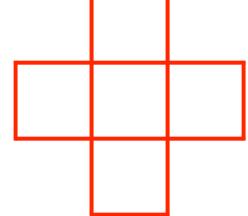
Image Filtering

Lee Hwee Kuan
Bioinformatics Institute
A*STAR

2	5	I	3	4	8	9
6	8	9	2	ന	7	9
5	9	5	9	0	8	9
7	ı	3	4	6	9	5
3	9	2	3	7	_	3
8	6	0		თ	9	2
7	3	4	2	4	8	6

13	16	18	10	18	28	26
21	37	25	26	16	35	33
27	28	35				

window

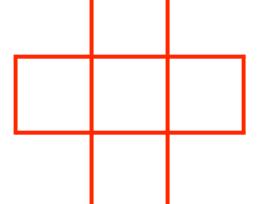


operations = sum of pixels

2	5	I	3	4	8	9
6	8	9	2	3	7	9
5	9	5	9	0	8	9
7		3	4	6	9	5
3	9	2	3	7		3
8	6	0		3	9	2
7	3	4	2	4	8	6

6	8	9	4	8	9	9
8	9	9	9	7	9	9
9	9	9				

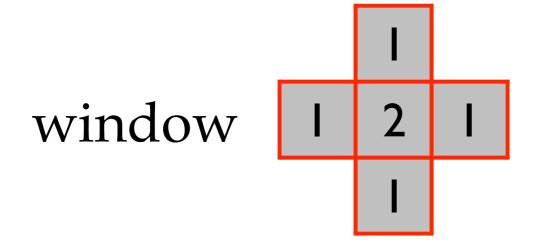
window



operations = max of pixels

2	2		0	2		I
3	2	I	2	3	2	0
I	0	2		0	2	I
I	0	2	-	0	2	I
2		I	0	2	2	I
	2	2	0	2	3	2
2	I	0	2	2	0	2

9	9	5	5	8	7	3
Ш	10	9	8	12	10	4
6	5	8				

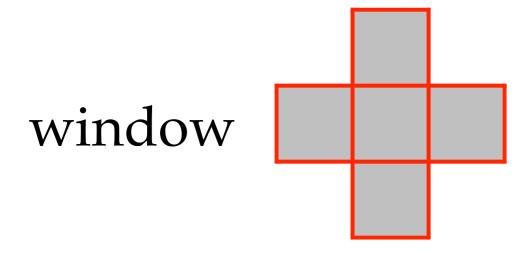


operations = weighted sum

Dilation as an image filter

	0	0	0	0	0	0	0
1	0	0	I	0	0	0	0
	0	I	I	I	0	0	0
	0	0	I	-	0	0	0
	0	0	0	I	0	0	0
	0	0	0		0	0	0
	0	0	0	0	0	0	0

0	0		0	0	0	0
0	_	_		0	0	0
I	_				0	0
0	_				0	0
0	0	_		_	0	0
0	0				0	0
0	0	0	I	0	0	0



operations = max pixel

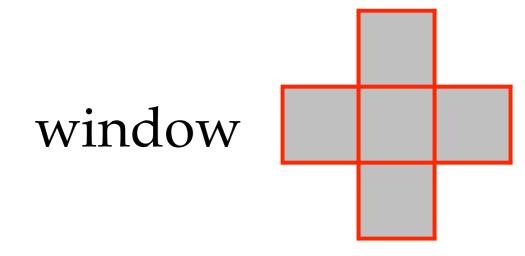
What filter is use for erosion?

Mean filter

1 = white pixel, 0 = black pixel

0	0	0	0	0	0	0
0	0	1	0	0	0	0
0	1	1	1	0	0	0
0	0	1	1	0	0	0
0	0	0	1	0	0	0
0	0	0	1	0	0	0
0	0	0	0	0	0	0

0	0	1/4	0	0	0	0
0	2/5	2/5	2/5	0	0	0
1/4	2/5	1	3/5	1/5	0	0
0	2/5	2/5	4/5	1/5	0	0
0	0	2/5	3/5	1/5	0	0
0	0	1/5	2/5	1/5	0	0
0	0	0	1/5	0	0	0

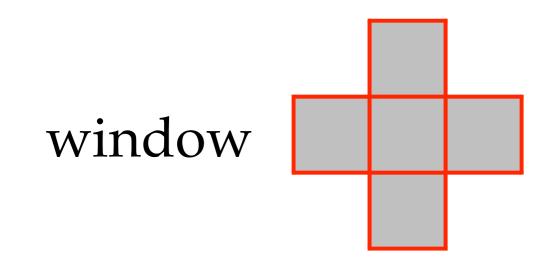


operations = mean

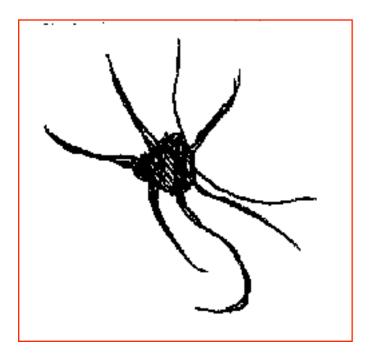
Mean filter

0	0	1/4	0	0	0	0
0	2/5	2/5	2/5	0	0	0
1/4	2/5	1	3/5	1/5	0	0
0	2/5	2/5	4/5	1/5	0	0
0	0	2/5	3/5	1/5	0	0
0	0	1/5	2/5	1/5	0	0
0	0	0	1/5	0	0	0

0	0.16	0.36	0.27	0	0	0
0.27	0.24	0.49	0.28	0.12	0	0
0.36	0.49	0.52	0.6	0.2	0.04	0
0.15	0.24	0.4	0.52	0.28	0.04	0
0	0.16	0.32	0.48	0.24	0.04	0
0	0.04	0.2	0.32	0.16	0.04	0
0	0	0.1	0.15	0.1	0	0



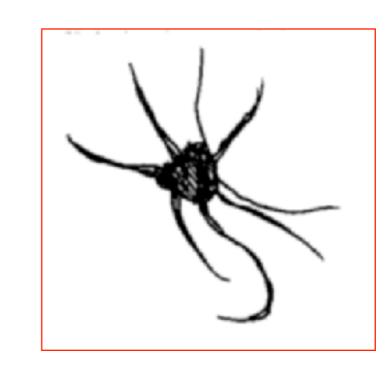
operations = mean



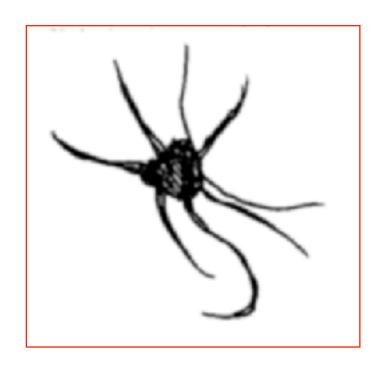
original image 344 x 332 pixels



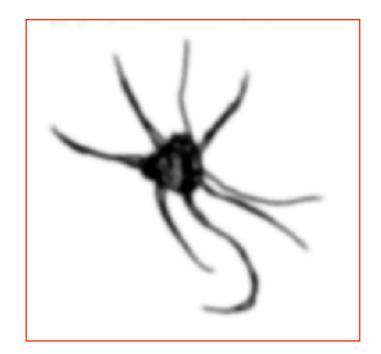
mean 1 time



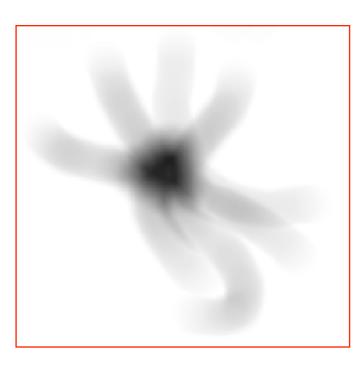
mean 2 times



mean 3 times



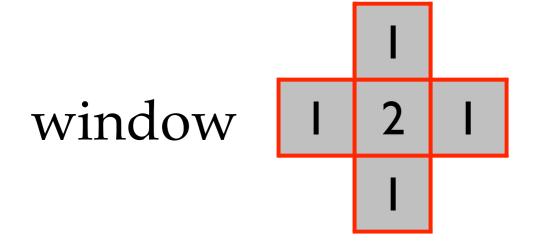
mean 10 times



mean 1 time with radius 20

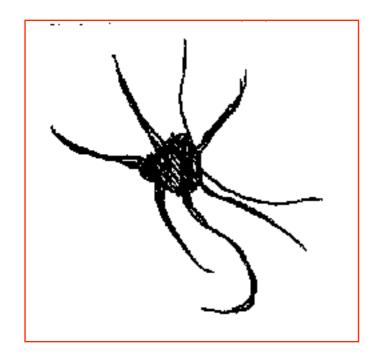
2			0	2	I	I
			2	3	2	0
I		2		0	2	I
ı	0	2		0	2	I
2	ı	-	0	2	2	I
I	2	2	0	2	3	2
2	I	0	2	2	0	2

2	2		I		I	I
2	2	2	I	2	2	I
I	ı	I				



operations = median filter

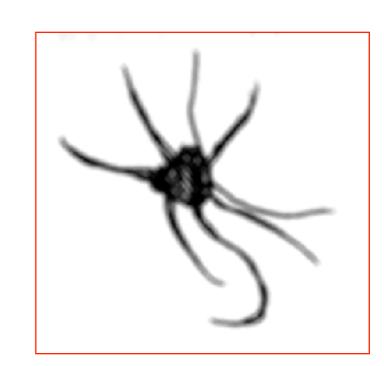
Median filter



original image 344 x 332 pixels



median filter radius 4



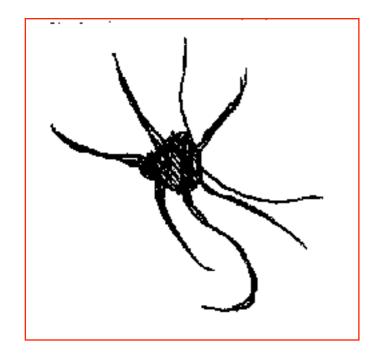
mean filter radius 4

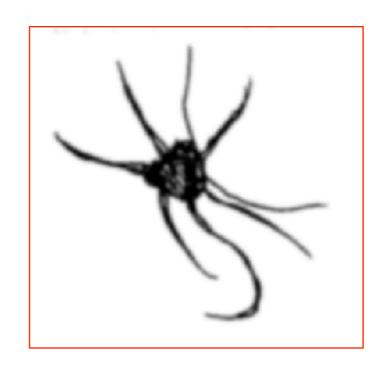
Gaussian filter

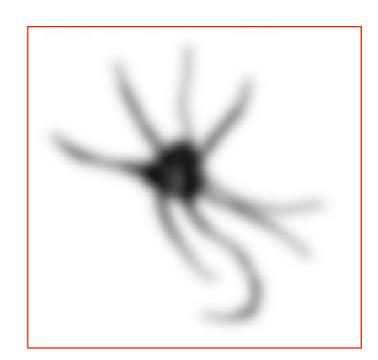
A weighted window

0.0075	0.01	0.02	0.01	0.0075
0.01	0.04	0.1	0.04	0.01
0.02	0.1	0.25	0.1	0.02
0.01	0.04	0.1	0.04	0.01
0.0075	0.01	0.02	0.01	0.0057

Put in weights with a gaussian profile -> a Gaussian filter







original image 344 x 332 pixels

filtered with sigma = 2 pixels

filtered with sigma = 8 pixels

Edge filter

1	1	1	1	5	5	5	5
1	1	1	1	5	5	5	5
1	1	1	1	5	5	5	5
1	1	1	1	5	5	5	5
1	1	1	1	5	5	5	5
1	1	1	1	5	5	5	5
4	4	4	4	5	5	5	5

-1	0	1
-1	0	1
-1	0	1

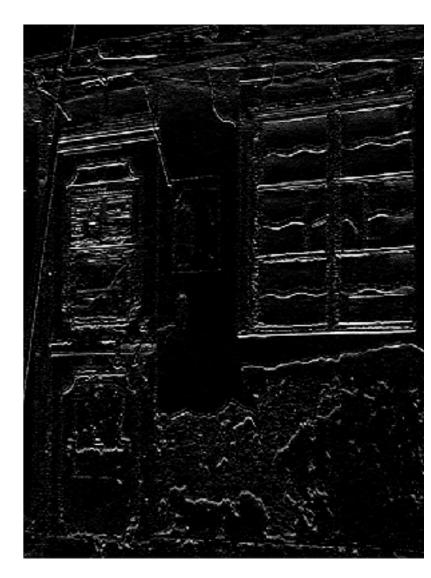
0	0	4	4	0	0
0	0	4	4	0	0
0	0	4	4	0	0
0	0	4	4	0	0
0	0	4	4	0	0
0	0	4	4	0	0
0	0	4	4	0	0

-1	0	1
-1	0	1
-1	0	1

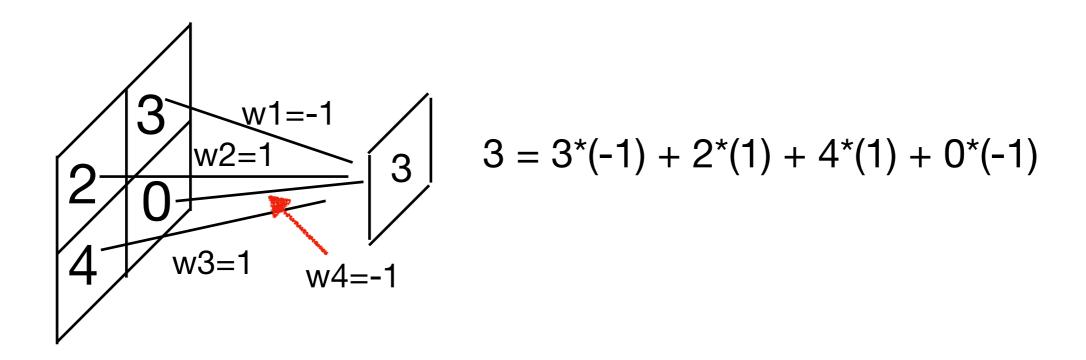
-1	-1	-1
0	0	0
1	1	1







Convolutional Neural Networks



https://towardsdatascience.com/types-of-convolutions-in-deep-learning-717013397f4d

https://deeplearning4j.org/convolutionalnetwork

Convolutional Neural Networks

Simple example

https://de.mathworks.com/solutions/deep-learning/convolutional-neural-network.html

State of the art

https://medium.com/@siddharthdas_32104/cnns-architectures-lenet-alexnet-vgg-googlenet-resnet-and-more-666091488df5