

Calibration results

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Camera-system parameters:

cam0 (/camera/front_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.3244079 0.09291513 -0.00299133 -0.00222464] +- [0.00354389 0.00239282 0.00050218 0.00034684]

projection: [393.51984191 393.76503251 328.64803984 252.00143881] +- [3.00669275 3.04007757 1.19685747 1.78380755]

reprojection error: [0.000001, 0.000002] +- [0.218202, 0.180605]

Target configuration

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Type: aprilgrid

Tags:

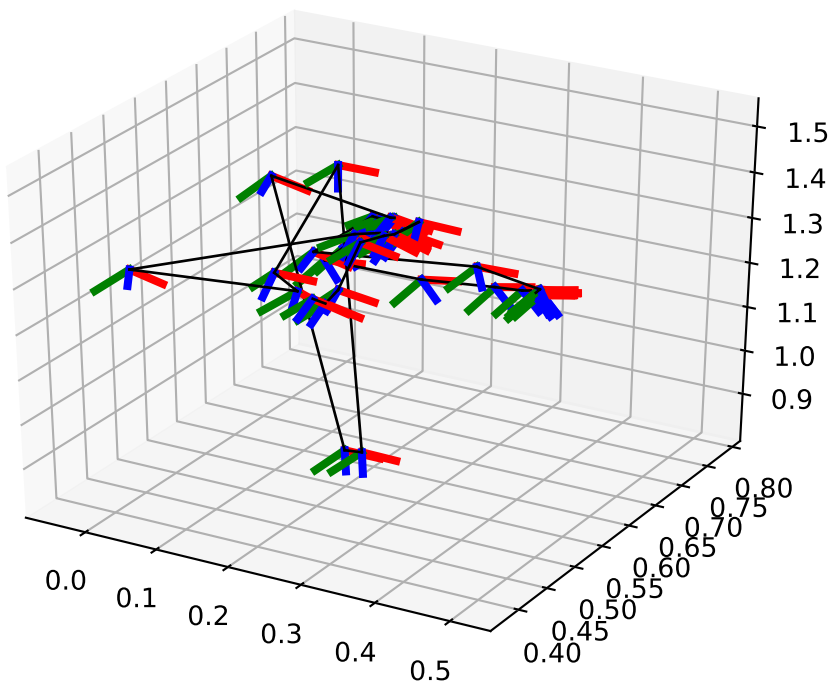
Rows: 6

Cols: 6

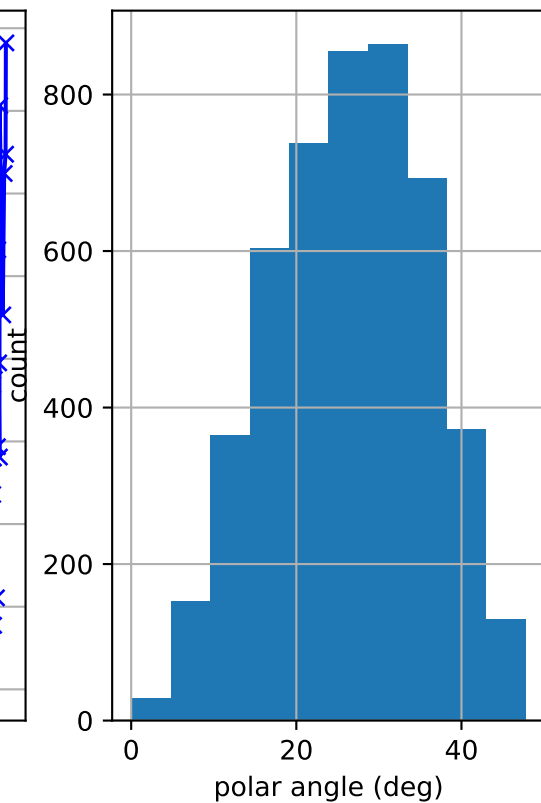
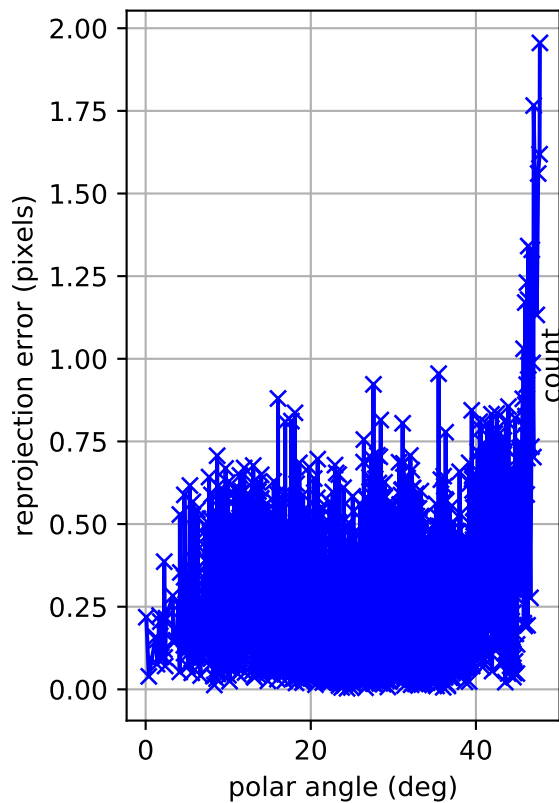
Size: 0.088 [m]

Spacing 0.026399999999999996 [m]

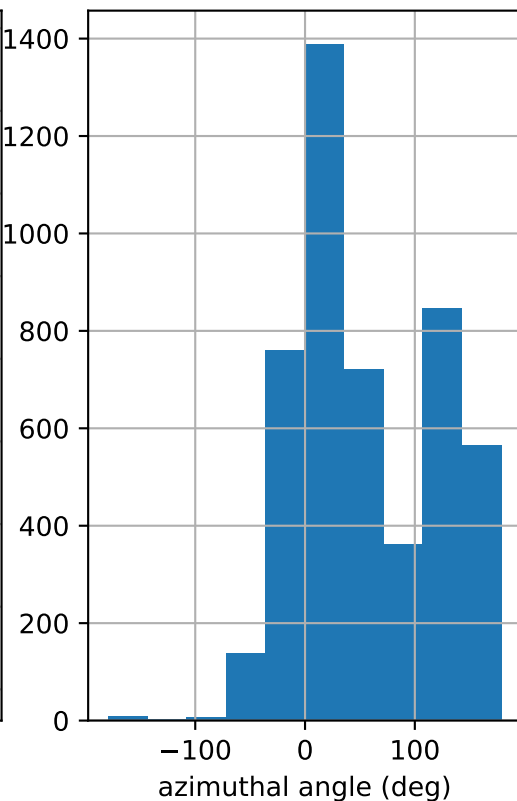
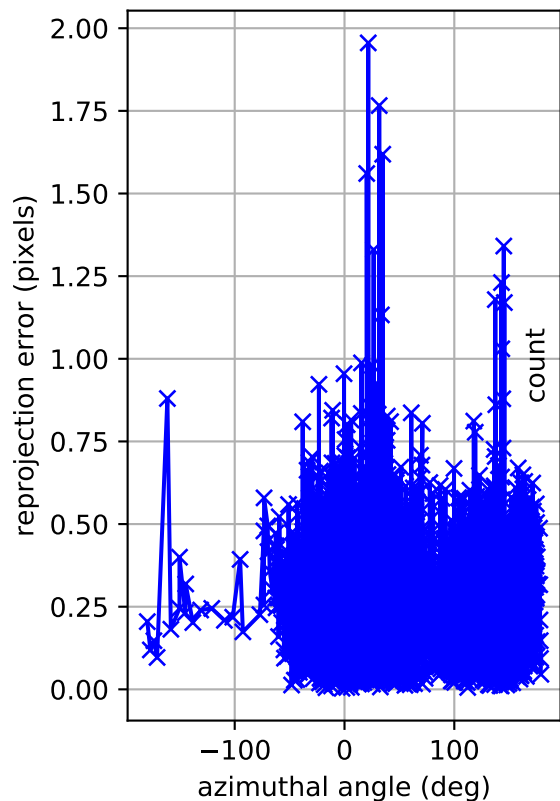
cam0: estimated poses



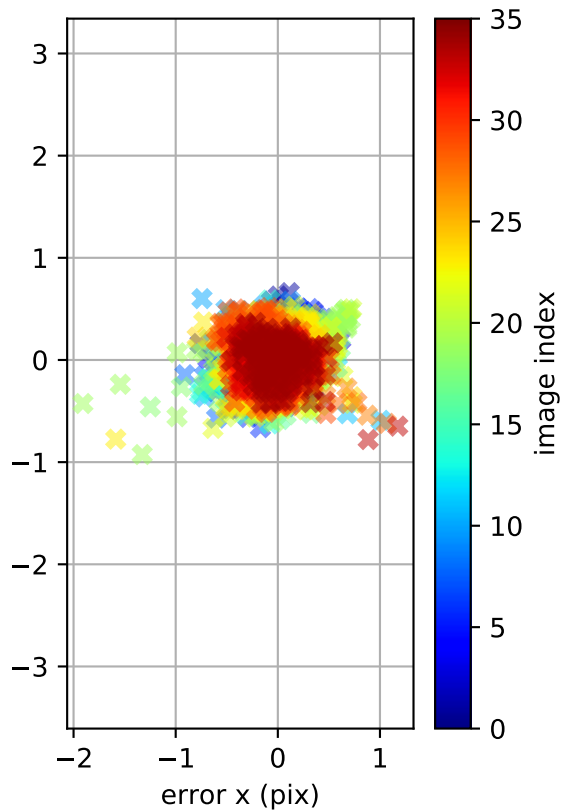
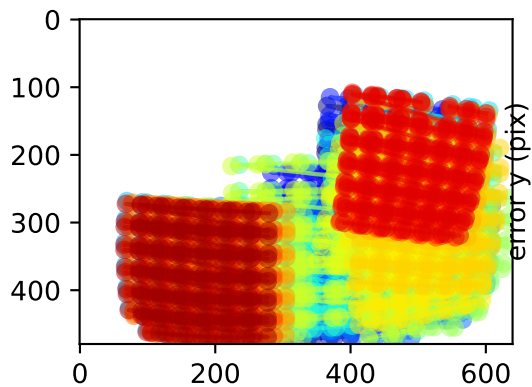
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

