Calibration results
====================
Camera-system parameters:
cam0 (/camera/front_right/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.35070046 0.11337663 -0.00109098 0.00025398] +- [0.00414215 0.0031483 0.00053054 0.00074864]
projection: [402.11740355 402.11524114 324.51475601 244.2856593] +- [3.00641546 3.04314969 1.85500493 1.67556491]
reprojection error: [0.000001, 0.000000] +- [0.178143, 0.157925]

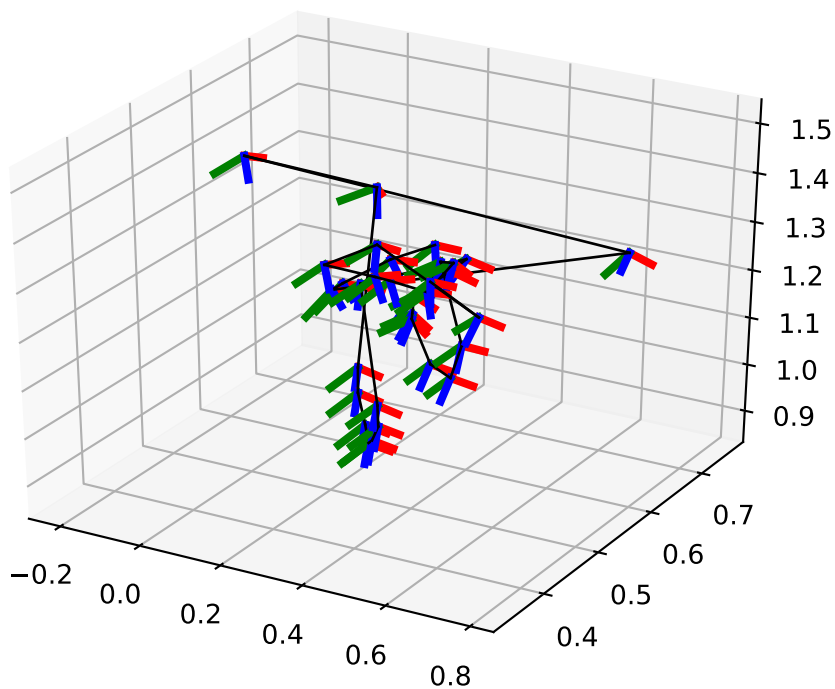Target configuration
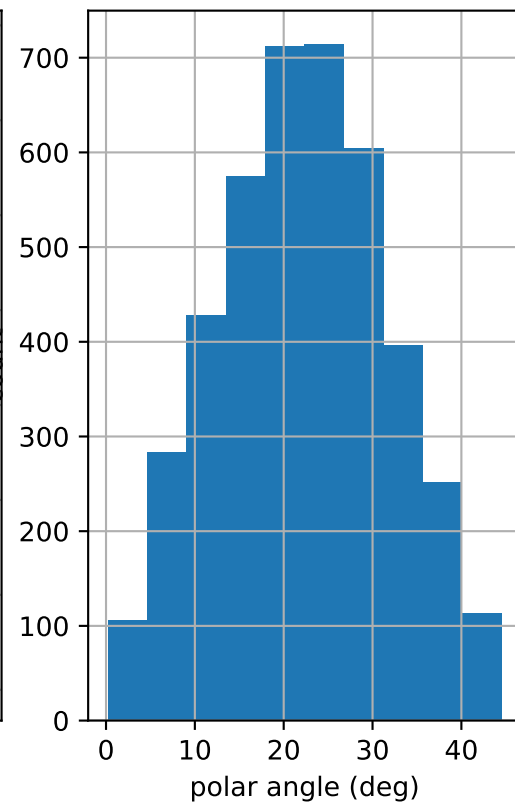====================
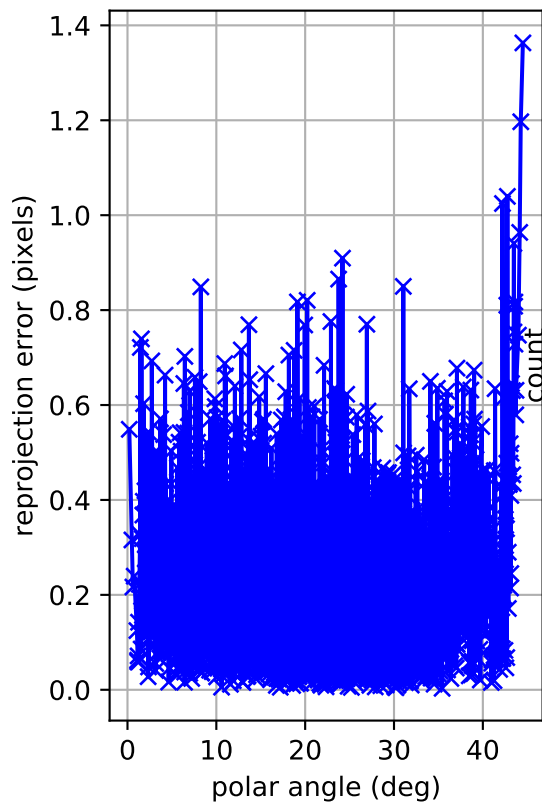
Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.088 [m]
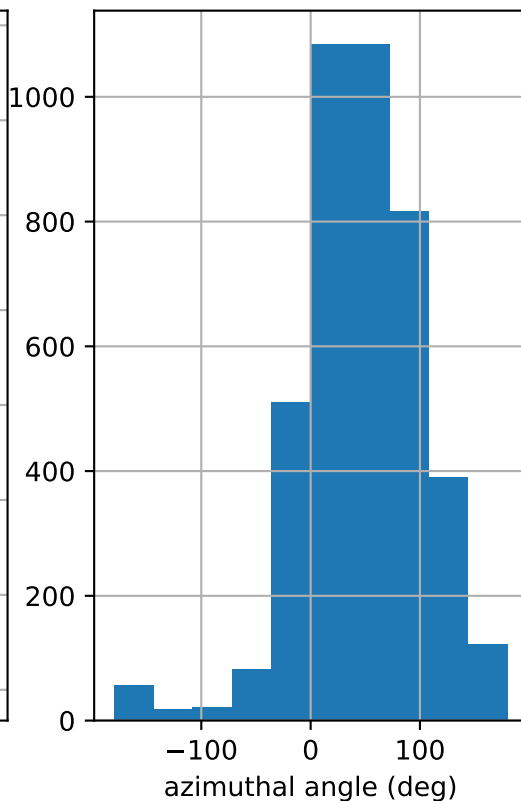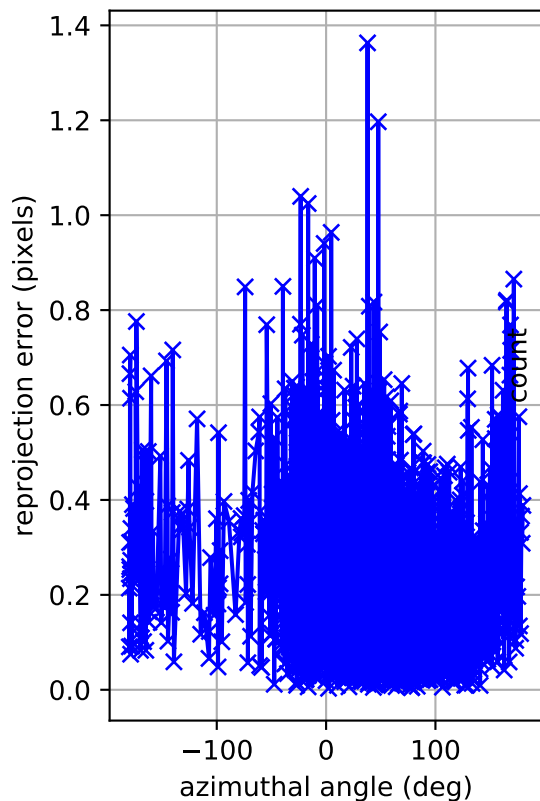Spacing 0.026399999999999996 [m]
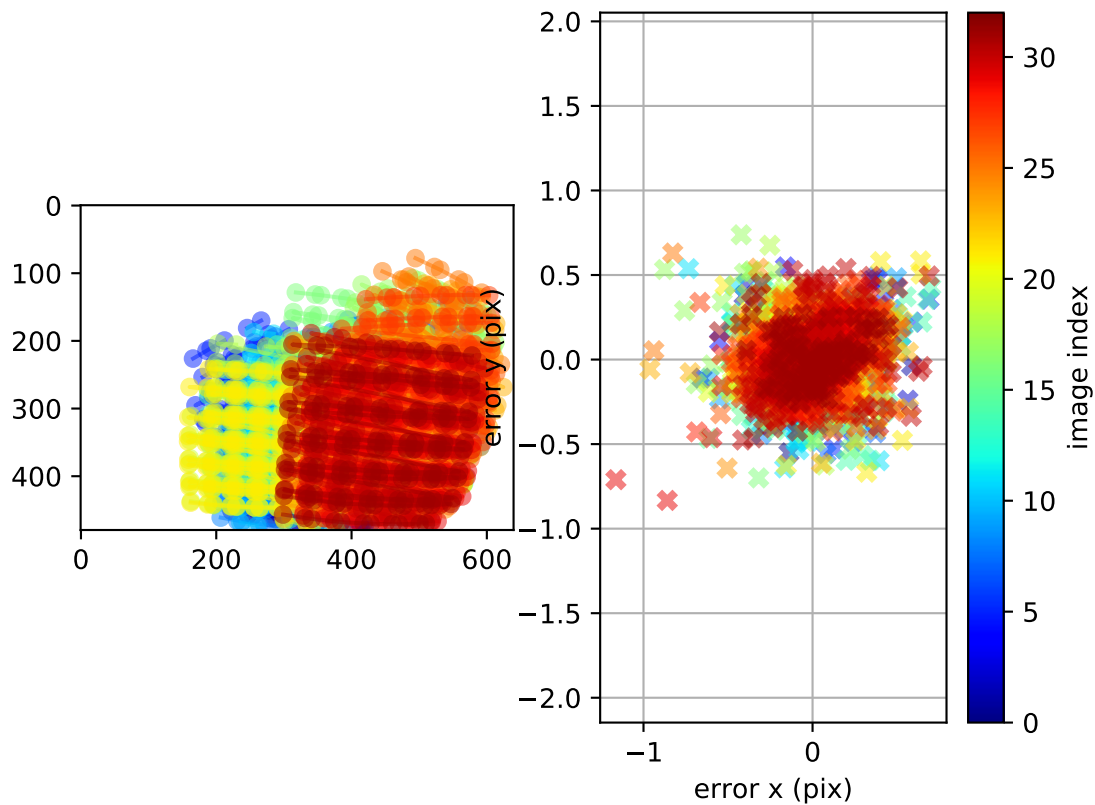
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0