

Calibration results

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Camera-system parameters:

cam0 (/camera/side_left/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [-0.33322061 0.09869279 0.00080725 0.00043153] +- [0.00144386 0.0011768 0.00019666 0.00011948]

projection: [393.08635473 393.16156735 320.05379598 236.50154501] +- [0.65660381 0.6650752 0.46754308 0.49134596]

reprojection error: [0.000000, 0.000001] +- [0.246374, 0.205532]

Target configuration

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Type: aprilgrid

Tags:

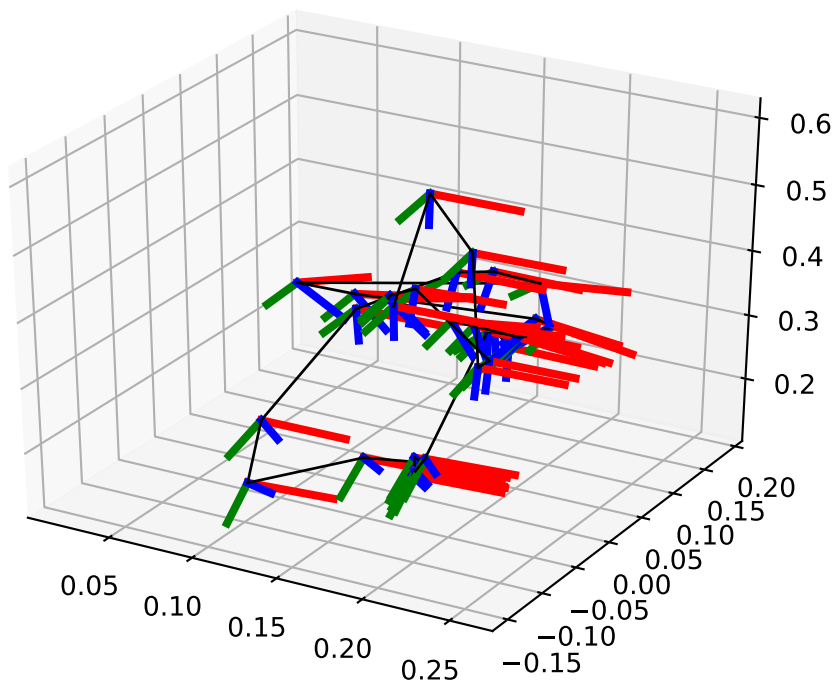
Rows: 6

Cols: 8

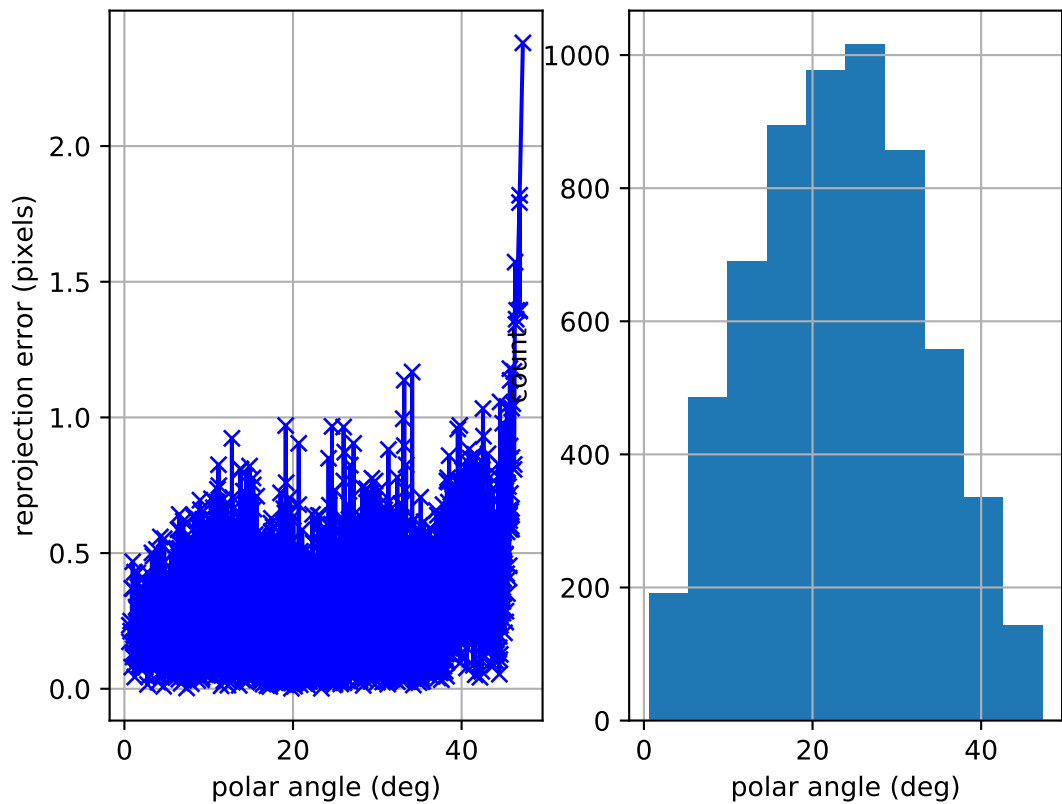
Size: 0.034 [m]

Spacing 0.0099994 [m]

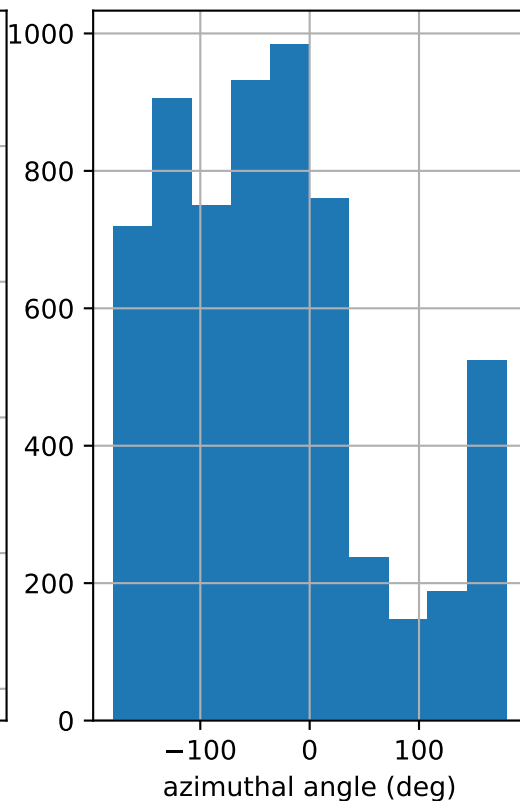
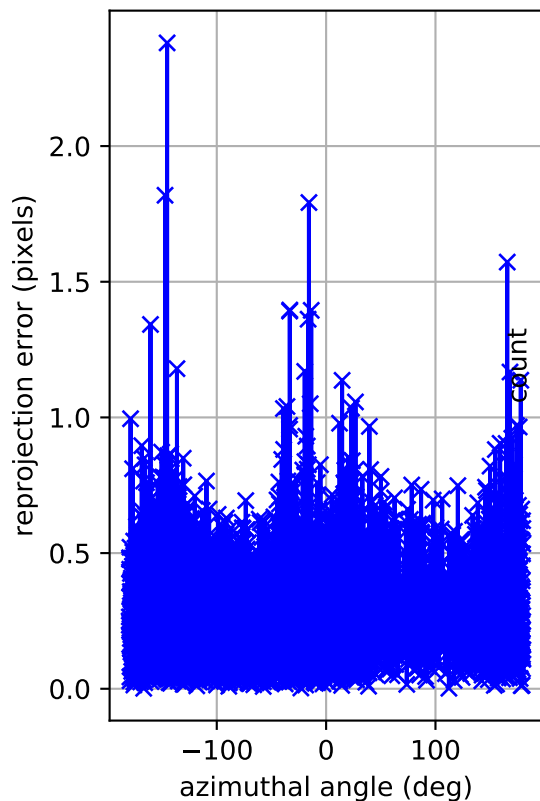
cam0: estimated poses



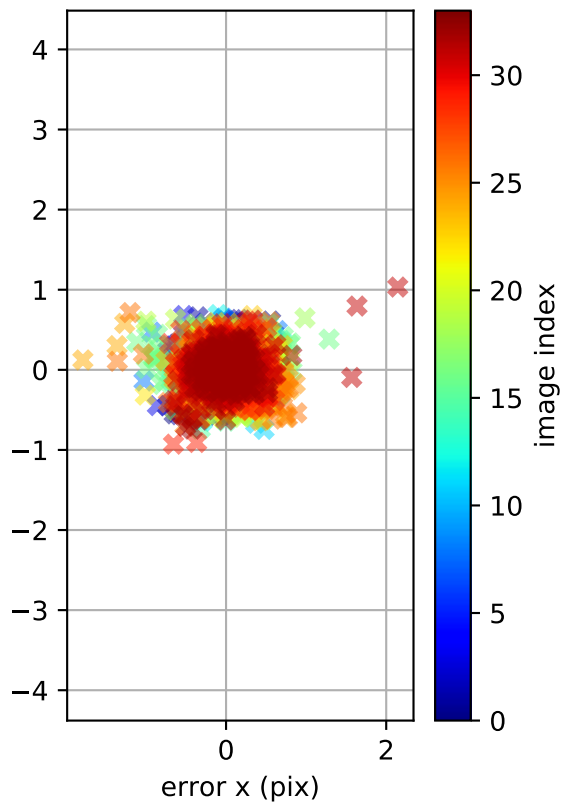
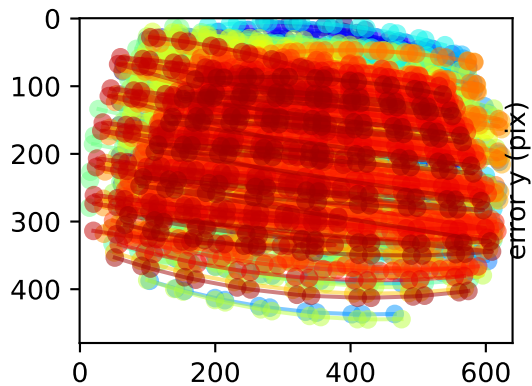
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

