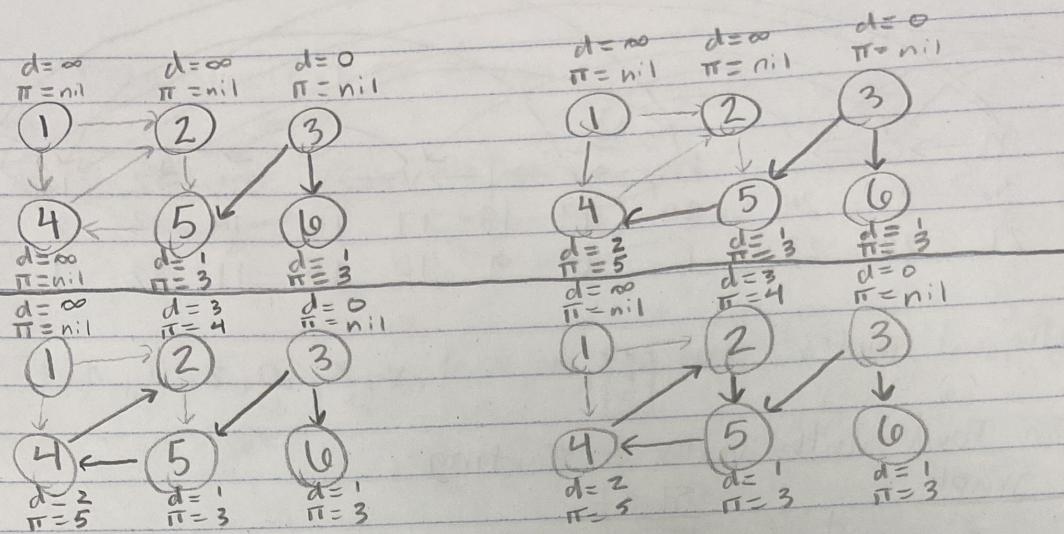
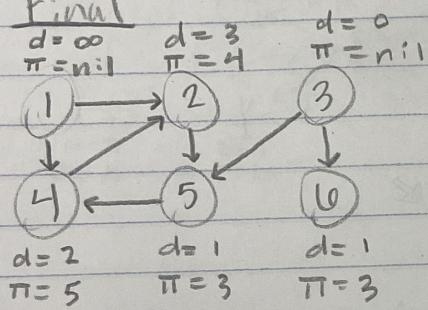


Homework 4

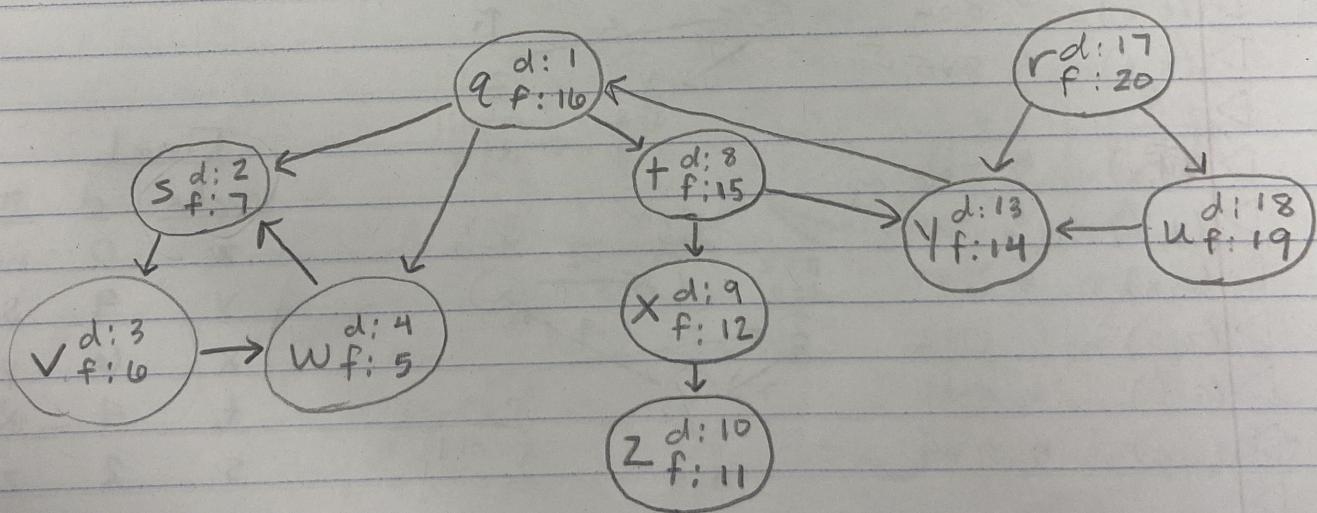
1 ▷



Final

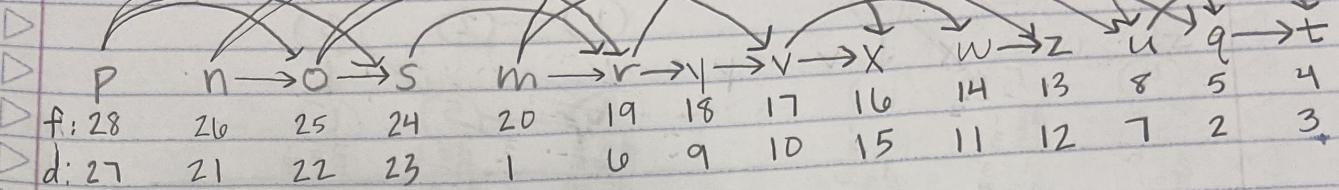


2 ▷



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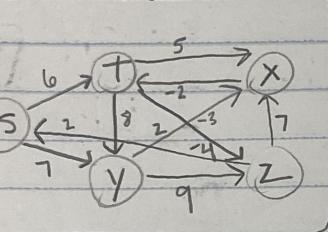
3 ▷



▷ Topological Order: $P, n, o, s, m, r, i, v, x, w, z, u, q, t$

4 ▷ Bellman-Ford with vertex z starting

Given graph



Start

$\pi = \text{nil}$
 $d = \infty$

$\pi = z$
 $d = 2$

$\pi = \text{nil}$
 $d = \infty$

$\pi = \text{nil}$
 $d = \infty$

$\pi = \text{nil}$
 $d = 0$

$\pi = \text{nil}$
 $d = 0$

$\pi = z$
 $d = 7$

$\pi = s$
 $d = 8$

$\pi = s$
 $d = 7$

$\pi = s$
 $d = 9$

$\pi = z$
 $d = 7$

$\pi = \text{nil}$
 $d = 0$

relax

(t, x) no b/c $7 \geq 13$

(t, y) no b/c $9 \geq 16$

(t, z) no b/c $0 \geq 4$

(x, t) yes b/c $8 \geq 5$

(y, x) yes b/c $7 \geq 6$

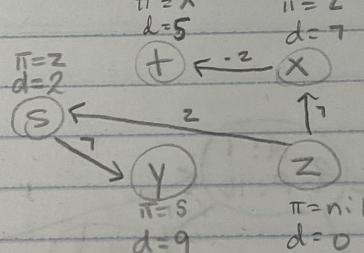
(y, z) no b/c $0 \geq 18$

(z, x) no b/c $6 \geq 7$

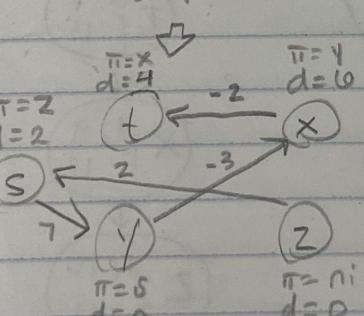
(z, s) no b/c $2 \geq 2$

(s, t) no b/c $5 \geq 8$

(s, y) no b/c $9 \geq 9$



↗

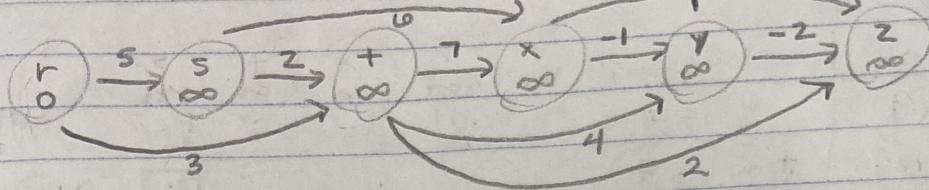


Final

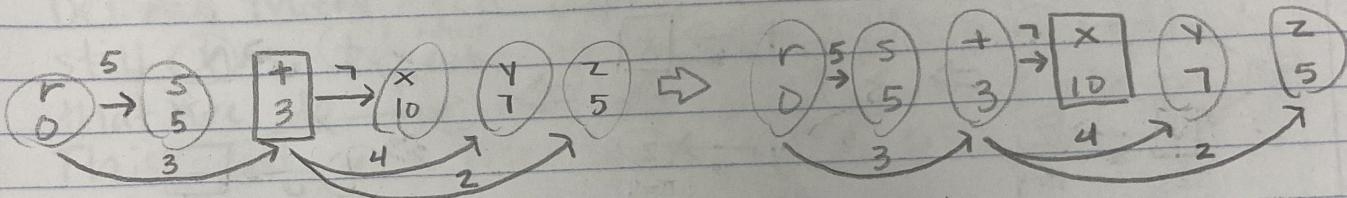
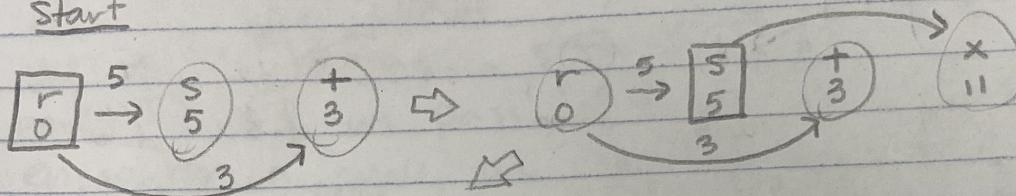
vertex	d	π
z	0	nil
y	9	s
x	6	y
t	4	x
s	2	z

Lauren
Lyon

5 ▷ Run DAG-SHORTEST-PATHS on directed graph using vertex r as start

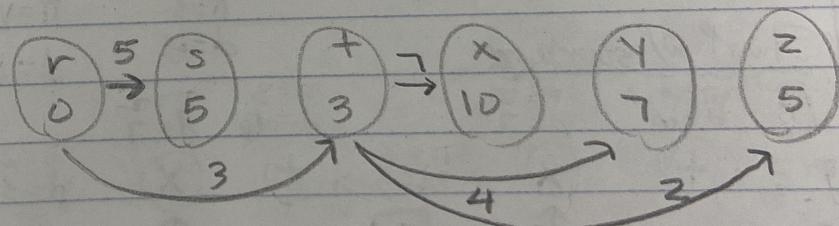


Start

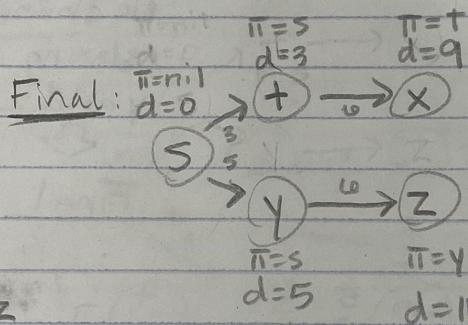
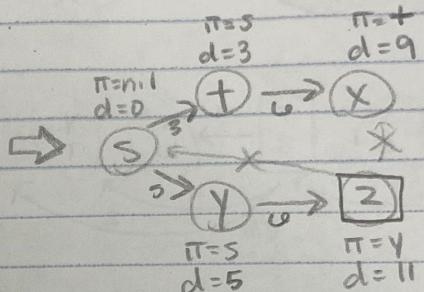
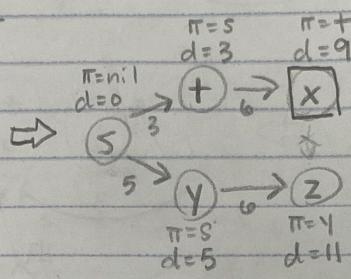
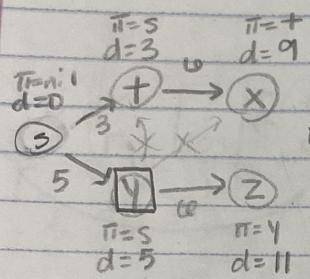
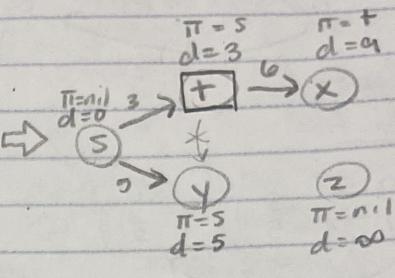
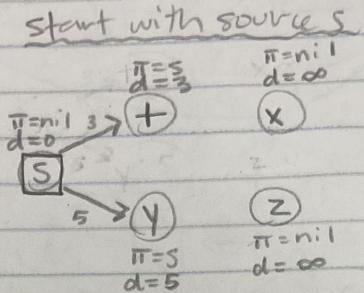
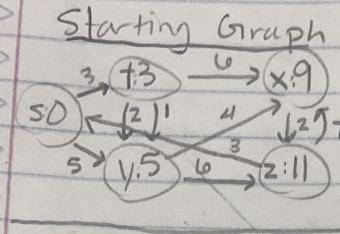


No changes from
relaxing for the vertices
y and z

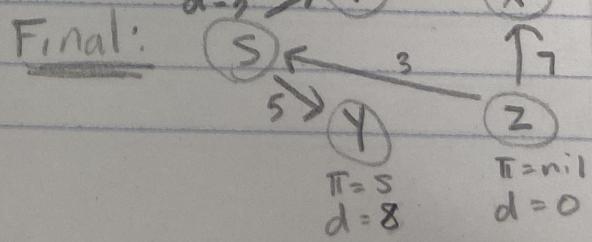
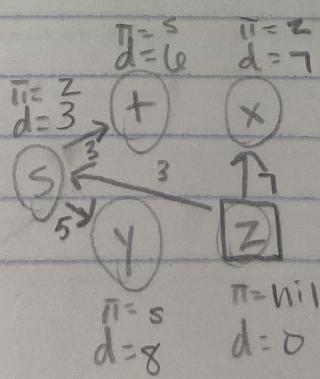
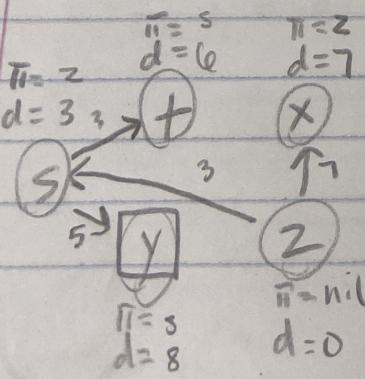
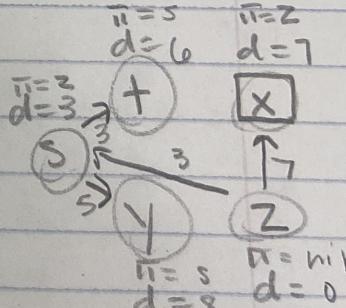
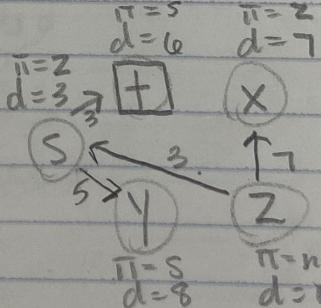
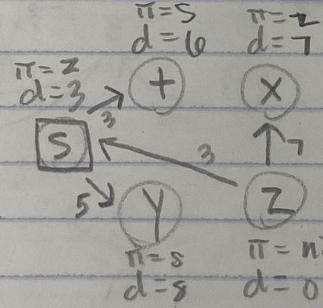
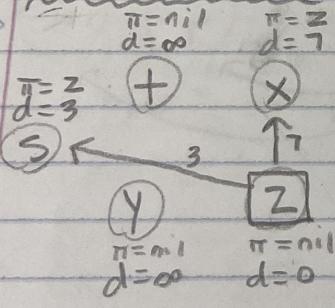
Final



(e) Dijkstra's using vertex S as source then vertex Z



Start w/ source Z



Lawnen Lyons

- After the new vertex and edges are added to the graph G_1 , it may not be an MST. So, using the DFS, we will check for cycles. The DFS algorithm uses white, gray, and black to indicate what has been visited. Using that, if we visit any vertex that is already gray, that is indicative of a cycle. So, when we are performing a DFS, we need a max-heap for each vertex we pass in the stack trace. So if we encounter a cycle, we can look at any vertex before that cycle detection up until a vertex still has adjacencies to check. That will ensure that we do not cut off any part of the graph. This will cost the same as a DFS, which is $O(|V| + |E|)$.