

what surveyors really need...

A professional-level drone made for survey-grade mapping applications...

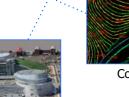
- 1. Simple assembly and quick hand launch
- 2. Humanized GCS software with interactive interfaces
- 3. Excellent flight attitude due to moderate drone weight
- 4. Quality imageries to generate survey-grade outputs
- 5. Reasonable costs versus high work efficiency
- 6. Trusted local dealer and renowned survey manufacturer standby







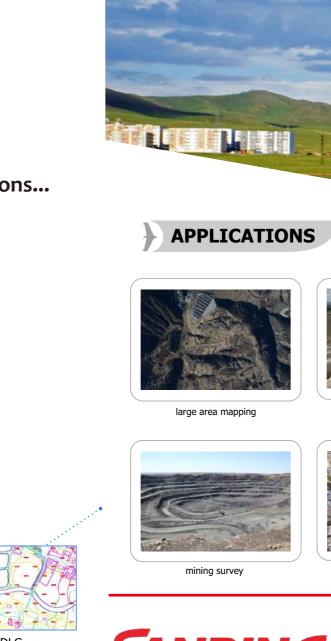












EVERY POINT MATTERS



piping planning & inspection

DKART

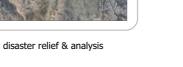


topographic survey

heavy earthwork construction



vegetation health survey





A Mapping Drone That Better Understands What Surveyors Need







What shall be considered before purchasing a mapping drone?

1. Easy operation 2. Automated control

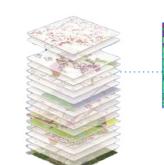
3. Output quality

4. Survey-grade demand

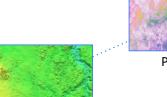
5. Cost efficiency

6. Responsive support

OUTPUTS











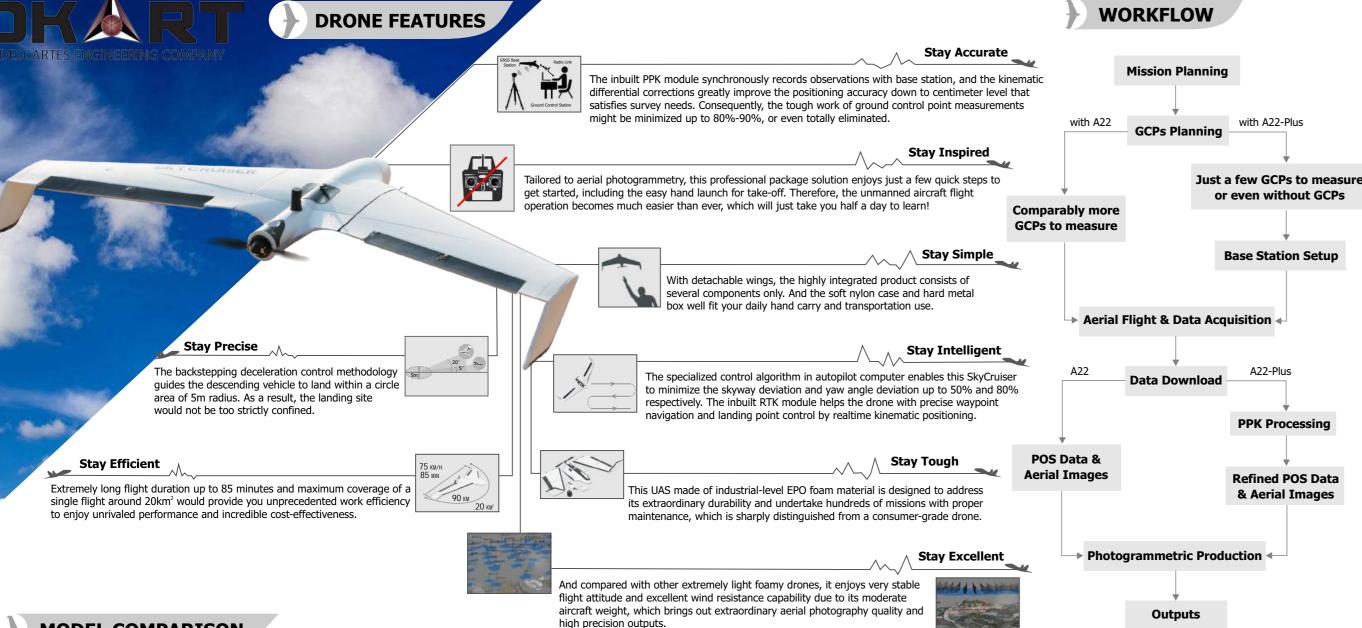


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Standard Version: A22 Professional Version: A22-Plus



MODEL COMPARISON

Model	Standard Version A22	Professional Version A22-Plus	
Inbuilt GPS Sensor	Yes (for aerial positioning, approx. 2-5m accuracy)		
Inbuilt GNSS Receiver	No	Yes (Base Station receiver built in radio datalink	
Induit 61455 Neceiver	110	device; Rover receiver built in drone fuselage)	
Airborne PPK Mode	No	Yes (for refined POS data with PPK differential	
		corrections)	
Airborne RTK Mode	No	Yes (for precise waypoint navigation and landing	
		point control)	
Realtime Skyway Deviation Rectification	No	Yes (managed by specialized control algorithm)	
Imaging Sensor	Sony ILCE-QX1, Exmor APS HD CMOS, 20.1 MP, Voigtlander Lens, E 21 mm, F 2.8		
Data Acquisition	Aerial imageries + original POS data	Aerial imageries + original POS data	
	Actial imagenes 1 original 1 05 data	+ base station observations + PPK records	
	Approx. 2-5 m, resulted from original POS data (based on GPS single-point positioning)	Approx. 5-10 cm / 10-30 cm (XY/Z), resulted from	
POS Data Accuracy		refined POS data (based on GNSS RTK aerial	
	, , , , , , , , , , , , , , , , , , , ,	positioning + GNSS PPK surveying)	
Survey-grade Mapping	Applicable	Applicable, and more suitable and highly efficient	
Mapping Accuracy	Centimeter level	Centimeter level	
riapping Accuracy	(with sufficient GCPs that are rationally distributed)	(with just a few or even without GCPs)	
GCPs Measurement	More GCPs required for further adjustment to generate	Much fewer GCPs or even no GCP required	
GCFS Medsulement	precise aerial mapping results	to generate precise aerial mapping results	
Pre-flight Setup	Regular (approx. 3-5 minutes)	Regular + base station setup (approx. 5-8 minutes)	
Landing Point Control	Deviation controlled within the confined area of	Deviation controlled within the confined circle of	
Landing Form Control	50 m X 4 m (length X width)	5m radius	
Landing Site Clearance	Comparatively bigger	Comparatively smaller	

AREA COVERAGE

Resolution (GSD)	Flight Altitude	Area Coverage (per flight)	Area Coverage (per day)
1.5 cm	70 m	2.0 km ²	8.0 km ²
5 cm	235 m	6.1 km²	24.4 km²
10 cm	470 m	11.8 km²	47.2 km²
15 cm	760 m	17.6 km²	70.4 km²
20 cm	940 m	22.2 km²	88.8 km²

Note: the data shown above is computed according to the forward overlap 75% and side overlap 60% from a 60-minute effective flight for a survey zone with aspect ratio around 2:1. And the area coverage per day results from 4 flights in the same day (2 flights each before and after lunch break). Theoretically, bigger coverage figures are expectable with rational parameter settings and increased flight arrangements.

SPECIFICATIONS

Aircraft	System
Aircraft Type	Fixed wing, wingspan 150 cm
Model	Standard Version A22 / Professional Version A22-Plu
Dimensions	150 x 70 x 13 cm
Packing Size	98 x 36 x 46 cm (soft carrying case); 98 x 36 x 46 cm (hard transportation box)
Empty Weight	A22: 1.45 kg; A22-Plus 1.55 kg
Body Material	Industrial EPO foam
Propulsion System	electric pusher motor, 12-inch foldable propeller
Electric Motor	500w
Power Supply	Lithium polymer battery, 10000mAh, 14.8V
Onboard	Sensors
Autopilot Computer	1X
Airspeedometer	1X
Accelerometer	1X
Barometer	1X
Magnetometer	1X
Gyroscope	1X
GPS Receiver	1X
Integrated RTK/PPK Receiver	Built-in chipset, L1/L2, GNSS (GPS/Glonass/Compass
(for model A22-Plus only)	Galileo ready), data refresh baud rate 20 Hz, positioning accuracy up to 3 cm
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Imagery Payload Standard Camera Sonv ILCE-OX1 Sensor Type Exmor APS HD CMOS 20.1 Mega Pixel Resolution Value Lens Configuration Voigtlander Focusing Length E 21mm Aperture Control F2.8 Picture Size 23.2 x 15.4 mm Imaging Resolution | 1.5-20 cm GSD (Ground Sampling Distance)

Pre-flight Checks Automated Flight Automations Automatic take-off, flight and landing operations Camera Triggering Automated Low-battery Warning Auto Return Upon low-battery indication Descending Control Three-section algorithm Fail-safe Routines Automated Fail-safe Commands Manually controlled

Operation Performance Pre-flight Setup 3-5 minutes (A22); 5-8 minutes (A22-Plus) Control Mode Weather Limit 10m/s (36km/h), Beaudfort scale 6, light rain Operating Temperature -10°C to 45°C Environmental Humidity 90% condensing Radio Datalink Control Frequency Typical 5-10 km; max. 30 km

Frequency Hopping Spread Spectrum (FHSS) Transmitting Power Communication Range Take-off Type Hand launch/automatic Landing Type Belly landing Landing Space Typical 20x6 m; recommended 50x10 m Endurance Not less than 59 minutes, best up to 80-85 minutes (customized unit only) Effective Photography Duration Best up to approx. 70-75 minutes Approx. 80-90 km Cruising Speed Typical 20m/s (72km/h) Flight Height Max. ceiling 4000 m Height above Take-off Location 70-940 m AGL (Above Ground Level) **Acquisition Performance** Single-point Positioning Accuracy A22: 2m CEP; A22-Plus: 3cm CEP Relative Accuracy (XY/Z) 1-3x/1-5x GSD (A22-Plus) Absolute Accuracy (without GCPs) A22: horizontal 0.8-2m / vertical 1-2.5m;

Absolute Accuracy (with GCPs)

A22-Plus: horizontal 3-10cm / vertical 5-15cm

A22-Plus: horizontal 2-3cm / vertical 5-10cm

A22: horizontal 2-3cm / vertical 5-10cm;

Required GCPs 80%-90% or even all to be eliminated (A22-Plus)

Mission Planning Simplicity

The ground control software that goes with this solution, very informative and intuitive, helps the user to optimize skyways and generate waypoints by simply defining GSD and overlap percentage. The software algorithm vividly tells what surveyors really expect: Simplicity and Ease of Use!





Low-battery Auto Return

Upon low battery warning, the SkyCruiser would activate Auto-Return function itself and ensure an expected safe landing. Once another charged battery is replaced for a second flight, the remained skyway of previous mission would be continued automatically.

Multi-zone Mission Planning

For the flight zone with complicated terrain conditions, a single flight mission consisting of several separate zones might be defined to deal with different flight heights in elevated areas



Large Area Photogrammetry

When the survey zone is too large to finish within a single flight, you might still keep it as one flight mission. Upon a second flight, the remained survey zone would be followed up automatically without extra flight planning.

Terrain Condition Evaluation

If the AGL (Above Ground Level) is less than 50m, the corresponding part of skyway would be displayed in red and users are suggested to adjust the flight height. Flight safety is the priority in drone operation, which is always acknowledged to both surveyors and GCS.





GCS Power-off Protection

In case that the laptop shuts down, restart it or change another laptop and run the GCS, the system would ask you whether to synchronize the existing mission from the aircraft. Even if you fail to restart the GCS, the drone would continue its flight and then land itself.

Compulsory Checklist Reminder

Before executing the mission, users would be guided to follow some checklists and double check the necessary procedures for flight safety and efficient operation. In other words, the GCS would always remind surveyors of all proper handlings in order not to make any mistake





One-key Return Home

The one-key operation for quick landing enables the drone to react then return home immediately in case of sudden rain or birds attack, which would effectively decrease the drone crash ratio.

All-in-one GCS Processing

Instead of operating in a third-party software kit, simply a one-key click in the GCS software will automatically process the PPK records and then generate the highly precise POS data.



Supposed a car stops or some people approach close to the landing point, user can abort this landing for emergency response. The aircraft would switch from landing status to climbing status and fly to start circle point then wait until a better chance for landing comes. Or change another point more suitable for alternative.

Extraordinary Interaction Experience

A mission information preview before flight and a prompt message asking whether to download POS after flight instantly appear, which all contributes to your master control of the aerial survey job.



