Calibration results
====================
Camera-system parameters:
cam0 (/camera/front_right/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.33536358  0.09957282  0.00009011 -0.00009774] +- [0.00133831 0.00114133 0.00018428 0.00015148]
projection: [392.83888831 392.31001372 323.41164792 242.1951651 ] +- [0.63926102 0.61363117 0.57300795 0.62145255]
reprojection error: [0.000004, -0.000000] +- [0.254776, 0.219896]


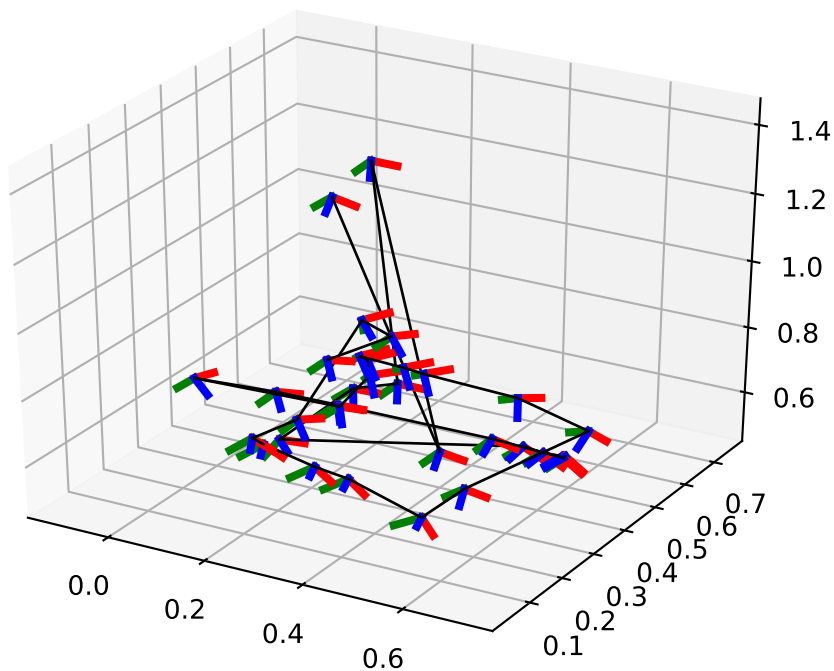Target configuration
====================
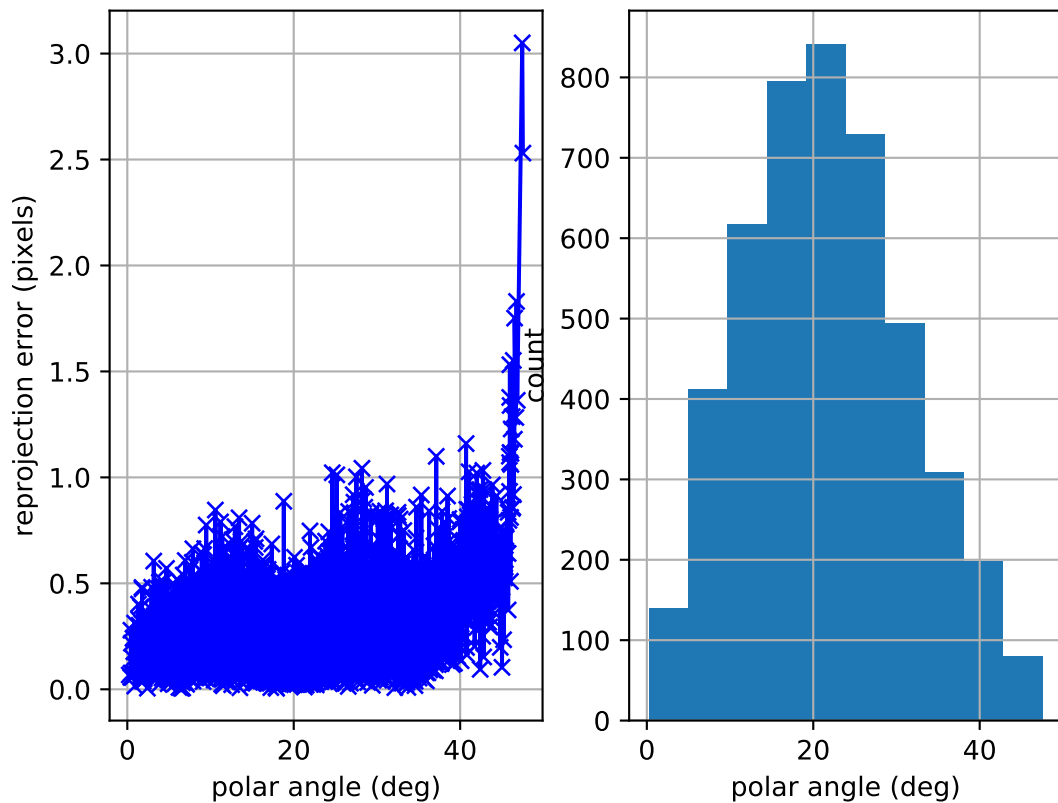
Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.088 [m]
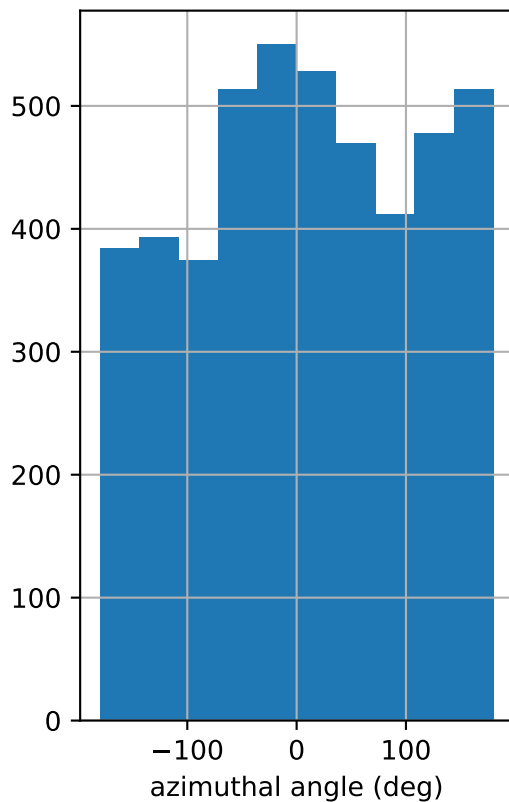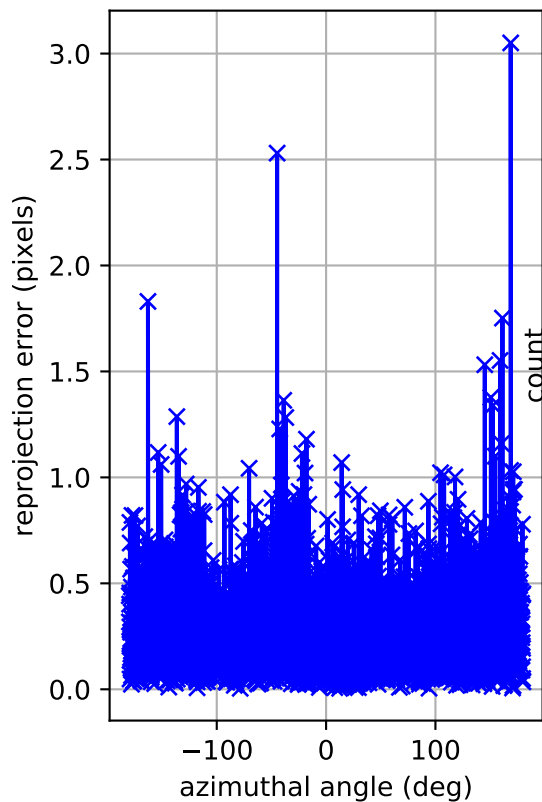Spacing 0.026399999999999996 [m]
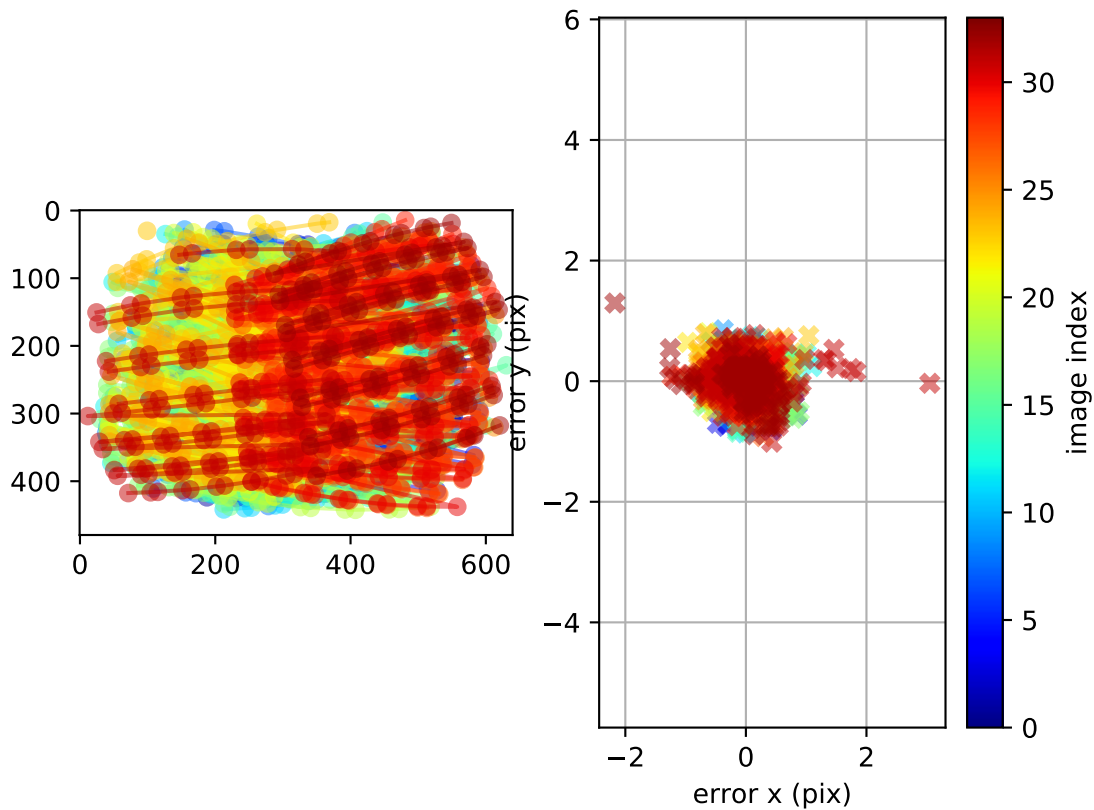
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0