



	There is no particular relationship between the two concepts										
	Best Case, Worst Case and Expected Case actually describe the big O or big Theta time for particular scenarios whereas these asymptotic notations describe the upper, lower and tight bounds for the runtime										
	<b>Space complexity</b>										
	Memory or space required by an algorithm	to create an array - if it is unidimensional, $O(N)$ space complexity; for a 2-D array, $O(N^2)$									
	Stack space in recursive calls counts too. Each call adds a level to the stack and takes up actual memory.	However, just because you have $N$ calls does not mean it will take $O(N)$ time: check the example on Page 41 for more details									
	<b>Drop the constants</b>										
	$O(2N)$ is actually $O(N)$										
	<b>Drop the non-dominant terms</b>										
	$O(N^2 + N)$ becomes $O(N^2)$										
	$O(N + \log N)$ becomes $O(N)$										
	$O(5 \cdot 2^N + 1000N^{100})$ becomes $O(2^N)$										
	$O(x!) > O(2^x) > O(x^2) > O(x \log x) \dots > O(x)$										
	<b>Multi-Parts algorithms: add versus multiply</b>										
	Add:	Non-nested chunk of work A and B	$O(A + B)$	"DO THIS THEN WHEN YOU ARE ALL DONE, DO THAT"							





[illegible]

[illegible]

		First of all the runtime for mergeSort would be $O(b \log b)$ . then, for each element in $a$ , we are doing binary search of $b$ - runtime would be $O(a * \log b)$ . hence overall runtime is $O(b \log b + a \log b)$ .								
<b>Section IX</b>	<b>Interview Questions</b>									
<b>Chapter 1</b>	<b>Arrays and Strings</b>									
	<b>Hash Table</b>									
	A hash table is a data structure that maps keys to values for efficient lookup.									
	<b>Hash Table Implementation</b>									
	<b>Approach 1</b>	We use an array of Linked Lists and a hash code function.								
		To insert a key ( a string or any other datatype) and value we follow the following steps:								
		1. Compute the key's hashcode, which will usually be an int or long. Two different keys could have the same hashcode, as there may be numerous keys but finite number of ints.								
		2. Then, we map the hash code to an index in the array. This could be done with something like $\text{hash}(\text{key}) \% \text{array\_length}$ . Two different hashcodes could of course map to the same index.								
		3. At this index, there is a linked list of keys and values. Store the key and value in the index. We must use a Linked List to tackle collisions: you could have two different keys with same hashcode or two different hashcodes but same index								
		To retrieve the value pair by its key, we repeat the process. Compute the hash code by key, and then index by hashcode. Then, search through the Linked List for the value and its key.	If it is the worst case, collisions are very high, runtime would be $O(N)$ where $N$ is the number of keys. And, if it is the best case, collisions are minimum, look up time would be $O(1)$							
	<b>Approach 2</b>	We can implement a look up system with a balanced binary search tree. This gives us $O(\log N)$ lookup time. The advantage of this approach is potentially less space, since we no longer allocate a large array. We can also iterate through keys in order.								