Calibration results
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Camera-system parameters:
cam0 (/camera/side_right/image_raw):
  type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
  distortion: [-0.35146283 0.12577703 0.00038027 -0.00042396] +- [0.00335971 0.0038754 0.00050903 0.00042778]
  projection: [391.15547519 391.35593062 314.56272966 244.13672452] +- [2.11990886 2.16269815 1.26391169 1.48134526]
  reprojection error: [0.000001, 0.000001] +- [0.152968, 0.145280]

Target configuration
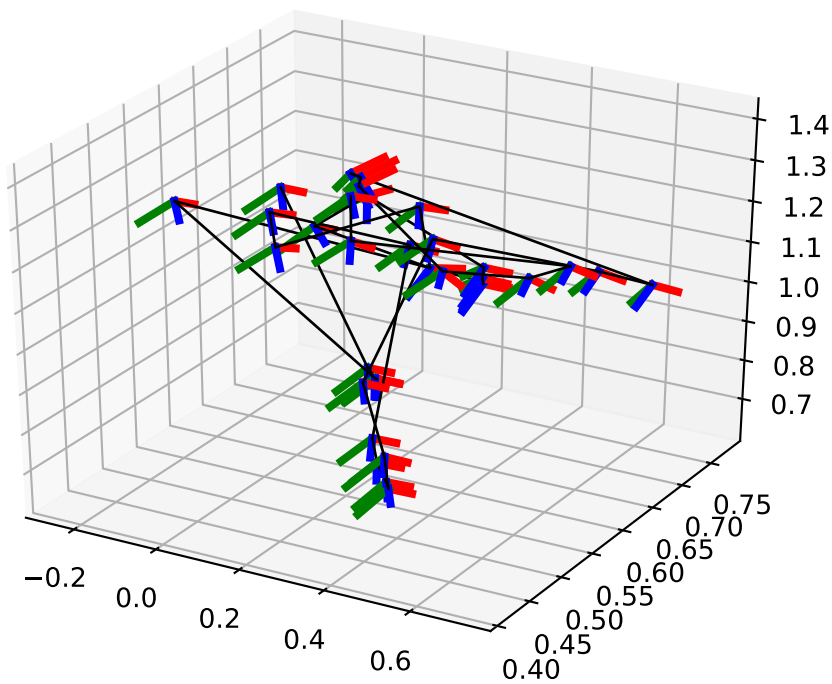====================

  Type: aprilgrid
  Tags:
  Rows: 6
  Cols: 6
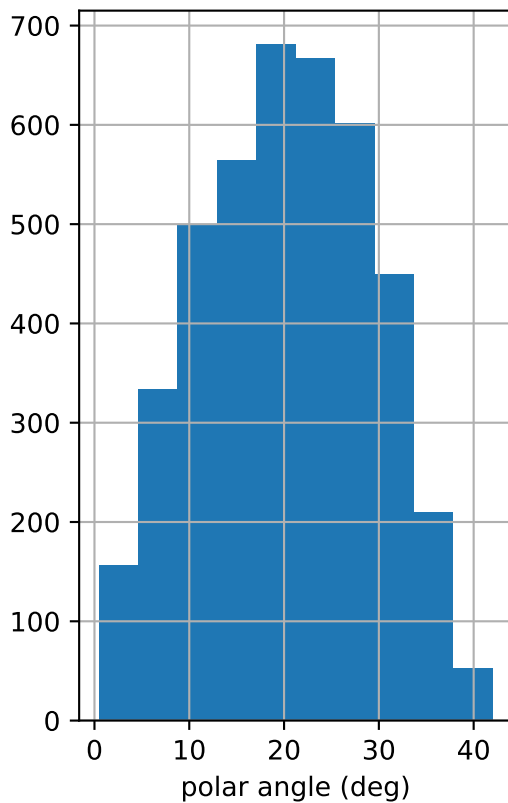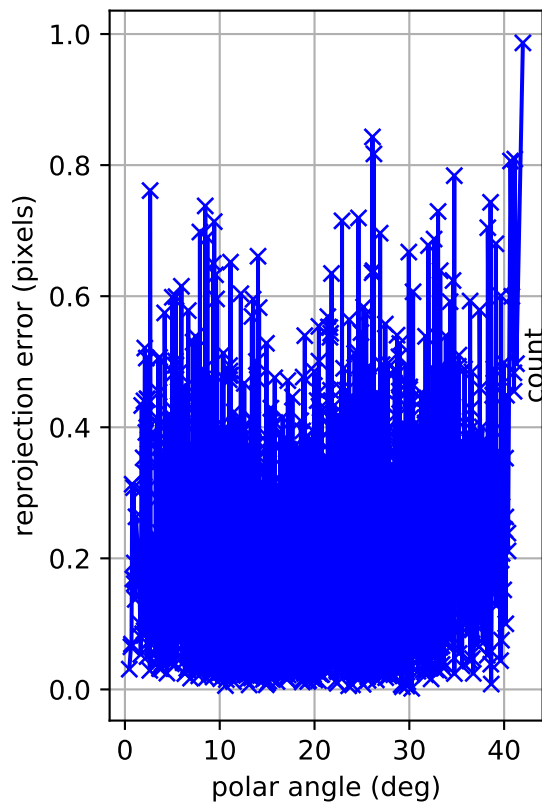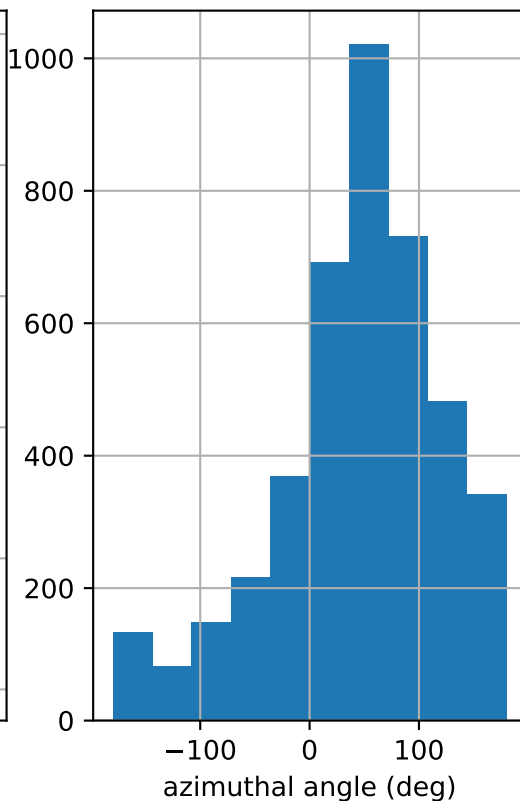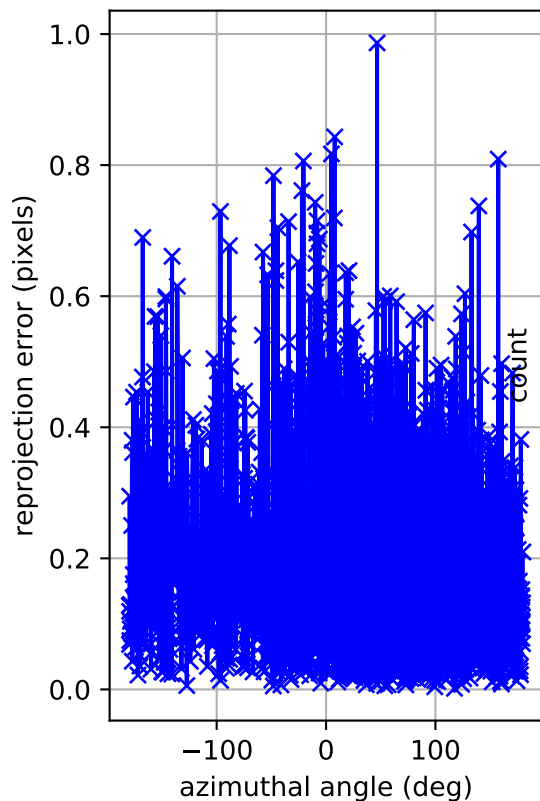 Size: 0.088 [m]
  Spacing 0.026399999999999996 [m]
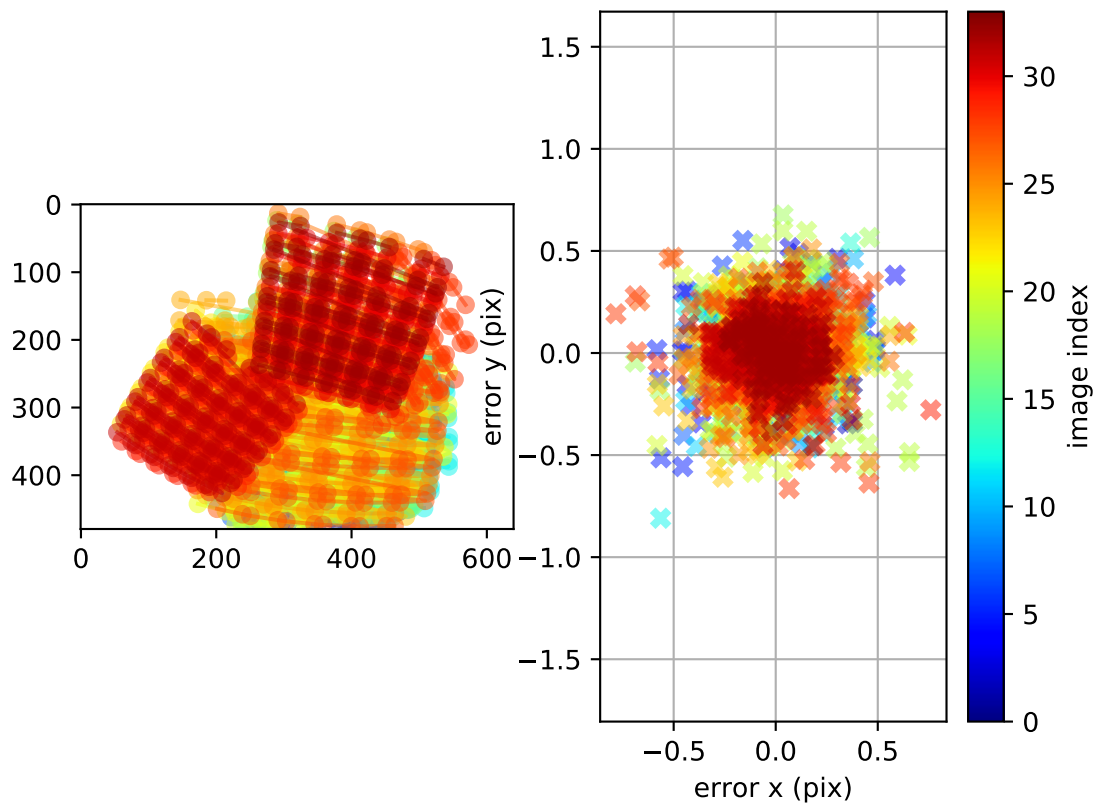
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0