

Calibration results

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Camera-system parameters:

cam0 (/camera/side_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.34335809 0.10337515 -0.00063146 0.00046744] +- [0.00287154 0.00262663 0.00049936 0.00047764]

projection: [398.02035665 397.36468632 326.02660841 240.65282244] +- [2.20965681 2.22804966 1.44251046 1.63433318]

reprojection error: [0.000001, 0.000004] +- [0.209125, 0.191766]

Target configuration

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Type: aprilgrid

Tags:

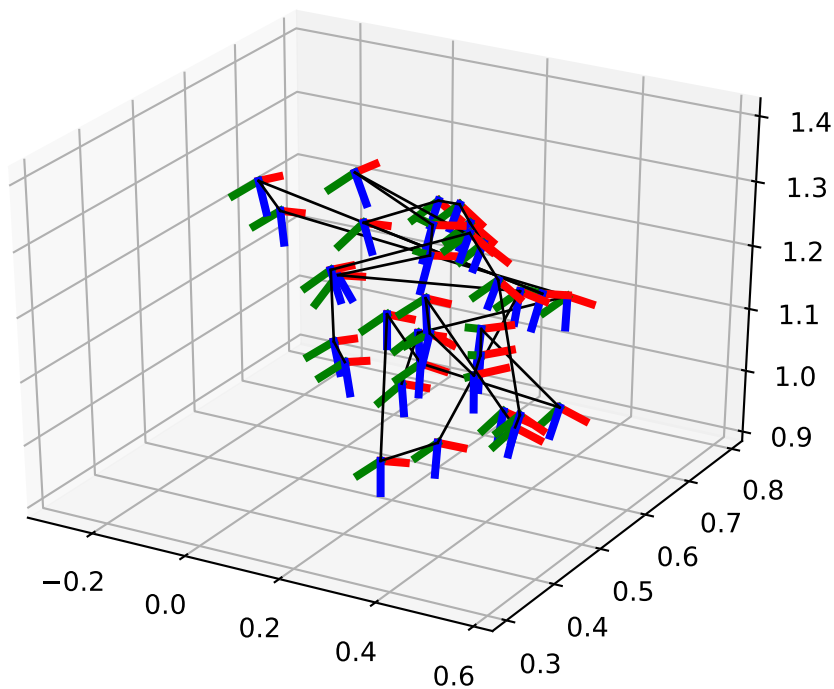
Rows: 6

Cols: 6

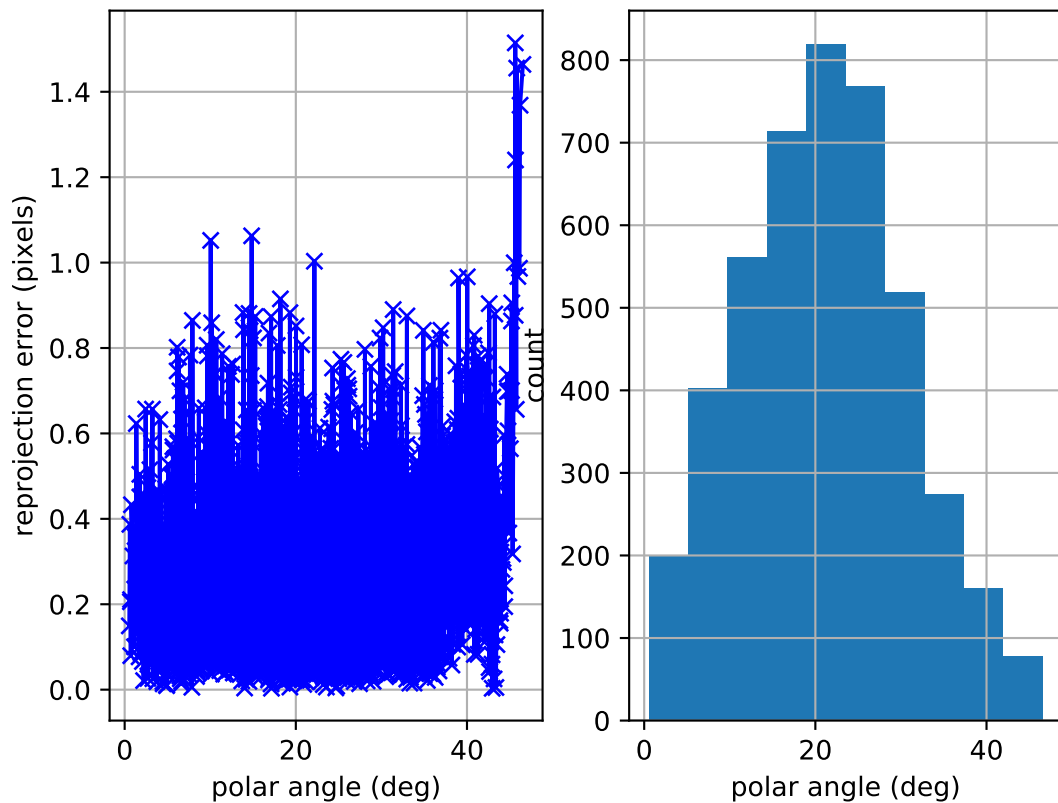
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

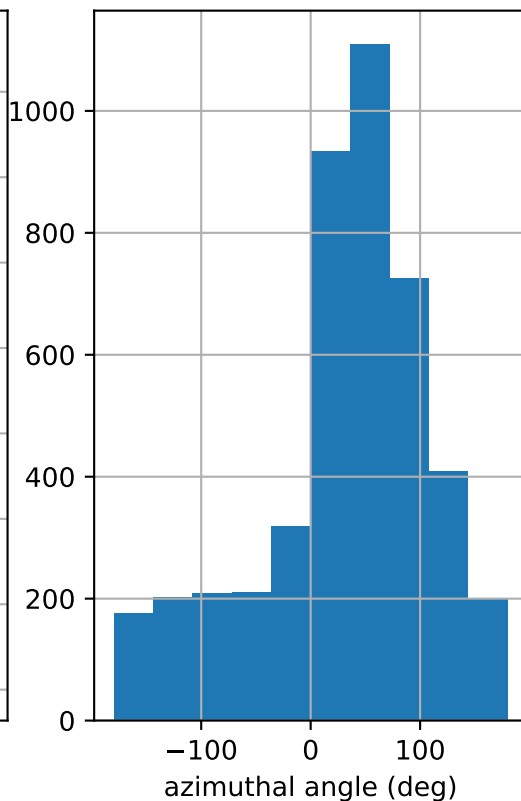
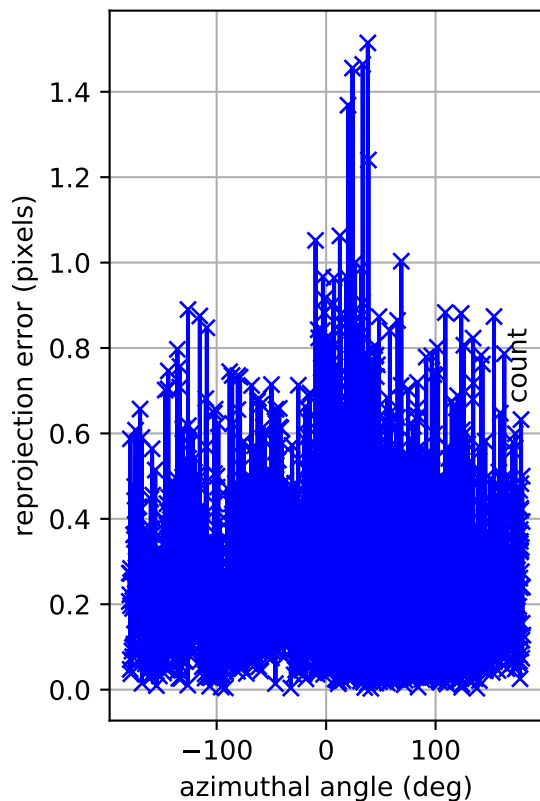
cam0: estimated poses



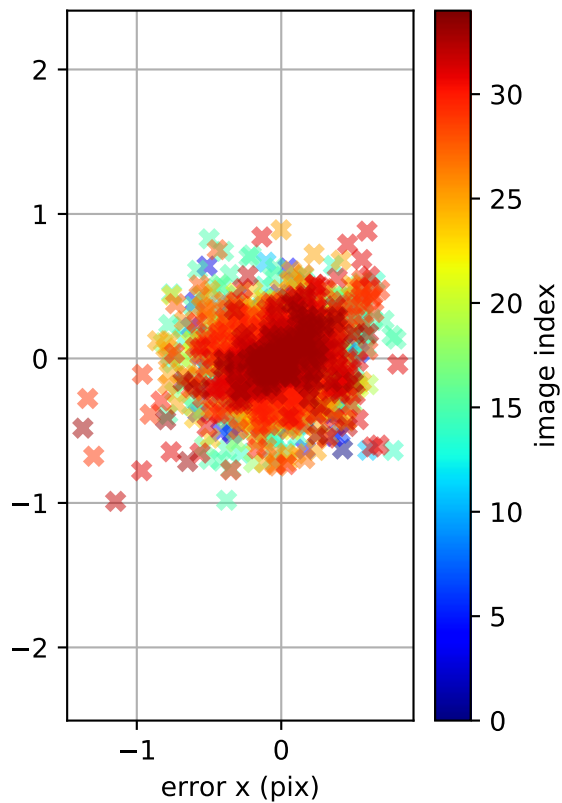
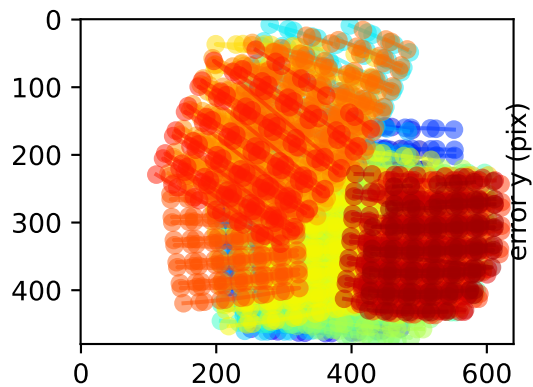
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

