view_frames Result Recorded at time: 1604356983.927 t265_odom_frame Broadcaster: /t265/realsense2_camera_manager Average rate: 199.785 Hz Most recent transform: 1604356983.924 (0.002 sec old) Buffer length: 4.975 sec t265_pose_frame Broadcaster: /t265_node_to_model Broadcaster: /t265/realsense2_camera_manager Average rate: 10.192 Hz Average rate: 10000.000 Hz Most recent transform: 1604356983.928 (-0.001 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 4.808 sec Buffer length: 0.000 sec t265_link t265_pose_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 0.000 sec sensor_t265 Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec fisheye1 fisheye2 body Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10000.000 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Average rate: 10.204 Hz Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 1604356983.847 (0.079 sec old) | Most recent transform: 1604356983.847 (0.079 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 1604356983.847 (0.079 sec old) \ Most recent transform: 1604356983.847 (0.079 sec old) \ \ Most recent transform: 1604356983.847 (0.079 sec old) Most recent transform: 1604356983.847 (0.079 sec old) Buffer length: 4.900 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.900 sec left_wheel_1 left_wheel_2 left_wheel_3 right_wheel_1 right_wheel_2 right_wheel_3 base_link camera_bottom_screw_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 0.000 sec camera_link Broadcaster: /model_to_d435_node Average rate: 10.194 Hz Most recent transform: 1604356983.936 (-0.009 sec old) Buffer length: 4.807 sec d400_link Broadcaster: /d400/realsense2_camera_manager Broadcaster: /d400/realsense2_camera_manager Broadcaster: /d400/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec d400_depth_frame d400_color_frame d400_aligned_depth_to_color_frame Broadcaster: /d400/realsense2_camera_manager Broadcaster: /d400/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1604356983.927 sec old) Most recent transform: 0.000 (1604356983.927 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec d400_depth_optical_frame d400_color_optical_frame