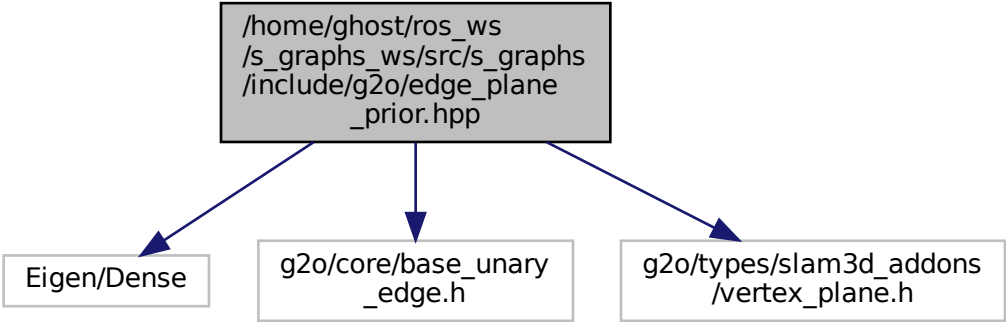


/home/ghost/ros_ws
/s_graphs_ws/src/s_graphs
/include/g2o/edge_plane
_prior.hpp



```
graph TD; A["/home/ghost/ros_ws<br>/s_graphs_ws/src/s_graphs<br>/include/g2o/edge_plane<br>_prior.hpp"] --> B["Eigen/Dense"]; A --> C["g2o/core/base_unary<br>_edge.h"]; A --> D["g2o/types/slam3d_addons<br>/vertex_plane.h"]
```

Eigen/Dense

g2o/core/base_unary
_edge.h

g2o/types/slam3d_addons
/vertex_plane.h