

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.32239366 0.08666196 0.00071699 -0.00017272] +- [0.00178602 0.00112269 0.00018741 0.00014387]

projection: [394.72021679 394.6892266 312.88527353 244.61446426] +- [1.08281381 1.05730944 0.4657314
0.49841922]

reprojection error: [-0.000001, -0.000003] +- [0.332783, 0.282613]

Target configuration

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Type: aprilgrid

Tags:

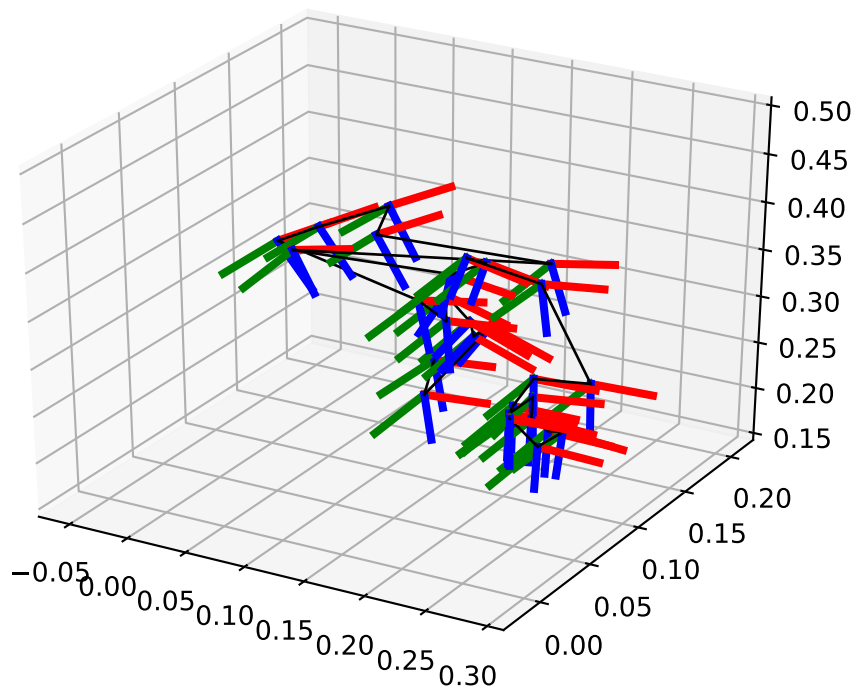
Rows: 6

Cols: 8

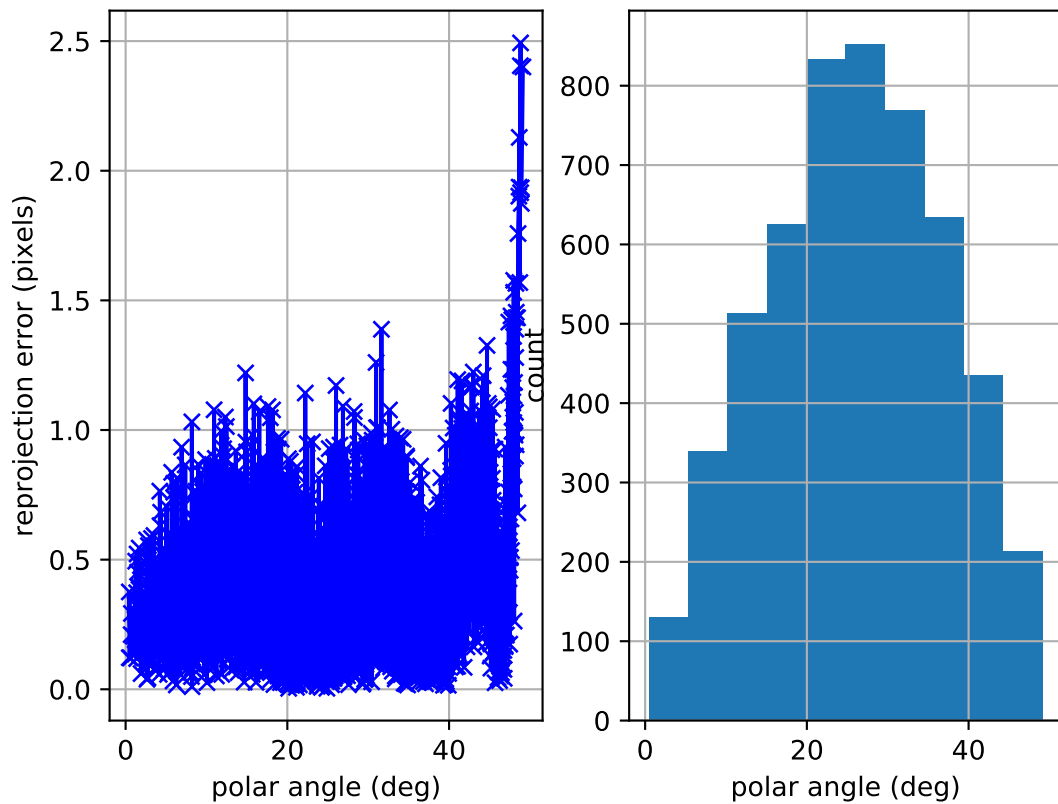
Size: 0.034 [m]

Spacing 0.0099994 [m]

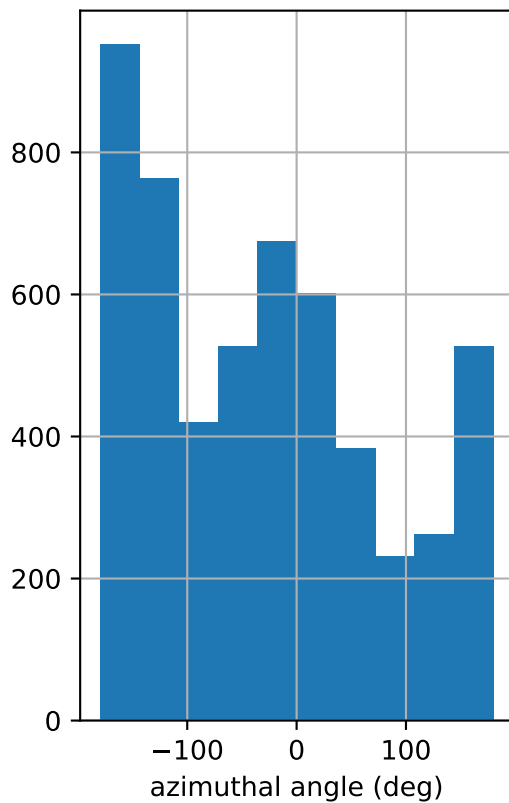
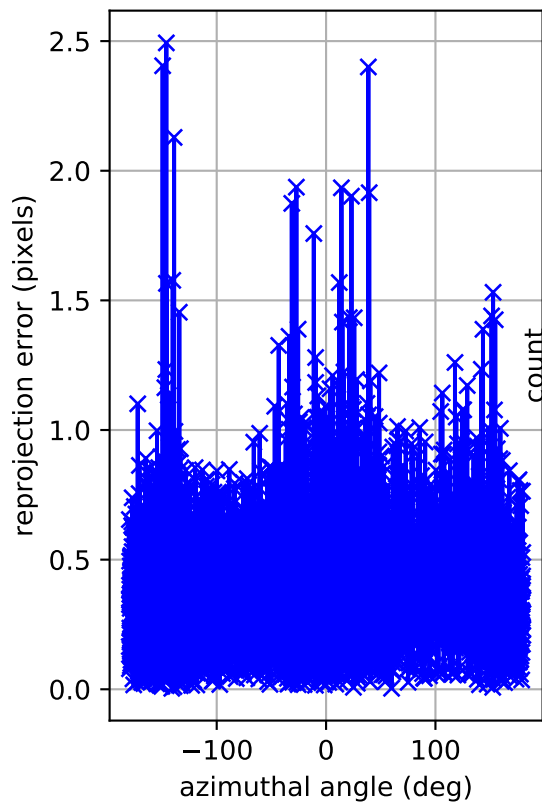
cam0: estimated poses



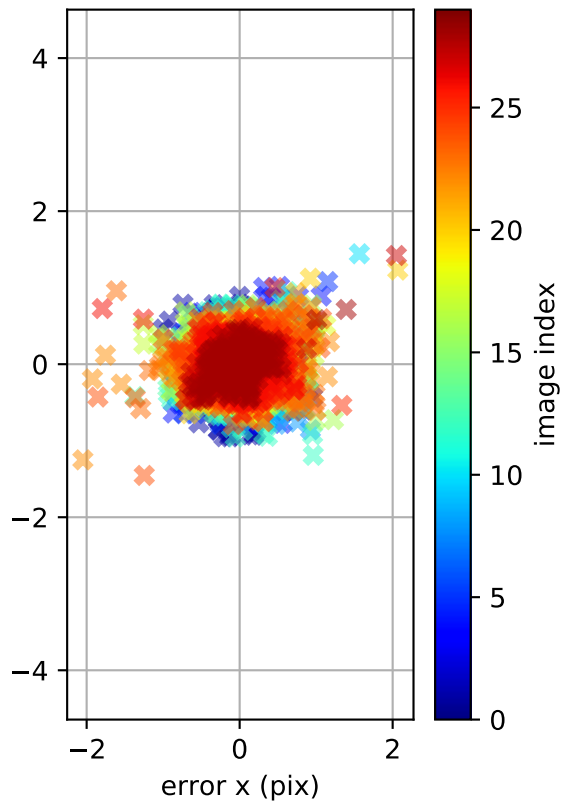
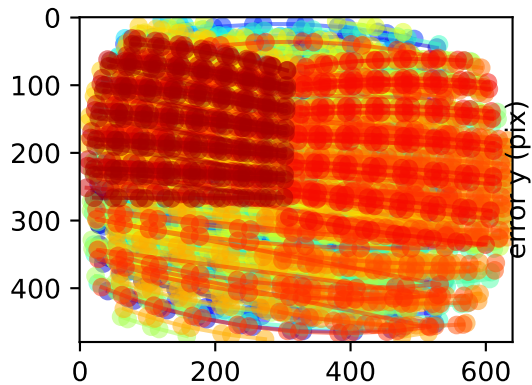
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

