

Calibration results

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Camera-system parameters:

cam0 (/camera/front_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33843518 0.10202463 -0.00021665 0.00014816] +- [0.00194309 0.00165542 0.00025234 0.0002699]

projection: [394.03538004 393.73346457 321.36647139 242.34252059] +- [1.20665013 1.18499328 0.75401862 0.78724871]

reprojection error: [0.000001, -0.000001] +- [0.192999, 0.148572]

Target configuration

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Type: aprilgrid

Tags:

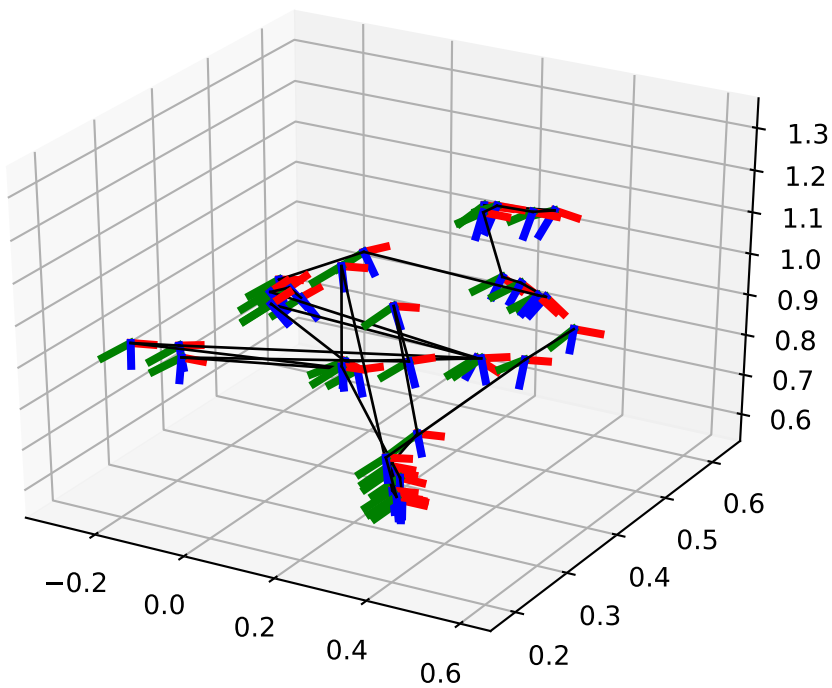
Rows: 6

Cols: 6

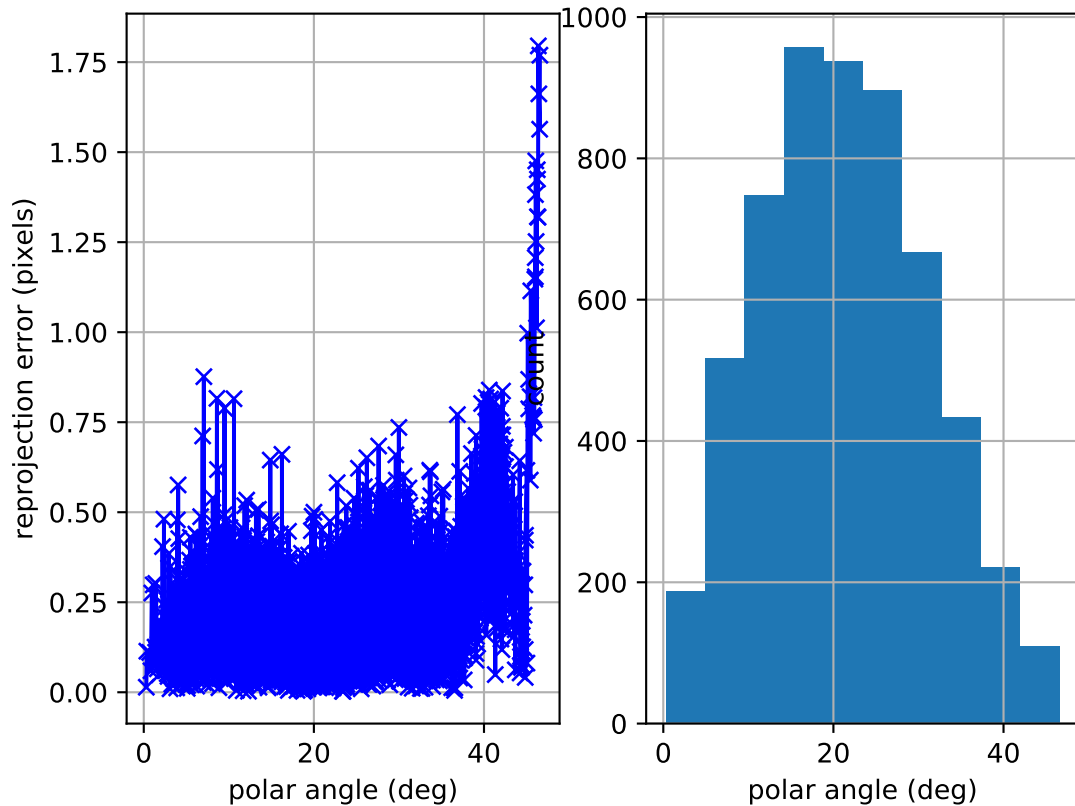
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

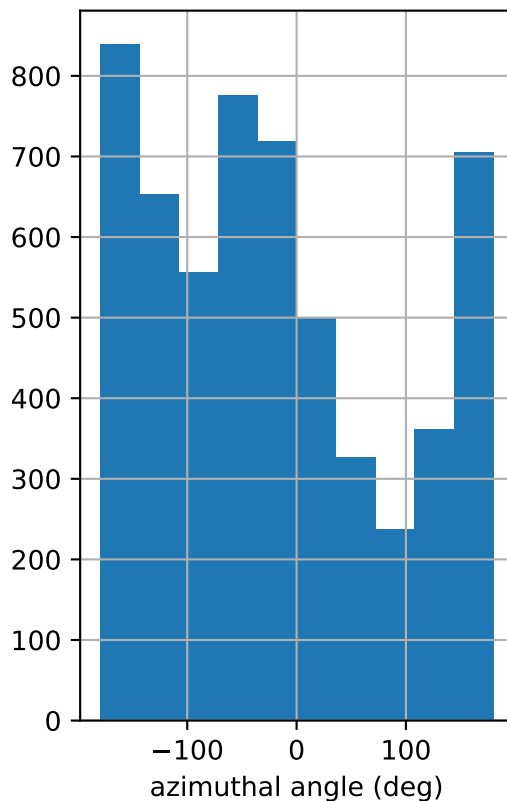
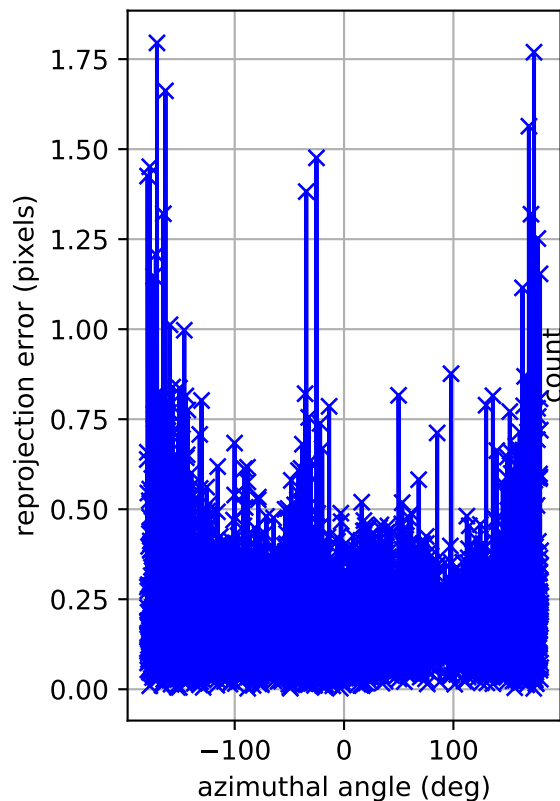
cam0: estimated poses



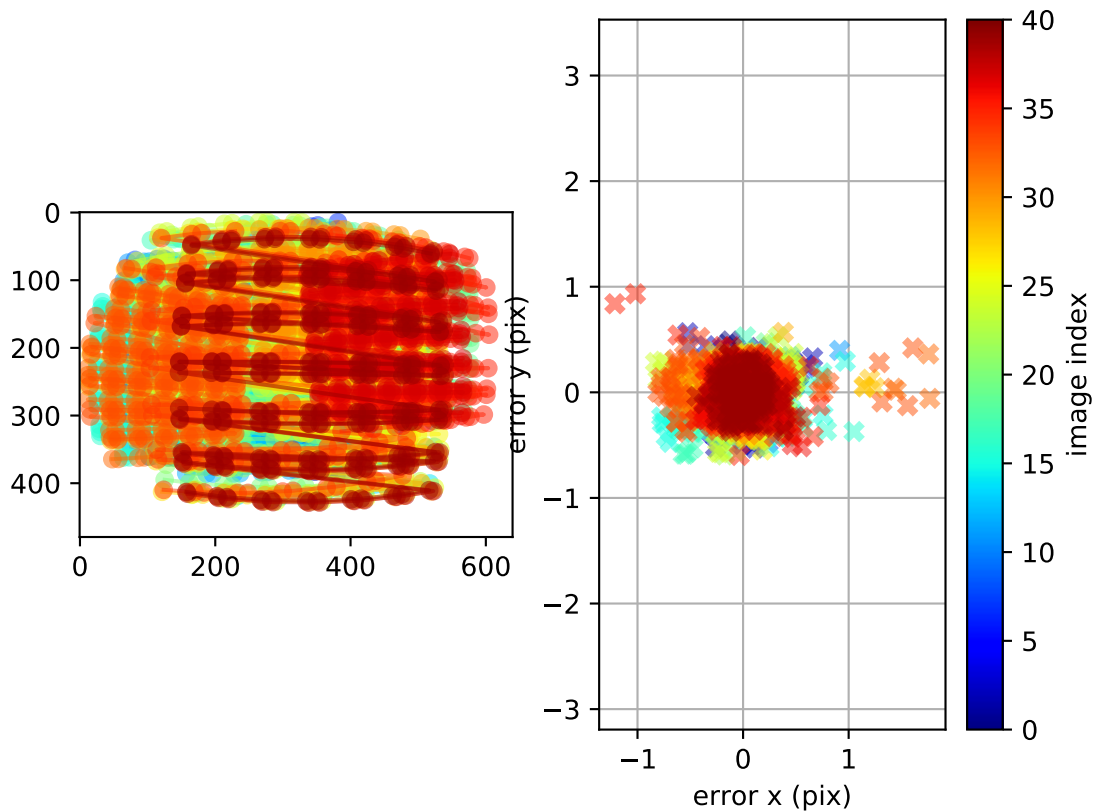
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

