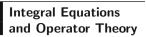
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Open Problems

Seventy Five (Thousand) Unsolved Problems in Analysis and Partial Differential Equations

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Abstract. This is a collection of open problems concerning various areas in function theory, functional analysis, theory of linear and nonlinear partial differential equations.

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Contents

1.	Introduction		4
2.	Basic Notations		4
3.	Sobolev Spaces of Integer and Fractional Orders		5
	3.1.	Isoperimetric Problem for Fractional Perimeter	5
	3.2.	Strong Capacitary Inequality for Functions with Arbitrary	
		Boundary Data	6
	3.3.	Boundary Traces of Functions in a Sobolev Space	6
	3.4.	Embedding of a Sobolev Space into the Space of Distributions	7
	3.5.	An Approximation Problem in the Theory of Sobolev Spaces	7
	3.6.	Extensions of Sobolev Functions Outside of an Angle	7
	3.7.	Best Constants in Some Classical Inequalities	8
	3.8.	Hardy Inequality with Capacitary Distance to $\partial\Omega$	8

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	3.9.	Uncertainty Principle for Divergence-Free Fields	9
	3.10.	Normalization of an Anisotropic Riesz Potential Space	9
	3.11.	Two-Weight Hardy Inequality Involving First and Second	
		Derivatives	10
	3.12.	Trace Inequality with a Non-Positive Measure	10
	3.13.	Domains for Which $L^{l,p}(\Omega) \cap L^{\infty}(\Omega)$ is a Banach Algebra	10
4.	Integ	ral Operators	11
	4.1.	A Multi-Dimensional Integral Equation Which can be Reduced to One-Dimensional	11
	4.2.	A Singular Integral Operator in $L^p(\mathbb{R}^n)$	11
	4.3.	Fredholm Radius of the Harmonic Double Layer Potential	11
	4.4.	Potential Theory for Surfaces with Cusps	12
	4.5.	Regularity of Domains in the Theory of Boundary Integral Equations	12
	4.6.	Integral Equations of Potential Theory Under Interaction of	14
	4.0.	Nearly Touching Particles	12
	4.7.	Non-Classical Maximal Operator	13
		•	13
-	4.8.	Fourier p-Capacity and Potentials	
5.		ar Elliptic Operators	13
	5.1.	Integral Inequality for the Integrable Laplacian	13
	5.2.	Hölder Regularity of a Boundary Point with Respect to an Elliptic Operator of Second Order	14
	5.3.	Uniqueness in the Cauchy Problem for the Laplace Equation	15
	5.4.	De Giorgi-Nash Theorem for Equations with Complex-Valued Coefficients	16
	5.5.	Fractal Domains Versus Lipschitz Domains	16
	5.6.	Dirichlet Problem in a Planar Jordan Domain	16
	5.7.	Hölder Regularity of Capacitary Potential of n -Simensional Cube	17
	5.8.	Non-Lipschitz Graph Domains Which are Weakly Lipschitz	17
	5.9.	Self-Adjointness of the Laplacian in a Weighted L^2 -Space	17
	5.10.	Peculiarities of Planar C^1 Domains and Extensions of the	
		Dirichlet Laplacian	18
	5.11.	Pointwise Estimates for Polyharmonic Green's Functions	18
	5.12.	Boundedness of Solutions to the Polyharmonic Equation in	
		Arbitrary Domains	19
	5.13.	Polyharmonic Capacitary Potentials	19
	5.14.	Subadditivity of the Polyharmonic Capacity	20
	5.15.	Normal Derivative of a Harmonic Function at a Boundary Point	20
	5.16.	Essential Spectrum of a Perturbed Polyharmonic Operator	21
	5.17.	Singularity of Green's Function for Second Order Elliptic Equations with Lower Order Terms	21
	5.18.	Generic Degenerating Oblique Derivative Problem	21
	5.19.	Matrix Generalization of the Oblique Derivative Problem	23
	5.20.	Coercive Weighted Estimates for Elliptic Equations in Domains	
	J J.	with Inner Cusps	23

Т	Seventy Five (Thousand) Open Problems Page 3 of 44	25
5.21.	Multiplicative Inequality for the Linear Elasticity System in	
	an Arbitrary Domain	23
5.22.	L^p -Dissipativity of the Lamé Operator	23
5.23.	Generalized Maximum Principle for the Lamé System in a	
	Domain with Non-Lipschitz Graph Conical Vertex	24
5.24.	Boundedness of the Displacement Vector in the Traction	
	Problem in Domains with Non-Lipschitz Graph Conical	2.4
r 0r	Vertices	24
5.25.	Comparison of Martin's and Euclidian Topologies	25
	inear Elliptic Operators	25
6.1.	Nonlinear Singularities at the Vertex of a Cone	25
6.2.	Nonlinear Boundary Value Problem with Infinite Dirichlet Data	26
6.3.	Singularities of Solutions to the Neumann Problem for a Semilinear Equation	26
6.4.	Positive Solutions of a Non-Linear Dirichlet Problem with Zero	20
0.4.	Boundary Data	27
6.5.	Positive p-Harmonic Functions in a Cone	27
6.6.	Phragmen–Lindelöf Principle for the <i>p</i> -Laplace equation	27
6.7.	Isolated Singularity of Solution to a Nonlinear Elliptic System	28
6.8.	Poisson Type Solutions of Riccati's Equation with Dirichlet	
0.0.	Data	28
Paral	bolic, Hyperbolic and General Differential Operators	28
7.1.	Behaviour at Infinity of Solutions to the Cauchy–Dirichlet	
	Problem for a Semi-Linear Parabolic Equation	28
7.2.	Two Inequalities Related to the Heat Equation	29
7.3.	Trace Space for the Maximal Operator Generated by the Wave	
	Operator	30
7.4.	Characteristic Problem for Nonlinear Hyperbolic Operators	30
7.5.	Boundary Traces of Functions in the Domain of a Maximal	
	Differential Operator with t-Dependent Coefficients	30
7.6.	Differential Operators Acting in Pairs of Sobolev Spaces	31
7.7.	Existence of a Well-Posed Boundary Value Problem for for	
_ ^	General Differential Operators in $L^p(\Omega)$	31
7.8.	Existence of a Well-Posed Boundary Value Problem for Unbound	
a	Domains	31
	onary Stokes and Navier–Stokes Systems	32
8.1.	Hölder Regularity of Solutions to the n -Dimensional Dirichlet— Stokes Problem	32
8.2.	Differentiability of Solutions to the Dirichlet Problem for the	34
0.4.	Equations of Hydrodynamics in Convex Domains	32
8.3.	Boundedness of Solutions to the Dirichlet Problem for the	54
J.J.	Stokes System in Arbitrary 3D Domains	33

		an Arbitrary Domain	23
	5.22.	L^p -Dissipativity of the Lamé Operator	23
	5.23.	Generalized Maximum Principle for the Lamé System in a	
		Domain with Non-Lipschitz Graph Conical Vertex	24
	5.24.	Boundedness of the Displacement Vector in the Traction	
		Problem in Domains with Non-Lipschitz Graph Conical	
		Vertices	24
	5.25.	Comparison of Martin's and Euclidian Topologies	25
3.	Nonl	inear Elliptic Operators	25
	6.1.	Nonlinear Singularities at the Vertex of a Cone	25
	6.2.	Nonlinear Boundary Value Problem with Infinite Dirichlet Data	26
	6.3.	Singularities of Solutions to the Neumann Problem for a	
		Semilinear Equation	26
	6.4.	Positive Solutions of a Non-Linear Dirichlet Problem with Zero	
		Boundary Data	27
	6.5.	Positive p-Harmonic Functions in a Cone	27
	6.6.	Phragmen–Lindelöf Principle for the <i>p</i> -Laplace equation	27
	6.7.	Isolated Singularity of Solution to a Nonlinear Elliptic System	28
	6.8.	Poisson Type Solutions of Riccati's Equation with Dirichlet	
		Data	28
7.	Para	bolic, Hyperbolic and General Differential Operators	28
	7.1.	Behaviour at Infinity of Solutions to the Cauchy–Dirichlet	
		Problem for a Semi-Linear Parabolic Equation	28
	7.2.	Two Inequalities Related to the Heat Equation	29
	7.3.	Trace Space for the Maximal Operator Generated by the Wave	
		Operator	30
	7.4.	Characteristic Problem for Nonlinear Hyperbolic Operators	30
	7.5.	Boundary Traces of Functions in the Domain of a Maximal	
		Differential Operator with t-Dependent Coefficients	30
	7.6.	Differential Operators Acting in Pairs of Sobolev Spaces	31
	7.7.	Existence of a Well-Posed Boundary Value Problem for for	
		General Differential Operators in $L^p(\Omega)$	31
	7.8.	Existence of a Well-Posed Boundary Value Problem for Unbound	
	a	Domains	31
3.		onary Stokes and Navier–Stokes Systems	32
	8.1.	Hölder Regularity of Solutions to the <i>n</i> -Dimensional Dirichlet–	00
	0.0	Stokes Problem	32
	8.2.	Differentiability of Solutions to the Dirichlet Problem for the	00
	0.0	Equations of Hydrodynamics in Convex Domains	32
	8.3.	Boundedness of Solutions to the Dirichlet Problem for the	กก
	0.4	Stokes System in Arbitrary 3D Domains	33
	8.4.	Resolvent L^p -Estimates for the Dirichlet–Stokes Operator	33
	8.5.	Non-Uniqueness for the Stationary Navier–Stokes System with	99
`	The-	Dirichlet Data	33
).	1 neo	ry of Surface Waves	34

	9.1.	Well-Posed Neumann–Kelvin Problem for a Surface-Piercing	
		Body	34
	9.2.	Solvability of the Two-Dimensional Kelvin–Neumann Problem	
		for a Submerged Cylinder	34
	9.3.	Counterexample in the Water-Wave Problem for a Submerged	
		Body	35
	9.4.	Sharp Hardy–Leray Inequality for Divergence-Free Fields	35
10.	Mis	cellaneous Topics	36
	10.1.	A Modified Riemann's Zeta Function Appearing in a Non-	
		Local Parabolic Cauchy Problem	36
	10.2.	Uniqueness Criterion for Analytic Functions with Finite	
		Dirichlet Integral	36
	10.3.	Hybrid Iterative Methods for Solving Boundary Value	
		Problems	37
	10.4.	Asymptotic Optimization of Multi-Structures	37
Ref	foronce	~	38

1. Introduction

The title of this article was inspired by the title of Sholem Aleichem's story "Seventy five thousand". Alas, the reader will find only seventy five problems here! I hope each of them can produce a long sequence (a thousand) of others.

The problems below present a sample of questions that I came across upon during many years of research, but have never seen them solved or even clearly formulated. Some of them might turn out being rather simple, while others would present a significant challenge and hopefully attract interest of beginning researchers and experts alike.

I tried to select questions that can be formulated without much preliminary knowledge. For more explanations the reader is directed to the cited literature.

The problems included here address both linear and non-linear PDEs. One can hear sometimes that "all linear problems had been already solved". Hopefully, the following list of problems will show that this opinion is mistaken.

2. Basic Notations

Here some notations which are used in the article are collected.

By a domain Ω we mean an open connected set in \mathbb{R}^n with boundary $\partial\Omega$. We say that Ω is a Lipschitz graph domain if it can be locally explicitly represented in a certain cartesian system by a Lipschitz function. The domain is weakly Lipschitz if it is locally Lipschitz diffeomorphic to a ball. Let H_{n-1} stand for the (n-1)-dimensional Hausdorff measure. Let $B_r(x)$ denote the open ball with center x and radius r, $B_r = B_r(O)$, where O is the origin. We shall use the notation m_n for n-dimensional Lebesgue measure and v_n for

 $m_n(B_1)$. We use the notation $\nabla_l u$ for the distributional gradient of order l, i.e. $\nabla_l u = \{D^{\alpha}u\}$, where α is a multi-index $(\alpha_1, \ldots, \alpha_n)$, $D^{\alpha} = D_{x_1}^{\alpha_1} \ldots D_{x_n}^{\alpha_n}$ and $|\alpha| = \sum_i \alpha_i = l$. We put $\nabla = \nabla_1$.

Let $1 \leq p < \infty$, $l \in \mathbb{N}$, and let Ω be a domain in \mathbb{R}^n . By $L^{l,p}(\Omega)$ we denote the space of distributions whose gradient of order l is in $L^p(\Omega)$ supplied with the norm

$$\|\nabla_l u\|_{L^p(\Omega)} + \|u\|_{L^p(\omega)},$$

where ω is a bounded subdomain of Ω with $\operatorname{dist}(\partial \omega, \partial \Omega) > 0$.

We call the quantities a and b equivalent if there are positive constants c_1 and c_2 such that $c_1a \leq b \leq c_2a$.

By c, C we denote different positive constants.

The Einstein summation convention is always assumed.

3. Sobolev Spaces of Integer and Fractional Orders

3.1. Isoperimetric Problem for Fractional Perimeter

Let Ω be a bounded domain with smooth boundary $\partial\Omega$ and $\alpha\in(0,1)$. The following set function was considered in [68]:

$$P_{\alpha}(\Omega) = \int_{\Omega} \int_{\mathbb{R}^n \setminus \Omega} \frac{dx \, dy}{|x - y|^{n + \alpha}}.$$

Later, $P_{\alpha}(g)$ was called the "fractional perimeter of Ω " and has attracted a lot of attention since.

By [68, Section 6], (see also [71, Section 11.10]), the best constant C in the isoperimetric inequality

$$P_{\alpha}(\Omega) \le C H_{n-1}(\partial \Omega)^{\frac{n-\alpha}{n-1}} \tag{3.1}$$

is the same as the best constant C in the functional inequality

$$\left(\int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \frac{|u(x) - u(y)|^q}{|x - y|^{n + \alpha}} dx \, dy\right)^{1/q} \le 2^{1/q} C \|\nabla u\|_{L^1(\mathbb{R}^n)},$$

where $q = n/(n - \alpha)$ and $u \in C_0^{\infty}(\mathbb{R}^n)$.

By [68, p. 333],

$$C \leq \frac{n \, v_n^{(n-1+\alpha)/n}}{\alpha(1-\alpha)} \Big(H_{n-1}(\partial B_1) \Big)^{\frac{n-\alpha}{n-1}}.$$

The constant factor on the right, although explicit, is hardly best possible.

Problem 1. Find the best value of the isoperimetric constant C in (3.1).

3.2. Strong Capacitary Inequality for Functions with Arbitrary Boundary Data

Let F be a relatively closed subset of Ω . By the capacity of F generated by the norm in $L^{l,p}(\Omega)$ we mean the set function

$$cap(F, L^{l,p}(\Omega)) = \inf\{\|u\|_{L^{l,p}(\Omega)}^p: \ u \in C^{\infty}(\Omega), \ u|_F \ge 1\}.$$
 (3.2)

Similar capacities are frequently used in potential theory, partial differential equations and theory of function spaces (see [60,69,70]).

Here is, for example, a simple application of capacity to the integral inequality

$$||u||_{L^p(\Omega,\mu)} \le c ||u||_{L^{l,p}(\Omega)},$$
 (3.3)

where $p \in (1, \infty)$, μ is a Borel measure on Ω and $u \in C^{\infty}(\Omega)$ is an arbitrary function. Take a relatively closed subset F of Ω and any function u from the above definition of $\operatorname{cap}(F, L^{l,p}(\Omega))$. Then (3.2) implies

$$\mu(F) \le C \operatorname{cap}(F, L^{l,p}(\Omega)). \tag{3.4}$$

Thus, this isocapacitary isoperimetric inequality proves to be a necessary condition for inequality (3.3).

It is easy to show that the condition (3.4) is sufficient for (3.3) provided that the so-called strong capacitary inequality

$$\int_{0}^{\infty} \operatorname{cap}(\{x \in \Omega : |u(x)| \ge t\}, L^{l,p}(\Omega)) d(t^{p}) \le c \|u\|_{L^{l,p}(\Omega)}^{p}$$
 (3.5)

holds for all $u \in C^{\infty}(\Omega)$.

For functions with zero boundary conditions inequalities of type (3.5) first appeared in [61] (see also [69] and [1]). If l=1, (3.5) holds without restrictions on Ω . However, already for l>1 the domain should satisfy some regularity conditions as the counterexample constructed in [80] shows (see also [83, Section 2.13]). This gives rise to the following

Problem 2. Find necessary and sufficient conditions, or only non-trivial sufficient conditions, on Ω quaranteeing the inequality (3.5).

3.3. Boundary Traces of Functions in a Sobolev Space

Let Ω be a bounded weakly Lipschitz domain and let $\varphi : \partial \Omega \to \mathbb{R}^1$.

It is well-known that φ is the trace of a function in $L^{1,p}(\Omega)$, if and only if $\varphi \in L^1(\partial\Omega)$ for p=1 and $\varphi \in L^{1-1/p,p}(\partial\Omega)$ for p>1, where the Besov space $L^{\alpha,p}(\partial\Omega)$, $0<\alpha<1$, is supplied with the seminorm

$$\left(\int_{\partial\Omega}\int_{\partial\Omega}|\varphi(x)-\varphi(y)|^p\frac{ds_x\,ds_y}{|x-y|^{n+\alpha p-2}}\right)^{1/p}.$$

This fact fails if Ω is not weakly Lipschitz. Other characterizations of the trace are given for some classes of non-Lipschitz domains in [83, Chapter 6].

Problem 3. Justify the following conjecture concerning an "extremal length" characterization of traces for an arbitrary domain Ω : The function φ is the trace of a function in $L^{1,p}(\Omega)$ if and only if there exists a function $\rho \in C(\Omega) \cap$

¹For the notion "extremal length" see [17].

 $L^p(\Omega)$ such that for "quasi-every" pair of points $x^{'}$ and $x^{''}$ on $\partial\Omega$ and for any locally rectifiable arc $\gamma \subset \Omega$ joining $x^{'}$ and $x^{''}$ there holds the inequality

$$\left|\varphi(x^{'})-\varphi(x^{''})\right|\leq \int_{\gamma}\rho(x)\,|dx|.$$

By "quasi-everywhere" one means outside of a set of zero $L^{1,p}$ -capacity.

3.4. Embedding of a Sobolev Space into the Space of Distributions

Let Ω be an open set in \mathbb{R}^n . By $L_0^{l,p}(\Omega,\mu)$ we denote the completion of $C_0^{\infty}(\Omega)$ in the norm

$$\|\nabla_l u\|_{L^p(\Omega)} + \left(\int_{\Omega} |u|^p d\mu\right)^{1/p},$$

where $p \in [1, \infty]$ and μ is a measure.

The question of embedding $L_0^{l,p}(\Omega,0)$ into the distribution space $[C_0^{\infty}(\Omega)]'$ is completely solved in [23] for p=2 and by [69, Theorem 15.2] for all values of p.

Problem 4. Find necessary and sufficient conditions on the measure μ ensuring the embedding of $L_0^{l,p}(\Omega,\mu)$ into $[C_0^{\infty}(\Omega)]'$.

3.5. An Approximation Problem in the Theory of Sobolev Spaces

Lewis [43] showed that $C^{\infty}(\overline{\Omega})$ is dense in $L^{1,p}(\Omega)$ if Ω is an arbitrary Jordan domain in the plane, i.e. $\partial\Omega$ is homeomorphic to ∂B_1 . In [44] he asked if $C^{\infty}(\overline{\Omega})$ is dense in $L^{l,p}(\Omega)$ with l > 1 for every Jordan domain $\Omega \subset \mathbb{R}^2$.

It is almost obvious that $L^{\infty}(\Omega) \cap L^{1,p}(\Omega)$ is dense in $L^{1,p}(\Omega)$ for every open set $\Omega \subset \mathbb{R}^n$. A direct extension of this property for $L^{l,p}(\Omega)$ with l > 1 is impossible, as shown in [80]. A planar domain Ω in the counterexample proposed in [80] is not Jordan, which gives rise to the following

Problem 5. Are bounded functions belonging to $L^{l,p}(\Omega)$, l > 1, dense in $L^{l,p}(\Omega)$ if Ω is an arbitrary Jordan domain?

3.6. Extensions of Sobolev Functions Outside of an Angle

Let A_{α} denote the angle $\{z \in \mathbb{C} : 0 < \arg z < \alpha\}$, $0 < \alpha < 2\pi$, and let \mathcal{E}_{α} be the extension operator $L^{1,2}(A_{\alpha}) \to L^{1,2}(\mathbb{R}^2)$ which has the least norm. Using the Radon transform, one can show that

$$\|\mathcal{E}_{\alpha}\| = \max\left\{ \left(\frac{\alpha}{2\pi - \alpha}\right)^{1/2}, \left(\frac{2\pi - \alpha}{\alpha}\right)^{1/2} \right\}.$$

Problem 6. Find the least norm of the extension operator $W^{1,2}(A_{\alpha}) \to W^{1,2}(\mathbb{R}^2)$, where

$$\|u\|_{W^{1,2}(\Omega)} = \left(\|\nabla u\|_{L^2(\Omega)}^2 + \|u\|_{L^2(\Omega)}^2\right)^{1/2}.$$

3.7. Best Constants in Some Classical Inequalities

Consider the inequality

$$\int_{\partial B_1} |u(x)|^2 d\omega \le C \int_{B_1} |\nabla u|^2 dx, \tag{3.6}$$

where B_1 is the open unit ball in \mathbb{R}^n , n > 2, $d\omega$ is an element of the surface area on the sphere ∂B_1 , and u is an arbitrary $C^{0,1}$ (Lipschitz) function given on $\overline{B_1}$ that vanishes on a closed subset F of $\overline{B_1}$. This inequality holds if and only if the harmonic (Wiener) capacity $\operatorname{cap}(F)$ is positive, where the Wiener capacity is defined as follows

$$\operatorname{cap}(F) = \inf \left\{ \int_{\mathbb{R}^n} |\nabla v|^2 dx : \ v \in C^{0,1}(\mathbb{R}^n), \ v \ge 1 \text{ on } F \right\}.$$

The following assertion containing an explicit value of C in (3.6) was obtained in [51], see also [91].

Let $u \in C^{0,1}(\overline{B_1})$, u = 0 on F, where $F \subset \overline{B_1}$. Then

$$\int_{\partial B_1} |u(x)|^2 d\omega \le \frac{c_n}{\operatorname{cap}(F)} \int_{B_1} |\nabla u|^2 dx, \tag{3.7}$$

where

$$c_n = 2(n-1)nv_n. (3.8)$$

Various inequalities related to (3.7) have interesting applications to the theory of partial differential equations and were studied from different points of view in [71] and elsewhere. However, the question of sharp constants has never been addressed. Therefore, it seems reasonable to formulate the problem.

Problem 7. Find the best value of c_n in (3.7).

3.8. Hardy Inequality with Capacitary Distance to $\partial\Omega$

Let Ω be a domain in \mathbb{R}^n , n > 2. As is well-known, the Hardy inequality

$$\int_{\Omega} \left(\frac{|u(x)|}{d(x)}\right)^2 dx \le c \int_{\Omega} |\nabla u|^2 dx,\tag{3.9}$$

where $u \in C_0^{\infty}(\Omega)$ and d(x) is the distance from x to $\partial\Omega$, does not hold for any domain and conditions for its validity are known (see [69, p. 733–735] for references).

Problem 8. Prove that (3.9) holds for any domain Ω if d(x) is replaced by the capacitary distance defined by

$$d_{\alpha}(x) = \inf \{ r > 0 : \operatorname{cap}(B_r(x) \backslash \Omega) \ge \alpha \operatorname{cap}(B_r) \},$$

where α is a positive parameter and cap denotes the Wiener capacity defined in the previous subsection.

3.9. Uncertainty Principle for Divergence-Free Fields

The inequality

$$\left(\int_{\mathbb{R}^1} u^2 dx\right)^2 \le 4 \left(\int_{\mathbb{R}^1} x^2 \, u^2 dx\right) \left(\int_{\mathbb{R}^1} (u')^2 dx\right)$$

is the so-called uncertainty principle in quantum mechanics, and the constant 4 is sharp.

Problem 9. What is the best constant C > 0 in the inequality

$$\left(\int_{\mathbb{R}^n} |\mathbf{u}|^2 dx\right)^2 \le C\left(\int_{\mathbb{R}^n} |x|^2 |\mathbf{u}|^2 dx\right) \left(\int_{\mathbb{R}^n} |\nabla \mathbf{u}|^2 dx\right),$$

where $\mathbf{u} = (u_1, \dots, u_n)$ is an arbitrary divergence-free vector field? Answer the same question concerning the inequality

$$\left(\int_{\mathbb{R}^n} |\mathbf{u}|^p dx\right)^2 \le C_p \left(\int_{\mathbb{R}^n} (|x| |\mathbf{u}|)^{p/(p-1)} dx\right)^{p-1} \left(\int_{\mathbb{R}^n} |\nabla \mathbf{u}|^p dx\right),$$

where $p \in (1, \infty)$ and div $\mathbf{u} = 0$ in \mathbb{R}^n .

3.10. Normalization of an Anisotropic Riesz Potential Space

Let $1 and let <math>\mathbf{l} = (l_1, \dots, l_n)$, where $0 < l_i < 1$. By $L^{\mathbf{l},p}(\mathbb{R}^n)$ we denote the generalization of the classical Riesz potential space normed by

$$\|\mu(D) u\|_{L^p(\mathbb{R}^n)},$$

where $\mu(D)$ is the pseudodifferential operator with symbol

$$\mu(\lambda) = \sum_{i=1}^{n} |\lambda_i|^{l_i}.$$

It is shown in [48] (see also [24]) that the space $L^{1,2}(\mathbb{R}^n)$ can be endowed with the norm $||D^{1,2}u||_{L^2(\mathbb{R}^n)}$, where

$$(D^{1,2})u(x) = \left(\int_{\mathbb{R}^n} |u(x+z) - u(x)|^2 \left(\sum_{i=1}^n |z_i|^{l_i} \right)^{-\delta} dz \right)^{1/2}$$

with

$$\delta = 2 + \sum_{i=1}^{n} l_i^{-1}.$$

This norm is useful in applications such as the description of multipliers in $L^{1,2}(\mathbb{R}^n)$ and the theory of Dirichlet forms.

Problem 10. For $p \neq 2$ find an analog of the just mentioned representation of the norm in $L^{1,p}(\mathbb{R}^n)$ involving the difference u(x+z) - u(x).

Remark. Strichartz [101] supplied the space of isotropic Riesz potentials with the norm $||S_l u||_{L^p(\mathbb{R}^n)}$, where

$$(S_l u)(x) = \left(\int_0^\infty \left[\int_{|z| < y} |u(x+z) - u(x)| \, dz \right]^2 \frac{dy}{y^{1+2(n+l)}} \right)^{1/2}.$$

3.11. Two-Weight Hardy Inequality Involving First and Second Derivatives

Let $p \ge 1$ and let $\gamma \ne 1 - 2/p$. By ψ we denote a function in $C_0^{\infty}(\mathbb{R}^2)$. In case $\gamma < 1 - 2/p$ we require additionally that $\nabla \psi(0) = 0$.

Problem 11. Find the best constant in the inequality

$$\int_{\mathbb{R}^2} |\nabla \psi|^p |x|^{p(\gamma-1)} dx \le C(p,\gamma) \int_{\mathbb{R}^2} (\psi_{x_1 x_1}^2 + 2\psi_{x_1 x_2}^2 + \psi_{x_2 x_2}^2)^{p/2} |x|^{p\gamma} dx.$$

It is proved in [10] (see also [69, p. 229]) that when p = 2,

$$C(2,\gamma) = \begin{cases} \frac{1 + (1-\gamma)^2}{\gamma^2 (3 + (1-\gamma)^2)} & \text{for } \gamma \in [-\sqrt{3} - 1, \sqrt{3} - 1], \\ (\gamma^2 + 1)^{-1} & \text{otherwise.} \end{cases}$$

The method used in the proof of this result cannot be applied to the case $p \neq 2$.

3.12. Trace Inequality with a Non-Positive Measure

Let Ω be a bounded smooth domain in \mathbb{R}^n and let σ be a real measure, not necessarily positive, even a distribution, supported on $\partial\Omega$.

Problem 12. Let n > p > 1 and let u be any function in $C^{\infty}(\overline{\Omega})$. Find necessary and sufficient condition on σ for the validity of the inequality

$$\inf_{c \in \mathbb{R}^1} \int_{\partial \Omega} |u - c|^p d\sigma \le C \int_{\Omega} |\nabla u(x)|^p dx.$$

A similar problem for the inequality

$$\int_{\Omega} |u|^p d\sigma \le C \int_{\Omega} |\nabla u(x)|^p dx$$

with σ supported on Ω was solved in [25] for p=2 and in [26] for an arbitrary p>1.

3.13. Domains for Which $L^{l,p}(\Omega) \cap L^{\infty}(\Omega)$ is a Banach Algebra

Let Ω be a domain in \mathbb{R}^n . We may ask whether the space $L^{l,p}(\Omega) \cap L^{\infty}(\Omega)$ is an algebra with respect to pointwise multiplication. Clearly, this is the case for l=1. Since Stein's extension operator from a Lipschitz graph domain Ω is continuous as an operator

$$L^{l,p}(\Omega) \cap L^{\infty}(\Omega) \to L^{l,p}(\mathbb{R}^n) \cap L^{\infty}(\mathbb{R}^n),$$

the above question has the affirmative answer for the union of a finite number of Lipschitz graph domains. For example, Ω can be a bounded domain having the cone property. However, by a counterexample proposed in [80] (see also [69, p. 120–121]), it turns out that the space $L^{l,p}(\Omega) \cap L^{\infty}(\Omega)$ is generally not an algebra.

Problem 13. Find a necessary and sufficient condition on $\Omega \subset \mathbb{R}^n$ ensuring that $L^{l,p}(\Omega) \cap L^{\infty}(\Omega)$ is a Banach algebra.

Remark. One can easily check that $W^{2,p}(\Omega) \cap L^{\infty}(\Omega)$ is an algebra with respect to the pointwise multiplication if and only if $W^{2,p}(\Omega) \cap L^{\infty}(\Omega)$ is imbedded into $W^{1,2p}(\Omega)$.

4. Integral Operators

4.1. A Multi-Dimensional Integral Equation Which can be Reduced to One-Dimensional

Let φ and ψ be functions defined on a multi-dimensional domain Ω .

Problem 14. Develop a theory of solvability of the integral equation

$$\lambda u(x) - \int_{\Omega} \frac{u(y)}{\varphi(x) - \psi(y)} dy = f(x), \tag{4.1}$$

where f is a given function and λ is a complex parameter.

Note that (4.1) can be reduced to a certain one-dimensional integral equation by using the so-called coarea formula, see [69].

4.2. A Singular Integral Operator in $L^p(\mathbb{R}^n)$

Consider the singular integral operator A with the symbol

$$\partial B_1 \ni \omega \to \exp(i \lambda \phi(\omega)),$$

where ϕ is a smooth real-valued function on ∂B_1 , and λ is a large real parameter.

Problem 15. Prove or disprove the estimate

$$||A||_{L^p(\mathbb{R}^n) \to L^p(\mathbb{R}^n)} \le c |\lambda|^{(n-1)\left|\frac{1}{2} - \frac{1}{p}\right|},$$

where $1 , c depends on n, p and the function <math>\phi$.

4.3. Fredholm Radius of the Harmonic Double Layer Potential

Considering the logarithmic harmonic potentials of the single and double layer on curves of "bounded rotation", J. Radon has introduced the notion of the essential norm and the Fredholm radius of a bounded operator in 1919.

The essential norm ||L|| of a linear bounded operator L acting on a Banach space \mathcal{B} is defined as

$$||L|| = \inf_{\{\mathcal{K}\}} ||L - \mathcal{K}||_{\mathcal{B} \to \mathcal{B}},$$

where $\{\mathcal{K}\}$ is the set of all linear compact operators on \mathcal{B} .

The Fredholm radius $\mathcal{R}(L)$ of the operator L is the radius of the largest circle on the complex λ -plane centered at $\lambda=0$ inside which $I+\lambda L$ is a Fredholm operator.

The essential norm ||L|| is related to $\mathcal{R}(L)$ by the inequality

$$\mathcal{R}(L) \ge ||L||^{-1}.$$

It was shown by Gohberg and Marcus [20] that the Fredholm radius of the operator L, acting on a Banach space \mathcal{B} equipped with the norm $\|\cdot\|_0$, satisfies

$$\mathcal{R}(L) = \sup \{ ||L||^{-1} : ||\cdot|| \in \mathcal{N}(||\cdot||_0) \},$$

where ||L|| is calculated with respect to a norm $||\cdot||$ in the set $\mathcal{N}(||\cdot||_0)$ of all norms in \mathcal{B} , equivalent to $||\cdot||_0$.

Král [35] and Burago and Maz'ya [5] showed that for a n-dimensional bounded domain \mathcal{D} with finite variation of the solid angle $\omega_{\mathcal{D}}(p, E)$ ($p \in \partial \mathcal{D}, E \subset \mathbb{R}^n$) the essential norm of the harmonic double layer potential in the Banach space $C(\partial \mathcal{D})$ is

$$\frac{2}{nv_n} \lim_{\delta \to 0} \sup_{p \in \partial \mathcal{D}} \operatorname{var} \omega_{\mathcal{D}}(p, B_{\delta}(p)).$$

References to other results in the same area can be found in [36, Chapter 7].

Problem 16. Find a geometrical representation for the Fredholm radius of the harmonic double layer potential as an operator in $C(\partial \mathcal{D})$.

4.4. Potential Theory for Surfaces with Cusps

A detailed theory of boundary integral equations for harmonic and elastic singe and double layer potentials on curves with exterior and interior cusps was constructed in [93].

Problem 17. Develop a theory of multidimensional boundary integral equations for domains with inner and outer cusps.

First results concerning the multidimensional case can be found in [84–86].

4.5. Regularity of Domains in the Theory of Boundary Integral Equations

In [90] (see also [88, Chapter 15]) a regularity theory of classical boundary integral equations involving harmonic, elastic and hydrodynamic potentials on nonsmooth surfaces is presented. A goal of this theory is to establish solvability in fractional Besov spaces.

Problem 18. Obtain results on the solvability of just mentioned equations in Sobolev spaces $L^{l,p}(\partial\Omega)$ with integer l under minimal requirements on $\partial\Omega$.

4.6. Integral Equations of Potential Theory Under Interaction of Nearly Touching Particles

The following difficulty arises when using the boundary element method to study hydrodynamic interactions among particles in suspensions and other similar phenomena when the particles are nearly touching. Integration of kernels of integral operators on elements near the closest contact points destroys the accuracy of the numerical procedure.

Problem 19. Find asymptotic representation for densities of harmonic, elastic, and hydrodynamic potentials satisfying the boundary integral equations by using the distance between particles as a small parameter.

4.7. Non-Classical Maximal Operator

Let the maximal operator M^{\Diamond} be defined by

$$(M^{\Diamond}f)(x) = \sup_{r>0} \left| \int_{B_r(x)} \frac{y-x}{|y-x|} f(y) dy \right|, \quad x \in \mathbb{R}^n,$$

where f is locally integrable in \mathbb{R}^n and the barred integral stands for the mean value. It is obviously dominated by the Hardy-Littlewood maximal operator M. A simple property of M^{\Diamond} is the sharp pointwise inequality for functions of one variable

$$|u'(x)|^2 \le \frac{8}{3} (M^{\Diamond}u)(x) (M^{\Diamond}u'')(x),$$

see [71, formula (12.0.5)].

Clearly, M^{\Diamond} is dominated by the sharp maximal operator M^{\sharp} defined by

$$(M^{\sharp}f)(x) = \sup_{r>0} \int_{B_r(x)} |f(y) - f_{B_r(x)}| dy,$$

where $f_{B_r(x)}$ stands for the mean value of f in the ball $B_r(x)$.

Problem 20. Does there exist a Banach space B such that one of the operators M^{\sharp} or M^{\Diamond} is bounded in B whereas the other operator is not bounded?

4.8. Fourier p-Capacity and Potentials

It is difficult to overestimate the role of various capacities of sets in analysis and partial differential equations.

Let us introduce the set function

$$\inf \left\{ \|\mathcal{F}u\|_{L^p(\mathbb{R}^n)}: \ u \in C_0^\infty(\mathbb{R}^n), \ u \ge 1 \text{ on } K \right\}$$
 (4.2)

where $p \in [1, \infty]$, \mathcal{F} is the Fourier transform and K is a compact set in \mathbb{R}^n . It is natural to call (4.2) the Fourier capacity of K. If p = 2, this capacity is equal to $(m_n K)^{1/2}$.

Problem 21. Find upper and lower geometrical estimates of the Fourier p-capacity. Develop a theory of Fourier p-potentials

$$\mathcal{F}^{-1}\big(|\mathcal{F}\,\mu|^{1/(p-1)}\mathcal{F}\,\mu\big),$$

where μ is a measure, in spirit of [73–75].

5. Linear Elliptic Operators

5.1. Integral Inequality for the Integrable Laplacian

It is shown in [89] that the inequality

$$\left| \int_{\mathbb{R}^2} \sum_{i,j=1}^2 a_{i,j} \, u_{x_i} \, \overline{u_{x_j}} \, dx \right| \le C \left(\int_{\mathbb{R}^2} |\Delta u| \, dx \right)^2,$$

where $a_{i,j}$ are constants and u is an arbitrary complex-valued function in $C_0^{\infty}(\mathbb{R}^2)$, holds if and only if $a_{1,1} + a_{2,2} = 0$.

Other results of a similar nature are obtained in [70], where in particular it is proved that the inequality

$$\left| \int_{\mathbb{R}^n} \sum_{j=1}^n \alpha_j \left| \frac{\partial u}{\partial x_j} \right| \left| \frac{dx}{|x|} \right| \le C \int_{\mathbb{R}^n} |\Delta u| \, dx,$$

where α_j are real constants, holds for all real-valued functions $u \in C_0^{\infty}(\mathbb{R}^n)$ if and only if

$$\sum_{j=1}^{n} \alpha_j = 0.$$

Problem 22. I conjecture that the inequality

$$\left| \int_{\mathbb{R}^n} \Phi(\nabla u) \, dx \right|^{\frac{n-1}{n}} \le \int_{\mathbb{R}^n} |\Delta u| \, dx,$$

where n > 1, Φ is a smooth function outside the origin and positive homogeneous of degree n/(n-1), holds for all $u \in C_0^{\infty}(\mathbb{R}^n)$ if and only if

$$\int_{\partial B_1} \Phi(x) \, d\omega_x = 0.$$

5.2. Hölder Regularity of a Boundary Point with Respect to an Elliptic Operator of Second Order

Let Ω be a bounded domain in \mathbb{R}^n , $n \geq 2$. We fix a non-isolated point $O \in \partial \Omega$ as the origin. Let us say that a function u defined on Ω is α -Hölder continuous at O with $\alpha > 0$ if it has a limit u(O) as $x \to O$ and there exists α such that

$$|u(x) - u(O)| \le C|x|^{\alpha}$$

for all $x \in \Omega$. Similarly, a function φ given on $\partial \Omega$ is called α -Hölder continuous at O if there is a limit $\varphi(O)$ of $\varphi(x)$ as $x \to O$, $x \in \partial \Omega$, and

$$|\varphi(x) - \varphi(O)| \le C|x|^{\alpha} \tag{5.1}$$

By u_{φ} we mean a bounded solution to the Dirichlet problem

$$Lu = 0$$
 in Ω , $u = \varphi$ on $\partial \Omega$,

where φ is a bounded Borel function on $\partial\Omega$ and

$$(Lu)(x) = \operatorname{div}(\mathcal{A}(x) \nabla u(x))$$

is a uniformly elliptic operator with a measurable symmetric coefficient matrix \mathcal{A} . Basic facts concerning solvability of this problem can be found in [45].

We introduce the *L*-harmonic measure $\mathcal{H}_L(x,\mathcal{B})$, where $x \in \Omega$ and \mathcal{B} is a Borel subset of $\partial\Omega$ (see e.g. [45, Definition 1.2.6]).

Definition. The point O is called

- (i) α -Hölder regular with respect to L if the α -Hölder continuity of φ at O implies the α -Hölder continuity of u_{φ} at O,
- (ii) Hölder regular with respect to L if there exists $\alpha > 0$ such that O is α -Hölder regular.

A necessary and sufficient condition for the Hölder regularity of O is contained in the following assertion proved in [72].

The point $O \in \partial \Omega$ is Hölder regular with respect to L if and only if, for some positive constants λ and C,

$$\mathcal{H}_L(x,\partial\Omega\backslash B_r) \le c\left(\frac{|x|}{r}\right)^{\lambda}$$
 (5.2)

for all r > 0 and $x \in \Omega \cap B_r$.

Let n > 2 and let cap denote the Wiener capacity defined in Sect. 3.7. The following condition, sufficient for the Hölder regularity of O and independent of L, was found in [52, 54, 55]:

$$\liminf_{r \to 0} \frac{1}{|\log r|} \int_{r}^{1} \operatorname{cap}(\Omega \backslash B_{\rho}) \frac{d\rho}{\rho^{n-1}} > 0.$$
(5.3)

Under additional restrictions on the domain, this condition proves to be necessary for the Hölder regularity, see [54, 104].

Clearly, (5.3) fails or works simultaneously for all operators L. However, it is not necessary for the Hölder regularity in general, see the counterexample in [66, p. 509-510]. Although (5.2) formally depends on L, it is natural to formulate the

Problem 23. Prove or disprove that the Hölder regularity of a point is independent of the operator L.

5.3. Uniqueness in the Cauchy Problem for the Laplace Equation

Let $\mathbb{R}^{n+1}_+ = \{(p,t) : p \in \mathbb{R}^n, t > 0\}$. Suppose a function $u \in C^1(\overline{\mathbb{R}^{n+1}_+} \cup \mathbb{R}^n)$ is harmonic in \mathbb{R}^{n+1}_+ and its Dirichlet data has zero of infinite order at the origin. Moreover, let the normal derivative satisfy

$$\left| \frac{\partial u}{\partial t}(p) \right| \le h(|p|), \quad p \in \mathbb{R}^n,$$
 (5.4)

where h is a function defined on $[0, \infty)$ positive on $(0, \infty)$ and such that $h(r) \downarrow 0$ as $r \downarrow 0$. One can ask for which h it is true that (5.4) implies u = 0.

The following answer to this question was obtained in [76].

Suppose h satisfies certain regularity conditions (not to be specified here), then (5.4) implies u=0 if and only if

$$\int_0^1 \log h(r) \, dr = -\infty. \tag{5.5}$$

By Kelvin's transform, the criterion (5.5) can be stated for harmonic functions in a ball. However, the method of proof given in [76] does not provide an answer to the following question.

Problem 24. Is it possible to replace \mathbb{R}^{n+1}_+ in the above exposition by a smooth domain? Also, can one replace the Laplace operator by an arbitrary second order elliptic operator with smooth coefficients?

In this case, it is only known that the uniqueness follows from the estimate

$$|\nabla u(x)| \le \exp(-1/|x|^c)$$

with a certain positive c (see [39]) and with $c = 2 + \varepsilon$, $\varepsilon > 0$, (see [41]).

5.4. De Giorgi-Nash Theorem for Equations with Complex-Valued Coefficients

Let Ω be a domain in \mathbb{R}^n . By the classical De Giorgi–Nash theorem, an arbitrary weak solution of the uniformly elliptic equation

$$\frac{\partial}{\partial x_i} \left(a_{ij}(x) \frac{\partial u}{\partial x_j} \right) = 0, \qquad 1 \le i, j \le n$$

with measurable bounded real-valued coefficients is locally Hölder continuous. If the coefficients a_{ij} are complex-valued and

$$\operatorname{Re}\left(a_{ij}(x)\xi_{i}\overline{\xi_{j}}\right) \geq C|\xi|^{2},$$

for all $x \in \Omega$ and $\xi \in \mathbb{R}^n$, this assertion is not true for dimensions n > 4. See [95, p. 391–393] for examples of equations whose weak solutions are even unbounded near an interior point of a domain.

Problem 25. Prove or disprove that De Giorgi-Nash property holds for dimensions n = 3 and n = 4.

The Hölder continuity of u in the case n=2 follows from [94].

5.5. Fractal Domains Versus Lipschitz Domains

During the last fifty years considerable progress has been made in the study of elliptic boundary value problems on Lipschitz graph domains (see [27] for a survey of this development). In particular, classes of solvability and estimates of solutions received considerable attention in this area.

A Lipschitz graph domain is locally given by

$$\{x = (x', x_n) \in \mathbb{R}^n, \quad x_n > \varphi(x')\},\$$

where φ satisfies the Lipschitz condition. Replacing here Lipschitz condition by Hölder condition, we arrive at the definition of a Hölder graph domain.

With the existing rich theory of boundary value problems in Lipschitz graph domains, the absence of similar results in Hölder graph domains seems ubiquitous.

Problem 26. Address this issue.

5.6. Dirichlet Problem in a Planar Jordan Domain

Let u be a variational solution of the Dirichlet problem with zero boundary data for the equation

$$\mathcal{L}_{2m}(D_x) u = f \tag{5.6}$$

in Ω , where Ω is an arbitrary bounded Jordan domain in \mathbb{R}^2 (see Sect. 3.5), $f \in C_0^{\infty}(\Omega)$ and \mathcal{L}_{2m} is a strongly elliptic operator with real constant coefficients.

Problem 27. Prove that the solution satisfies

$$\int_{\Omega} |\nabla_m u|^{4-\varepsilon} dx < \infty \tag{5.7}$$

for every small $\varepsilon > 0$.

This problem is unsolved even for the case of the Laplace operator which is related to Brennan's conjecture [7].

Inequality (5.7) holds for an arbitrary piecewise smooth domain without cusps, see [33, Chapter 9] and [87, Chapter 4].

5.7. Hölder Regularity of Capacitary Potential of n-Simensional Cube

It can be easily proved by a barrier argument that the harmonic capacitary potential of the cube $\{x: 0 \le x_i \le 1, i = 1,...,n\}$ belongs to a certain Hölder class $C^{\alpha(n)}$, $0 < \alpha(n) < 1$, which gives rise to the following

Problem 28. Describe the asymptotic behaviour of $\alpha(n)$ as $n \to \infty$.

5.8. Non-Lipschitz Graph Domains Which are Weakly Lipschitz

Recall that open sets, locally Lipschitz diffeomorphic to a half-space, are called weak Lipschitz domains. One can easily construct cones with boundary smooth outside the vertex and polyhedra which are not Lipschitz graph domains (see [33, p. 4]).

Problem 29. Do the known results on elliptic equations in Lipschitz graph domains (see [27] and references therein) extend to arbitrary weakly Lipschitz domains?

It seems, there are no counterexamples to this question and some results concerning non-Lipschitz graph cones suggest the affirmative answer to it, see [33,87].

5.9. Self-Adjointness of the Laplacian in a Weighted L^2 -Space

Let $\rho \in L^1_{loc}(\mathbb{R}^n)$, $\rho > 0$, and let

$$L^{2}(\rho) = \left\{ u : \int_{\mathbb{D}_{n}} |u(x)|^{2} \rho(x) dx < \infty \right\}.$$

In 1990 Eidus [14] proved that for $n\geq 3$ a necessary condition for the operator $\rho^{-1}\Delta$ in $L^2(\rho)$ to be self-adjoint is

$$\int_{\mathbb{R}^n} \rho(x) \, dx = \infty. \tag{5.8}$$

One can replace (5.8) by

$$\int_{\mathbb{R}^n \setminus F} \rho(x) \, dx = \infty \tag{5.9}$$

for all closed sets F with finite harmonic capacity (see [71, Section 17.1]).

Problem 30. Show that (5.9) is not sufficient and find a sharp sufficient condition for the self-adjointness of $\rho^{-1}\Delta$ in $L^2(\rho)$.

5.10. Peculiarities of Planar \mathbb{C}^1 Domains and Extensions of the Dirichlet Laplacian

By $L_0^{1,2}(\Omega)$ we denote the completion of $C_0^{\infty}(\Omega)$ in the norm of $L^{1,2}(\Omega)$. By $\overline{\Delta}$ we denote the closure of the Laplacian $\Delta: L^{2,2}(\Omega) \cap L_0^{1,2}(\Omega) \to L^2(\Omega)$. Let $\widetilde{\Delta}$ be the Friedrichs extension of Δ and let Δ^* denote the adjoint of Δ . It is well known that $\Delta = \overline{\Delta} = \widetilde{\Delta} = \Delta^*$, if Ω is sufficiently smooth. This is not true in general if Ω is not in the class C^2 .

The following result was obtained in [56,63].

Let $\omega(r)$ be the angle measure of $\{x \in \Omega : |x| = r\}$, where $O \in \partial\Omega$ and $\Omega \subset \mathbb{R}^2$. If $\partial\Omega\setminus\{O\}$ is smooth and

$$\int_0^1 \exp\left(\frac{2}{\pi} \int_0^1 \frac{\pi - \omega(r)}{r} dr\right) \frac{d\rho}{\rho} = \infty,$$

then $\overline{\Delta} = \tilde{\Delta}$. This condition is also necessary under some additional restrictions.

Here are two surprising consequences of the above statement.

(i) There exists a planar C^1 domain Ω such that the closure of Δ is self-adjoint, but the estimate

$$||u||_{L^{2,2}(\Omega)} \le C||\Delta u||_{L^{2}(\Omega)} \tag{5.10}$$

does not hold for all u in the domain of $\tilde{\Delta}$, i.e. $\overline{\Delta} = \tilde{\Delta}$ but $\Delta \neq \overline{\Delta}$.

(ii) The closure of the operator $(1+\varepsilon)$ $\partial_{x_1}^2 + \partial_{x_2}^2$, $\varepsilon > 0$, can be non-selfadjoint whilst for the same Ω , the generalized solution $u \in L_0^{1,2}(\Omega)$ of the equation $\Delta u = f$ satisfies (5.10) and, consequently, $\Delta = \overline{\Delta} = \widetilde{\Delta}$.

Example. Let

$$\Omega = \left\{ x \in B_1 : \ x_2 > \frac{-C|x_1|}{|\log|x_1||} \right\} \subset \mathbb{R}^2,$$

where C is a positive constant. Then

$$\begin{split} &\Delta = \overline{\Delta} = \widetilde{\Delta} & \text{if and only if} \quad C < \pi/4, \\ &\Delta \neq \overline{\Delta}, \ \overline{\Delta} = \widetilde{\Delta} & \text{if and only if} \quad C = \pi/4, \\ &\Delta \neq \overline{\Delta}, \ \text{ind} \ \overline{\Delta} = 1 & \text{if and only if} \quad C > \pi/4. \end{split}$$

These isolated phenomena were studied only for the particular case n=2 and the Laplace–Dirichlet operator

Problem 31. Obtain similar results for various extensions of elliptic differential operators under minimal restrictions on Ω and the coefficients.

Concerning the index of elliptic boundary value problems in domains with angle and cone vertices see [15,82].

5.11. Pointwise Estimates for Polyharmonic Green's Functions

Let Ω be an arbitrary domain in \mathbb{R}^n . Green's function of Δ^m is a solution of

$$\Delta_x^m G_m(x,y) = \delta(x-y), \quad x,y \in \Omega,$$

subject to zero Dirichlet conditions for $x \in \partial \Omega$. Here δ is the Dirac function.

Problem 32. Let n > 2m. Prove or disprove that

$$|G_m(x,y)| \le \frac{c(m,n)}{|x-y|^{n-2m}}, \quad x,y \in \Omega, \ x \ne y,$$

where c(m,n) does not depend on Ω .

This estimate is known for the dimensions n = 5, 6, 7 if m = 2 and n = 2m + 1, 2m + 2 if m > 2, see [67].

5.12. Boundedness of Solutions to the Polyharmonic Equation in Arbitrary Domains

Let Ω be an arbitrary bounded domain in \mathbb{R}^n and suppose n > 2m + 2 if m > 2 and $n \ge 8$ if m = 2.

Problem 33. Prove or disprove that the variational solution of the equation

$$\Delta^m u = f, \qquad f \in C_0^{\infty}(\Omega),$$

subject to zero Dirichlet boundary conditions is in $L^{\infty}(\Omega)$.

This is true for the dimensions listed at the end of the previous subsection (see [67]) and fails for the operator

$$\Delta_x^2 + 10 \frac{\partial^4}{\partial x_8^4}$$

with $x = (x_1, \dots, x_8)$, see [78].

5.13. Polyharmonic Capacitary Potentials

Let $m=1,2,\ldots$ The *m*-harmonic capacity of a compact set F in \mathbb{R}^n is defined by

$$\begin{split} \operatorname{cap}_m(F) &= \inf \Big\{ \sum_{|\alpha| = m} \frac{m!}{\alpha!} \|\partial^\alpha u\|_{L^2(\mathbb{R}^n)}^2: \ u \in C_0^\infty(\Omega), \\ u &= 1 \ \text{in a neigborhood of } F \Big\} \end{split} \tag{5.11}$$

was introduced in [50] (see also [53]) and proved to be useful in the theory of higher order elliptic equations. It is well-known that $cap_m(F) = 0$ for all compact sets F if $2m \ge n$.

Let n > 2m. One of the definitions of the potential-theoretic Riesz capacity of order 2m is as follows:

$$R_{2m}(F) = \inf \Big\{ \sum_{|\alpha|=m} \frac{m!}{\alpha!} \|\partial^{\alpha} u\|_{L^{2}(\mathbb{R}^{n})}^{2} : u \in C_{0}^{\infty}(\mathbb{R}^{n}), u \ge 1 \text{ on } F \Big\}.$$
 (5.12)

The capacities $cap_m(F)$ and $R_{2m}(F)$ are equivalent, that is their ratio is bounded and separated from zero by positive constants depending only on n and m (see [57,62] and [71, Section 13.3]).

The minimizer in R_{2m} is a Riesz potential of a measure whereas that in cap_m is a Riesz potential of a distribution. The last minimizer will be denoted by U_F . By [67], for the dimensions n = 5, 6, 7 if m = 2 and n = 2m+1, 2m+2 if m > 2, the inequalities

$$0 < U_F(x) < 2 (5.13)$$

hold for all $x \in \mathbb{R}^n \backslash F$. In general, the constant 2 cannot be replaced by 1.

Problem 34. Is it possible to extend (5.13) for dimensions $n \ge 8$ if m = 2, and $n \ge 2m + 3$ for m > 2? Another question: is the constant 2 in (5.13) best possible?

5.14. Subadditivity of the Polyharmonic Capacity

Let $cap_m(F)$ and $R_{2m}(F)$ be the capacities defined by (5.11) and (5.12). By the classical potential theory, the Riesz capacity R_{2m} is upper subadditive. However, the following problem is open.

Problem 35. Prove or disprove that the m-harmonic capacity cap_m is upper subadditive.

5.15. Normal Derivative of a Harmonic Function at a Boundary Point

Let a δ -neighborhood of the origin $O \in \partial \Omega$ be given by the inequality $x_n > \varphi(x')$, where φ is a Lipschitz function of the variable $x' \in \mathbb{R}^{n-1}$, $\varphi(0) = 0$. We assume that the function

$$\omega(r) = \sup_{|x'| < r} \, \left| \nabla \varphi(x') \right|$$

satisfies

$$\int_{0}^{\delta} \frac{\omega^{2}(r)}{r} dr < \infty. \tag{5.14}$$

Consider also the condition

$$\int_{|\xi|<\delta} \varphi(\xi) \frac{d\xi}{|\xi|^n} < \infty, \tag{5.15}$$

where the integral is improper.

The following property of harmonic functions appeared in mathematical literature at the end of the XIX century: if a harmonic function takes its minimum value at O, then its inner normal derivative at O is strictly positive.

Problem 36. Prove that under the a priori requirement (5.14), the condition (5.15) is necessary and sufficient for the validity of the just formulated property of harmonic functions.

Note that (5.15) is much weaker than the Dini condition

$$\int_0^\delta \frac{\omega(r)}{r} \, dr < \infty$$

which previously appeared in the same context (see [2], where other references can be found).

Remark. One possible approach is to use the asymptotic formula for harmonic functions near the Lipschitz boundary established in [30].

5.16. Essential Spectrum of a Perturbed Polyharmonic Operator

Consider the selfadjoint operator L in $L^2(\mathbb{R}^n)$ generated by the differential expression

$$\left(-\Delta\right)^m + q(x),$$

where q is a locally integrable nonnegative function in \mathbb{R}^n .

Problem 37. Let m > 1 and $2m \le n$. Is it true that either the essential spectrum of L coincides with the half-axis $\lambda \ge 0$, or the point $\lambda = 0$ does not belong to the spectrum of L?

This "spectral alternative" was established by Putnam [98] for n = 1, m = 1, by Glazman [19] for $n \ge 1$, m = 1, and by Yafaev [107] for 2m > n.

5.17. Singularity of Green's Function for Second Order Elliptic Equations with Lower Order Terms

It is well-known that Green's function G(x, y) of the uniformly elliptic operator

$$Lu = -\frac{\partial}{\partial x_i} \left(a_{ij}(x) \frac{\partial u}{\partial x_j} \right), \quad n > 2,$$

with measurable bounded coefficients is equivalent to $|x - y|^{2-n}$ near the point y (see [45,99]).

Problem 38. Find necessary and sufficient conditions for the coefficients b_1, \ldots, b_n and c preserving the equivalence of $|x-y|^{2-n}$ and Green's function of the operator

$$u \to Lu + b_i(x) \frac{\partial u}{\partial x_i} + c(x) u.$$

5.18. Generic Degenerating Oblique Derivative Problem

Oblique derivative problem consists in determining solutions of the second order elliptic equation in a domain $\Omega \subset \mathbb{R}^n$ subject to the boundary condition

$$\frac{\partial u}{\partial l} = f \quad \text{on } \partial \Omega,$$

where l denotes a field of unit vectors on $\partial\Omega$. The corresponding boundary pseudodifferential operator is elliptic if and only if l is nowhere tangent to $\partial\Omega$. In the non-elliptic case the oblique derivative problem is called degenerate.

Around 1970 Arnold [3] stressed the importance of the so-called *generic* case of degeneration, where the vector field l is tangent to $\partial\Omega$ on a submanifold of codimention 1 and is not transversal to this submanifold (see also his well-known book [4, Section 29]).

In [4, Section 29] Arnold writes:

"One of the simplest problems of such a calculation of infinite codimensions corresponding to kernels and cokernels consisting of functions on manifolds of different dimensions is the oblique derivative problem. If we consider this problem on the sphere bounding an *n*-dimensional ball, a vector field tangent to the n-dimensional ambient space is given. A function harmonic in the ball is to be determined whose derivative in the direction of the field is equal to a given boundary function.

We consider, for example, the case n=3. In this case, a generic field is tangent to the sphere on some smooth curve. There are singular points on this curve where the field is tangent to the curve itself. The structure of the field in the neighborhood of each of these singular points is standard: it can be proved that for any n of a generic field in the neighborhood of every point of the boundary, the field is given, in an appropriate coordinate system, by a formula of the form

$$x_2\partial_1 + x_3\partial_2 + \dots + x_k\partial_{k-1} + \partial_k, \qquad k \le n,$$

where $\partial_j = \partial/\partial x_j$ and $x_1 = 0$ on the boundary (cf. S.M. Višik, On the oblique derivative problem, Vestnik MGU, Ser. Mathem. 1 (1972), 21–28).

The oblique derivative problem apparently has to be stated according to the following scheme. The manifold of tangency of the field with the boundary, the manifold of the tangency of the field with the tangency manifolds, etc. divide the boundary into parts of various dimensions. On some of these parts of the boundary, conditions have to be given: on some other parts, the boundary function itself has to satisfy certain conditions for the existence of the classical solution of the problem."

In 1972 [59] I published a result related to the generic degeneration, still the only known one. I assumed that there are smooth manifolds

$$\Gamma_0 \supset \Gamma_1 \ldots \supset \Gamma_s$$

of dimensions $n-2, n-3, \ldots, n-2-s$ such that l is tangent to Γ_j exactly at the points of Γ_{j+1} , whereas l is nowhere tangent to Γ_s . A local model of this situation is given by the following:

$$\Omega = \{x \in \mathbb{R}^n : x_1 > 0\}, \qquad \Gamma = \{x_1 = 0\},$$

$$l = x_2 \partial_1 + x_3 \partial_2 + \dots + x_k \partial_{k-1} + \partial_k, \qquad k \le n,$$

$$\Gamma_j = \{x_1 = x_2 = \dots = x_{2+j} = 0\}, \quad j = 0, \dots, k-2.$$

Some function spaces of the right-hand side and solutions ensuring the unique solvability of the problem are found in [59]. The success was achieved by a choice of weight functions in the derivation of a priori estimates for the solution. Additionally, I proved that the inverse operator of the problem is always compact on $L^p(\Gamma)$, 1 . It turned out that the tangent manifolds of codimension greater than one do not influence the correct statement of the problem, contrary to Arnold's expectations.

However, the following problem is still unsolved.

Problem 39. Describe the asymptotic behaviour of solutions near the points of tangency of the field l. In particular, it seems challenging to find asymptotics near the point of Γ_1 whose neighbourhood contains both points of entrance and exit of the field l with respect to Γ .

More generally, it would be interesting to obtain regularity results for strong solutions of the generic degenerating problem.

5.19. Matrix Generalization of the Oblique Derivative Problem

Let Ω be a domain in \mathbb{R}^n . Consider the Laplace equation $\Delta \mathbf{u} = 0$ in Ω , where \mathbf{u} is a k-dimensional vector field, and add the condition

$$\sum_{i=1}^{n} A_i(x) \frac{\partial \mathbf{u}}{\partial x_i} = \varphi(x) \quad \text{on } \partial \Omega,$$

where $\{A_i\}_{1 \le i \le n}$ is a collection of $k \times k$ matrix function.

Problem 40. Develop a theory of solvability of the boundary value problem above in the case when the corresponding pseudodifferential operator on $\partial\Omega$ is not elliptic. An interesting particular case is the boundary condition

$$(\mathbf{a} + i\,\mathbf{b}) \cdot \nabla u = \varphi,$$

where **a** and **b** are real vector fields and u is a complex-valued scalar function.

5.20. Coercive Weighted Estimates for Elliptic Equations in Domains with Inner Cusps

Consider the Dirichlet problem for an arbitrary elliptic equation of order 2m in a domain $\Omega \subset \mathbb{R}^n$ with inner cusp. Two-sided estimates for derivatives of order 2m of solutions were obtained in [32, Chapter 10] with n > 2m + 1.

Problem 41. Obtain estimates of the same nature for $n \leq 2m + 1$.

5.21. Multiplicative Inequality for the Linear Elasticity System in an Arbitrary Domain

One of the theorems obtained in [47] reads as follows:

Let Ω be a three-dimensional domain and let $\mathcal L$ denote the Lamé operator defined by

$$\mathcal{L}u = -\Delta u - \alpha \nabla \operatorname{div} u$$
.

where $\alpha = 1/(1-2\nu) > -1$ and ν is the Poisson's ratio. Let 1 < q < 3, p = q/(q-1) and let $L_0^{1,q}(\Omega)$ stand for the completion of $C_0^{\infty}(\Omega)$ in the Sobolev space $L^{1,q}(\Omega)$. By [47], the condition

$$\alpha \in (\alpha_-, \alpha_+) \approx (-0.194, 1.524),$$
(5.16)

implies the inequality

$$||u||_{L^{\infty}(\Omega)} \le C ||\mathcal{L}u||_{L^{p}(\Omega)}^{1/2} ||\nabla u||_{L^{q}(\Omega)}^{1/2}, \tag{5.17}$$

where C is an absolute constant depending only on α .

Problem 42. Does (5.17) hold for an arbitrary domain $\Omega \subset \mathbb{R}^3$ without the assumption (5.16)?

5.22. L^p -Dissipativity of the Lamé Operator

Consider the Dirichlet problem with zero boundary condition for the Lamé operator \mathcal{L} defined in the previous section.

We say that \mathcal{L} is L^p -dissipative if for all $u \in [C_0^{\infty}(\Omega)]^n$

$$\int_{\Omega} \mathcal{L}u \cdot |u|^{p-2} \, u \, dx \le 0,$$

where 1 .

In [9, Chapter 3], we prove that for n=2 the operator $\mathcal L$ is L^p -dissipative if and only if

$$\left(\frac{1}{2} - \frac{1}{p}\right)^2 \le \frac{2(\nu - 1)(2\nu - 1)}{(3 - 4\nu)^2}.$$
(5.18)

For n=3 this inequality is necessary for the L^p -dissipativity of \mathcal{L} and there are some sufficient conditions. However, the following problem is unsolved.

Problem 43. Prove or disprove that (5.18) is sufficient for the L^p -dissipativity of \mathcal{L} in the three-dimensional case.

5.23. Generalized Maximum Principle for the Lamé System in a Domain with Non-Lipschitz Graph Conical Vertex

Let Ω be a domain with compact closure and whose boundary $\partial\Omega$ is smooth outside one point. We assume that near this point $\partial\Omega$ coincides with a cone, not necessarily a Lipschitz graph.

We consider the Dirichlet problem

$$\Delta \mathbf{u} + (1 - 2\nu)^{-1} \nabla \operatorname{div} \mathbf{u} = 0 \quad \text{in } \Omega,$$

 $\mathbf{u} = \mathbf{g} \quad \text{on } \partial \Omega,$

where $\nu < 1$. The case $\nu = 1/2$ corresponds to the Stokes system, when the condition div $\mathbf{u} = 0$ becomes explicit.

By [81] for n=3 (see also [33, Sections 3.6 and 5.5]) and [13] for $n\geq 3$, the generalized maximum principle

$$\|\mathbf{u}\|_{C(\overline{\Omega})} \le C\|\mathbf{g}\|_{C(\partial\Omega)} \tag{5.19}$$

holds provided $\nu \leq 1/2$. The proof fails for $\nu > 1/2$, which gives rise to the following

Problem 44. Prove (5.19) under the assumption $1/2 < \nu < 1$.

5.24. Boundedness of the Displacement Vector in the Traction Problem in Domains with Non-Lipschitz Graph Conical Vertices

Let Ω be a domain in \mathbb{R}^3 with $\partial\Omega$ smooth outside one point, the vertex of a non-Lipschitz graph cone. Consider the Neumann problem for the linear elasticity system

$$\frac{\partial \sigma_{i,j}(\mathbf{u})}{\partial x_j} = f \quad \text{in } \Omega,
\sigma_{i,j}(\mathbf{u}) \nu_j = 0 \quad \text{on } \partial\Omega,$$
(5.20)

where $f \in C_0^{\infty}(\Omega)$, **u** is the displacement vector,

$$\begin{split} &\sigma_{i,j} = \lambda \theta \delta_{i,j} + 2\mu \varepsilon_{i,j}, \quad \theta = \varepsilon_{11} + \varepsilon_{22} + \varepsilon_{33}, \\ &\varepsilon_{i,j} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right). \end{split}$$

Problem 45. Prove or disprove that the displacement vector is uniformly bounded.

In case of Lipschitz graph domains, the positive answer was given in [12,29], and [11].

5.25. Comparison of Martin's and Euclidian Topologies

In [65] a description of the Martin boundary and of the minimal positive harmonic functions were given without proofs for a class of domains in \mathbb{R}^n . The description just mentioned is as follows.

Let Ω be a bounded domain in \mathbb{R}^n with Euclidean boundary $\partial\Omega$, $O\in\partial\Omega$, and let $\partial\Omega\setminus\{O\}$ be a C^2 manifold. Take spherical coordinates (ρ,τ,α) with origin O $(\rho\geq 0,\,|\tau|\leq\pi/2,\,\alpha\in S^{n-2})$ and consider the case when Ω is obtained by rotating about the axis $|\tau|=\pi/2$ a domain ω contained in the half-plane $\{(\rho,\tau):\rho>0,\,|\tau|<\pi/2\}$, which is given near $\rho=0$ by an inequality of the form $|\tau-\psi(\rho)|<\Theta(\rho)$, so that the boundary of Ω near O is made up of two tangential components under certain conditions on ψ and Θ . The necessary and sufficient condition for O to give rise to exactly one Martin boundary point is the divergence of the integral

$$\int_0^1 \frac{\Theta(t) dt}{\left(\pi - 2|\psi(t)|\right)^2 t}.$$
(5.21)

In other words, (5.21) is equivalent to the existence of the limit

$$\lim_{x \to 0} \frac{G(x,y)}{G(x,z)},$$

where G is Green's function and x, y, z are points in Ω .

For me, the period of time when I worked on the topic, was difficult and I was not able to prepare a detailed exposition. Even later I did not return to the area so that [65] became a collection of unproved lemmas. Since it is impossible for me to do this job in the future, I dare to propose it as an unsolved

Problem 46. Justify the criterion (5.21) and prove assertions on the Martin boundary formulated in [65].

6. Nonlinear Elliptic Operators

6.1. Nonlinear Singularities at the Vertex of a Cone

Let Δ_p be the *p*-Laplace operator

$$u \to \operatorname{div}(|\nabla u|^{p-2}\operatorname{grad} u).$$

Variational solutions of the Dirichlet problem for the *p*-Laplace equation in a cone $\Omega \subset \mathbb{R}^n$ with vertex at the origin $O \in \mathbb{R}^n$:

$$\Delta_p u = 0$$
 in Ω near O ,
 $u = 0$ on $\partial \Omega$ near O

admit the asymptotics

$$u(x) \sim C|x|^{\lambda} \Psi\left(\frac{x}{|x|}\right),$$
 (6.1)

see [37] and [103].

Problem 47. No analogue of (6.1) is known for higher order nonlinear equations

$$\sum_{|\alpha| \le m} \partial^{\alpha} (\mathbf{a}_{\alpha}(\nabla_m u)) = 0,$$

where \mathbf{a}_{α} are positive homogeneous vector-valued functions. The same applies elliptic systems of the second order.

6.2. Nonlinear Boundary Value Problem with Infinite Dirichlet Data

Let Ω be a bounded smooth domain in \mathbb{R}^n and let Q denote a function on $\Omega \times \mathbb{R}^n$, positive homogeneous of degree $p \in (1, \infty)$, $Q(x, \xi) > 0$ for $x \in \Omega$, $\xi \neq 0$. By Δ_p we denote the p-Laplace operator.

Problem 48. Prove that there exists a unique positive λ such that the Dirichlet problem

$$\Delta_p u + Q(x, \nabla u) + \lambda = 0 \quad in \quad \Omega,$$

$$u|_{\partial\Omega} = -\infty$$
(6.2)

is uniquely solvable up to a constant term.

Remark. The pair (u, λ) should solve the variational problem

$$\lambda = \sup_{v \mid \alpha_0 = -\infty} \inf_{x \in \Omega} \left(-\Delta_p \, v - Q(x, \nabla \, v) \right).$$

It is obvious that for p=2 and $Q(\xi)=|\xi|^2$, (6.2) is the classical variational principle for the first eigenvalue of the Laplacian [96].

6.3. Singularities of Solutions to the Neumann Problem for a Semilinear Equation

Let the planar domain Ω have an angle with vertex O. The Neumann problem

$$\begin{cases} \Delta u + a(x) u_{x_1}^2 + 2b(x) u_{x_1} u_{x_2} + c(x) u_{x_2}^2 = 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial n} = 0 & \text{on } \partial \Omega \text{ near } O, \end{cases}$$

$$(6.3)$$

is considered in [28], where an asymptotic formula for an unbounded solution is given under the assumption of the positivity of the quadratic form

$$a(x)\xi^2 + 2b(x)\xi\eta + c(x)\eta^2$$
. (6.4)

Roughly speaking, the solution has a log log r^{-1} singularity. This asymptotic behaviour fails without positivity of the quadratic form. Indeed, the function $u(x) = \log r^{-1} + \cos \theta$ satisfies

$$\Delta u + \frac{\cos \theta}{1 + \sin^2 \theta} |\nabla u|^2 = 0$$

on \mathbb{R}^2_+ as well as zero Neumann condition. This example suggests the following problem.

Problem 49. Describe the asymptotic behaviour of solutions to (6.3) without assumption of positivity of the quadratic form (6.4).

6.4. Positive Solutions of a Non-Linear Dirichlet Problem with Zero Boundary Data

Let Ω be a bounded planar domain and let $\partial\Omega$ be smooth except for an angular point O.

Problem 50. Study the existence, uniqueness and regularity of solutions of the equation

$$\Delta u - \lambda u^k = 0 \quad in \quad \Omega$$

that are positive in Ω and vanish on $\partial\Omega\setminus\{O\}$. Here λ and k are real numbers.

Remark. Obviously, for $\lambda = 0$ and the sector

$$\Omega = \{x = r \exp(i\varphi) : 0 < r < 1, 0 < \varphi < \alpha\}$$

all solutions in question are given by

$$u(x) = C(r^{-\pi/\alpha} - 1)\sin(\frac{\pi}{\alpha}\varphi).$$

6.5. Positive *p*-Harmonic Functions in a Cone

Let u denote a positive locally bounded solution of the equation $\Delta_p u = 0$ in a cone vanishing at the boundary.

Problem 51. Prove that

$$u(x) = C |x|^{\lambda} \psi\left(\frac{x}{|x|}\right), \tag{6.5}$$

where $\lambda > 0$ and C is an arbitrary constant.

The existence of solutions appearing in the right-hand side of (6.5) was studied in [37] and [103]. If the cone is the half-space $\{x: x_n > 0\}$, formula (6.5) becomes $u(x) = Cx_n$.

6.6. Phragmen-Lindelöf Principle for the p-Laplace equation

By [58], bounded solutions u(x) of the p-Laplace equation, $1 , with zero Dirichlet data in a <math>\delta$ -neighborhood of a point $O \in \partial \Omega$, admit the pointwise majorant

$$C \exp\left(-c \int_{|x|}^{\delta} \left(\frac{\operatorname{cap}_{p}(B_{\rho} \backslash \Omega)}{\operatorname{cap}_{p}(B_{\rho})}\right)^{1/(p-1)} \frac{d\rho}{\rho}\right),\,$$

where

$$cap_{p}(F) = \inf\{\|\nabla u\|_{L^{p}(\mathbb{R}^{n})}^{p}: u \in C_{0}^{\infty}(\mathbb{R}^{n}), u \ge 1 \text{ on } F\}.$$
 (6.6)

Problem 52. Prove the following conjecture. If the energy integral of u is divergent, then, for $2r < \delta$,

$$||u||_{L^p(B_\delta \setminus B_r)} \ge \frac{c(\delta)}{r^{\frac{n-p}{p-1}}} \exp\left(c \int_r^\delta \frac{\operatorname{cap}_p(B_\rho \setminus \Omega)}{\operatorname{cap}_p(B_\rho)} \frac{d\rho}{\rho}\right).$$

This assertion was established for the linear uniformly elliptic equation

$$-\frac{\partial}{\partial x_i} \left(a_{ij}(x) \frac{\partial u}{\partial x_j} \right) = 0$$

with measurable bounded coefficients in [55].

6.7. Isolated Singularity of Solution to a Nonlinear Elliptic System

In [16], J. Frehse noticed that the elliptic system with smooth nonlinearity

$$\Delta u_{1} = -\frac{2 u_{1}}{|\mathbf{u}|^{2} + 1} \left(\left| \frac{\partial \mathbf{u}}{\partial x} \right|^{2} + \left| \frac{\partial \mathbf{u}}{\partial y} \right|^{2} \right),$$

$$\Delta u_{2} = -\frac{2 u_{2}}{|\mathbf{u}|^{2} + 1} \left(\left| \frac{\partial \mathbf{u}}{\partial x} \right|^{2} + \left| \frac{\partial \mathbf{u}}{\partial y} \right|^{2} \right)$$
(6.7)

has the weak discontinuous solution

$$u_1 = \cos \log r, \qquad u_2 = \sin \log r, \tag{6.8}$$

where $r = \sqrt{x^2 + y^2} < e^{-2}$.

Problem 53. Is the right-hand side of (6.8) the only possible isolated singularity of solutions to system (6.7) at the origin?

6.8. Poisson Type Solutions of Riccati's Equation with Dirichlet Data

Let Ω be a smooth, bounded planar domain and let the origin O be a point of $\partial\Omega$. Consider the equation

$$\Delta u + \alpha u_x^2 + \beta u_y^2 = 0 \quad \text{in} \quad \Omega,$$

where α and β are smooth positive functions given on $\overline{\Omega}$. We assume that the solution u satisfies u = 0 on $\partial \Omega \setminus \{O\}$.

Problem 54. Prove that either u = 0 on $\partial\Omega$, or u has a logarithmic singularity at O and depends upon an arbitrary constant.

A formal asymptotic expansion of u near O can be found in [92], also for more general equations.

7. Parabolic, Hyperbolic and General Differential Operators

7.1. Behaviour at Infinity of Solutions to the Cauchy–Dirichlet Problem for a Semi-Linear Parabolic Equation

Consider the equation

$$\frac{\partial u}{\partial t} - \Delta u = \nabla u A(x) \nabla u,$$

in the half-cylinder $\{(x,t): x \in \Omega, t > 0\}$, where A is a positive-definite matrix and Ω is a bounded domain in \mathbb{R}^n . Assume that

$$u = 0$$
 for $x \in \partial \Omega$, $t > 0$.

If A is the unit matrix, the replacement of u by $\log v$ with v > 0 shows that at infinity either u vanishes exponentially, or u behaves as t at any positive distance from the boundary.

Problem 55. Show that the same alternative holds if A is not the unit matrix. Describe an asymptotic behaviour of unbounded solutions. What happens if A is not positive-definite?

7.2. Two Inequalities Related to the Heat Equation

Let Ω be an open subset of \mathbb{R}^n . By [49] and [71, Section 2.5.2], the inequality

$$\int_{\Omega} |u|^2 d\mu \le C \int_{\Omega} |\nabla u|^2 dx,\tag{7.1}$$

where μ is a non-negative measure in Ω , holds for all $u \in C_0^{\infty}(\Omega)$ if and only if

$$\sup_{F} \frac{\mu(F)}{\operatorname{cap}(F,\Omega)} < \infty. \tag{7.2}$$

Here $\operatorname{cap}(F,\Omega)$ is the relative harmonic capacity of a compact subset F of Ω with respect to Ω

$$\operatorname{cap}(F,\Omega) = \inf \left\{ \int_{\Omega} |\nabla v|^2 dx : \ v \in C^{0,1}(\Omega), \ v \ge 1 \text{ on } F \right\}.$$

Inequality (7.1) is important in particular in the theory of the Schrödinger operator $\Delta + \mu$, see [49] and [71, Section 2.5].

The following inequality finds applications in the theory of the Cauchy–Dirichlet problem for the operator

$$u \to \frac{\partial u}{\partial t} - \Delta u - \mu u$$

in the cylinder $\Omega \times (0,T)$, where μ is a measure defined on this cylinder:

$$\int_{\Omega \times [0,T)} u^2 d\mu(x,t) \le C \left(\int_{\Omega \times [0,T)} |\nabla_x u|^2 dx dt + \sup_{t \in [0,T)} \int_{\Omega} \left(u(x,t) \right)^2 dx \right). \tag{7.3}$$

Problem 56. Give a complete characterization of the measure μ subject to the inequality (7.3) for all smooth functions u given on $\Omega \times [0,T)$ and vanishing near $\partial \Omega \times [0,T]$.

Answer the same question for the inequality

$$\int_{\Omega\times[0,T)}u^2d\mu(x,t)\leq C\left(\int_{\Omega\times[0,T)}|\nabla_x u|^2dxdt+\int_0^T\left\|\frac{\partial u}{\partial t}\right\|_{L^{-1,2}(\Omega)}^2dt\right),$$

where $L^{-1,2}(\Omega)$ is the dual space of $L_0^{1,2}(\Omega)$.

A necessary condition of type (7.2) obviously holds with the parabolic capacity studied in [97]. Most probably, it is also sufficient.

7.3. Trace Space for the Maximal Operator Generated by the Wave Operator

Let Ω be a domain in $\mathbb{R}^1 \times \mathbb{R}^n$ and let $\square_{x,t} = \partial^2/\partial t^2 - \Delta_x$. By $\overline{\square}$ denote the maximal operator generated by $\square_{x,t}$, i.e. the closure of $\square_{x,t}$ defined on $C^{\infty}(\overline{\Omega})$ in the norm

$$\left(\|\Box_{x,t}u\|_{L^{2}(\Omega)}^{2}+\|u\|_{L^{2}(\Omega)}^{2}\right)^{1/2}.$$

Problem 57. Describe the space of boundary traces for functions in the domain of $\overline{\square}$.

Remark. If $\Omega = \mathbb{R}^{n+1}_+ = \{(x,t) : x \in \mathbb{R}^n, t > 0\}$, then by [18, Corollary 4.6.2] the traces in question make up the Besov space $B^{1/2,2}(\mathbb{R}^n)$.

7.4. Characteristic Problem for Nonlinear Hyperbolic Operators

In [106], the authors study the initial value problem for a hyperbolic linear equation of order 2m, when the initial surface has characteristic points on some compact set Γ . It is proved that the problem is well posed if the set Γ is free from the last initial condition $D_t^{2m-1}u=f$. In the case m=1 a similar result was later obtained in [22].

Problem 58. Obtain a similar result without linearity assumption for the hyperbolic operator.

The only result in this direction known to me is in [6]. It concerns the global characteristic Cauchy problem (Goursat problem) for the nonlinear wave equation. The boundary data in [6] are prescribed on the light cone with two singularities representing both past and future.

7.5. Boundary Traces of Functions in the Domain of a Maximal Differential Operator with t-Dependent Coefficients

Let $P(D_t, D_x)$ be an arbitrary differential operator acting on functions defined on the half-space $\mathbb{R}^n_+ = \{(x,t): x \in \mathbb{R}^n, t > 0\}$ and let P_{max} be the corresponding maximal operator. The domain of P_{max} is the completion of the space of functions smooth on $\overline{\mathbb{R}^n_+}$ and vanishing at infinity in the norm

$$||P u||_{L^2(\mathbb{R}^n_+)} + ||u||_{L^2(\mathbb{R}^n_+)}.$$
 (7.4)

In [18, Chapter 2], an algebraic characterization of boundary traces of functions in the domain of P_{max} was found.

Problem 59. Describe traces on the hyperplane t = 0 of functions in the domain of P_{max} assuming that P is an arbitrary differential operator of the first order in t with coefficients depending on t.

This is only an example which points to the possible development of the theory in [18] for differential operators with coefficients depending only on t.

7.6. Differential Operators Acting in Pairs of Sobolev Spaces

Obviously, a differential operator of order h with variable coefficients maps the Sobolev space $L^{l,p}(\mathbb{R}^n)$ into $L^{l-h,p}(\mathbb{R}^n)$ if the coefficients are multipliers in the proper pairs of Sobolev spaces. This statement can be inverted for some classes of differential operators as shown in [88, Section 10.1.1]. However, the following counterexample proposed in [88, Section 10.1.2] shows that this is not a general property of differential operators.

The coefficient a of the operator

$$u \to a(x) \frac{\partial u}{\partial x_n} : W^{2,2}(\mathbb{R}^n) \to L^2(\mathbb{R}^n),$$
 (7.5)

where $W^{l,2} = L^{l,2} \cap L^2$, need not be a multiplier from $W^{1,2}(\mathbb{R}^n)$ into $L^2(\mathbb{R}^n)$. This gives rise to the following

Problem 60. Find a condition on the function a, necessary and sufficient for the validity of the inequality

$$\left\|a(x)\,\frac{\partial u}{\partial x_n}\right\|_{L^2(\mathbb{R}^n)}\leq c\,\|u\|_{W^{2,2}(\mathbb{R}^n)}$$

for all $u \in C_0^{\infty}(\mathbb{R}^n)$, where n > 3.

Let me point out that if a is independent of the variable x_n , then the criterion is

$$\sup_{0 < r < 1, y' \in \mathbb{R}^{n-1}} r^{3-n} \int_{|x' - y'| < r} a(x') \, dx' < \infty,$$

see [88, Section 10.1.2].

7.7. Existence of a Well-Posed Boundary Value Problem for General Differential Operators in $L^p(\Omega)$

Hörmander (1955) showed the existence of a well-posed boundary value problem for every differential operator with constant coefficients in an arbitrary bounded domain. Equivalently, he proved the estimate

$$||u||_{L^2(\Omega)} \le C ||\mathcal{L}(D) u||_{L^2(\Omega)},$$
 (7.6)

where u is an arbitrary function in $C_0^{\infty}(\Omega)$.

Problem 61. Does (7.6) hold with $L^p(\Omega)$ instead of $L^2(\Omega)$?

7.8. Existence of a Well-Posed Boundary Value Problem for Unbounded Domains

Estimate (7.6) fails for some unbounded domains which gives rise to

Problem 62. Let $\mathcal{L}(D)$ be a differential operator in \mathbb{R}^n with constant coefficients. Characterise the domains satisfying (7.6).

Example. For $\mathcal{L}(D) = \Delta - 1$, any domain is admissible whereas for $\mathcal{L}(D) = \Delta$, n = 3, inequality (7.6) holds if and only if Ω does not contain balls with arbitrary radii. For $n \geq 4$, one needs the notion of biharmonic capacity to formulate a necessary and sufficient condition in terms of a capacitary inner radius (see [71, Chapter 16]).

One can even ask the same question for special operators. For instance, it seems interesting to characterize unbounded domains for which the inequalities

$$||u||_{L^{p}(\Omega)} \leq C ||\Delta u + u||_{L^{p}(\Omega)},$$

$$||u||_{L^{p}(\Omega)} \leq C ||\Box u||_{L^{p}(\Omega)},$$

$$||u||_{L^{p}(\Omega)} \leq C ||\partial_{x_{n}} u - \Delta_{x'} u||_{L^{p}(\Omega)}$$

hold for all $u \in C_0^{\infty}(\Omega)$. Here \square and $\partial_{x_n} - \Delta_{x'}$ are the wave and heat operators.

8. Stationary Stokes and Navier-Stokes Systems

8.1. Hölder Regularity of Solutions to the n-Dimensional Dirichlet–Stokes Problem

Consider the Dirichlet problem for the Stokes system

$$-\nu \, \Delta \mathbf{v} + \nabla \, p = \mathbf{f} \quad \text{in } \Omega,$$
$$\operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega,$$
$$\mathbf{v} = \mathbf{g} \quad \text{on } \partial \Omega,$$

where Ω is a polyhedron in \mathbb{R}^n , $n \geq 3$, and $\mathbf{v} \in L^{1,2}(\Omega)$.

Problem 63. Assuming that **g** belongs to the Hölder space $C^{0,\alpha}(\partial\Omega)$ for a certain $\alpha \in (0,1)$, prove that there exists $\beta \in (0,1)$ such that $\mathbf{v} \in C^{0,\beta}(\overline{\Omega})$.

Remark. The starting point could be the following property obtained in [13]: for any solution of the form $|x|^{\lambda}\psi(x/|x|)$ with $\text{Re}\lambda > 1-n/2$ one has $\text{Re}\lambda > 0$.

8.2. Differentiability of Solutions to the Dirichlet Problem for the Equations of Hydrodynamics in Convex Domains

Consider the Dirichlet problem for the Stokes system

$$-\nu \Delta \mathbf{v} + \nabla p = \mathbf{f} \quad \text{in } \Omega,$$

$$\operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega,$$

$$\mathbf{v} = \mathbf{g} \quad \text{on } \partial \Omega.$$
(8.1)

The following result is obtained in [30, Section 6.3].

Let Ω be a bounded convex two-dimensional domain and let $\mathbf{f} \in L^q(\Omega)$, for some q > 2. Then $\mathbf{v} \in C^{0,1}(\overline{\Omega})$, i.e. \mathbf{v} is Lipschitz and

$$\|\mathbf{v}\|_{C^{0,1}(\overline{\Omega})} \le C \|\mathbf{f}\|_{L^q(\Omega)},$$

where C depends only on Ω .

The following similar result for the Navier–Stokes system was also established in [30, Section 6.3].

Let $L_0^{1,2}$ be the space introduced in Sect. 3.4. Suppose that $(\mathbf{v}, p) \in L_0^{1,2}(\Omega) \times L^2(\Omega)$ satisfy the Dirichlet problem

$$\begin{split} -\nu \, \Delta \mathbf{v} + \nabla \, p + \sum_{1 \leq k \leq 2} v_k \, \partial_{x_k} \mathbf{v} &= \mathbf{f} \quad \text{in } \Omega, \\ \operatorname{div} \mathbf{v} &= 0 \quad \text{in } \Omega, \\ \mathbf{v} &= 0 \quad \text{on } \partial \Omega, \end{split}$$

where Ω is a bounded convex two-dimensional domain and $\mathbf{f} \in L^q(\Omega)$ for some q > 2. Then $\mathbf{v} \in C^{0,1}(\overline{\Omega})$.

Problem 64. Show that the above two facts hold with q > 2 replaced by q > 3 for the three-dimensional case.

8.3. Boundedness of Solutions to the Dirichlet Problem for the Stokes System in Arbitrary 3D Domains

Let Ω be an arbitrary bounded three-dimensional domain. Consider the Dirichlet problem (8.1).

Problem 65. Prove or disprove that the variational solutions are uniformly bounded in Ω .

8.4. Resolvent L^p -Estimates for the Dirichlet-Stokes Operator

Let R_{λ} be the resolvent operator of the Dirichlet problem

$$\Delta \mathbf{v} + \nabla p + \lambda \mathbf{v} = \mathbf{f} \quad \text{in } \Omega,$$
$$\operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega,$$
$$\mathbf{v} = 0 \quad \text{on } \partial \Omega,$$

where $\lambda \in \mathbb{R}^1$ and Ω is a bounded domain in \mathbb{R}^n .

Problem 66. 1. Justify the following conjecture. If $\Omega \subset \mathbb{R}^n$ is convex, then, for all $\lambda \in \mathbb{R}^1 \setminus \{0\}$ and 1 ,

$$||R_{\lambda}||_{L^{p}(\Omega) \to L^{p}(\Omega)} \le \frac{c}{|\lambda|},$$
 (8.2)

where c is a constant which does not depend on λ .

2. Let Ω be smooth outside of a smooth (n-2)-dimensional submanifold M without boundary. Assume that $\partial\Omega$ has a reentrant dihedral angle with edge M and opening $\alpha > \pi$. Prove that (8.2) holds for all $\lambda \in \mathbb{R}^1 \setminus \{0\}$ if

$$\left|\frac{1}{p} - \frac{1}{2}\right| < \frac{\pi}{2\alpha}.$$

Note that for three-dimensional Lipschitz graph domains the question of validity of (8.2) for

$$\frac{3}{2} - \varepsilon$$

with certain $\varepsilon > 0$, was raised by Taylor [102] and answered affirmatively by Shen [100].

8.5. Non-Uniqueness for the Stationary Navier–Stokes System with Dirichlet Data

Let Ω be a simply connected bounded domain in \mathbb{R}^3 . It is well known [40] that the Dirichlet problem for the stationary Navier–Stokes system has at most one variational solution provided the Reynolds number is sufficiently small. It seems probable that the uniqueness fails for large Reynolds numbers.

Problem 67. Construct a counterexample showing that the just mentioned Dirichlet problem may have more than one solution for small viscosity and big data.

This problem is classical but seems half-forgotten to me. Therefore, I include it in the present list.

9. Theory of Surface Waves

9.1. Well-Posed Neumann-Kelvin Problem for a Surface-Piercing Body

When solving the seakeeping problem with forward speed which is called Neumann–Kelvin problem, one looks for a velocity potential u(x, y, z) defined on a lower half-space outside the wetted part S of a body moving in the x-direction. The normal derivative of u is prescribed on S and the condition

$$\frac{\partial^2 u}{\partial x^2} + \nu \frac{\partial u}{\partial z} = 0, \quad \nu = \text{const} > 0,$$

should be satisfied on the flat surface F outside the body (see [38, Chapter 8]).

This classical boundary value problem is in an unsatisfactory state both from theoretical and numerical points of view.

Problem 68. Verify the following conjecture. The Neumann–Kelvin problem becomes Fredholm if the above formulation is completed by prescribing the elevation of the free surface on a part of the water line L, to be more precise, by adding the values of $\partial u/\partial x$ at those points of L where the angle between the exterior normal to L and the x-axis is not greater than $\pi/2$.

Note that the asymptotics of u near the curve L is not known. However, the existence of $\partial u/\partial x$ is suggested by the asymptotic formula (8.8) in [38] obtained for the two-dimensional case.

9.2. Solvability of the Two-Dimensional Kelvin–Neumann Problem for a Submerged Cylinder

In [46], the two-dimensional problem on the steady flow of infinite depth about a submerged cylinder is considered and the existence of the unique solution of any velocity v of the undisturbed flow upstream in the case of an arbitrary circular cylinder is proved.

This boundary value problem is stated as follows. One looks for the velocity potential u(x,y) of the steady motion of a heavy ideal incompressible fluid induced by the cylinder with the cross-section Ω which moves uniformly in the x-direction. The function u satisfies

$$\Delta u = 0 \quad \text{in } W = \mathbb{R}^2_- \setminus \overline{\Omega},\tag{9.1}$$

$$\frac{\partial^2 u}{\partial x^2} + \nu \frac{\partial u}{\partial y} = 0 \quad \text{for } y = 0, \tag{9.2}$$

where $\mathbb{R}^2_-=\{(x,y):y<0\}$ and $\nu=gv^{-2}$ with g being the acceleration due to gravity. In addition,

$$\sup |\nabla u| < \infty, \quad |\nabla u| = o(1) \quad \text{as } x \to \infty, \tag{9.3}$$

$$\frac{\partial u}{\partial n} = v \cos(N, x)$$
 on $\partial \Omega$, (9.4)

where N is the unit normal to $\partial\Omega$ directed into Ω .

The second relation in (9.3) is equivalent to the absence of waves far upstream.

The result obtained in [46], which is of course rather special, seems, however, to be the only known uniqueness theorem for the boundary value problem just stated not relying on any restrictions on ν .

Hence we naturally arrive at the following

Problem 69. Show the unique solvability of (9.1)–(9.4) for a fairly arbitrary domain and for all values of ν .

Note that the proof in [46] is based on the theorem in [105] ensuring the uniqueness of a solution with finite Dirichlet integral under the assumption

$$x \cos(N, x) > 0$$
 on $\partial \Omega$.

The proof of uniqueness in [105] concerns the *n*-dimensional case, $n \geq 2$.

For a modern state of the art presentation of the linear theory of water waves see [38].

9.3. Counterexample in the Water-Wave Problem for a Submerged Body

Let us use the geometrical assumptions made in Section 48. The boundary value problem of harmonic oscillations of the fluid induced by a submerged body is stated as follows. The function u satisfies (9.1), (9.3), while (9.2) is replaced by

$$\frac{\partial u}{\partial y} - \nu u = 0 \quad \text{for } y = 0$$

and a radiation condition at infinity is required (see [38]).

In [64] a class of domains is found for which the problem in question is uniquely solvable for all $\nu > 0$, see also [38, Chapter 1].

Problem 70. Construct an example of a connected set Ω showing that some restrictions on Ω ensuring solvability are necessary.

9.4. Sharp Hardy-Leray Inequality for Divergence-Free Fields

Let **u** denote a vector field in \mathbb{R}^n with components in $C_0^{\infty}(\mathbb{R}^n)$. The following n-dimensional generalization of the one-dimensional Hardy inequality [21]

$$\int_{\mathbb{R}^n} \frac{|\mathbf{u}|^2}{|x|^2} dx \le \frac{4}{(n-2)^2} \int_{\mathbb{R}^n} |\nabla \mathbf{u}|^2 dx \tag{9.5}$$

appears for n=3 in Leray's pioneering paper on the Navier–Stokes equations [42]. The constant factor on the right-hand side is sharp. Since one frequently deals with divergence-free fields in hydrodynamics, it is natural to ask whether this restriction can improve the constant in (9.5).

It is shown in [10] that this is the case indeed if n > 2 and the vector field **u** is axisymmetric by proving that the aforementioned constant can be replaced by the (smaller) optimal value

$$\frac{4}{(n-2)^2} \left(1 - \frac{8}{(n+2)^2} \right) \tag{9.6}$$

which, in particular, becomes 68/25 in three dimensions.

However, the following problem remains unsolved.

Problem 71. Prove or disprove that the constant $4(n-2)^{-2}$ is optimal if **u** is an arbitrary divergence-free vector field with components in $C_0^{\infty}(\mathbb{R}^n)$.

10. Miscellaneous Topics

10.1. A Modified Riemann's Zeta Function Appearing in a Non-Local Parabolic Cauchy Problem

Let C be a unit circle and let u denote a function defined on C. Consider the integral operator A:

$$(A u)(x) = \int_C \frac{u(x) - u(y)}{|x - y|} |dy|.$$

The spectrum of A is described in [79, Section 12.2.2].

Problem 72. Show that the fundamental solution of the Cauchy problem for the operator

$$\frac{d}{dt} + A, \qquad t > 0,$$

which is reminiscent of the modified Riemann zeta function

$$f(z) = \sum_{n \ge 1} \exp\left(-z \sum_{1 \le k \le n} \frac{1}{k}\right),$$

admits a meromorphic extension to the complex $z=t+i\tau$ plane. Study properties of this extension.

10.2. Uniqueness Criterion for Analytic Functions with Finite Dirichlet Integral

The following question was raised by Carleson [8]. Suppose that f is analytic in the unit disc U and

$$\int_{U} |f'|^p \, dA < \infty$$

for some p > 1. Let E be a subset of $(-\pi, \pi)$ and suppose that for $\theta \in E$,

$$f(re^{i\theta}) \to 0$$
 as $r \to 1$.

Of what size must E be to force the conclusion that f is identically zero?

In [8], sufficient conditions for a set of zero length which ensure the uniqueness in the case p=2 are given. One of the conditions is the positivity of the Riesz potential theoretic capacity R_{α} of a certain positive order α .

Maz'ya and Havin [75] described a class of uniqueness sets which is not included into Carleson's. To state our theorem, denote by E a Borel subset of ∂U and let Δ be a set of non-overlapping open arcs $\delta \subset \partial U$. Let $|\delta|$ be the length of δ and put $E_{\delta} := E \cap \delta$. Suppose $p \in (1,2)$ and

$$\sum_{\delta \in \Lambda} |\delta| \log \frac{|\delta|}{c(\delta)} = -\infty, \tag{10.1}$$

where $c(\delta) := \operatorname{cap}_p(E_{\delta})$ is the capacity of E_{δ} defined by (6.6). Then E is a uniqueness set for $A^{1,p}$, the class of all functions f analytic in U with $f' \in L^p(U)$.

This theorem is also valid for p=2 with a slightly different meaning of $c(\delta)$ due to the peculiarity of dimension two: it is now the cap₂-capacity of E_{δ} with respect to the disc $2 d_{\delta}$, where d_{δ} is a disc contained in E_{δ} . This capacity can be expressed by the logarithmic capacity of E_{δ} or by its transfinite diameter. The case (p, ∞) can also be included, but it is not interesting. It is not hard to construct a set E satisfying (10.1) whose Riesz capacities $R_{\alpha}(E)$ of any order $\alpha > 0$ vanish. Thus our theorem enlarges the class of uniqueness sets for $A^{1,2}$ found in [8].

However, the following problem is still open.

Problem 73. Give a complete characterization of the uniqueness sets for analytic functions in the class $A^{1,p}(U)$.

10.3. Hybrid Iterative Methods for Solving Boundary Value Problems

In [34], a mathematical justification of certain new iterative schemes used in solving the Dirichlet and Neumann problems for the Laplace equation is given. These schemes are based on a combination of Green's formula and some numerical methods, FEM, for example, which is applied to some auxiliary mixed boundary value problem on a subset of the original domain.

The proofs in [34] rely upon geometrical requirements on the boundary of the domain of strong convexity type which do not seem natural.

Problem 74. Extend the class of domains with preservation of convergence of the iterative procedures proposed in [34].

10.4. Asymptotic Optimization of Multi-Structures

The present section concerns boundary value problems for multi-structures, i.e. domains dependent on small parameters in such a way that the limit region, as parameters tend to zero, consists of subsets of different space dimensions. Asymptotic analysis of physical fields in multi-structures is developed in [31,77] and elsewhere. Direct methods of variational calculus are often ineffective for solving problems of optimal control of multi-structures because of their complicated geometry. However, [77, Remark 4.4] suggests the following promising

Problem 75. Apply algebraic optimization methods to asymptotic approximations of fields in 1D–3D multi-structures.

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