

Calibration results

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Camera-system parameters:

cam0 (/camera/realsense/color/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.09664591 -0.1789841 0.00185079 0.00217812] +- [0.00442055 0.01198935 0.00062452 0.00057776]

projection: [601.3186412 601.27688535 333.27919851 255.8812825] +- [1.39833781 1.34296363 1.01122272 1.07477967]

reprojection error: [-0.000000, 0.000000] +- [0.307185, 0.284981]

Target configuration

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Type: aprilgrid

Tags:

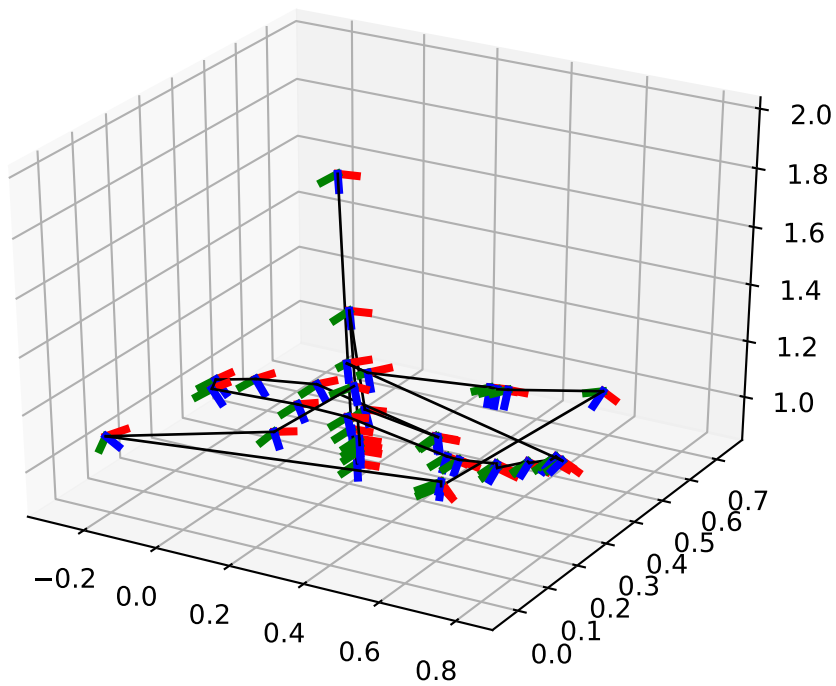
Rows: 6

Cols: 6

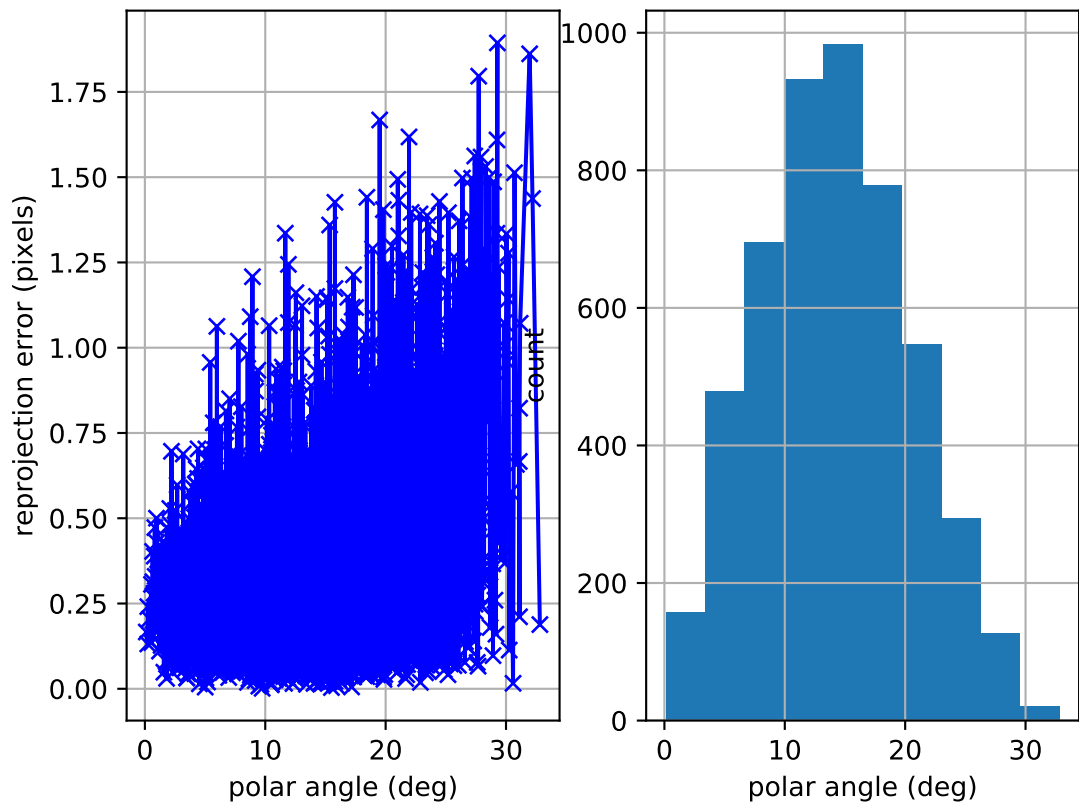
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

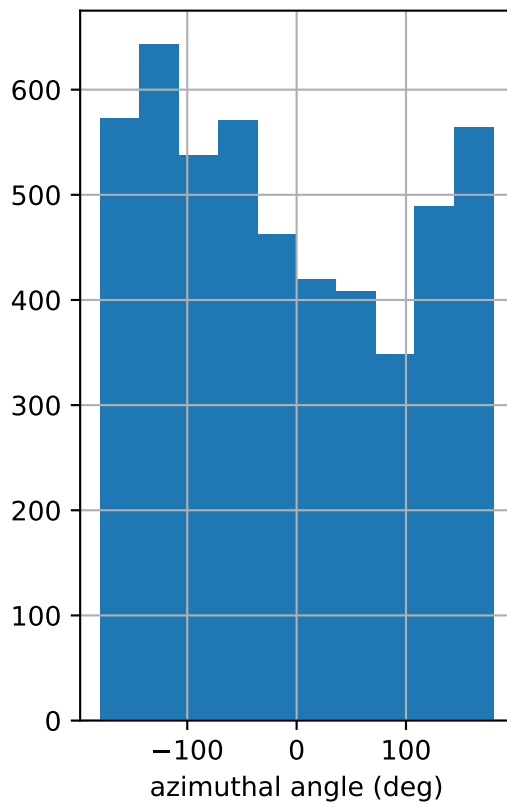
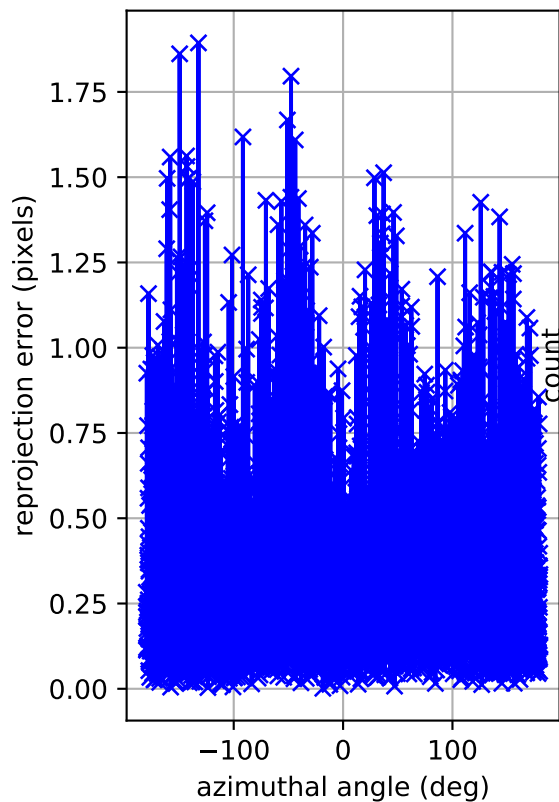
cam0: estimated poses



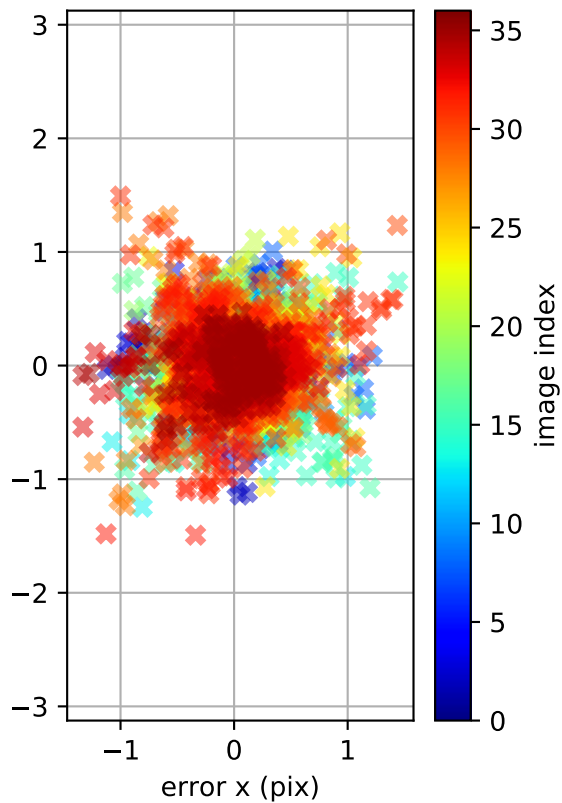
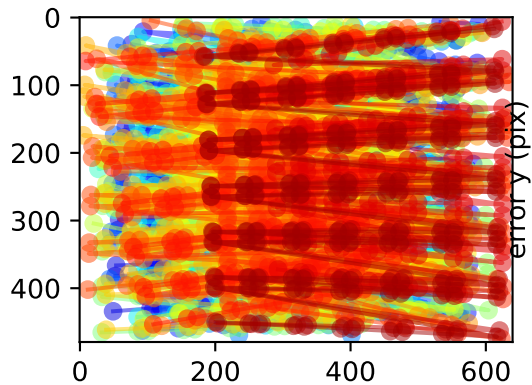
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

