

XGBoost

$V_1(x) = \text{WP}$ if you have 1st and 10
at game-state x

dataset i index of the i^{th} play
 x_i game-state of the i^{th} play
 y_i 1/0 win/loss corresponding to i^{th} play

learn relationship b/t y and x
using Machine Learning.

- decision trees \rightarrow overfit
 - random forests \rightarrow reduces overfitting by reducing variance
- We can do better.
- boosting \rightarrow also Reduces bias

Bias-Variance Tradeoff;

$$\text{out-of-sample prediction error} = \underbrace{\text{bias}}_{\substack{\text{the model} \\ \text{actually being} \\ \text{WRONG}}} + \underbrace{\text{variance}}_{\substack{\text{noise coming} \\ \text{from randomness} \\ \text{in the training set}}} + \underbrace{\text{irreducible error}}_{\substack{\text{fundamental} \\ \text{difficulty of} \\ \text{the problem}}}$$

Random Forests reduce Variance
 boosting reduces bias and variance

Boosting — train multiple models (e.g. decision trees) sequentially, train each successive model to optimize some loss function to improve the accuracy of the overall system.

Tree Boosting in a nutshell

dataset $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$

n training examples $n = |\mathcal{D}|$

m features (columns) $x_i \in \mathbb{R}^m$

outcome

$y_i \in \mathbb{R}$

$$\hat{y}_i = \mathcal{D}(x_i) = \sum_{k=1}^K f_k(x_i)$$

f_k decision tree

To learn the set of functions (trees) $\{f_k\}$ used in this model, we minimize a regularized objective function,

$$\mathcal{L}(\emptyset) = \sum_i l(y_i, \hat{y}_i) + \sum_k \Omega(f_k)$$

where $\Omega(f) = \gamma \cdot T + \frac{1}{2} \lambda \cdot \sum_j w_{jk}^2$

$y_i \in \{1, 0\}$ binary: $l(y_i, \hat{y}_i) = \text{log loss}$

$y_i \in \mathbb{R}$ continuous: $l(y_i, \hat{y}_i) = \begin{aligned} &= y_i \log \hat{y}_i + (1-y_i) \log (1-\hat{y}_i) \\ &= \text{squared error} \\ &= (y_i - \hat{y}_i)^2 \end{aligned}$

Regularization: $\Omega(f_k) = \text{regularization term on the decision tree } f_k$

$T = \# \text{ of leaves}$

$w_{jk} = \text{weight value of tree } k \text{ leaf } j$

→ making # leaves smaller and weights smaller

$$\Omega(f_k) = \gamma \cdot T_k + \frac{1}{2} \lambda \cdot \sum_j w_{jk}^2$$

$$\emptyset = \sum_k f_k = \underset{\emptyset}{\operatorname{argmin}} \quad \mathcal{L}(\emptyset)$$

$$\mathcal{L}(\emptyset) = \sum_i l(y_i, \hat{y}_i) + \sum_k \Omega(f_k)$$

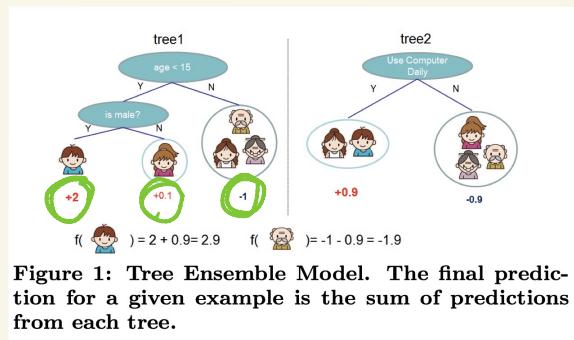


Figure 1: Tree Ensemble Model. The final prediction for a given example is the sum of predictions from each tree.

Ridge Regression $\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^n (y_i - x_i^\top \beta)^2 + \lambda \sum_j \beta_j^2$

$\underbrace{\sum_{i=1}^n (y_i - x_i^\top \beta)^2}_{\text{Squared error}}$ $\underbrace{\lambda \sum_j \beta_j^2}_{\text{Regularized term}}$

We wrote down a loss function

$L(\emptyset) = L\left(\sum_k f_k\right)$ that we want to minimize in order to train our decision trees $\{f_k\}$. But how can we actually

Minimize this?

$$L(\emptyset) = \sum_i l(y_i, \hat{y}_i) + \sum_k \Omega(f_k)$$

→ minimize in a sequential manner.

At iteration t , $\hat{y}_i^{(t)}$ prediction of i^{th} datapoint.
To fit the decision tree f_t at the t^{th} iteration,
lets use a modified version of L ,

$$L^{(t)}(f_t) = \sum_{i=1}^n l(y_i, \hat{y}_i^{(t-1)} + f_t(x_i)) + \Omega(f_t).$$

Assume we've already fit $t-1$ decision trees.
Then we have a prediction $\hat{y}_i^{(t-1)}$ from the
aggregation of these $t-1$ decision trees.

Then the t^{th} aggregation looks like $\hat{y}_i^{(t-1)} + f_t(x_i)$.

Recall $\sum_{k=1}^t f_k = \left(\sum_{k=1}^{t-1} f_k \right) + f_t$.

Boosting = sequential optimization.

$$f_t = \underset{f_t}{\operatorname{argmin}} L^{(t)}(f_t)$$

How to actually minimize $L^{(t)}$?

Consider many decision trees f_t and simply select the one which minimizes $L^{(t)}$.

Ben Baldwin

$$V_1(x) = \hat{WP}(x) \text{ 1st down and } 10$$

x = yardline, score diff, timeouts,

game sec. rem., point spread, Receive 2nd half kickoff.

y_i = index i^{th} play

$y_i = 1/0$ if team with

win the game possession on play i

x_i = game-state on play i

$$\hat{WP}_1 = X \text{GBBoost}(y, x)$$

P_{FG} , $P_{\text{conversion}}$, \mathbb{E} next yardline after punting, \hat{WP}_1

$$\rightarrow V_{GO}(x), V_{FG}(x), V_{\text{punt}}(x)$$

Choose the decision which maximizes estimated value (w/ probability),

$$\operatorname{Argmax}_{d \in \{\text{Gro}, \text{Fg}, \text{Aunt}\}} V_d(x).$$

Up 3, 4th & 1, 14 yards from opponent end zone
Qtr 2, 03:58 | Timeouts: Off 0, Def 3

	Win %	Success % ¹	Fail	Succeed	Win % if
Go for it	72	68	64	76	
Field goal attempt	68	94	62	69	

¹ Likelihood of converting on 4th down or of making field goal
Source: @ben_bot_baldwin

4th down decision bot @ben_bot_baldwin · Jan 29
• Automated
----> CIN (3) @ KC (6) <---
KC has 4th & 1 at the CIN 14

Recommendation (STRONG): ⚪ Go for it (+3.8 WP)
Actual play: ⚪ (Shotgun) P.Mahomes pass short right to T.Kelce for 14 yards, TOUCHDOWN. H.Butker extra point is GOO

(a)

(b)

Figure 6: Baldwin's decision making for example play 1.

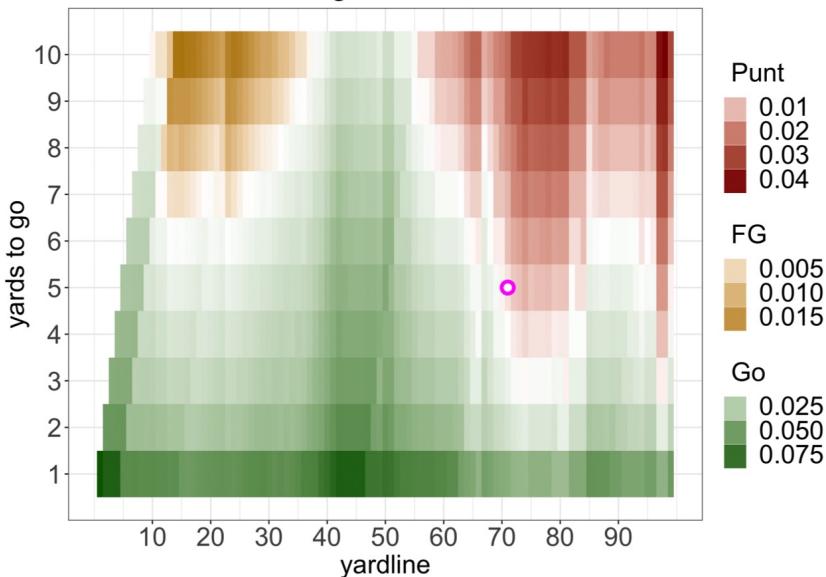
$$\text{gain} = \frac{\text{Value of Best}}{\text{Value of 2nd best}}$$

Up 1, 4th & 5, 71 yards from opponent endzone

Qtr 3, 5:53 | Timeouts: Off 3, Def 3 | Point Spread: 3

decision	WP	success prob	WP if fail	WP if succeed	baseline coach %
Punt	0.440				0.934
Go for it	0.436		0.426	0.345	0.066
Field goal	0.345		0.000	0.345	0.000

win probability added by
making that decision



Commodores
have the
ball against
the Colts
in week
8 of 2022

What if the model Sucks?

Can we measure our confidence in the
Model's estimates?