

## Calibration results

=====

### Camera-system parameters:

cam0 (/camera/front\_left/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [-0.34081516 0.1071886 -0.00117313 -0.00047062] +- [0.0016018 0.00155367 0.00019812 0.00017062]

projection: [393.25659596 392.92684999 322.0897045 249.50449632] +- [0.69744924 0.65521872 0.54446306 0.58104157]

reprojection error: [-0.000000, -0.000001] +- [0.235227, 0.212571]

## Target configuration

=====

Type: aprilgrid

Tags:

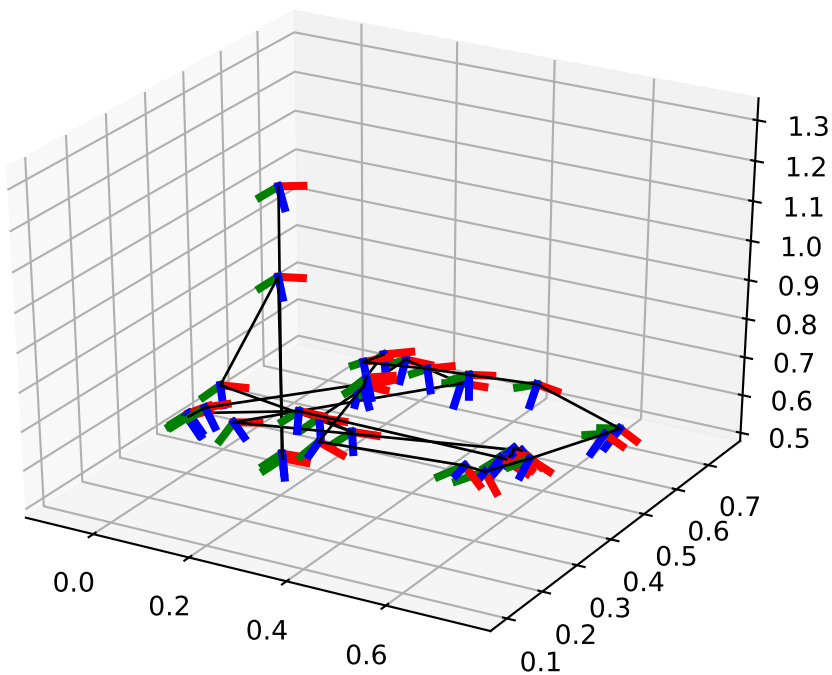
Rows: 6

Cols: 6

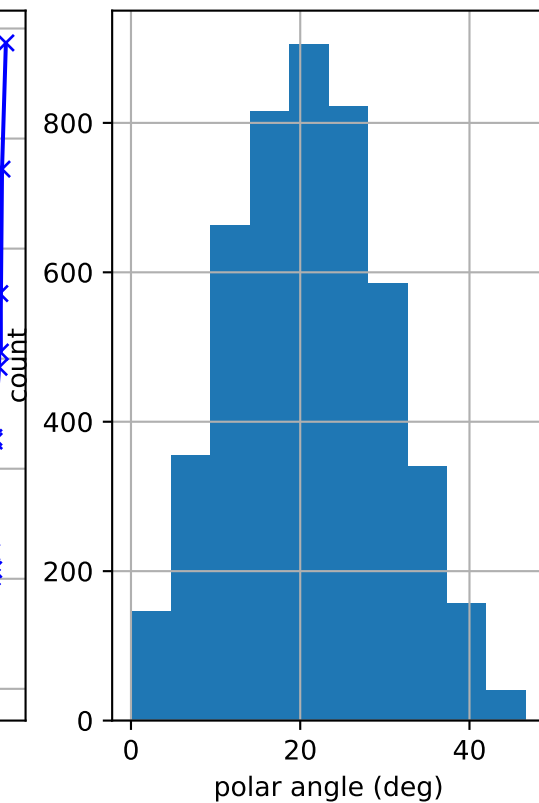
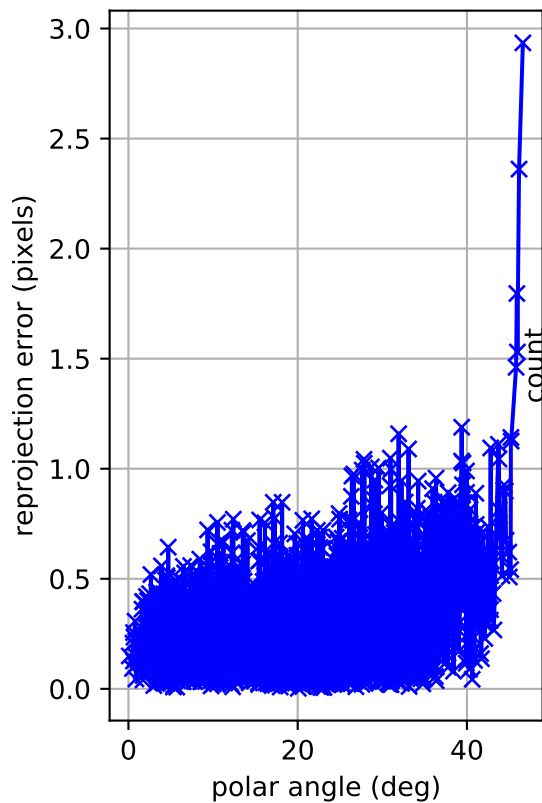
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

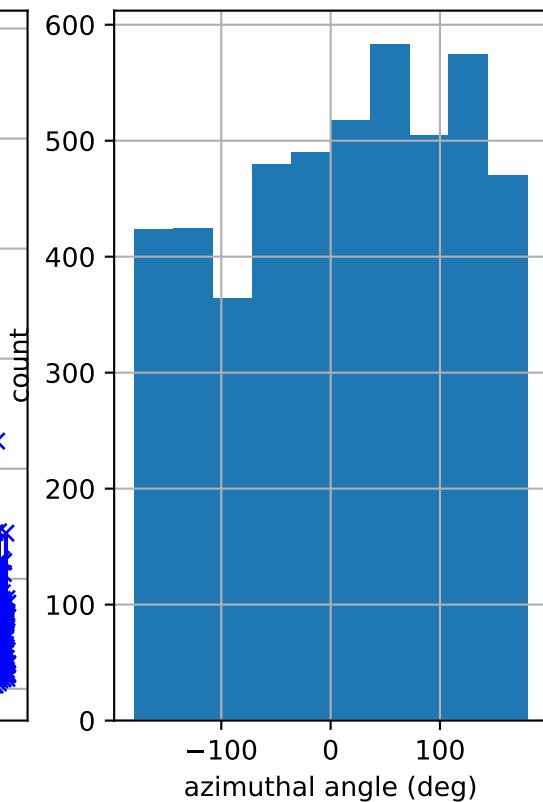
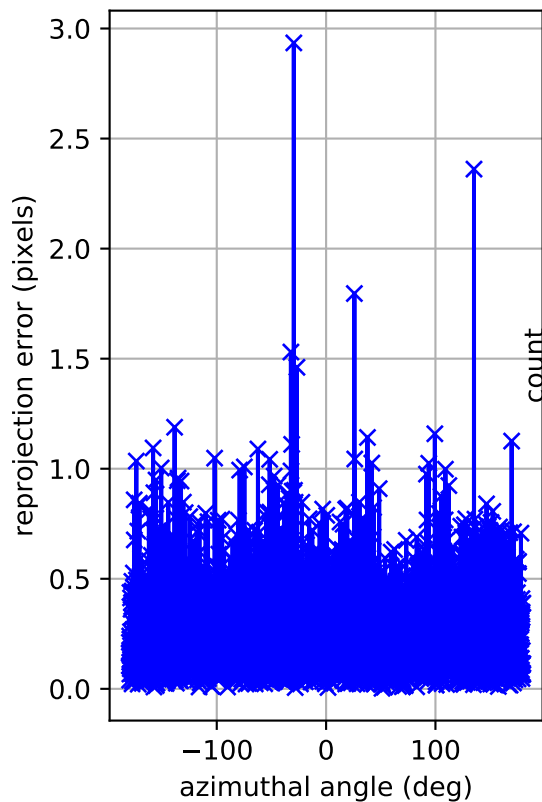
cam0: estimated poses



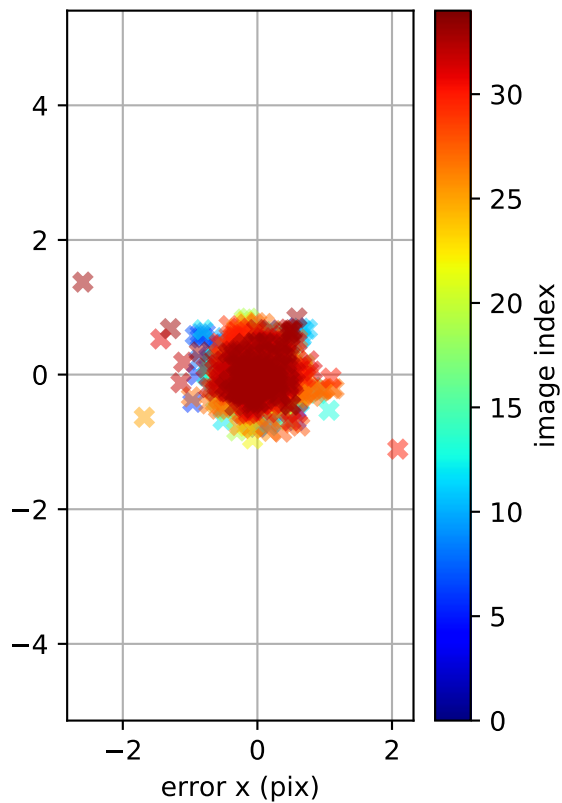
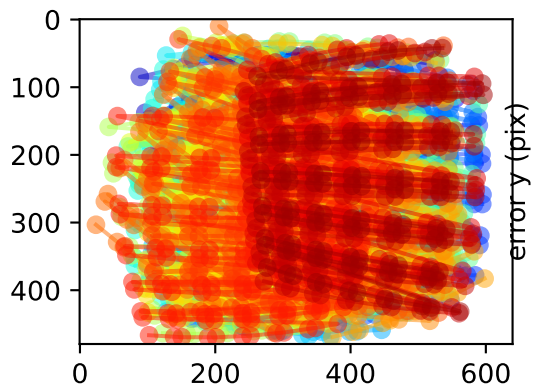
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

