

Lecture 1: Review (Mostly)

Chris Conlon

February 1, 2021

NYU Stern

Packages for Today

Let's load some packages so that I can make some better looking plots:

```
#always  
library(tidyverse)  
# for SE's  
library(estimatr)  
library(broom)  
# for Panel  
library(lfe)  
library(plm)
```

Today's Plan

- Recap OLS and various forms of standard errors
- Standard errors are tedious but I guess you are supposed to know this stuff
- Hopefully first and last time we talk about this

Recap: Asymptotics for OLS and the Linear Model

$$y_i = \beta_0 + \beta x_i + u_i$$

Recall the three basic OLS assumptions

1. $E(u_i|X_i) = 0$
2. (X_i, Y_i) , $i = 1, \dots, n$, are i.i.d.
3. Large outliers are rare $E[Y^4] < \infty$ and $E[X^4] < \infty$.

Gauss Markov Theorem

Gauss Markov Adds two assumptions:

1. $E(u_i|X_i) = 0$
2. $(X_i, Y_i), i = 1, \dots, n$, are i.i.d.
3. Large outliers are rare $E[Y^4] < \infty$ and $E[X^4] < \infty$.
4. $Var(u_i) = \sigma^2$ (homoskedasticity)
5. $u_i \sim N(0, \sigma^2)$ (normal errors)

Under these assumptions you learned that OLS is BLUE

Unbiasedness and Consistency

- Unbiasedness means on average we don't over or under estimate $\widehat{\beta}$

$$\mathbb{E}[\widehat{\beta}] - \beta_0 = 0$$

- this holds whether $N = 1$ or $N \rightarrow \infty$.

Variance of $\hat{\beta}$

Start with the variance of the residuals to form a **diagonal** matrix D :

$$\text{Var}(\mathbf{u}|\mathbf{X}) = \mathbb{E}(\mathbf{u}\mathbf{u}'|\mathbf{X}) = \mathbf{D}$$

$$\mathbf{D} = \text{diag}(\sigma_1^2, \dots, \sigma_n^2) = \begin{pmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n^2 \end{pmatrix}$$

- \mathbf{D} is diagonal because $\mathbb{E}[u_i u_j | X] = \mathbb{E}[u_i | x_i] \mathbb{E}[u_j | x_j] = 0$ (independence)
- The elements of D_i are given by $\mathbb{E}[u_i^2 | X] = \mathbb{E}[u_i^2 | x_i] = \sigma_i^2$.
- In the **homoskedastic** case $\mathbf{D} = \sigma^2 \mathbf{I}_n$.

Variance of $\widehat{\beta}$

A useful identity for linear algebra:

$$\begin{aligned}\text{Var}(a\mathbf{Z}) &= a^2 \text{Var}(\mathbf{Z}) \\ \text{Var}(A\mathbf{Z}) &= A \text{Var}(\mathbf{Z}) A'\end{aligned}$$

Recall that $\text{Var}(\mathbf{Y}|\mathbf{X}) = \text{Var}(\mathbf{u}|\mathbf{X})$ and also recall the formula for $\widehat{\beta}$:

$$\begin{aligned}\widehat{\beta} &= \underbrace{(X'X)^{-1}X'}_A Y = A'Y \\ \mathbf{V}_{\widehat{\beta}} &= \text{Var}(\widehat{\beta}|\mathbf{X}) = (X'X)^{-1}X' \text{Var}(Y|\mathbf{X})X(X'X)^{-1} \\ &= (X'X)^{-1}(X'\mathbf{D}X)(X'X)^{-1}\end{aligned}$$

We have that $(X'\mathbf{D}X) = \sum_{i=1}^N x_i x_i' \sigma_i^2$. Under homoskedasticity $\mathbf{D} = \sigma^2 \mathbf{I}_n$ and $\mathbf{V}_{\widehat{\beta}} = \sigma^2 (X'X)^{-1}$.

Variance of $\widehat{\beta}$

$$\mathbf{D} = \text{diag}(\sigma_1^2, \dots, \sigma_n^2) = \mathbb{E}(u_i u_i' | \mathbf{X}) = \mathbb{E}(\widetilde{\mathbf{D}} | \mathbf{X})$$

We can estimate $\widehat{\mathbf{V}}_{\widehat{\beta}}$ by plugging in $\mathbf{D} \rightarrow \widetilde{\mathbf{D}}$:

$$\begin{aligned}\mathbf{V}_{\widehat{\beta}} &= (\mathbf{X}'\mathbf{X})^{-1}(\mathbf{X}'\widetilde{\mathbf{D}}\mathbf{X})(\mathbf{X}'\mathbf{X})^{-1} \\ &= (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{i=1}^N x_i x_i' u_i^2 \right) (\mathbf{X}'\mathbf{X})^{-1}\end{aligned}$$

The expectation shows us this estimator is unbiased:

$$\begin{aligned}E[\mathbf{V}_{\widehat{\beta}} | \mathbf{X}] &= (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{i=1}^N x_i x_i' E[u_i^2 | \mathbf{X}] \right) (\mathbf{X}'\mathbf{X})^{-1} \\ &= (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{i=1}^N x_i x_i' \sigma_i^2 \right) (\mathbf{X}'\mathbf{X})^{-1} = (\mathbf{X}'\mathbf{X})^{-1} (\mathbf{X}'\mathbf{D}\mathbf{X}) (\mathbf{X}'\mathbf{X})^{-1}\end{aligned}$$

Heteroskedasticity Consistent (HC) Variance Estimates

What we need is a consistent estimator for \hat{u}_i^2 .

$$\mathbf{v}_{\hat{\beta}}^{HC0} = (X'X)^{-1} \left(\sum_{i=1}^N x_i x_i' \hat{u}_i^2 \right) (X'X)^{-1}$$

$$\mathbf{v}_{\hat{\beta}}^{HC1} = (X'X)^{-1} \left(\sum_{i=1}^N x_i x_i' \hat{u}_i^2 \right) (X'X)^{-1} \cdot \left(\frac{n}{n-k} \right)$$

Could use \tilde{u}_i instead of \hat{u}_i for a better estimate

$$\mathbf{v}_{\hat{\beta}}^{HC2} = (X'X)^{-1} \left(\sum_{i=1}^N (1 - h_{ii})^{-1} x_i x_i' \hat{u}_i^2 \right) (X'X)^{-1}$$

$$\mathbf{v}_{\hat{\beta}}^{HC3} = (X'X)^{-1} \left(\sum_{i=1}^N (1 - h_{ii})^{-2} x_i x_i' \hat{u}_i^2 \right) (X'X)^{-1}$$

Heteroskedasticity Consistent (HC) Variance Estimates

- We know that $\mathbf{V}_{\hat{\beta}}^{HC3} > \mathbf{V}_{\hat{\beta}}^{HC2} > \mathbf{V}_{\hat{\beta}}^{HC0}$ because $(1 - h_{ii}) < 1$.
- *HC3* are the most **conservative** and also place the most weight on potential outliers.
- Stata uses *HC1* as the default and it is what most people refer to when they say **robust standard errors**.
- These are often called White (1980) SE's or Eicher-Huber-White SE's.
- In small sample some evidence that *HC2* does better.

Heteroskedasticity Consistent (HC) Variance Estimates

To read about SE's in estimatr:

<https://declaredesign.org/r/estimatr/articles/mathematical-notes.html>

```
dat <- data.frame(X = matrix(rnorm(2000*5), 2000), y = rnorm(2000))
hc0<-lm_robust(y ~ ., data = dat, se_type="HC0")$std.error
hc1<-lm_robust(y ~ ., data = dat, se_type="HC1")$std.error
hc2<-lm_robust(y ~ ., data = dat, se_type="HC2")$std.error
hc3<-lm_robust(y ~ ., data = dat, se_type="HC3")$std.error
all(hc2 > hc0 )
[1] TRUE
all(hc3> hc2 )
[1] TRUE
```

What is Clustering?

Suppose we want to relax our i.i.d. assumption:

- Each observation i is a villager and each group g is a village
- Each observation i is a student and each group g is a class.
- Each observation t is a year and each entity i is a state.
- Each observation t is a week and each entity i is a shopper.

We might expect that $\text{Cov}(u_{g1}, u_{g2}, \dots, u_{gN}) \neq 0 \rightarrow$ independence is a bad assumption.

Clustering: Intuition

The groups (villages, classrooms, states) are independent of one another, but within each group we can allow for arbitrary correlation.

- If correlation is within an individual over time we call it **serial correlation** or **autocorrelation**
- Just like in time-series→ we have fewer effective independent observations in our sample.
- Asymptotics now about the number of groups $G \rightarrow \infty$ not observations $N \rightarrow \infty$

Clustering

Begin by stacking up observations in each group $\mathbf{y}_g = [y_{g1}, \dots, y_{gn_g}]$, we can write OLS three ways:

$$y_{ig} = \mathbf{x}'_{ig}\beta + u_{ig}$$

$$\mathbf{y}_g = \mathbf{X}_g\beta + \mathbf{u}_g$$

$$\mathbf{Y} = \mathbf{X}\beta + \mathbf{u}$$

All of these are equivalent:

$$\widehat{\beta} = \left(\sum_{g=1}^G \sum_{i=1}^{n_g} \mathbf{x}'_{ig} \mathbf{x}_{ig} \right)^{-1} \left(\sum_{g=1}^G \sum_{i=1}^{n_g} \mathbf{x}'_{ig} y_{ig} \right)$$

$$\widehat{\beta} = \left(\sum_{g=1}^G \mathbf{X}'_g \mathbf{X}_g \right)^{-1} \left(\sum_{g=1}^G \mathbf{X}'_g \mathbf{y}_g \right)$$

$$\widehat{\beta} = (\mathbf{X}'\mathbf{X})^{-1} (\mathbf{X}'\mathbf{Y})$$

Clustering (Continued)

The error terms have covariance within each cluster g as:

$$\Sigma_g = \mathbb{E}(\mathbf{u}_g \mathbf{u}_g' | \mathbf{X}_g)$$

In order to calculate $\widehat{V}_{\widehat{\beta}}$ we replace the covariance matrix \mathbf{D} with Ω and consider an estimator $\widehat{\Omega}_n$. We exploit **independence across clusters**:

$$\text{var}\left(\left(\sum_{g=1}^G \mathbf{X}_g' \mathbf{u}_g\right) | \mathbf{X}\right) = \sum_{g=1}^G \text{var}(\mathbf{X}_g' \mathbf{u}_g | \mathbf{X}_g) = \sum_{g=1}^G \mathbf{X}_g' \mathbb{E}(\mathbf{u}_g \mathbf{u}_g' | \mathbf{X}_g) \mathbf{X}_g = \sum_{g=1}^G \mathbf{X}_g' \Sigma_g \mathbf{X}_g \equiv \Omega_N$$

And an estimate of the variance:

$$\mathbf{V}_{\widehat{\beta}} = \text{var}(\widehat{\beta} | \mathbf{X}) = (\mathbf{X}'\mathbf{X})^{-1} \widehat{\Omega}_n (\mathbf{X}'\mathbf{X})^{-1}$$

$$\begin{aligned}\widehat{\Omega}_n &= \sum_{g=1}^G X_g' \widehat{\mathbf{u}}_g \widehat{\mathbf{u}}_g' X_g \\ &= \sum_{g=1}^G \sum_{i=1}^{n_g} \sum_{\ell=1}^{n_g} x_{ig} x_{\ell g}' \widehat{u}_{ig} \widehat{u}_{\ell g} \\ &= \sum_{g=1}^G \left(\sum_{i=1}^{n_g} x_{ig} \widehat{u}_{ig} \right) \left(\sum_{\ell=1}^{n_g} x_{\ell g} \widehat{u}_{\ell g} \right)'\end{aligned}$$

- First line makes explicit: independence over each of G clusters
- Last line easiest for computer

$$\widehat{\mathbf{V}}_{\hat{\beta}}^{\text{CR1}} = (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{g=1}^G \mathbf{X}'_g \widehat{\mathbf{u}}_g \widehat{\mathbf{u}}'_g \mathbf{X}_g \right) (\mathbf{X}'\mathbf{X})^{-1}$$

$$\widehat{\mathbf{V}}_{\hat{\beta}}^{\text{CR3}} = (\mathbf{X}'\mathbf{X})^{-1} \left(\sum_{g=1}^G \mathbf{X}'_g \widetilde{\mathbf{u}}_g \widetilde{\mathbf{u}}'_g \mathbf{X}_g \right) (\mathbf{X}'\mathbf{X})^{-1}$$

- Can replace $\widehat{\mathbf{u}}_g \rightarrow \widetilde{\mathbf{u}}_g$ for leave-one out like *HC3* (these are called *CR3*).

```
lm_robust(y~ x1 + x2, data=df, se_type="CR0", cluster=group_id )  
lm_robust(y~ x1 + x2, data=df, se_type="CR2", cluster=group_id )  
lm_robust(y~ x1 + x2, data=df, se_type="CR1", cluster=group_id )
```

Most Asked PhD Student Econometric Question

How should I cluster my standard errors?

- Heck if I know.
- This is very problem specific
- It matters a lot → standard errors can get orders of magnitude larger.
- Do you believe across group independence or not? [this is the only thing that matters]
- If you include **fixed effects** probably you need at least clustering at that level.

Newey West Standard Errors (HAC)

- In serially correlated data we need to account for $\text{Cov}(u_t, u_{t-1}, \dots) \neq 0$.
- Clustering is one solution, but we may end up throwing away all of our data.
- Instead we could estimate the serial correlation.
- May also want standard errors that are **heteroskedasticity AND autocorrelation consistent** (HAC).
- Have to select a number of lags L

$$\widehat{\Omega}_{n,L}^{HAC} = \sum_{t=1}^T u_t^2 x_t x_t' + \sum_{l=1}^L \sum_{t=l+1}^T w_l u_t u_{t-l} (x_t x_{t-l}' + x_{t-l} x_t')$$
$$w_l = 1 - \frac{l}{L+1}$$

What about β ?

- All of the estimates above should produce **identical** point estimates
- We have just been talking about adjusting **standard errors**
- Should the presence of heteroskedasticity change our estimates of $\hat{\beta}$ as well?

A simple extension is Weighted Least Squares (WLS)

- Different motivations
- Suppose we have sampling weights that are not $\frac{1}{n}$ from survey data, etc:
 - If my population is supposed to represent all US residents and my sample is 75% Women...
 - Relax LSA (2) (X_i, Y_i) , $i = 1, \dots, n$, are i.i.d.
- In this case, OLS is still unbiased and consistent, just **inefficient**

Can weight each observation as w_i so that $\sum_{i=1}^N w_i = 1$ instead of $w_i = \frac{1}{N}$.

Can define a diagonal matrix W with entries w_i .

$$\arg \min_{\beta} \sum_{i=1}^N w_i (y_i - X_i \beta)^2 = \arg \min_{\beta} \|W^{1/2} Y - X \beta\|$$

Can also consider a transformation of the data

$$\begin{aligned}\tilde{y}_i &= \sqrt{w_i} y_i, & \tilde{x}_i &= \sqrt{w_i} x_i \\ \tilde{Y} &= W^{1/2} Y, & \tilde{X} &= W^{1/2} X\end{aligned}$$

A regression of \tilde{Y} on \tilde{X} :

$$\hat{\beta}_{WLS} = (\tilde{X}' \tilde{X})^{-1} \tilde{X}' \tilde{Y} = (X' W X)^{-1} X' W Y$$

Also used as a solution to heteroskedasticity

- Relax LSA (2) (X_i, Y_i) , $i = 1, \dots, n$, are i.i.d.
- Relax LSA (4) $\text{Var}(u_i) = \sigma^2$ (homoskedasticity)

Why? We are minimizing weighted sum of squared residuals:

$$\sum_{i=1}^N w_i (y_i - \hat{y}_i)^2 = \sum_{i=1}^N w_i \varepsilon_i^2$$

Suppose we have heteroskedasticity so that $\text{Var}(\varepsilon_i) = \sigma_i^2$ and $w_i \propto \frac{1}{\sigma_i^2}$.

In this setting WLS is **BLUE**.

Why does anyone ever run OLS instead of WLS?

- Problem is that σ_i^2 is unknown before we run our regression.
- We can estimate $\widehat{\sigma}_i^2$.

This procedure is known as Iteratively Re-weighted Least Squares **IRLS**

1. Initialize weights to identity matrix: $W = I$
2. Regress Y on X with weights W
3. Obtain $\widehat{\varepsilon}_i$.
4. Update W with $w_{ii} = \frac{1}{\widehat{\varepsilon}_i^2}$
5. Repeat until parameter estimates don't change

There is no reason to require that W be diagonal. This gives us **Generalized Least Squares**

$$\widehat{\beta}_{GLS} = (\tilde{X}'\tilde{X})^{-1}\tilde{X}'\tilde{Y} = (X'\Omega X)^{-1}\Omega'WY$$

The idea is to use the **inverse covariance matrix** of residuals. But this is high dimensional ($N \times N$) and estimating it is harder than our original problem!

Feasible Generalized Least Squares **FGLS**:

1. Initialize weights to identity matrix: $\widehat{\Omega} = I$
2. Regress Y on X with weighting matrix $\widehat{\Omega}$
3. Obtain $\widehat{\varepsilon}_i$.
4. Construct $E[\varepsilon_i^2|X, Z]$ via (nonlinear) regression: $\exp[\gamma_0 + \gamma_1 x_i + \gamma_2 z_i]$.
5. Update $\widehat{\Omega}$ with $E[\varepsilon_i^2|X, Z]$
6. Repeat until parameter estimates don't change

Outliers and Leverage

One way to find outliers is to calculate the leverage of each observation i . We begin with the hat matrix:

$$P = X(X'X)^{-1}X'$$

and consider the diagonal elements which for some reason are labeled h_{ii}

$$h_{ii} = x_i(X'X)^{-1}x_i'$$

This tells us how influential an observation is in our estimate of $\hat{\beta}$. Particularly important for $\{0, 1\}$ dummy variables with uneven groups.

Leave One Out Regression

- This is sometimes called the **Jackknife**
- Sometimes it is helpful to know what would happen if we omitted a single observation i
- Turns out we don't need to run N regressions

$$\begin{aligned}\widehat{\beta}_{-i} &= (X'_{-i}X_{-i})^{-1}X'_{-i}Y_{-i} \\ &= \widehat{\beta} - (X'X)^{-1}x_i\tilde{u}_i \quad \text{where } \tilde{u}_i = (1 - h_{ii})^{-1}\hat{u}_i\end{aligned}$$

- \tilde{u}_i has the interpretation of the **LOO prediction error**.
- high leverage observations move $\widehat{\beta}$ a lot.

You can read more about this in Ch3 of Hansen. [Skip derivation]

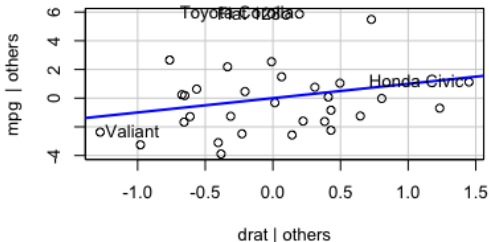
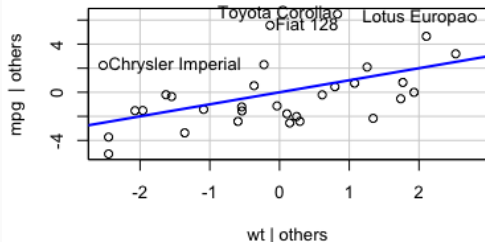
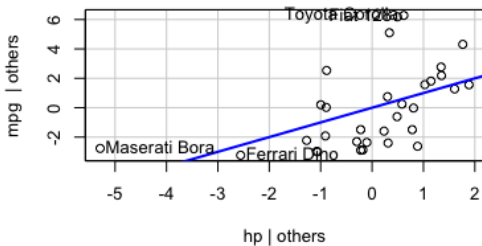
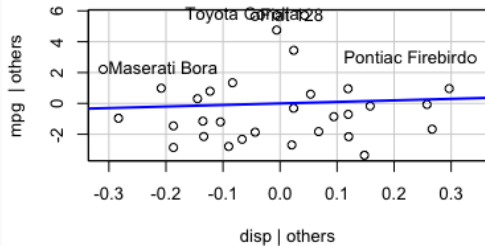
Leverage and QQ plots

```
library(car)
fit <- lm(mpg~disp+hp+wt+drat, data=mtcars)

# Assessing Outliers
outlierTest(fit) # Bonferonni p-value for most extreme obs
qqPlot(fit, main="QQ Plot") #qq plot for studentized resid
leveragePlots(fit) # leverage plots
```

Leverage Plot

Leverage Plots



Regression “Fit”

How “well” does this regression perform?

- $R^2 = 1 - \frac{\sum_{i=1}^N (y_i - \hat{y}_i)^2}{\sum_{i=1}^N (y_i - \bar{y})^2}$: fraction of variance explained by X_i (and the fraction explained by ε_i).
- Alternative: **mean squared error** (MSE) $\frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2$.
 - This is of course what least-squares is actually minimizing!
- Alternative: **root mean squared error** (RMSE) $\sqrt{\frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2}$.
 - The average distance from a point to the line of best fit.
- Alternative: **mean absolute deviation** (MAD) $\frac{1}{N} \sum_{i=1}^N (|y_i - \hat{y}_i|)$.
 - The average residual.
- Alternative: **median absolute error** (MAE) median $(|y_i - \hat{y}_i|)$.
 - The median residual (insensitive to outliers).
- If you read enough econometrics papers, you will see enough of these.

Regression “Fit” (continued)

- Nearly all of those measures will improve as we add parameters to the model
- If we choose the model with the lowest $RMSE$ or highest R^2 we will nearly always choose a model with more parameters!
- We might be worried about **overfitting**: choosing a regression model that fits our particular sample (y_i, x_i) well but might not perform well on a new but similar sample.
- A common solution is **penalization**

Penalized Regression

$$\min_{\beta} \sum_{i=1}^N (y_i - X_i \beta)^2 + f(\beta)$$

Idea if β has too many nonzero elements, or elements are too large – increase the penalty:

- AIC and BIC set $f(\beta)$ as penalty in terms of number of nonzero elements of β the so called L_0 norm.
- Lasso penalizes the L_1 norm $\sum_{k=1}^K |\beta_k|$.
- Ridge penalizes the L_2 norm $\sum_{k=1}^K |\beta_k|^2$.
- We will talk about penalization later, but this prevents us from selecting models that are “too complicated”.

Thanks!
