Calibration results
====================
Camera-system parameters:
cam0 (/camera/front_right/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [-0.32461861 0.08921186 0.00046597 -0.00065441] +- [0.00205085 0.00140348 0.00022387 0.0001992]
projection: [391.25376159 391.66990525 325.77321058 243.65641578] +- [1.25536087 1.21138351 0.62909739 0.58840541]
reprojection error: [-0.000002, -0.000005] +- [0.313355, 0.245497]

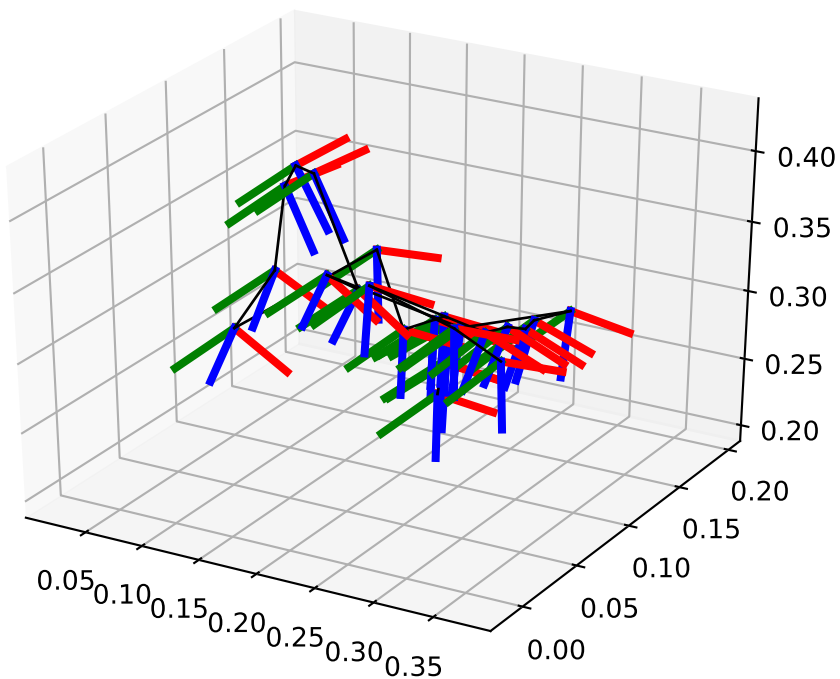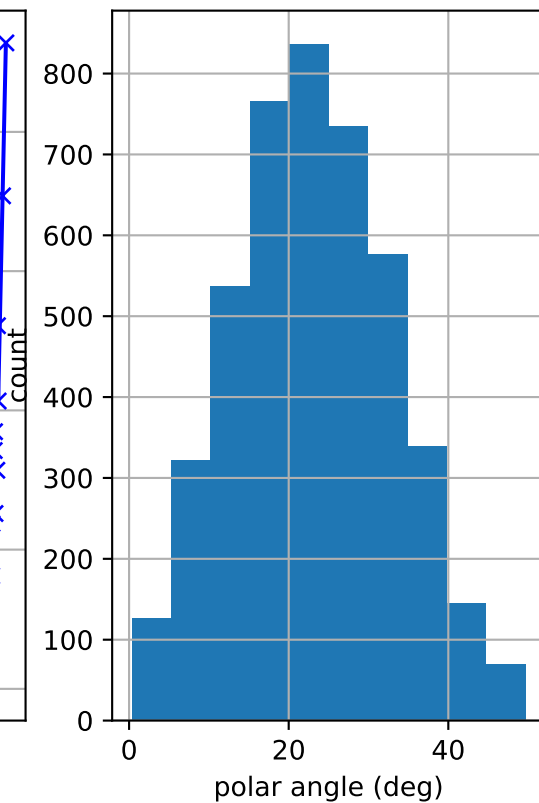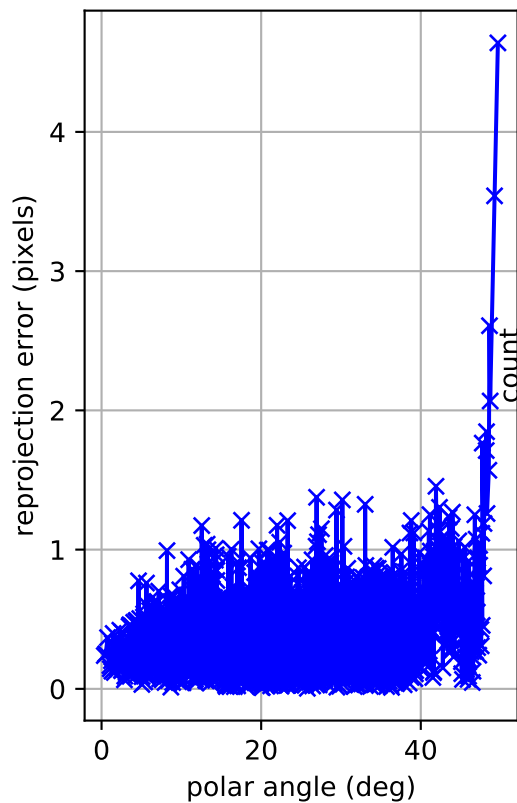Target configuration
====================

Type: aprilgrid
Tags:
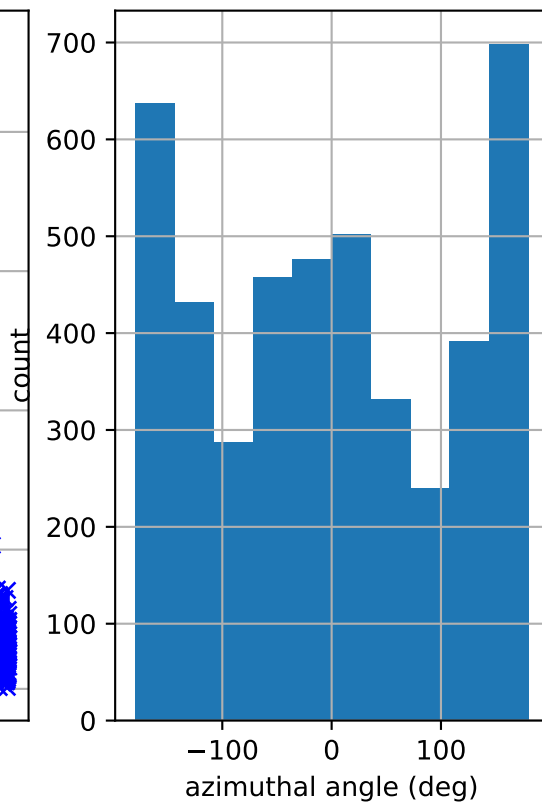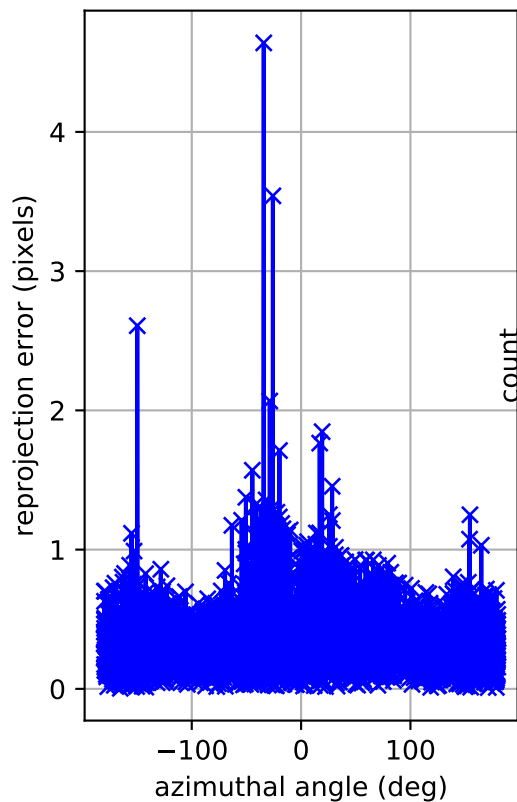Rows: 6
Cols: 8
Size: 0.034 [m]
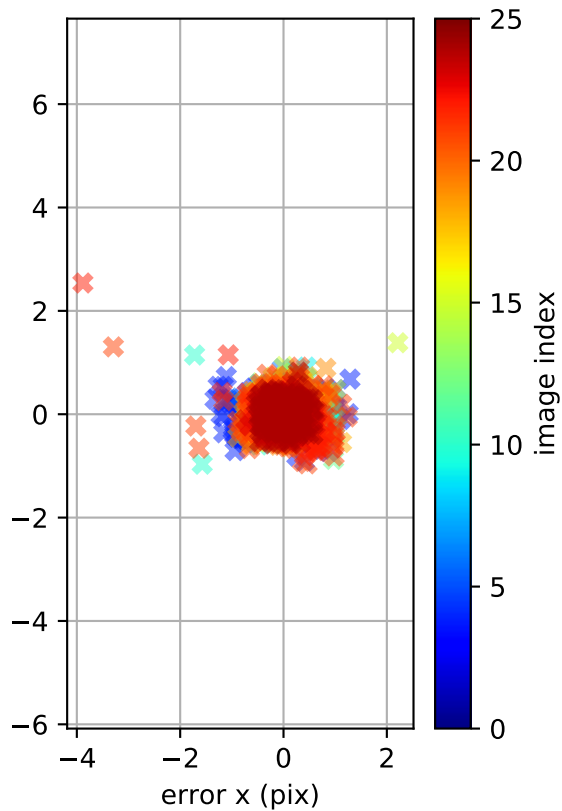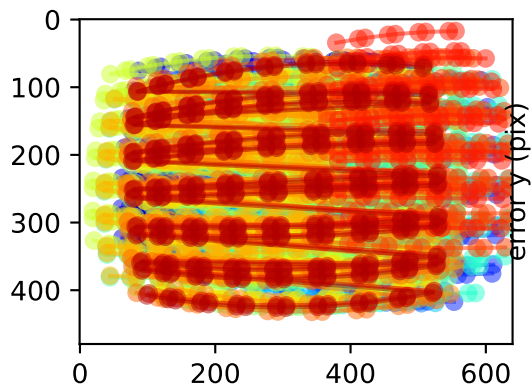Spacing 0.0099994 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0