

Calibration results

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Camera-system parameters:

cam0 (/camera/front_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.3337571 0.09906735 -0.00087637 0.00003617] +- [0.00413453 0.00286391 0.00054384 0.00039127]

projection: [396.33713723 396.31674795 319.20160479 245.13430779] +- [3.37009752 3.38984888 1.31320739 1.81348962]

reprojection error: [0.000001, 0.000002] +- [0.186517, 0.158228]

Target configuration

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Type: aprilgrid

Tags:

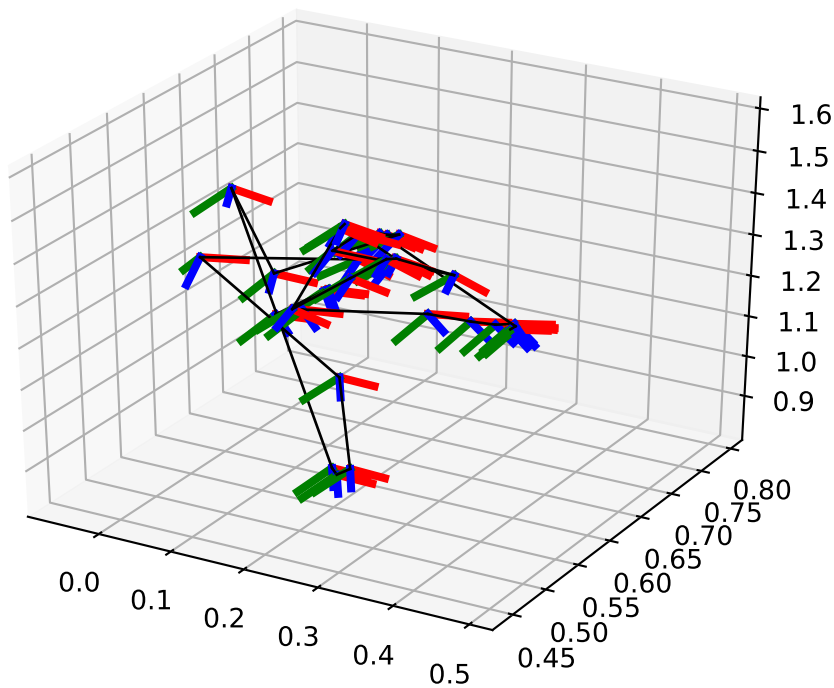
Rows: 6

Cols: 6

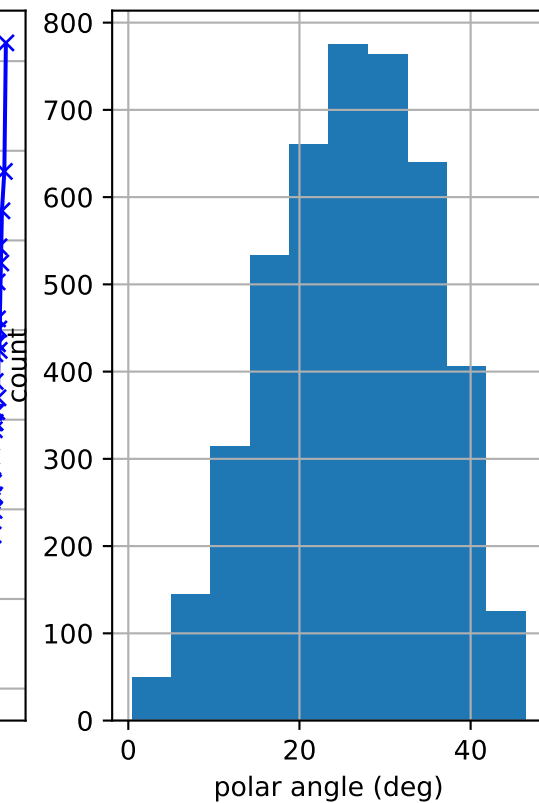
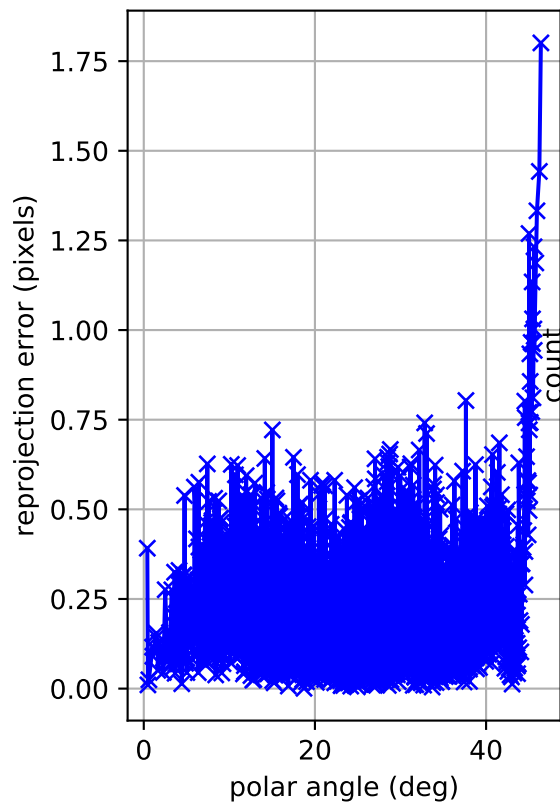
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

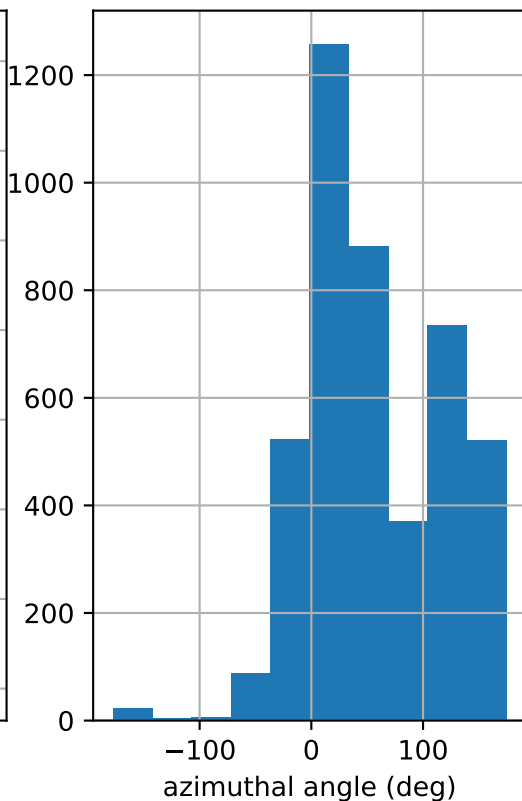
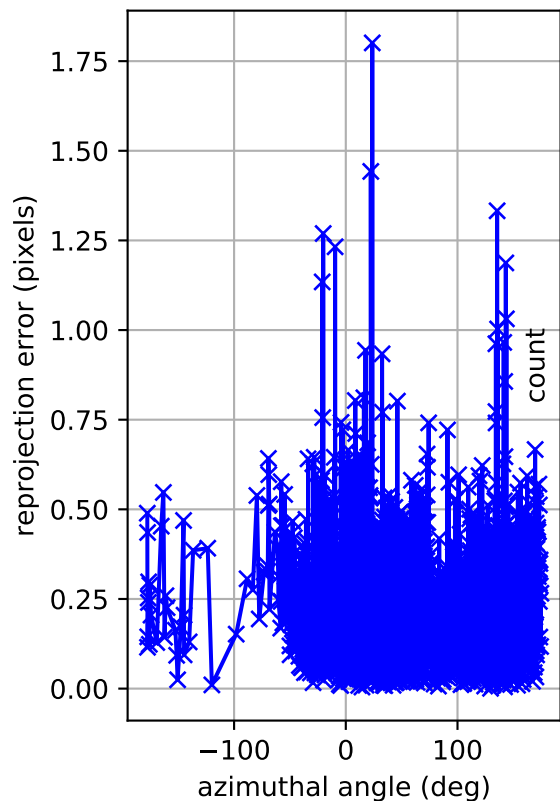
cam0: estimated poses



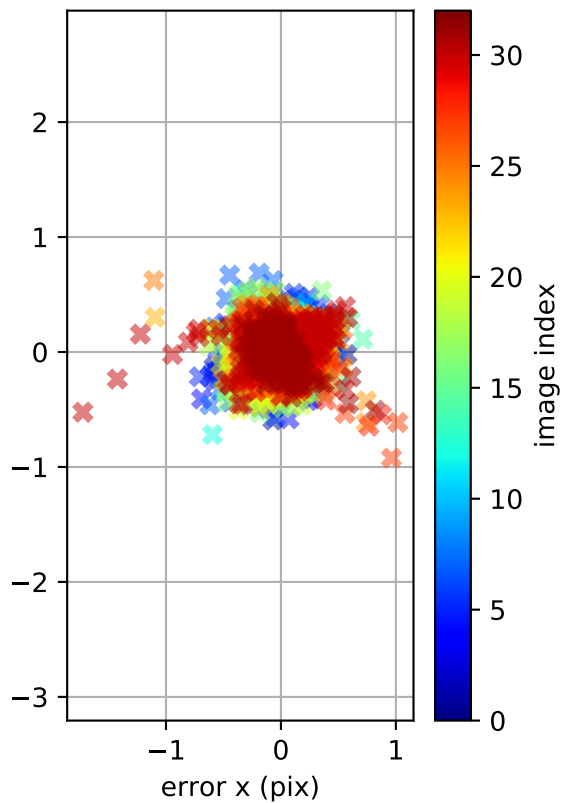
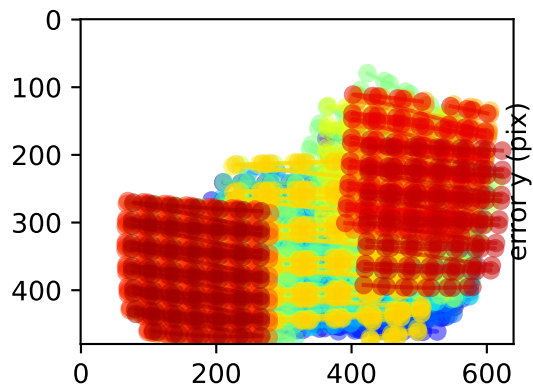
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

