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Reconfigurable Intelligent Surfaces:

Beamforming, Modulation, and Channel Shaping

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Declaration

I hereby declare that the contents presented in this dissertation are original and have been carried out by myself under the guidance of my supervisor Prof. Bruno Clerckx. Any work from other researchers, scholars, or sources have been properly cited and acknowledged. The contents have not been submitted in whole or in part for consideration of any other degree or qualification in any academic institution. I am aware of the ethical standards and academic integrity policies of Imperial College London, and I have adhered to these principles throughout the course of my study. In signing this declaration, I affirm my commitment to academic honesty, intellectual integrity, and the pursuit of knowledge in the service of truth and understanding.

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The source code of all simulation results in this dissertation are publicly available at https://github.com/snowztail/.

Yang Zhao March 2024

Abstract

This is where you write your abstract ...

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Abbreviations

bpcu bits per channel use

bps/Hz bits per second per Hertz

AF Amplify-and-Forward
AI Artificial Intelligence
AM Arithmetic Mean

AmBC Ambient Backscatter Communication

AO Alternating Optimization

AP Access Point

AWGN Additive White Gaussian Noise

BackCom Backscatter Communication

BBC Bistatic Backscatter Communication

BCD Block Coordinate Descent

BD Beyond-Diagonal BER Bit Error Rate

BIBO Binary-Input Binary-Output BLS Backtracking Line Search

CLT Central Limit Theorem
CP Canonical Polyadic
CR Cognitive Radio

CSCG Circularly Symmetric Complex Gaussian

CSI Channel State Information

CSIT Channel State Information at the Transmitter

CW Continuous Waveform

DC Direct Current

xiv Abbreviations

DCMC Discrete-input Continuous-output Memoryless Channel

DF Decode-and-Forward

DMC Discrete Memoryless Channel

DMMAC Discrete Memoryless Multiple Access Channel
DMTC Discrete Memoryless Thresholding Channel

DoF Degree of Freedom
DP Dynamic Programming

EIRP Effective Isotropic Radiated Power

eMBB enhanced Mobile Broadband

FDMA Frequency-Division Multiple Access

FPGA Field-Programmable Gate Array

GM Geomtric Mean

GP Geometric Programming

i.i.d. independent and identically distributed

IC Interference Channel
IM Index Modulation
IoE Internet of Everything

IoT Internet of Things

KKT Karush-Kuhn-Tucker

LC Low-Complexity
LoS Line-of-Sight

M2M Machine-to-Machine

MAC Multiple Access Channel

MBC Monostatic Backscatter Communication

MC Multiplication Coding

MIMO Multiple-Input Multiple-Output
MISO Multiple-Input Single-Output

ML Maximum-Likelihood

MMSE Minimum Mean-Square-Error

Abbreviations

mMTC massive Machine-Type Communication

MRC Maximal Ratio Combining
MRT Maximum Ratio Transmission

MSE Mean-Square Error

NLoS Non-Line-of-Sight

NOMA Non-Orthogonal Multiple Access

OFDM Orthogonal Frequency-Division Multiplexing

PC Point-to-point Channel

PDF Probability Density Function PGA Projected Gradient Ascent PIN Positive Intrinsic Negative

PS Power Splitting
PSK Phase Shift Keying

QAM Quadrature Amplitude Modulation

QoS Quality of Service

R-E Rate-Energy

RCG Riemannian Conjugate Gradient

RF Radio-Frequency

RFID Radio-Frequency Identification
RIS Reconfigurable Intelligent Surface

SC Superposition Coding

SCA Successive Convex Approximation
 SDMA Space-Division Multiple Access
 SDP Semi-Definite Programming
 SDR Semi-Definite Relaxation

SIC Successive Interference Cancellation

SIMO Single-Input Multiple-Output

SINR Signal-to-Interference-plus-Noise Ratio

SISO Single-Input Single-Output

SMAWK Shor-Moran-Aggarwal-Wilber-Klawe

xvi Abbreviations

SMF Scaled Matched Filter SNR Signal-to-Noise Ratio SR Symbiotic Radio

SVD Singular Value Decomposition

SWIPT Simultaneous Wireless Information and Power Transfer

TDMA Time-Division Multiple Access

TS Time Switching

UE User Equipment

URLLC Ultra-Reliable Low-Latency Communication

WF Water-Filling

WIT Wireless Information Transfer

WPCN Wireless Powered Communication Network

WPT Wireless Power Transfer WSR Weighted Sum-Rate

ZF Zero-Forcing

Notation

Constants

e Euler's number $\simeq 2.71828...$ j The imaginary unit $= \sqrt{-1}$

 π Archimedes' constant $\simeq 3.14159...$

Objects

a, A Scalar

a Column vector

A Matrix
A Finite set
0 Zero matrix
1 One matrix
I Identity matrix

Sets

 \mathbb{R} Real numbers

 \mathbb{R}_+ Real nonnegative numbers

 \mathbb{C} Complex numbers

I Probability domain [0, 1]

 $\mathbb{H}^{n\times n}_+$ Positive semi-definite matrices of dimension $n\times n$

 $\mathbb{U}^{n \times n}$ Unitary matrices of dimension $n \times n$

Operations

 $(\cdot)^*$ Complex conjugate

 $(\cdot)^{\mathsf{T}}$ Transpose

 $(\cdot)^{H}$ Hermitian (conjugate transpose)

 $(\cdot)^{\dagger}$ Moore-Penrose inverse

xviii Notation

$(\cdot)^+$	Ramp function $\max(0,\cdot)$
$ \cdot $	Absolute value of a complex number
$\ \cdot\ $	Euclidean norm of a vector
$\lVert \cdot \rVert_{\mathrm{F}}$	Frobenius norm of a matrix
$\operatorname{arg}(\cdot)$	Argument of a complex number
$\operatorname{card}(\cdot)$	Cardinality of a finite set
$\log(\cdot)$	Natural logarithm of a real number
$\exp(\cdot)$	Exponential of a scalar or square matrix
$\mathrm{tr}(\cdot)$	Trace of a square matrix
$\det(\cdot)$	Determinant of a square matrix
$\mathrm{sv}(\cdot)$	Singular values sorted from largest to smallest
$\mathrm{diag}(\cdot)$	Constructs a square matrix with inputs on the main diagonal
$\operatorname{diag}^{-1}(\cdot)$	Retrieves the main diagonal of a square matrix
$\Re(\cdot)$	Retrieves the real part of a complex number
$\Im(\cdot)$	Retrieves the imaginary part of a complex number
$\mathbb{E}(\cdot)$	Expectation operator
$\mathbb{A}(\cdot)$	Extracts the Direct Current component of a signal
\odot	Hadamard product
\otimes	Kronecker product
$(\cdot)_{[x:y]}$	Shortcut for $(\cdot)_x, (\cdot)_{x+1}, \dots, (\cdot)_y$

Distributions

 \sim Follows a distribution

 $\mathcal{CN}(0,\Sigma)$ — Multivariate Circularly Symmetric Complex Gaussian with covariance Σ

Subscripts

Backward
Direct
Forward
Information
Power

Superscripts

 $(\cdot)^{(r)}$ r-th iterated value $(\cdot)^*$ Stationary point

Chapter 1

Introduction

1.1 Background and Motivation

The quest for better wireless connectivity has been long-standing since Marconi's illuminating radio in 1895. Great successes have been made at the transmitter and receiver sides over the past century, and the communications society is unprecedentedly close to the Shannon limit [2]. By 2025, global mobile data traffic is expected to reach 607 exabytes per year [3] while the number of connected devices may exceed 75 billion [4]. At the same time, wireless applications are also evolving in various forms to address world-changing incidents like COVID-19, climate change, geopolitical tensions, and Artificial Intelligence (AI) revolution. An initial attempt was made in 5G where the network prioritizes among high-throughput, ubiquitous-coverage, high-reliability, low-latency, massive-connectivity, and energy-efficient services [5]. However, the desire of human and machine for better communication shows no signs of slowing down. Emerging applications such as smart cities, autonomous driving, telemedicine, extended reality, federated learning, and generative intelligence are calling for a stronger and smarter wireless infrastructure. It is envisioned that 6G will be designed to meet the following requirements [6–8]:

- *Throughput*: The network would be able to provide a peak data rate of 1 Tbps and an average data rate of 100 Gbps per user.
- Latency: Sub-millisecond end-to-end latency would be achieved for low-latency
 applications like autonomous driving and remote surgery.
- *Reliability*: A success rate of 99.9999% would be guaranteed for ultra-reliable applications like industrial automation and cooperative robotics.

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• *Connectivity*: The number of connected devices per kilometer square would be increased to 10 million for supporting Internet of Everything (IoE).

- *Mobility*: Commercial airlines with a maximal velocity of 1000 km/h would be the target application scenario.
- *Energy efficiency*: Power consumption has been a major criticism for 5G. It is expected that energy per bit would be reduced by over 90% in 6G to reduce carbon footprints.
- *Positioning accuracy*: Thanks to THz base stations, a 3D positioning accuracy of centimeter level may be achieved for indoor and outdoor environments.
- *Coverage*: Poor coverage has been another bottleneck for 5G. A terrestrial-satelliteaerial integrated network would provide a ubiquitous and uniform coverage for urban, rural, and remote areas.
- Security and privacy: Physical-layer security can be improved with narrower beams at higher frequencies and destructive scattering at the environment. Privacy can be enhanced with federated learning and homomorphic encryption.

Beyond the statistical requirements above, the next-generation wireless network is desired to integrate human, machine, environment, and AI seamlessly for a harmonic ecosphere. This paradigm shift from *connectivity* to *intelligence* is fueled by the latest advances in machine learning (theory) and programmable metamaterials (hardware). The former enables the network to understand the environment while the latter evolves the environment from a chaotic medium to a conscious agent that can serve on demand. Together, they form a symbiotic relationship with the potential to revolutionize how the world energize, sense, communicate, and interact.

One promising candidate within this 6G vision is Reconfigurable Intelligent Surface (RIS), a programmable metasurface that recycles and redistributes the electromagnetic waves in the air for improved wireless performance. It could be incorporated into the transmitter and receiver for *beamforming*, employed as a free-rider information source for *modulation*, or simply placed in space as a standalone device for *channel shaping*. These applications have distinctive requirements and trade-offs, but the operation principles are the same and those roles are not mutually exclusive. Imagine a future where everything can be "smartened" by coating with a metamaterial layer and attaching a microcontroller tag. Only a few active radiating sources (like the sun) are needed, while most objects (like the universe) can exploit the surrounding waves to energize themselves, sense the environment, communicate with others, and help those in need when idle. This vision motivates three research questions to be addressed in this thesis:

- How does RIS impact different wireless applications such as communication and far-field power transfer?
- Is it possible to integrate RIS with Backscatter Communication (BackCom) into a versatile tool that blurs the boundary between the network and environment?
- What is the ultimate limit of channel reshaping through passive RIS and what are the implications on transceiver designs?

Before delving into these questions, we first provide a short overview of RIS and introduce some potential applications in the next section. A detailed literature review and technical discussion on RIS and other topics will be reserved for Chapter 2.

1.2 Overview on Reconfigurable Intelligent Surface (RIS)

1.2.1 Concept

RIS is commonly known as a planar surface involving numerous wave scattering elements (a.k.a. unit cells, reflective patches), whose amplitude and phase responses can be engineered in real-time to achieve a desired radiation pattern. As shown in Fig. 1.1, its typical architecture consists of three stacked layers and a controller [1]. The top layer is a two-dimensional array of scattering elements printed on a dielectric substrate. The elements directly interact with the impinging waves, which are usually fabricated from metamaterial or patch/dipole antennas with sub-wavelength dimension and spacing. The middle layer is a copper ground plate that provides voltage reference and avoids signal leakage. The bottom later is a circuit board that associate each element with adjustable components like varactor and Positive Intrinsic Negative (PIN) diodes [9]. It also hosts a Field-Programmable Gate Array (FPGA) controller that controls the circuit and coordinate with other devices in the network. By adjusting the scatter response of each element, the RIS can effectively manipulate the wavefront and thus improve the ambient wireless environment.

1.2.2 Characteristics

The key characteristics of RIS are summarized as follows:

• Passive and environmental-friendly: RIS reflects the incident waves in a passive manner and does not require dedicated Radio-Frequency (RF) chains. This is different from

¹The controller may be implemented with low-power components and powered by ambient energy.

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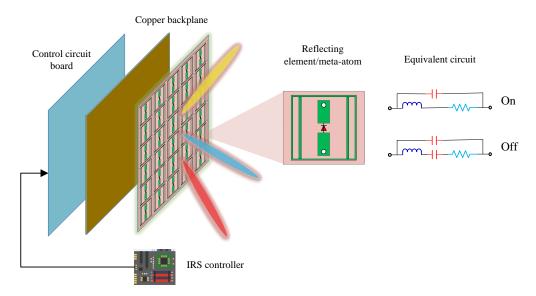


Fig. 1.1 A typical architecture of RIS [1].

Amplify-and-Forward (AF) relays that require power-hungry oscillators and introduces additional thermal noise.

- *Flexible:* It provides a software configurable environment that can be adapted for different applications and scenarios. This is different from reflectarray [10] and frequency selective surfaces [11] with predefined radiation patterns and frequency response.
- *Full-duplex and universal:* This physical-layer solution can simultaneously benefit downlink and uplink thanks to channel reciprocity [12], and simultaneously support communication, sensing, and power transfer without self-interference. This is different from Decode-and-Forward (DF) relays that are designed for a specific communication link and suffers from packet delays.
- Low-cost and conformal: It can be manufactured from low-cost materials and deployed in various forms (e.g., walls, windows, ceilings, tables) to provide seamless coverage and powerful customization for indoor and outdoor environments. This is different from conventional multi-antenna systems that features complex hardware and bulky structures.

1.2.3 Applications

1.3 Outline and Contributions

The thesis is outlined as follows:

- Chapter 1 introduces RIS as a promising technology for ambient wave redirection and highlights its potential benefits in future wireless networks. It discusses the motivation, objectives, and contributions of each research chapter. A list of publications is also provided.
- Chapter 2 provides the necessary background knowledge for the subsequent chapters, including the fundamental concepts, operating principles, hardware implementation, signal and system models, performance metrics, and design challenges for RIS, Wireless Power Transfer (WPT), Simultaneous Wireless Information and Power Transfer (SWIPT), BackCom, and Multiple-Input Multiple-Output (MIMO) systems. It also reviews the state-of-the-art research in relevant topics and raise critical questions to be addressed in the following chapters.
- Chapter ?? investigate the impact of RIS on wireless information and power transfer. The key contributions include:
 - Introduce RIS to a multi-antenna multi-carrier SWIPT system with different receiver architectures;
 - Consider joint waveform and beamforming design for the proposed system under a practical energy harvester model;
 - Characterize the Rate-Energy (R-E) performance trade-off by maximizing harvested energy subject to different communication rate constraints;
 - Propose local-optimal and low-complexity algorithms and evaluate their narrow and wideband performance through numerical simulations;
 - Discuss the array gain for communication and the scaling order for power transfer in terms of the number of transmit antennas and RIS elements.
- Chapter ?? develops a novel scatter protocol that integrates beamforming and modulation. The key contributions include:
 - Provide an in-depth comparison of RIS with state-of-the-art BackCom technologies and discuss the key properties of active and passive transmissions coexisting systems;

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 Unify RIS and BackCom as one battery-free cognitive radio called RIScatter, where dispersed or co-located scatter nodes ride over an active primary link to modulate their own information and engineering the legacy channel simultaneously;

- Integrate backscatter modulation and passive beamforming seamlessly into the input distribution design that allows arbitrary trade-off in between;
- Propose a low-complexity cooperative receiver that sequentially decodes both coexisting links and exploits backscatter detection as part of channel training;
- Characterize the achievable primary-backscatter rate region over different designs
 of input distribution at the scatter nodes, active beamforming at the Access Point
 (AP), and energy detector at the receiver;
- Discuss the impact of practical factors such as the number of scatter nodes and states, transmit antenna size, backscatter symbol duration, and Signal-to-Noise Ratio (SNR) on the system performance.
- Chapter ?? explores the ultimate channel shaping capabilities of RIS in MIMO systems. The key contributions include:
 - Quantify the capability of a passive RIS to reshape the MIMO Point-to-point Channel (PC) in terms of singular values via analytical bounds and numerical optimization;
 - Focus on a general Beyond-Diagonal (BD)-RIS architecture featuring elementwise connections and demonstrate its superior signal processing performance (subspace alignment and subchannel rearrangement) over the widely-adopted diagonal model;
 - Propose an efficient Riemannian Conjugate Gradient (RCG) algorithm for general BD-RIS optimization and provide low-complexity solutions for quadratic problems;
 - Characterize the Pareto frontiers of channel singular values and obtain powerand rate-optimal BD-RIS configurations in MIMO PC;
 - Investigate the impact of BD-RIS on leakage interference suppression and Weighted Sum-Rate (WSR) maximization in MIMO Interference Channel (IC);
 - Discuss how channel shaping helps to decouple joint RIS-transceiver designs with comparable performance and significantly reduced complexity.

1.4 Publications 7

1.4 Publications

• Y. Zhao, B. Clerckx, and Z. Feng, "IRS-aided SWIPT: Joint waveform, active and passive beamforming design under nonlinear harvester model," *IEEE Transactions on Communications*, vol. 70, pp. 1345–1359, 2022

- Y. Zhao and B. Clerckx, "Riscatter: Unifying backscatter communication and reconfigurable intelligent surface," 12 2022
- —, RIS in Wireless Information and Power Transfer. John Wiley & Sons, Ltd, 2023, pp. 271–295
- Y. Zhao, H. Li, M. Franceschetti, and B. Clerckx, "Channel shaping using reconfigurable intelligent surfaces: From diagonal to beyond," *To be submitted to IEEE Transactions on Wireless Communications*

Chapter 2

Background and Literature Review

2.1 Reconfigurable Intelligent Surface (RIS)

2.1.1 Hardware Implementation

2.1.1.1 Programmable Metamaterials

Metamaterials refer to artificial structures engineered for unusual properties that may not be found in nature. The concept was initially proposed by Victor Veselago in 1967, who conjectured the existence of mediums with negative dielectric constant $\epsilon < 0$ and negative permeability $\mu < 0$ [17]. Such metamaterials are known as "negative-index" because the refraction index is defined as the *negative* square root $n = -\sqrt{\epsilon\mu} < 0$, in order to be consistent with Maxwell's equations. It was not until 1999 that their feasibility was experimentally demonstrated by John Pendry at Imperial College using split-ring resonators [18]. Since then, metamaterials have attracted significant interests due to their counterintuitive properties, to name a few:

• *Negative refraction:* As shown in Fig. 2.1, the incident and refracted rays stay at the same side of the normal axis. This phenomenon is in contrast to the usual refraction but can still be predicted from Snell's law

$$\frac{\sin \theta_1}{\sin \theta_2} = n. \tag{2.1}$$

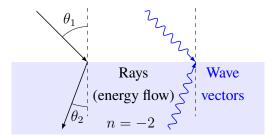


Fig. 2.1 Refraction of electromagnetic waves at the interface between a positive-index and a negative-index material.

• *Opposite wave direction:* As shown in Fig. 2.2, the wave vector and energy flow (indicated by the Poynting vector) are opposite to each other in a negative-index material. This can be inferred from the electric field equation

$$\vec{E} = \vec{E}_0 \exp(jkz - j\omega t) \tag{2.2}$$

where $k=k_0n<0$ is the wavenumber, \vec{E}_0 and k_0 are the free-space reference, z is the propagation distance, ω is the angular frequency, and t is the time. Negative-index materials are thus also called "left-hand" because the propagation direction of the electric and magnetic fields can be determined by a left-hand rule.

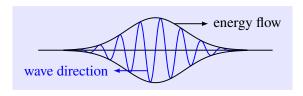


Fig. 2.2 Wave and energy flows in a negative-index material.

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2.5 Multiple-Input Multiple-Output (MIMO)

2.4.3 Ambient Backscatter Communication (AmBC)

Symbiotic Radio (SR)

2.4.4

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