## Additional notes for the modified Standard form (the standard equality form)

$$\frac{\text{Matrix notation}}{\text{Matrix}} \qquad A = \begin{bmatrix} a_{11} & a_{12} & a_{1n} & 1 \\ a_{n1} & a_{n2} & a_{nn} & 1 \end{bmatrix} \qquad \underset{\text{matrix}}{\text{matrix}} \\
\vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ o \\ o \end{bmatrix} \in \mathbb{R}^m \qquad \vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ c_n \\ c_n \end{bmatrix} \in \mathbb{R}^m \qquad \vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ c_n \\ c_n \end{bmatrix} \in \mathbb{R}^m \qquad \vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ c_n \\ c_n \end{bmatrix} \in \mathbb{R}^m \qquad \vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ c_n \\ c_n \end{bmatrix} \in \mathbb{R}^m \qquad \vec{c} = \begin{bmatrix} c_1 \\ c_2 \\ c_n \\ c_n \\ c_n \end{bmatrix}$$

Can rewrite the LP

Note  $\vec{a} = \begin{bmatrix} a_1 \\ b_2 \end{bmatrix}$ ,  $\vec{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ Maximize  $\vec{c} \cdot \vec{x}$ Subject  $(\vec{A}\vec{x} = \vec{b})$   $\vec{x} \ge \vec{0}$ Means  $(\vec{a}, \vec{b})$ ;

For all  $\vec{a}$ Means  $(\vec{a}, \vec{b})$ ;

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Means  $(\vec{a},$ 

Terminology: hyperplane in an n-dimensional space is an (n-1)-dimensional plane

· geometry of the feasible region 3 x = Rntm ( Ax=1, x>0} of the modified standard form

(equality form) The teasible set is contained in X := 0  $3\vec{x} \mid A \vec{x} = \vec{b}$  on  $\vec{n}$ -dim'l subspace

the hyperplanes of anxi+ xn+1=bi

Re call.

Thunk Let ai, az, am e Rn bi, bm e R Let n≥m

Define hyperplanes: 
$$L_k = \{\vec{x} \in \mathbb{R}^n | \vec{a}_k \cdot \vec{x} = b_k\}$$

Suppose ai, ..., am are linearly independent.

(i.e. 
$$y_1\vec{a_1} + y_2\vec{a_2} + \cdots + y_m\vec{a_m} = \vec{0} \leftarrow \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
)

[mplies  $y_1 = y_2 = \cdots = y_m = 0$ 

Then the intersection LIALZA... OLm 

is an (n-m)-dimensional subspace in IR"