

# Introduction to ML and Regression

## Statistical Natural Language Processing

Çağrı Çöltekin

University of Tübingen  
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# Why machine learning?

- Majority of the modern computational linguistic tasks and applications are based on machine learning
  - Tokenization
  - Part of speech tagging
  - Parsing
  - ...
  - Speech recognition
  - Named Entity recognition
  - Document classification
  - Question answering
  - Machine translation
  - ...

# Machine learning is ...

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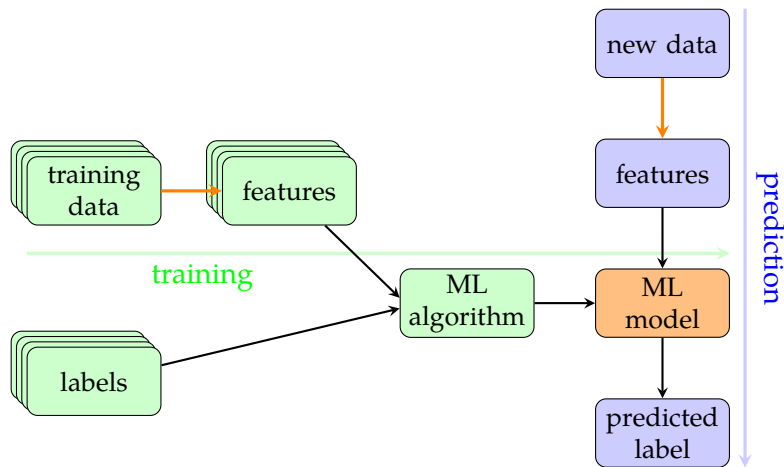
*Statistical learning refers to a vast set of tools for **understanding data**.* —James et al. (2013)

# Supervised or unsupervised

- Machine learning methods are often divided into two broad categories: *supervised* and *unsupervised*
- Supervised methods rely on *labeled* (or *annotated*) data
- Unsupervised methods try to find regularities in the data without any (direct) supervision
- Some methods do not fit any (or fit both):
  - *Semi-supervised* methods use a mixture of both
  - *Reinforcement learning* refers to the methods where supervision is indirect and/or delayed

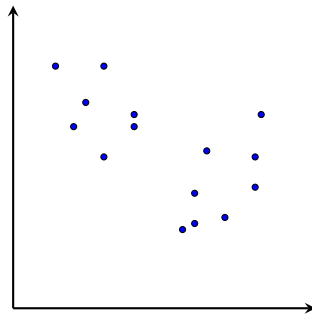
In this course, we will mostly discuss/use supervised methods.

# Supervised learning



# Unsupervised learning

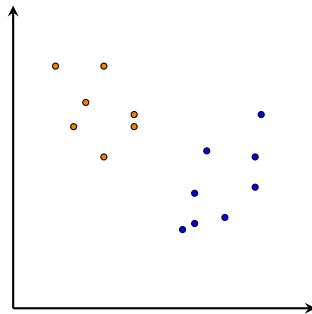
- In unsupervised learning we do not have any labels
- The aim is discovering some 'latent' structure in the data
- Common examples include
  - Clustering
  - Density estimation
  - Dimensionality reduction
- The methods that do not require (manual) annotation are sometimes called unsupervised





# Unsupervised learning

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# Supervised learning

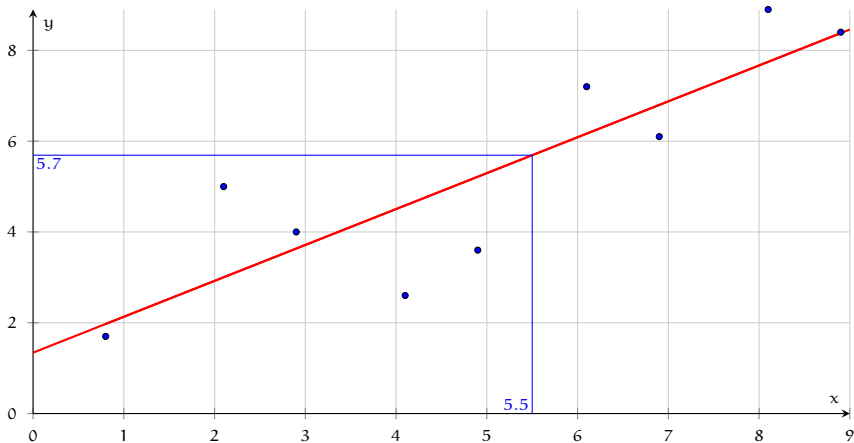
two common settings

A supervised ML method is called

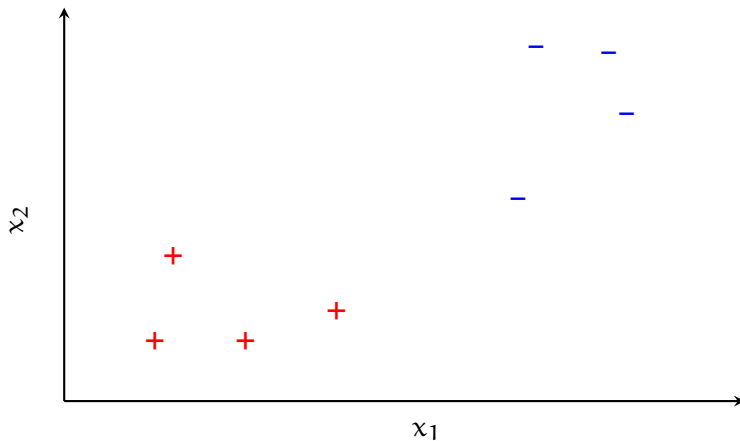
*regression* if the outcome to be predicted is a numeric (continuous) variable

*classification* if the outcome to be predicted is a categorical variable

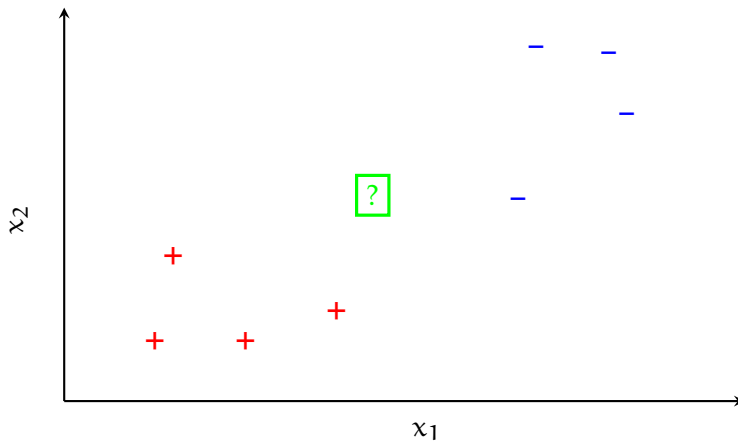
# Regression



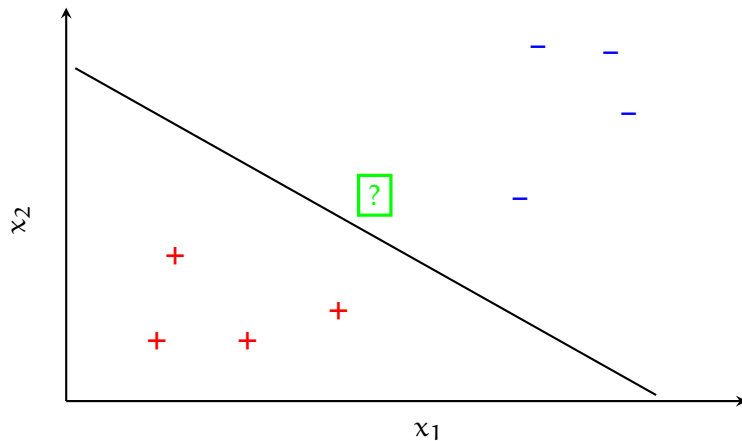
# Classification



# Classification



# Classification



# ML topics we will cover in this course

- (Linear) Regression (today)
- Classification (perceptron, logistic regression, ANNs)
- Evaluating ML methods / algorithms
- Unsupervised learning
- Sequence learning

# Machine learning and statistics

- The methods largely overlap (it was even suggested that both should be collectively called 'data science')
- Aims differ
  - In statistics (used as in experimental sciences) aim is making inferences using the models
  - In machine learning correct predictions are at the focus
- A more diverse set of models/methods are used in ML



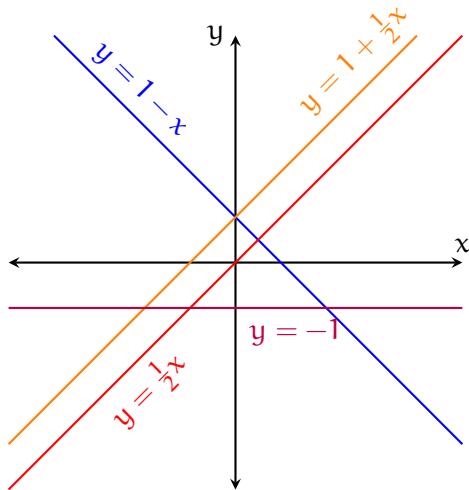
# Machine learning and models

- A machine learning method makes its predictions based on a model
- The models are often parametrized: a set of parameters defines a model
- Learning can be viewed as finding the ‘best’ model among a family of models (that differ based on their parameters)

# The linear equation: the regression model

$$y = a + bx$$

- a (intercept) is where the line crosses the y axis.
- b (slope) is the change in y as x is increased one unit.



# The simple linear model

some terminology

$$y_i = a + bx_i$$

$y$  is the *outcome* (or response, or dependent) variable. The index  $i$  represents each unit observation/measurement (sometimes called a 'case')

$x$  is the *predictor* (or explanatory, or independent) variable

$a$  is the *intercept* (called *bias* in the NN literature)

$b$  is the *slope* of the regression line.

$a$  and  $b$  are called *coefficients* or *parameters*

$a + bx$  is the model's prediction of  $y$  ( $\hat{y}$ ), given  $x$

# Notation differences for the regression equation

$$y_i = a + bx_i$$

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$$y_i = \alpha + \beta x_i$$

- Sometimes, Greek letters  $\alpha$  and  $\beta$  are used for intercept and the slope, respectively

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- Sometimes coefficients wear hats, to emphasize that they are estimates



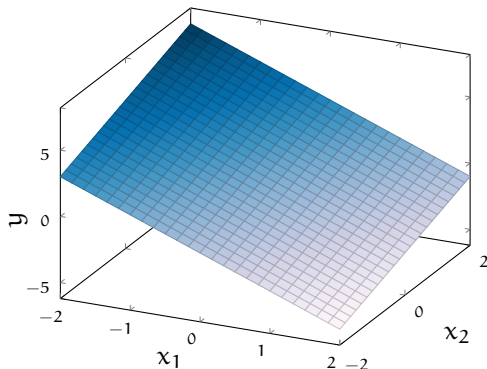
# Notation differences for the regression equation

$$y_i = \mathbf{w} \mathbf{x}_i$$

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- Sometimes coefficients wear hats, to emphasize that they are estimates
- Often, we use the vector notation for both input(s) and coefficients:  
 $\mathbf{w} = (w_0, w_1)$  and  $\mathbf{x}_i = (1, x_i)$

# Regression models with multiple predictors

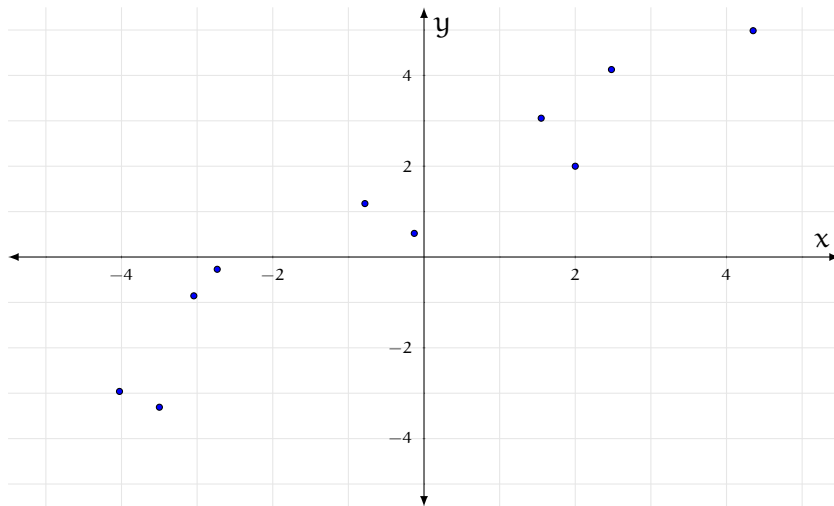
- The equation defines a (hyper)plane
- With 2 predictors:  
 $y = w_0 + w_1x_1 + w_2x_2$
- With more predictors it is more convenient to use the vector notation:  $y = \mathbf{w}\mathbf{x}$



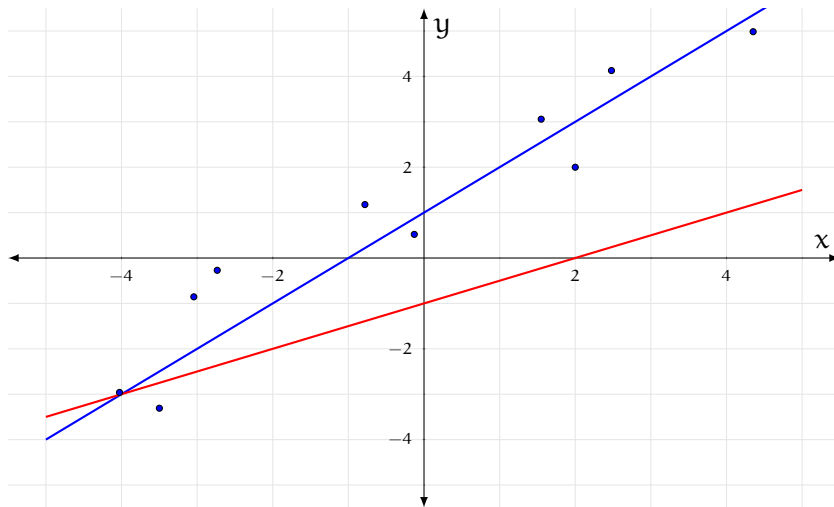
# Parameter estimation

- In ML, we are interested in finding the best model based on data
- Learning is selecting a model from a family of models that differ in their parameters
- Typically, we seek the parameters that reduce the prediction error on a training set
- Ultimately, we seek models that do not only do well on the training data, but also new, unseen instances

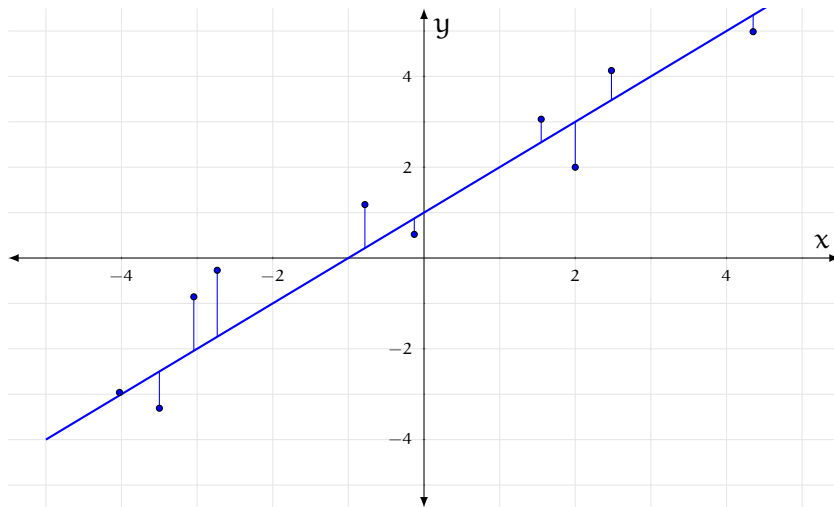
# Parameter estimation for regression



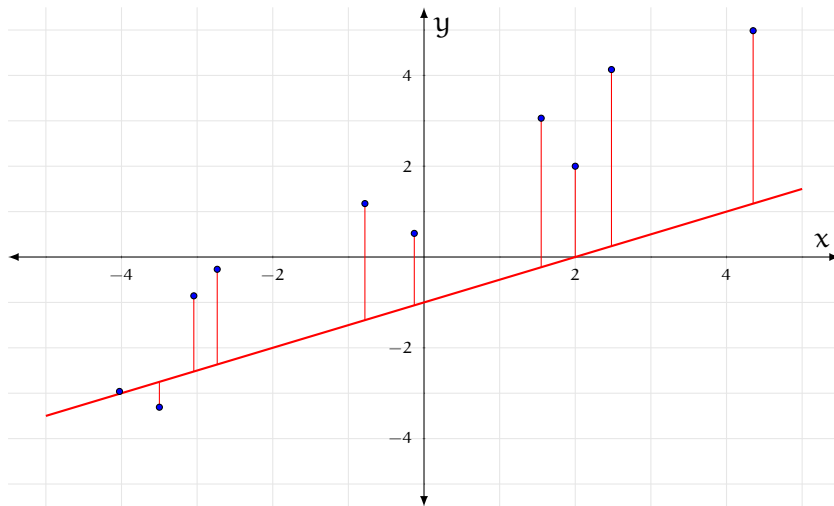
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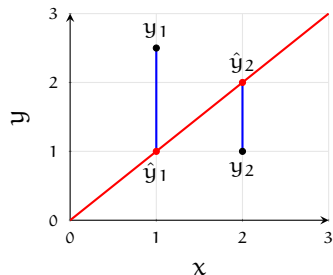


# Parameter estimation for regression



# Estimating regression parameters

- We view learning as a search for the regression equation with least **error**
- The error terms are also called *residuals*
- We want error to be low for the whole training set: average (or sum) of the error has to be reduced
- Can we minimize the sum of the errors?



$$y_i = \underbrace{w_0 + w_1 x_i}_{\hat{y}_i} + \epsilon_i$$



# Least-squares regression

- Find  $w_0$  and  $w_1$ , that minimize the *sum of the squared errors* (SSE)

$$E(\mathbf{w}) = \sum_i \epsilon_i^2 = \sum_i (y_i - \hat{y}_i)^2 = \sum_i (y_i - (w_0 + w_1 x_i))^2$$

- We can minimize  $E(\mathbf{w})$  analytically

$$w_1 = \frac{\sigma_{xy}}{\sigma_x^2} = r \frac{sd_y}{sd_x} \qquad w_0 = \bar{y} - w_1 \bar{x}$$

## Short digression: minimizing functions

In least squares regression, we want to find  $w_0$  and  $w_1$  values that minimize

$$E(\mathbf{w}) = \sum_i (y_i - (w_0 + w_1 x_i))^2$$

- Note that  $E(\mathbf{w})$  is a *quadratic* function of  $\mathbf{w} = (w_0, w_1)$
- As a result,  $E(\mathbf{w})$  is *convex* and have a single extreme value
  - there is a unique solution for our minimization problem
- In case of least squares regression, there is an analytic solution
- Even if we do not have an analytic solution, if the error function is convex, a search procedure like *gradient descent* can still find the *global minimum*

# What is special about least-squares?

- Minimizing MSE (or  $SS_R$ ) is equivalent to MLE estimate under the assumption  $\epsilon \sim \mathcal{N}(0, \sigma^2)$
- Working with ‘minus log likelihood’ is more convenient

$$E(\mathbf{w}) = -\log \mathcal{L}(\mathbf{w}) = -\log \prod_i \frac{e^{-\frac{(y_i - \hat{y}_i)^2}{2\sigma^2}}}{\sigma\sqrt{2\pi}}$$

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} (-\log \mathcal{L}(\mathbf{w})) = \arg \min_{\mathbf{w}} \sum_i (y_i - \hat{y}_i)^2$$

- There are other error functions, e.g., absolute value of the errors, that can be used (and used in practice)
- One can also estimate regression parameters using Bayesian estimation

# Regression with multiple predictors

$$y_i = \underbrace{w_0 + w_1 x_{i,1} + w_2 x_{i,2} + \dots + w_k x_{i,k}}_{\hat{y}} + \epsilon_i = \mathbf{w} \mathbf{x}_i + \epsilon_i$$

$w_0$  is the intercept (as before).

$w_{1..k}$  are the coefficients of the respective predictors.

$\epsilon$  is the error term (residual).

- using the vector notation the equation becomes:

$$y_i = \mathbf{w} \mathbf{x}_i + \epsilon_i$$

where  $\mathbf{w} = (w_0, w_1, \dots, w_k)$  and  $\mathbf{x}_i = (1, x_{i,1}, \dots, x_{i,k})$

It is a generalization of simple regression with some additional power and complexity.

# Evaluating machine learning systems

- Any (machine learning) system needs a way to measure its success
- For measuring success (or failure) in a machine learning system we need quantitative measures
- Remember that we need to measure the success outside the training data

# Measuring success in Regression

- *Root-mean-square error* (RMSE)

$$\text{RMSE} = \sqrt{\frac{1}{n} \sum_i^n (y_i - \hat{y}_i)^2}$$

measures average error in the units compatible with the outcome variable.

- Another well-known measure is the *coefficient of determination*

$$R^2 = \frac{\sum_i^n (\hat{y}_i - \bar{y})^2}{\sum_i^n (y_i - \bar{y})^2} = 1 - \left( \frac{\text{RMSE}}{\sigma_y} \right)^2$$

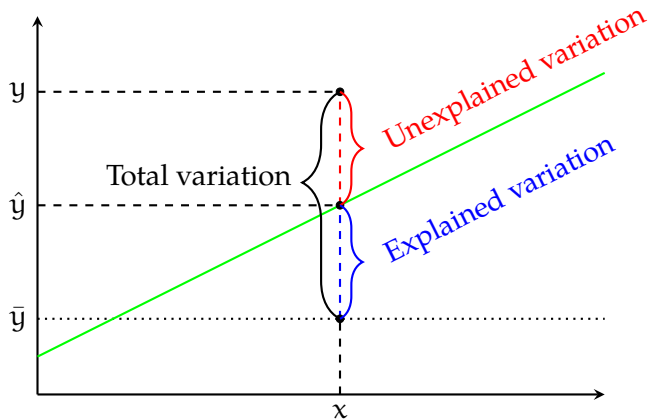
## Assessing the model fit: $R^2$

We can express the variation explained by a regression model as:

$$\frac{\text{Explained variation}}{\text{Total variation}} = \frac{\sum_i^n (\hat{y}_i - \bar{y})^2}{\sum_i^n (y_i - \bar{y})^2}$$

- In simple regression, it is the square of the correlation coefficient between the outcome and the predictor
- The range of  $R^2$  is  $[0, 1]$
- $100 \times R^2$  is interpreted as 'the percentage of variance explained by the model'
- $R^2$  shows how well the model fits to the data: closer the data points to the regression line, higher the value of  $R^2$

# Explained variation



$$\begin{aligned} \text{Total variation} &= \text{Unexplained variation} + \text{Explained variation} \\ y - \bar{y} &= y - \hat{y} + \hat{y} - \bar{y} \end{aligned}$$



## Dealing with non-linearity

- Least-squares estimation works because the regression equation is linear with respect to parameters  $\mathbf{w}$  (error function is quadratic)
- Introducing non-linear combinations of inputs does not affect the estimation procedure. The following are still linear models

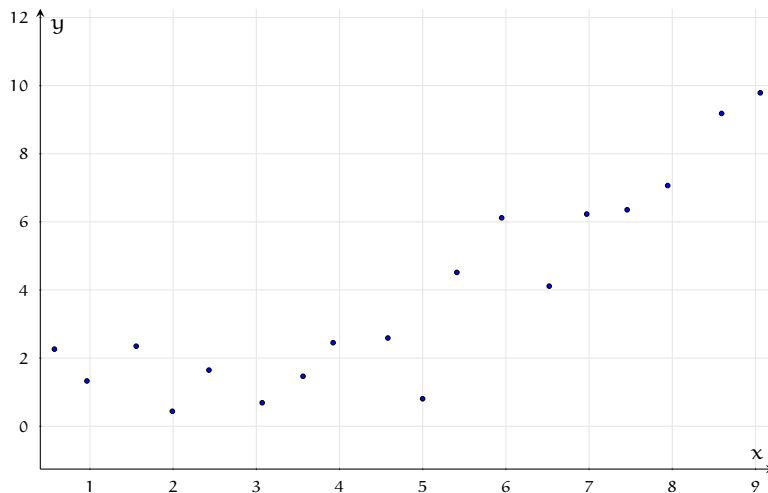
$$y = w_0 + w_1 x^2 + \epsilon$$

$$y = w_0 + w_1 \log(x) + \epsilon$$

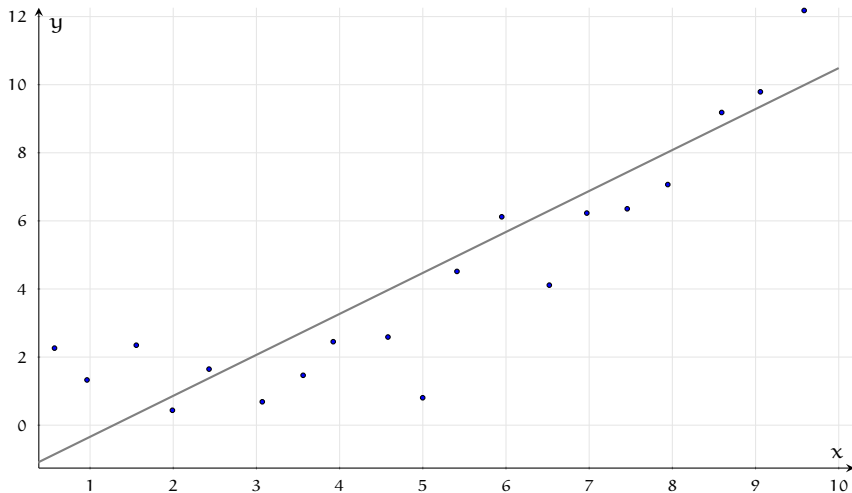
$$y = w_0 + w_1 x_1 + w_2 x_2 + w_3 x_1 x_2 + \epsilon$$

- In general, we can replace input  $x$  by a function of the input(s)  $\Phi(x)$ .  $\Phi()$  is called a *basis function*
- Basis functions allow linear models to model non-linear relations by *transforming* the input variables

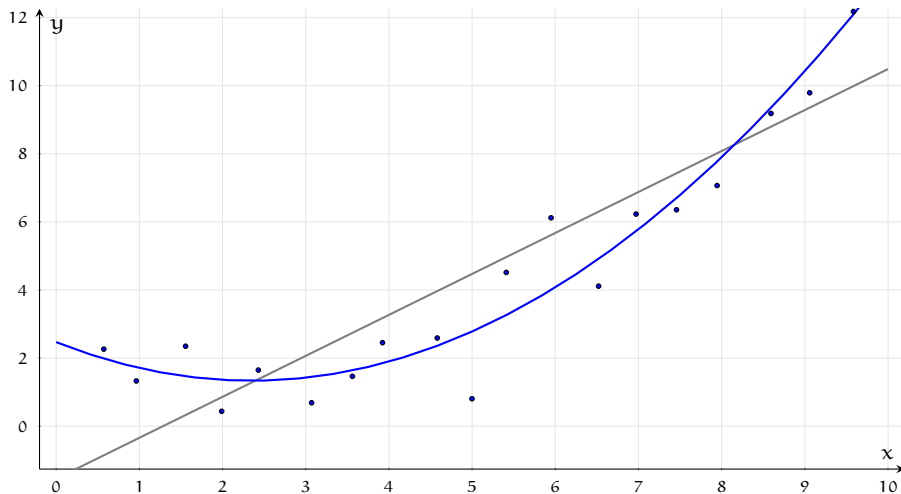
## Example: polynomial basis functions



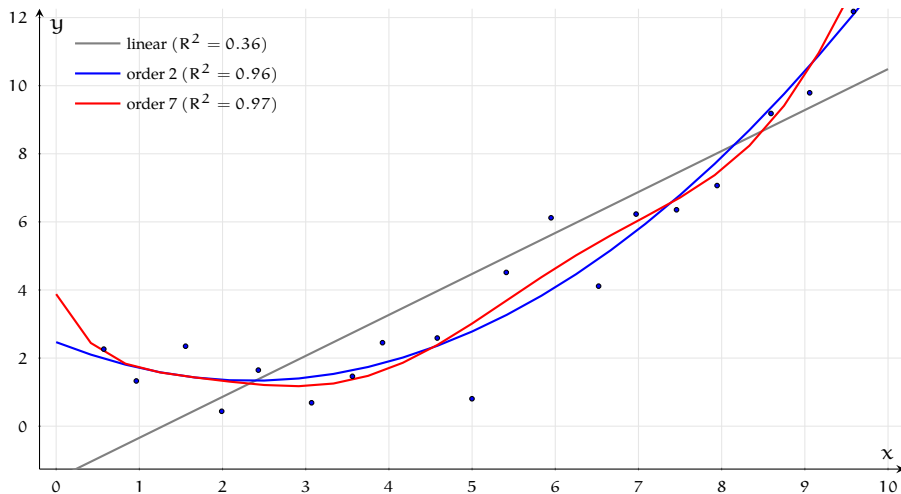
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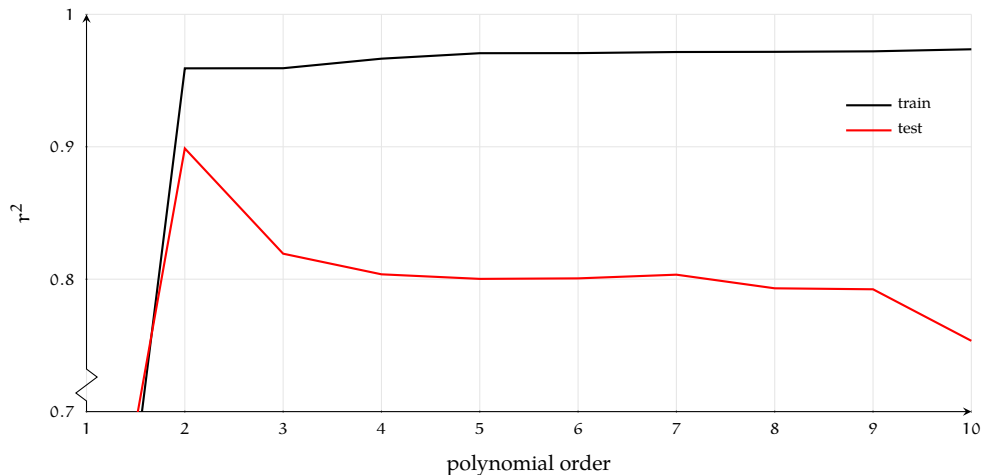


# Overfitting

- *Overfitting* is an important problem in ML, happens when the model learns peculiarities/noise in the training data
- An overfitted model will perform well on training data, but worse on new/unseen data
- Typically ‘more complex’ models are more likely to overfit

# Overfitting

demonstration through polynomial regression



# Preventing overfitting

- A straightforward approach is to choose a simpler model (family), e.g., by reducing the number of predictors
- More training data helps: it is less likely to overfit if number of training instances are (much) larger than the parameters
- There are other methods (one is coming on the next slide)
- We will return to this topic frequently during later lectures



# Regularized parameter estimation

- *Regularization* is a general method for avoiding overfitting
- The idea is to constrain the parameter values in addition to minimizing the training error
- For example, the regression estimation becomes:

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \sum_i (y_i - \hat{y}_i)^2$$

# Regularized parameter estimation

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$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \sum_i (\mathbf{y}_i - \hat{\mathbf{y}}_i)^2 + \lambda \sum_{j=1}^k w_j^2$$

- The new part is called the regularization term,
- $\lambda$  is a *hyperparameter* that determines the strength of the regularization
- In effect, we are preferring small values for the coefficients
- Note that we do not include  $w_0$  in the regularization term

## L2 regularization

The form of regularization, where we minimize the regularized cost function,

$$J(\mathbf{w}) + \lambda \|\mathbf{w}\|_2$$

is called L2 regularization.

- Note that we are minimizing the L2-norm of the weight vector
- In statistic literature L2-regularized regression is called *ridge regression*
- The method is general: it can be applied to other ML methods as well
- The choice of  $\lambda$  is important
- Note that the scale of the input also becomes important

# L1 regularization

In L1 regularization we minimize

$$J(\mathbf{w}) + \lambda \sum_{j=1}^k |w_j|$$

- The additional term is the L1-norm of the weight vector (excluding  $w_0$ )
- In statistics literature the L1-regularized regression is called *lasso*
- The main difference from L2 regularization is that L1 regularization forces some values to be 0 – the resulting model is said to be ‘sparse’

# Regularization as constrained optimization

L1 and L2 regularization can be viewed as minimization with constraints

L2 regularization

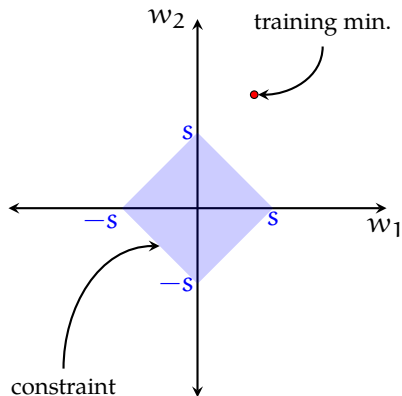
Minimize  $J(\mathbf{w})$  with constraint  $\|\mathbf{w}\| < s$

L1 regularization

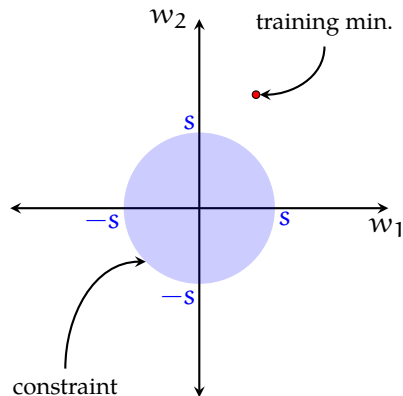
Minimize  $J(\mathbf{w})$  with constraint  $\|\mathbf{w}\|_1 < s$

# Visualization of regularization constraints

## L1 regularization

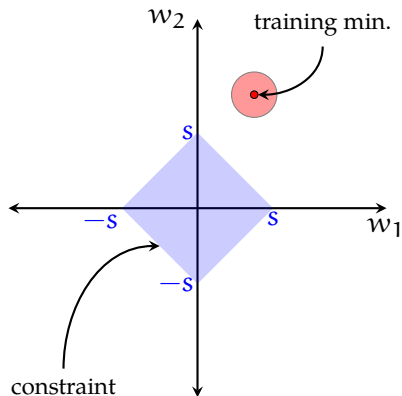


## L2 regularization

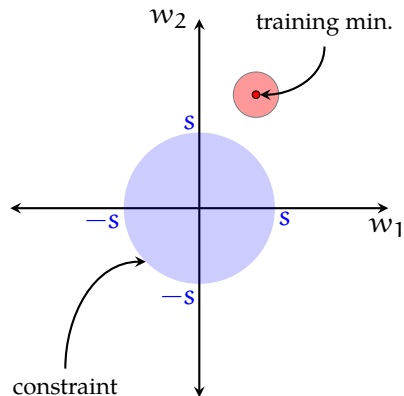


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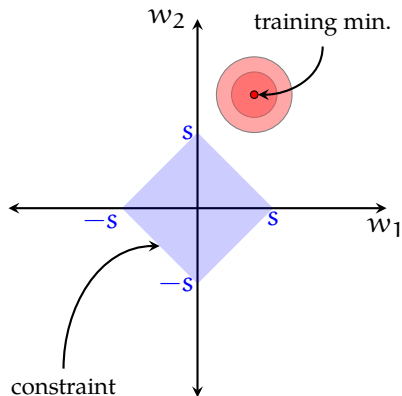


## L2 regularization

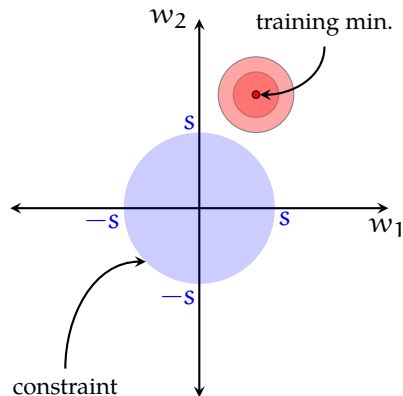


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## L1 regularization



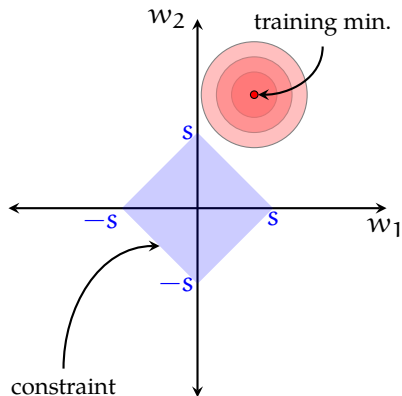
## L2 regularization



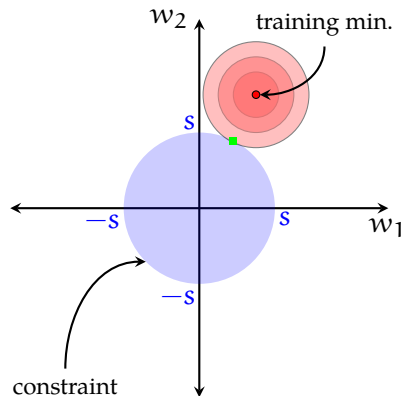


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## L1 regularization

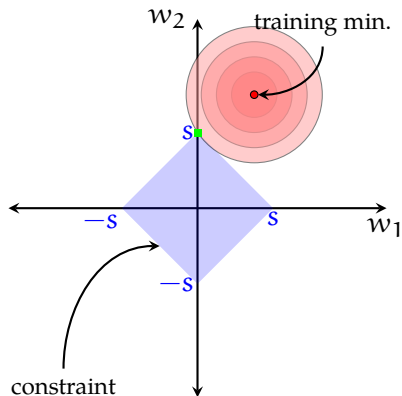


## L2 regularization

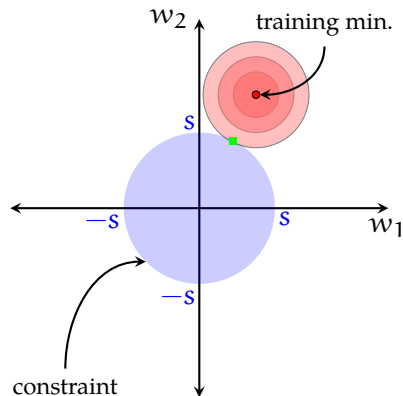


# Visualization of regularization constraints

## L1 regularization



## L2 regularization



# Regularization: some remarks

- Regularization prevents overfitting
- The *hyperparameter*  $\lambda$  needs to be determined
  - best value is found typically using a *grid search*, or a *random search*
  - it is tuned on an additional partition of the data, *development set*
  - **development set cannot overlap with training or test set**
- The regularization terms can be interpreted as *priors* in a Bayesian setting
- Particularly, L2 regularization is equivalent to a normal prior with zero mean

# Gradient descent for parameter estimation

- In many ML problems, we do not have a closed form solution for finding the minimum of the error function
- In these cases, we use a search strategy
- *Gradient descent* is a search method for finding a minimum of a (error) function
- The general idea is to approach a minimum of the error function in small steps

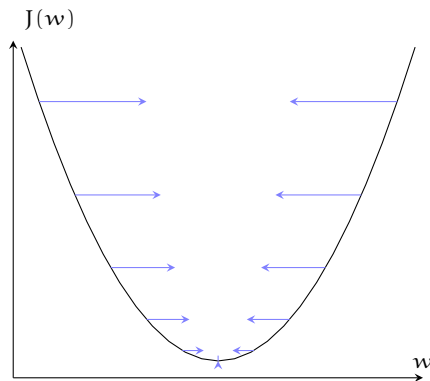
$$\mathbf{w} \leftarrow \mathbf{w} - \eta \nabla J(\mathbf{w})$$

$\nabla J$  is the gradient of the loss function, it points to the direction of the maximum increase

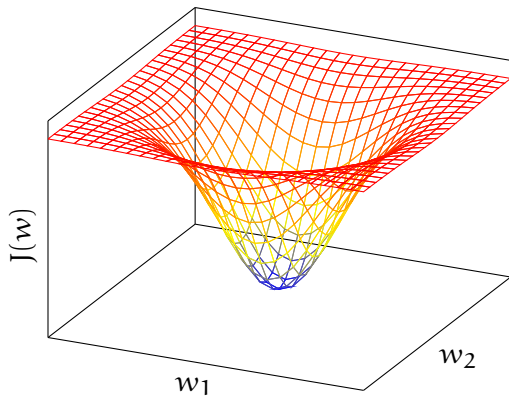
$\eta$  is the learning rate

# Gradient descent with single parameter

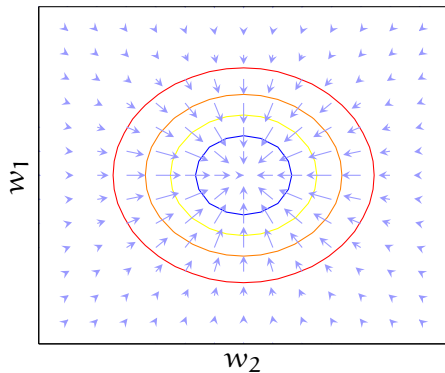
- For a single parameter, gradient is a one-dimensional vector
- The direction of gradient is towards the maximum increase
- We take steps proportional to  $-\nabla J(w)$
- Steeper the curve, the larger the parameter update



# Gradient descent with single parameter



Objective function



Negative gradients

## Categorical predictors

- Categorical predictors are represented as multiple binary coded input variables
- For a binary predictor, we use a single binary input. For example, (1 for one of the values, and 0 for the other)

$$x = \begin{cases} 0 & \text{for male} \\ 1 & \text{for female} \end{cases}$$

- For a categorical predictor with k values, we use one-hot encoding (other coding schemes are possible)

$$x = \begin{cases} (0, 0, 1) & \text{neutral} \\ (0, 1, 0) & \text{negative} \\ (1, 0, 0) & \text{positive} \end{cases}$$

# Summary

What to remember:

- Supervised vs. unsupervised learning
- Regression vs. classification
- Linear regression equation
- Least-square estimate
- MSE,  $R^2$
- non-linearity & basis functions
- L1 & L2 regularization (lasso and ridge)

Next:

Wed classification

Fri first lab session

Mon classification



## Additional reading, references, credits

- Hastie, Tibshirani, and Friedman (2009) discuss introductory bits in chapter 1, and regression on chapter 3 (sections 3.2 and 3.4 are most relevant to this lecture)
- Jurafsky and Martin (2009) has a short section (6.6.1) on regression
- You can also consult any machine learning book (including the ones listed below)



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# A hands-on exercise

Draw a regression line over the plot

