

Calibration results

=====

Camera-system parameters:

cam0 (/camera/side_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.32201131 0.08680743 0.00003892 0.00006133] +- [0.00230067 0.00141515 0.00020115 0.00016923]

projection: [390.45597408 390.22416046 322.84506513 237.46722073] +- [1.24246316 1.23915271 0.46138078 0.49184567]

reprojection error: [-0.000001, 0.000001] +- [0.379369, 0.301230]

Target configuration

=====

Type: aprilgrid

Tags:

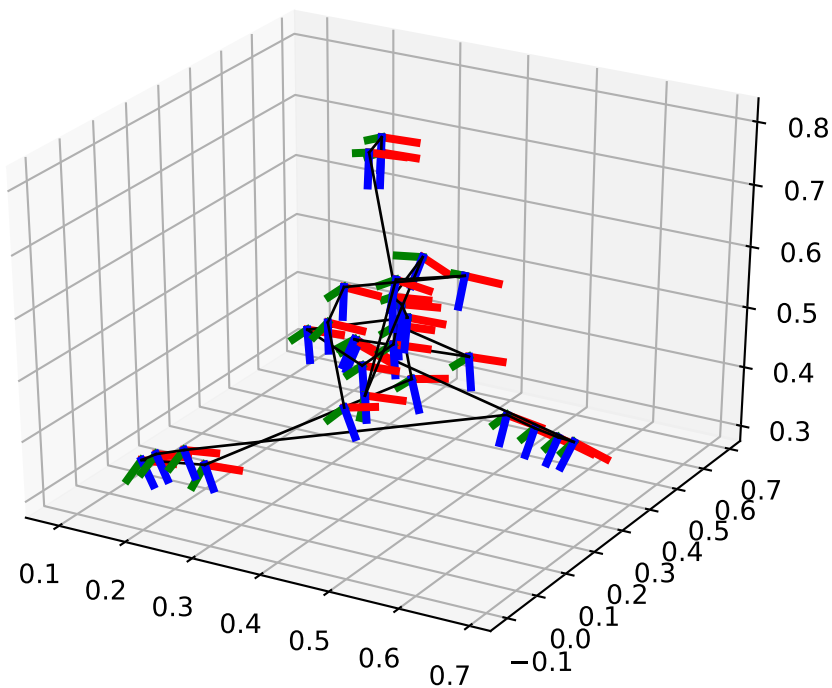
Rows: 6

Cols: 6

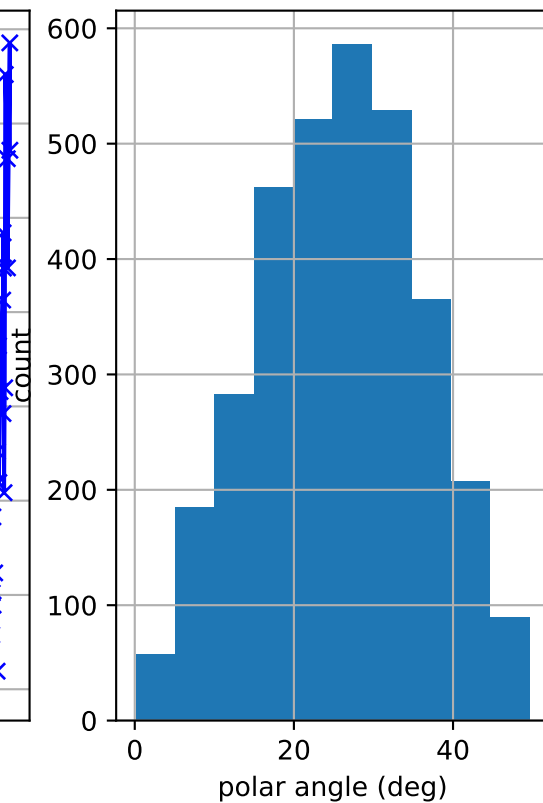
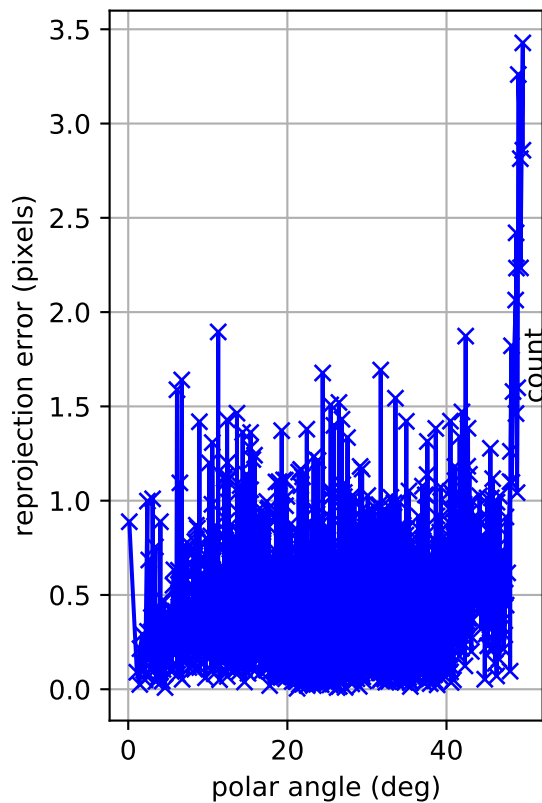
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

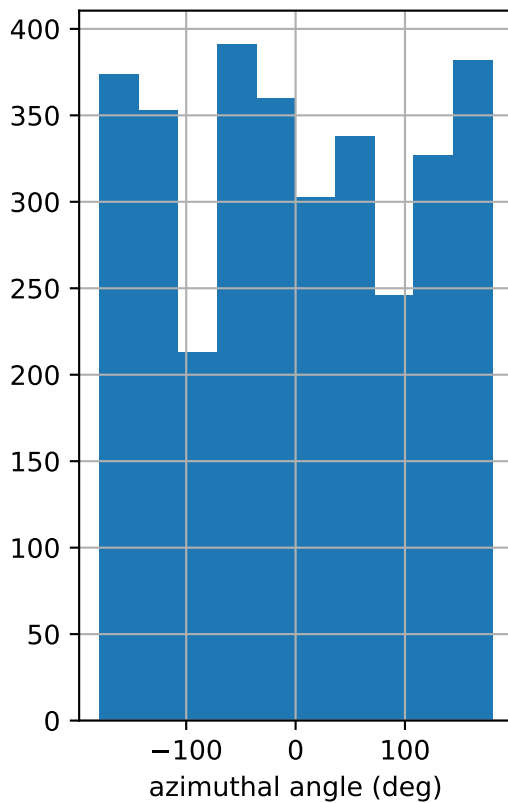
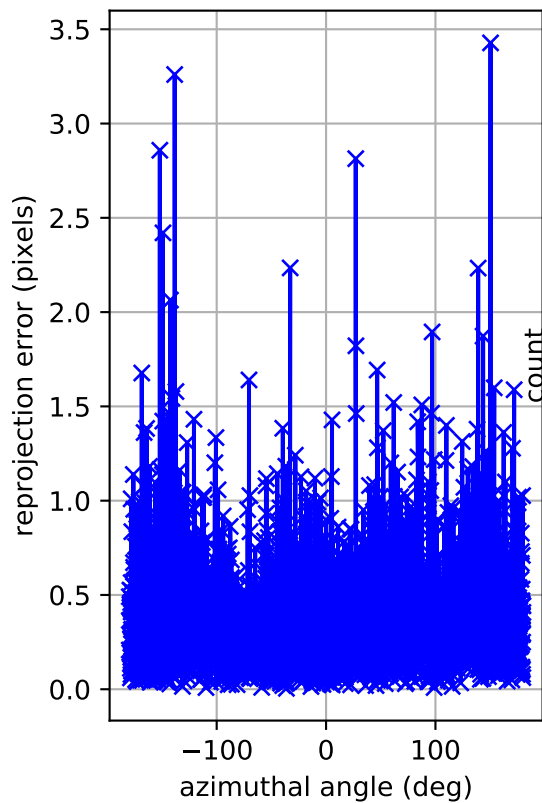
cam0: estimated poses



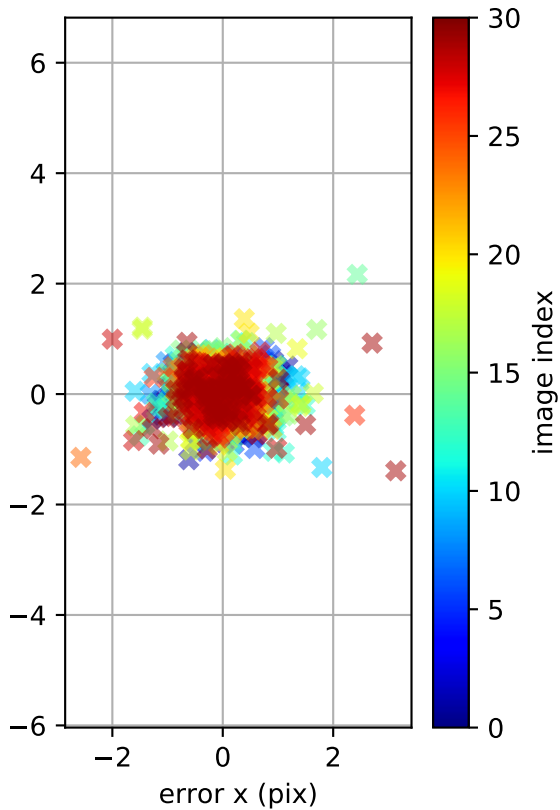
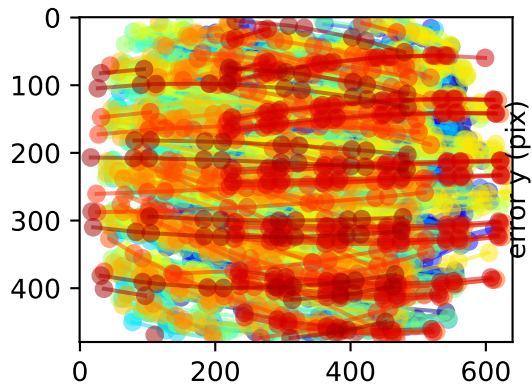
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

