Section VI	Big O								
	Asymptotic notations								
	O(Big O)	Describes an upper bound on time		on the runtime; similar to a less-	then we also say that X<=	In industry, O and theta have been put together and we have to give the tightest description of runtime			
	Omega(n)	Describes the lower bound	for example: printing the values in an array is Omega (n) as well as Omega(logn) as well as Omega(1)						
	Theta(n)	Describes the tight bound on runtime	Theta here means both O and Omega; in this example, it would be Theta(n)						
	Best Case, Worst Case and Expected Case								
	Best Case:	For example, in Quick Sort, if all the elements are equal, then quick sort will, on average, just traverse through the array once - O(N) time	elements greater than pivot - this gives partial sort. then it recursively sorts the left and						
	Worst Case:	The pivot could be repeatedly the biggest element in the array. If pivot is the first element in a reversely sorted array. In this cae, our recursion does not divide the array in half and recurse on other half. Instead, it justs shrinks the subarray by 1 element.	Time taken would O(N^2)						
		both the above best and worst conditions would rarely happen; thus we can expect a runtime of O(nlogn)	, ,						
		etween Asymptotic notations Worst Case and Expected							

There is no particular relationship between the two concepts										
	10 15 110									
Best Case, Wor	st Case and Expected Case act	ually describe the big O or big	g Theta time for part	ticular scenarios w	hereas these asy	mptotic notations	describe the upp	er, lower and tigh	t bounds for the ru	ıntime
Space complexity										
Memory or space required by an algorithm	to create an array - if it is unidimensional, O(N) space complexity; for a 2-D array, O (N^2)									
Stack space in recursive calls counts too. Each call adds a level tot he stack and takes up actual memory.	However, just because you have N calls does not mean it will take O(N) time: check the example on Page 41 for more details									
Drop the constants										
O(2N) is actually O(N)										
Drop the non- dominant terms										
O(N^2 + N) becomes O (N^2)										
O(N + logN) becomes O(N)										
O(5*2^N + 1000N^100) becomes O (2^N)										
$O(x!) > O(2^x) > 0$	$O(x^2) > O(x\log x) > O(x)$									
Multi-Parts algorithms: add versus mutiply										
Add:	Non-nested chunk of work A and B	O(A + B)	"DO THIS THEN WHEN YOU ARE ALL DONE, DO THAT"							

Multiply	Nested A and B	O(AB)	"DO THIS FOR EACH TIME YOU DO THAT"				
Multiply	Nesteu A anu B	O(AB)	TOO DO THAT				
Amortized time							
	That copying might take additional O(N) time after accounting for initial O(N) time of adding the elements	into a new array does not	that the worst ca every once in a happens it won't				
Adding X more space to an array takes additional O(X) time; thus the amortized time for each adding is O(1)	X + X/2 + X/4 + X/8 = 2X						
logN runtimes							
Example:							
Binary search. We are looking for an element x in a sorted array. We first compare to the midpoint. If x == middle, then we return else if x < middle, we search on the left side of array		The total runtime is then a matter of how many steps we can take before it becomes 1	$2^k = N \Rightarrow k = \log N$ with base 2	Basically, when you see a problem with logN runtime, the problem space gets halved in each step			
Recursive runtimes							
Program:	int f(int n){						
	if(n <= 1){						
	return 1}						
	return f(n -1) + f(n -1);}						
How many calls in the tree?							
Do not count and say 2							

It will have recursive calls with a depth N and 2^N nodes at the bottom most level	More genrically, 2^0 + 2^1 + 2^2 +2^n-1 = 2^n - 1 nodes		The space complexity would still be O (n) - even though we have O(2^n) nodes in tree total, only O(n) exists at a time				
Examples and I							
Example 1	O(n) time as we iterate through array once in each loop which are non-nested						
Example 2	O(N^2) time as we have two nested loops						
Example 3	j basically runs for N-1 steps in first iteration, N-2 steps in second iteration and so on.	1 + 2 + 3 ++ N-1 = N(N - 1)/2 ~ N^2	O(N^2)				
Example 4	For each element of array A, the inner loop goes through b iterations where b is the length of array B. Thus, time complexity is O(ab)						
Example 5	Similar to example 4, 100,000 units of work is still constant; so the run time is O(ab)						
Example 6	O(N) time as the array is iterated even if half of it (constant 1/2 can be ignored)						
Example 7	There is no established relationship between N and M , thus all but the last one are equivalent to O(N)						
Example 8	s = length of the longest string Sorting each string would take elements of the array; thus O(a array would take O(s * aloga) a would take O(s) time in additio take O(aloga); thus adding the aloga) = O(a *s (log a + log s)	O(slogs) and we do this for a a * slogs) . Now, sorting the as each string comparison n to array sorting that would					
Example 9	Approach 1: for summing up the nodes in a BST, each node is exactly traversed once, thus O(N) time complexity						
	Approach 2: The number of recursive calls is 2 and the depth is logN in a BST> O (branches ^ depth) = O(2 ^ logN) where the base of logN is also 2 => time complexity = O(N) after simpllifying						

) as the for loop stant time and runs N)) time			
process c	ne recursive alls from N to N-1 to o on until 1			
that we br time. this string. So path with	h 1: We make a tree for an example string say 'abc anch 4 times at the root , then 3 times, then 2 time gives us 4*3*2*1 leaf nodes. We could say n! leaf r , total nodes would be n * n! as each leaf node is a n nodes. Also, string concatenation will also take C me complexity in worst case would be O(n * n * n!)	es, and then 1 nodes for n length attached to a D(n) time. Thus,		
nodes; at total node 1/n!). Nov n! * e who Thus, the	n 2: At level 6, we have 6! / 0! nodes; at level 5 we level 4 we have 6!/2! nodesat level 0, we have 6! s in the tree in terms of n can be: n!(1/0! + 1/1	!/6! nodes. so, the 1/2! + 1/3!+ of Euler's number: Iropped further.		
pattern for	We can also get tighter runtime as O(1.6^N) if we consider that there might be just one call instead of 2 at the bottom of call stack of chepth) = O(2^N).			
time. And, 2^2 + 2^3	vious example, we deduce that fib(n) taken 2^n we have fib(1) + fib(2) + fib(3) +fib(n) = 2^1 ++ 2^n = 2^n (n+1) - 2, thus we can say that the s approx. 2^n			
are doing which the reduces to and fib(i - array at ea we are do amount of	e in this program we memoization due to amount of work b looking up fib(i - 1) 2) values in memo ach call fib(i). Thus, ing a constant f work n times in n ce time complexity:			
times we until we guntil we gunte case 1. As number of	ne is the number of can divide n by 2 et down to the base s, we know the firmes we can ntil we get 1 is O			
Additional Problems				
	op iterates through ne complexity is O			
through b	sive call iterates calls as it subtracts iteration, thus time y is O(b)			

3	It does constant amount of work, thus time complexity is O(1)			
4	The variable count will eventually equal a/b. The while loop iterates through count times. Thus time complexity is O(a/b)			
5	The algorithm is actually doing a binary search to find the square root. Thus the runtime is O(logN)			
6	This is straightforward loop that stops when guess*guess > n or guess> sqrt(n); hence time complexity is O(sqrt(n))			
7	Ifa binary tree is not balanced, the max time to find an element would be the depth of the tree. The tree since it is imbalanced could be a straight list downwards and ave depth n. Thus, runtime is O(n)			
8	Without any ordering or sorting in a binary tree, we might need to traverse through all the nodes in the tree , thus the time complexity is O(n) where n is the number of nodes in the tree.			
9	The first call to appendToNew takes 1 copy. The second call takes 2 copies. The third call takes 3 copies. And so on. The total time will be sum through 1 to n, which is O(n^2)			
10	The runtime would be O(d) where d is the number of digits in the given number. A number with d digits can have a value upto 10^d. If n = 10^d, then d = log n. Thus, time complexity is O(log n) where the log is with base 10.			
11	If the length of the string is k, then to check if the string is inOrder or sorted , takes $O(k)$ time. Also, suppose the length of the string is c characters. Now, to get strings of c characters and k length would be $O(c^{\Lambda}k)$. for example, you wish to construct astring length 3 with just two characters a and b, thus the number of strings possible would be $2^{\Lambda}3$. Similarly here , that runtime would be $O(c^{\Lambda}k)$. Thus, overall runtime to get all the strings of k length with c characters and check if they are sorted would be $O(kc^{\Lambda}k)$.			

	First of all the runtime for mergeSort would be O(blogb). then, for each element in a, we are doing binary search of b-runtime would be O(a * log b). hence overall runtime is O (b log b + a log b).							
Section IX	Interview Ques	tions						
Chapter 1	Arrays and Stri							
	Hash Table							
		a data structure that maps keys cient lookup.						
	Hash Table Imp	olementation						
	Approach 1	We use an array of Linked List	s and a hash code function.					
		To insert a key (a string or any we follow the following steps:	other datatype) and value					
		Compute the key's hashcod or long. Two different keys cou as there may be numerous key	ld have the same hashcode,					
		2. Then, we map the hash cod This could be done with somet array_length. Two different has to the same index.	hing like hash (key) %					
	3. At this index, there is a linked list of keys Store the key and value in the index. We n List to tackle collisions: you could have two with same hashcode or two different hasho index		index. We must use a Linked uld have two different keys					
			If it is the worst case, collisions are very high, runtime would be O(N) where N is the number of keys. And, if it is the best case, collisions are minimum, look up time would be O(1)					
	Approach 2	We can implement a look up s search tree. This gives us O(ladvantage of this approach is we no longer allocate a large a through keys in order.	ogN) lookup time. The potentially less space , since					
	ArrayList & Res	sizable Arrays						
	A typical implementation is that when the array is full, the array-like datastructure with dynamic resizing, you should use an ArrayList. A typical implementation is that when the array is full, the array doubles in size (in Java, the size might instead increase to get an array of size N/8 ++ 2+ 1 = N. Therefore, elements takes O(N) worktotal. insertion on an average takes O worst case.			each capacity e N: N/2 + N/4 + e, inserting N I. Thus, each O(1), even				
	StringBuilder							

	Normally, concatenating n strings of x characters each would take O (xn^2).	$O(x + 2x + 3x + 3x + nx) = O(xn^2)$						
	StringBuilder ca the strings, copy	n reduce this complexity as it cr ring them to one string only if ne	eates a resizeable array of all reded					
Chapter 2	Linked Lists							
	LinkedList is a datastructure representing a sequence of nodes.	Singly Linked List> there is a pointer to the next node	Doubly Linked List> there is a pointer to the next and previous nodes					
	constant time access to any element of the list. It takes iterating through K elements to get the		Benefit of a Linked List is that one can add or remove items from the beginning of the list in constant time					
Chapter 3	Stacks and Que	eues						
	Stack uses LIFO	Operations of a stack: pop(), push(item), peek(), isEmpty()	A stack does not offer constant-time access to the ith item. However, it allows constant time adds and removes as it does not require shifting elements around.	most useful case algorithms - one temporary data one recurses, buthem as one bac	needs to push oto a stack as ut then remove			
	Queue implements FIFO	Operations of a queue: add (item), remove(), peek(), isEmpty()	most useful case: breadth- first search and implementing a cache					