

# PATH FINDING AND GRAPH TRAVERSAL

## PATH FINDING AND GRAPH TRAVERSAL

- **Path finding** refers to determining the shortest path between two vertices in a graph.
- We discussed the Floyd–Warshall algorithm previously, but you may achieve similar results with the Dijkstra or Bellman-Ford algorithms.
- **Graph traversal** refers to the problem of visiting a set of nodes in a graph in a certain way.
- You can use depth- or breadth-first search algorithms to traverse an entire graph starting from a given "root" (source vertex).

## PATH FINDING AND GRAPH TRAVERSAL

- Perhaps more useful to you are methods for finding traversable paths between multiple points.
- You have probably looked for such algorithms already. Today we will discuss one possible approach, namely the **A\* (A star) search algorithm**.
- Key idea: Find the least-cost path from a source to one destination, out of one or more possible ones.
- Effectively builds a tree of partial paths, whose leaves are stored in a priority queue.
- Vertices are ordered in the queue according to a cost that consists of the distance travelled from source and an estimate of the distance to a goal (destination).

## A\* SEARCH

- Formally, the cost function for a vertex  $n$  is expressed as:

$$f(n) = g(n) + h(n).$$

- $g(n)$  is the cost of getting from the source to  $n$  and is tracked by the algorithm
- $h(n)$  is a heuristic that estimates the cost from  $n$  to any possible goal.
- $h(n)$  must be admissible, that is it should never overestimate the cost of reaching a goal (destination).
- One possibility is to compute  $h(n)$  as the shortest distance between any two vertices.

# A\* SEARCH

## Operation:

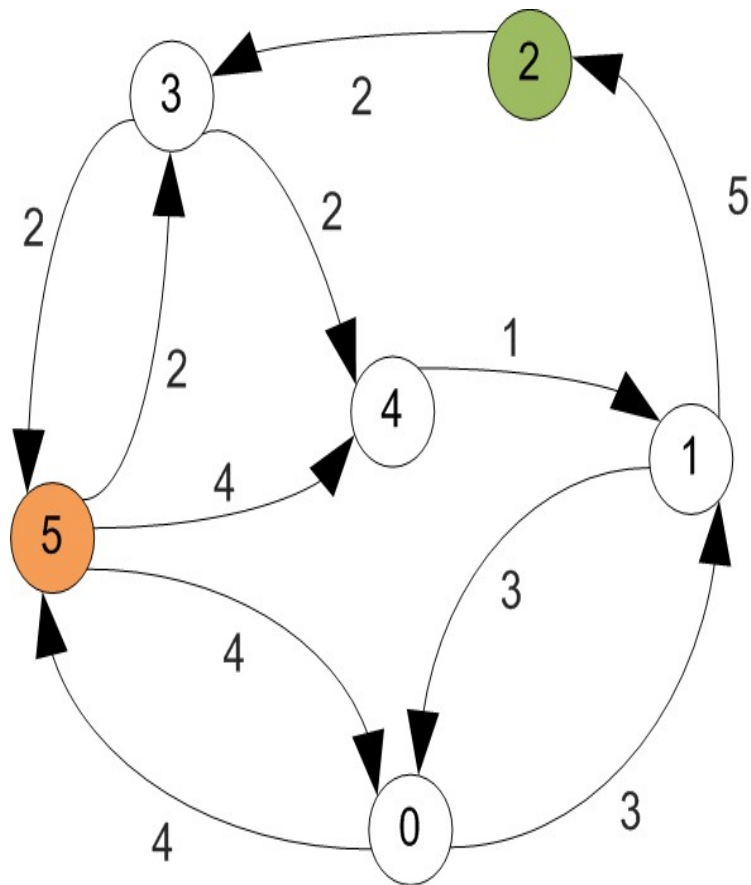
- First search routes most likely to lead to destination.
- This goes beyond best-first search, as it also considers the distance travelled so far.
- Maintain a priority queue of traversed vertices (open set/fringe). Low  $f(n)$  corresponds to high priority.
- At each step, remove node with lowest  $f$  from queue, update the  $f$  (and  $g$ ) values of their neighbours, and add neighbours to the queue.
- Stop when a goal node has a value  $f$  lower than any other nodes in the queue, or queue is empty.

## A\* SEARCH

Important remarks:

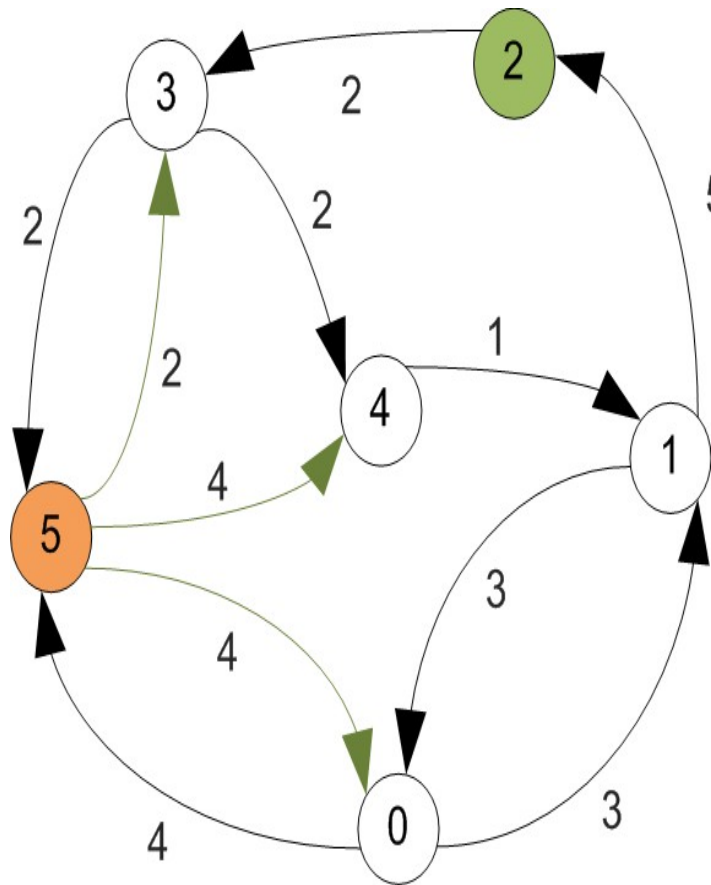
- Remember to set  $g(n) = 0$  when  $n$  is a goal.
- To reconstruct the path, each node must keep track of its predecessor.
- You may want to perform some pre-processing on the graph at the start of the simulation (e.g. build the equivalent complete graph), to improve efficiency.

## EXAMPLE



$$5, f = g + h = 0 + 1 = 1$$

# EXAMPLE

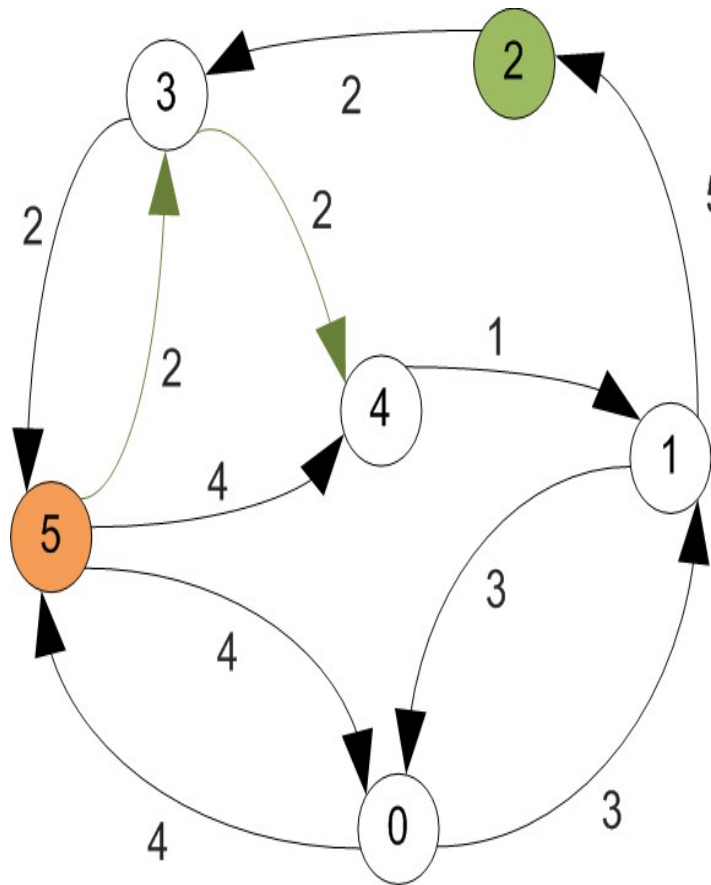


$$5, f = g + h = \mathbf{0} + 1 = 1$$

$$5 - 0, f = (0 + 4) + 1 = 5 \quad 5 - 3, f = (0 + 2) + 1 = 3 \quad 5 - 4, f = (0 + 4) + 1 = 5$$

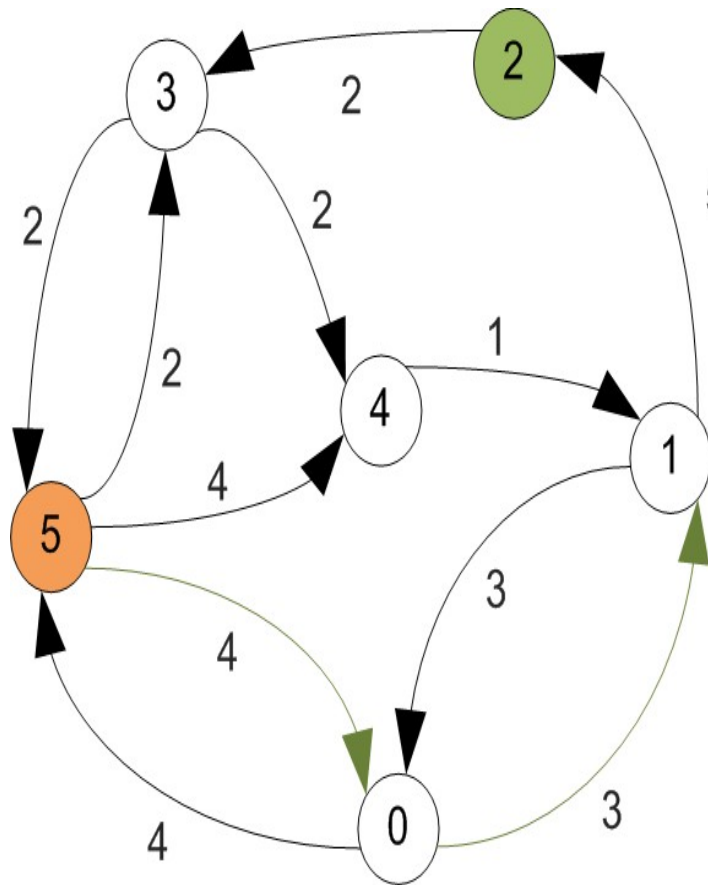


# EXAMPLE



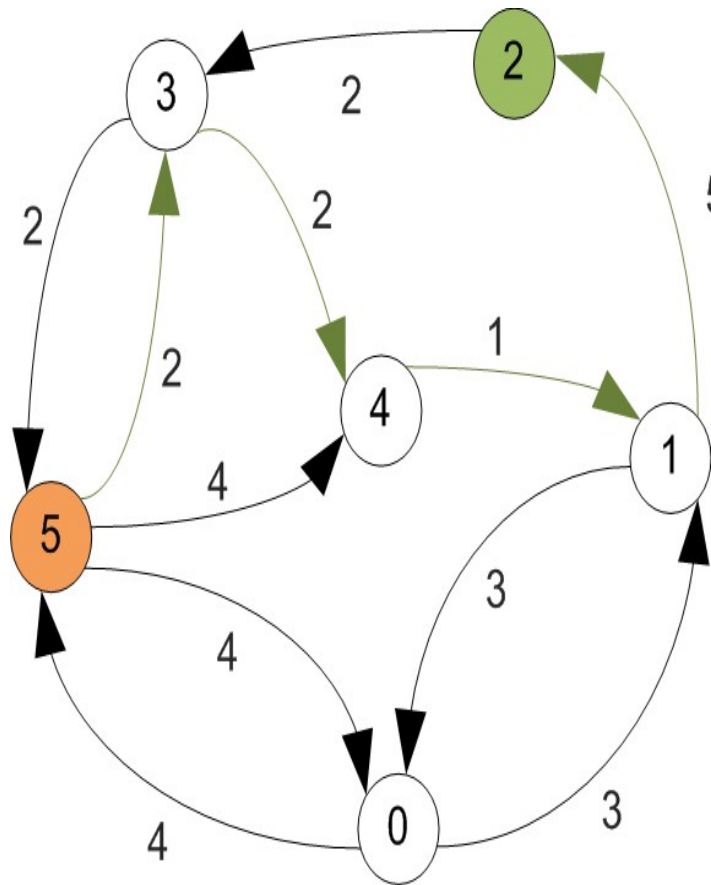
$$\begin{array}{c}
 5, f = g+h = \mathbf{0}+1 = 1 \\
 \swarrow \quad \downarrow \quad \searrow \\
 5-0, f = (0+4)+1 = 5 \quad 5-3, f = (\mathbf{0}+\mathbf{2})+1 = 3 \quad 5-4, f = (0+4)+1 = 5 \\
 \quad \quad \quad \downarrow \\
 5-\mathbf{3}-\mathbf{4}, f = (2+2)+1 = 5
 \end{array}$$

# EXAMPLE



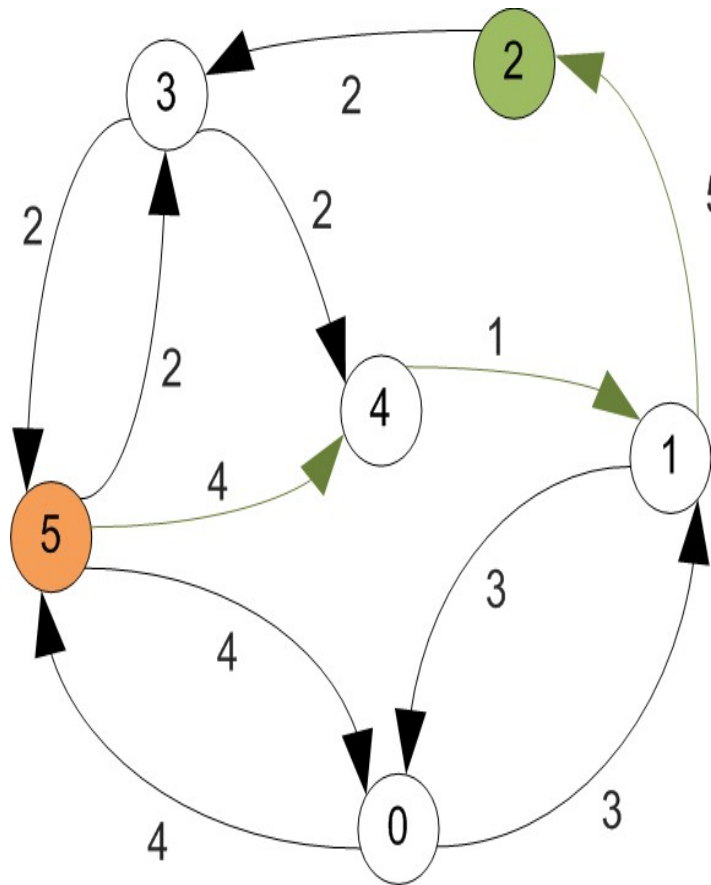
$$\begin{array}{l}
 5, f = g+h = 0+1 = 1 \\
 \hline
 5-0, f = (0+4)+1 = 5 \quad 5-3, f = (0+2)+1 = 3 \quad 5-4, f = (0+4)+1 = 5 \\
 \text{(alphabetical tie break)} \\
 \hline
 5-3-4, f = (2+2)+1 = 5 \\
 \hline
 5-0-1, f = (4+3)+1 = 8
 \end{array}$$

# EXAMPLE



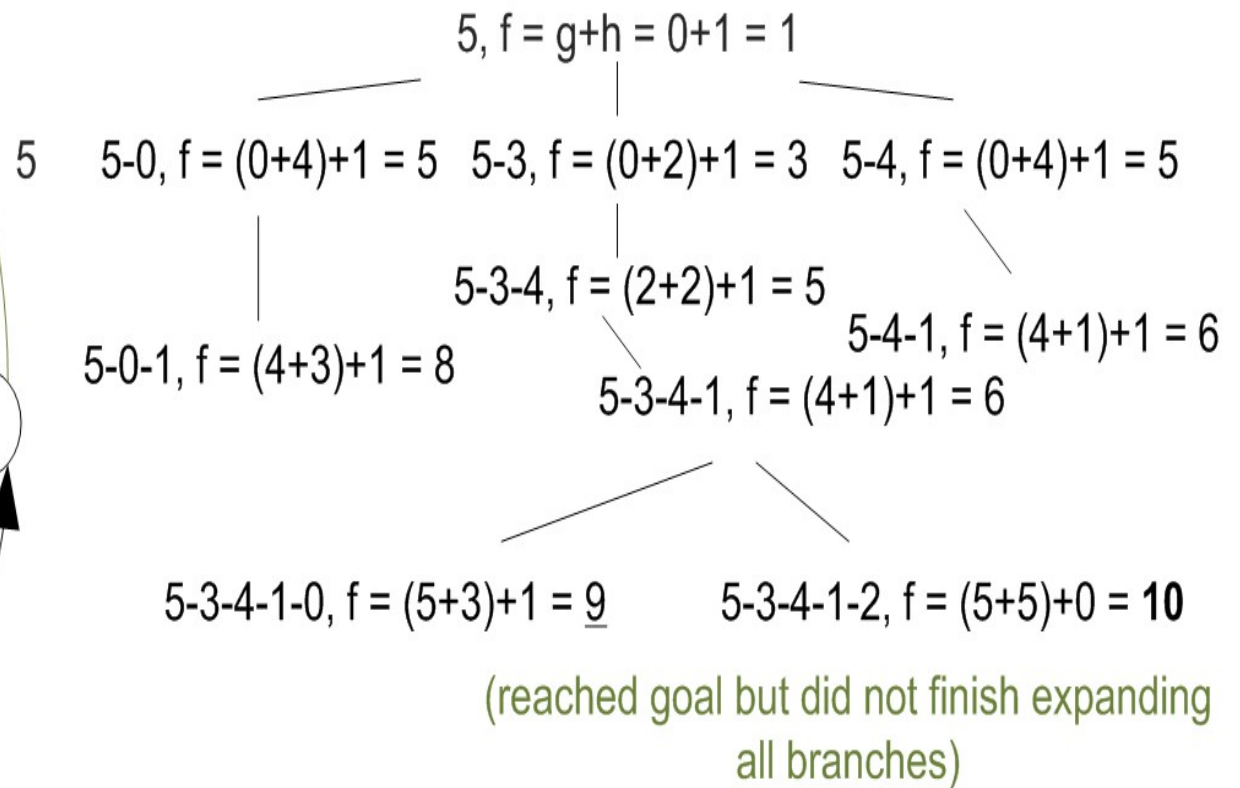
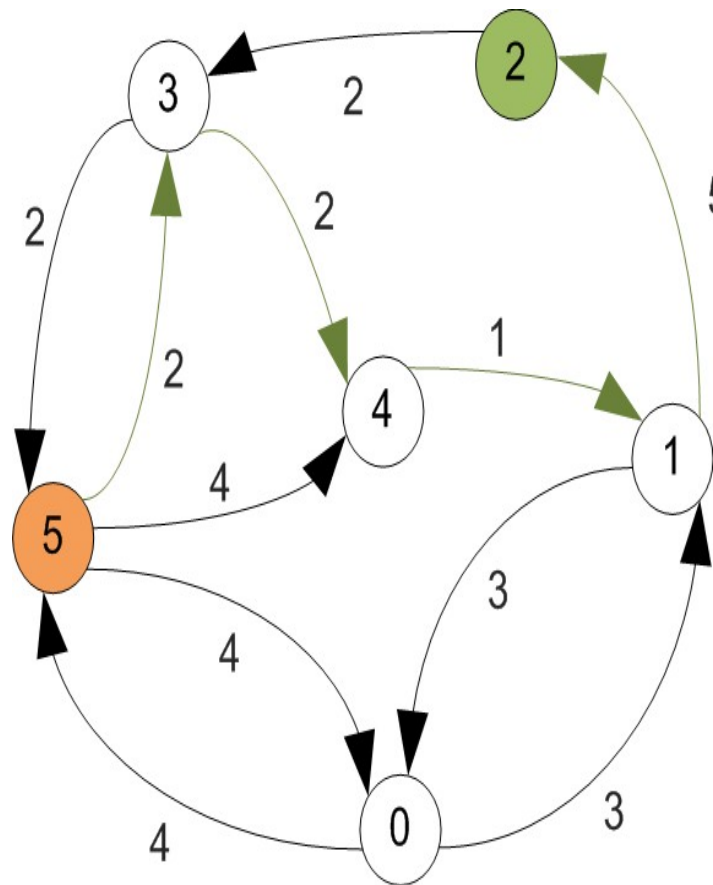
$$\begin{array}{c}
 5, f = g+h = 0+1 = 1 \\
 \swarrow \quad \downarrow \quad \searrow \\
 5-0, f = (0+4)+1 = 5 \quad 5-3, f = (0+2)+1 = 3 \quad 5-4, f = (0+4)+1 = 5 \\
 \downarrow \quad \quad \downarrow \\
 5-0-1, f = (4+3)+1 = 8 \quad 5-3-4, f = (2+2)+1 = 5 \\
 \quad \quad \quad \downarrow \\
 \quad \quad \quad 5-3-4-1, f = (4+1)+1 = 6
 \end{array}$$

# EXAMPLE

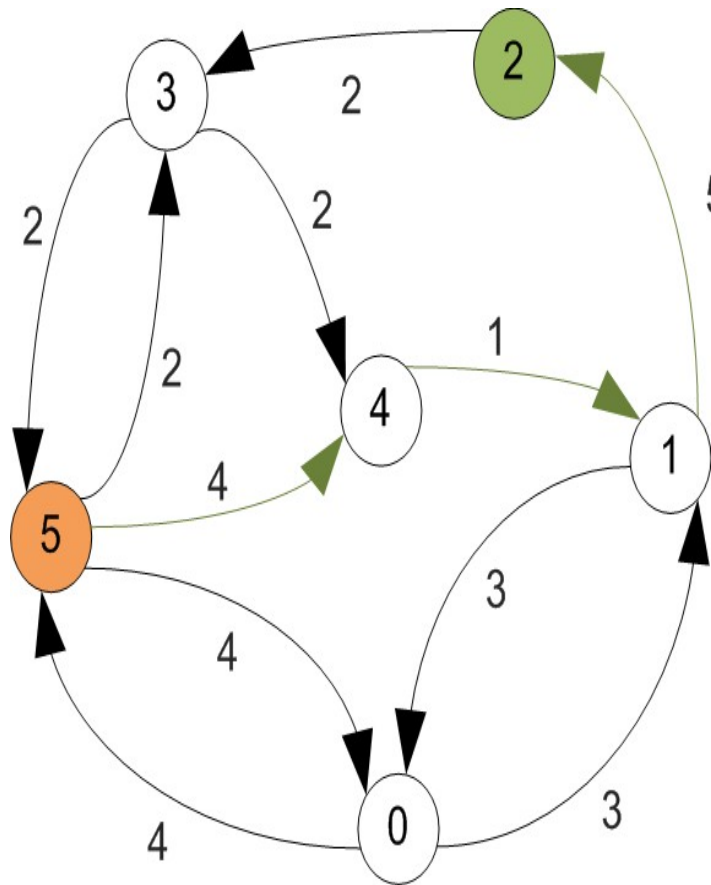


$$\begin{array}{rcl}
 & 5, f = g+h = 0+1 = 1 & \\
 & | & \\
 5-0, f = (0+4)+1 = 5 & 5-3, f = (0+2)+1 = 3 & 5-4, f = (0+4)+1 = 5 \\
 & | & | \\
 & 5-3-4, f = (2+2)+1 = 5 & 5-4-1, f = (4+1)+1 = \underline{6} \\
 & | & | \\
 5-0-1, f = (4+3)+1 = 8 & 5-3-4-1, f = (4+1)+1 = 6 & 
 \end{array}$$

# EXAMPLE

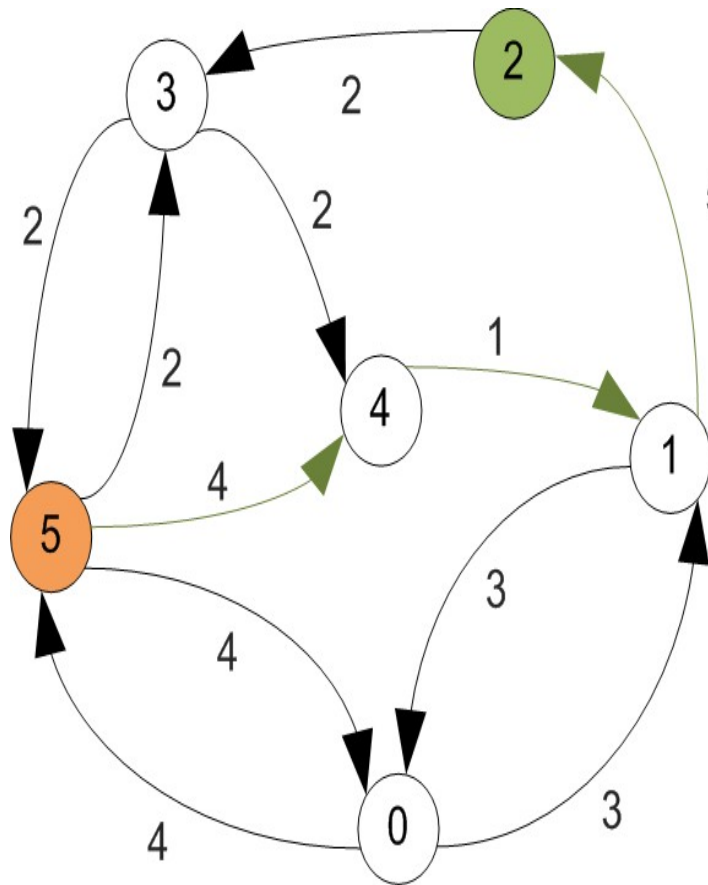


# EXAMPLE



$$\begin{array}{rcl}
 & 5, f = g+h = 0+1 = 1 & \\
 & \swarrow \quad \downarrow \quad \searrow & \\
 5-0, f = (0+4)+1 = 5 & 5-3, f = (0+2)+1 = 3 & 5-4, f = (0+4)+1 = 5 \\
 \downarrow & \downarrow & \swarrow \quad \searrow \\
 5-0-1, f = (4+3)+1 = 8 & 5-3-4, f = (2+2)+1 = 5 & 5-4-1, f = (4+1)+1 = 6 \\
 & \swarrow \quad \searrow & \swarrow \quad \searrow \\
 & 5-3-4-1, f = (4+1)+1 = 6 & 5-4-1-2, f = (5+5)+0 = 10 \\
 & \swarrow \quad \searrow & \\
 5-3-4-1-0, f = (5+3)+1 = 9 & & 5-3-4-1-2, f = (5+5)+0 = 10
 \end{array}$$

## EXAMPLE



$$\begin{array}{l}
 5, f = g+h = 0+1 = 1 \\
 \begin{array}{l}
 5-0, f = (0+4)+1 = 5 \quad 5-3, f = (0+2)+1 = 3 \quad 5-4, f = (0+4)+1 = 5 \\
 \begin{array}{l}
 5-3-4, f = (2+2)+1 = 5 \quad 5-4-1, f = (4+1)+1 = 6 \\
 5-0-1, f = (4+3)+1 = 8 \quad 5-3-4-1, f = (4+1)+1 = 6 \\
 5-0-1-2, f = (7+5)+0 = 12 \quad \mathbf{5-4-1-2, f = (5+5)+0 = 10} \\
 5-3-4-1-0, f = (5+3)+1 = 9 \quad 5-3-4-1-2, f = (5+5)+0 = 10
 \end{array}
 \end{array}
 \end{array}$$

(reached goal, but at higher cost; further expanding would return to already visited nodes)

## A\* SEARCH

Optimising the execution time is possible by working with a so called *closed list*

- Start with an empty list.
- Add the nodes that have been expanded to the closed list.
- Do not explore other branches of a node that is already in the closed list.



# PSEUDO-CODE

```
create closed list; initialise empty
create open list of vertices we currently work on; initialise with source

while (goal not reached) {
    consider best node in open list (lowest f value)
    if (goal reached) {
        done, return;
    } else {
        move current node to closed list and examine all its neighbours
        for (each neighbour) {
            if (in closed list current g value is lower) {
                update neighbour with the new, lower, g value
                change neighbour's parent to current node
            } else if (neighbour in open list and current g value is lower) {
                update neighbour with the new, lower, g value
                change neighbour's parent to current node
            } else { // neighbour in neither open or closed list
                add neighbour to open list and set its g value
            }
        }
    }
}
```

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# REVIEW OF PART 1

## SUBMISSIONS

- 36 out of 82 students submitted at least something.
- That's 44% submission rate –was expecting something slightly above 50%.
- Many of you did not ask any explicit questions nor highlighted any aspects or which you wanted feedback.
- A couple of submissions did not compile!

## MULTIPLE FILES

- There seems to be a preference for using a relatively large number of files, given the small size of this project.
- There is nothing wrong with that, but pay attention to memory management.
- Using more/less files will not be penalised – just explain why you chose to implement things in a certain way.
- If refactoring is a reason, do emphasize that.

## THE READMEs

- Ranged from very basic ones, containing a couple of lines, to very detailed ones.
- Most of them explained how to build and execute the simulator, which is good. For Part 2 submit a makefile.
- Some acknowledged the limitations of the code and problems known at the time of submission.
- Some did not state explicitly at which stage of the development they were.
- Some did not submit a README – you will be losing points if this happens for Part 2.

## RANDOM GOODNESS

- *“I was pushing the submission to the last possible moment, in (vain) hope that I will be able to debug the program.”*

## RANDOM NOT-SO-GOODNESS

- Low-level coding decisions:
  - Prone to change and you *will* forget to update the README
  - Should be in comments in the source code file concerned – some code lacked commenting altogether.
- High-level structure: you are more likely to remember to change the README in case of a major re-structuring.

## RANDOM NOT-SO-GOODNESS

- Make sure you read carefully the requirements
  - On one occasion the first command line parameter was not the input script, but a keyword that introduced the input script.
  - Although working to some extent, some did not implement any command line parsing at all.
  - One submission was prompting the user for input after the execution started – remember that your code will be automatically tested.



# REFACTORING

- Only a small number of READMEs contained mentions of refactoring,
- Both with reference to future refactoring:
  - Either promising to refactor later **or**
  - Done a good bit of refactoring already, but planning to do more.
- It was still early days; however, refactoring is something you should be *trying* to do constantly.

## INVALID INPUT

- Try to think of exceptions which you really do not believe can happen under normal executing conditions.
- The user may simply make some typing errors when producing the input.
- Some parameters may have been given in an order different than the expected one.
- When is this a serious problem?
- Distinguish between warnings/errors where possible.

## INVALID INPUT

- What should you do if you discover you have incomplete information during simulation run?
- For example, you attempt to retrieve the `noBuses` and find that this was not given.
- This is not problematic for parsing, because the user may have simply forgotten to specify the fleet size.
- However, if you validate the input before running the simulation, then it really becomes a problem to find you have no buses to schedule during the simulation.
- The simulation should not have been started since the validation should have uncovered the error.

## FURTHER CHECKS

- Check the sign of numbers.
- Check whether it is indeed numbers you find when numbers are expected.
- Check if a number has the type you expect (integer/real).
- Be careful with hours/minutes/seconds conversions.

## INPUT SCRIPTS

- You have not spend much time authoring input scripts.
- I recently made some examples available, but it is essential that you produce your own test scripts.
- Network size is not the only thing that matters.
- Think of scenarios where e.g. route planning algorithms may have a hard time.

# FINALADVICE

## FINALADVICE (I)

- I said this already, but read the handout carefully again
- Submit a README file and explain your design choices and main building blocks therein, as well as any known bugs, limitations, and requirements not implemented or additional features implemented.
- Include a Makefile. Running 'make' in the *root directory of your project* should be enough to build an executable.
- Make sure you expect an input script as a command line parameter and check that the one specified by the user actually exists.

## FINALADVICE (II)

- Do not prompt the user for input.
- Implement a parser. If you do not manage to get this working, not much can be tested.
- Conform to the output specification (remember the automated testing).
- Build a set of tests and submit them as evidence of testing. Explain briefly what you tested for with each.
- Comment your code, though not excessively.
- Clean up your code, have consistent spacing, remove commented out blocks.



## IN SUMMARY...

- Strive at least for a half decent simulator.
- Make sure it compiles and runs on DiCE, and it does not require super-user privileges!
- As a backup plan, have at least a planning algorithm that works in a taxi fashion (one bus allocated to each request, if possible).
- There is no minimum page requirement for the report: "Demonstrate you are familiar with discrete-event stochastic simulations, you can interpret the output, understand the system's performance and you can present your results in a clear and concise manner."