Calibration results
====================
Camera-system parameters:
cam0 (/camera/realsense/color/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [0.08382439 -0.12969977 0.01050247 0.00914606] +- [0.00450935 0.00947031 0.00069214 0.00065312]
projection: [581.13032655 581.46788763 343.68283653 273.81670962] +- [2.93513911 2.9163151 1.41110842 1.42472265]
reprojection error: [-0.000001, 0.000002] +- [0.369571, 0.362580]

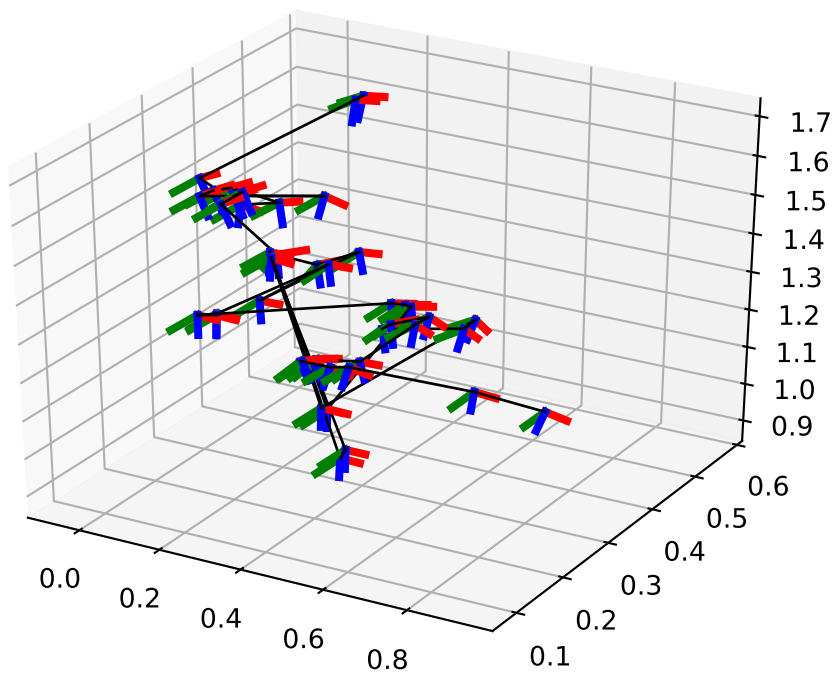Target configuration
====================
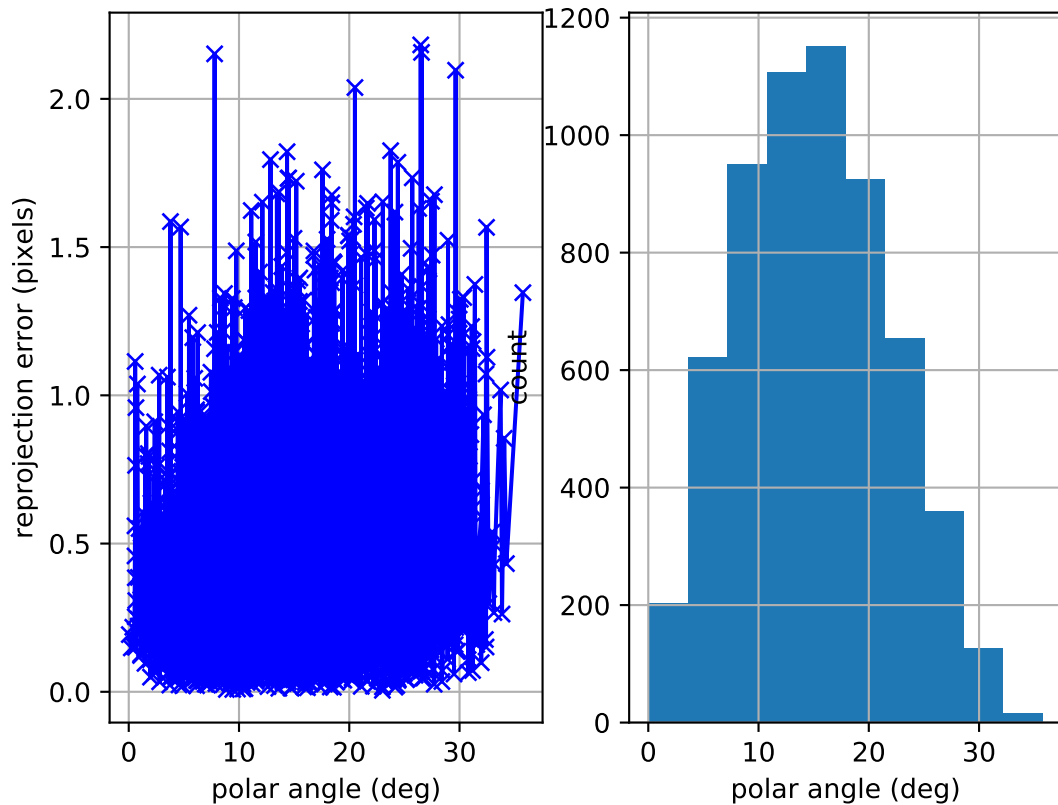
Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.088 [m]
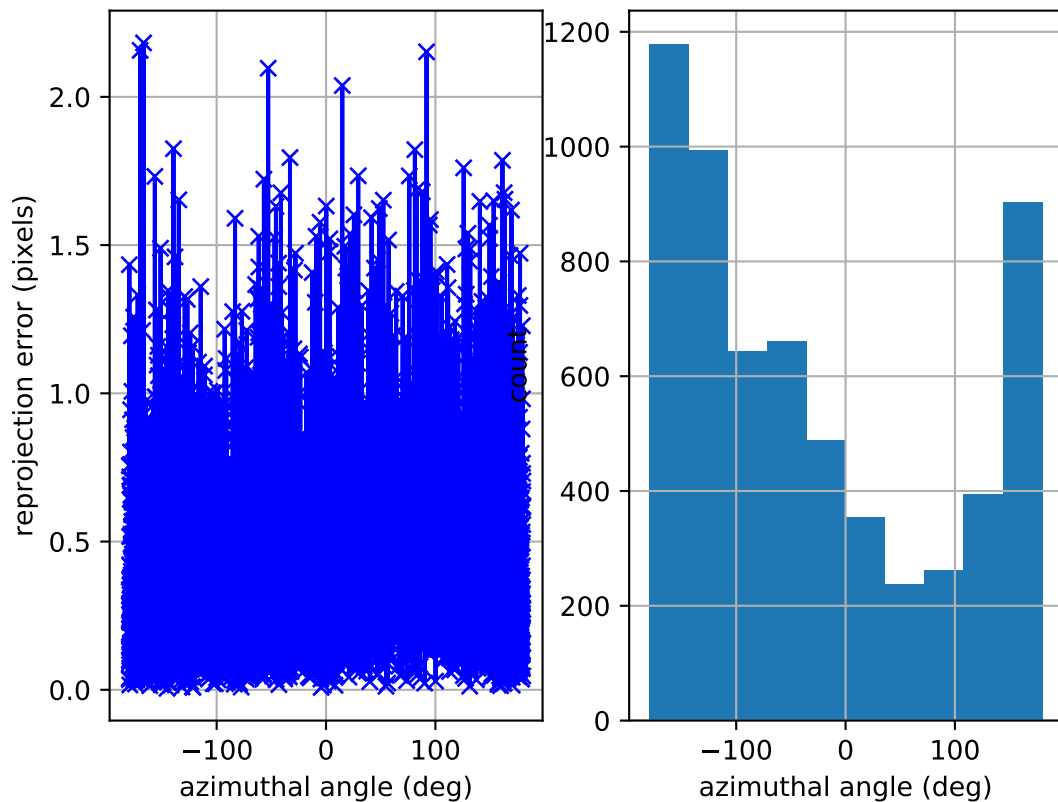Spacing 0.026399999999999996 [m]
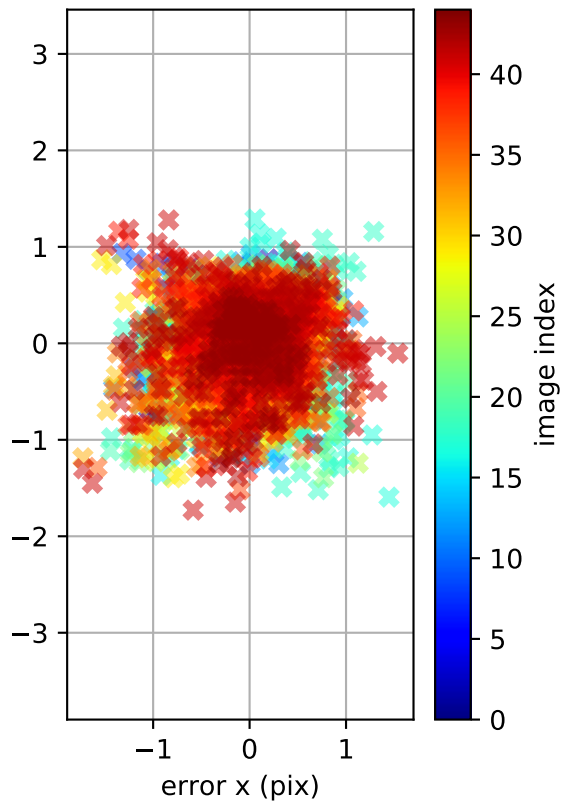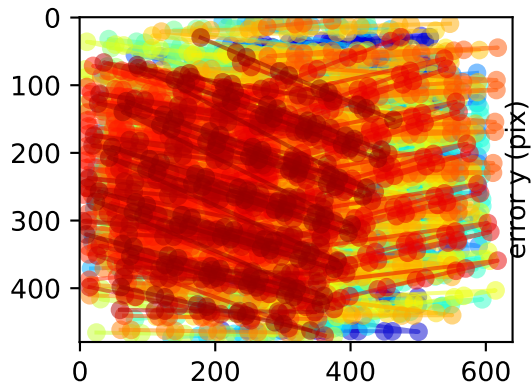
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners
cam0