

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.3458491 0.11686045 -0.00115991 -0.00048624] +- [0.00275166 0.00291393 0.00043878 0.00041017]

projection: [392.06109318 391.59721145 314.79954596 247.47784518] +- [1.92845736 1.96226151 1.25060154 1.39615027]

reprojection error: [-0.000000, -0.000000] +- [0.184047, 0.177976]

Target configuration

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Type: aprilgrid

Tags:

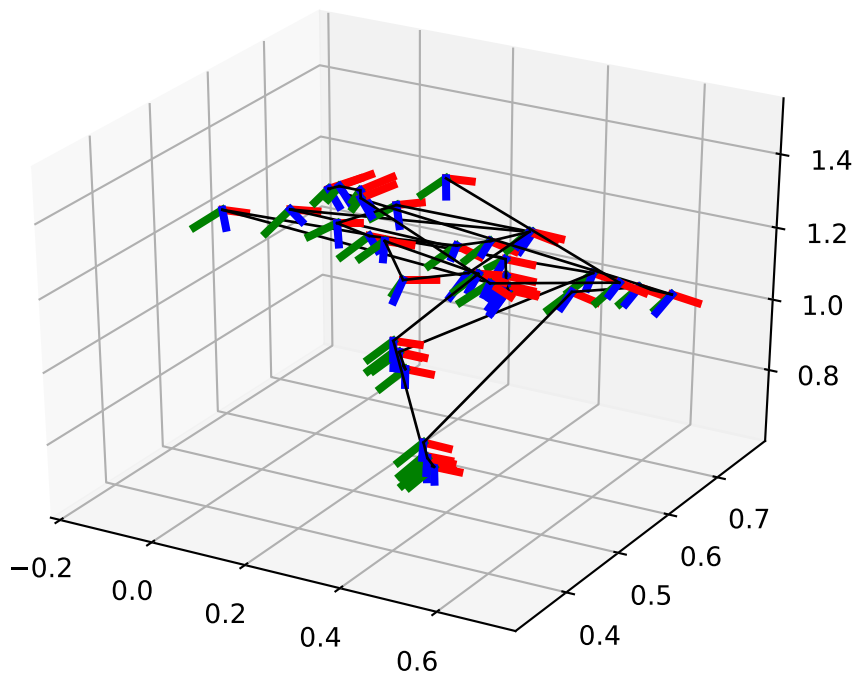
Rows: 6

Cols: 6

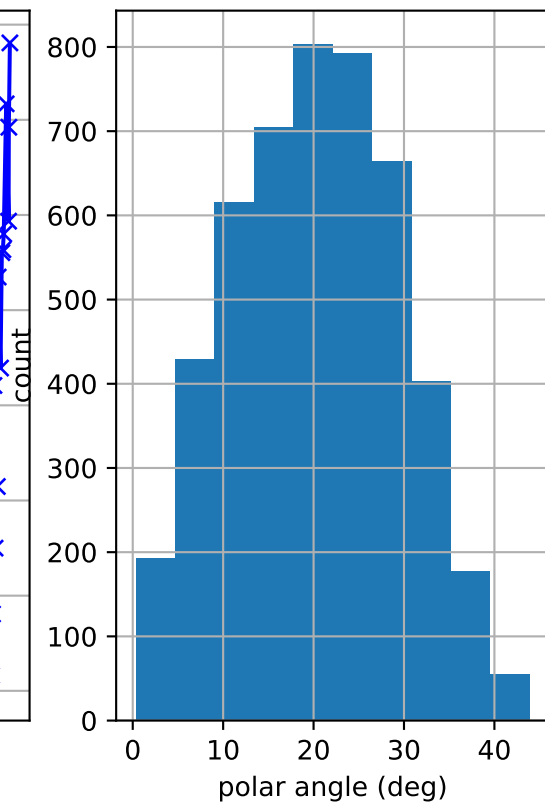
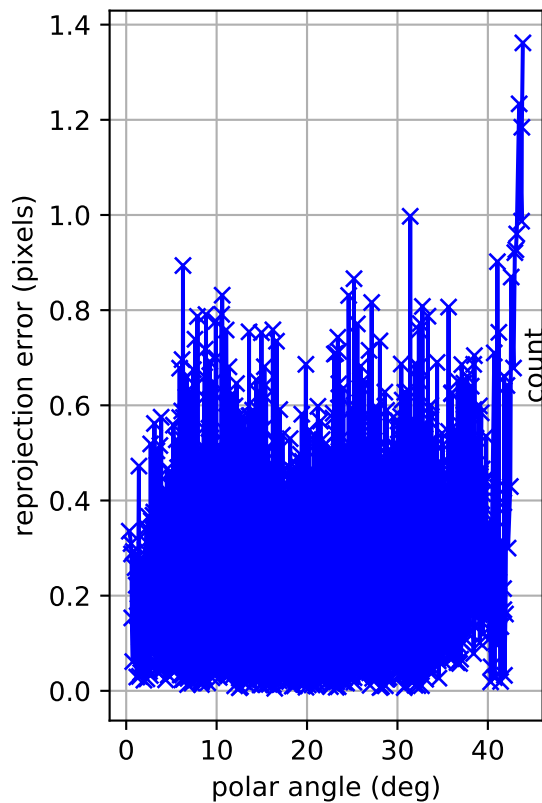
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

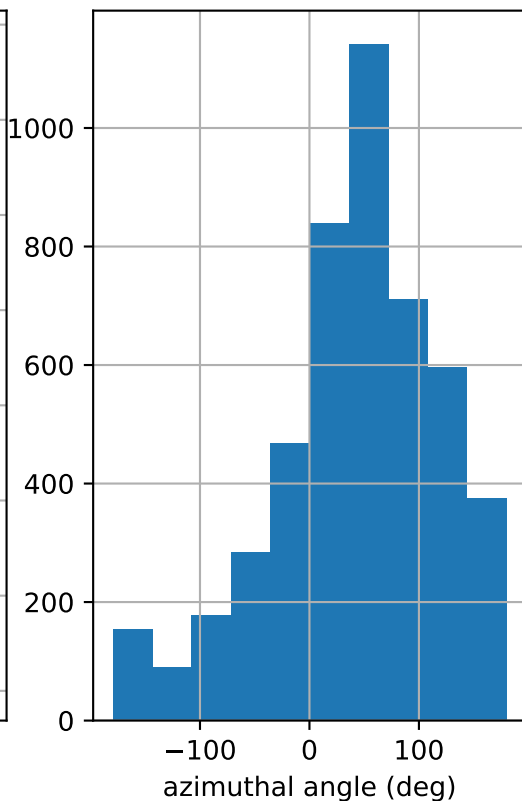
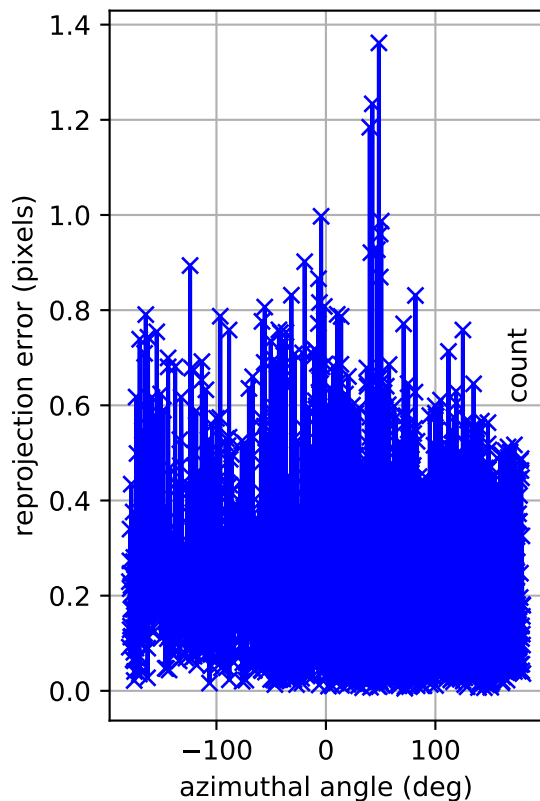
cam0: estimated poses



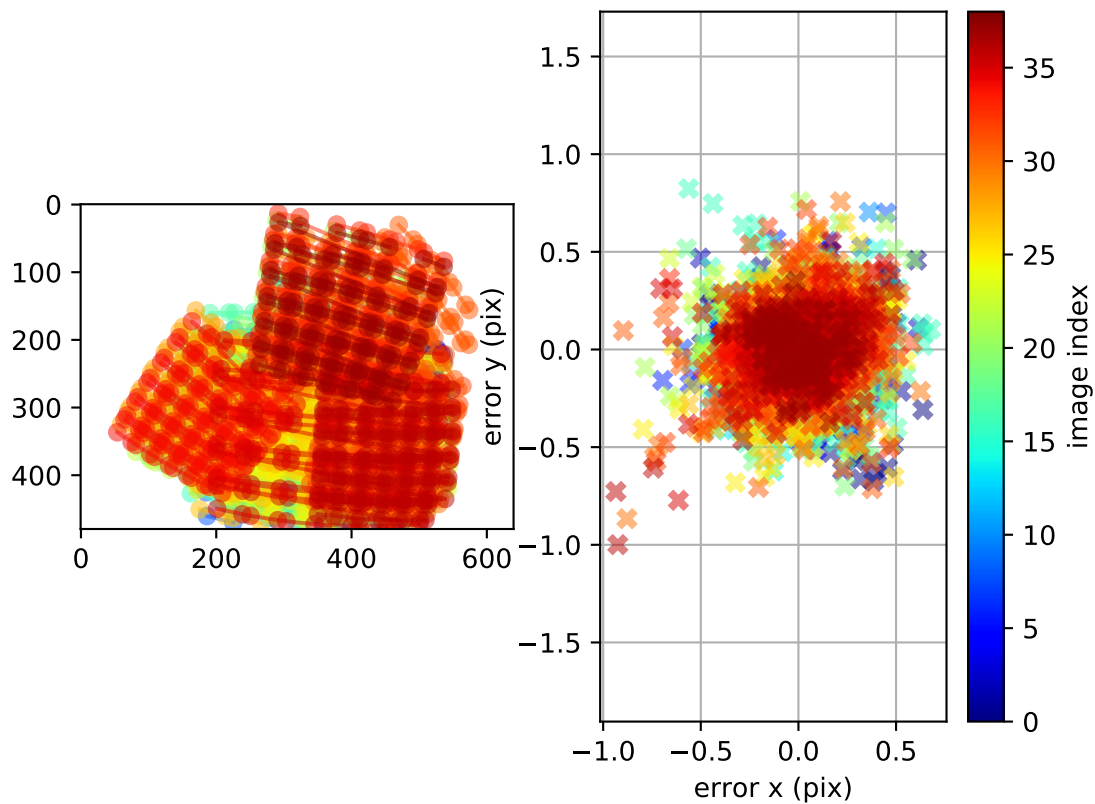
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

