


/home/ghost/ros_ws
/s_graphs_ws/src/s_graphs
/include/g2o/vertex_room.hpp

g2o/types/slam3d/g2o
_types_slam3d_api.h

g2o/core/base_vertex.h

g2o/core/hyper_graph
_action.h

Eigen/Core



```
graph TD; A["/home/ghost/ros_ws  
/s_graphs_ws/src/s_graphs  
/include/g2o/vertex_room.hpp"] --> B["g2o/types/slam3d/g2o  
_types_slam3d_api.h"]; A --> C["g2o/core/base_vertex.h"]; A --> D["g2o/core/hyper_graph  
_action.h"]; A --> E["Eigen/Core"];
```