

Calibration results

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Camera-system parameters:

cam0 (/camera/side_right/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.32772351 0.09163685 0.00086972 0.00033764] +- [0.00136766 0.00109874 0.00016749 0.00015351]

projection: [392.73524168 392.46761004 320.32319256 237.24499769] +- [0.72326853 0.7014296 0.54636257 0.60645929]

reprojection error: [0.000001, -0.000001] +- [0.267938, 0.243569]

Target configuration

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Type: aprilgrid

Tags:

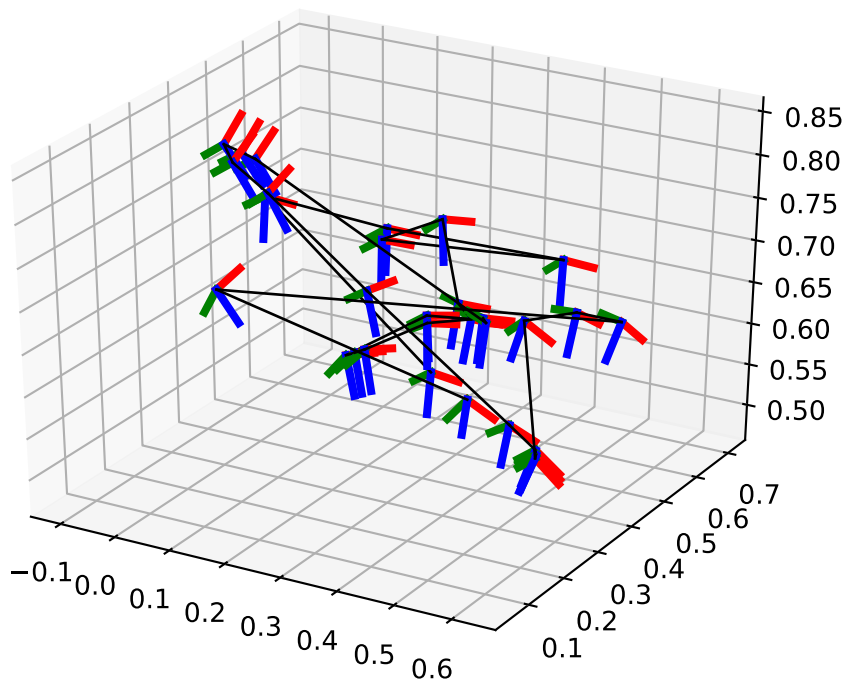
Rows: 6

Cols: 6

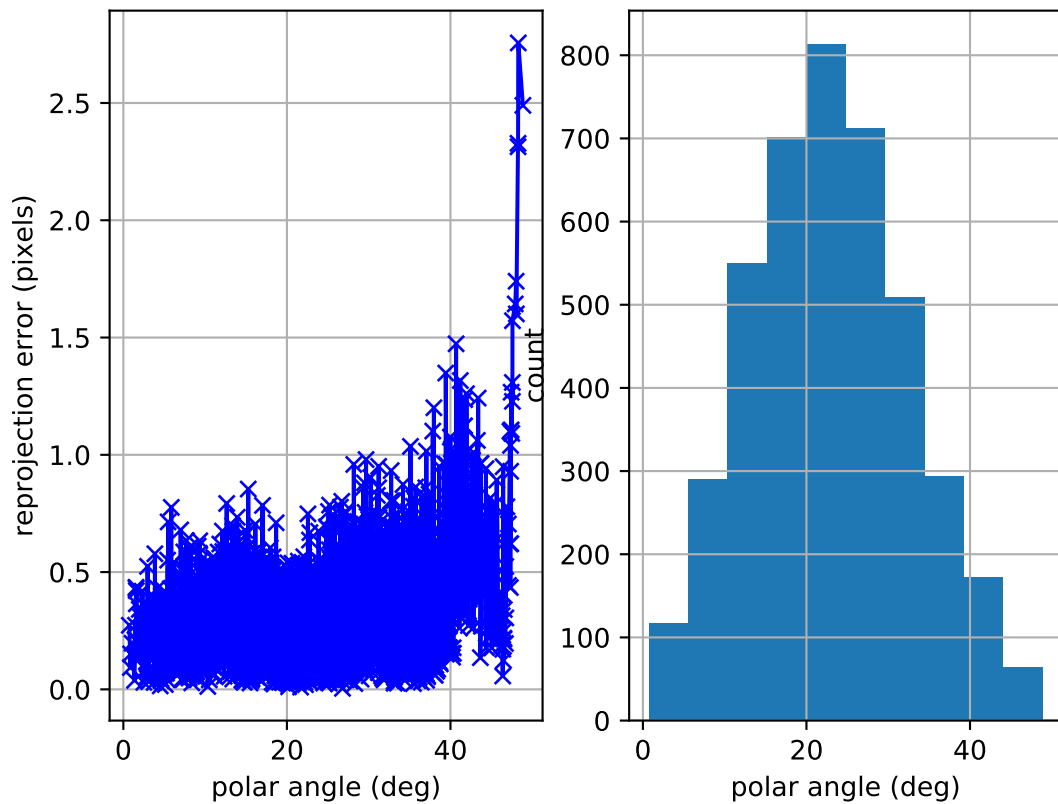
Size: 0.088 [m]

Spacing 0.02639999999999996 [m]

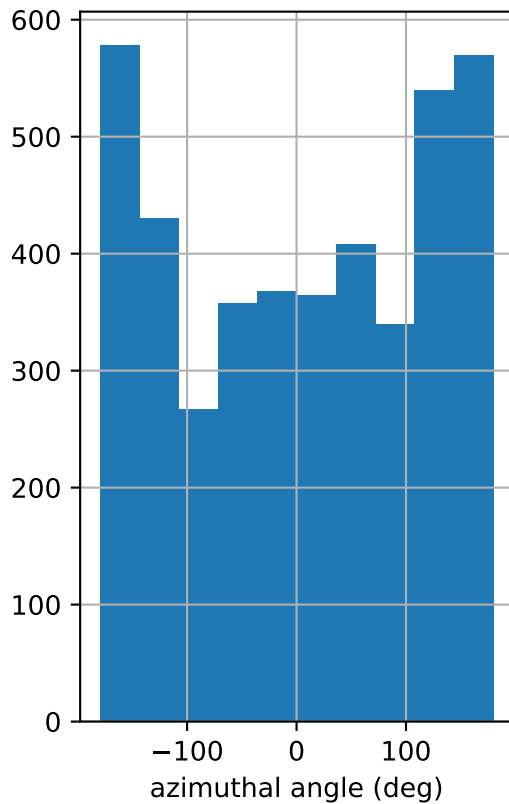
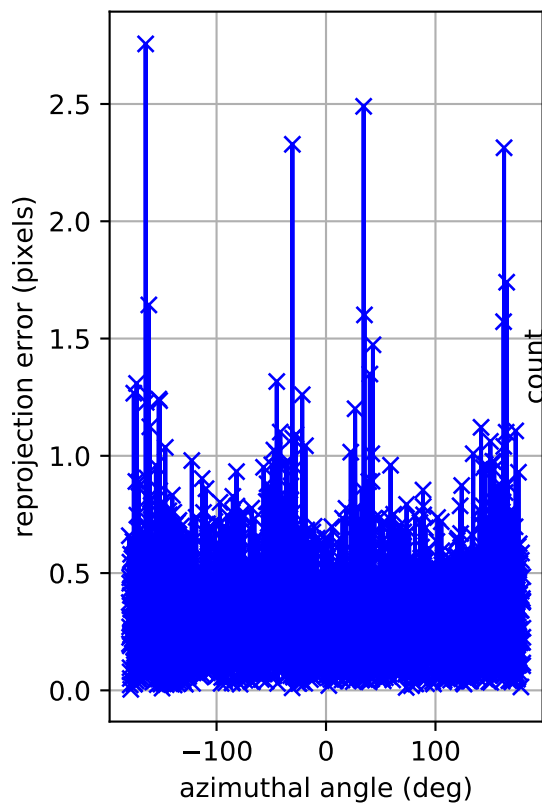
cam0: estimated poses



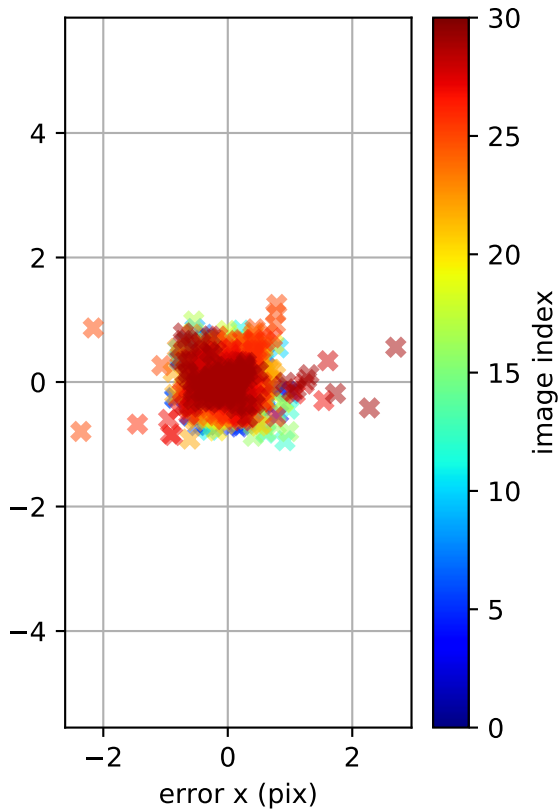
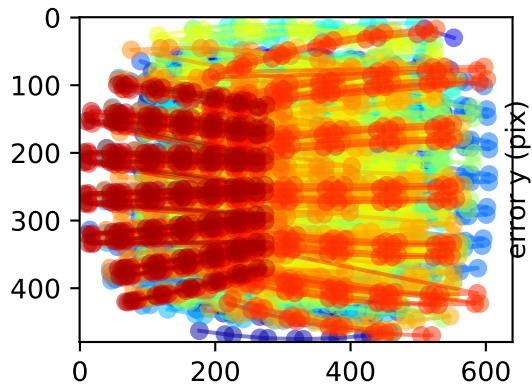
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

