

Channel Shaping Using Reconfigurable Intelligent Surfaces: From Diagonal to Beyond

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Abstract—This paper investigates how a passive Reconfigurable Intelligent Surface (RIS) can reshape the Multiple-Input Multiple-Output (MIMO) point-to-point channel in terms of singular values. We depart from the widely-adapted diagonal phase shift model to a general Beyond-Diagonal (BD) architecture, which provides superior shaping capability thanks to in-group connections between elements. An efficient Riemannian Conjugate Gradient (RCG) algorithm is tailored for smooth optimization problems of asymmetric BD RIS with arbitrary group size, then invoked for the Pareto frontier of channel singular values. To understand the gain from off-diagonal entries, we also derive analytical singular value bounds in Line-of-Sight (LoS) and fully-connected scenarios. As a side product, we tackle MIMO rate maximization problem by alternating between active beamformer (eigenmode transmission) and passive beamformer (RCG algorithm) until convergence. A low-complexity suboptimal solution decoupling both blocks is also proposed, where the channel shaping subproblem is formulated as channel power maximization and solved iteratively in closed form. Theoretical analysis and numerical evaluation reveal that the shaping advantage of BD RIS increases with group size and stems from stronger subchannel rearrangement and subspace alignment capabilities.

Index Terms—Reconfigurable intelligent surface, multi-input multi-output, manifold optimization, singular value control, rate maximization.

I. INTRODUCTION

Today we are witnessing a paradigm shift from connectivity to intelligence, where the wireless environment is no longer a chaotic medium but a conscious agent that serves on demand. This is empowered by the recent advances in Reconfigurable Intelligent Surface (RIS), a real-time programmable metasurface of numerous non-resonant sub-wavelength scattering elements. It can manipulate the amplitude, phase, frequency, and polarization of the scattered waves [1] with a higher energy efficiency, lower cost, lighter footprint, and greater scalability than relays. Using RIS for passive beamforming has attracted significant interest in wireless communication [2]–[5], backscatter [6], [7], sensing [8], [9], and power transfer literature [10]–[12], reporting a second-order array gain and fourth-order power scaling law (with proper waveform). On the other hand, RIS also enables backscatter modulation by dynamically switching between different patterns, as already investigated [13]–[15] and prototyped [16], [17]. Despite fruitful outcomes, one critical unanswered question is the channel shaping capability: *To what extent can a passive RIS reshape the wireless channel?*

The answer indeed depends on the hardware architecture and scattering model. In conventional (a.k.a. diagonal) RIS, each scattering element is tuned by a dedicated impedance and acts as an *individual* phase shifter [18]. The concept is generalized to Beyond-Diagonal (BD) RIS [19], [20] which groups adjacent

elements using passive components. This allows *cooperative* scattering — wave impinging on one element can propagate within the circuit and depart partially from any element in the same group. BD RIS can thus control both amplitude and phase of the reflected wave, generalizing the scattering matrix from diagonal with unit-magnitude entries to block diagonal with unitary blocks. Its benefit has been recently shown in receive power maximization [21]–[24], transmit power minimization [25], and rate maximization [24]–[28]. Practical issues such as channel estimation [29] and mutual coupling [30] have also been investigated. Therefore, BD RIS is envisioned as the next generation channel shaper with stronger signal processing flexibility [31].

Channel shaping is different from passive beamforming as it seeks to modify the inherent properties of the channel itself. This allows one to decouple the RIS-transceiver design and explore the fundamental limits of channel manipulation. For example, diagonal RIS has been proved useful for improving channel power [32], degree of freedom [33], [34], condition number [35], [36], and effective rank [37], [38] in Multiple-Input Multiple-Output (MIMO). On the other hand, BD RIS can provide a higher channel power but the results are limited to Single-Input Single-Output (SISO) [21] and Multiple-Input Single-Output (MISO) [22]. While these studies offer promising glimpses into the channel shaping potential of passive RIS, a comprehensive understanding of its capabilities and limitations is desired, and a universal design framework is still missing. This paper aims to answer the channel shaping question through theoretical analysis and numerical optimization. The contributions are summarized below.

First, we examine the capability of BD RIS to redistribute the channel singular values in MIMO Point-to-point Channel (PC). The Pareto frontiers are characterized by optimizing the *weighted sum of singular values*, where the weights can be positive, zero, or negative. It generalizes all singular value metrics and provides a powerful design framework. We then discuss some analytical singular value bounds under rank-deficient and no-direct scenarios.

Second, we tailor a Riemannian Conjugate Gradient (RCG) algorithm for asymmetric¹ BD RIS optimization. Specifically, block-wise update is performed along the geodesics² of the Stiefel manifold and concisely evaluated as matrix exponential.

¹Although the constraint of symmetric scattering parameters is widely respected in the literature [19], [21]–[27], it can be relaxed when the BD RIS involves asymmetric passive components (e.g., ring hybrids and branch-line hybrids) [39], as previously assumed in [20], [28]. Symmetry can be enforced by projection if necessary.

²A geodesic refers to the shortest path between two points in a Riemannian manifold.

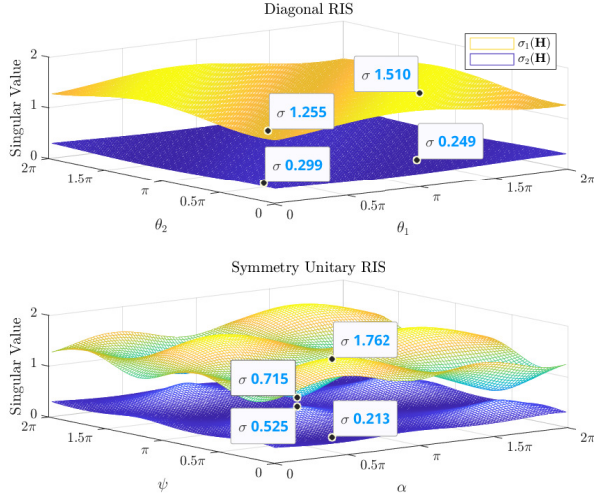


Fig. 1. Channel singular value shaping by diagonal and symmetry unitary RIS. $(N^T, N^S, N^R) = (2, 2, 2)$. Direct link is absent.

The proposed method not only features lower complexity and faster convergence than universal manifold optimization [40], [41], but also applies to any BD RIS problem where gradient exists. It effectively solves the Pareto singular problem.

Third, we propose a closed-form iterative algorithm for power centric channel shaping problems. The idea is to successively approximate the quadratic objective by a sequence of affines and solve the local problems by Singular Value Decomposition (SVD). Case studies are conducted for channel power maximization in PC and leakage interference minimization in Interference Channel (IC).

Fourth, we perform extensive simulations to validate and quantify the signal processing advantage of BD RIS. Besides channel shaping, we also consider typical joint active and passive beamforming problems, including rate maximization in PC and Weighted Sum-Rate (WSR) maximization in IC. Results suggest that BD RIS achieves a larger array gain in PC and a higher Degree of Freedom (DoF) in IC.

II. MIMO-PC

A. Channel Singular Value Redistribution

We first show the channel shaping benefit of BD RIS by a toy example. Consider $(N^T, N^S, N^R) = (2, 2, 2)$ and assume the direct link is absent. The diagonal RIS is $\Theta^D = \text{diag}(e^{j\theta_1}, e^{j\theta_2})$ while the unitary RIS has 4 independent angular parameters

$$\Theta^U = e^{j\phi} \begin{bmatrix} e^{j\alpha} \cos\psi & e^{j\beta} \sin\psi \\ -e^{-j\beta} \sin\psi & e^{-j\alpha} \cos\psi \end{bmatrix}. \quad (1)$$

When the direct link is absent, ϕ has no impact on the singular value because $\text{sv}(e^{j\phi} \mathbf{A}) = \text{sv}(\mathbf{A})$. For a fair comparison, we enforce symmetry with $\beta = \pi/2$. Fig. 1 illustrates all possible channel singular values achieved by diagonal and symmetry unitary RIS. Despite using the same number of elements and parameters, BD RIS provides much wider dynamic ranges of $\sigma_1(\mathbf{H})$ and $\sigma_2(\mathbf{H})$ than diagonal RIS. Larger gaps are expected when the symmetry constraint can be relaxed.

We then analyze the channel shaping *capability* of BD RIS under specific setups.

1) *Rank-Deficient Channel*: In rank-deficient channels, BD RIS Θ^B cannot achieve a higher DoF than diagonal RIS Θ^D . This is because $\text{sv}(\Theta^B) = \text{sv}(\Theta^D) = \mathbf{1}$ and

$$\begin{aligned} \text{rank}(\mathbf{H}) &\leq \text{rank}(\mathbf{H}^D) + \text{rank}(\mathbf{H}^B \Theta \mathbf{H}^F) \\ &\leq \text{rank}(\mathbf{H}^D) + \min(\text{rank}(\mathbf{H}^B), \text{rank}(\Theta), \text{rank}(\mathbf{H}^F)). \end{aligned} \quad (2)$$

Note BD RIS can still provide a higher indirect Signal-to-Noise Ratio (SNR) as shown in Fig. 4 and 5.

2) *Rank-1 Indirect Channel*: The indirect channel is rank-1 iff the forward or backward channel is rank-1. Let $\mathbf{H}^F = \sigma^F \mathbf{u}^F \mathbf{v}^{FH}$ without loss of generality. In this case, the channel Gram matrix can be written as Hermitian-plus-rank-1:

$$\mathbf{G} \triangleq \mathbf{H} \mathbf{H}^H = \mathbf{Y} + \mathbf{z} \mathbf{z}^H, \quad (3)$$

where $\mathbf{Y} \triangleq \mathbf{H}^D (\mathbf{I} - \mathbf{v}^F \mathbf{v}^{FH}) \mathbf{H}^D = \mathbf{T} \mathbf{T}^H$ and $\mathbf{z} \triangleq \sigma^F \mathbf{H}^B \Theta \mathbf{u}^F + \mathbf{H}^D \mathbf{v}^F$. Regardless of RIS size and structure³, its n -th ($n \geq 2$) eigenvalues are bounded by the Cauchy interlacing formula [43]

$$\lambda_1(\mathbf{Y}) \geq \lambda_2(\mathbf{G}) \geq \lambda_2(\mathbf{Y}) \geq \dots \geq \lambda_{N-1}(\mathbf{Y}) \geq \lambda_N(\mathbf{G}) \geq \lambda_N(\mathbf{Y}). \quad (4)$$

The equivalent singular value inequality is

$$\sigma_1(\mathbf{T}) \geq \sigma_2(\mathbf{H}) \geq \sigma_2(\mathbf{T}) \geq \dots \geq \sigma_{N-1}(\mathbf{T}) \geq \sigma_N(\mathbf{H}) \geq \sigma_N(\mathbf{T}). \quad (5)$$

(5) implies that, if the indirect channel is rank-1, then the RIS can at most enlarge the n -th ($n \geq 2$) channel singular value to the $(n-1)$ -th singular value of \mathbf{T} . Note that the largest channel singular value is unbounded with a sufficiently large RIS.

3) *Fully-Connected RIS Without Direct Link*: Denote the singular value decomposition of forward / backward channels as $\mathbf{H}^{B/F} = \mathbf{U}^{B/F} \Sigma^{B/F} \mathbf{V}^{B/FH}$. The composite channel is

$$\mathbf{H} = \mathbf{H}^B \Theta \mathbf{H}^F = \mathbf{U}^B \Sigma^B \mathbf{X} \Sigma^F \mathbf{V}^{FH}, \quad (6)$$

where $\mathbf{X} = \mathbf{V}^{BH} \Theta \mathbf{U}^F$.

Proposition 1. *In this case, the singular value bounds on \mathbf{H} are equivalent to the singular value bounds on $\mathbf{B}\mathbf{F}$, where \mathbf{B} and \mathbf{F} are arbitrary matrices with singular values Σ^B and Σ^F .*

Proof. We first observe that singular value control problem can be solved w.r.t. unitary \mathbf{X} and retrieved by $\Theta = \mathbf{V}^B \mathbf{X} \mathbf{U}^{FH}$. Also, $\text{sv}(\mathbf{U}^B \Sigma^B \mathbf{X} \Sigma^F \mathbf{V}^{FH}) = \text{sv}(\bar{\mathbf{U}}^B \Sigma^B \bar{\mathbf{V}}^{BH} \bar{\mathbf{U}}^F \Sigma^F \bar{\mathbf{V}}^{FH}) = \text{sv}(\mathbf{B}\mathbf{F})$ where $\bar{\mathbf{U}}^{B/F}$ and $\bar{\mathbf{V}}^{B/F}$ are arbitrary unitary matrices. \square

The problem now becomes, given Σ^B and Σ^F , what can we say about the singular value of $\mathbf{B}\mathbf{F}$. One comprehensive answer is Horn's inequality [44]: for all admissible triples (I, J, K) ,

$$\prod_{k \in K} \sigma_k(\mathbf{B}\mathbf{F}) \leq \prod_{i \in I} \sigma_i(\mathbf{B}) \prod_{j \in J} \sigma_j(\mathbf{F}). \quad (7)$$

³A similar conclusion was made for diagonal RIS in [42].

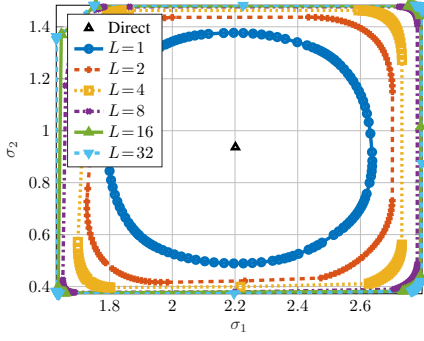


Fig. 2. Singular value Pareto frontier. $(N^T, N^S, N^R) = (4, 64, 2)$, $(A^D, A^F, A^B) = (0, -17.5, -17.5)$ dB.

It gives upper bound on the largest singular value and lower bound on the smallest singular value:

$$\sigma_1(\mathbf{BF}) \leq \sigma_1(\mathbf{B})\sigma_1(\mathbf{F}) \quad (8)$$

$$\sigma_N(\mathbf{BF}) \geq \sigma_N(\mathbf{B})\sigma_N(\mathbf{F}). \quad (9)$$

Another useful result is introduced in [45]: for all $p > 0$,

$$\sum_n \sigma_n^p(\mathbf{BF}) \leq \sum_n \sigma_n^p(\mathbf{B})\sigma_n^p(\mathbf{F}). \quad (10)$$

When $p=2$, it implies the channel energy is upper bounded by the sum of element-wise power product of the forward and backward channels, as illustrated in Fig. 5(a). Interestingly, (8)–(10) are simultaneously tight when $\mathbf{X} = \mathbf{I}$ and $\mathbf{\Theta} = \mathbf{V}^B \mathbf{U}^{FH}$. This solution was claimed in [27] to achieve channel capacity, but it is not true at moderate SNR.

Finally, we characterize the *Pareto frontier* of channel singular values via optimization approach.

$$\max_{\mathbf{\Theta}} / \min_{\mathbf{\Theta}} \quad J_1 = \sum_n \rho_n \sigma_n(\mathbf{H}) \quad (11a)$$

$$\text{s.t.} \quad \mathbf{\Theta}_g^H \mathbf{\Theta}_g = \mathbf{I}, \quad \forall g, \quad (11b)$$

where ρ_n is the weight of n -th singular value. The complex derivative of (11a) w.r.t. RIS block g is

$$\frac{\partial J_1}{\partial \mathbf{\Theta}_g^*} = \mathbf{H}_g^{BH} \mathbf{U} \text{diag}(\boldsymbol{\rho}) \mathbf{V}^H \mathbf{H}_g^{FH}, \quad (12)$$

where \mathbf{U} and \mathbf{V} are left and right singular matrix of \mathbf{H} . (11) can be solved by RCG Algorithm 1 with (26) replaced by (12).

The Pareto frontier and evolving trend of channel singular values are shown in Fig. 2 and 3. Clearly, BD RIS with a larger group size can redistribute the channel singular values to a wider range.

B. Channel Power Maximization

Consider a BD RIS with N^S elements, which is divided into G groups of equal L elements.

$$\max_{\mathbf{\Theta}} \quad \left\| \mathbf{H}^D + \sum_g \mathbf{H}_g^B \mathbf{\Theta}_g \mathbf{H}_g^F \right\|_F^2 \quad (13a)$$

$$\text{s.t.} \quad \mathbf{\Theta}_g^H \mathbf{\Theta}_g = \mathbf{I}, \quad \forall g \in \mathcal{G} \triangleq \{1, \dots, G\}. \quad (13b)$$

For *symmetric* BD-RIS, the problem has been solved in

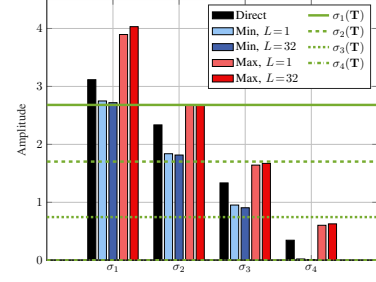


Fig. 3. Singular value bounds for rank-1 indirect channel. $(N^T, N^S, N^R) = (4, 32, 4)$, $(A^D, A^F, A^B) = (0, -17.5, -17.5)$ dB.

- Matteo's paper [21]: SISO and equivalent⁴;
- Ignacio's paper [22]: SISO and directless MISO/SIMO.

Remark 1. The difficulty of (13) is that the RIS needs to balance the additive (direct-indirect) and multiplicative (forward-backward) eigenspace alignment. Interestingly, it has the same form as the weighted orthogonal Procrustes problem [46]:

$$\min_{\mathbf{\Theta}} \quad \|\mathbf{C} - \mathbf{A} \mathbf{\Theta} \mathbf{B}\|_F^2 \quad (14a)$$

$$\text{s.t.} \quad \mathbf{\Theta}^H \mathbf{\Theta} = \mathbf{I}. \quad (14b)$$

There exists no trivial solution to (14). One lossy transformation, by moving $\mathbf{\Theta}$ to one side [47], formulates a standard orthogonal Procrustes problem:

$$\min_{\mathbf{\Theta}} \quad \|\mathbf{A}^\dagger \mathbf{C} - \mathbf{\Theta} \mathbf{B}\|_F^2 \quad (15a)$$

$$\text{s.t.} \quad \mathbf{\Theta}^H \mathbf{\Theta} = \mathbf{I}. \quad (15b)$$

(15) has a global optimal solution $\mathbf{\Theta}^* = \mathbf{U} \mathbf{V}^H$, where \mathbf{U} and \mathbf{V} are left and right singular matrix of $\mathbf{A}^\dagger \mathbf{C} \mathbf{B}^H$ [43]. This low-complexity solution will be compared with the one proposed later.

Inspired by [48], we propose an iterative algorithm to solve (13). The idea is to successively approximate the quadratic objective with a sequence of affine functions and solve the resulting subproblems in closed form.

Proposition 2. Start from any $\mathbf{\Theta}^{(0)}$, the sequence

$$\mathbf{\Theta}_g^{(r+1)} = \mathbf{U}_g^{(r)} \mathbf{V}_g^{(r)}, \quad \forall g \quad (16)$$

converges to a stationary point of (13), where $\mathbf{U}_g^{(r)}$ and $\mathbf{V}_g^{(r)}$ are left and right singular matrix of

$$\begin{aligned} \mathbf{M}_g^{(r)} = & \mathbf{H}_g^{BH} \mathbf{H}^D \mathbf{H}_g^{FH} + \sum_{g' < g} \mathbf{H}_{g'}^{BH} \mathbf{H}_{g'}^B \mathbf{\Theta}_{g'}^{(r+1)} \mathbf{H}_{g'}^F \mathbf{H}_{g'}^H \\ & + \sum_{g' \geq g} \mathbf{H}_{g'}^{BH} \mathbf{H}_{g'}^B \mathbf{\Theta}_{g'}^{(r)} \mathbf{H}_{g'}^F \mathbf{H}_{g'}^H. \end{aligned} \quad (17)$$

Proof. To be added. \square

Fig. 4 shows that, apart from adding reflecting elements N^S , increasing the group size L also improves the channel power. This behavior is more pronounced for a large RIS. For example, the gain of pairwise connection is 2.8 % for

⁴Single-stream MIMO with given precoder and combiner.

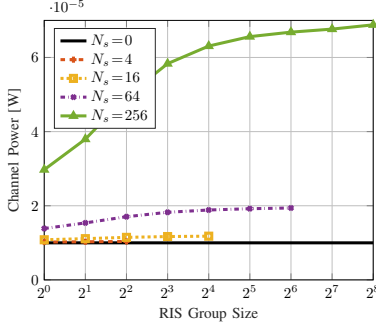


Fig. 4. Average channel power versus RIS elements N^S and group size L . $(N^T, N^R) = (8, 4)$, $(A^D, A^F, A^B) = (65, 54, 46)$ dB.

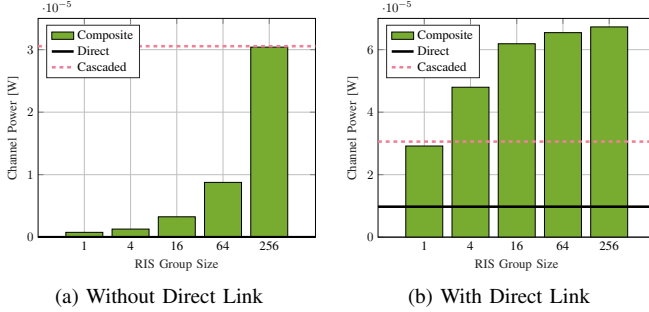


Fig. 5. Average channel power versus RIS group size L . $(N^T, N^S, N^R) = (8, 256, 4)$, $(A^D, A^F, A^B) = (65, 54, 46)$ dB.

$N^S = 16$ and 28 % for $N^S = 256$. It implies that the channel shaping capability of BD RIS scales with group size L .

Fig. 5b and 5a compare the average channel power without and with direct link. “Cascaded” means the sum of element-wise product of first $N = \min(N^T, N^S, N^R)$ eigenvalues (i.e., element-wise power product) of the forward and backward channels. We observe that diagonal RIS wastes substantial cascaded power and struggles to align the direct-indirect eigenspace. When the direct link is absent, only 2.6 % of available power is utilized by diagonal RIS while 100 % power is recycled by fully-connected RIS. When the direct link is present, the proposed BD RIS design can balance the direct-indirect and forward-backward eigenspace alignment for an optimal channel boost. It is worth noting that, when L is sufficiently large, the composite channel power surpasses the power sum of direct and cascaded channels, thanks to the constructive *amplitude superposition* of direct and cascaded channels. This again emphasizes the advantage of in-group connection of BD RIS.

C. Rate Maximization

The problem is formulated w.r.t. precoder (instead of transmit covariance matrix) for reference:

$$\max_{\mathbf{W}, \Theta} R = \log \det \left(\mathbf{I} + \frac{\mathbf{W}^H \mathbf{H}^H \mathbf{H} \mathbf{W}}{\eta} \right) \quad (18a)$$

$$\text{s.t.} \quad \|\mathbf{W}\|_F^2 \leq P, \quad (18b)$$

$$\Theta_g^H \Theta_g = \mathbf{I}, \quad \forall g. \quad (18c)$$

(18) is jointly non-convex and solved by Alternating Optimization (AO). For a given Θ , the optimal precoder is given by

$$\mathbf{W}^* = \mathbf{V} \mathbf{S}^{*1/2}, \quad (19)$$

where \mathbf{V} is right singular matrix of \mathbf{H} and \mathbf{S}^* is a diagonal matrix of the water-filling power allocation. For a given \mathbf{W} , we update Θ by RCG method along the geodesics [49].

Remark 2. A geodesic refers to the shortest path between two points in a Riemannian manifold. Unitary constraint (18c) translates to a Stiefel manifold where the geodesics have simple expressions described by the exponential map [50].

For general optimization problems with block unitary constraint, the adapted RCG method at iteration r for block g is summarized below, where $f(\Theta_g^{(r)})$ is the objective function also evaluated over $\{\{\Theta_{g'}^{(r+1)}\}_{g' < g}, \{\Theta_{g'}^{(r)}\}_{g' > g}\}$.

- 1) Compute the Euclidean gradient

$$\nabla_g^{\mathbf{E}(r)} = \frac{\partial f(\Theta_g^{(r)})}{\partial \Theta_g^*}; \quad (20)$$

- 2) Translate to the Riemannian gradient

$$\nabla_g^{\mathbf{R}(r)} = \nabla_g^{\mathbf{E}(r)} \Theta_g^{(r)H} - \Theta_g^{(r)} \nabla_g^{\mathbf{E}(r)H}; \quad (21)$$

- 3) Determine the weight factor

$$\gamma_g^{(r)} = \frac{\text{tr}((\nabla_g^{\mathbf{R}(r)} - \nabla_g^{\mathbf{R}(r-1)}) \nabla_g^{\mathbf{R}(r)H})}{\text{tr}(\nabla_g^{\mathbf{R}(r-1)} \nabla_g^{\mathbf{R}(r-1)H})}; \quad (22)$$

- 4) Compute the conjugate direction

$$\mathbf{D}_g^{(r)} = \nabla_g^{\mathbf{R}(r)} + \gamma_g^{(r)} \mathbf{D}_g^{(r-1)}; \quad (23)$$

- 5) Determine the Armijo step size⁵

$$\mu_g^{(r)} = \arg \max_{\mu_g} f(\exp(\mu_g \mathbf{D}_g^{(r)}) \Theta_g^{(r)}); \quad (24)$$

- 6) Perform rotational update along local geodesics

$$\Theta_g^{(r+1)} = \exp(\mu_g^{(r)} \mathbf{D}_g^{(r)}) \Theta_g^{(r)}. \quad (25)$$

Remark 3. The adapted RCG method leverages the fact that block unitary matrices are closed under multiplication (but not necessarily under addition). Its advantage over universal manifold optimization [40], [41] is trifold:

- No retraction is involved;
- Lower computational complexity per iteration [50];
- Faster convergence thanks appropriate operational space.

The complex derivative of (18a) w.r.t. RIS block g is

$$\frac{\partial R}{\partial \Theta_g^*} = \frac{1}{\eta} \mathbf{H}_g^H \mathbf{H} \mathbf{W} \left(\mathbf{I} + \frac{\mathbf{W}^H \mathbf{H}^H \mathbf{H} \mathbf{W}}{\eta} \right)^{-1} \mathbf{W}^H \mathbf{H}_g^H. \quad (26)$$

Algorithm 1 summarizes the adapted RCG method for the RIS rate maximization subproblem.

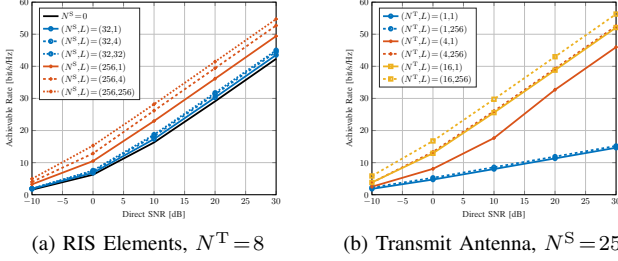
⁵To double the step size, simply square the argument instead of recomputing the matrix exponential, i.e., $\exp(2\mu_g \mathbf{D}_g) = \exp^2(\mu_g \mathbf{D}_g)$.

Algorithm 1: RCG Method for RIS MIMO-PC Rate Maximization
Input: $\mathbf{H}^D, \mathbf{H}^F, \mathbf{H}^B, \mathbf{W}, L, \eta$
Output: Θ^*

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1:  $r \leftarrow 0, \Theta^{(0)}$ 
2: Repeat
3:    $r \leftarrow r+1$ 
4:   For  $g \leftarrow 1$  to  $G$ 
5:      $\Theta_g^{(r)} \leftarrow (26), (21)-(25)$ 
6:   End For
7: Until  $|R^{(r)} - R^{(r-1)}|/R^{(r-1)} \leq \epsilon$ 

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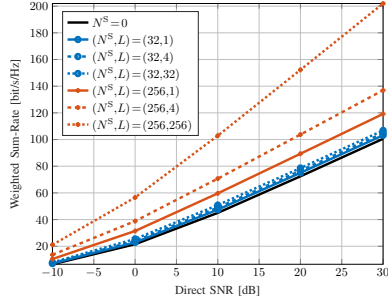


Fig. 8. Average weighted sum-rate versus SNR, RIS elements N^S and group size L . $(N^T, N^R, N^E, K) = (8, 4, 3, 5)$, $(A^D, A^F, A^B) = (65, 54, 46)$ dB, $\rho_k = 1, \forall k$.

where ρ_k is the weight of user k and \mathbf{Q}_k is the interference-plus-noise covariance matrix

$$\mathbf{Q}_k = \sum_{j \neq k} \mathbf{H}_{kj} \mathbf{W}_j \mathbf{W}_j^H \mathbf{H}_{kk}^H + \eta \mathbf{I}. \quad (35)$$

For a given Θ , (34) reduces to conventional linear beamforming problem, for which a closed-form iterative solution based on WSR-Weighted MMSE (WMMSE) relationship is proposed in [53]. At iteration r , the Minimum Mean-Square Error (MMSE) combiner at receiver k is

$$\mathbf{G}_k^{(r)} = \mathbf{W}_k^{(r-1)H} \mathbf{H}_{kk}^H (\mathbf{Q}_k^{(r-1)} + \mathbf{H}_{kk} \mathbf{W}_k^{(r-1)} \mathbf{W}_k^{(r-1)H} \mathbf{H}_{kk}^H)^{-1}, \quad (36)$$

the corresponding error matrix is

$$\mathbf{E}_k^{(r)} = (\mathbf{I} + \mathbf{W}_k^{(r-1)H} \mathbf{H}_{kk}^H \mathbf{Q}_k^{(r-1)} \mathbf{H}_{kk} \mathbf{W}_k^{(r-1)})^{-1}, \quad (37)$$

the Mean-Square Error (MSE) weight is

$$\Omega_k^{(r)} = \rho_k \mathbf{E}_k^{(r)-1}, \quad (38)$$

the Lagrange multiplier is

$$\lambda_k^{(r)} = \frac{\text{tr}(\eta \Omega_k^{(r)} \mathbf{G}_k^{(r)} \mathbf{G}_k^{(r)H} + \sum_j \Omega_k^{(r)} \mathbf{T}_{kj}^{(r)} \mathbf{T}_{kj}^{(r)H} - \Omega_j^{(r)} \mathbf{T}_{jk}^{(r)} \mathbf{T}_{jk}^{(r)H})}{P_k}, \quad (39)$$

where $\mathbf{T}_{kj}^{(r)} = \mathbf{G}_k^{(r)} \mathbf{H}_{kj} \mathbf{W}_j^{(r)}$. The precoder at transmitter k is

$$\mathbf{W}_k^{(r)} = \left(\sum_j \mathbf{H}_{jk}^H \mathbf{G}_j^{(r)H} \Omega_k^{(r)} \mathbf{G}_j^{(r)} \mathbf{H}_{jk} + \lambda_k^{(r)} \mathbf{I} \right)^{-1} \mathbf{H}_{kk}^H \mathbf{G}_j^{(r)H} \Omega_k^{(r)}. \quad (40)$$

Once $\{\mathbf{W}_k\}$ is determined, the complex derivative of (34a) w.r.t. RIS block g is

$$\begin{aligned} \frac{\partial J_2}{\partial \Theta_g^*} &= \sum_k \rho_k \mathbf{H}_{k,g}^H \mathbf{Q}_k^{-1} \mathbf{H}_{kk} \mathbf{W}_k \mathbf{E}_k \mathbf{W}_k^H \\ &\quad \times (\mathbf{H}_{k,g}^H - \mathbf{H}_{kk}^H \mathbf{Q}_k^{-1} \sum_{j \neq k} \mathbf{H}_{kj} \mathbf{W}_j \mathbf{W}_j^H \mathbf{H}_{j,g}^H). \end{aligned} \quad (41)$$

The RIS subproblem can be solved by RCG Algorithm 1 with (26) replaced by (41).

A new observation from Fig. 8 that the interference alignment capability of BD RIS scales much faster with group size than number of elements.⁶

⁶The results are not very stable and depend heavily on initialization.

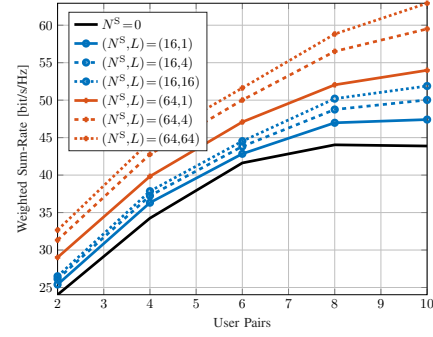


Fig. 9. Average weighted sum-rate versus user pairs K , RIS elements N^S and group size L at SNR=15dB. $(N^T, N^R, N^E) = (4, 4, 3)$, $\rho_k = 1, \forall k$.

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