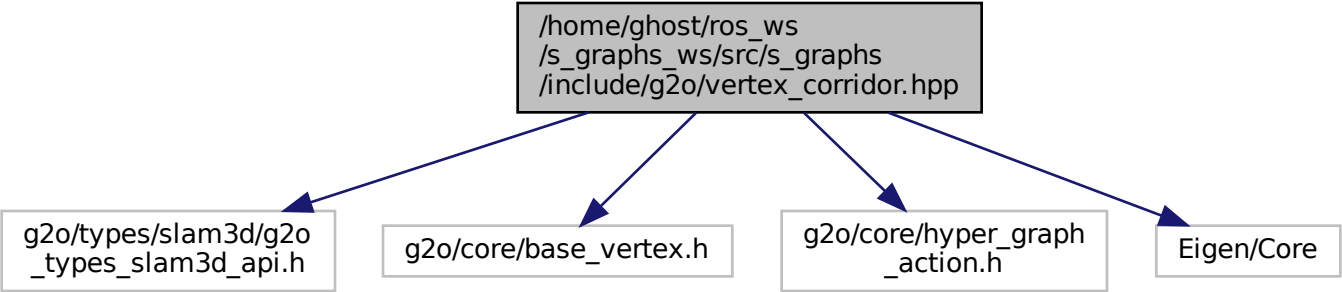


/home/ghost/ros\_ws  
/s\_graphs\_ws/src/s\_graphs  
/include/g2o/vertex\_corridor.hpp



```
graph TD; A["/home/ghost/ros_ws<br>/s_graphs_ws/src/s_graphs<br>/include/g2o/vertex_corridor.hpp"] --> B["g2o/types/slam3d/g2o<br>_types_slam3d_api.h"]; A --> C["g2o/core/base_vertex.h"]; A --> D["g2o/core/hyper_graph<br>_action.h"]; A --> E["Eigen/Core"];
```

The diagram illustrates the include dependencies for the file `/include/g2o/vertex_corridor.hpp`. It is a tree structure where the root node at the top points to four child nodes below it. The root node is shaded gray, while the child nodes are white with gray borders. Blue arrows indicate the direction of the dependencies.

g2o/types/slam3d/g2o  
\_types\_slam3d\_api.h

g2o/core/base\_vertex.h

g2o/core/hyper\_graph  
\_action.h

Eigen/Core