

## Calibration results

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### Camera-system parameters:

cam0 (/camera/side\_left/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33260706 0.09642275 0.00010666 -0.0003222 ] +- [0.00121238 0.00103004 0.00015431 0.00013537]

projection: [393.94744396 393.59413982 315.28951461 246.1073115 ] +- [0.55595004 0.53294499 0.50566225  
0.5319154 ]

reprojection error: [-0.000001, -0.000001] +- [0.267606, 0.237429]

## Target configuration

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Type: aprilgrid

Tags:

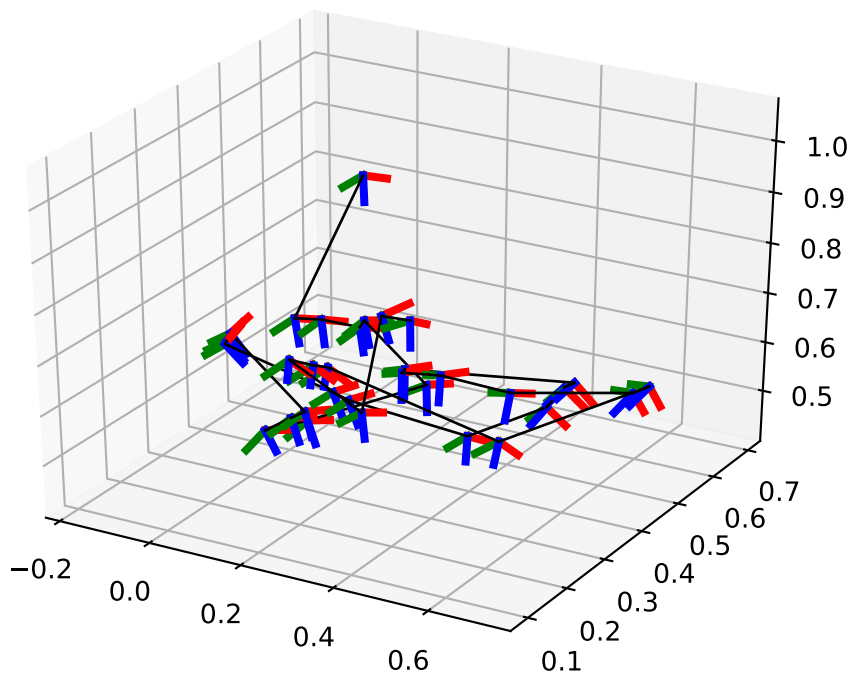
Rows: 6

Cols: 6

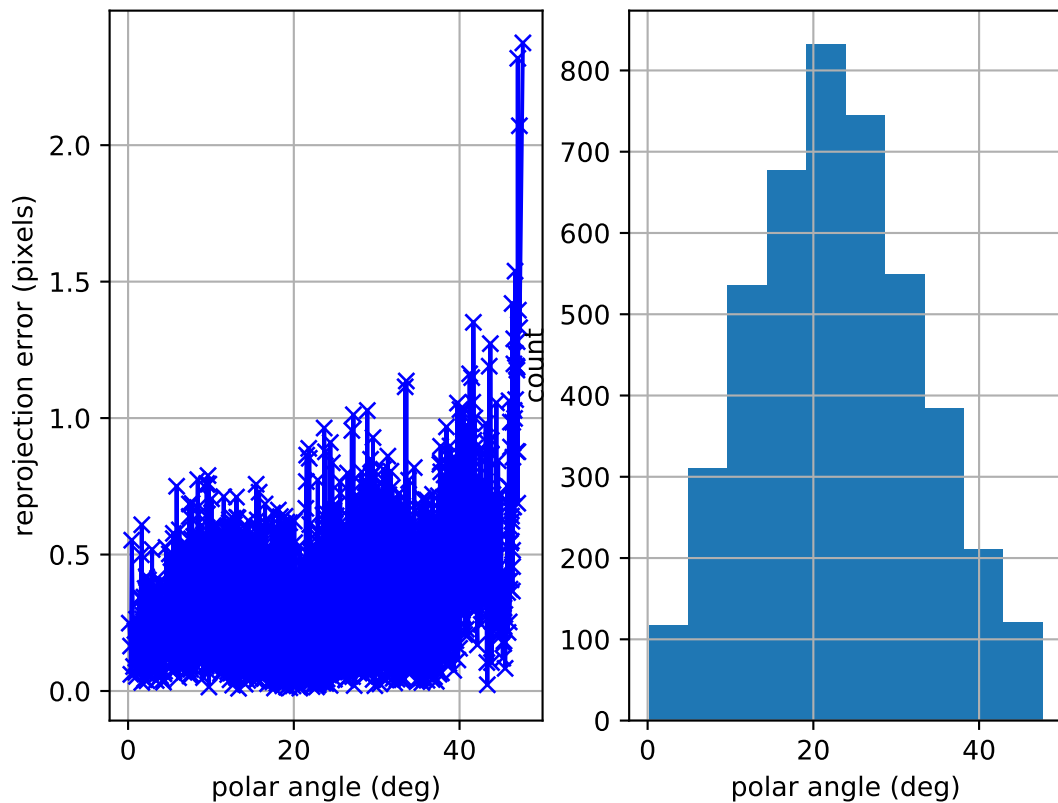
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

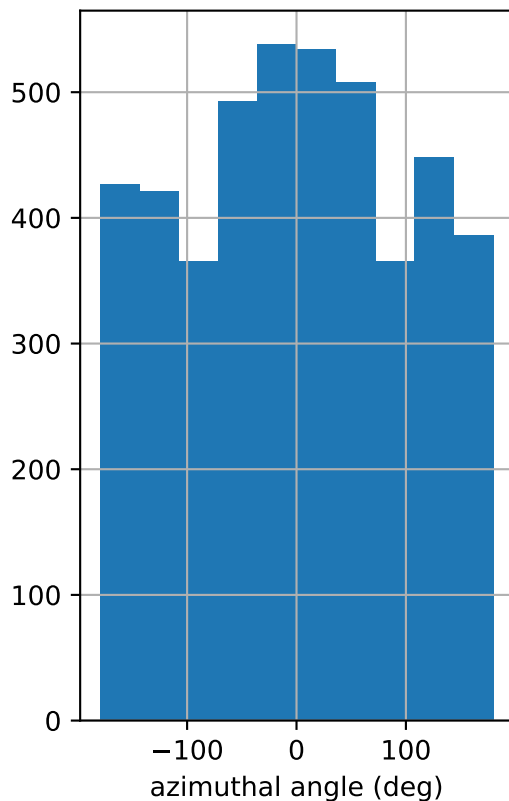
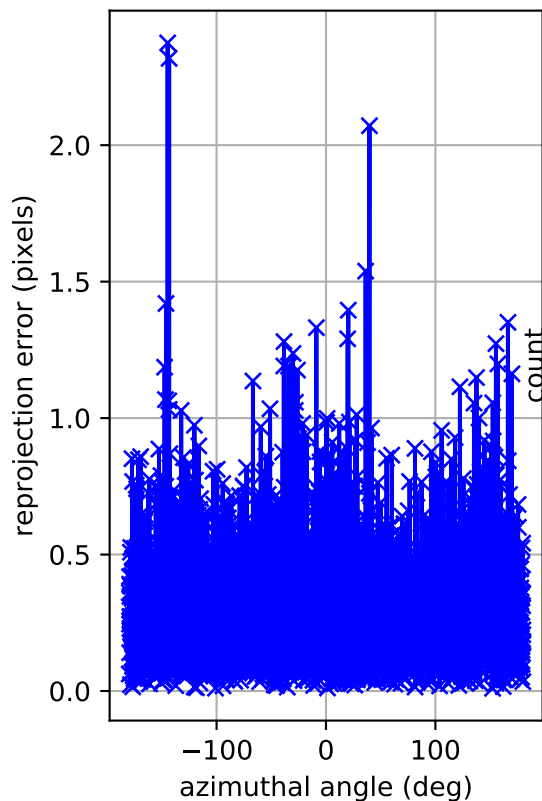
cam0: estimated poses



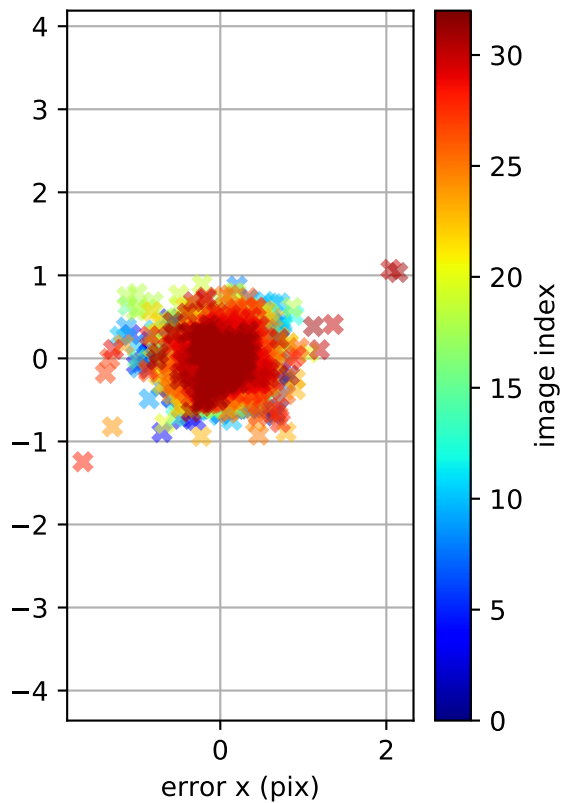
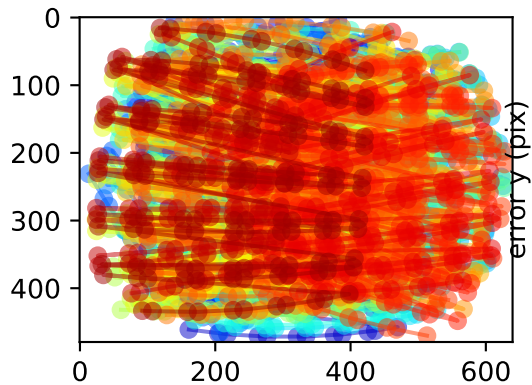
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

