

## Calibration results

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### Camera-system parameters:

cam0 (/camera/side\_left/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [-0.34126426 0.10257233 -0.00028809 0.00050313] +- [0.00294906 0.00266789 0.00051795 0.0004833 ]

projection: [396.59993641 396.42090822 326.34870177 239.38795468] +- [2.25515947 2.27451017 1.50036991 1.70013681]

reprojection error: [-0.000000, -0.000000] +- [0.203748, 0.185809]

## Target configuration

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Type: aprilgrid

Tags:

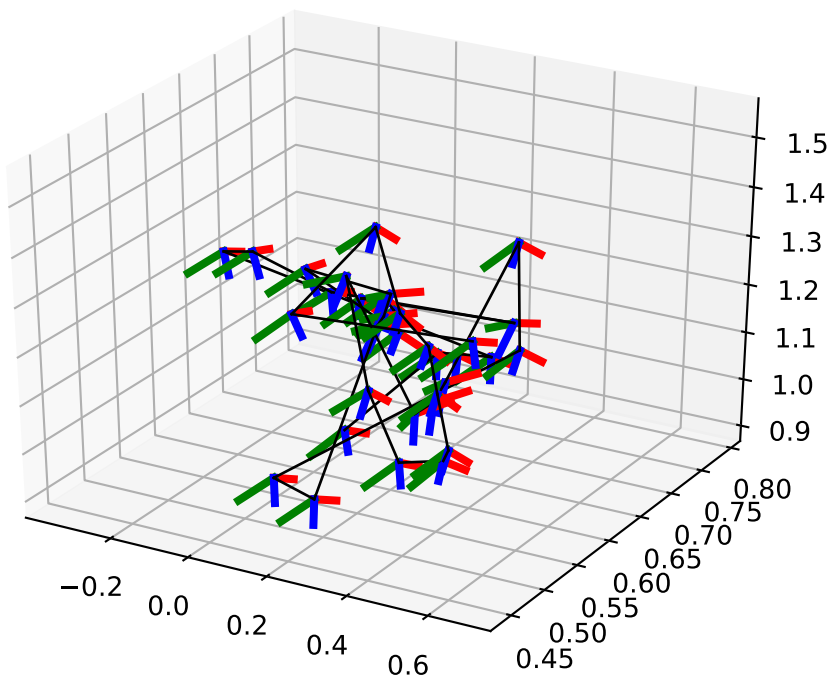
Rows: 6

Cols: 6

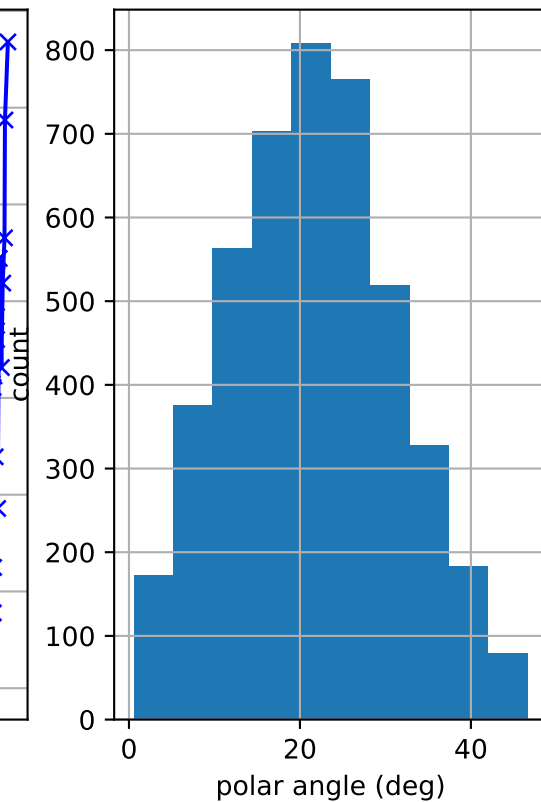
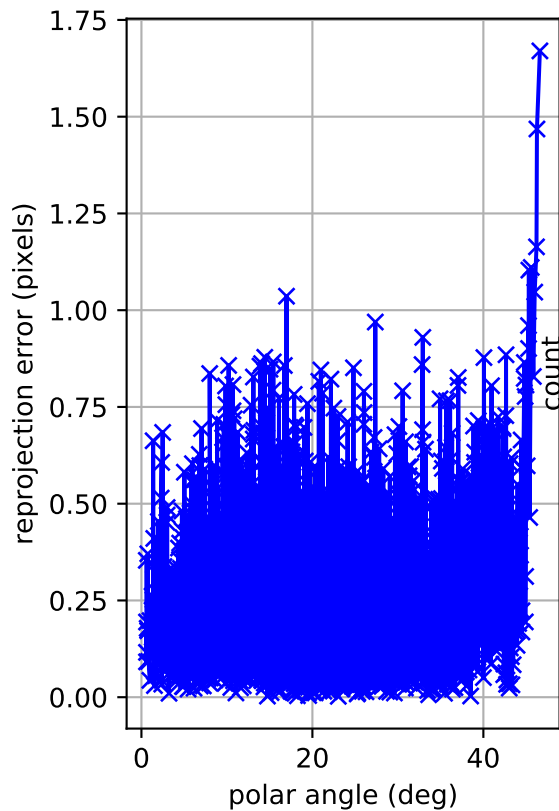
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

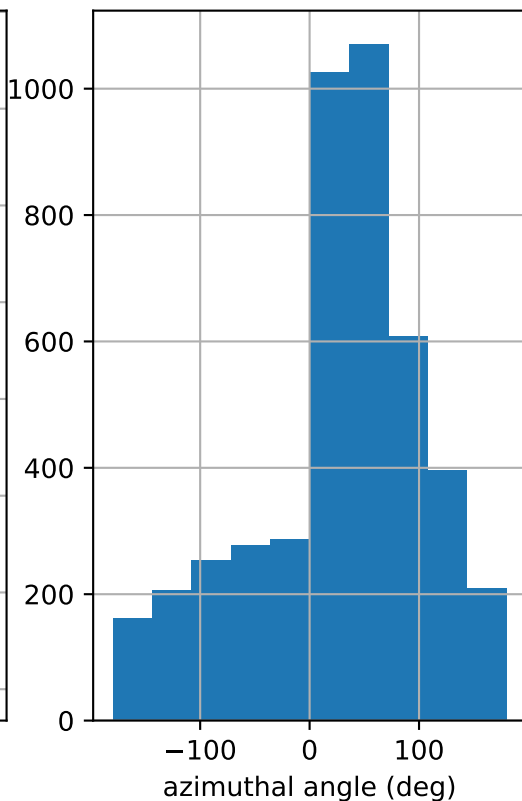
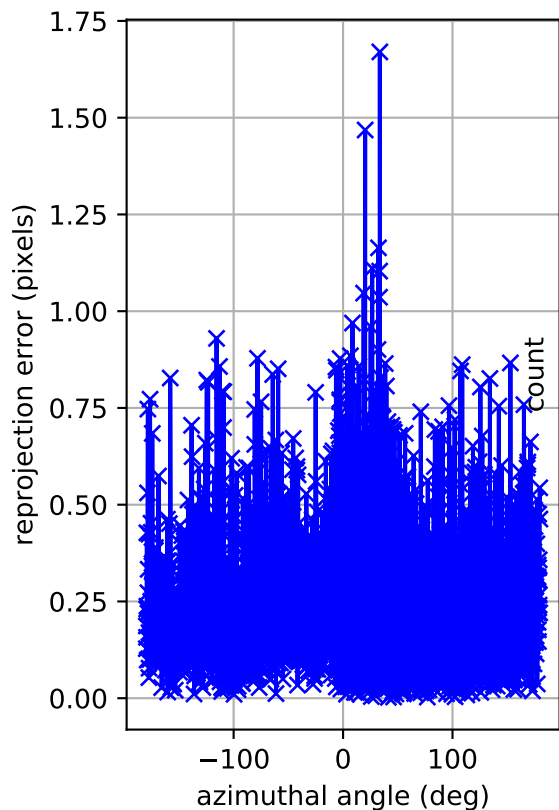
cam0: estimated poses



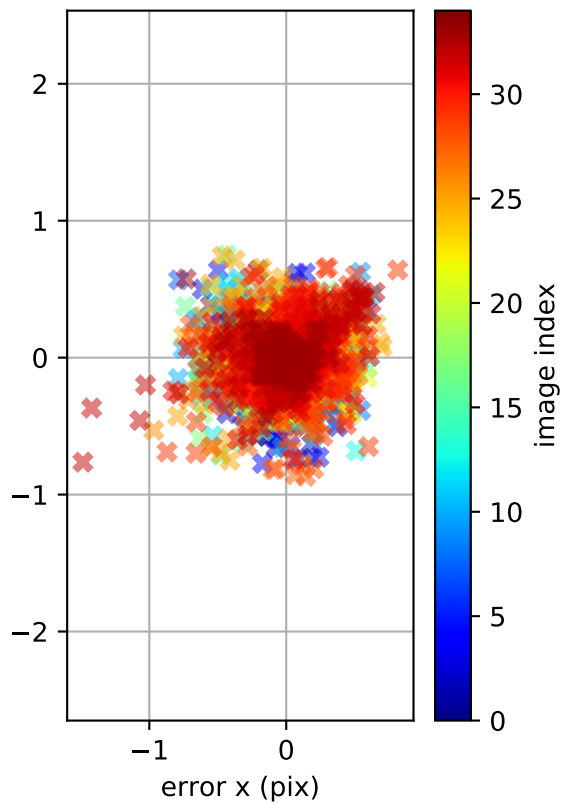
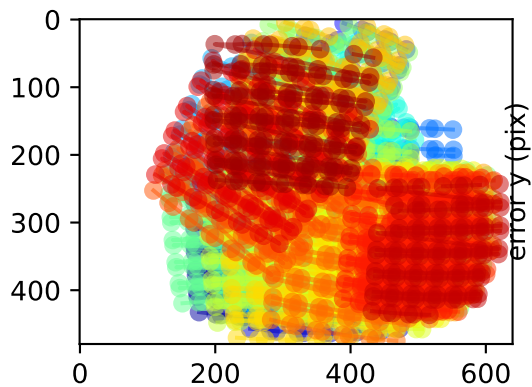
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



# Location of removed outlier corners

cam0

