

A multi-stage linear approach to structure from motion

README for supplementary webpage

Paper ID 4

1 Instructions

Please open **index.html** in a web browser, to see images of the following:

- vanishing point matches used for rotation estimation.
- our Sfm reconstructions.

To compare the various reconstructions (for eg. *before* and *after* bundle adjustment), move the mouse over the HTML links to BLINK between the images. Table 1 shows the datasets used in the experiments, out of which the nine in the first three columns are reported in the paper.

1.1 Internet Explorer users

You must choose **Allow blocked content**, if you see a message *To help protect your security, Internet Explorer has restricted this webpage from running scripts or ActiveX controls that could access your computer. Click here for options.*













			
HERZJESU-P25 25 images	CASTLE-P30 30 images	STATUE 111 images	SHED 12 images
			
FACADE1 63 images	FACADE2 38 images	HALLWAY 184 images	HALLWAY1 74 images
			
STREET 65 images	BUILDING1 61 images	BUILDING2 63 images	INDOOR 32 images

Table 1. A sample image from each of the datasets.