

Calibration results

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Camera-system parameters:

cam0 (/camera/front_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.32634353 0.09041794 0.00069436 0.00001007] +- [0.00150707 0.00103004 0.0001874 0.0001498]

projection: [394.00384392 393.90985645 319.01662811 244.44692281] +- [0.84552903 0.82862147 0.46518102 0.46999049]

reprojection error: [-0.000000, -0.000000] +- [0.319935, 0.270845]

Target configuration

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Type: aprilgrid

Tags:

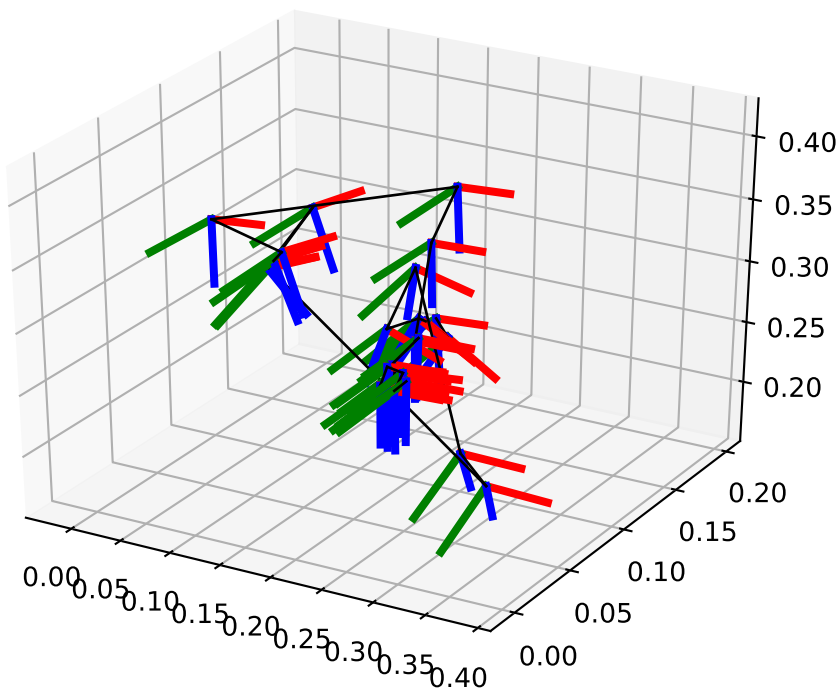
Rows: 6

Cols: 8

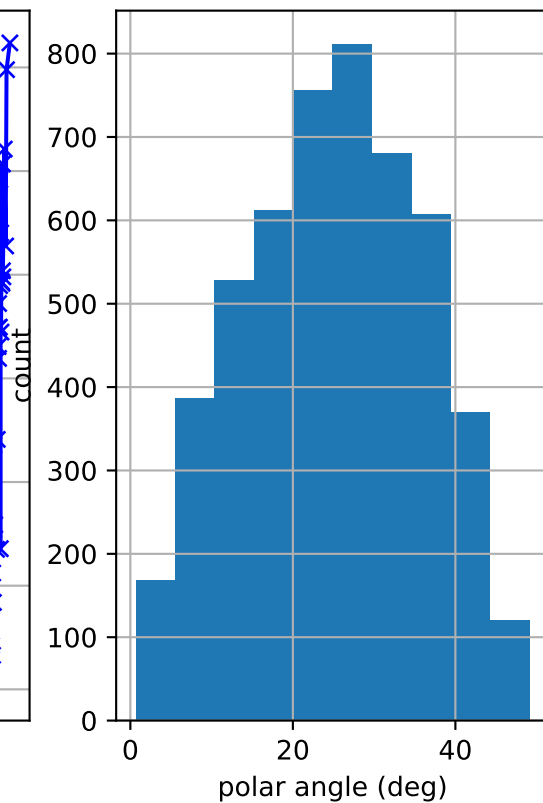
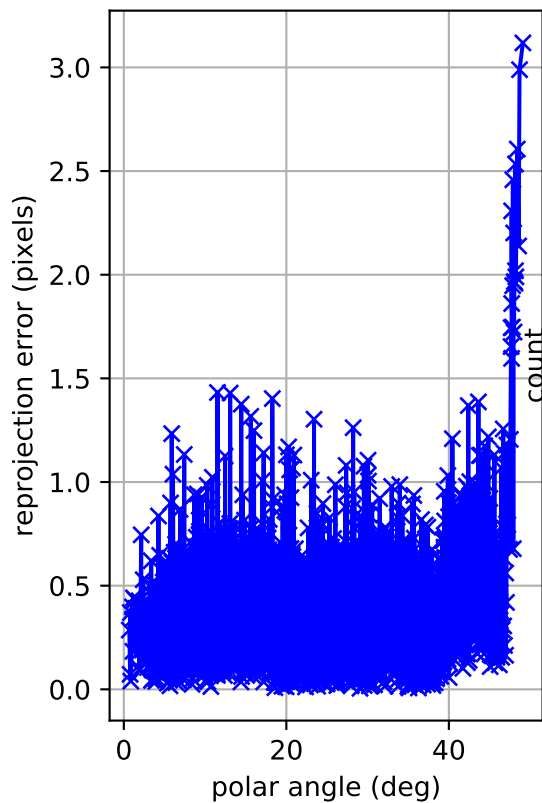
Size: 0.034 [m]

Spacing 0.0099994 [m]

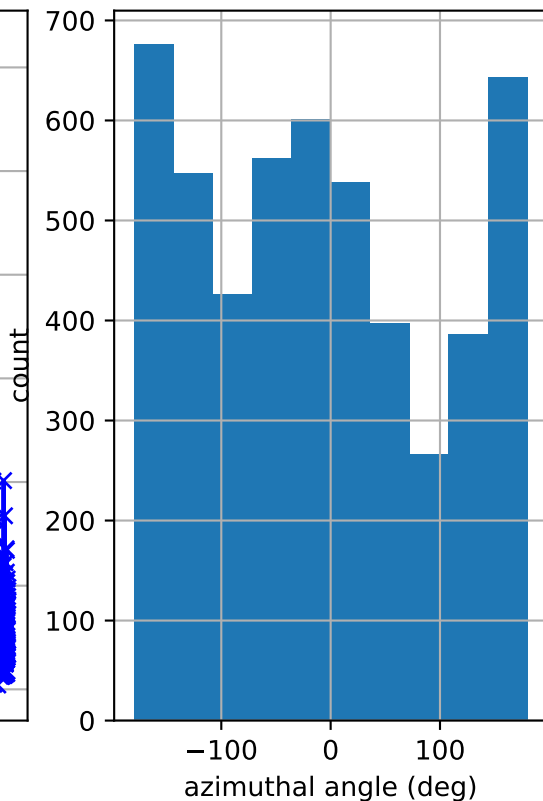
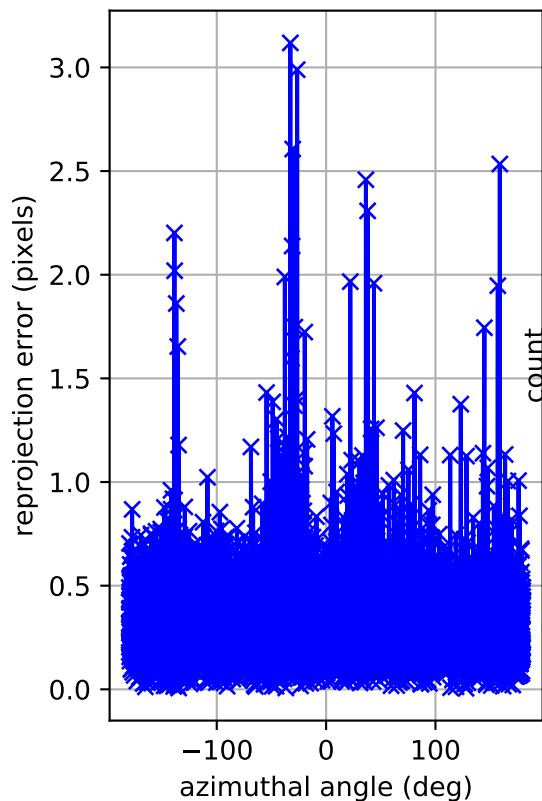
cam0: estimated poses



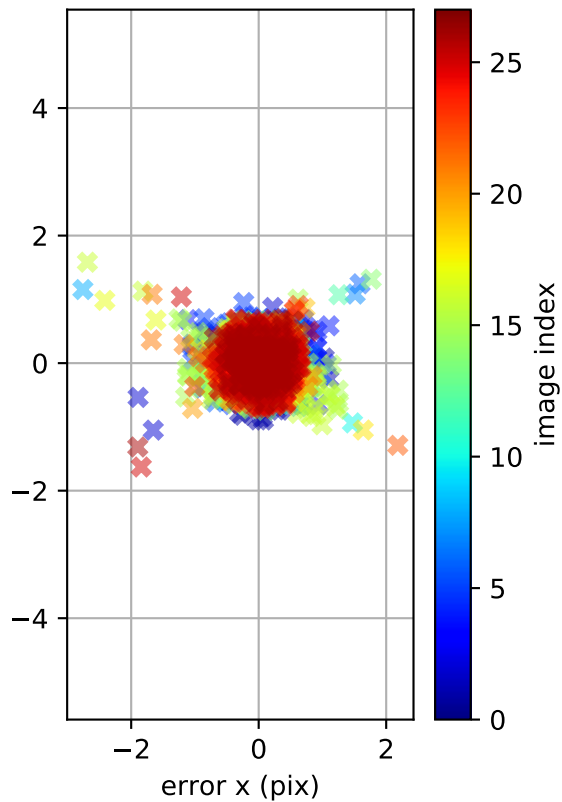
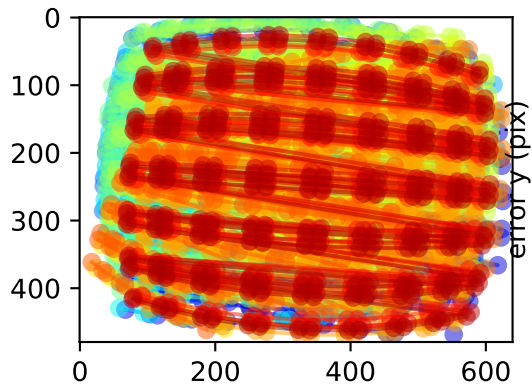
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

