	1		
{			
if(A[low]== key)			
{			
return I;			
}			
else			
{			
return 0;			

	}	
	else	
	{	
	mid = I + h / 2 //taking floor value	1
	if(key == A[mid])	1
	{return mid;}	
	if(key < A[mid])	1
	{	
	return RBinarySearch(I, mid - 1, key)	T(n/2)
	}	
	else	
	{	
	return RBinarySearch(mid+1, h, key)	T(n/2)
	}	
	}	
		T(n) = 1; n =1
		T(n) = T(n/2) + 1 for $n > 1$
		theta(logn)
	34 Heaps	
а	Representation of a binary tree using an array	
	T {A, B, C, D, E, F, G}	
	if a node is at index i;	
	its left child is at node 2*i	
	its right child is at node 2*i + 1	
	its parent is at node i/2	
	if there are missing nodes, we leave a blank in its place in the	
	array	
b	Full binary tree	
~	In its hieght, it has maximum number of nodes and if we wish	
	to add a node, height would increase	
	Max no. of nodes = 2 ^h - 1	
С	Complete binary tree	
	there is no missing element from first element to the last element in array representation of the binary tree	

	Every full binary tree is also a complete binary tree		
	A complete binary tree is a full binary tree until height h - 1		
	Height of a complete binary tree would be minimum i.e. logn		
d	Неар		
	Heap is a complete binary tree		
	Max Heap: every node has value greater than all its descendants {50, 30, 20, 15, 10, 8, 16}		
	Min Heap: every node has value smaller or equal to than all its descendants {10, 30, 20, 35, 40, 32, 25}		
	35 Insert operation in a max heap		
	Insert 60 in the above given max heap		
	this value should be inserted in the last free space in the array		
	i.e. left child of the left most leaf node		
	Then, adjust the elements to make it as a heap		
	So, compare and move 60 up the levels and in the array check at i/2 indices where initially i would be the last empty index where 60 was inserted		
	Time taken would be equal to the number of swaps		
	this depends upon the height of the tree i.e. logn, hence O (logn)		
	minimum time is of no swaps O(1); max would be O(logn)		
	36 Delete operation in a max heap		
	From the heap, we need to remove the root / top most element only		
	The last element in the complete binary tree would come in its place		
	Adjust the elements to maintain heap order		
	From the root towards the leaf, adjust		
	Compare the children (2i and 2i +1) and whichever child is greater than compare with the parent		
	Time taken depends upon the height; max could be O(logn)		
	Whenever you delete from max heap, you get the next max element and in case of min heap, it would be the next min element		
	37 HeapSort		

	For a given set of numbers, create a heap				
	Delete all the elements from the heap				
	Total N elements we have inserted; each element we assume is moved up to the root; so time taken O(NlogN)				
	Then we delete the elements				
	Store deleted elements in the array in free space in the end				
	Deletion also takes O(NlogN) time				
	Thus, heapsort takes O(NlogN)				
38	Heapify				
	The process of creating heap but direction is opposite than creating a heap				
	O(N)				
39	Priority Queue				
	elements will have priority and they would be inserted and deleted as per the priority order				
	For min heap, smaller the no. higher the priority				
	For max heap, greater the no. higher the priority				
	O(logN) for insertion and/or deletion				
40	TwoWay MergeSort - Iterative method	Algorithm Merge(A, B, m, n)			
	merging two sorted lists to get a sorted result	{i = 1, j = 1, k = 1;			
	A = {2, 8, 15, 18} i	while(i <= m && j<=n){			
	B = { 5, 9, 12, 17} j	if(A[i] < B[j])			
	Compare A(i) with B(j) to get C(k) and move to next location	{			
	m + n elements are obtained , thus theta($m + n$)	C[k++] = A[i++];			
		}			
		else {			
		C[k++] = B[j++];			
		}			
		for(; i <=m; i++){			
		C[k++]=A[i];			
		}			
		for(;j<= n;j++){			
		C[k++] = B[j];			
		}			

		}			
41	Merging more than two lists				
	M-way merging				
	A = {4, 6, 12}				
	B = {3, 5, 9}				
	C = {8, 10, 16}				
	D = {2, 4, 18}				
	One way is that we merge A and B; C and D and then finally merge the two resulting lists> so we perform merge three times here				
	Another way is that we first merge A and B; then we merge resulting list with C; and the resulting list with D				
	Two-way mergesort is an iterative process whereas mergeSort is a recursive process				
	A = (0 2 7 5 6 4 9 2) given an array and we have to see				
	$A = \{9, 3, 7, 5, 6, 4, 8, 2\}$ - given an array and we have to sort them using 2-way mergesort				
Ist pass	We would consider each element as a sorted list and merge	merged n elements in this pass			
	First select two lists 3 and 9; then merge them - 3, 9				
	Similarly, we select two lists 7 and 5 , merge them - 5 and 7				
	Another lists we get are {4, 6} and {2, 8}				
	Now, we have 4 lists with two elements each				
2nd pass	When we merged we kept the resulting 4 lists in another array B; B = $\{\{3, 9\}, \{5, 7\}, \{4, 6\}, \{2, 8\}\}$	merged n elements in this pass			
	We merge two lists each				
3rd pass	C = {{3, 5, 7, 9}, {2, 4, 6, 8}}	merged n elements in this pass			
	we merge the above two lists to get a single sorted list				
	D = {2, 3, 4, 5, 6, 7, 8, 9}				
	log(no of elements) = no. of passes				
	Time complexity: O(n(logn))				
42	MergeSort				
	A = {9, 3, 7, 5, 6, 4, 8, 2}	Algorithm MergeSort(I, h){	T(n)		
	If there is a single element, we can consider it as a base or small problem {Divide and conquer}				
		if(l < h){			

		mid = (I + h) / 2;	1		
		MergeSort(I, mid);	T(n/2)		
		MergeSort(mid + 1, h);	T(n/2)		
		Merge(I, mid, h);	n		
		}	T(n) = 2T (n/2) + n for n > 1		
		}	T(n) = 1 for n = 1		
	time complexity: theta(nlogn)		using master's theorem, a = 2, b = 2, k = 1		
	merging is done in post order traversal		loga with base b = 1 = k		
			thus, it is case 2		
			theta(nlogn)		
43	Pros of MergeSort	Cons of MergeSort			
	works great for Large size lists	Extra space (not inplace sort)			
	suitable for Linked List	no small problem			
	supports external sorting	recursive and uses a stack (need n + logn space) i.e. space complexity: O(n + logn) where n is the extra space and logn is the stack space			
	stable: the order of duplicates is maintained				
		insertion sort (O(n^2))			
		mergesort O(nlogn)			
		for small problems, n <= 15; insertionsort works better> use insertion sort			
43	QuickSort				
	students arranging themselves in increasing order of heights				
	10 80 90 60 30 20				
	5 6 3 4 2 1 9				
	4 6 7 10 16 12 13 14				
	A = {10, 16, 8, 12, 15, 6, 3, 9, 5, INFINITY}	partition(I, h){			
	select first element as a pivot	pivot = A[I];			

	pivot = 10	i = I; j = h;		
	we need to find the sorted position for 10	while(i <j){do< td=""><td></td><td></td></j){do<>		
	i starting form pivot and j starting from infinity	{		
	i would check for elements greater than 10; j would heck for elements smaller than pivot	i++;		
	we are using the partitioning procedure	} while(A[i]<= pivot);		
	increment i until next vlue is greater than 10 and decrement j until next value is smaller than pivot; stop and swap	do		
	{10, 5, 8, 9, 3, 6, 15, 12, 16}	{		
	send pivot element at j position	j;		
	now, we can sort the two lists around the partitioning position by performing quicksort recursively	<pre>}while(A[j] > pivot);</pre>		
		if(i <j){< td=""><td></td><td></td></j){<>		
	QuickSort(I, h)	swap(A[i], A[j]);		
	{	}		
	if(I < h)	swap(A[I], A[j]);		
	{	return j;		
	j = partition(l, h);	}		
	QuickSort(I, j);			
	QuickSort(j+ 1, h);			
	}			
	}			
44	QuickSort Analysis			
	suppose it is partitioning in the middle of 1 and 15th index			
	then, two partitions: [1, 7]; [9, 15]			
	further partitions: [1, 3]; [5, 7]; [9, 11]; [13, 15]			
	at each level , n elements are being handled			
	and there are logn levels			
	thus time complexity for best case: O(nlogn)			
	median : middle element of a sorted list			
	best case of quicksort is that the partitioning occurs exactly at the middle			
	worstcase: if we have an already sorted list			
	time complexity for worstcase: O(n^2)			
	to handle this, try taking middle element as a pivot			

2. select random element as a pivot			
45 Strassen's matrix multiplication			
A = [a11 a12			
a21. a22]			
B = [b11 b12			
b21 b22]			
Cij = Summing up Aik*Bkj			
$for(i = 0; i < n; i++){$			
$for(j = 0; i < n; j++){$			
C[i,j]= 0;			
for(k=0;k <n;k++){< td=""><td></td><td></td><td></td></n;k++){<>			
C[i,j] += A[i, k]*B[k, i];			
}			
}			
}			
C11 = a11*b11 + a12*b21			
C21 = a11*b12 + a12*b22	A = [a11]		
C21 = a21*b11 + a22*b21	B = [b11]		
c22 = a21*b12 + a22*b22	C = [a11*b11]		
for [2*2] matrix, we would use above formula	for [1*1] matrix, use above formula		
we assume that the matrix has dimensions of power of 2	Algorithm MM(A, B, n)		
	{		
	if(n <= 2		
8 times the function is calling itself	{		
$T(n) = 8T(n/2) + n^2 $ for $n > 1$	C = 4 formula stated above;		
a = 8, b = 2, log a with base b = 3	}		
k = 2	else		
it is case 1 of master's theorem	{		
theta(n^3)	mid = n/2		
	MM(A11, B11, n/2) + MM(A12, B21, n/2);		
	MM(A11, B12, n/2) + MM(A12, B22, n/2);		
	MM(A21, B11, n/2) + MM(A22, B21, n/2);		
	MM(A22, B22, n/2) + MM(A21, B12, n/2);		

	}			
	}			
Strassen's approach -				
has given 4 different formulas with 7 multiplications	P = (A11 + A22)(B11 + B22)			
C11 = A11*B11 + A12*B21	Q = (A21 + A22) B11			
C21 = A11*B12 + A12*B22	R = A11(B12 - B22)			
C21 = A21*B11 + A22*B21	S = A22(B21 - B11)			
C22 = A21*B12 + A22*B22	T = (A11 + A12)B22			
<u> </u>	U = (A21 - A11)(B11 + B12)			
	V = (A12 - A22)(B21 + B22)			
	((((((((((((((((((((
	C11 = P + S - T + V			
	C12 = R + T			
	C13 = Q + S			
	C22 = P + R- Q + U			
	922 1 7 1			
	$T(n) = 7T(n/2) + n^2 $ for $n > 2$			
	T(n) = 1 for n<= 2			
	using master's theorm,			
	$O(n^{(\log 7 \text{ with base 2})}) = O(n^{2.81})$			
	, , ,			
Strategies used for solving optimization problems - G and bound	reedy Method, Dymanic programming, branch			
46 Greedy method				
Design wich we can adopt to solve similar problems		Greedy method says that each problem should be solved in stages - each stage we give an input, check if the solution is feasible then we pick it up and move to		

Algorithm Greedy(a, n) a = {a1, a2, a3, a4, a5}; n = 5 { Minimum cost journey - "Minimization problem"; then feasible solutions giving minimum cost are called optimal solutions. There can be many feasible solutions but ponly one optimal solution Example: Hire a person for your company Algorithm Greedy(a, n) a = {a1, a2, a3, a4, a5}; n = 5 { for i = 1 to n do { x = select(a): if feasible(x) then
Minimum cost journey - "Minimization problem"; then feasible solutions giving minimum cost are called optimal solutions. There can be many feasible solutions but ponly one optimal solution =xample: Hire a person for your company if feasible(x)
problem"; then feasible solutions giving for i = 1 to n do There can be many feasible solutions but only one optimal solution =xample: Hire a person for your company if feasible(x)
-xamble file a person for your combany
Method 2: Conduct an assessment center to filter people at each stage and get the best person
So, the person may not be the best but the approach is greedy here as we are using our criteria and constraints to choose the best person solution = solution + x;
}
Bag capacity is 15 kgs and we have been given 7 objects. we have to fill this bag with hese objects. Profit is the gain we get by transfering this object. Problem is a
container loading problem. Problem is filling the container with the objects as the capacity of container is limited
the container with the objects as the
the container with the objects as the capacity of container is limited
the container with the objects as the capacity of container is limited Optimization and maximization problem }
the container with the objects as the capacity of container is limited Optimization and maximization problem }
the container with the objects as the capacity of container is limited Optimization and maximization problem }
the container with the objects as the capacity of container is limited Optimization and maximization problem }
the container with the objects as the capacity of container is limited Optimization and maximization problem }
So, the person may not be the best but the approach is greedy here as we are using our criteria and constraints to choose the best person So, the person may not be the best but the solution = solution = solution + x;

Method 2	Take things with smaller weight so that you can put in more things		
Method 3	Take things that have highest profit by weight		
	Let's use method 3		
	First, I include object 5 that has maximum profit by weight. Then I check remaining weight I can put in. We can still put ir 14 kgs. Then we select all the quantity of object 1. Remaining weight limit 12 kgs. Add all of object 6. Remaining weight limit 8 kgs. Add all of object 3. Remaining weight limit 3 kgs. Add all of object 7. Remaining weight limit is 2 kgs. Add 2/3 cobject 2 as we have only 2 kgs limit remaining.		
X	(1 2/3 1 0 1 1 1)		
	Calculate total profit and verify weight		
	Total weight = 1*2 + 2/3*3 + 1*5 + 0*7 + 1*1 + 1*4 + 1*1 = 15	//Multiplying x elements by Weight w for each object	
	Total profits = 1*10 + 2/3*5 +1*15 + 1*6 + 1*18 + 1*3 = 54.6	//Multiplying x elements by Profit P for each object	
48	0/1 Knapsack problem		
	Objects are indivisble and fractions are not allowed i.e. either you include the whole thing or you do not include it at all		
49	Job sequencing with deadlines	n = 5 (tasks)	
Jobs	J1 J2 J3 J4 J5		
Profits	20 15 10 5 1		
Deadlines	2 2 1 3 3		
	Assume that there is a machine, on which each job has to be processed and each job takes 1 unit of time (hour) for completion		
	Set of the jobs which can be completed within their deadlines such that profit is maximized	Constraints: deadlines must be met	
deadlines	03	maximum 3 slots / jobs	
time slots	9am10am11am12am		
Jobs chosen	J2 J1 J4		
Profits	15 + 20 + 5 = 40		
Sequence	J1> J2> J4 J2> J1> J4		

Job consider	Slot assign	Solution	Profit
J1	[1,2]	J1	20
J2	[0,1][1,2]	J1J2	20 + 15
J3	[0,1][1,2]	J1J2	20 + 15
J4	[0,1][1,2][2,3]	J1J2J4	20 + 15 + 5
J5	[0,1][1,2][2,3]	J1J2J4	20 + 15 + 5
50	Job sequencing with deadlines another example	n = 7 (jobs)	
Jobs	J1 J2 J3 J4 J5 J6 J7		
Profits	35 30 25 20 15 12 5		
Deadlines	3 4 4 2 3 1 2		
deadlines	04	4 SLOTS AVAILABLE	
Jobs chosen	J4 J3 J1 J2		
Profits	20 25 35 30	110	0
5	Optimal Merge Patern		
	A = {3, 8, 12, 20}		
	B = {5, 9, 11, 16}		
	C = {3, 5, 8, 9, 11, 12, 16 20}	How merging works for two sorted lists; time = theta(m + n)	
	what happens if we have 4 lists?		
List	A B C D		
Sizes	6 5 2 3		
Choice 1	We can merge at a time two lists - first A and B; the merge it with C and finally with D. total cost= 11 + 13 + 16 = 40		
Choice 2	Merge A anb; C and D that gives cost 11 and 5 respectively. Merge resulting two lists which will cost 16. Total cost would be 11 + 5 + 16 = 32		
Choice 3	Merge Cand D, resulting list is merged with B and then finally with A; total cost = $5 + 10 + 16 = 31$		
optimal method	Always merge two small sized lists , then combined time would be reduced		

Example:													
List	x1	x2	х3	x4	x5								
	20	30	10	5	30								
Sizes	20	30	10	3	30								
Increasing order of	5	10	20	30	30								
sizes	3	10	20	30	30								
Lists	x4	х3	x1	x2	x5								
	First	x4 and	x3 are me	raed cos	st = 15: t	hen result is me	aed						
	with 2	<1; cost	= 35; x2 a	and x5 ar	e merge	d with cost = 60	the						
	two r	esulting	lists are r	nerged w	ith cost	= 95							
Total cost	15 +	35 + 60	+ 95 = 20)5									
	3*5 +	3*10 +	2*20 + 2*	30 + 2*3	0 = 205				of each node a	and size			
	-						of each	node					
52	_	nan Co											
			n techniqu	e used to	reduce	the size of data	or						
	mess	age											
	D00	4 D D D D	4 E O O D D	. = D D O O									
Message			AECCBBA	AEDDCC									
		th = 20											
			ent using	ASCII co	des (8-	oit)							
	A 6		1000001				Size = 8	3*20 = 160 bits					
	B 6		01000010										
	C 6												
	D 6	8											
	E 6	69											
	Can	we use	our own c	odes inst	tead of A	SCII codes?							
	Fixed	d size n	nethod										
Character	Α	В	C D	Е									
Count	3	5	6 4	2			Total co	unt = 20					
Code	000	001	010 0	11 10	0								
message	BCC	ABBDD	AECCBBA	AEDDCC	,								
bit code	0010						size = 2	0*3 = 60 bits					
DIL COUE	0010								code translati	ions			
							5"3 = 18	o bits> our a	ssigned codes	i			

		40 + 15 = 55 bits
		message: 60 bits
		chart: 55 bits
		total message size: 115 bits
		so, the message size reduced from 160 bits to 115 bits
		thus, 40% reduction in size with fixed sized code
	Huffman coding - variable sized code	element that appears more / often should have a smaller sized code
character	A B C D E	
count	3 5 6 4 2	
code		
	first, arrange the letters with increasing count / frequency	
character	E A D B C	
	2 3 4 5 6	
count	2 3 4 5 0	Mana tua amallar anna ura mat 5 dhan
code	000 001 01 10 11	Merge two smaller ones, we get 5, then combine with D, we get 9. Combine B and C, we get 11. Finally, combine two resulting lists, we get 20.
bit count	6 9 8 10 12	On left side paths, mark as 0 and on right side mark as 1
total bits for message	45 bits	Bit count for message can also be obtained from the tree, by counting number of edges for a letter and multiplying by the number of occurences for that letter in the message i.e. summation of distance and frequency of a letter
ASCII codes for chart	5*8 = 40 bits	
assigned codes	12 bits	
total bits for tree/table	52 bits	
Size of total msg	52 + 45 = 97 bits	
Message transferred	00111110110111100101100011111010001010000	A tree or a table would be needed along with it
Decoding	BCCD	
	1	

5	Minimum Cost Spanning Tree				
	G = (V, E)				
	V = {1, 2, 3, 4, 5, 6}	V = n = 6			
	E= {(1,2), (2,3), (3,4), (4,5), (5, 6), (6,1)}	V - 1 = 5 edges			
	the tree should not have a cycle				
	S is a subset of G, WHERE IN S = (V', E')	V' = V; E' = V - 1			
	Number of edges in graph = 6 out of whch I have to select 5 edges for spanning tree - thus i can select in 6C5 ways	Suppose we have 7 edges, out of which the seventh edge (3,5) divides the graph into two cycles of less tha 6 vertices, then we can select 5 edges for spanning tree in 7C5 - 2 ways			
General formula	E C(V -1) - no. of cycles				
	Now, if we have a weighted graph, I wish to know the number of possible spanning tree				
	Vertices = 4				
	Edges = 3				
	cost = 14				
	similarly , depending upon the edges we select, cost may vary each time				
	Can I found the minimum cost spanning tree?				
Method 1	Try all possible spanning trees and get the minimum cost spanning tree				
Method 2	Prim's algorithm (Greedy method)				
Method 3	Kriskal's algorithm (Greedy method)				
Method 2:	Prim's algorithm				
	Select the minimum cost edge from the graph first	(6,1); w = 10			
	Then, following this select minimum cost edge but make sure it is connected to previously chosen vertices	(5, 6); w = 25			
		(5, 4); w = 22			
		(4, 3); w = 12			
		(3, 2); w = 16			
		(2, 7); w = 14			
	Now, if we add costs of all the chosen edges, total cost = 99				

	For non connected graphs we cannot find the minimum cost				
	spanning tree or spanning tree				
Method 3	Kruskal's method				
	Always select smallest cost edge				
	(1,6); w = 10				
	(3, 4); w = 12				
	(2, 7); w = 14				
	(2, 3); w = 16				
	(4, 5); w = 22				
	(5, 6); w = 25				
	total cost = 99				
		To get a minimum cost edge each time, min			
	vertices count : V	heap can be used			
	edges count: V - 1	theta(nlogn)			
	theta(V E)				
	theta(n.e) = theta(n^2)				
	for non-connected graphs, spanning tree cannot be found				
	Kruskal algo may give spanning tree for those non connected				
	componr=ents but bot for the graph as a whole				
	if in a certain graph, certain edges' weights are missing, then use the given weights of remaining edges to guess the weight				
	use the given weights of fernalling eages to guess the weight				
5	4 Dijkstra algorithm				
	Single source shortest path to all the vertices				
	find the shortest path to a vertex annu update it to other				
	vertices, this updation is called relaxation				
	Relaxation				
	$if(d[u] + c(u,v) < d[v]){d[v] = d[u] + c(u,v)}$				
	no of vertices = V				
	at most no. of vertices relaxing = V				

	V	vors	t case tim	e of Dijl	kstra algorit	hm: theta(n*n)				
	E	Exar	nple - star	ting ver	tex is 1					
selected vertex	2	2	3	4	5	6				
	4 5	50	45	10	infinity	infinity				
	5 5	50	45	10	25	infinity				
	2	15	45	10	25	infinity				
	3 4	15	45	10	25	infinity				
	6	15	45	10	25	infinity				
	A	\not	her exam	ole - sta	rting vertex	c is 1				
selected vertex	{	2,	3,	4]	}					
	2 {	3,	infinity,	,	5}					
	4 {	3,	infinity,		5}					
	3 {	3,	7,		5}					
	{	3,	7,		5}					
	A	Anot	her exam	ole - sta	rting vertex	c is 1				
selected vertex	{	2,	3,	4)	}					
	2 {	3,	infinity,		5}					
	4 {	3,	infinity,		5}					
	3 {		7,		5}					
	{	-3,	7,		5}					
	[6	Dijks edge	stra algorit e having n	hm mig egative	ht work or r weightage	night not work in case of en				
			amic prog							
) Oyn	amic prog	grammi	ng vs gree	dy method				

In Greedy method, we try to follow a predefined procedure that gives us the best / optimal result. The procedure is already known for optimization. But, in dynamic programming, we try to get all the solutions and then decide the best solution. Mostly dynamic programming questions are solved using recursive procedures. They follow a prnciple of optimality. In greedy method, decision is taken just once and followed through whereas in dynamic programming, decision is taken at each step			
Example:			
Fibonacci series			
fib(n) = 0 if n = 0	$T(n) = 2T(n-1) + 1{Approximating T(n-2) \sim T (n-1) here}$		
fib(n) = 1 if n = 1	Time taken would be O(2^n) by using Master's theorem		
fib(n) = fib(n-2) + fib(n-1) if n > 1	Why can't we reduce the function calls to reduce the time taken?		
	For this, we would take a global array and initially fill it with -1		
int fib(n) {	F = {-1,-1,-1,-1}		
if(n<= 1){	Then, as the function calls f(1), mark it as 1		
return n;}	Then f(0) is marked as 1		
return fib(n-2) + fib(n-1);	Then use the stored result to get the rest.		
}	Finally, F would get updated as we solve: F = {0, 1, 1, 2, 3, 5}		
	Total 6 calls are made then i.e. n+1 calls i.e. O(n)		
	This is called result of memorization		
From the above example, we can see reduction in number of calls from O(2 ⁿ) to O(n) using memorization. It follows top down approach. The same problem can be solved using tabular method (iterative process) as shown below:			
int fib(int n) {			
if(n <= 1) {			
return n;}			
F[0] = 0; F[1] = 1;			
for(int i = 2; i <= n; i++){			
F[i] = F[i-2] + F[i-1];			
}			
return F[n];			
}			

	F= {0, 1, 1, 2, 3, 5}			
	This is a bottom - up approach i.e. starting from F[0] and moving to F[n]			
56	Multistage Graph			
	A multistage graph is a directed weighted graph. The vertices are divided into stages such that the edges are connecting vertices from one stage to next stage only. First stage and last stage will have only one vertex to represent start and end point. This is usually used to represent resource allocation.			
	The objective of the problem is that I have to select a path which gives me minimum cost.	//it is a minimization or optimization problem		
	Dymanic programming works on principle of optimality. Principle of optimality says that a problem can be solved in a squence of decisions.			
	From first stage I have to select one optimal vertex that leads to minimum cost and I have to take this decision at each stage. Thus, I can apply dynamic programming here.			
V	1 2 3 4 5 6 7 8 9 10 11 12			
Cost	16 7 9 18 15 7 5 7 4 2 5 0	cost(5, 12) = 0; here 5 is the stage and 12 is the vertex		
d	2/3 7 6 8 8 10 10 10 12 12 12 12	cost(4, 9) = 4		
		cost(4, 10) = 2		
	Formula for multistage graph:	cost(4, 11) = 5		
	$cost(Ith\ stage,\ jth\ vertex\ no.) = cost(i,\ j) = min\{C(j,\ l) + cost(i+1,\ l)\}$	cost(3, 6) = min{ C(6, 9) + cost(4, 9) , C(6, 10) + cost(4, 10)} = min{6 + 4, 5 + 2} = 7		
		Similarly, $cost(3, 7) = min\{8, 5\} = 5$		
	Now, we will solve it by going in forward direction and taking decisions based on above data;	$cost(3, 8) = min\{7, 11\} = 7$		
	d(1,1) = 2	Similarly, $cost(2, 2) = min\{C(2, 6) + cost(3, 6), C(2, 7) + cost(3, 7), C(2, 8) + cost(3, 8)\}$ = $min\{11, 7, 8\} = 7$		
	d(2,2) = 7	$cost(2, 3) = min{9, 12} = 9$		
	d(3, 7) = 10	$cost(2, 4) = min\{18\} = 18$		
	d(4, 10) = 12	cost(2, 5) = min{16, 15} = 15		
	Path: 2> 7> 10> 12	cost(1,1) = min{16, 16, 21, 17} = 16		
	d(1, 1) = 3			
	d(2, 3) = 6			
	d(3, 6) = 10			
	d(4, 10) = 12			
	Path: 3> 6> 10> 12			

		So,	we ha	ve two	paths	s with s	same	cost.			
				e Gra			n)				
		Cos	t adja	acency	Matri	ix					main(){
		0	1	2	3	4	5	6	7	8	int stages = 4, min;
	0	0	0	0	0	0	0	0	0	0	int n = 8;
	1	0	0	2	1	3	0	0	0	0	int cost[9], d[9], path[9];
	2	0	0	0	0	0	2	3	0	0	int c[9][9] = {{0,0,0,0,0,0,0,0,0}, {0,0,0,0,0,2,3,0,0},}
	3	0	0	0	0	0	6	7	0	0	cost[n] = 0;
	4	0	0	0	0	0	6	8	9	0	for(int i = n-1; i >=1; i){
	5	0	0	0	0	0	0	0	0	6	min = 32767;
	6	0	0	0	0	0	0	0	0	4	for(int k = i + 1; k <= n; k++){
	7	0	0	0	0	0	0	0	0	5	$if(C[i][k] != 0 && C[i][k] +C[k] < min){$
	8	0	0	0	0	0	0	0	0	0	min = C[i][k] +C[k] ;
											d[i] = k;
		0	1	2	3	4	5	6	7	8	
cost			9	7	11	12	6	4	5	0	}
d			2	6	6	5	8	8	8		}
path			1	2	6	8					cost[i] = min;
											}
		Path [2] =	ath is calculated using the following formula: p[i] d[p[i-1]]; p 2] = d[p[2-1]] = d[1] = 2						mula: p	[i] d[p[i-1]] ; p	p[1] = 1, p[stages] = 11,
		time	com	plexity	/: O(n	^2)					for(i = 2; i < stages; i++){
											p[i] = p[d[i-1]];
	_			Shorte							
									to find O(n^3)	the shortest	
A0 =		1	2	3	4						
	1	0	3	INF	7						
	2	8	0	2	INF						
	3	5	INF	0	1						
	4	2	INF	INF	0						
		Con	sideri	ng vert	ex 1 a	ıs intei	rmedia	ate ver	tex		A0[2,3] A0[2,1] + A0[1,3]
A1 =		1	2	3	4						2 < 8 + INF

1 0 3 INF 7 2 8 0 2 15 A0[2,4] A0[2,1] +A0[1,4] 3 5 8 0 1 INF > 8 + 7 = 15 A0[3,2] A0[3,1] +A0[1,2] Considering vertex 2 as intermediate vertex INF > 5 + 3 = 8 A2 = 1 2 3 4 A[1,3] A[1,2] +A[2,3] INF < 3 + 2 = 5 3 5 8 0 1 A[1,3] A[1,2] +A[2,3] INF < 3 + 2 = 5 A[1,3] A[1,2] +A[2,3] A[1,3] A[1,	
3 5 8 0 1 4 2 8 INF 0 A0[3,2] A0[3,1] + A0[1,2] Considering vertex 2 as intermediate vertex INF > 5 + 3 = 8 A2 = 1 2 3 4 1 0 3 5 7 A[1,3] A[1,2] + A[2,3] 2 8 0 2 15 INF < 3 + 2 = 5 3 5 8 0 1 4 2 5 7 0 for(k = 1; k <= n; k++){ for(j = 1; j <= n; j++){ for(j = 1; j <= n; j++){ A3 = 1 2 3 4 A[i,j] = min(A[i,j], A[i,k] + A[k,j]) 1 0 3 5 6 } 2 7 0 2 3 } 3 5 8 0 1 4 2 5 7 0	
4 2 8 INF 0 A0[3,2] A0[3,1] +A0[1,2] Considering vertex 2 as intermediate vertex INF 5 5 +3 8 A1 2 3 4 <th></th>	
A0[3,2] A0[3,1] +A0[1,2] Considering vertex 2 as intermediate vertex INF > 5 + 3 = 8 A2 = 1 2 3 4 A[1,3] A[1,2] + A[2,3] A[1,3] A[1,2] + A[2,3] INF < 3 + 2 = 5 A[1,3] A[1,2] + A[2,3] A[1,3]	
Considering vertex 2 as intermediate vertex A2 = 1 2 3 4 1 0 3 5 7 A[1,3] A[1,2] + A[2,3] 1 NF < 3 + 2 = 5 NF < 4 2 5 7 0 for(k = 1; k <= n; k++){ for(i = 1; i <= n; i++){ Considering vertex 3 as intermediate matrix for(j = 1; j <= n; j++){ A3 = 1 2 3 4 A[i,j] = min(A[i,j], A[i,k] + A[k,j]) 1 0 3 5 6 } 2 7 0 2 3 } 3 5 8 0 1 A 2 5 7 0	
A2 = 1 2 3 4 1 0 3 5 7 A[1,3] A[1,2] + A[2,3] 2 8 0 2 15 INF < 3 + 2 = 5 3 5 8 0 1 4 2 5 7 0 for(k = 1; k <= n; k++){	
1 0 3 5 7	
2 8 0 2 15	
3 5 8 0 1 4 2 5 7 0 for(k = 1; k <= n; k++){ for(i = 1; i <= n; i++){ Considering vertex 3 as intermediate matrix for(j = 1; j <= n; j++){ A3 = 1 2 3 4	
4 2 5 7 0 for(k = 1; k <= n; k++){ for(i = 1; i <= n; i++){ Considering vertex 3 as intermediate matrix for(j = 1; j <= n; j++){ A3 = 1 2 3 4 A[i,j] = min(A[i,j], A[i,k] + A[k,j]) 1 0 3 5 6 } 2 7 0 2 3 } 3 5 8 0 1 } 4 2 5 7 0	
for(i = 1; i <= n; i++){ Considering vertex 3 as intermediate matrix for(j = 1; j <= n; j++){ A3 = 1 2 3 4	
Considering vertex 3 as intermediate matrix for(j= 1; j <= n; j++){ A3 = 1 2 3 4	
A3 = 1 2 3 4 A[i,j] = min(A[i,j], A[i,k] + A[k,j]) 1 0 3 5 6 3 5 8 0 1 <th></th>	
1 0 3 5 6 } 2 7 0 2 3 } 3 5 8 0 1 } 4 2 5 7 0	
2 7 0 2 3 } 3 5 8 0 1 } 4 2 5 7 0	
3 5 8 0 1 4 2 5 7 0	
4 2 5 7 0	
Considering vertex 4 as intermediate matrix	
A4 = 1 2 3 4	
1 0 3 5 6	
2 5 0 2 3	
3 3 6 0 1	
4 2 5 7 0	
Formula used to make the above matrices:	
$A[i,j] = min\{A[i,j], A[i,k] + A[k, j]\}$	
time complexity = O(n^3)	
59 Matrix chain multiplication	
A1 . A2 . A3 . A4	
(5X4) (4X6) (6X2) (2X7)	

	For generating a single matrix C after single multiplication of 2 matrices of order (5X4) and (5X3) , we would need to do 60 multiplications				
	((A1.A2).A3).A4				
	or (A1.A2).(A3.A4)				
	orthere could be several ways				
	then, how to choose theright way?				
	T(n) = 2nCn/n+1 trees are possible				
	thus, with 3 nodes; $T(3) = 5$				
	Using tabular approach (bottom up apprach),				
m		in m[1,1] i.e. A1 , nothing is multiplied, hence it can be taken as zero			
	1 0 120 88 158	m[1,2] = A1. A2			
	2 - 0 48 104	(5X4) (4X6)			
	3 0 84	Total cost of multiplication = 5 *4* 6 = 120			
	4 0				
		m[1,3] = A1.A2.A3			
s	1 2 3 4	Two possibilities: A1.(A2.A3) or (A1.A2).A3			
	1 - 1 1 3	(5X4) (4X6) (6X2)			
	2 3 2	for A1.(A2.A3)> m[1,1] + m[2,3] + (5*4*2)	for (A1.A2). A3> m[1,2] + m[3,3] + (5*6*2)		
	3 3	0 + 48 + 40	120 + 0 + 60		
	4	88	180		
		Similarly, m[2,4]			
	formula:	A2.(A3.A4) (A2.A3).A4			
	m[i,j] = m[i,k] + m[k+1, j] + di-1 * dk * dj	(4X6) (6X2)(2X7) (4X6) (6X2)(2X7)			
		for A2.(A3.A4)> m[2,2] + m[3,4] + (4*6*7)	for (A2.A3). A4> m[2,3] + m[4,4] + (4*2*7)		
	time complexity = O(n^3)	0 + 84 + 168	48 + 0 + 56		
		252	104		
		m[1,4]			

		min{m[1,1] + m[2,4] + (5*4*7), m[1,2] + m		
		[3,4] + (5*6*7), m[1,3] + m[4,4] + (5*2*7)}		
		min{0+104+140, 120 + 84+210, 88+70}		
		min{244, 414, 158}		
	60 Matrix chain multiplication - A few pointers			
	Condition of the multiplication : The number of columns in the first matrix involved in the multiplication must be equal to the number of rows in the second matrix			
A=	a11 a12 a13	2X3 dimension		
	a21 a22 a23			
B=	b11 b12	3X2 dimension		
	b21 b22			
	b31 b32			
A*B =	a11*b11 + a12*b21 + a13*b31 a11*b12 + a12*b22 + a13*b32	12 multiplications (2*3*2)		
	a21*b11 + a22*b21 + a23*b31 a21*b12 + a22*b22 + a31*b32	2X2 dimensions of the resultant matrix		
	A1 X A2 X A3 {Multiplication of more than two matrices}			
	2X3 3X4 4X2			
	d0 d1. d1 d2 d2 d3			
	Same answer by the two following methods (Associative property)			
	Method 1: (A1 X A2) X A3	Method 2: A1 X (A2 X A3)		
	2X3 3X4 i.e (2*3*4) = 24 multiplications for A1 X A2	2X3 3X4 4X2		
	Now, (A1 X A2) X A3 would require (2*4*2) = 16 multiplications	A2 X A3 requires (3*4*2) = 24 multiplications		
	Thus, altogether 40 multiplications are required	A1 X (A2 X A3) requires (2*3*2) = 12 multiplications		
		Altogether, 36 multiplications are needed here.		
	Now, dynamic programming asks us to find all the possible methods for matrix multiplication and check which one costs the minimum> thsi implies that for 10 matrices, there would be numerous methods and we would have to check for all before proceeding with any one of them. Thus, we need a formula to check all that			
	We need to find C[1,3]			
	Method 1: (A1 X A2) X A3	Method 2: A1 X (A2 X A3)		
	C[1,2] = 24; $C[3,3] = 0$	C[1,1] = 0; C[2,3] = 24		

	C[1,2] + C[3,3] + d0*d2*d3 = 40	C[1,1] + C[2,3] + d0*d1*d3 = 36		
	C[i,j] = C[i, k] + C[k+1, j] + di-1 * dk * dj			
	After generalization,			
	$C[i,j] = min \{ C[i,k] + C[k+1,j] + di-1 * dk * dj \}$			
	where i<=k <j< td=""><td></td><td></td><td></td></j<>			
	A1 X A2 X A3 X A4			
	d0 d1 d1 d2 d2 d3 d3 d4			
	Check which method works the best for the above matrix chain multiplication	2n C n / n + 1 multiplications are possible where n = no. of matrices - 1		
	1. A1 (A2 (A3A4))	Modified formula: 2(n-1) C (n-1) / n		
	2. A1 ((A2A3)A4)	Now, for n = 4, 2*3C3 / 4 = 6*5*4/3*2*1 / 4 = 5		
	3. (A1A2)(A3A4)	n = 5, 14 multiplications		
	4. (A1(A2A3))A4			
	5. ((A1A2)A3)A4			
	Applying the formula			
4.4.0	Applying the formula:			
4-1 = 3 values	$C[1,4] = min \{ k = 1; C[1,1] + C[2,4] + d0*d1*d4,$			
	k = 2; $C[1,2] + C[3,4] + d0*d2*d4$,			
	k = 3; $C[1,3] + C[4,4] + d0*d3*d4$			
	1<= k < 4			
	4.44 (404044)			
	1. A1 (A2A3A4)			
	2. (A1 A2) (A3 A4)			
	3. (A1A2A3) A4			
	here, C[1,1] = 0; C[4,4] = 0			
4-2 = 2 values	$C[2,4] = min\{k = 2; C[2,2] + C[3,4] + d1*d2*d4$			
	k = 3; C[2,3] + C[4,4] + d1*d3*d4}			
	2<=k<4			

4-3 = 1 value		C[3,4]	= C[3,3] +	C[4,4] + d2	*d3*d4			
		A1 X A	2 X A3 X A	\4				
		3X2 2	X4 4X2 2	X5				
			1 d2 d2 d3 d					
		such a	s C[3,4] or	C[4,4], the	repetition of the values needed , re is unneccessary calculation, nould use a table (4X4)			
C table		1	2	3	4	$C[1,2] = min\{k=1; C[1,1] + C[2,2] + d0*d1*d2$		
	1	0	24	28	58	Thus, C[1,2] = 3*2*4 = 24		
	2	_	0	16	36	$C[2,3] = min\{k = 2; C[2,2] + C[3,3] + d1*d2*d3$		
	3	-	-	0	40	Thus, C[2,3] = 2*4*2 = 16		
	4	-	-	-	0	C[3,4] = d2*d3*d4 = 4*2*5 = 40		
						$C[1,3] = min\{k=1; C[1,1] + C[2,3] + d0*d1*d3$		
k table		1	2	3	4	k = 2; C[1,2] + C[3,3] + d0*d2*d3}		
	1	-	1	1	3	C[1,3] = min{16 + 3*2*2, 24 + 3*4*2}		
	2	-	-	2	3	C[1,3] = min{28, 48] = 28		
	3	-	-	-	3			
	4	-	-	-	-	$C[2,4] = min\{C[2,2] + C[3,4] + d1*d2*d4,$		
						C[2,3] + C[4,4] + d1*d3*d4}		
					ed to do minimum of 58 ult of A1 X A2 X A3 X A4	$C[2,4] = min\{40 + 2*4*5 , 16 + 2*2*5\}$		
		The k	table will gi	ve the para	anthesization	C[2,4] = min{80, 36} = 36		
		((A1) (A2 A3))(A	\ 4)				
		How m ~ n^2	nuch time it	has taken	? 1+2+3+4 = 4(5) /2 i.e. n(n+1)/2	C[1,4] = min{k = 1; C[1,1] + C[2, 4] + d0*d1*d4,		
		we als	o tried n po ne taken is	osisble valu s n^2 * n i.e	es of k to compute this value, . O(n^3)	k = 2; C[1,2] + C[3,4] + d0*d2*d4,		
						k=3; C[1,3] + C[4,4] + d0*d3*d4}		
						C[1,4] = min{36 + 3*2*5, 24 + 40 + 3*4*5, 28 + 3*2*5}		
						C[1,4] = min{66, 124, 58} = 58		
	61	Matrix	chain mu	Itiplication	Program			
		A1 X A	2 X A3 XA	4		main{		
		5X4 4	X6 6X2 2	X7		int n = 5;		

	int P[] = {5, 4, 6, 2, 7};		
P = { 5,4,6,2,7}	int m[5][5] = {0};		
	int s[5][5] = {0};		
	int j, min, q;		
	for(int d = 1; d < n -1; d++)		
	{		
	for(int $i = 1$; $i < n - d$; $i++$)		
	{		
	j = i + d;		
	min = 32767;		
	for(int $k = 1$; $k < = j - 1$; $k++$)		
	{		
	q = m[i][k] + m[k + 1][j] + P[i - 1] * P[k] * P[j];		
	if(q < min)		
	{		
	min = q;		
	s[i][j] = k;		
	}		
	}		
	m[i][j] = min;		
	}		
	}		
	cout << m[1][n -1];		
	}		
Single source shortest path (Bellman Ford Algorithm)	Example of Bellman Ford algorithm:		
For doing this, we already have Dijkstra algorithm but it may not eork correctly if we have negative weights, thus we need some other method that works with negative weights	edges> (3,2)(4,3)(1,4)(1,2)		
Bellman Ford algorithm says that we should relax the edges N-1 times where the number of vertices is equal to N	mark source vertex 1 as 0 and rest all as infinity		
V = N = 7	there are 4 vertices, so we should relax allt the edges for 3 times		
So, we should relax them for V - 1 times	First iteration:		
so, we would cover all possible paths even the longest path	for (3,2)> infinity - 10 is infinity only, so no change		

Relaxation means between a pair of vertices u and v if there is an edge, then check if:	for (4,3)> infinity + 3 s infinity only, so no change			
$if(d[u] + C(u,v) < d[v]){$	for (1,4), 0 +5 < infinity , thus vertex 4 is updated to 5			
d[v] = d[u] + C(u,v)	for (1,2) 0 + 4 < infinity, thus vertex 2 is updated to 4			
edgeList> (1,2)(1,3)(1,4)(2,5)(3,2)(3,5)(4,3)(4,6)(5,7)(6,7)	Second iteration:			
Now, I have to relax these edges for V - 1 i.e. 6 times	for (3,2), vertex 2 is already 4, which is less than d[u] + C(u,v) in this case			
Initially, mark the distance for source vertex as 0 and for the rest of the vertices as infinity	for (4,3) vertex 3 is updated to 5+3 = 8			
Now, let's relax edge (1,2)	for (1,4)> no change			
here, $d[u] = 0$; $d[v] = infinity$; $C(u,v) = 6$	for(1,2)> no change			
0 + 6 < infinity ; thus d[v] = 6	Third iteration			
for vertex 2, distance is 6;	for(3,2), $8 - 10 = -2 < d[v]$ which is 4 right now; thus updated for vertex 2 as -2			
similarly, relaxing (1,3); thus its distance is updated to 5 from infinity	for the rest of the edges there won't be any change			
in similar way, (1,4) is relaxed, following that the distance of vertex 4 is updated to 5 from infinity	results obtained :			
Now, relaxing (2,5); $d[u] = 6$; $C(u,v) = -1$; $d[v] = infinity$	vertex 1> 0			
the distance (2,5) is updated to 6 - 1 = 5	vertex 2> -2			
similarly, relaxing (3,2); d[u] = 5, C(u,v) = -2, d[v] = 6	vertex 3> 8			
5 - 2 = 3 < 6 thus, d[v] is updated here to 3 i.e. at vertex 2, distance is updated to 3	vertex 4> 5			
Now, relaxing (3,5), $d[u] = 5$, $C(u,v) = 1$, $d[v] = 5$ here $d[u] + C(u,v)$ is not smaller than $d[v]$ hence the distance of vertex 5 is not modified	Now, if I relax one more time extra, there's no change			
Moving to (4,3), relaxing it> $d[u] = 5$, $C(u,v) = -2$; $d[v] = 5$, $d[u] + C(u,v) = 3 < d[v]$ hence distance of vertex 3 is updated to 3	Drawback of Bellman Ford algorithm:			
following this (4,6) is relaxed again and checked, $d[u] = 5$, C $(u,v) = -1$; thus distance of vertex 6 is updated to 5-1 = 4	let us an edge(2,4) in the above example			
Now, relaxing (5,7), $d[u] = 5$; $C(u,v) = 3$; $d[v] = infinity$	we see even after N-1 iterations, there is one vertex changing, we note that there's a problem			
thus, d[v] is updated to 8 for edge (5,7)	the reason is that there is a cycle of edges where total weight of edges is negative i.e. $5 + 3 + (-10) = -2$, thus graph cannot be solved			
moving to (6,7), $d[u] = 4$, $C(u,v) = 3$; $d[v] = 8$	hence, for a negative weighted cycle , the bellman ford algorithm fails			

d[v] is updated to 7 here for edge (6,7)			
let us continue second time;			
there won't be any change in (1,2), (1,3), (1,4)			
when we check for $(2,5)$; $d[u] = 3 C(u,v) = -1 d[v] = 5$; $d[v]$ for edge $(2,5)$ is updated to 2			
similarly, for edge $(3,2)$, the value is change to $3 - 2 = 1$; earlier it was 3			
(4,3) and (4,6), there's no change			
for $(5,7)$ d[u] has changed from 5 to 2; thus d[v] changes to 2 $+$ 3 = 5			
for (6,7) there won't be any change			
let us continue third time;			
there won't be any change in (1,2), (1,3), (1,4),			
when we check for $(2,5)$; $d[u] = 1$ $C(u,v) = -1$ $d[v] = 2$; $d[v]$ for edge $(2,5)$ is updated to 0			
for (3,2) there own't be any change			
for (3,5) again thee won't be any change			
for (4,3), (4,6)> no change			
for (5,7) d[v] gets updated to 0 + 3 = 3			
for (6,7)> no change			
let us check for fourth time,			
we notice for all edges> no change			
results obtained:			
vertex 1> 0			
vertex 2> 1			
vertex 3> 3			
vertex 4> 5			
vertex 5> 0			
vertex 6> 4			
vertex 7> 3			
so, finally these are the shortest paths			
time complexity: O(E (V - 1)) ~ O(V E) ~ O(N^2)			
If it is a complete graph, that is between every two vertex there is an edge, then number of edges is N(N - 1) / 2			
i.e. E = N(N - 1) /2			
then time complexity = $O(E V) O(N((N-1)/2)(N-1)) \sim O(N^3)$			

	e.	0/4	1 Knapsack Problem = 8; n = 4 where m is the capacity of the bag										
	ο.			•			0.000	ooitu of	thaka	~			
		_				II IS TN	e cap	acity 01	me ba	y			
		_	-	2, 5, 6]									
				3, 4, 5	-								
		Ha ma	ve to iximiz	give a e prof	a soluti fit	on of	what a	all shou	ıld be ir	ncluded 1	0		
		хс	an be	e eithe	r 0 or	1; we	canno	ot take t	fraction	of an ob	ject		
		χV	vould	be like	e {1, 0,	,1}							
		su	m of p	orofits	is max	kimize	d i.e. ı	max{su	ım(Pixi)	}			
		su	m(wix	i) <= n	n								
		2^4	4 solu	itions	possib	le i.e.	n^4 s	olution	S				
		let	us u	us use tabulation method									
		+	as the capacity is 8 so we would take 0-8 columns and 0-5										
		as						take ()-8 colu	ımns and	0-5		
		rov	· · · · ·					i take c	, o oola	iiiiio aiic			
٧		0	1	2	3	4	5	6	7	8			
P W	0	0	0	0	0	0	0	0	0	0			
1 2	1	0	0	1	1	1	1	1	1	1			
2 3	2	0	0	1	2	2	3	3	3	3			
5 4	3	0	0	1	2	5	5	6	7	7			
6 5	4		0		2	5	6	6	7	8			
		V[i	,w] =	max{\	/[i-1, w	/], V[i ·	-1, w-\	w[i]]+ F	P[i]}				
										3,1], V[3	-41 + 6}		
		_								equal to			
		_								THAT L			
		5T		IGHT						IEGATIV			
				nBER ve fill these values as it is from previous row until colun					vious ro	ow until o	column		
		for	5th c	h column, $V[4,5] = max\{V[3,5], V[3,0] + 6\} = max\{5, 0 - 6\}$					3,0] + 6	6} = max{	5, 0 +		
		V[4	_	max{\	V[3,6]	, V[3,	1] + 6]	} = max	< {6, 6} -	> so tal	e 6		
		V[4	1,7] =	max{\	V[3,7],	V[3,2] + 6}	= max{	7,7} =	7			
		V[4	1,81 =	max{\	V[3,8].	V[3,3] +6} =	= max{7	7, 2 + 6	} = max{	7,8} = 8		

Now, we need to write down x1, x2, x3 and x4 values			
let us come with maximum profit i.e. 8 which we got only by including 4th object			
thus x4 = 1; remaining profit = 8 - 6 = 2			
now, check for object 3, if there is a value 2; check if the value 2 is there in for object 2 as well at the same place, if yes, then object 3 was not taken i.e. $x3 = 0$; if the same 2 is there for object 1 then $x2 = 0$ else $x2 = 1$			
here, x3 = 0			
x2 = 1			
x1 = 0 as the remaining profit is 0			
x = {0 1 0 1} for maximizing the profit			
let us use sets method			
we will prepare sets of P and w			
s0 = {(0,0)}			
$s0(1) = \{(1,2)\}\$ here, we added first object to elements of set $s0$			
$s1 = \{(0,0),(1,2)\}$ merged the above two sets to get $s1$			
$s1(1) = \{(2,3), (3,5)\}$, added second object to elements of s1			
$s2 = \{(0,0),(1,2)(2,3),(3,5)\}$ merged the above two sets to get $s2$			
$s2(1) = \{(5,4),(6,6),(7,7),(8,9)\}$			
$s3 = \{(0,0),(1,2),(2,3),(3,5),(5,4),(6,6),(7,7)\}$ removed (8,9) as it exceeded the permitted limit			
in the above set, we notice that as profit increases, weight increases, but at (5,4) profit has increased from (3,5) whereas weight has decreased			
thus, we discard (3,5) with lesser profit {dominance rule}			
so, s3 = $\{(0,0),(1,2),(2,3),(5,4),(6,6),(7,7)\}$			
now, considering the fourth object,			
s3(1) = {(6,5),(7,7),(8,8)(11,9),(12,11)(13,12)}			
$s4 = \{(0,0),(1,2),(2,3),(5,4),(6,6),(7,7),(8,8)\}$ merged above two sets and removed elements using dominance rule and those exceeding the weight limits			
time taken is almost (2 ⁿ)			
maximum order is (8,8)			
(8,8) belongs to s4			

	check whether it belongs to s3> it does not, hence object 4			
	is included			
	now (8,8) - (6,5) = (2,3)			
	(2,3)> check if it belongs to s3> yes, check whether it belongs to s2 -> yes, thus object 3 is not included> now, check if it belongs to s1> no, that means object 2 is included and object 1 is not			
	2-2, 3-3 = (0,0)			
	(0,0) belongs to set 1 and set 0 as well therefore object 1 is not included			
	x = {0 1 0 1}			
64	4 0/1 Knapsack Dynamic Programming			
		main()		
	$P = \{0, 1, 2, 5, 6\}$	{		
	wt = {0, 2, 3, 4, 5}	int P[5] = {0, 1, 2, 5, 6}		
		int wt[5] = {0, 2, 3, 4, 5}		
	n = 4, m = 8	int m = 8, n = 4;		
		int k[5][9];		
	i = n ; j = m;			
	while($i > 0 && j > 0$) {	for(int i = 0; i <= n; i++)		
	if(k[i][j] == k[i-1][j])	{		
	{	for(int $w = 0$; $w \le m$; $w++$)		
	cout << i << "=0" << endl; i;	{		
	}	if(i==0 w == 0)		
	else {	{		
	cout << i << "=1" << endl; i; j = j - wt[i];	k[i][w] = 0;		
	}	} else if (wt[i] <= w)		
	}	{		
		$k[i][w] = max{P[i] + k}$ [i-1][w - wt[i]], k[i-1]w};		
		}		
		else		
		{		
		k[i][w] = k[i-1][w];		
		}		
		}		
		cout< <k[n][w];< td=""><td></td><td></td></k[n][w];<>		

							}			
65	Optir	mal Bina	ary Searc	ch Tree						
), 50, 60, 7						
	where	taken for e n is the nt of the	e number	ng a partion of nodes	cular key in a B and logn is the	ST is logn minimum				
		target k ccessful		in the tree	e, the search w	ould be				
	2n C	n / n + 1	hinary s	earches a	are possible for	n kevs				
			-		of comparison	-				
	A bal	anced b		rch tree w	ould require th					
	numb		mparison		problem, in ad consider the fi					
	1	2	3	4			C[0,2]			
keys	10	20	30	40			10 20			
frequency	4	2	6	3			4 2			
	j									
	0	1	2	3	4					
	0	4	81	20з	263		I = j - i = 0			
	0	0	2	10₃	163		0 - 0 = 0			
_	0	0	0	6	123		1 - 1 = 0			
	0	0	0	0	3		2 - 2 = 0			
4	0	0	0	0	0		3 - 3 = 0			
							4 - 4 = 0			
	-			re 0<=i <=			set up cost for all diagonala values as 0;			
	_			ase, C[0,2]] = C[0,0] + C[1]	,2] + w[0,2]	I = j - i = 1			
	C[0,2	2] = 0 + 2	2 + 6				C[0,1] i.e. considering only key 1			
	C[0,2	2] = 8					cost is 4			
		arly, cald 2,2] + w[0		ost C[0,2]	in the second	case = C[0,1]	similarly, C[1,2] i.e. considering only second key			
	here,	C[0,2] =	4 + 0 +	6 = 10			cost is 2			
							Similarly, C[2,3] = 6 and C[3,4] = 3			

C[1,3] (CASE 1 when 20 2*1 + 6* 2 = 14) is the root and 30 is it's right node) =	Now, $I = j - i = 2$ i.e. we would consider 2 keys at a time		
C[1,3] (CASE 2 when 30 6*1 + 2*2 = 10) is the root and 20 is its left node) =	i.e C[0,2] , C[1,3] and C[2,4]		
		C[0,2]: key 10 and 20 with frequency 4 and 2 respectively		
C[2,4] (CASE 1 when 30 6*1 + 3*2 = 12) is the root and 40 is its right node) =	Two possibilities: 10 in the root and 20 it's right node OR 20 in the root and 10 it's left node		
C[2,4] (CASE 2 when 40 3*1 + 6*2 = 15) is the root and 30 is on the left) =	for first case: Cost = 4*1 + 2*2 = 8		
		for second case: Cost = 2*1 + 4*2 = 10		
I = j - i = 3		minimum cost is 8 and the root is 1		
C[0,3], C[1,4] for C[0,3]	, w[0,3] = 12			
For C[0,3] , (CASE 1 : 1 is the right node of 20) = 12 = 22	0 as a root and 20 it's right node, 30 = C[0,0] + C[1,3] + w[0,3] = 0 + 10 +			
(CASE 2, 10 as a root a node of 30)	nd 30 it's right node, 20 is the left			
(CASE 3 when 20 is the child) = C[0,1] + C[2,3]	root, 10 it's left child and 30 it's right + 12 = 4 + 6 + 12 = 22			
	root, 20 is the left child and 10 is its 3] + 12 = 8 + 0 + 12 = 20			
(CASE 5 when 30 is the right child of 10)	root, 10 is its left child and 20 is the			
C[1,4] ; w[1,4] = 11				
	2,4] + 11; C[1,2] + C[3,4] + 11; C[1,3]			
	; 2 + 3 + 11; 10 + 0 + 11} = min{23,			
I = j - i = 4 = 4 - 0 ; w[0,4	1 – 15			
	•			
+ C[3,4] + 15; C[0,3] + C	[1,4] + 15; C[0,1] + C[2,4] + 15; C[0,2] C[4,4] + 15} = min { 0 + 16 + 15; 4 + + 0 + 15} = min{31, 31, 26, 35} = 26			

	root[0,4] = 3			
	then left child is root[0,2] and right child is root[3,4]			
	root[0,2] is 1 and root[3,4] is 4; root[3,4] is further subdivided into root[3,3] and root[4,4]			
	root[0,2] is further divided into root[0,0] and root[1,2]			
	root[1,2] is the second key and its further divided into root[1,1] and root[2,2]			
	$C[i,j] = min\{ C[i,k-1] + C[k,j]\} + w(i,j) \text{ where } i < k <= j$			
66	Optimal Binary Search Tree Successful And Unsuccessful Probability			
	Unsuccessful nodes can be represented by dummy nodes			
	If there are n keys, there ould be n+1 square dummy nodes			
	Successful search probability represents probability of getting a given key in the lot whereas unsuccessul search probability represents a range of values of the key			
	cost [0,n] = P _i * level(a _i) + Q _i * (level(e _i) - 1)			
	this cost value is calculated over 1<= i < = n for successful searches (Pi) and 0<= i <= n for unsuccesful searches (Qi)			
	the above cost is minimized for optimal binary search tree			
	Is it possible that we find out the best tree without calculating the cost of all the trees			
	Let's use dynamic programming to find out the minimum cost arrangement without actually computing cost for each binary search tree possible			
	$C[i,j] = min\{ C[i,k-1] + C[k,j]\} + w(i,j) \text{ where } i < k <= j$			
	Let us consider it for just three nodes			
	i.e. $C[0,3] = min\{C[0,0] + C[1,3] + w[0,3], C[0,1] + C[2,3] + w$ [0,3], $C[0,2] + C[3,3] + w[0,3]\}$ where $0 < k < = 3$			
	C[0,0] = C[3,3] = 0			
	C[1,3] = min{C[1,1] + C[2,3] , C[1,2] + C[3,3]} + w[1,3] where 1 < k <= 3			

	Here	, C[1,1] = C[3,	,3] = 0							
	Value C[2,3	es we r 3], C[0,	need, C 2], C[1,	[0,0], C[1, 3], C[0,3]	1], C[2,2], C[3,3], C[0,1], C[1,2],						
	i,j										
j - i = 0	C[0,0)] C[1,1]	C[2,2]	C[3,3]	w[0,2] = q0 + p1 + q1 + p2 + q2					
j - i = 1	C[0,1] C[1,2]	C[2,3]		w[0,3] = q0 + p1 + q1 + p2 + q2 + p3 + q3					
j - i = 2	C[0,2	2] C[1,3]			thus, $w[0,3] = w[0,2] + p3 + q3$					
j - i = 3	C[0,3	3]				$w[i, j] = w[i, j-1] + p_j + q_j$					
	we ba		y need t	to find the	cost, weight and the root at each						
	0	1	2	3	4	j>	0	1	2	3	4
keys		10	20	30	40	j - i = 0	$w_{00} = q_0 = 2$ $C_{00} = 0$ $r_{00} = 0$		$w_{22} = q_2 = 1$ $C_{22} = 0$ $r_{22} = 0$	$w_{33} = q_3 = 1$	W44 = Q4 = 1 C44= 0 r44 = 0
p _i		3	3	1	1	j - i = 1	Wo1 = w[0,0] + p1 + q1 = 8 Co1= 8 ro1 = 1	w ₁₂ = 7 C ₁₂		w ₃₄ = 3 C ₃₄ = 3 r ₃₄ = 4	144 - 0
q _i	2	3	1	1	1	j - i = 2	$w_{02} = 12$ $C_{02} = 19$ $r_{02} = 1$	w ₁₂ = 9 C ₁₂ = 12 r ₁₂ = 2	w ₂₄ = 5 C ₂₄ = 8 r ₂₄ = 3		
						j - i = 3	w ₀₃ = 14 C ₀₃ = 25 r ₀₃ = 2	w ₁₄ = 11 C ₁₄ = 19 r ₁₄ = 2			
						j - i = 4	w ₀₄ = 16 C ₀₄ = 32 r ₀₄ = 2				
	Final	ly , the	tree lo	oks like th	e below tree:						
	r[0,4]	= 20									
r[0,1] = 10						r[2,4] = 30					
						r[3,4] = 40					
67	Trave Prog	elling : ramm	Salesm ing	nan Probl	em Using Dynamic						
	A dire	ected v ht	veighte	d graph is	given and every edge is having						
	and r	eturn b	oack to		vertex and travel all the vertices g vertex and the cost of n						

	1	2	3	4								
1	0	10	15	20								
-	5	0	9	10								
	6	13	0	12								
	8	8	9	0								
-												
	g(i,s	s) = mi	n { Cik	+ g(k, s -	{k})} where	e k belongs	s to s					
		{2,3,4 2,3,4}	}) = mir	n{ C1k + g	g(k, {2,3,4}	- {k})} whe	re k belongs	Now, this is a recursive result can be obtained by recursive tree				
	vert	ex 1										
here, costs can be taken from given table	vert	ex 2 g	(1,2) = (min{ C12 -	+ g(2, {3,4}	})} ; C12 = 1	10	vertex 3 g(1,3) = min{C ² = 15	3 + g(3, {2,4})); C13	vertex 4 g (1,4) = C14 + g(4, {2,3})}; C14 = 20		
	vert C23	ex 3 C = 9, C	23 + g(224 = 10	3, {4}))	verte	ex 4 C24 +	g(4, {3});	vertex 2 C32 + g(2, {4}) g(4, {2}); C32 = 13, C34	vertex 4 C34 + = 12	vertex 2 C42 + g(2, {3}) vertex 3 C43 + g(3, {2}); C42 = 8, C43 = 9		
	g(3, phi) phi)	; C34 :	C34 + ç = 12, C4	g(4, phi i.e 43 = 9; g(4	. nothing) ; 1, phi) ~ g(g(4, {3}) = 4,1) = 8; sir	C43 + g(3, nilarly, g(3,	g(2, {4}) = C24 + g(4, ph + g(2, phi); C24 = 10, C- g(2, phi) = 5	ii); g(4,{2}) = C42 42 = 8, g(4, phi) = 8,	g(2,{3}) = C23 + g(3, phi); g(3, {2}) = C32 + g(2, phi); C23 = 9, C32 = 13; g(3, phi) = 6, g(2, phi) = 5		
	we i		oular m	ethod to s	olve these	from bottor	m to top					
	_	phi) =	5									
	_	phi) =										
	_	phi) =										
	_	(3}) =										
	_	{4}) =										
	_	{2}) =										
	_	{4}) = 2										
	g(4,	(2}) =	13									

	g(4,{3})	= 15										
	g(2, {3,	4}) = minim	um of the c	options = 25								
	g(3, {2,	4}) = 25										
	g(4, {2,	3}) = 23										
	g(1, {2,	3,4}) = 35										
68		lity Design										
		e to set up	-									
	-	consists of										
		perfectly /		s the probability of a device	Exampl	le:						
DEVICES	D1	D2	D3	D4	Di	Ci	ri	ui				
COST	C1	C2	C3	C4	D1	30	0.9	2				
RELIABILITY	r1	r2	r3	r4	D2	15	8.0	3				
	0.9	0.9	0.9	0.9	D3	20	0.5	3				
					C = 105	5						
	reliabilit	ty of the dev	vices = 0.9	n = product of individual ^4 = 0.6561 i.e. 35% chance nce a failure	At least taken, s	t one cop so C1 + 0	y of eac C2 + C3	h device = 30 + 1	must be 5 + 20 = 65			
	In case of device	of failure, s es as a bac	system is de ck up	esigned to have parallel copies	Remair = 40	ning amo	unt = C	- sum(Ci)	= 105 - 65			
	here, r1	= 0.9			if I sper D1, I w	nd the er ould be a	ntire rema	aining an urchase	nount on I D1 device			
	1 - r1 =	1 - 0.9 = 0.	.1		ui = [C device		Ci) / Ci] -	1 copie	s of any			
		^3 = 0.1^3			for D2,	40/15 =	2 + 1 = 3	copies				
	probabi ^3 = 0.9	lity that thre	ee copies a	re working perfectly = 1 - (1 - r1)	for D3,	40/20 =	2 + 1 = 3	copies				
	Reliabil	ity has impi	roved by us	sing a parallel system				the set met's delve	ethod of deeper			
		any devices system's re		uy within the given cost such maximized	(R,C)							
					s0 = {(1	1,0)}						
						er D1, s						
					s12 = {(1(1-0.9)^	2)} = 1 -	e firstd e\ 0.1^2 = 0				
					thus, s1	12 = {(0.9	9, 60)}					

	s1 = {(0.9, 30), (0.99, 60)}		
	consider D2 one copy, $s2_1 = \{(0.72,45), (0.792, 75)\}$		
	Taking 2 copies of D2, $s2_2 = 1 - (1 - r2)^2 = 1 - (1 - 0.8)^2 = 1 - 0.04 = 0.96$		
	{(0.864, 60), (0.9504, 90)}		
	in the last case, remaining cost = 105 - 90 = 15; we cannot purchase D3 as its cost is 20 which is more than our remaining amount; so we would discard that set option as. it is unfeasible		
	consider 3 copies of D2, reliability = 1 - (1 - r2)^3 = 1 - (1 - 0.8)^3 = 1 - 0.008 = 0.992		
	s2 ₃ = {(0.8928, 75), (, 105)}> second case is discarded as it is unfeasible		
	s2 = {(0.72,45), (0.792, 75), (0.864, 60), (0.8928, 75)}		
	in s2, the third case has cost decreased but reliability is increased, thus we would use domimance rule to remove / discard the third case		
	Now, consider one copy of D3, s3 ₁ = {(0.36,65), (0.432, 80), (0.4464, 95)}		
	r3 = 0.5 ; 1- (!-r3)^2 = 1- 0.25 = 0.75		
	$s3_2 = \{(0.54, 85), (0.648, 100)\}$ the third case has cost exceeding 105 thus it has been discarded		
	Consider three copies; 1 - (1 - r3) ^3 = 0.875		
	s3 ₃ = {(0.63, 105)}		
	s3 = {(0.36,65), (0.432, 80), (0.4464, 95), (0.54, 85), (0.648, 100), (0.63, 105)}		
	Using dominance rule, s3 = {(0.36,65), (0.432, 80), (0.54, 85), (0.648, 100)}		
	Maximum reliability = 0.648 and the cost would be 100		
	for getting the number of copies of devices, go backward from 0.648, 100 ordered pair		
	which shows 1 copy of D1, 2 copies of D2, 2 copies of D3		
69 Longest Common Subsequence (LCS)			
What is LCS?			

	LCS Using Recursion			
	LCS Using Memoization (to save time as recursion is time consuming)			
	LCS Using Dynamic Programming			
	String 1: a b c d e f g h i j	String1: a b d a c e		
	String 2: e c d g i	String 2: b a b c e		
	c d g i is the longest subsequence	b a c e and a b c e are the longest subsequences		
	LCS Using recursion			
Α	b d \0	int LCS(i,j)		
		{		
В	a b c d \0	if (A[i] == '\0' B[j] == '\0')		
		return 0;		
		else if (A[i] == B[j])		
		return 1 + LCS(i + 1, j + 1);		
		else		
		return max(LCS(i+1, j), LCS(i, j+1);		
		}		
	Recursion tree for the above example -			
	A[0] , B[0] : b, a : 2			
Call1	A[1], B[0] : d, a : 1	A[0], B[1]: b, b : 2		
Call2	A[2], B[0] : \0 , a A[1], B[1] : d, b : 1	1 + A[1], B[2] : 1 + d, c		
Call3	0 A[2], B[1] : \0, b A[1], B[2] : d, c : 1	1 + A[2], B[2] 1+ A[1], B[3]		
Call 4	0 0 A[2], B[2] : \0, c A[1], B[3] : d, d : 1	1 + \0 1 + 1		
	0 0 0 1 + A[2], B[4] : 1 + \0 : 1			
	The purpose of the above problem was to depict that there is an issue of overlapping. But, there is no reason for repeat recalls if we can store the answer of previous stage. Thus, we use memoization			
	LCS using memoization			
	a b c d \0			

		0	1		2	3	4				
b	0	2	2		_	_	_				
d	1	1	1		1	1					
\0	2	0	0		0	_	0	1			
10											
		n) w	noizati here r ective	n and	n red n are	uce the the cou	numbe unts in	er of fun String 1	ction ca I and 2	lls : O(m X	
		1.00	·in	. d			m m in c				
			LCS using dynamic programming					11 4 41-	. 4-1-1- 4		
		DP would follow bottom up approach and fill out the table top to bottom whereas in the previous approach we were following top down approach and filling the table in bottom up manner				pproac	h we we	ere	: (A (i) D(i)\		
		A : t	d								{
		B : a	a b	c d							LCS[i,j] = 1 + LCS[i - 1, j - 1];
											} else
			а	k)	С	d				{
		0	1		2	3	4				LCS[i,j] = max(LCS(i - 1, j], LCS[i, j - 1])
	0	0	0		0	0	0				}
b	1	0	0		1	1	1				
d	2	0	0		1	1	2				
		we (go bac) and	kward then d	ls dia diago	gonally	to 1 (b, ck to 0	,c) , the (0,a); tl	n horizo hus ther	e see that intally to 1 e are two	
str 1		s t	o n	e							
str 2			n g		s t						
		+ -	3		-						
			ı	0	n	g	е	s	t		
		0		2	3	4	5	6	7		
0	0	0		0	0	0	0	0	0		
s	1	0	0	0	0	0	0	1	1		
t	2	0	0	0	0	0	0	1	2		
0	3	0		1	1	1	1	1	2		
n		0	0	1	2	2	2	2	2		
			-								

e 5	0 0 1 2 2 3 3 3				
LCS	Take the elements which came from a diagonal - o n e				
70	0 Graph Traversals - BFS and DFS				
	Visiting a vertex				
	Exploration of a vertex - visiting all of the adjacent vertices				
	BFS: 1, 2, 4, 5, 3, 6, 7				
	DFS: 1, 2, 3, 6, 7, 4, 5				
_	BFS: 1 4 2 3 5 8 7 10 9 6				
Queue: Q	1 4 2 3 5 8 7 10 9 6				
	Breadth first search spanning tree -				
	1				
	42				
	3 5 8 7				
	10 9				
	6				
	DFS: 1 4 3 10 9 2 8 7 5 6				
	Stack:	Depth first search spanning tree			
	O(n) where n is the number of vertices	1			
	5	4			
	7	3			
	8	10 9 2			
	2	8			
	4	7			
	1	Ę	5		
		6			
7	1 Articulation point				
	Biconnected components				
	In a graph, if there is a vertex whose removal would segregate the graph into distinct components, then that vertex is called the articulation ppoint				
	To tackle articulation point, we need to extend an edge from vertex in one component to another				

How to find an articulation point in a graph?	Algorithm:		
DFS: 1 2 3 4 5 6	Conduct depth first search and find depth first search spanning tree		
d: 1 6 3 2 4 5	Mention the discovery times for each vertex		
L: 1 1 1 3 3	We need to find the lowest discovery number to find any vertex by taking a back edge		
u, v: parent, child then the lowest number of v i.e. $L[v] >= d[u]$ then u is an articulaion point. This condition is true for all except the root.	Find out articulation point		
The above algorithm is true for $v = 5$ and $u = 3$; hence 3 is the articulation point			
If root has more than one child, then root is also an articulation point			
TO DOUBLE OF THE PROPERTY OF T			
72 Backtracking			
Brute force approach			
When you have multiple solutions and you want to get all those solutions , then you use backtracking			
Example: B1B2G1 (Three students) in 3 chairs	All possible arrangements 3! ways		
State space tree			
B1 (in chair 1)			
B2 (in chair 2)			
G1 (in chair 3)			
for another arrangement, take out B2 and G1; then G1 can sit in chair 2 and B2 in chair 3			
Now, no more solutions with B1 in chair 1; then take out B1 as well; put B2 in chair 1			
B1 in chair 2 and G1 in chair 3; B1 in chair 3 and G1 in chair 2			
Again, no more solutions with B2 in chair 1, so take B2 out and put G1 in chair 1			
B1 in chair 2 and B2 in chair 3; B2 in chair 2 and B1 in chair 3			
thus, altogether 6 solutions	Now, in backtracking problems, usually we have certain constraints and we select solutions that work for them; for instance, G1 cannot sit in any middle positions		
	Then, possible solutions are: B1B2G1; B2B1G1; G1B1B2; G1B2B1		
	The rest of the nodes are killed when we applied the bounding function		

	Same brute force approach is used by branch and bound strategy ; both strategies also generate state space tree as wellbut back tracking follows depth first search whereas branch and bound follows breadth first search approach							
	Branch	and bound sta	te space tree i	is generated level-wise				
73	N-Que	ens Problem						
	A chess	s board is giver		case of simplicity even (8. We are given 4	Queen's moves can be diagonal or horizontal or vertical; we need to place the 4 queens such that they are not under attack i.e. they are not in the same row, column or diagonal			
	1	2	3	4	We have more than one solution and we want all possible solutions			
1					I can place them in 16C4 ways. But, A queen cannot be kept anywhere on the board but first queen in Row 1; second in row 2 and so on We can avoid keeping more than one queen in single column			
2	2							
3	3							
4	l		••••					
	State s	pace tree first v	vithout taking	care of diagonal attacks				
	Q1 in c		in column2>	> Q3 in column 3> Q4				
	Now, m	ove back and r	move Q3 in co	lumn 4 and Q4 in column				
		ove back and r 4 in column 4	move Q2 in co	lumn 3> Q3 in column				
	Again , column		d move Q3 in	column 4 and Q4 in				
	Now, m Q3 in c in colur	olumn 2 and Q	move Q2 in co 4 in column 3;	lumn 2> 2 possibilities Q3 in column 3 and Q4				
		oll back comple to above set of		in column 2 and we get				
	4*3*2 +		when we have	ecking: 1 + 4 + 4*3 + e avoided same rows and liaagonals	65 nodes			

	$1+Summation(Product(N\ -\ j))$ where j ranges from 0 to i and i ranges from 0 to 3; here N is 4; for 8X8 board, N would be 8			
	Now, let us solve this with bounding function i.e. condition - not same row, same column , same diagonal			
	State space tree			
	Q1 in column 1> Q2 in column 2> under attack> kill the node			
	Q1 in column 1> Q2 in column 3> Q3 in column 2> under attack> kill the node			
	Q1 in column 1> Q2 in column 3> Q3 in column 4> under attack> kill the node			
	Q1 in column 1> Q2 in column 4> Q3 in column 2> Q4 in column 3> under attack> kill the node			
	Q1 in column 1> Q2 in column 4> Q3 in column 3> Q4 in column 2> under attack> kill the node			
	Q1 in column 2> Q2 in column 1> under attack> kill the node			
	Q1 in column 2> Q2 in column 3> under attack> kill the node			
	Q1 in column 2> Q2 in column 4> Q3 in column 1> Q4 in column 3	solution 1		
	Q1 in column 3> Q2 in column 1> Q3 in column 4> Q4 in column 2	solution 2 (mirror image of solution 1)		
74	Sum of subsets problem			
	w[1:6] = {5, 10, 12, 13, 15, 18}	Six weights are given; we have to take a subset such that their sum is 30		
	n = 6; m = 30	Total is 73 here for given weights		
	x =			
	1 2 3 4 5 6	Each xi value can be 0/1		
	State space tree			
	Either first weight is included Or first weight is not included			
	Either second weight is included Or second weight is not included			
	Either third weight is included Or second third is not included			
	so, we get 7 levels> 2^6 paths i.e. 2^n paths	thus, it is time consuming but we try to kill the nodes if they do not satisfy the bounding function		
	0, 73			

	5, 68 (first weight is included)				
	15, 58 (second weight is included)				
	27, 46 (third weight is included)				
	if I include fourth weight> 40, 33> exceeds the bounding condition> kill this node	Summation(wixii=1 to k) + wk+1 <= m			
	Try without including 4th object, 27, 33				
	Try including 5th object> 43, 18> kill this node				
	Try without 5th object> 27, 18				
	Now, try including 6th object> 45, 0> exceeding> kill the node				
	Try without 6th object> 27, 0> meaningless> not enough weights	Summation($w_i x_{i i = 1 \text{ to } k}$) + $w_{i i = k + 1 \text{ to } n} > m$			
	T I. Francisco 45, 40				
	Try excluding object 3; 15, 46				
	Try including 4th object> 28, 33				
	Try including 5th object> 43, 18> exceeding> kill the node				
	Try without 5th object and include 6th object> 44, 0> kill the node				
	Try excluding objct 4 as well : 15, 33				
	Try including 5th object : 30, 18	Solution 1: Object 1, 2 and 5			
	Several other possible solutions by following depth first search in this backtracking problem				
75	Graph coloring problem				
	A graph is given and some colors are given. We need to color the vertices of the graph such that no two neighboring vertices are of the same color				
	So, let us start from vertex 1 (Red color)	we have 5 vertices and three colors: R, G, B			
	vertex 2 (neighbors 1 and 3) : G color				
	vertex 3 (neighbors 2, 4 and 5): R color				
	vertex 4 (neighbors 3 and 5): G color				
	vertex 5 (neighbors 4, 1, 2 and 3): B color				
	1 2 3 4 5				
	R G R G B	m Coloring Decision Problem (can the graph be colored or not) or Chromatic color problem			

	G R G R B	m Coloring Optimization Problem (minimum how many colors are needed)			
	if we had just two colors, it can not be colored				
	we just want to know if the graph can be colored by the given number of colors				
	4 vertices: 1,2, 3, 4				
	3 colrs: RGB				
	State space tree				
	vertex 1 can be R , G , or B				
	following that vertex 2 can be R, G, B and so on	Right now, we are not applying adjacency condition			
		Total number of nodes generated: 1 + 3 + 3*3 + 3*3*3 + 3*3*3*3 = 1 + 3 + 9 + 27 + 81 = 3^5 - 1 / 3 - 1			
		Total time spent is 3^n+1 i.e. C^n+1			
	Now, let us consider adjacency condition				
	vertex 1: R color				
	vertex 2 (neighbors 1 and 3): G color				
	vertex 3 (neighbors 2 and 4): R color				
	vertex 4 (neighbors 1 and 3): G or B color				
	RGRG RGRB				
	RGBG				
	RBRB RBRG				
	R B G B				
	-				
	I have a map with different regions. We need to color the map such that the adjacent areas are not of the same color. Minimum number of times the sheet needs to be passed through a printer				
	For each region of a map, we mention it as a vertex and we would draw an edge for neighboring regions				
	Then, we can solve the m-coloring problem in the graph and implement those colors for the map				
76	Hamiltonian cycle				
10	-				
	If a graph is given, we have to start from any one vertex and travel through all the vertices and reach back to the starting vertex> this forms a cycle> we need to check if there is a hamiltonian cycle possible> find all possibilities				

	Graph given may be directed or non-directed but it must be connected		
	It's an exponential time taking problem		
	If the order of the vertices is the same, even though the starting vertex varies , it is still considered the same hamiltonian cycle		
	If there is an <i>articulation point</i> (junction point) in a graph, then hamiltonian cycle is not possible in the graph		
	If there is a pendant vertex in a graph, then hamiltonian cycle is not possible in the graph		
	Adjacency matrix for the graph:	Algorithm	
G	1 2 3 4 5	{	
	1 0 1 1 0 1	do	
	2 1 0 1 1 1	{	
	3 1 1 0 1 0	NextVertex(k);	
	4 0 1 1 0 1	if(x[k] == 0)	
	5 1 1 0 1 0	{	
		return;	
	Array to determine if the cycle has been found:	}	
x		if(k == n)	
	1 2 3 4 5	{	
	Initially all these values are zero;	print(x[1:n]);	
	we do not want repetitions, so we fix the starting vertex; let us take it as $\ensuremath{1}$	} else	
x	1 0 0 0 0	{	
	State space tree:	Hamiltonian(k+1)	
	vertex 1	}	
	try to put 1 in vertex 2; but 1 is already at vertex 1; so put 2 at vertex 2> check if there is an edge from 1 to 2> adjacency matrix shows that there is an edge	} while(true);	
x	1 2 0 0 0	}	
	For next position i.e. vertex 3, try putting 1 or 2 but they are already there so use 3; check if there is an edge between 2 and 3> yes, there is	Algorithm NextVertex(k)	
x	1 2 3 0 0	{	
	Similarly, check if vertex 4 is connected to vertex 3 by an edge> yes	do	
x	1 2 3 4 0	{	
	Now, 4 is connected with 5 with an edge	x[k] = (x[k] + 1) mod(n+1);	

x	1 2 3 4 5	if(x[k] == 0) return;	
	Now, from 5 to 1 there is an edge, hence a cycle is formed and first solution is obtained	if(G[x[k - 1], x[k]] not equals 0){	
	we can check for cycle again by using vertices in another order	for $j = 1$ to $k - 1$ do if $(x[j] == x[k])$ break;	
x	1 2 5 4 3	if(j == k)	
	all possibilities: 4!	if(k < n or (k == n) && $G[x[n], x[1]]$ not equals zero	
	for n vertices graph , (n - 1)!, thus time complexity is O (n^n)	return;	
		} while(true);	
		}	
77	Branch and bound strategy		
	Useful for solving optimization problem(just minimization problem)		
	Example: Job sequencing		
	Jobs: { J1, J2, J3, J4}		
	P = {10, 5, 8, 3}		
	d = {1, 2, 1, 2}		
	Methods of prepresenting solutions:		
	S1: {J1, J4}; Variable sized solution or subset method		
	S2: {1, 0, 0, 1}: Fixed sized solution		
	State space tree		
	J1 is considered; J2 is considered; J3 is considered; J4 is considered	Breadth first search unlike backtracking	
	Following this if J1> J2, J3 or J4 can be taken	J1> J2> J3> J4 J1> J2> J4	
	J2> J3 and J4 are considered; J1 has been discarded		
	J3> J4 ; J1 and J2 are discarded		
	Another method: while constructing the state space tree, place the nodes in a stack		
	Now, pop out first node and expand the fifth node		
	But, 5th node is the last node and there is no expansion possible, thus pop out second last node and expand the 4th node		

	Further expansion already been pla		possible as the fifth node has				
	similar manner, J2	l3 and J4	are popped and placed as child of				
	If we use queue	> FIFO	Branch and bound				
			Branch and Bound				
	Now let us leak	at I a a a t	and bronch and barred mathed				
			cost branch and bound method				
		vertex 1	and compute cost at each node				
	1, Cost = infinity						
	J1, cost: 25						
	J2, cost = 12						
	J3, cost 19						
	J4, cost = 30						
	let us explore the node with the minimum cost i.e. J2						
78	Job sequencing	with de	adline problem				
	bound can only s	olve min to penal	maximize profit but branch and imization problems, thus we have ty and problem now becomes to lity				
Jobs	1 2	3	4				
Penalty	5 10	6	3				
Deadline	1 3	2	1				
Time taken for completion	1 2	1	1				
	By generating a	state spa	ce tree:	each node will be specified by upper bound (sum of all the penalties for the jobs that have not been included till now); cost (sum of penalties of jobs included till now)			
	1: U = INFINIT	Y, COST	0				
	2: J1 is included;	cost: 0,	u: 19				
	3: J2 is included	and we a	are not doing J1: u: 14, cost = 5				

	4: J3 is included and we are not doing J1 and J2: cost = 15; u: 14	here, cost has increased from the previous node whereas the upper value remains the same, thus we kill this node		
	5: J4 is included and we are not doing J1, J2 and J3; COST = 21 (HIGHER THAN THE PREVIOUS NODE, THUS KILL THIS NODE)			
	Now, let's move to the next level in the state space tree			
	Let us include J1 and further three scenarios: J2 is included; J3 is included; J4 is included			
	6: J2 is included, cost = 0; u = 9			
	7: J3 is included, cost = 10 (2nd job is not included); u = 9> kill this node			
	8: J4 is included whereas J2 and J3 are excluded; cost = 16> kill this node			
	for J2, 2 possibilities: J3 is included; J4 is included			
	9: J1 is not included, J2 is included, J3 is included: cost = 5; u = 8			
	10: J1 is not included, J2 is included, J3 is not included, J4 is included: cost = 11; u = 8> kill this node			
	44 445 5 1 1 1 1 2 2 3 5 5 1 1 1 1 2 3 5 5 1 1 1 1			
	11: J1is included> J2 is included> J3 is included			
	but, if we complete J1 and J2, 3 hours are used and there is no time left for J3> this job cannot be done; similarly J4 cannot be done			
	12: J1 is not included, J2 is included, J3 is included, J4 is included; cost = 5; u = 5; but they cannot be done this manner based on the time and deadlines			
	Thus, optimum cost we got is 5 and penalty is 8: doing J2 and J3			
	0/1 Knapsack problem			
Profit	10 10 12 18			
Weight	2 4 6 9			
	m = 15; n = 4			
	Maximize profit when you can fill the bag with complete weight or not take it at all			

	Branch and bound can solve only minimization problems, so to convert this maximization problem to a minimization one, we would convert positive profits to negative ones and then minimize them overall			
	We will use LC Branch and bound (always exploring that node whose cost is minimum)			
	u = summation(Pixi) <= m			
	C = summation(Pixi) with fraction			
	We would generate a state space tree but we need to decide what kind of solution we want - a subset or a fixed-sized solution of 0's and 1's. So, here we are seeking a fixed sized solution			
	Let us generate state space tree			
	upper = infinity			
	C = 10 + 10 + 12			
	2 + 4 + 6 i.e total comes out to 12			
	we can include 3 more kgs			
	thus, C = 10 + 10 + 12 + 18/9 * 3 = -38			
	u = -32			
u	-32			
С	-38			
	Now, I am including the first object then we get the same solution, $u = -32$, $v = -38$; but if we exclude object 1, then			
	C = 10 + 12 + 18/9 * 5 = -32; upper = -22			
	4 + 6 + 5 kgs			
	Now, this cost is not greater than the previous upper, so no need to kill this node			
	we will follow least cost branch and bound; and go ahead with the least cost branch which is including object 1 as the cost is -38			
	it can be further explored, if we include object 2 after including object 1 or not			
	if we include object 2, then the cost and upper bound remain the same as nothing has been excluded			
	on the other hand, if we exclude object 2, the new cost and upper bound value in this scenario is as follows:			
	u = -22			

C = 10 + 12 + 18/9 * 7 = -36				
2+6+7				
Now, the cost is not greater than u = -32, thus we would not kill it				
Now, least cost is -38 when we include both objects 1 nd 2 , so we would explore that path more				
if Object 3 is included, cost remains the same i.e. $C = -38$, $u = -32$				
if Object 3 is excluded, cost is as follows:				
C = 10 + 10 + 18 = -38				
2 + 4 + 9				
u = - 38				
here, we got the smaller upperbound, so upper bound gets updated to -38				
also look at the cost of alive nodes, and kill those nodes whose Cost is greater than -38				
Now, if we take further the scenario that all objects are included, it is not feasible as weight exceeds the bag limit				
so, we would explore the scenario when object 3 is exluded while the rest are included				
C = -38; u = -38				
and if we consider not including 4th object, then C = -20; tthis cost is greater than -38 so kill the node				
thus, answer is x{1, 1, 0, 1}				
maximum profit is 38 and weight is 15				
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