

# MULTIFIDELITY FORWARD-INVERSE WORKFLOW IN DAKOTA. A DEMONSTRATION IN WIND ENERGY

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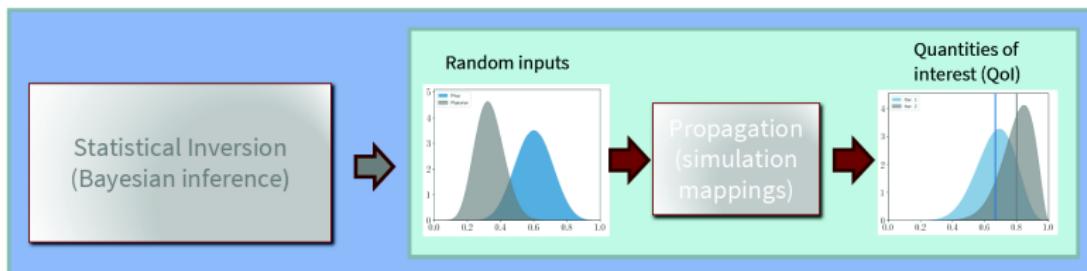
## PLAN OF THE TALK

- UNCERTAINTY QUANTIFICATION
- MF IN UQ: MOTIVATION
- MULTIFIDELITY SURROGATE UQ
- SURROGATE-BASED INVERSE UQ
- INVERSE UQ DEMONSTRATION FOR WIND
- CONCLUSIONS

# **Uncertainty Quantification**

# UNCERTAINTY QUANTIFICATION

## GENERALITIES



### Uncertainty Quantification:

- ▶ **Forward UQ:** random inputs are propagated through the computer code and statistics of the QoI are evaluated
- ▶ **Inverse UQ:** measurements of the QoIs are used to obtain data-informed distributions of the input parameters

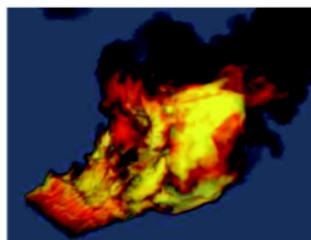
### Forward and Inverse UQ are part of the same workflow:

- ▶ Prior distributions based on a priori knowledge
- ▶ From observational data (experiments, etc.) we can infer posterior distributions via Bayes rule
- ▶ Use of data can reduce uncertainty in parameter to QoI mapping (priors are constrained)
- ▶ Design using prior uncertainties can be overly conservative
- ▶ Reduced uncertainty of data-informed UQ can produce designs with greater performance

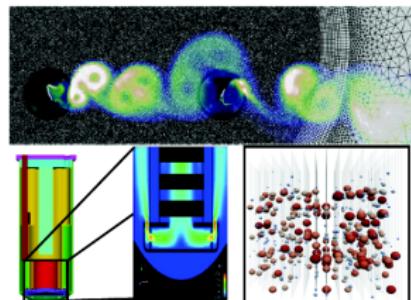
## **Why multifidelity in Uncertainty Quantification?**

## UNCERTAINTY QUANTIFICATION DoE AND DoD DEPLOYMENT ACTIVITIES

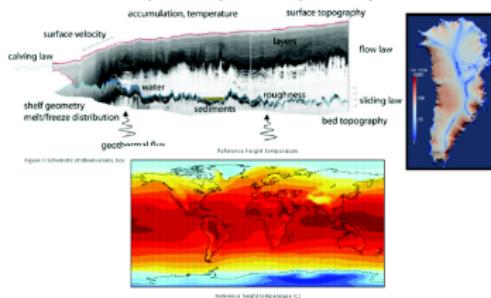
### Stewardship (NNSA ASC) Safety in abnormal environments



### Energy (ASCR, EERE, NE) Wind turbines, nuclear reactors



### Climate (SciDAC, CSSEF, ACME) Ice sheets, CISM, CESM, ISSM, CSDMS



### Addtnl. Office of Science: (SciDAC, EFRC)

Comp. Matls: waste forms /  
hazardous mats (WastePD, CHWM)  
MHD: Tokamak disruption (TDS)

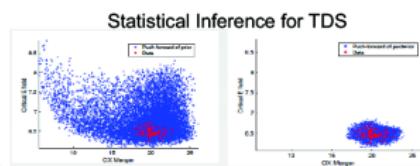
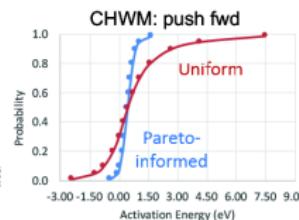
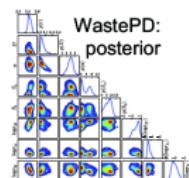


FIGURE: Courtesy of Mike Eldred

High-fidelity state-of-the-art modeling and simulations with HPC

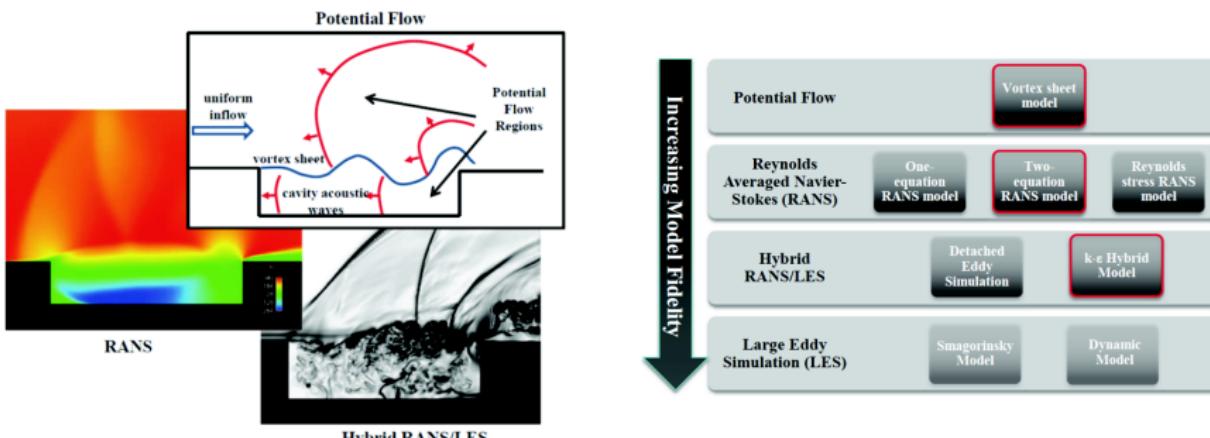
- ▶ Severe simulations **budget constraints**
- ▶ Significant dimensionality driven by model complexity

# UNCERTAINTY QUANTIFICATION

## RICH SET OF MODELING CHOICES – DISCRETIZATION VS FIDELITY

**Multi-fidelity:** several accuracy levels available

- ▶ Physical models (Laminar/Turbulent, Reacting/non-reacting, viscous/inviscid...)
- ▶ Numerical methods (high/low order, Euler/RANS/LES, etc...)
- ▶ Numerical discretization (fine/coarse mesh...)
- ▶ Quality of statistics (long/short time history for turbulent flow...)



**Relationships** amongst models can be difficult to anticipate

- ▶ **Hierarchical** relationships usually correspond to modeling choices like, e.g. discretization
- ▶ However, **peer** relationships are often observed in the presence of physical approximations

# MF UNCERTAINTY QUANTIFICATION

## SAMPLING, SURROGATE BASED METHODS AND CHALLENGES

### MF Sampling methods

- ▶ Derive directly from **Monte Carlo**
- ▶ Exploit **correlation** among model outputs
- ▶ Are built to obtain an **estimator variance reduction**
- ▶ Ex: MLMC (Giles, 2015), MFMC (Peherstorfer *et al.*, 2016), MLMF (Geraci *et al.*, 2015) ACV (Gorodetsky *et al.*, 2020)

### MF Surrogate methods

- ▶ Provide an approximation of the *input-output* mapping
- ▶ Achieve **rapid error decrease** (as the amount of data increases), provided that the *input-output* mapping is smooth
- ▶ Can be **easily integrated** in inverse and OUU workflows
- ▶ Ex: Co-Kriging (Gradiet and Garnier, 2014) and stage-fitting (Liu *et al.* 2018)

## **Surrogate-based Multifidelity**

## SEMINAL IDEA

### DECREASING 'COMPLEXITY' FOR THE DISCREPANCY FUNCTION

- ▶ The concept of **multifidelity** has been known/exploited in the optimization community for decades
- ▶ One of the first applications of this concept in UQ:

Ng and Eldred. *Multifidelity uncertainty quantification using non-intrusive polynomial chaos and stochastic collocation*. In 53rd AIAA/ASME/ASCE/AHS/ASC Structures, Structural Dynamics and Materials Conference, 2012.

The **main idea** is quite simple and effective: Can you use a **LF model to capture most of the response** and use only **fewer HF evaluations to correct** it?

An illustrative demonstration:

$$Q_{HF} = \exp -0.05\xi^2 \cos 0.5\xi - 0.5 \exp -0.02(\xi - 5)^2$$

$$Q_{LF} = \exp -0.05\xi^2 \cos 0.5\xi$$

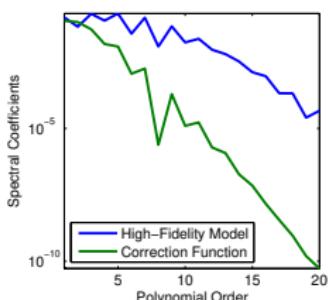


FIGURE: Spectral content

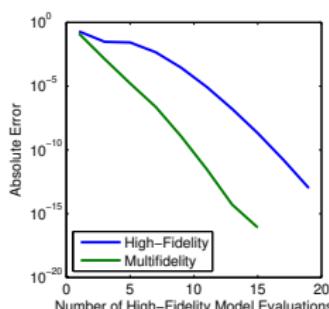


FIGURE: Error (Mean)

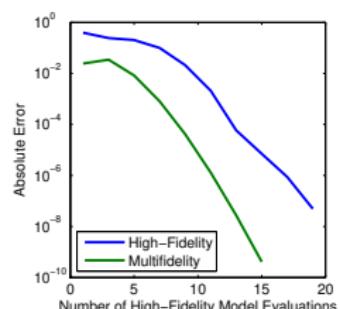


FIGURE: Error (Mean)

## 'COMPLEXITY' OF A FUNCTION ORDER, SPARSITY, LOW-RANK STRUCTURE...

The original idea was based on the following assumptions:

- ▶ the LF model is able to capture the high frequencies of the response
- ▶ only the low-order terms are included in the discrepancy term → **few evaluations of the discrepancy are needed** to build the response for the discrepancy

In many **practical applications**:

- ▶ the **LF model only captures low-order effects**
- ▶ however the discrepancy term can have a structure that we can still exploit

**Two possible structures** that we can exploit are:

- ▶ **Sparsity** → Compressed sensing: orthogonal matching pursuit (OMP), basis pursuit denoising (BPDN), least angle regression (LARS), least absolute selection and shrinkage operator (LASSO)...
- ▶ **Low-rank** → Functional Tensor-Train decomposition (TT)

## EXPLOITING FAVORABLE FUNCTION'S STRUCTURES

### THREE MAIN STRATEGIES – HIERARCHICAL RELATIONSHIP AMONG MODELS

In order we have tried **several approaches**:

- 1 **Optimal resources allocation** (direct extension of MLMC concepts to surrogates)

## EXPLOITING FAVORABLE FUNCTION'S STRUCTURES

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- 2 Exploiting **Restricted Isometry Property** (RIP)

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- 1 **Optimal resources allocation** (direct extension of MLMC concepts to surrogates)
- 2 Exploiting **Restricted Isometry Property** (RIP)
- 3 **Greedy Multilevel Refinement**

# EXPLOITING FAVORABLE FUNCTION'S STRUCTURES

## STRATEGY 1: EXTENDING THE MLMC SAMPLING APPROACH TO SURROGATES

**Main idea:** Parametrize the variance of the recovered discrepancy term

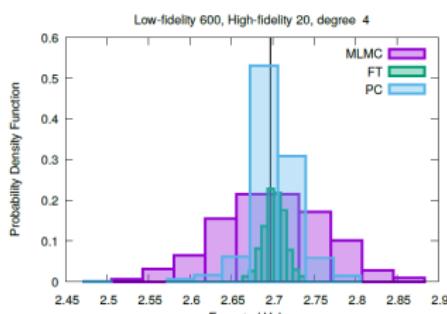
$$\text{Var} [\hat{Y}_\ell] = \frac{\text{Var} [Y_\ell]}{\gamma N^k} \rightarrow N_\ell = \sqrt[k]{\frac{\sum_{q=0}^L \sqrt[k+1]{\text{Var} [Y_q] C_q^k}}{\gamma \varepsilon^2 / 2}} \sqrt[k+1]{\frac{\text{Var} [Y_\ell]}{C_\ell}}$$

### Notes:

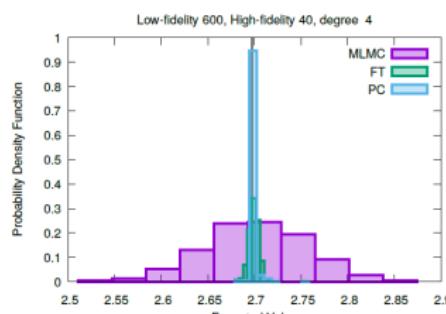
- ▶  $\gamma$  and  $k$  can be obtained as by-product of the k-fold cross-validation process
- ▶ this approach can be extended to level-dependent parameters, i.e.  $\gamma_\ell$  and  $k_\ell$  (slightly different closed form solution)

### Findings:

- ▶ **Abrupt transition** in both sparse and low-rank recovery **does not allow to efficiently estimate the parameters** and exploit the faster convergence



(a)  $N_{low} = 600$ ,  $N_{high} = 20$  and  $deg = 4$



(b)  $N_{low} = 600$ ,  $N_{high} = 40$  and  $deg = 4$

## EXPLOITING FAVORABLE FUNCTION'S STRUCTURES

### STRATEGY 2: RESTRICTED ISOMETRY PROPERTY (RIP) FROM Jakeman, Narayan, Zhou, 2016

**Main idea:** Address/Avoid abrupt transition by **ensuring enough samples** for accurate recovery

$$\text{RIP : } N_\ell \geq s_\ell L_\ell \log^3(s_\ell) \log(C_\ell)$$

where

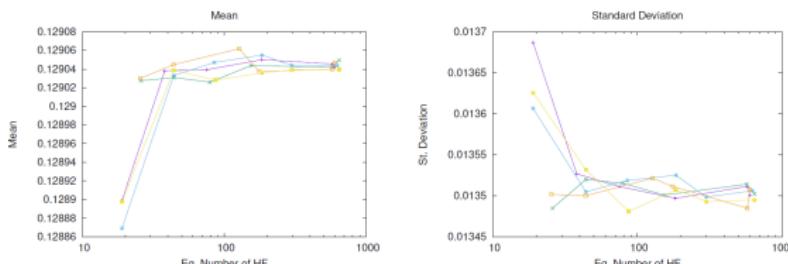
- ▶  $s_\ell$  is the sparsity, i.e. number of non-zero coefficients
- ▶  $L_\ell$  is the mutual coherence, i.e. if  $a_i$  are the normalized ( $a_i^T a_i = 1$ ) columns of the matrix  $A$  then  
 $L = \max |a_i^T a_j|$  for  $i \neq j$
- ▶  $C_\ell$  is the cardinality of the dictionary

#### Algorithm:

- ▶ Start with pilot sample to estimate sparsity at each level  $\ell$
- ▶ Number of samples is increased to allow the recovery

#### Findings:

- ▶ **RIP is quite conservative** and it is likely to overshoot so it is necessary to add a constraint on the profile → very difficult to handle the feedback



## EXPLOITING FAVORABLE FUNCTION'S STRUCTURES

### STRATEGY 3: GREEDY MULTILEVEL REFINEMENT

Main issues discovered with strategy #1 and #2 are:

- ▶ Difficult to estimate a trend
- ▶ Difficult to handle the sample allocation in order to avoid overshooting

**Proposed solution:** Greedy refinement - compete refinement candidates to **maximize induced change per unit cost**

**Algorithm:**

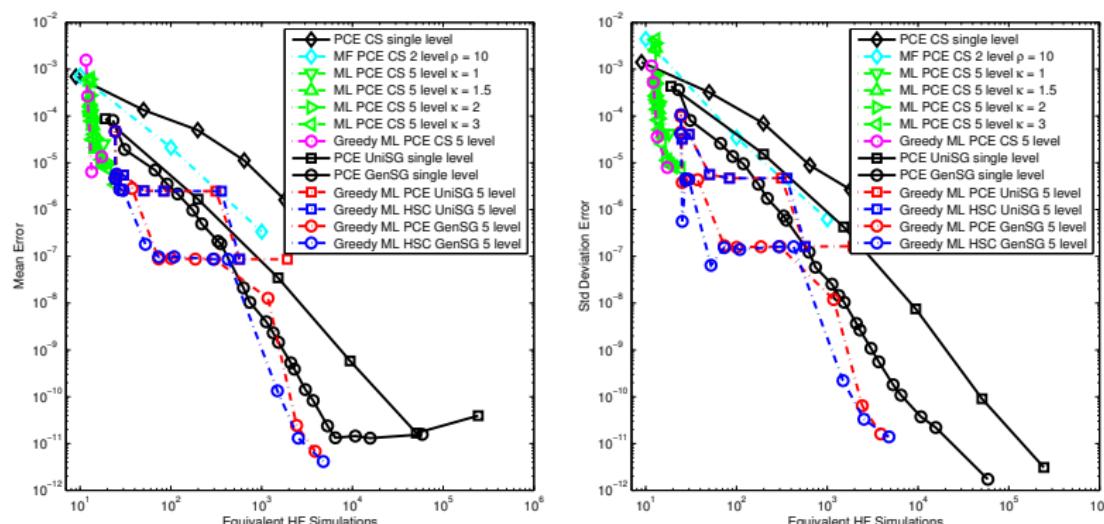
- ▶ One or more **candidates are generated** per each level
- ▶ The **impact of each candidate on the final Qols statistics is evaluated** and normalized by the relative cost of level increment
- ▶ **Greedy selection** of the best candidate
- ▶ **Generation of new candidates** for the selected level

## GREEDY MULTILEVEL REFINEMENT

### LEVEL CANDIDATE GENERATORS – CURRENT OPTIONS IN DAKOTA

- ▶ **Uniform refinement:** coarse-grained refinement with one expansion order / grid level candidate per model level
  - ▶ Tensor / sparse grids: projection PCE and nodal/hierarchical SC
  - ▶ Regression PCE: least squares / compressed sensing using a fixed sample ratio
- ▶ **Anisotropic refinement:** coarse-grained refinement with one expansion order / grid level candidate per model level
  - ▶ Tensor / sparse grids: projection PCE and nodal/hierarchical SC
- ▶ **Index-set-based refinement:** fine-grained refinement with multiple index set candidates per model level; exponential growth in size of candidate set with dimension.
  - ▶ Generalized sparse grids: projection PCE and nodal/hierarchical SC
- ▶ **Basis selection:** coarse-grained refinement with a few expansion order frontier advancements per model level
  - ▶ Regression PCE

## GREEDY MULTILEVEL REFINEMENT CS/GSG - STATISTICS



**FIGURE:** Convergence for greedy multilevel PCE comparing generalized sparse grids and compressed sensing.

### Notes:

- The explicit nature of the sparse grid approaches allows for more precise convergence
- The CS-based approaches are hampered in accuracy by the large implicit system solve needed at the coarse level

## **Surrogate-based inverse UQ**

## BAYESIAN INVERSION

### GENERALITIES ON THE APPROACH ADOPTED IN THIS WORK

#### Bayesian calibration

- ▶ Sandia's UQ software **Dakota** (see Dakota Theory Manual for more details)
- ▶ **Markov Chain Monte Carlo** for computing a sample-based **posterior distribution**
- ▶ We are interested in calibrating the parameters  $\theta$
- ▶ We assume that a surrogate for the computational model is available for the QoI:  $\mathbf{q} = \mathbf{q}(\theta)$
- ▶ Reference data  $\mathbf{d}$  are available

#### NOTES:

- ▶ From computational perspective it is more convenient to work with the negative log-likelihood
$$-\log \mathcal{L}(\theta; \mathbf{d}) = \frac{n}{2} \log(2\pi) + \frac{1}{2} \log |\Sigma_{\mathbf{d}}| + \frac{1}{2} \mathbf{r}^T \Sigma_{\mathbf{d}}^{-1} \mathbf{r}$$
- ▶ The term  $\mathbf{r}^T \Sigma_{\mathbf{d}}^{-1} \mathbf{r}$  is called **Misfit Function**
- ▶ Minimizing the **Misfit Function** corresponds to maximizing the **Likelihood**
- ▶ Maximizing the Likelihood (MLE) does not in general correspond to the Maximum A posteriori (MAP) point
- ▶ Posterior probability is analytically intractable and therefore MCMC is used to approximate it
- ▶ We use the QUESO library in Dakota to perform MCMC

## BAYESIAN INVERSION

### WHY DOES HAVING A SURROGATE HELP?

- ▶ MCMC requires a very large number of runs/evaluations to converge
- ▶ Surrogates can provide:
  - ▶ Computing local accurate proposal density (by using Hessian information)
  - ▶ Pre-solving for the MAP in order to eliminate the initial burn-in phase

#### Computing a local accurate proposal density

- ▶ The MCMC proposal covariance to be the inverse of the Hessian of the negative log posterior

$$\nabla_{\boldsymbol{\theta}}^2 [-\log(\pi_{\text{post}}(\boldsymbol{\theta}))] = \nabla_{\boldsymbol{\theta}}^2 M(\boldsymbol{\theta}) - \nabla_{\boldsymbol{\theta}}^2 [\log(\pi_0(\boldsymbol{\theta}))]$$

- ▶ A standard approximation is the multivariate normal (MVN) distribution with mean centered at the actual point in the chain and prescribed covariance

$$-\nabla_{\boldsymbol{\theta}}^2 [\log(\pi_0(\boldsymbol{\theta}))] = \boldsymbol{\Sigma}_{\mathbf{0}}^{-1} \rightarrow \nabla_{\boldsymbol{\theta}}^2 [-\log(\pi_{\text{post}}(\boldsymbol{\theta}))] = \nabla_{\boldsymbol{\theta}}^2 M(\boldsymbol{\theta}) + \boldsymbol{\Sigma}_{\mathbf{0}}^{-1} [\log(\pi_0(\boldsymbol{\theta}))]$$

- ▶ The Hessian of the Misfit Function can be computed through the surrogate model as

$$\nabla_{\boldsymbol{\theta}}^2 M(\boldsymbol{\theta}) = \nabla_{\boldsymbol{\theta}} \mathbf{q}(\boldsymbol{\theta})^T \boldsymbol{\Sigma}_{\mathbf{d}}^{-1} \nabla_{\boldsymbol{\theta}} \mathbf{q}(\boldsymbol{\theta}) + \nabla_{\boldsymbol{\theta}}^2 \mathbf{q}(\boldsymbol{\theta}) \cdot [\boldsymbol{\Sigma}_{\mathbf{d}}^{-1} \mathbf{r}] .$$

#### Avoiding the burn-in phase

- ▶ When a surrogate is available the burn-in can be avoided by pre-solving for the MAP point using an optimizer to minimize the negative log posterior

$$\boldsymbol{\theta}_{\text{MAP}} = \underset{\boldsymbol{\theta}}{\operatorname{argmin}} [-\log(\pi_{\text{post}}(\boldsymbol{\theta}))]$$

**Inverse UQ demonstration  
Nalu/WindSE**

## BAYESIAN INVERSION

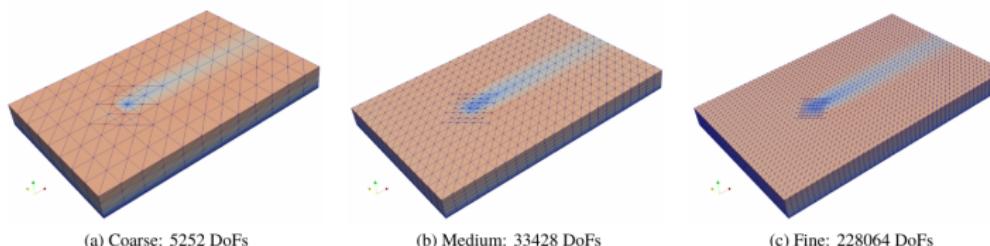
### WAKE CHARACTERIZATION FOR A V27 ROTOR – MULTILEVEL PROBLEM SETUP

#### Reference data from Nalu

- ▶ 100 m × 110 m slice 5D downstream (135m)
- ▶ Data acquired each second for 10 minutes
- ▶ Reference data are averaged

#### Computational tool: WindSE

- ▶ Medium fidelity tool for 3D Reynolds-averaged Navier Stokes (RANS) simulations
- ▶ Turbines are represented by means of **non-rotating** actuator disks
- ▶ Turbulence closure via mixing length
- ▶ Based on FEniCS which enables easy user customization

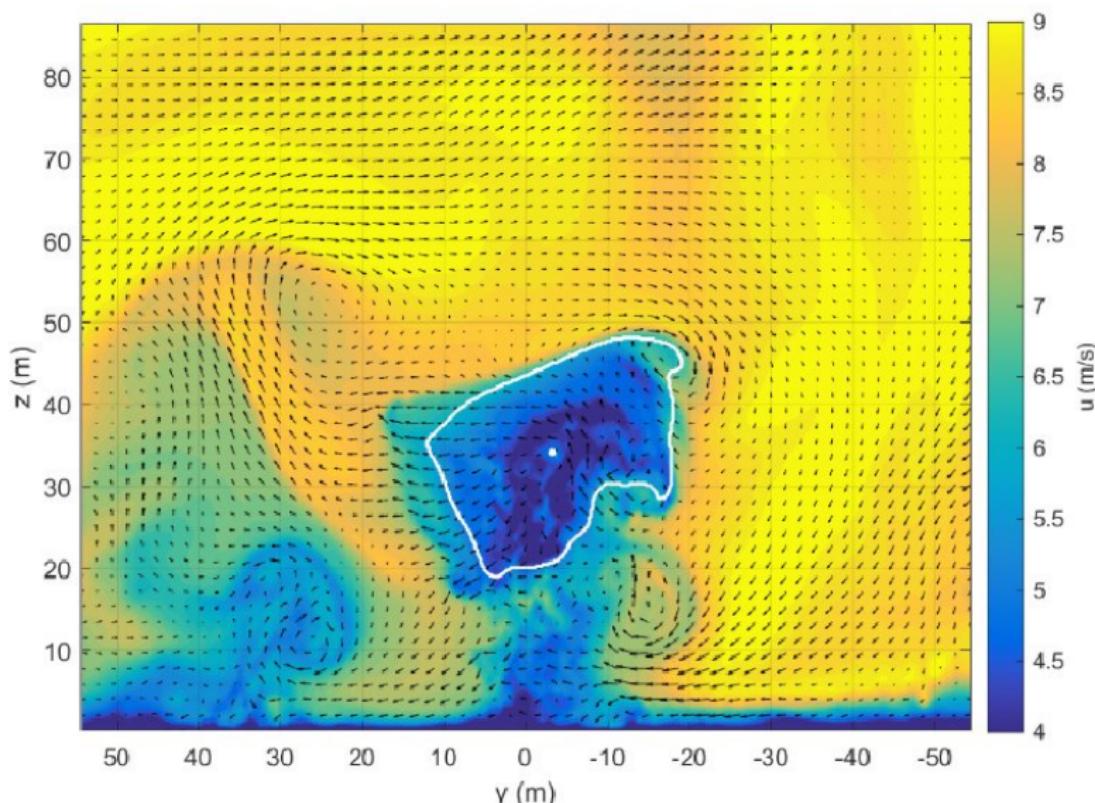


Model Resolution	$N_x$	$N_y = N_z$	Cost (s)
Coarse	12	8	8.51
Medium	24	16	60.4
Fine	48	32	1270

TABLE: Multilevel model hierarchy unrefined grid discretization and simulation cost.

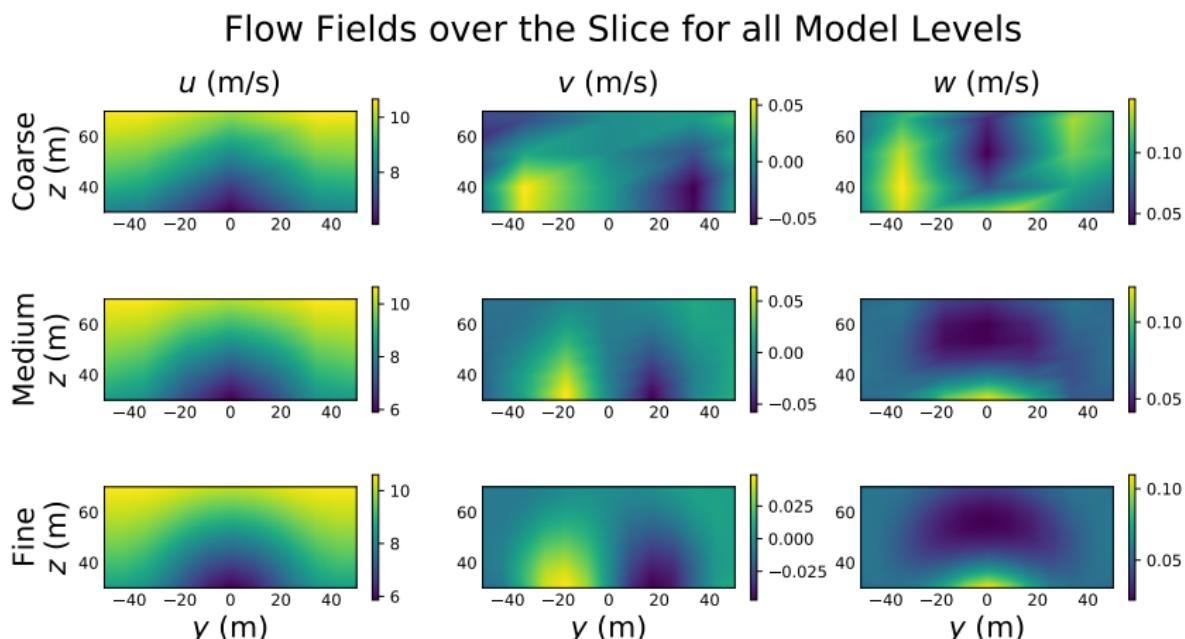
## BAYESIAN INVERSION

### WAKE CHARACTERIZATION FOR A V27 ROTOR – REFERENCE HF (NALU-WIND) SNAPSHOT



## BAYESIAN INVERSION

### WAKE CHARACTERIZATION FOR A V27 ROTOR – NOMINAL CONDITIONS



**FIGURE:** Nominal output for three velocity components  $u$ ,  $v$  and  $w$  over all models.

## BAYESIAN INVERSION

### WAKE CHARACTERIZATION FOR A V27 ROTOR – MULTILEVEL SURROGATE CONSTRUCTION

Parameter	$u_H$ ( $\frac{m}{s}$ )	$\alpha$	$\theta_{wind}$ ( $^{\circ}$ )	Eff. Thickness (m)	Ax. Ind. Factor	$\ell_{max}$ (m)
Lower bound	8.25	0.02	-15	2.4	0.15	3.5
Upper bound	8.75	0.5	15	15	0.9	15

TABLE: Uniform parameter bounds for the forward and inverse UQ studies.

#### RANS data

- First set of tests demonstrated that the misfit between the data was dominated by boundary layer data
- We truncated the spatial region of interest to  $30m < z < 70m$  (total of  $131 \times 161$  points)
- The total number of QoIs to be considered is 31 395

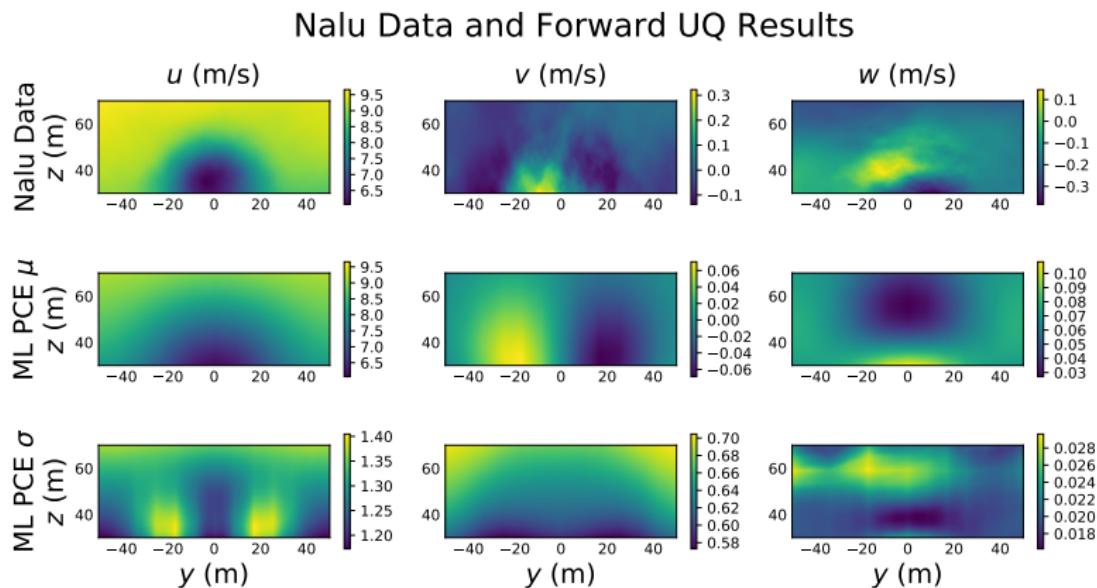
Tolerance	5e-4		5e-5		5e-6	
	SF	ML	SF	ML	SF	ML
Coarse Evaluations	N/A	129	N/A	409	N/A	1201
Medium Evaluations	N/A	53	N/A	137	N/A	601
Fine Evaluations	81	13	209	17	433	61
Equivalent Fine Evaluations	17		27		99	
ML Speedup	4.9		8.0		4.4	

TABLE: Number of model evaluations for SF (single high-fidelity) and ML (multilevel) PCEs for three tolerances. The construction of each ML PCE requires less than a quarter of the cost of the corresponding SF model.

NOTE: A cost saving factor 4 – 9 can be obtained in this case!

## BAYESIAN INVERSION

### ML FORWARD PROPAGATION – A PRIORI SURROGATE IS NOT ABLE TO REPRODUCE THE DATA

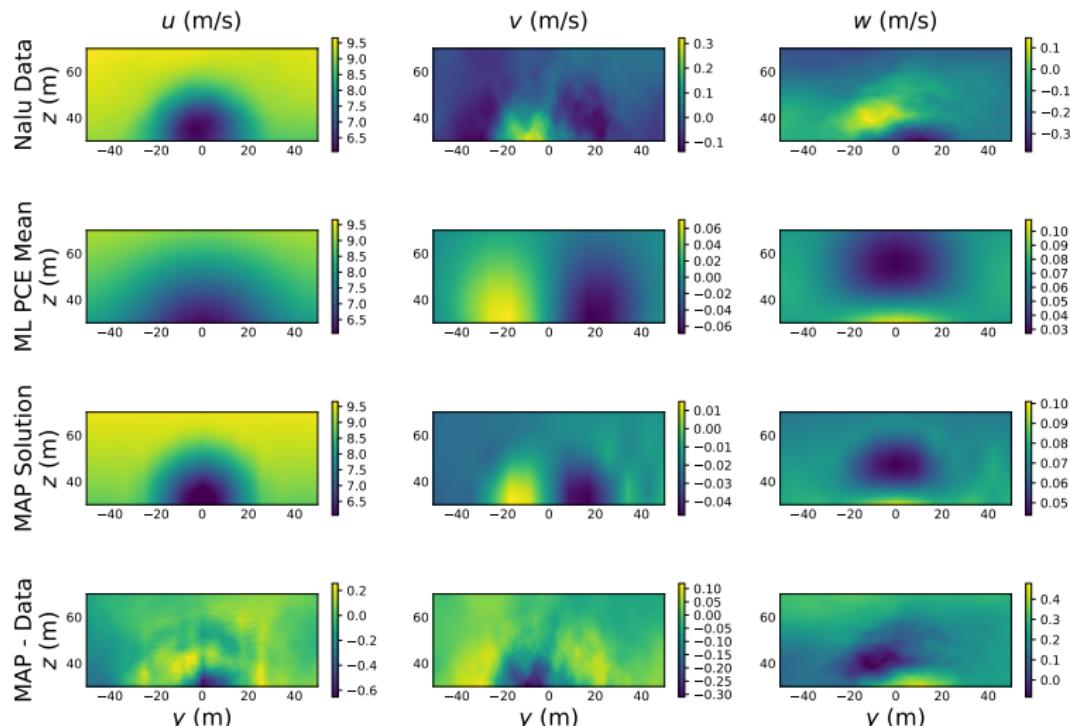


**FIGURE:** ML PCE built for all velocity components compared with the time-averaged Nalu slice data. The mean  $u$  component resembles the Nalu data but the other components do not due to the model error between WindSE and Nalu.

## BAYESIAN INVERSION

### WAKE CHARACTERIZATION FOR A V27 ROTOR – MULTILEVEL SURROGATE AFTER CALIBRATION

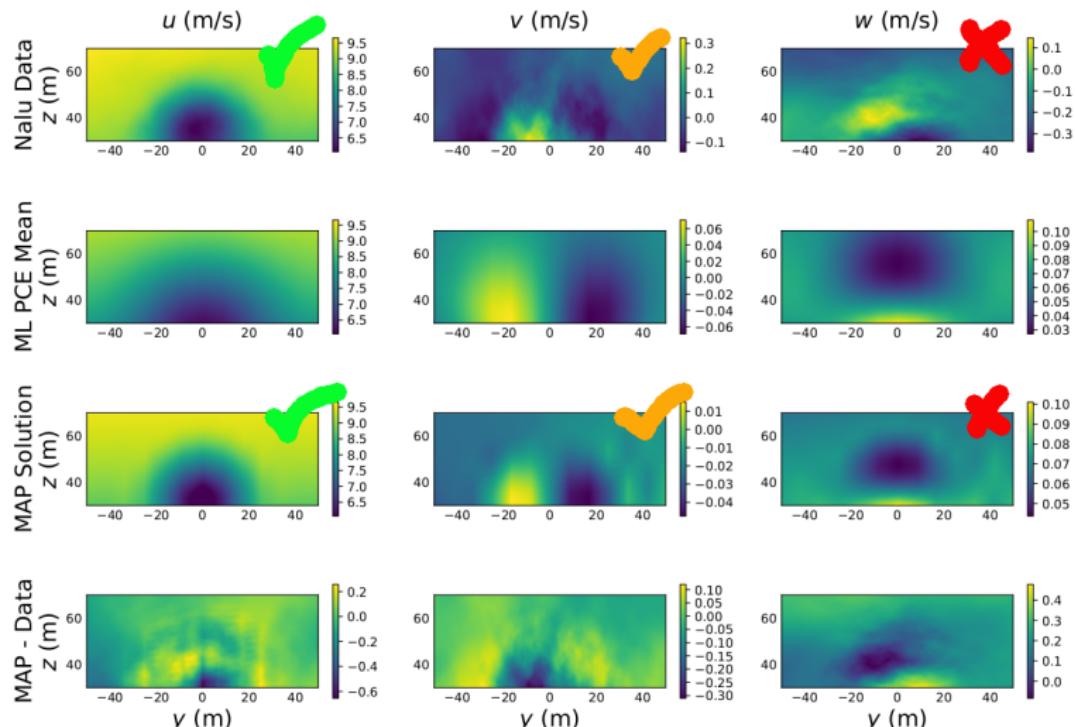
Inference Results from  $u$ ,  $v$ , and  $w$  Nalu Data



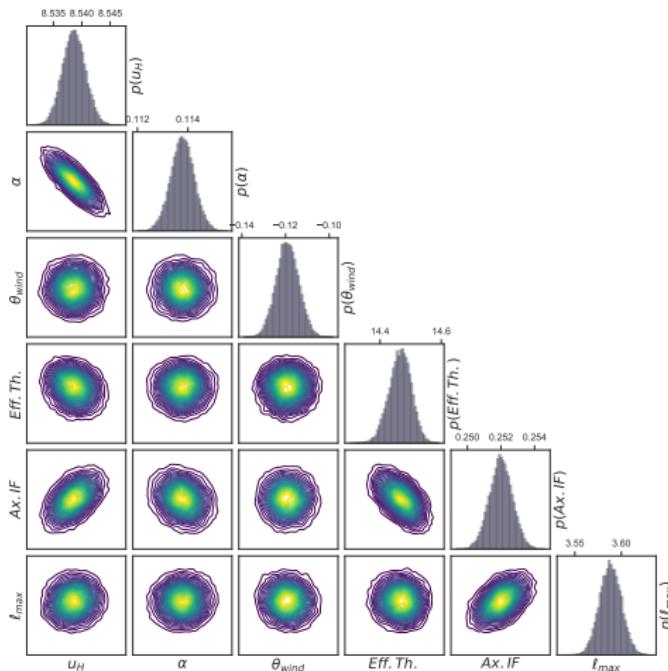
## BAYESIAN INVERSION

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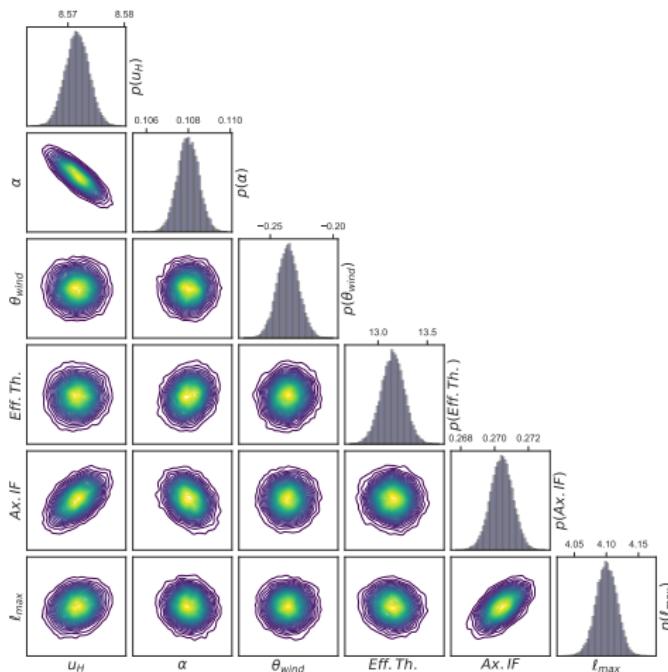
## BAYESIAN INVERSION POSTERIOR DISTRIBUTION



**FIGURE:** Visualization of the six-dimensional posterior distribution obtained through emulator-based inference from *all* velocity components. Marginal distributions are shown as histograms and pairwise joint distributions are displayed as contour plots.

## BAYESIAN INVERSION

### POSTERIOR DISTRIBUTION



**FIGURE:** Visualization of the six-dimensional posterior distribution obtained through emulator-based inference from  $u$  data only. Marginal distributions are shown as histograms and pairwise joint distributions are displayed as contour plots.

## **Conclusions**

## CONCLUDING REMARKS

### STILL AN ACTIVE RESEARCH AREA

#### Summary:

- ▶ Well designed Multifidelity estimators can **accelerate the construction of surrogates**
- ▶ Multifidelity surrogates can **accelerate the inverse UQ workflow**
- ▶ NOTE: Multifidelity surrogate-based **inversion cannot compensate for missing physics** – Non-rotating Actuator Disk in RANS Vs LES

#### (Incomplete) list of references:

- ▶ G. Geraci, M.S. Eldred, A.A. Gorodetsky & J.D. Jakeman, Recent advancements in Multilevel-Multifidelity techniques for forward UQ in the DARPA Sequoia project. *AIAA Scitech 2019 Forum*
- ▶ D.T. Seidl, G. Geraci, R. King, F. Menhorn, A. Glaws and M.S. Eldred, Multifidelity strategies for forward and inverse uncertainty quantification of wind energy applications. *AIAA Scitech 2020 Forum*
- ▶ A.A. Gorodetsky, J.D. Jakeman, G. Geraci, M. Eldred, MFNets: Multi-fidelity data-driven networks for Bayesian learning and prediction. *International Journal for Uncertainty Quantification*, Vol. 10(6), pp. 595–622, 2020.
- ▶ A.A. Gorodetsky, J.D. Jakeman, G. Geraci, MFNets: Learning network representations for multifidelity surrogate modeling. *Journal of Computational Physics*, Under review, 2020. <https://arxiv.org/pdf/2008.02672.pdf>

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