

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33582666 0.10180877 -0.00008911 -0.00028972] +- [0.00187929 0.00149254 0.00028843 0.00020137]

projection: [392.59904852 392.50624902 323.46481604 238.86345955] +- [1.43487332 1.41363856 0.8030799
1.00454128]

reprojection error: [0.000000, 0.000000] +- [0.202043, 0.163921]

Target configuration

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Type: aprilgrid

Tags:

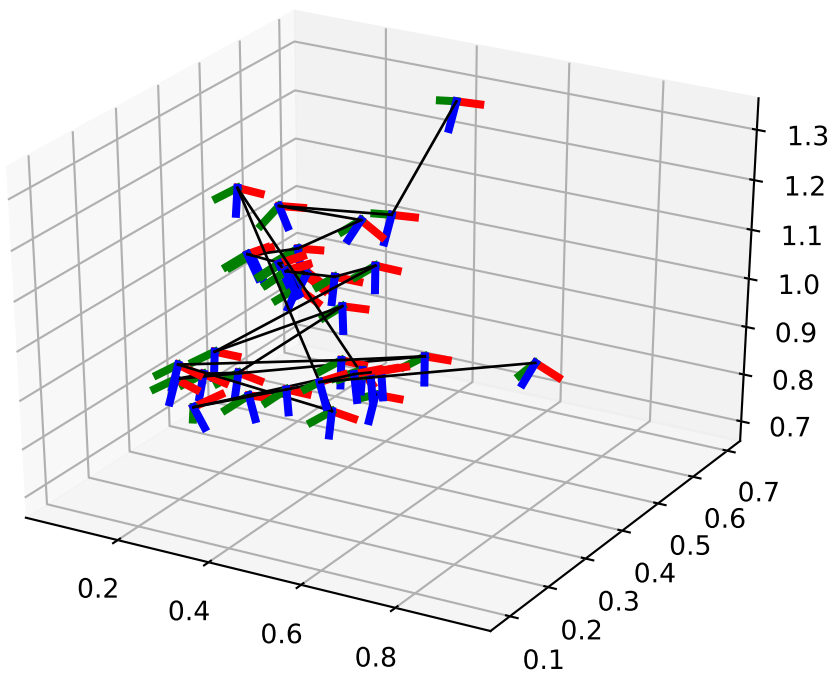
Rows: 6

Cols: 6

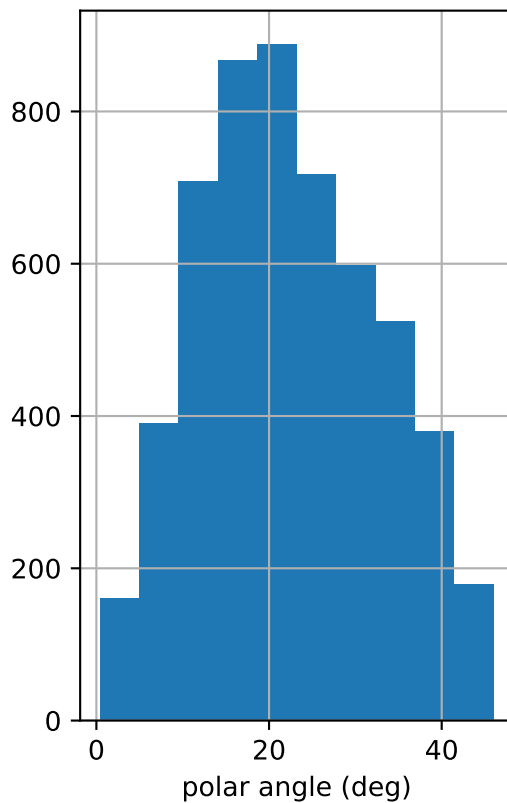
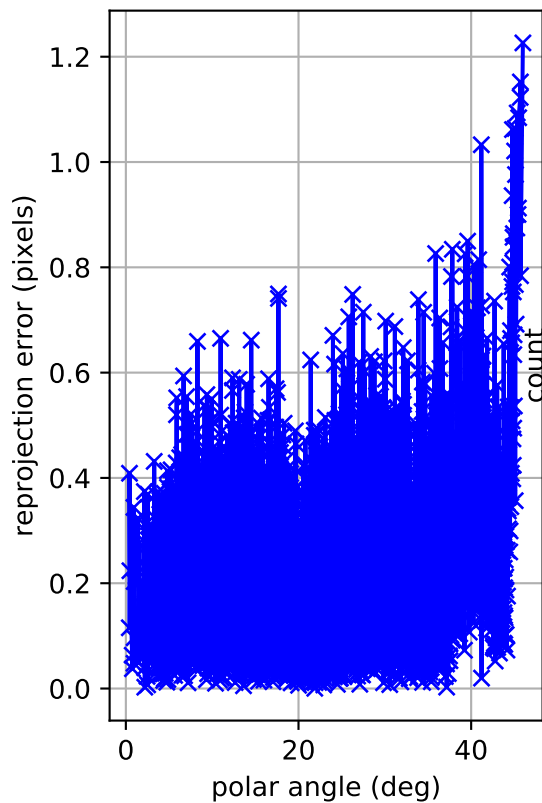
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

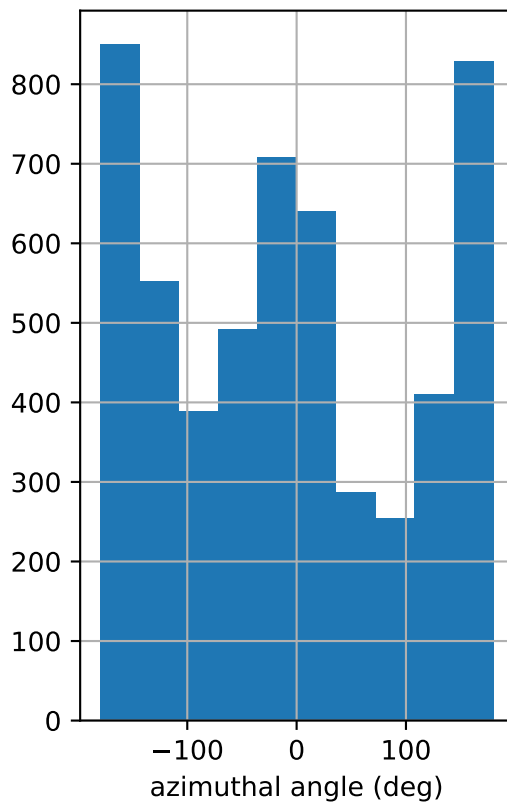
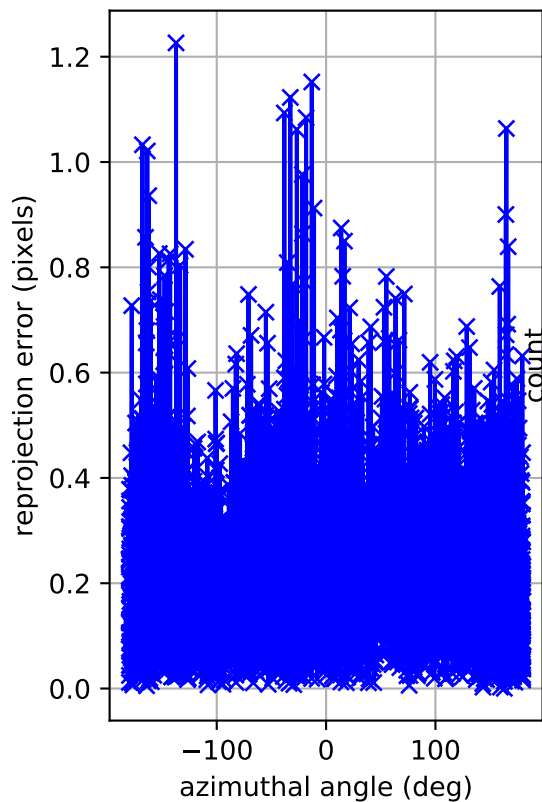
cam0: estimated poses



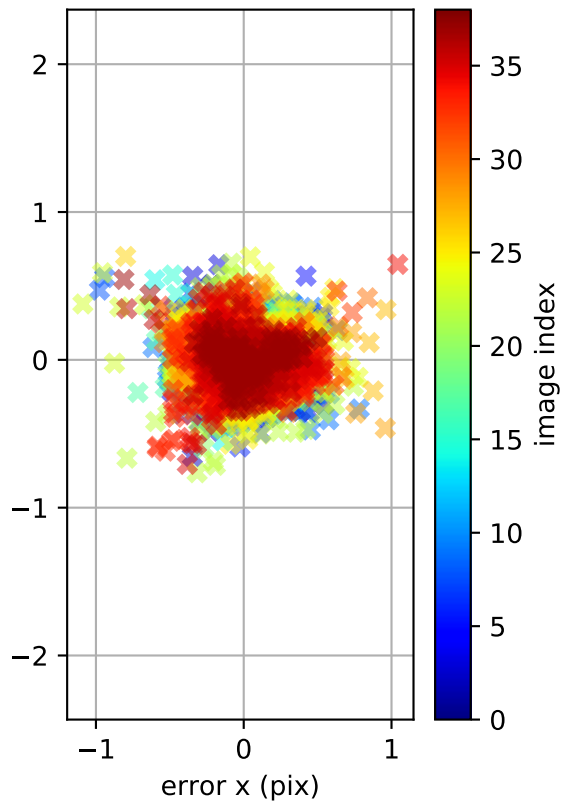
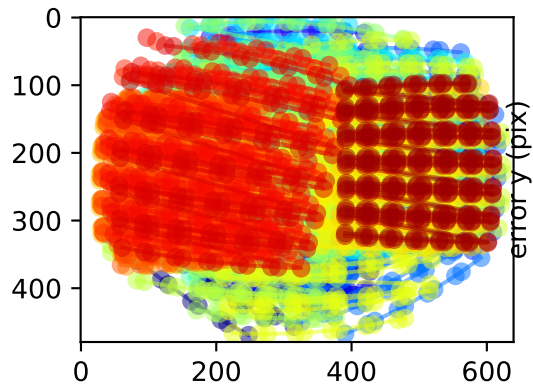
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

