

Calibration results

=====

Camera-system parameters:

cam0 (/camera/side_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.3364055 0.09647296 -0.00103249 0.00118006] +- [0.00294033 0.00252479 0.00052153 0.00048208]

projection: [395.72747965 395.24447247 324.53311925 242.18542815] +- [2.31176212 2.32880004 1.50457003 1.73012891]

reprojection error: [0.000001, 0.000000] +- [0.218245, 0.204824]

Target configuration

=====

Type: aprilgrid

Tags:

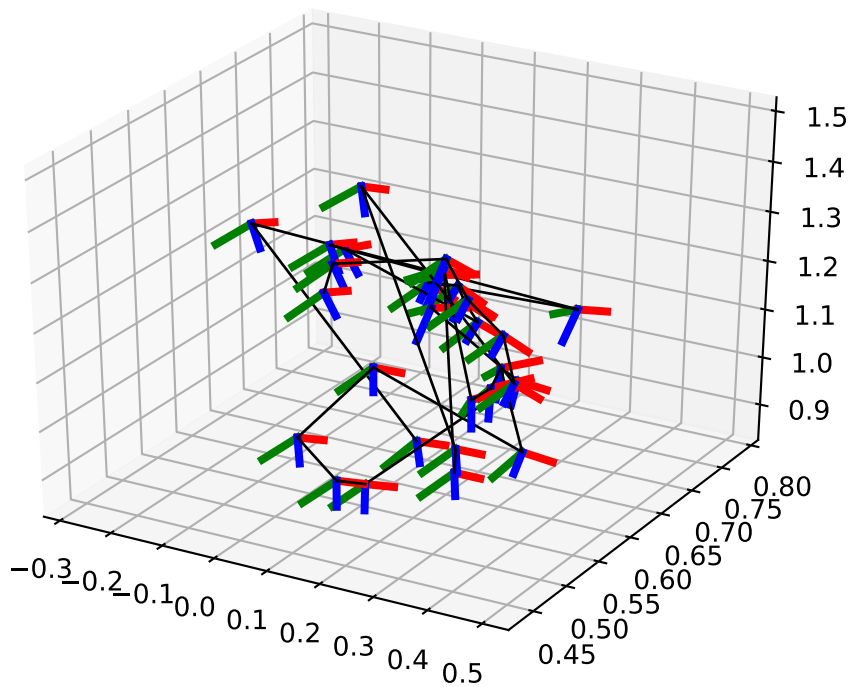
Rows: 6

Cols: 6

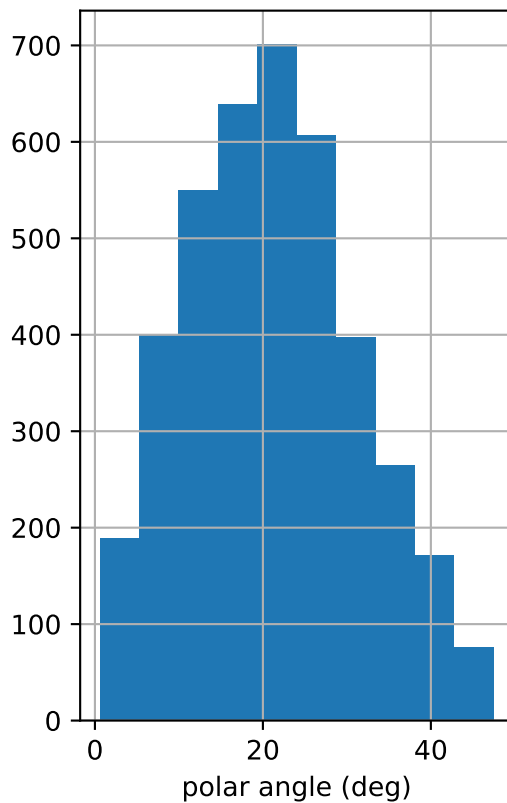
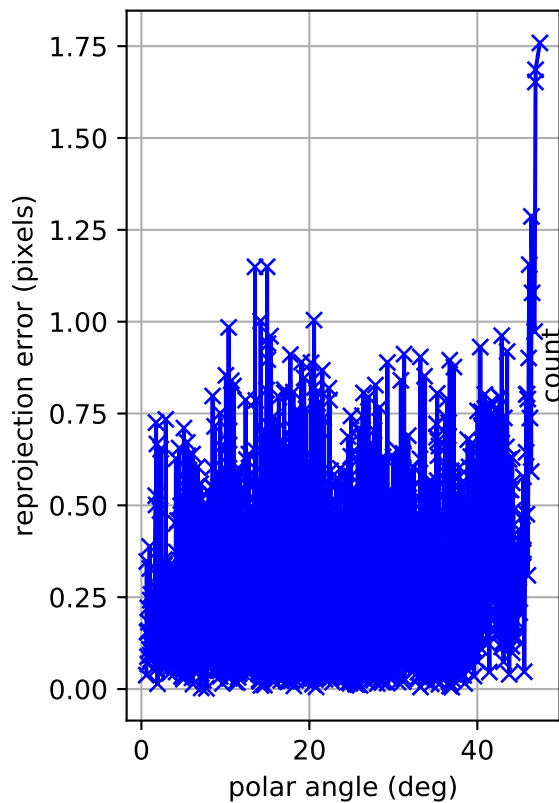
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

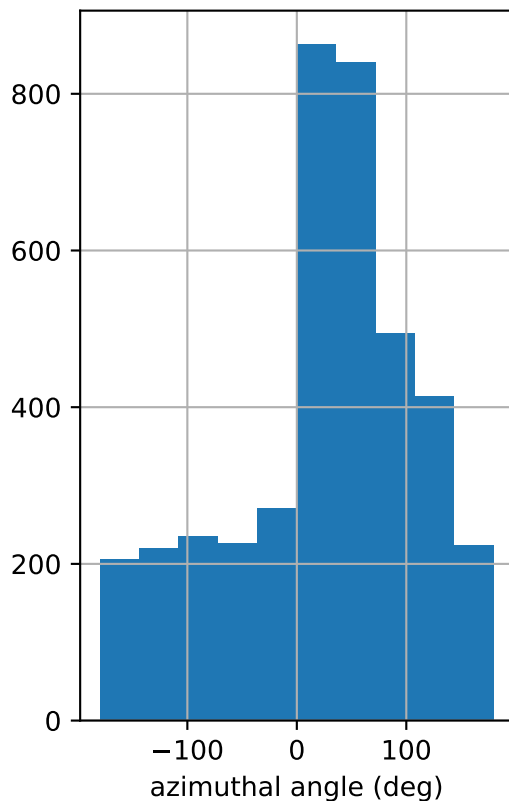
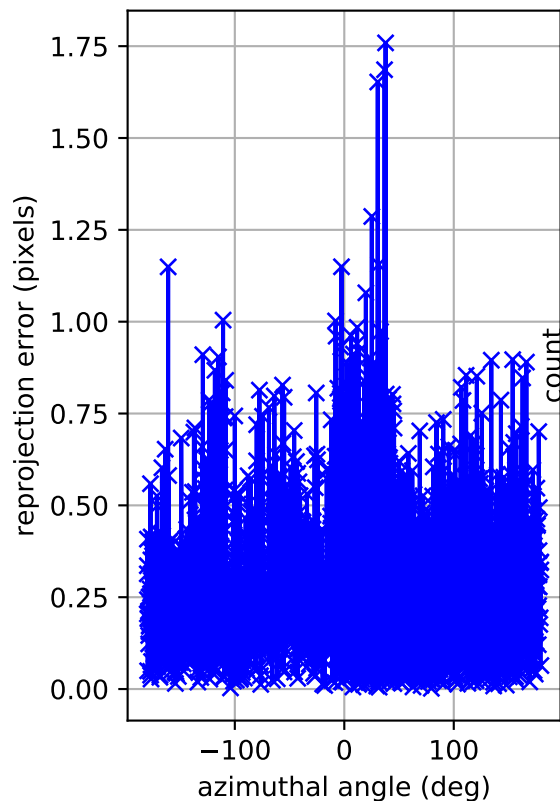
cam0: estimated poses



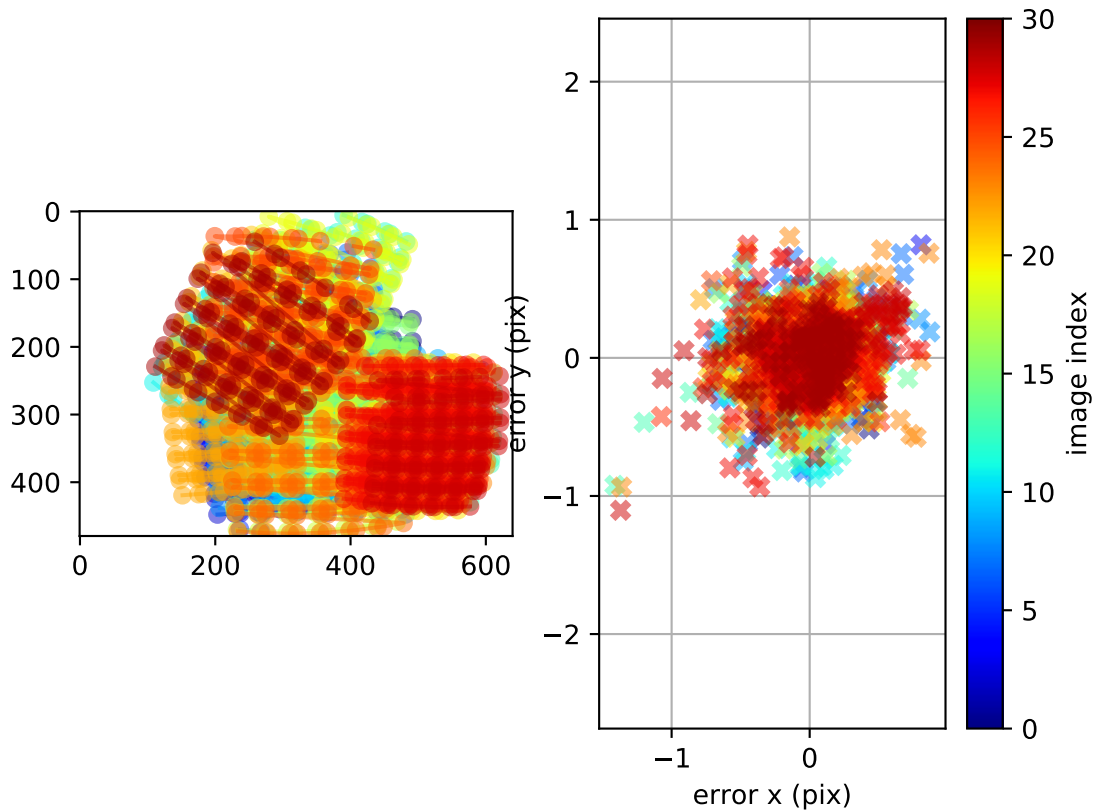
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

