

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33239045 0.09437278 -0.00022199 -0.00004808] +- [0.00231786 0.00153081 0.00019502 0.00017768]

projection: [394.88099696 394.54001341 312.80370879 244.83934767] +- [1.24934965 1.21584631 0.44448264 0.46093973]

reprojection error: [-0.000001, 0.000000] +- [0.321834, 0.280067]

Target configuration

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Type: aprilgrid

Tags:

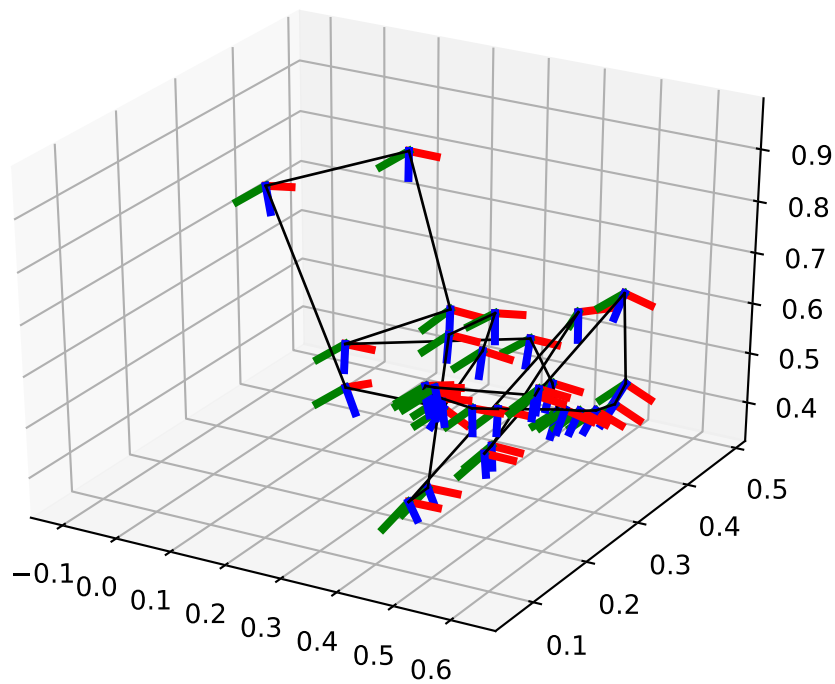
Rows: 6

Cols: 6

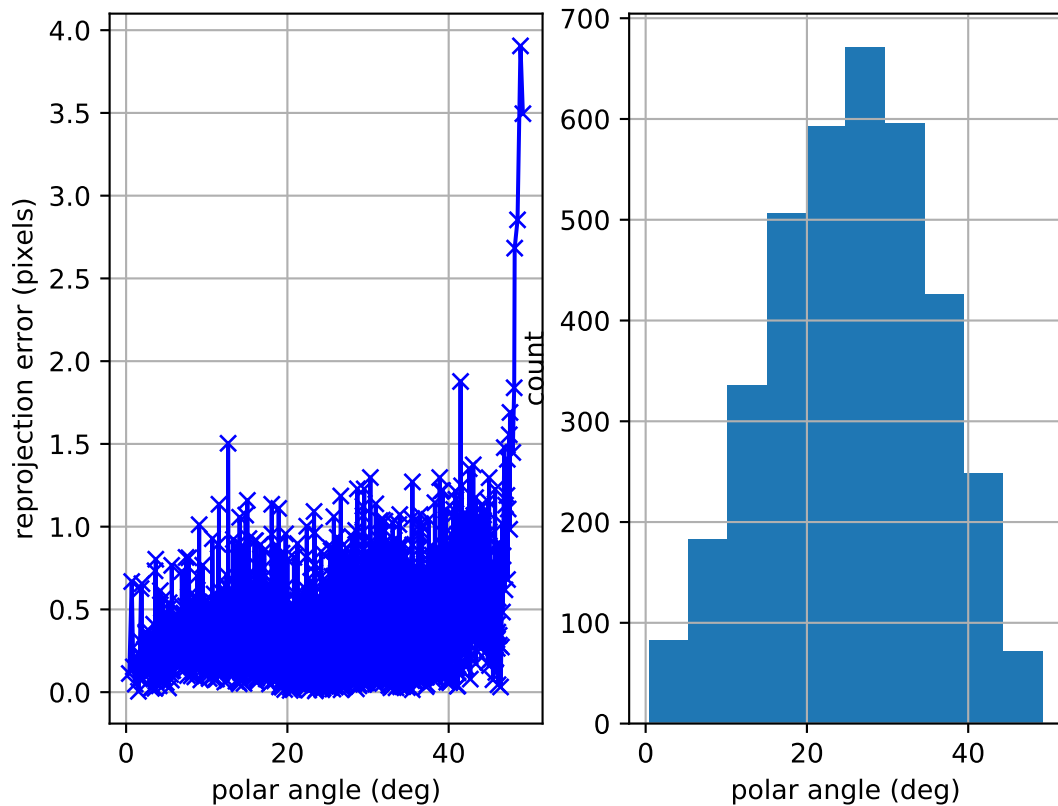
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

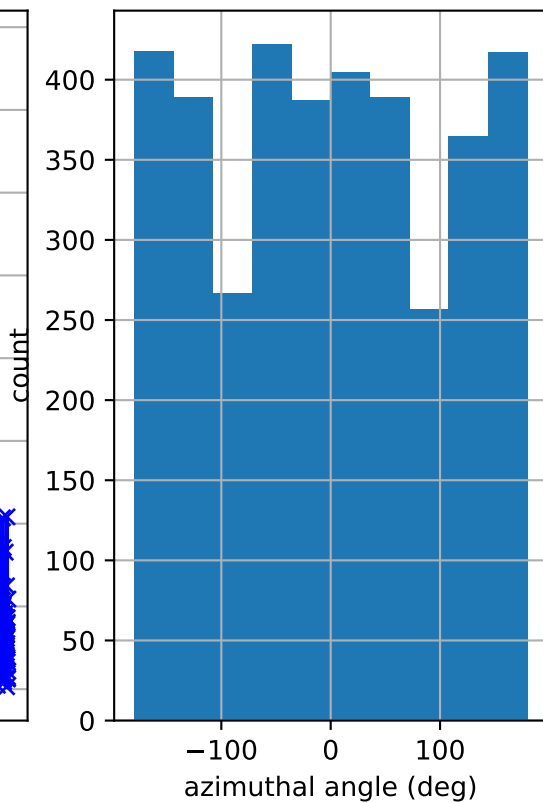
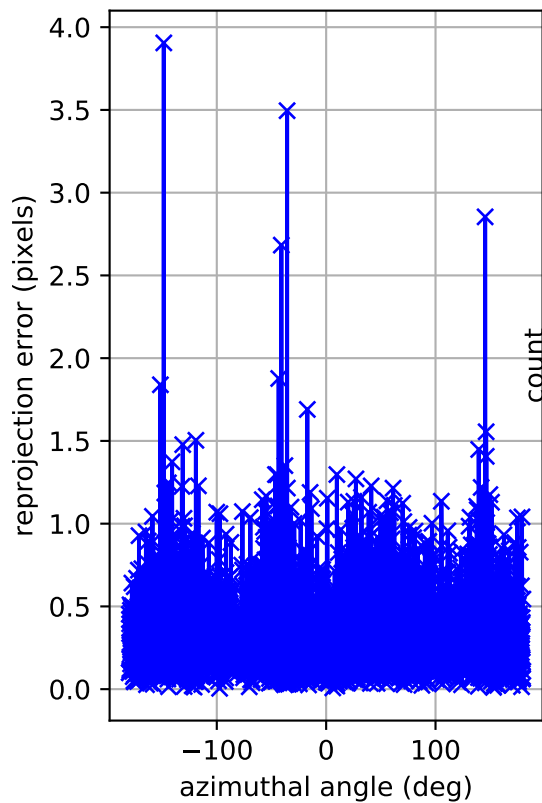
cam0: estimated poses



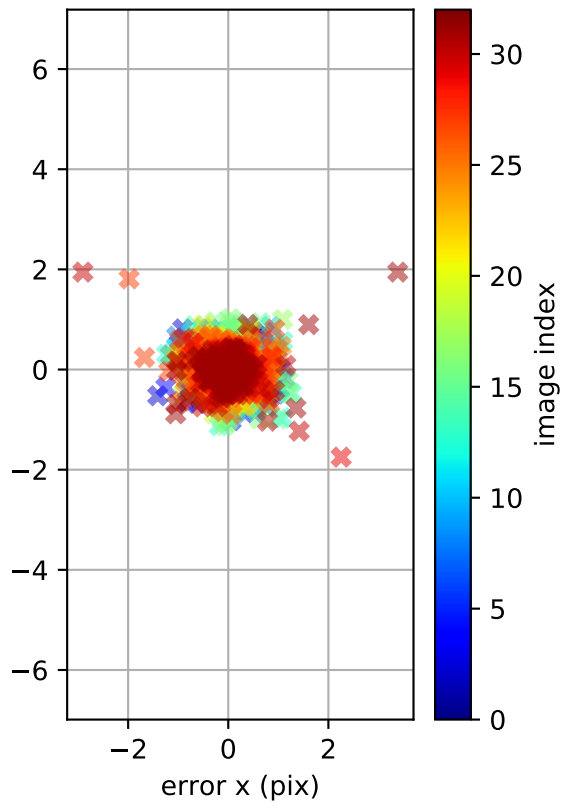
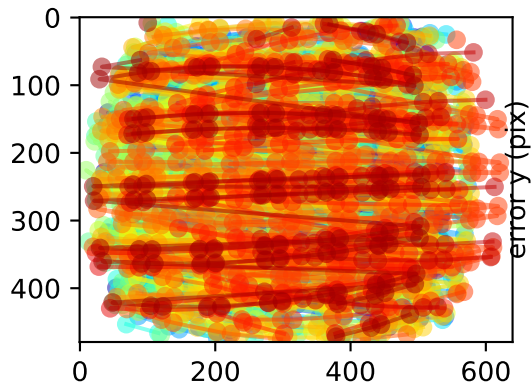
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

