DEEP LEARNING BASED CANCER METASTASES DETECTION

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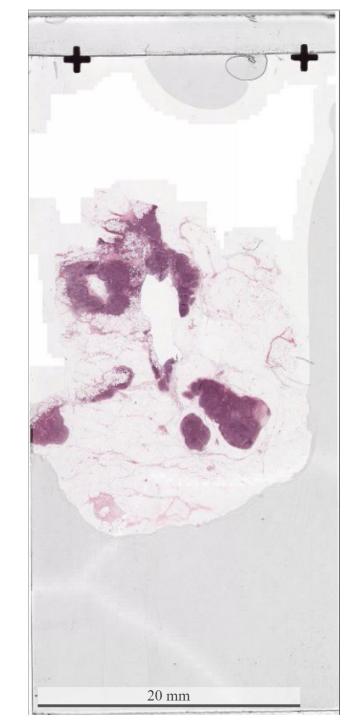
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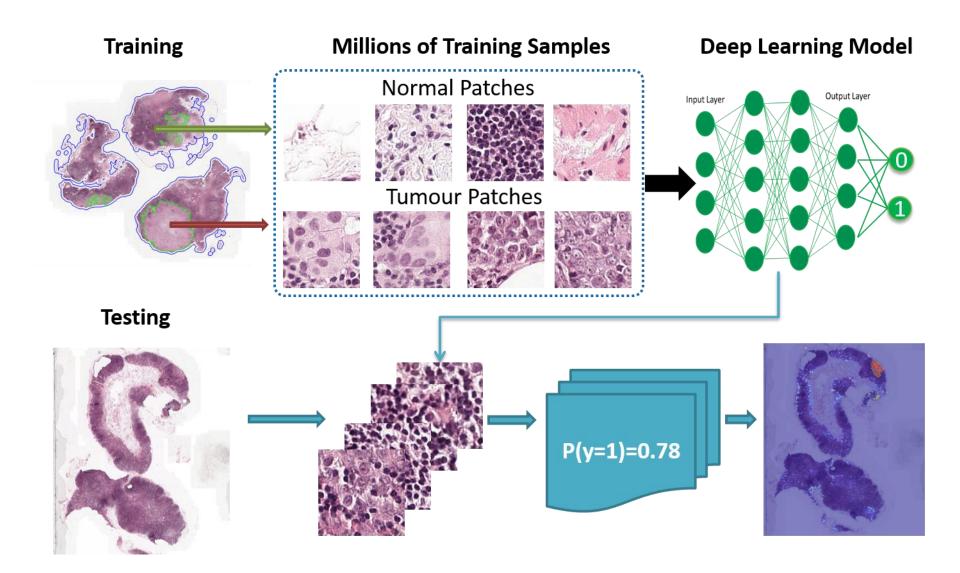
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TASKS

- Training and Evaluation
 - 110 tumor slides
 - 160 normal slides
 - 130 evaluation slides
- lst Task
 - Whole slide level prediction
 - Binary classification problem
- 2nd Task
 - Find metastasis location
 - Segmentation problem



SYSTEM FRAMEWORK



SEVERAL ESSENTIAL COMPONENTS

Network architecture

Training set construction

Computing environment

Post-processing for classification and segmentation

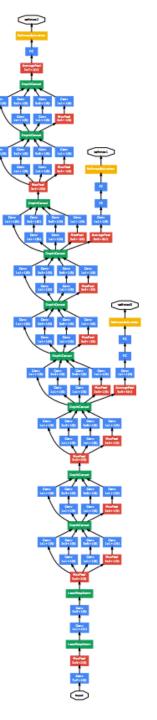
NETWORK ARCHITECTURE DESIGN

- We compared several networks
 - GoogLeNet (Szegedy et al. ILSCV 2014): 98.4%



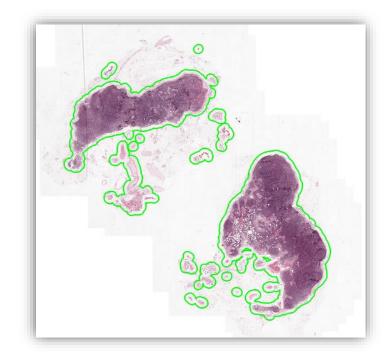
- VGG16 (Simonyan and Zisserman): 97.9%
- FaceNet (Wang et al. 2015): 96.8%
- AlexNet (Krizhevsky et al. NIPS 2012): 92.1%

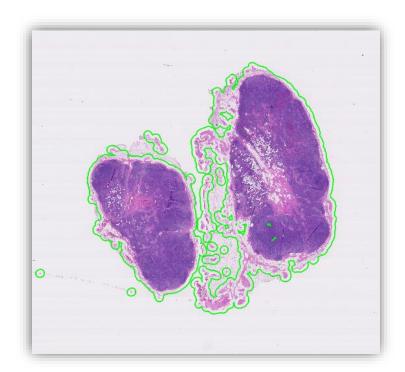
- Details of GoogLeNet
 - 27 layers in total
 - ~6 million parameters
 - three loss layers
 - Christian Szegedy et al. Going Deeper with Convolutions



TRAINING SET CONSTRUCTION

- Preprocessing
 - Tissue region segmentation (Otsu's method of foreground segmentation)
 - Remove 82% of WSI region on average





TRAINING SET CONSTRUCTION

• Step 1:

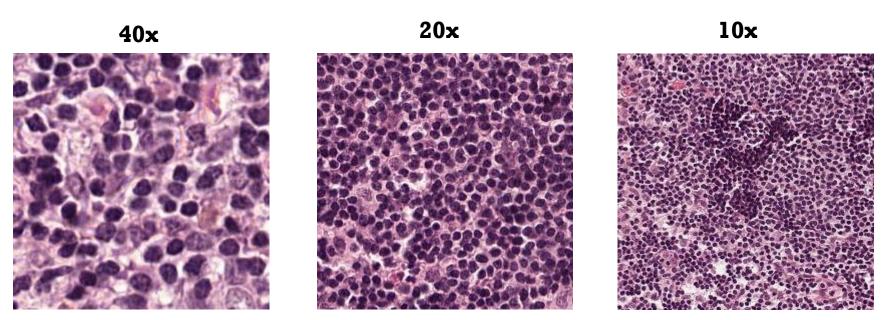
- Randomly extract patches (256 x 256) on the tissue region
 - Tumor slide: 1K positive and 1K negative from each slide
 - Normal slide: 1K negative from each slide
 - ~290K training patches

• Step 2:

- Make predictions and construct heatmaps
- Extract additional ~60K training patches from false positive regions
- 290K + 60K = 350K training patches in total

PATCH EXTRACTION AT 40X

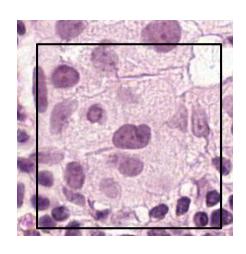
- We evaluate performance with patch extraction at several magnifications
 - Experimental results indicate that 40x is the best



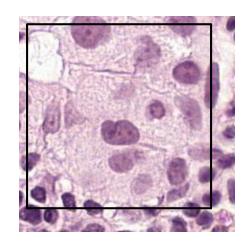
Example patches of size 256 x 256 with 40x, 20x and 10x magnification Normal Slide, ID: 001

DATA AUGMENTATION

• Randomly crop a 224 x 224 sub-region and flip patches horizontally

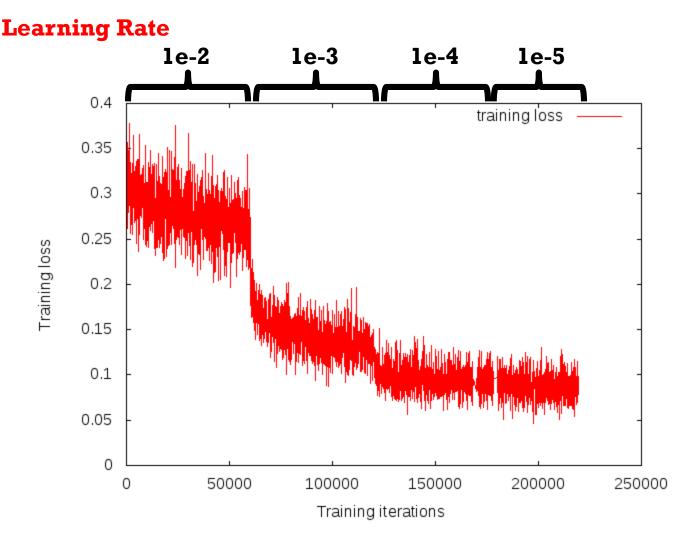


or



NETWORK TRAINING

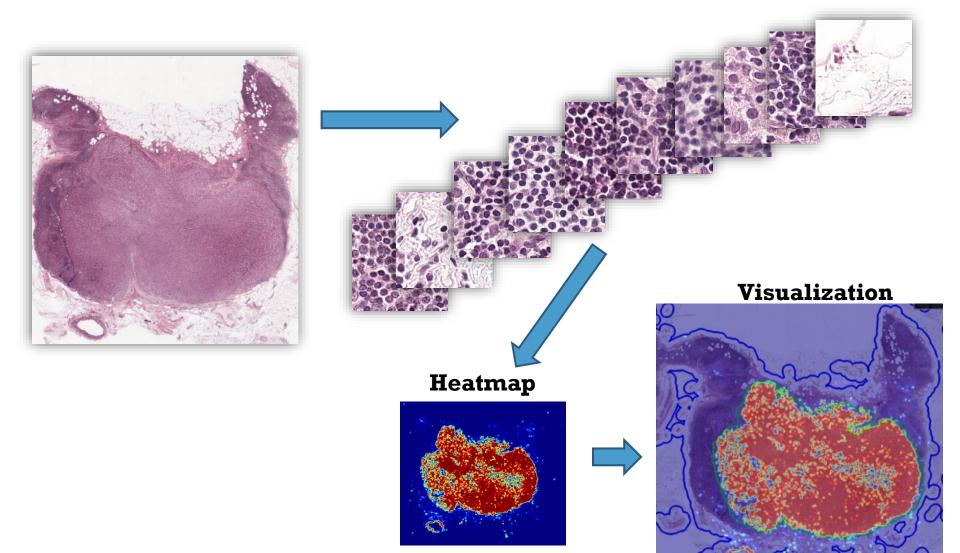
Deep model is trained from scratch using mini-batch SGD



Environment

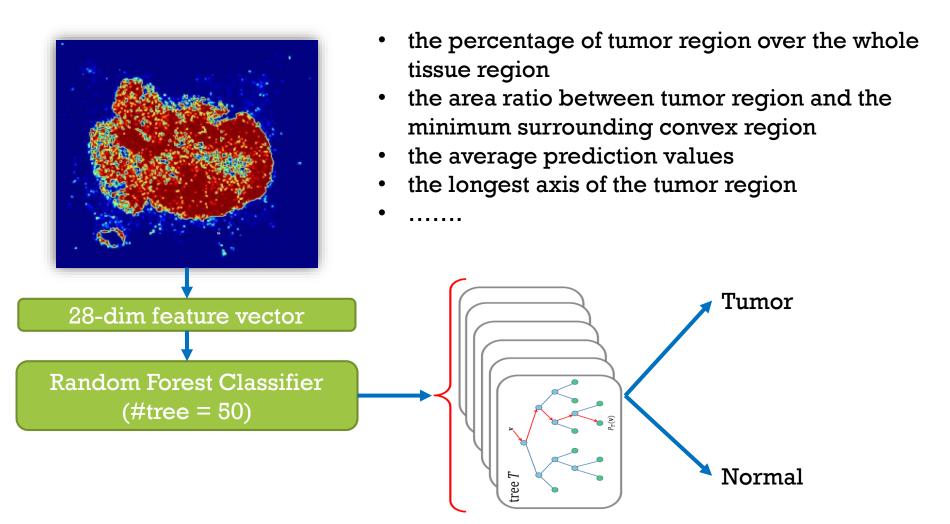
- GPU:
 - 2 x NVidia Tesla K80 graphics cards
- CPU:
 - Intel ® Xeon®
 CPU E5-2620 v3
 @ 2.40GHz
 - #cores=12
- · Hard Disk:
 - 4T SSD
- Memory:
 - 64 GB RAM

TUMOR PROBATILITY HEATMAP GENERATION

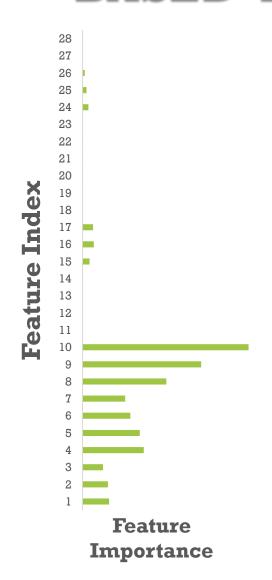


POST-PROCESSING FOR SLIDE-BASED TUMOR CLASSIFICATION

Extracting higher level features from tumor heatmaps



POST-PROCESSING FOR SLIDE-BASED TUMOR CLASSIFICATION



Top 5 important features, computed using the "regionprops" function in skimage. t is the threshold value

- **Feature 10:** given t=0.5, the longest axis in the largest tumor region
- **Feature 09:** given t=0.5, ratio of pixels in the region to pixels in the total bounding box ("extent")
- Feature 08: eccentricity of the ellipse that has the same second–moments as the region. ("eccentricity")
- **Feature 04:** ratio of tumor region when t=0.9 to the tissue region
- **Feature 05:** given t = 0.5, the area of largest tumor region

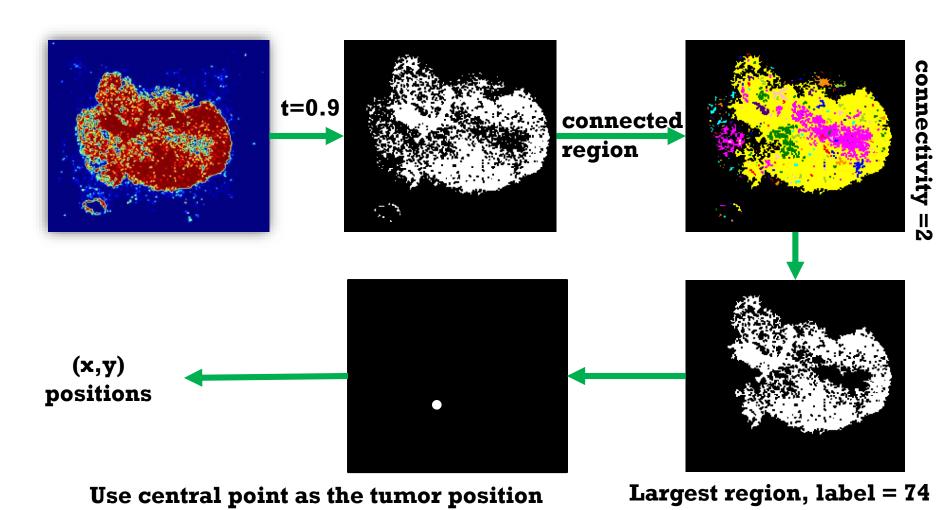
POST-PROCESSING FOR LESION-BASED TUMOR REGION SEGMENTATION

 Train a sensitive model (D-1) for estimation of tumor location (threshold = 0.9)

- Train a more specific model (D-2) for tumor probability estimation
 - ~30K extra training patches extracted from normal area adjacent to tumor region

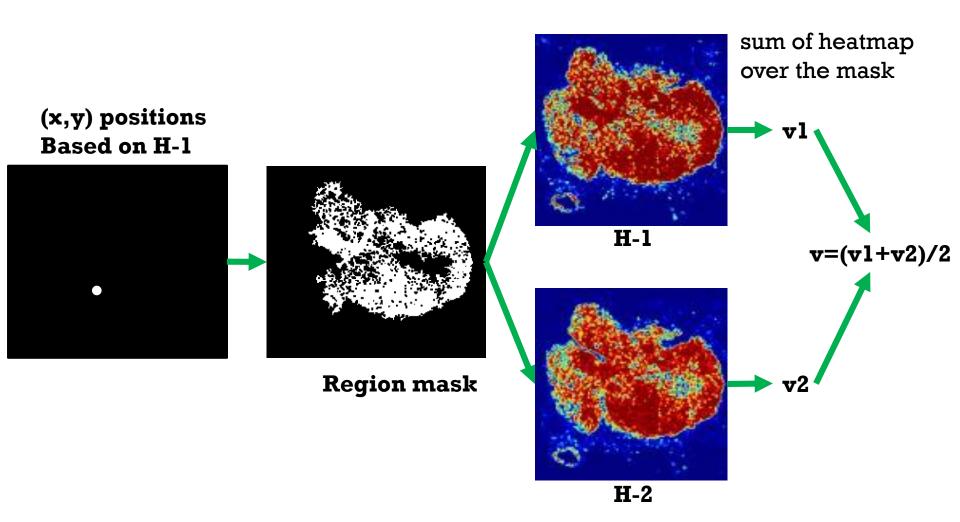
LESION-BASED TUMOR REGION SEGMENTATION

Generate the locations using H-1



LESION-BASED TUMOR REGION SEGMENTATION

Generate the prediction value using H-1 and H-2



CONCLUSIONS

- We developed a deep learning based framework for metastatic cancer detection in lymph nodes
 - Architecture: Based on GoogLeNet
 - Training: Additional training patches from false positive and tumor adjacent regions
 - Post-processing:
 - Random forest classifier on heatmap-based features for classification task
 - Integration of a more sensitive (for tumor location)
 and more specific (for tumor probability) model for
 segmentation task