

Calibration results

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Camera-system parameters:

cam0 (/camera/front_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.34200865 0.10879942 -0.00032296 -0.00045427] +- [0.00195367 0.00188139 0.00026371 0.00022789]

projection: [392.81141516 392.88374894 322.46669249 248.22708354] +- [1.3515694 1.31849869 0.91096937 1.01371328]

reprojection error: [-0.000001, 0.000001] +- [0.165781, 0.149661]

Target configuration

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Type: aprilgrid

Tags:

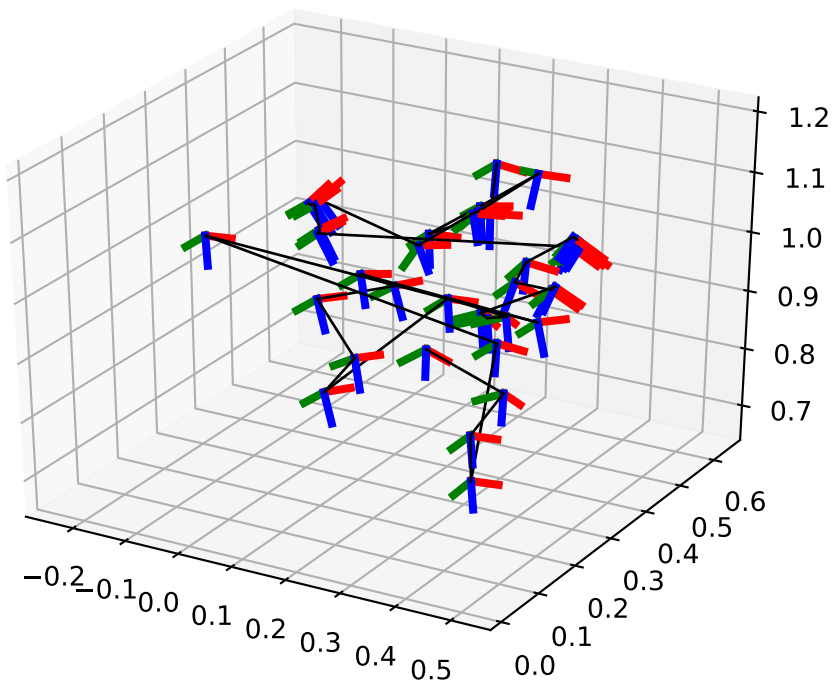
Rows: 6

Cols: 6

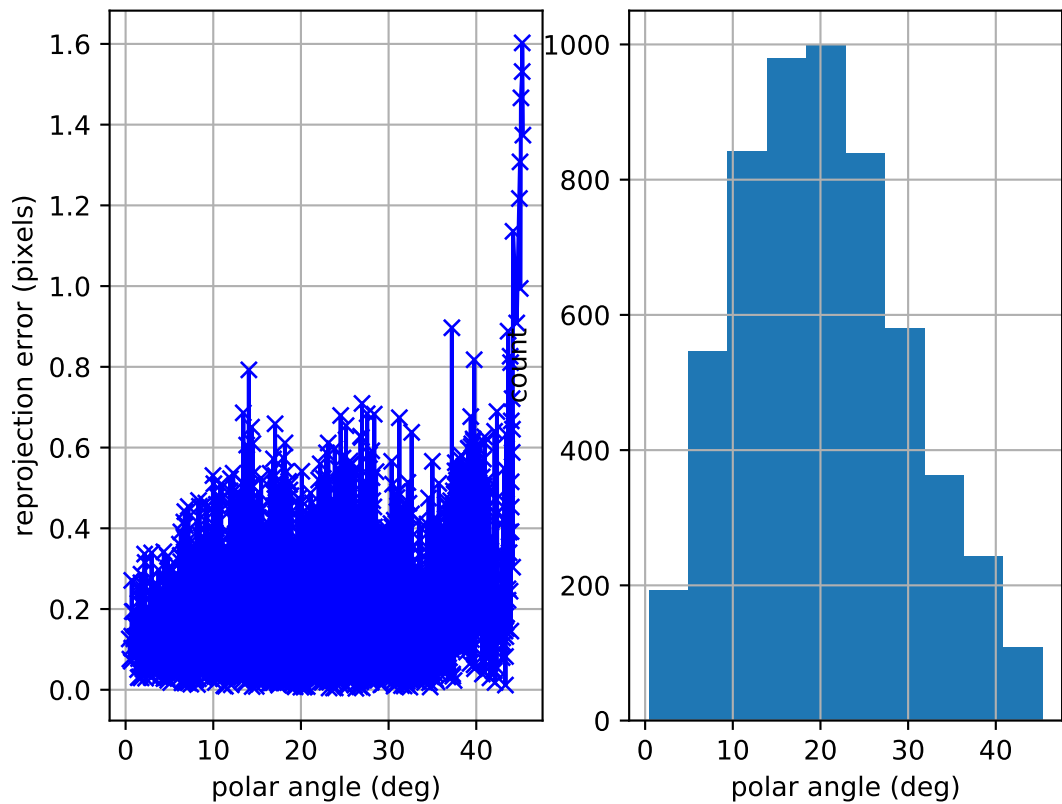
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

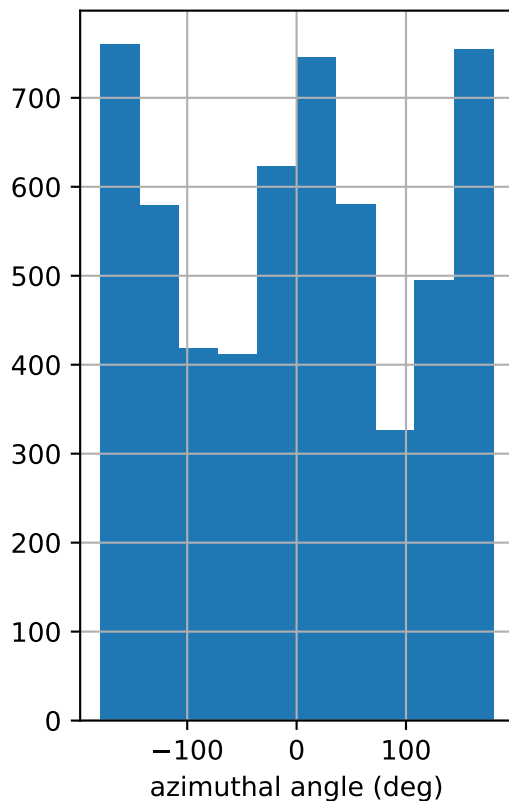
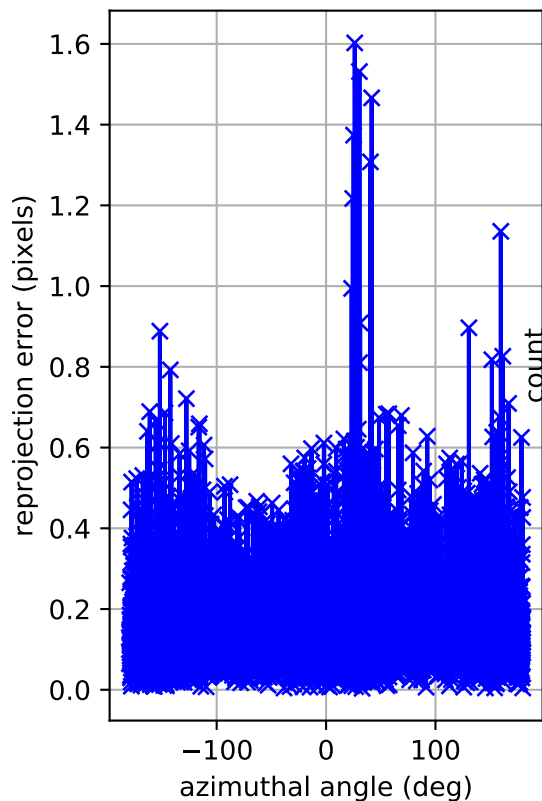
cam0: estimated poses



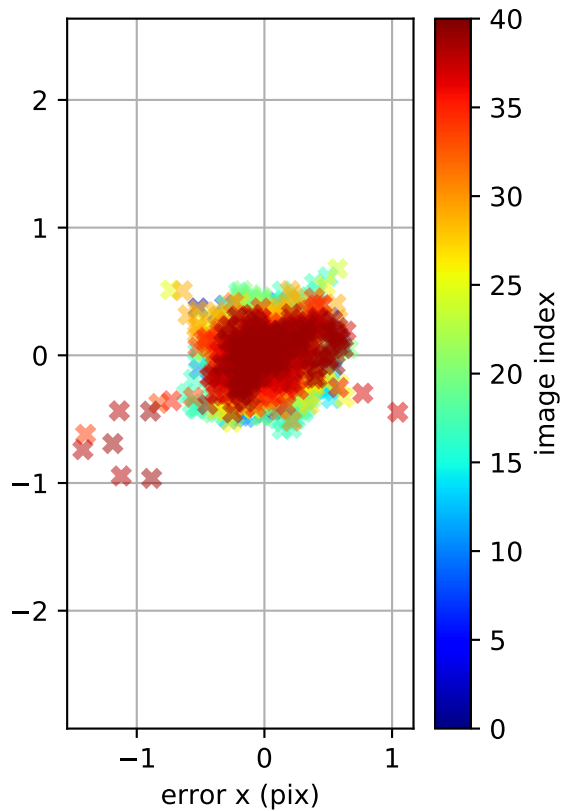
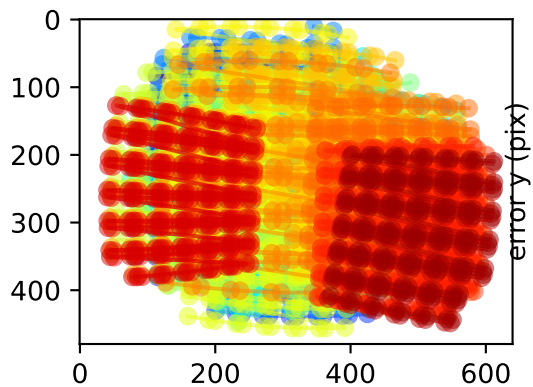
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

