

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.343289 0.11935125 -0.00038009 -0.00168097] +- [0.00341151 0.00368253 0.00051629 0.00044065]

projection: [386.34806423 385.86251694 317.60737814 246.91469385] +- [2.25838235 2.29354341 1.32295023 1.58082941]

reprojection error: [-0.000001, -0.000001] +- [0.150776, 0.145673]

Target configuration

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Type: aprilgrid

Tags:

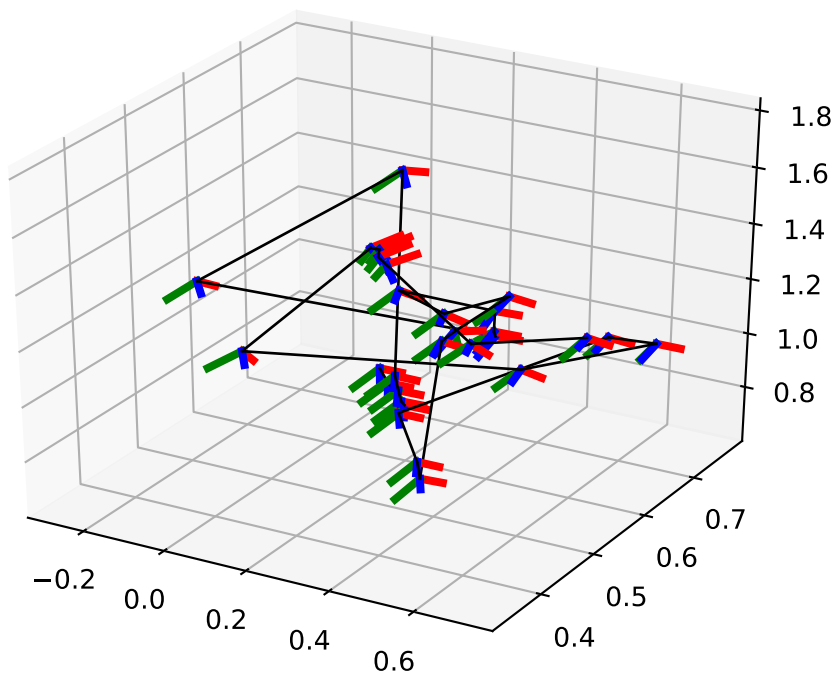
Rows: 6

Cols: 6

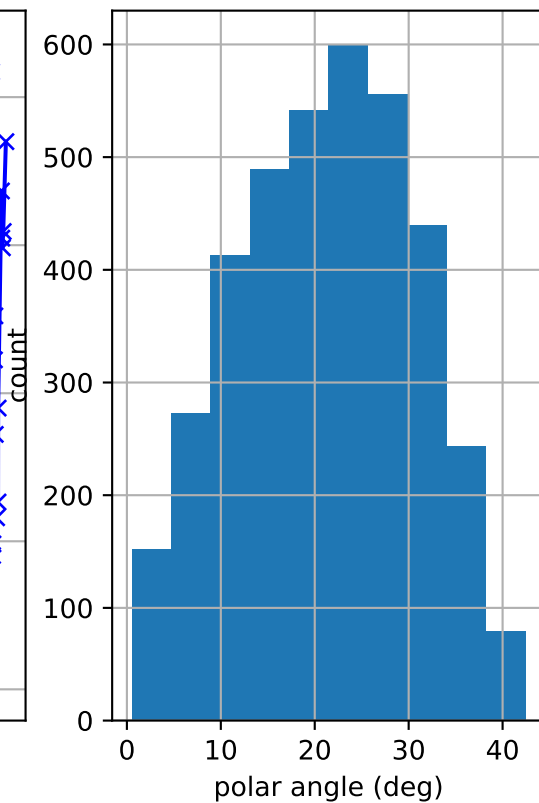
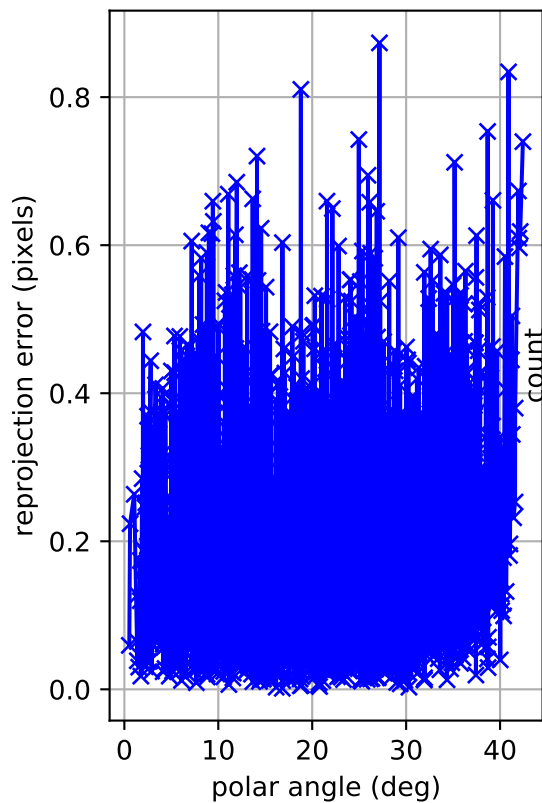
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

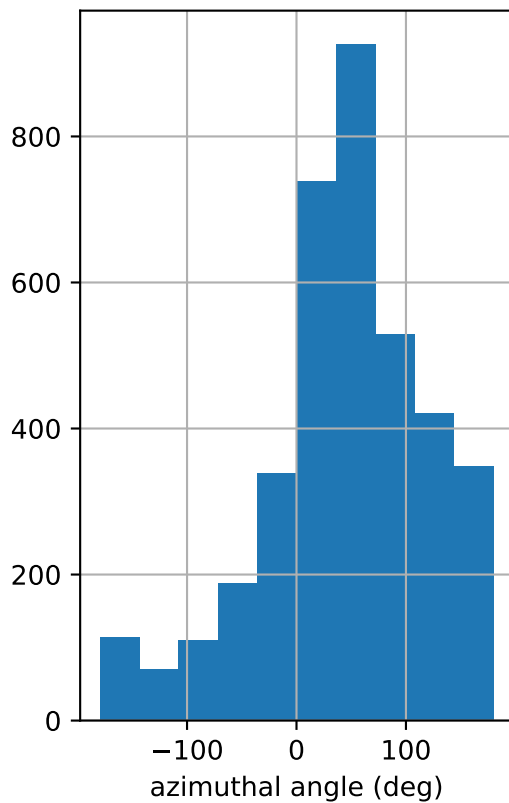
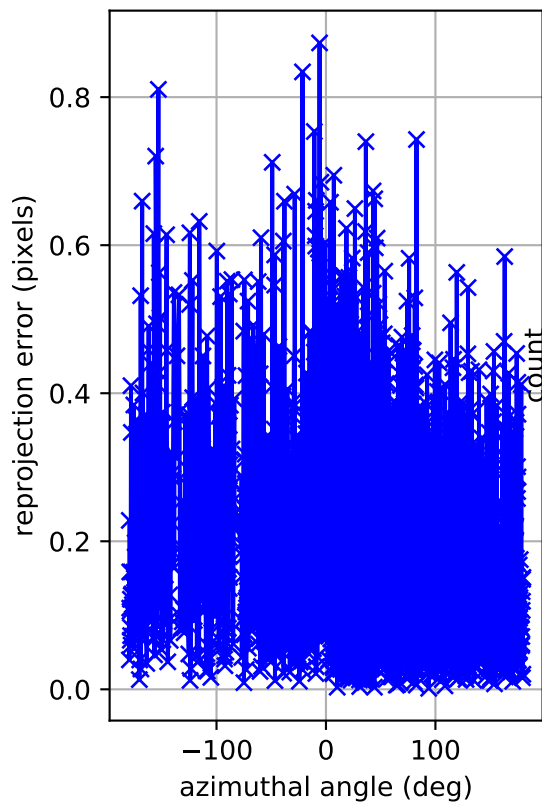
cam0: estimated poses



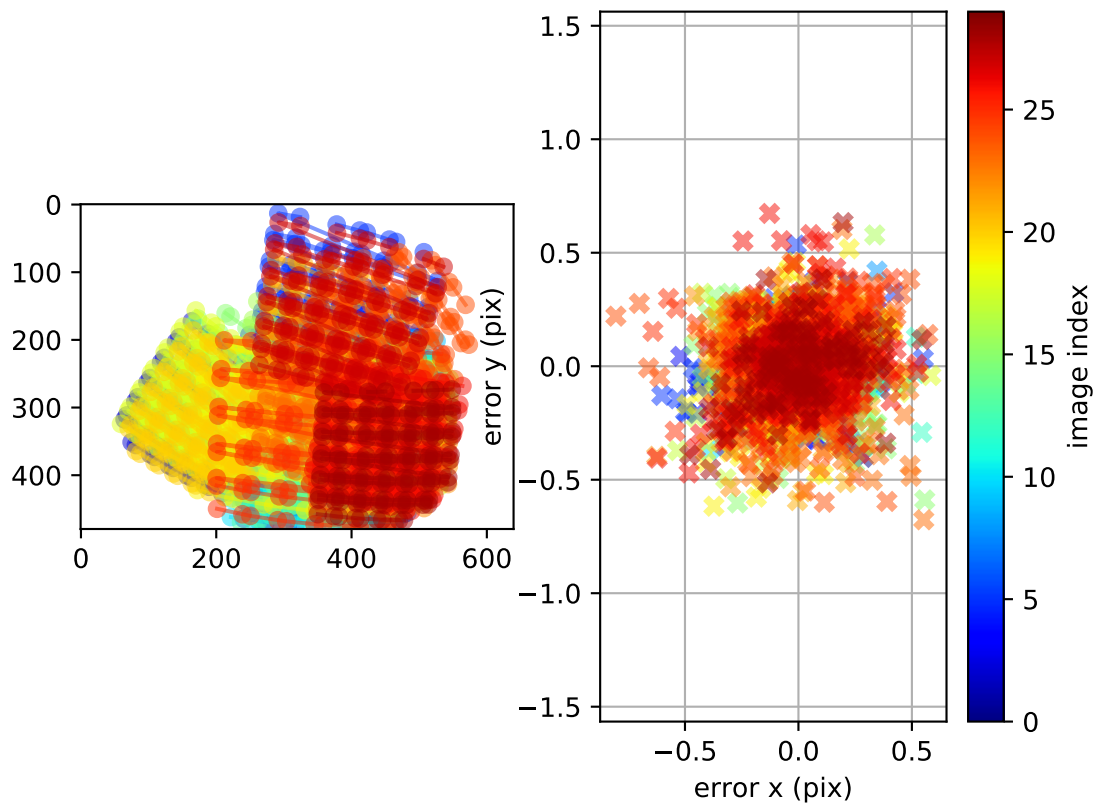
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

