

/home/ghost/ros_ws
/s_graphs_ws/src/s_graphs
/include/s_graphs/ros_utils.hpp

```
graph BT; A["/home/ghost/ros_ws<br>/s_graphs_ws/src/s_graphs<br>/include/s_graphs/ros_utils.hpp"]; B["/home/ghost/ros_ws<br>/s_graphs_ws/src/s_graphs<br>/apps/s_graphs_nodelet.cpp"]; C["/home/ghost/ros_ws<br>/s_graphs_ws/src/s_graphs<br>/apps/scan_matching_odometry_nodelet.cpp"]; B --> A; C --> A;
```

/home/ghost/ros_ws
/s_graphs_ws/src/s_graphs
/apps/s_graphs_nodelet.cpp

/home/ghost/ros_ws
/s_graphs_ws/src/s_graphs
/apps/scan_matching_odometry_nodelet.cpp