

## Calibration results

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### Camera-system parameters:

cam0 (/camera/side\_left/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33872664 0.10577532 -0.00078651 -0.00029819] +- [0.0024488 0.00217458 0.00029019 0.00023065]

projection: [390.96396645 390.67392022 314.95318601 246.83142318] +- [1.42727856 1.3987448 0.74643177  
0.85826905]

reprojection error: [0.000000, 0.000001] +- [0.152585, 0.130522]

## Target configuration

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Type: aprilgrid

Tags:

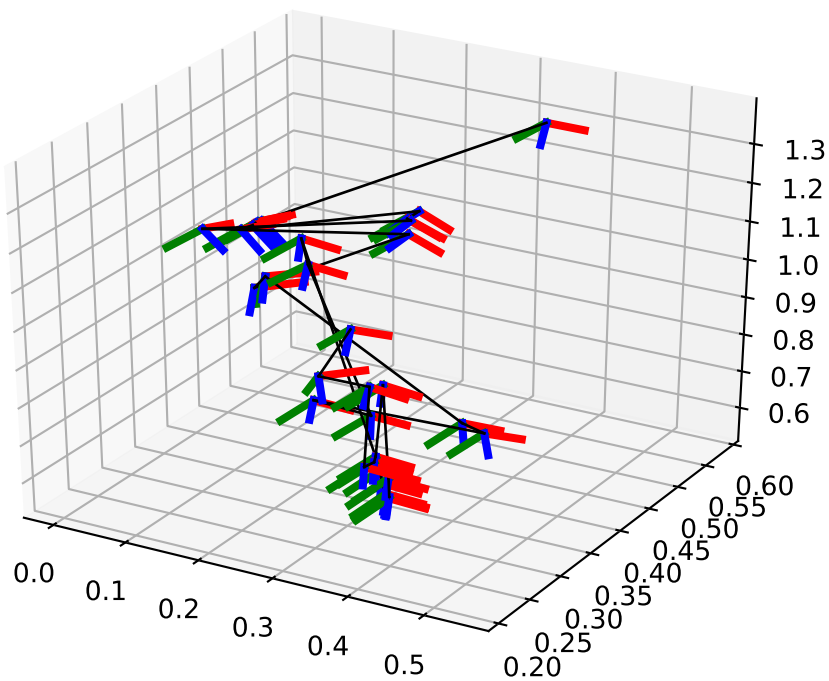
Rows: 6

Cols: 6

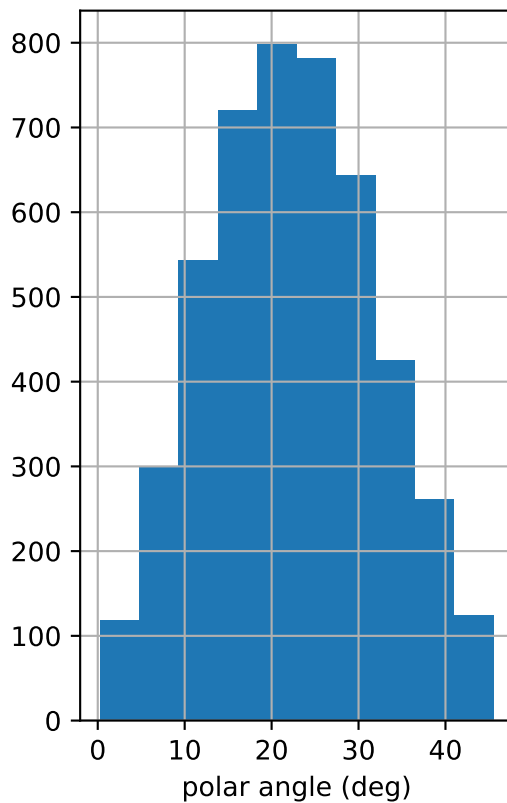
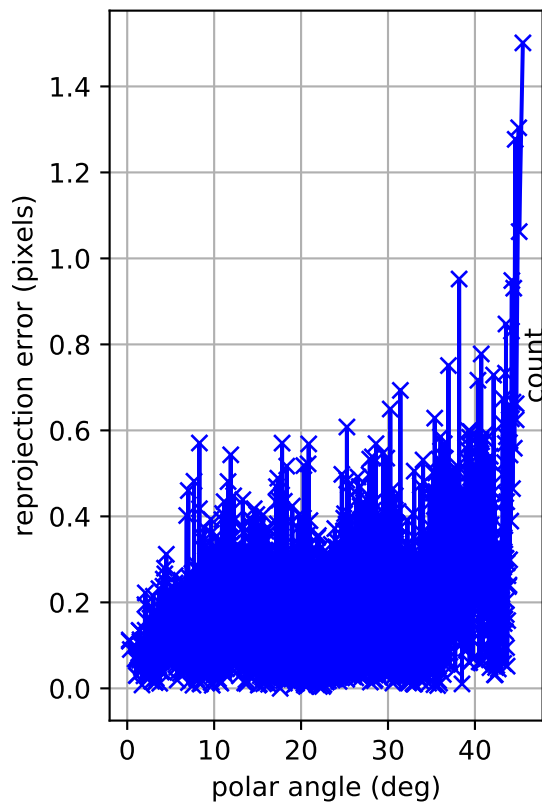
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

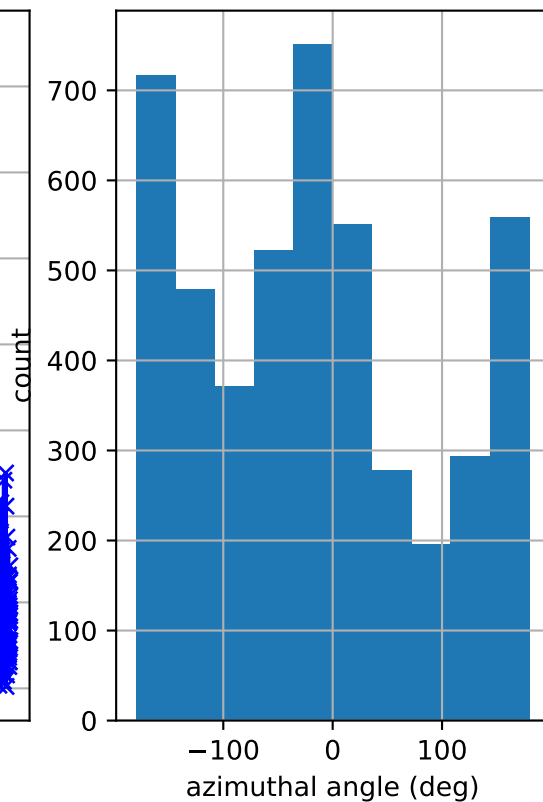
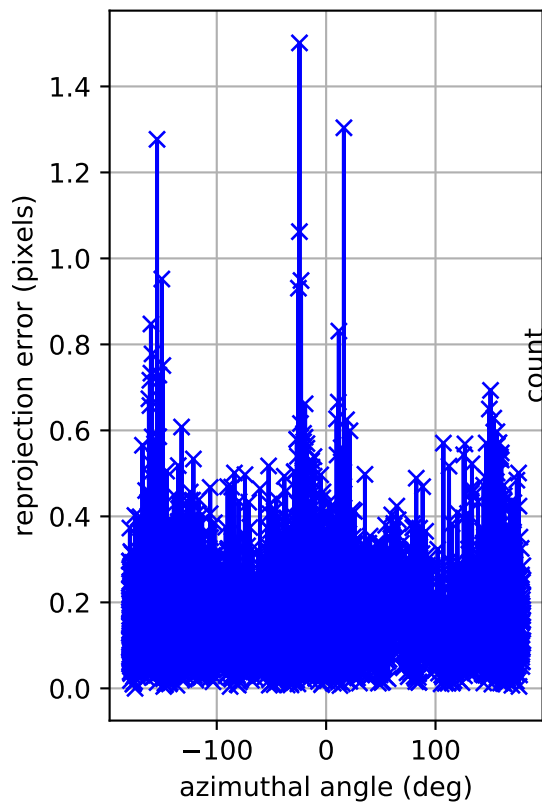
cam0: estimated poses



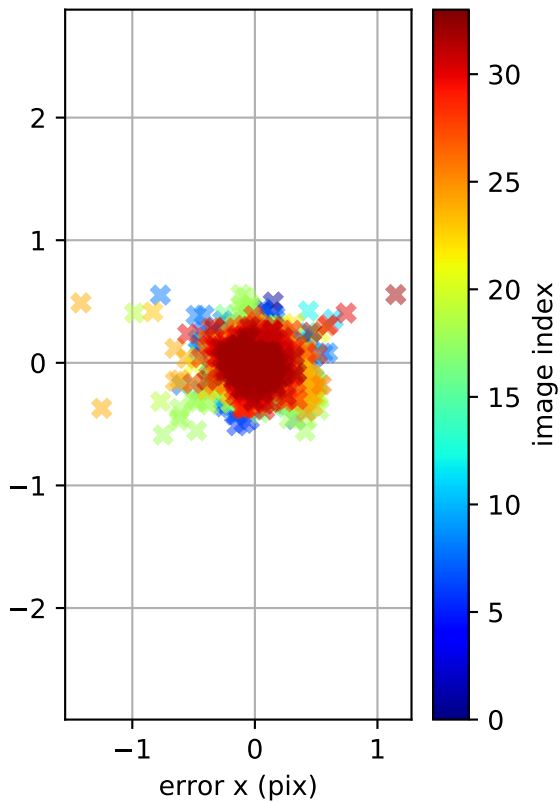
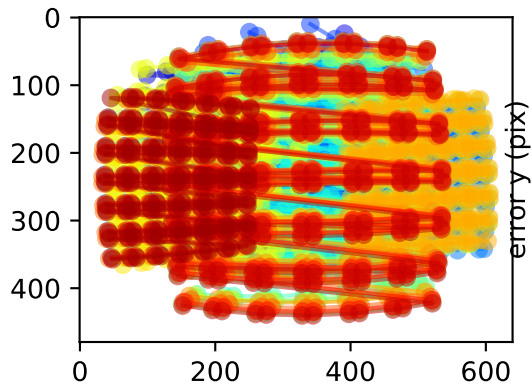
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



# Location of removed outlier corners

cam0

