Calibration results
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Camera-system parameters:
cam0 (/camera/front_right/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.31957898 0.0806469 -0.00080197 0.00035669] +- [0.00196815 0.00109669 0.00023507 0.00018263]
projection: [393.06641796 392.98060045 323.6422896 244.46900485] +- [1.10550742 1.10277156 0.45731078 0.50662746]
reprojection error: [-0.000002, 0.000001] +- [0.439053, 0.347816]

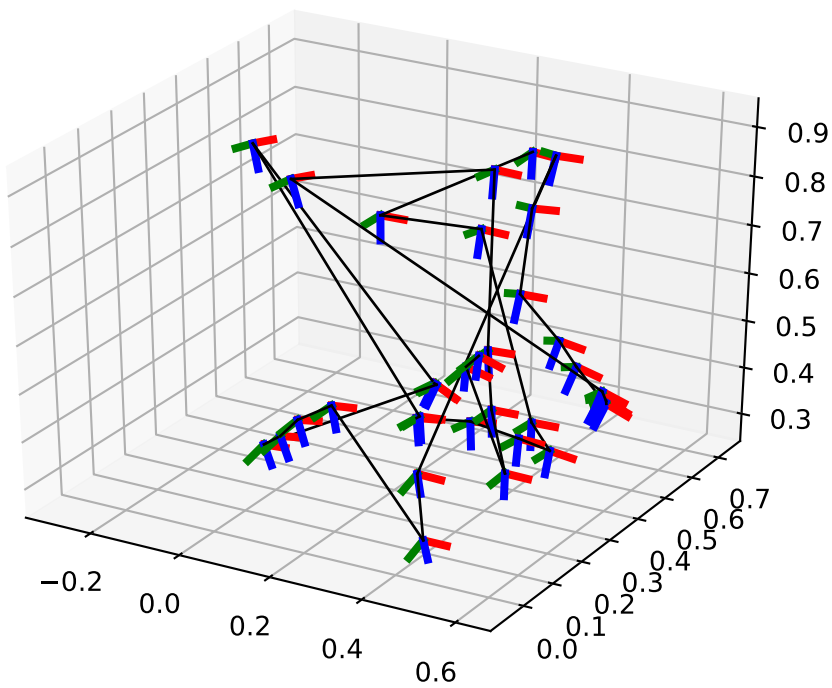Target configuration
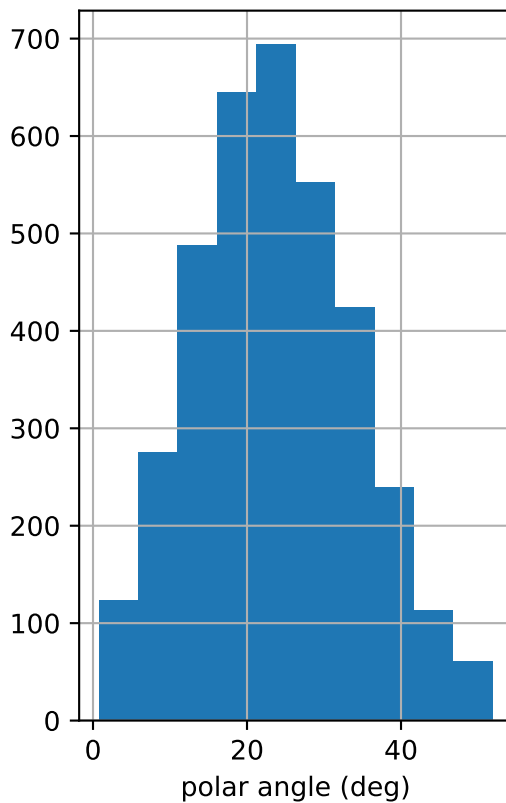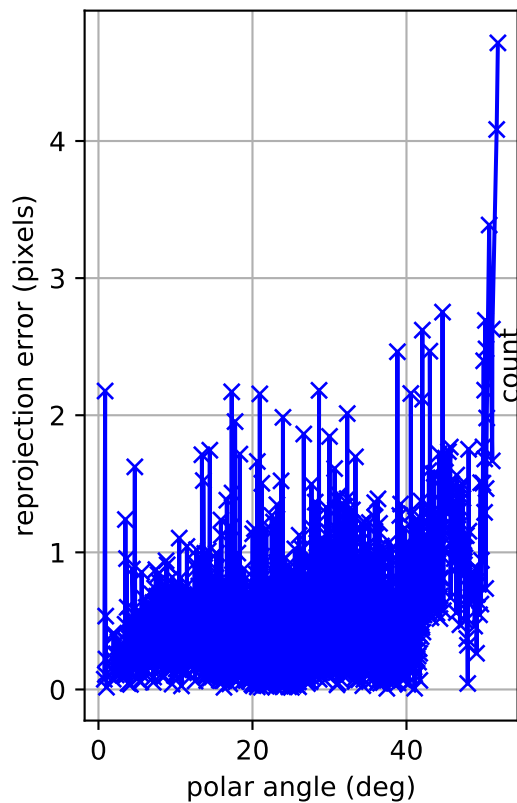====================

Type: aprilgrid
Tags:
Rows: 6
Cols: 6
Size: 0.088 [m]
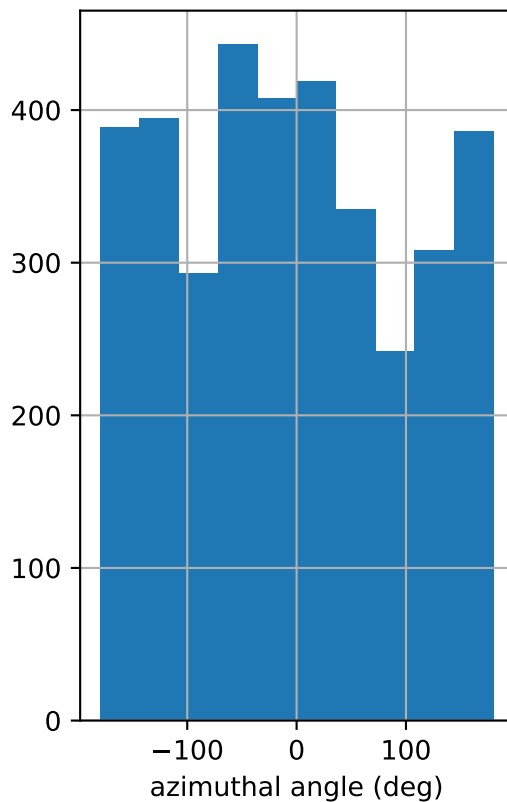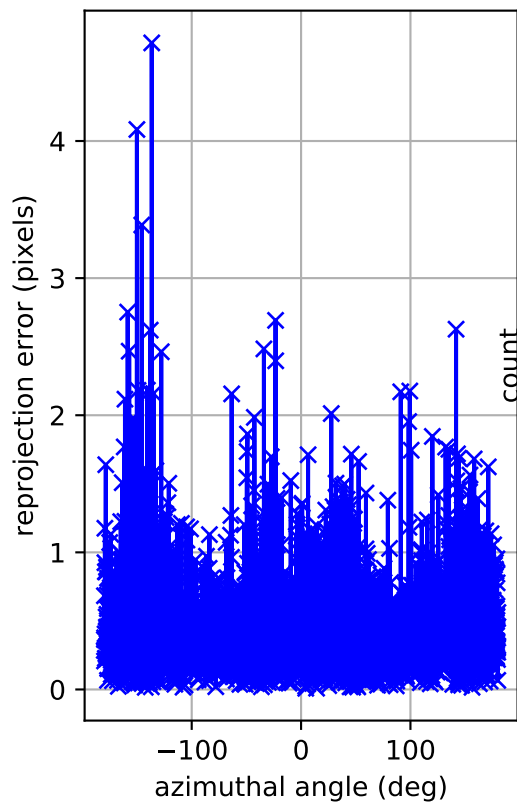Spacing 0.026399999999999996 [m]
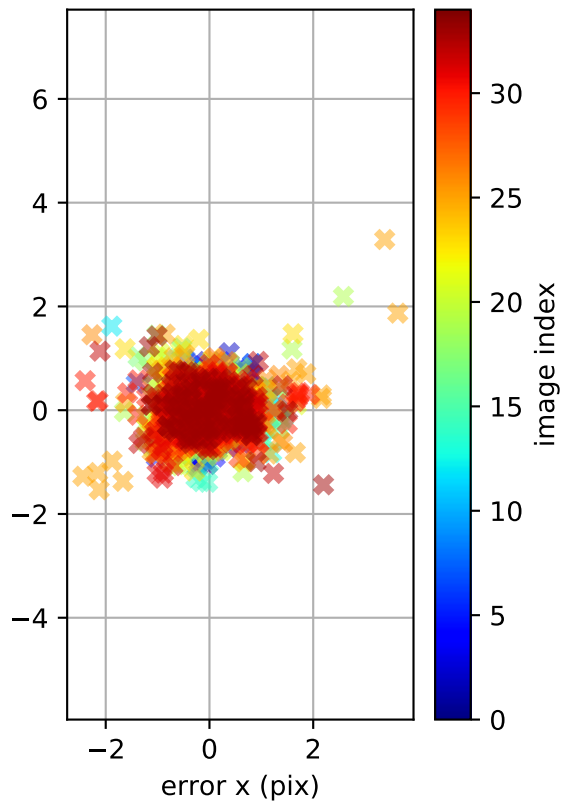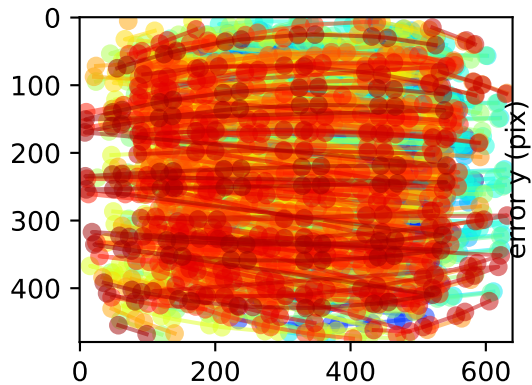
cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0