

An Introduction to SoarML

Design

An abstraction that defines the constraints, form, and function of your software

Allows manipulation and analysis

Directs implementation (what and how)

Facilitates human communication and review

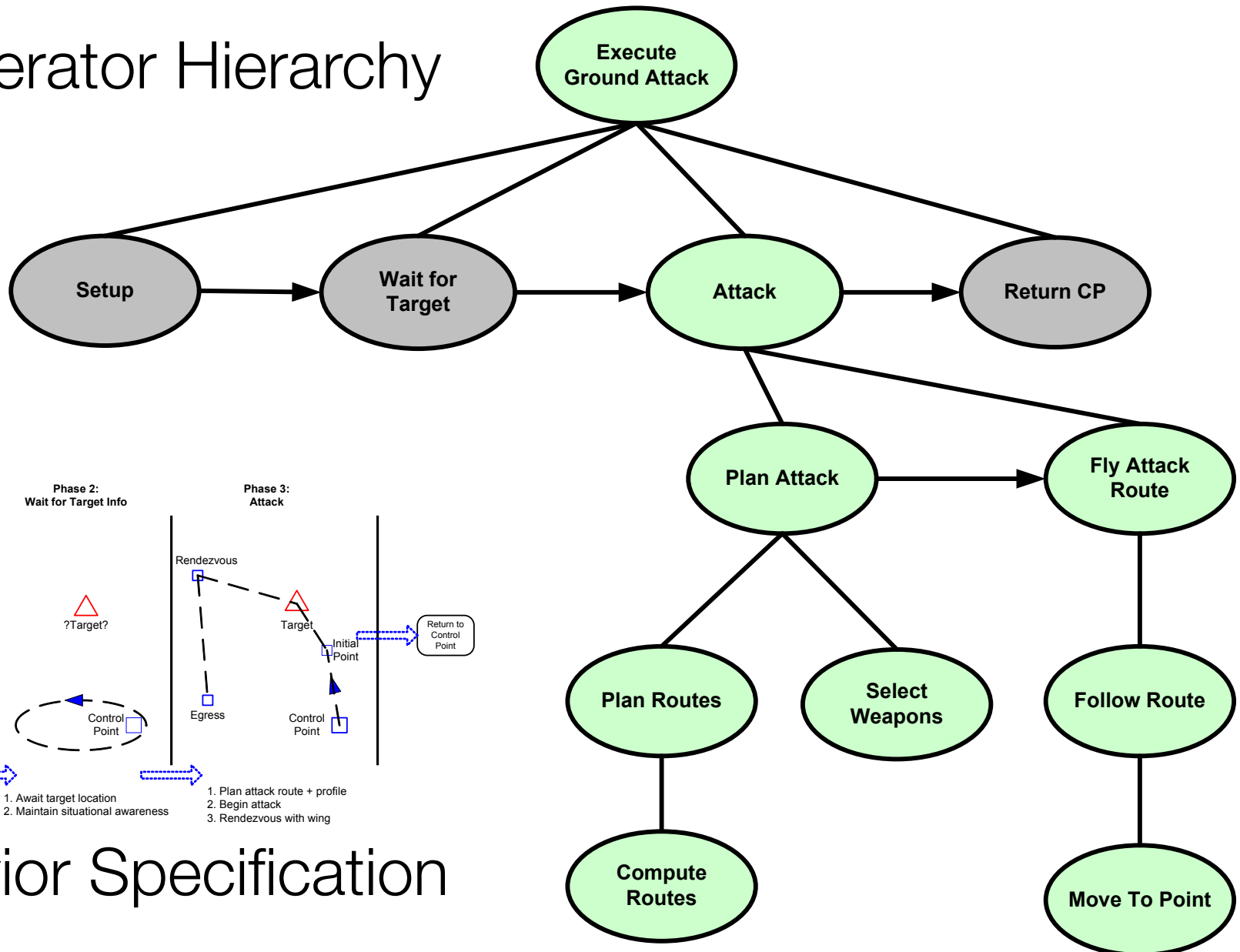
Suggests ways to share and reuse software

At Soartech you sometimes hear: “Listen to the architecture”

This means let the design of Soar guide your implementation

Design and Soar

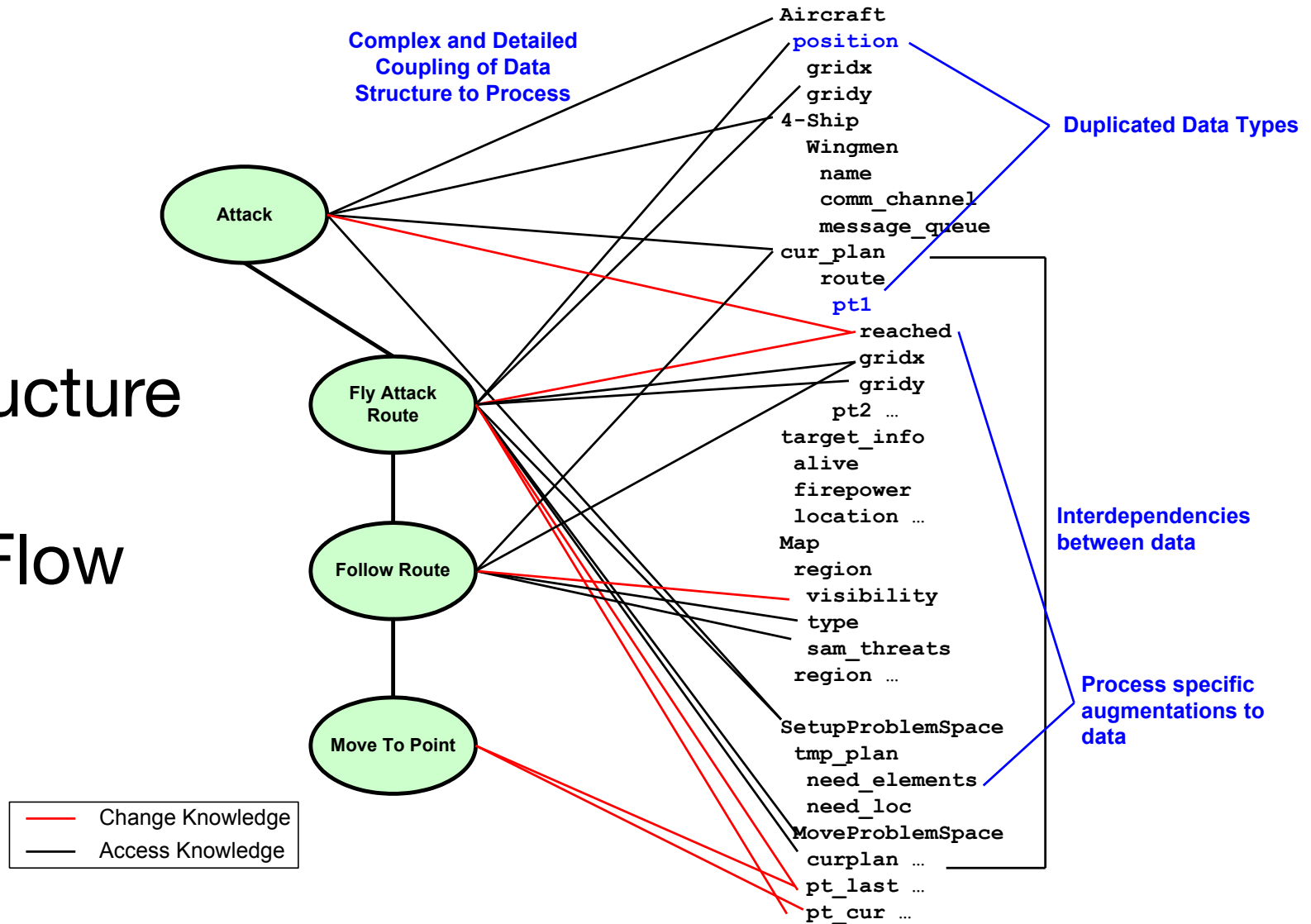
Operator Hierarchy



What is Missing?

Data Structure

Control Flow



HLSR work drove SoarML development

Elements of Soar Design

Working Memory Structure

(borrow from UML objects)

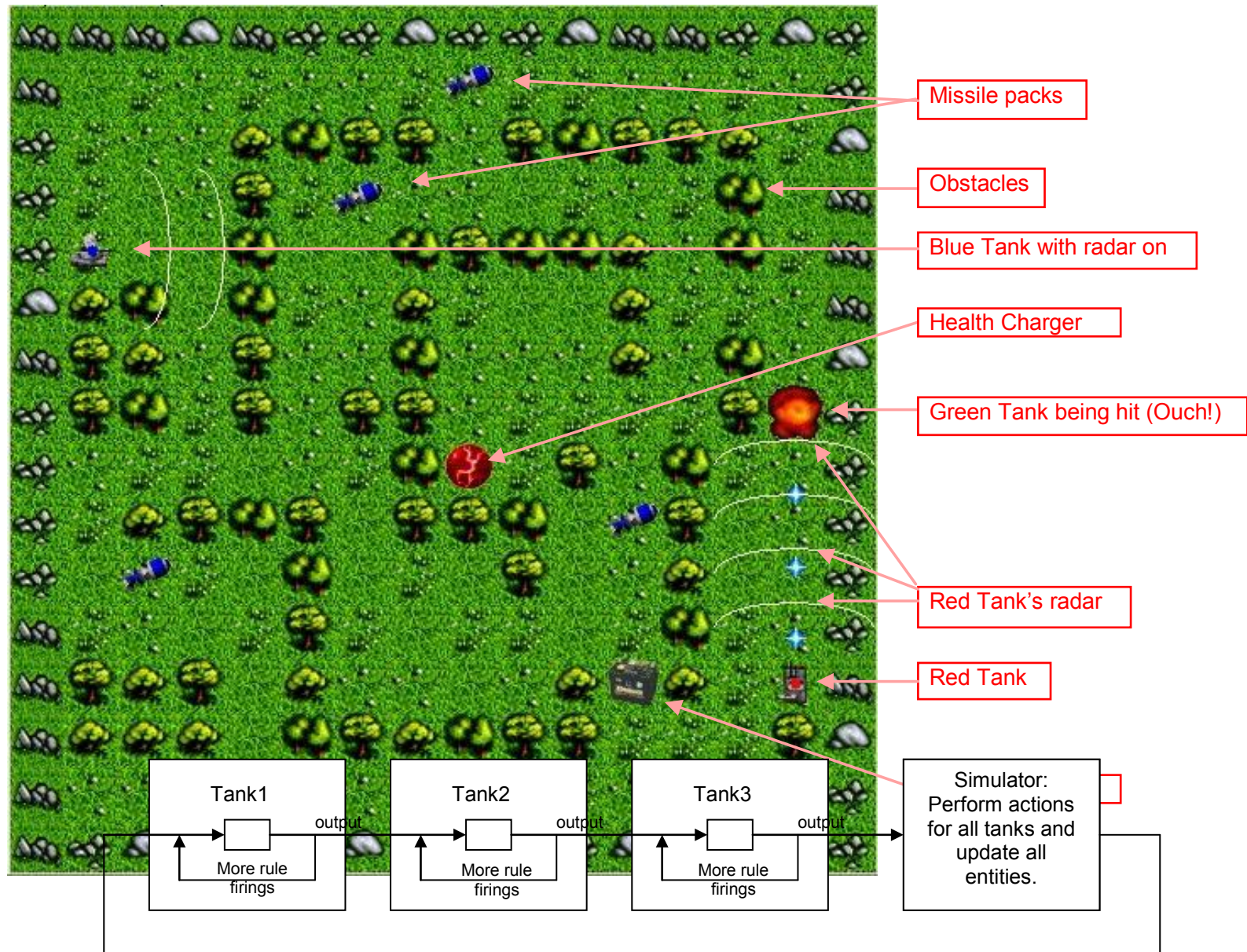
Goals

(borrow from agent design languages)

Processes

(blends goals and memory with operators)

Tank Environment



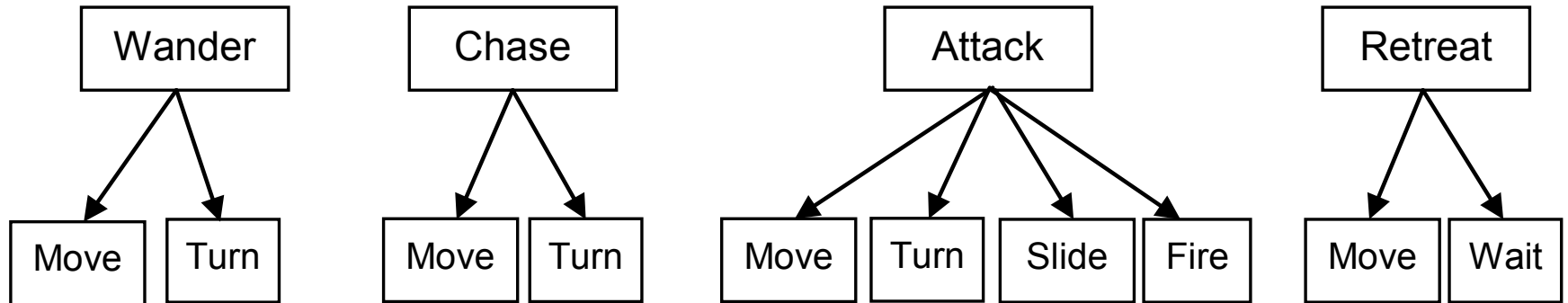
Overview of IO

```
^io
  ^input-link
    ^blocked
      ^backward yes/no
      ^forward yes/no
      ^left yes/no
      ^right yes/no
    ^incoming
      ^backward yes/no
      ^forward yes/no
      ^left yes/no
      ^right yes/no
    ^radar
      ^energy
        ^distance 0-13
        ^position left/center/right
      ^health
        ^distance 0-13
        ^position left/center/right
      ^missiles
        ^distance 0-13
        ^position left/center/right
      ^obstacle
        ^distance 0-13
        ^position left/center/right
      ^open
        ^distance 0-13
        ^position left/center/right
      ^tank
        ^distance 0-13
        ^position left/center/right
```

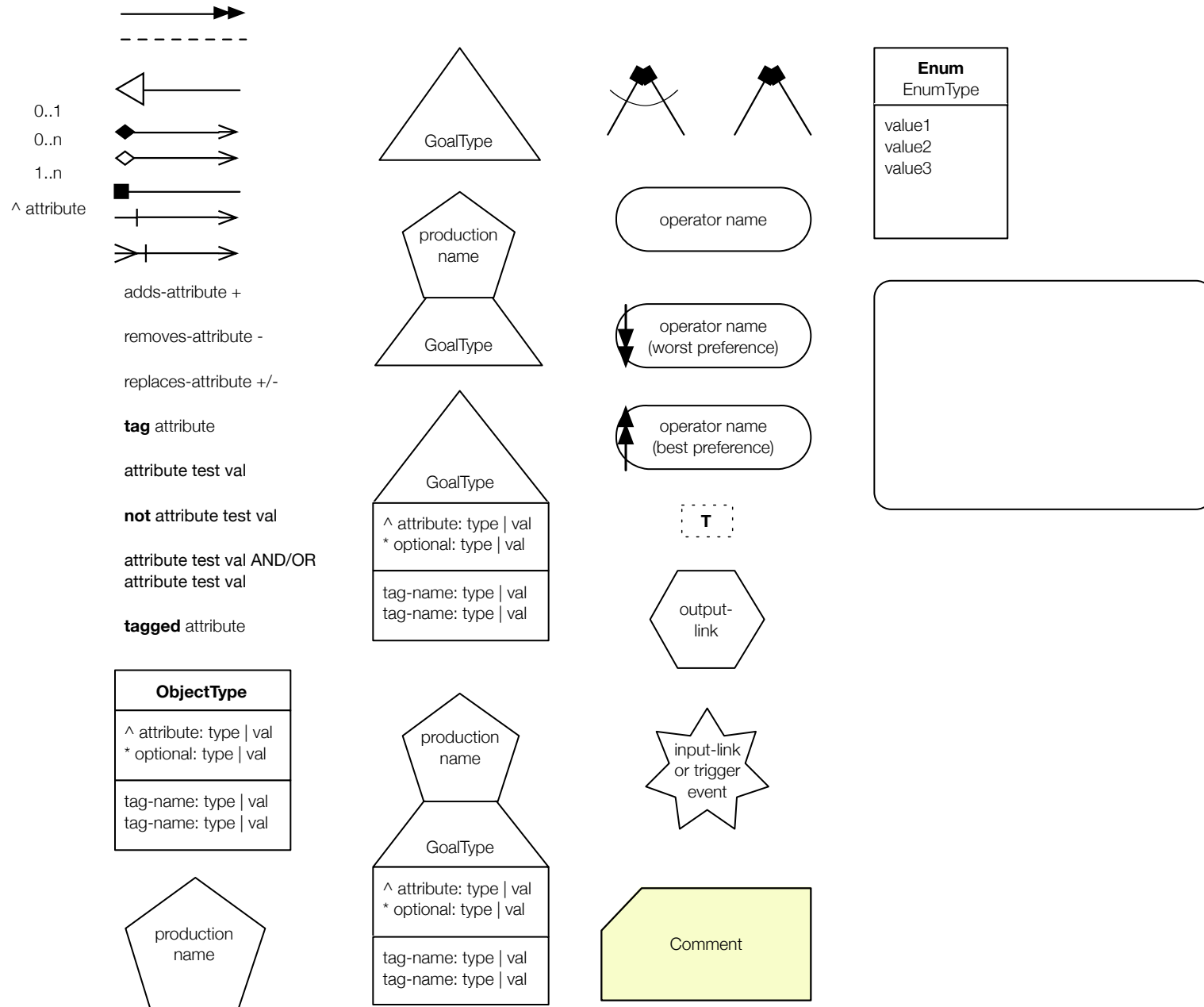
```
^io
  ^input-link
    ^rwaves
      ^backward yes/no
      ^forward yes/no
      ^left yes/no
      ^right yes/no
    ^smell
      ^color none/red/blue/purple/...
      ^distance none/0-28
    ^sound silent/left/right/
      forward/backward
    ^clock 1-N
    ^direction north/east/south/west
    ^energy 0-1000
    ^energyrecharger no/yes
    ^health 0-1000
    ^healthrecharger no/yes
    ^missiles 0-N
    ^my-color blue/red/purple/...
    ^radar-distance 1-14
    ^radar-setting 1-14
    ^radar-status on/off
    ^random 0.0-1.0
    ^resurrect no/yes
    ^shield-status on/off
    ^x 1-14
    ^y 1-14
  ^io
    ^output-link
      ^move.direction left/right/forward/backward/none
      ^rotate.direction left/right
      ^fire.weapon missile
      ^radar.switch on/off
      ^radar-power.setting 1-14
      ^shields.switch on/off
```

There are 41 productions in simple-bot

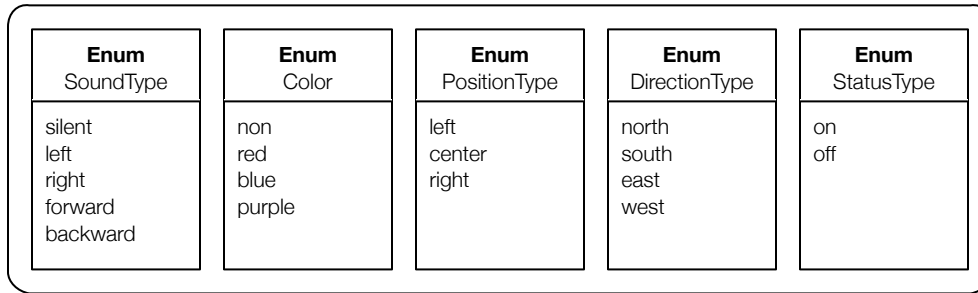
Design in Tutorial



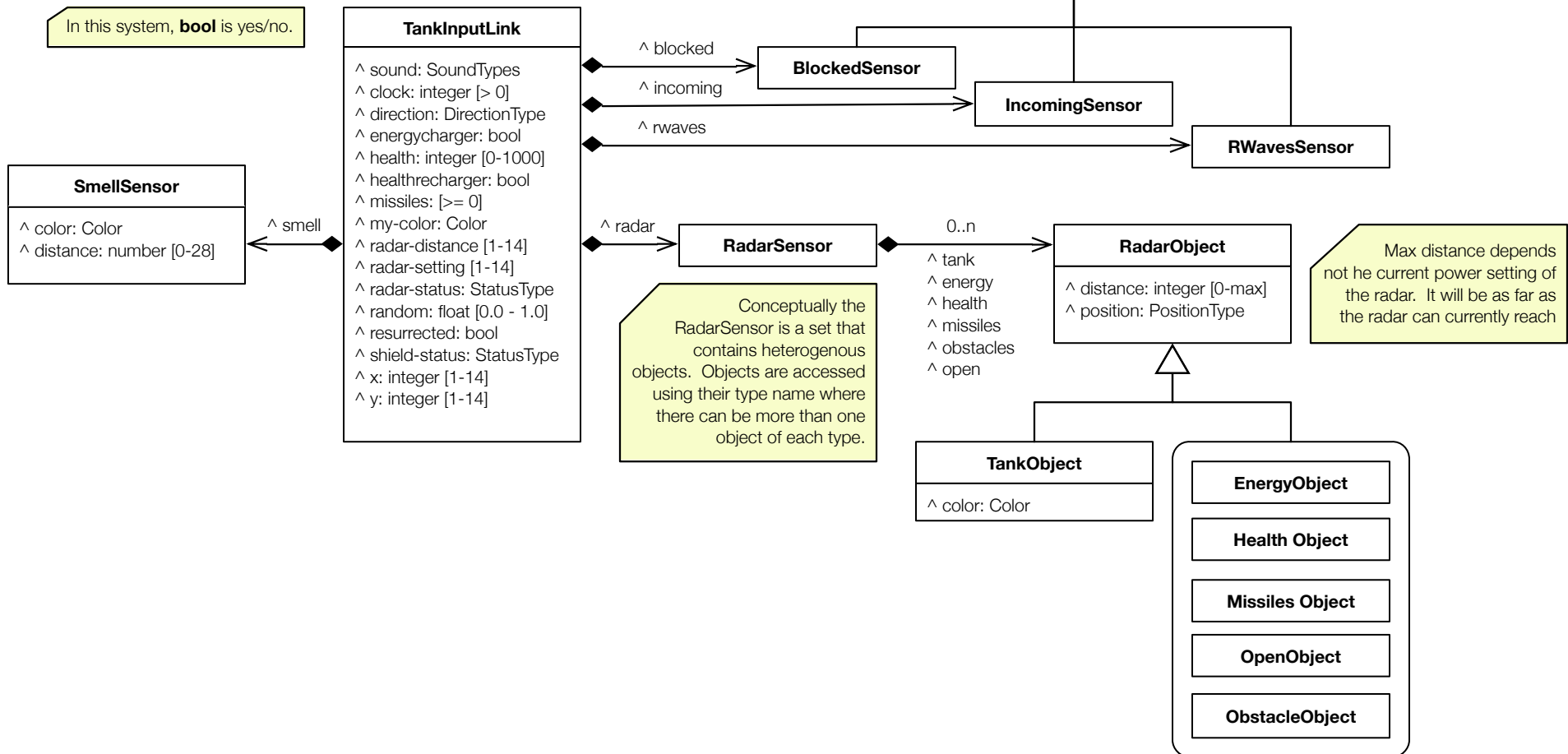
SoarML Symbols Template (Omnigraffle)



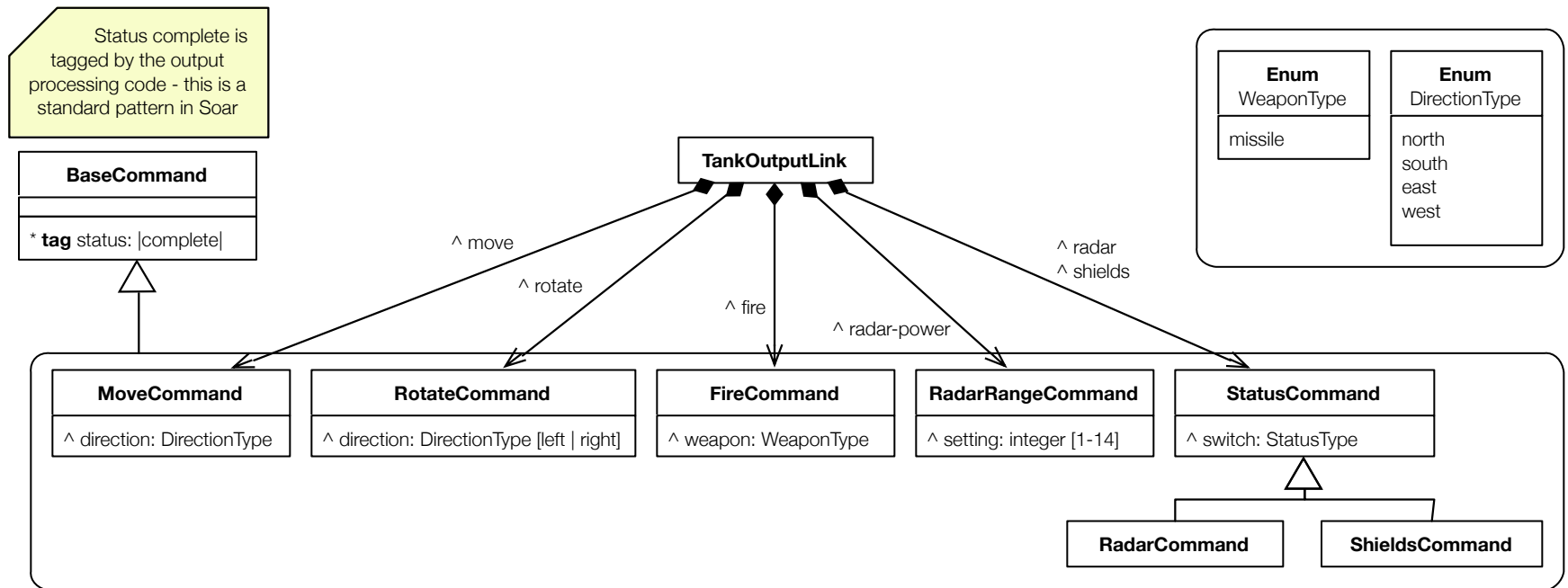
Input Link in SoarML



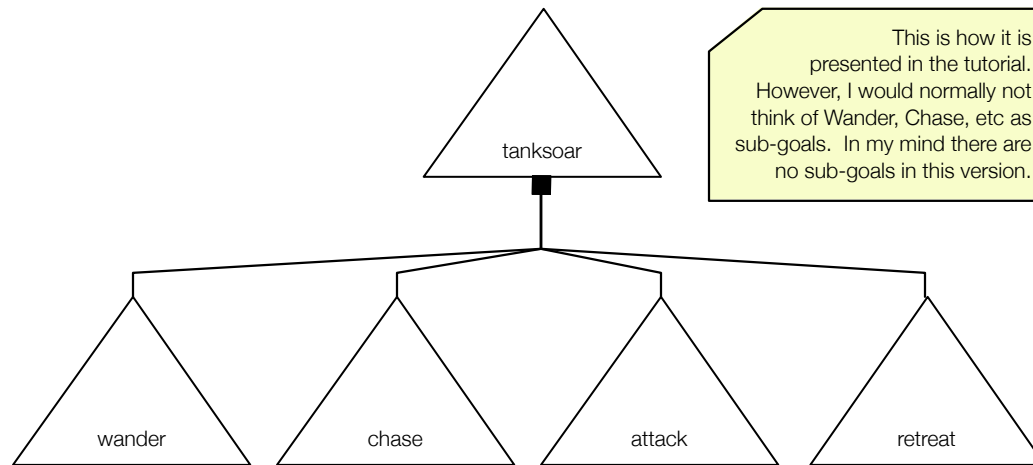
In this system, **bool** is yes/no.



Output Link in SoarML

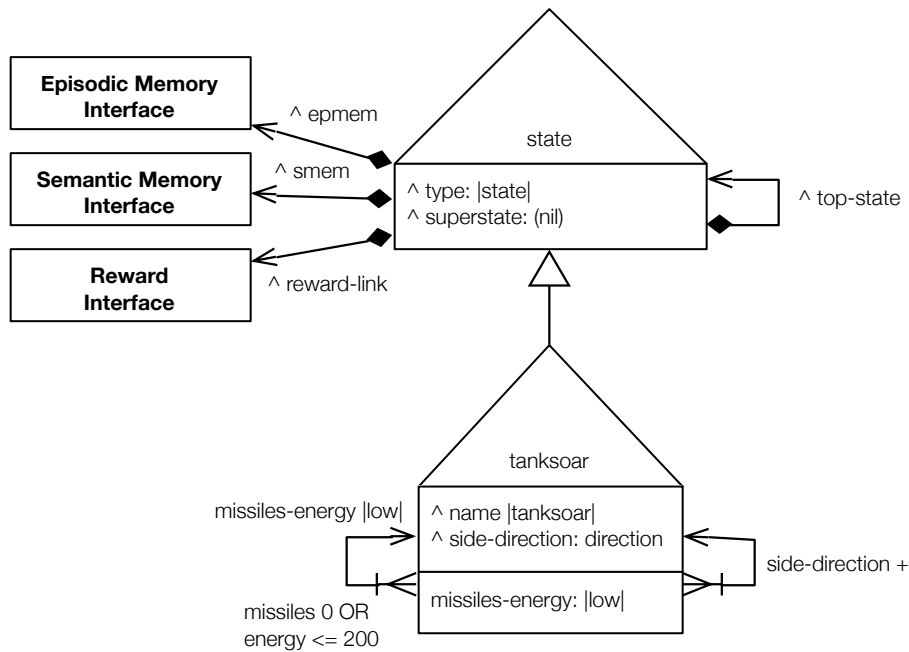


The Goal Hierarchy

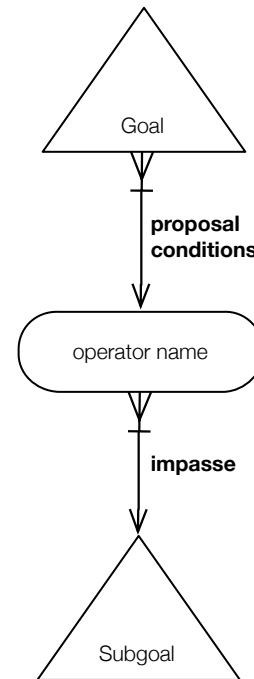


Goals: Conventions

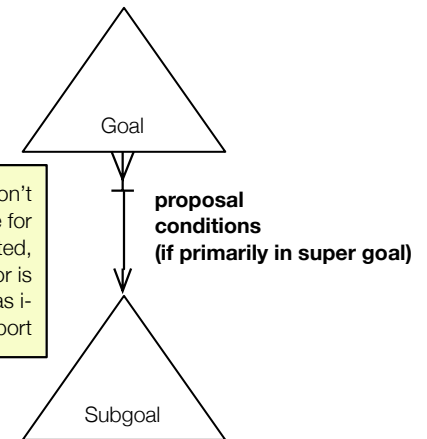
Basic Goal Structure



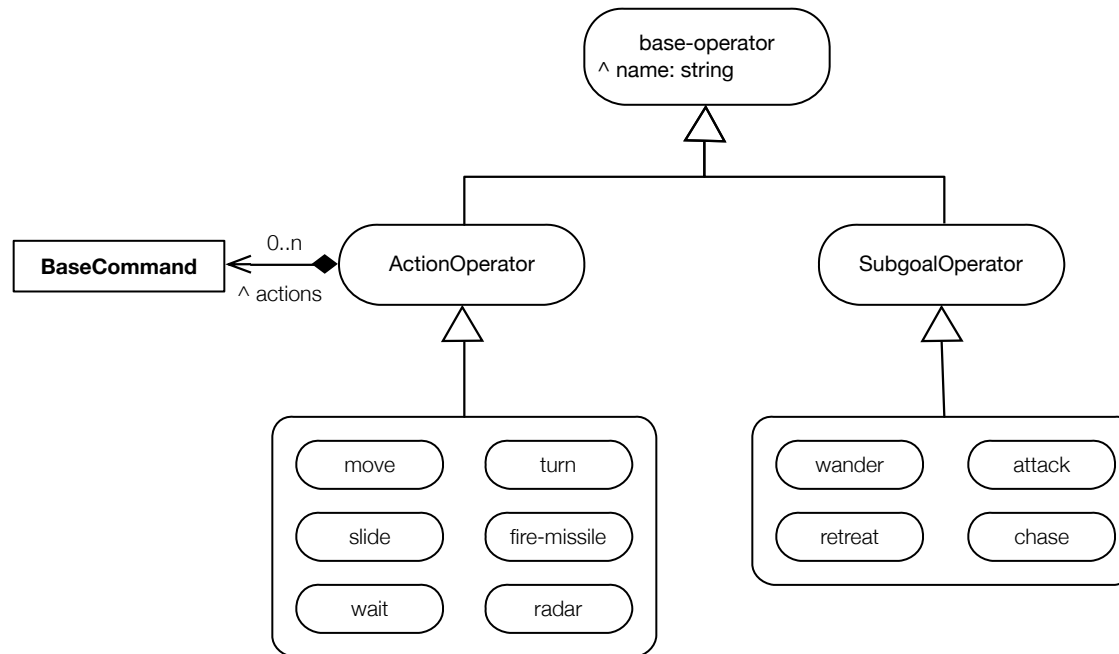
Impasse States as Goals (Michigan Goal System)



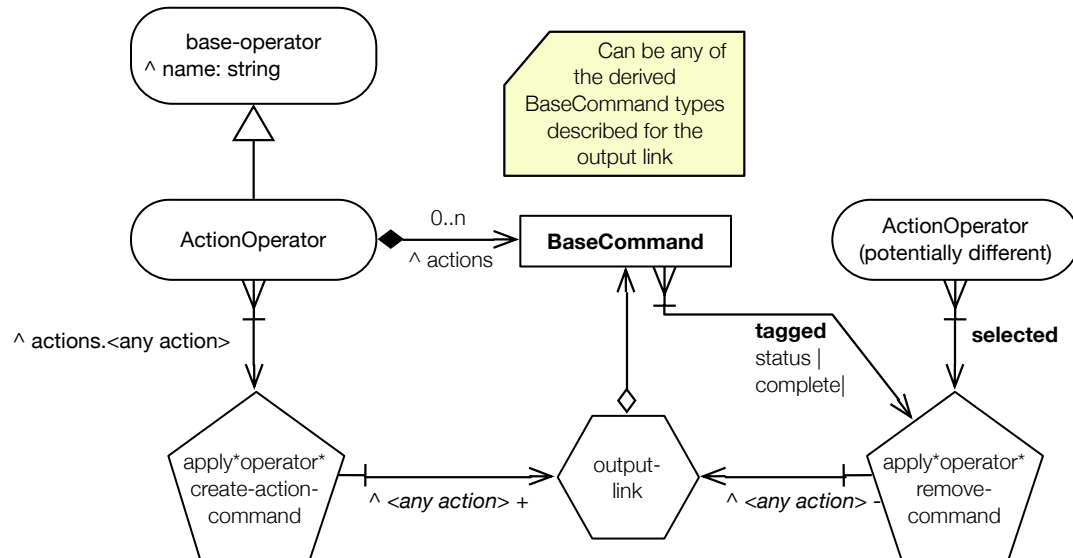
Shorthand



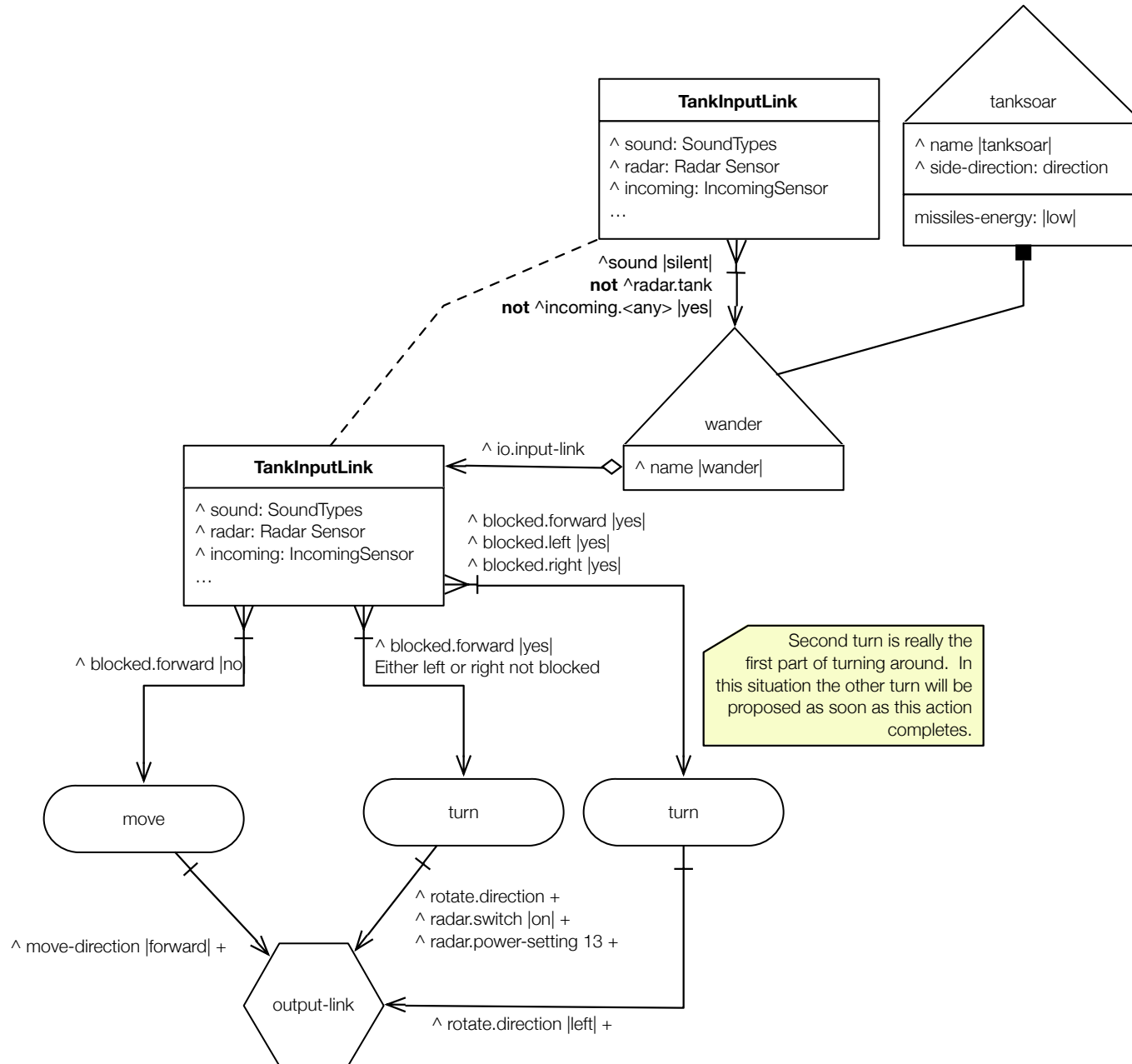
Operator Type Hierarchy



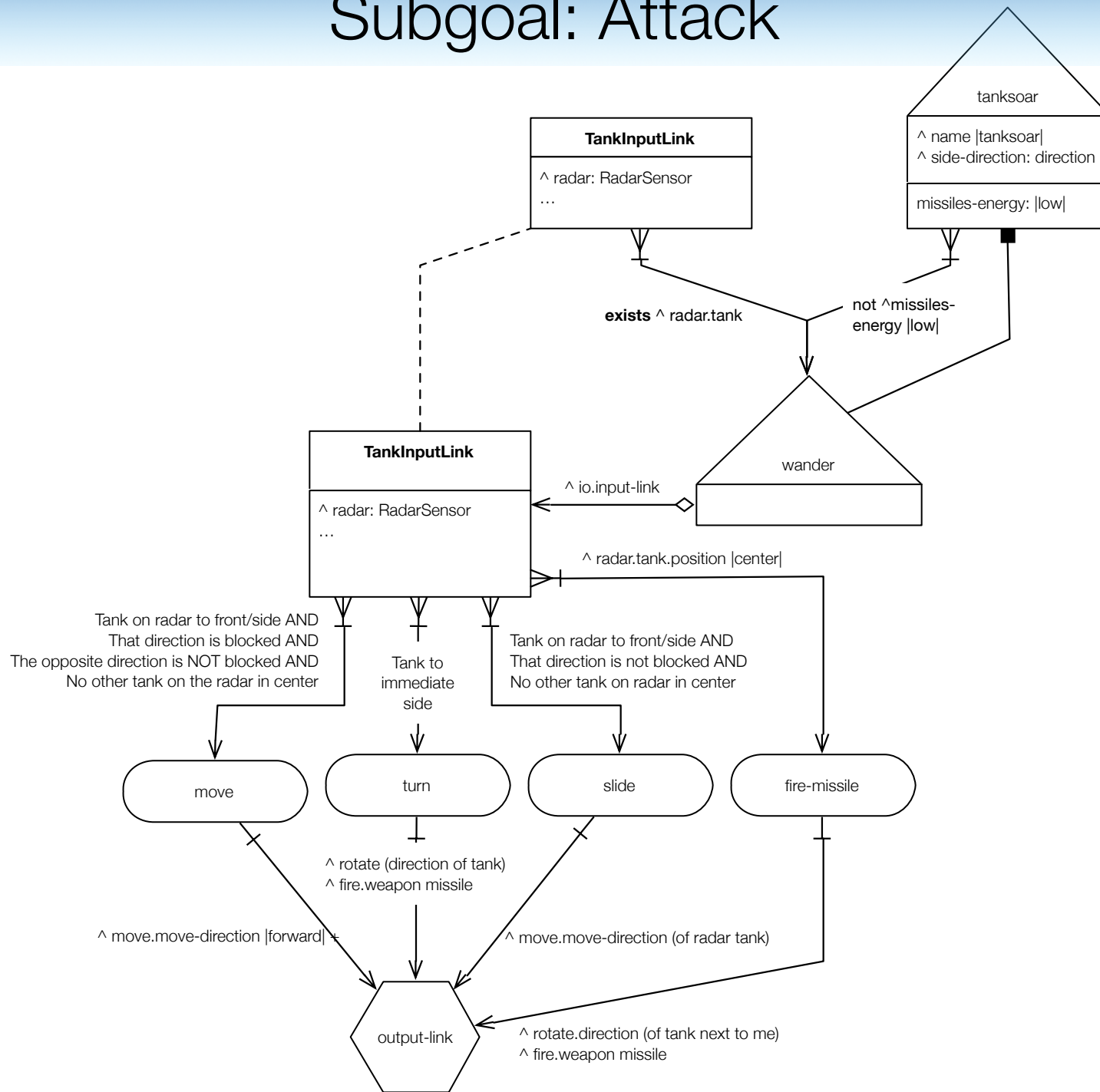
Aspect: External Action Handling



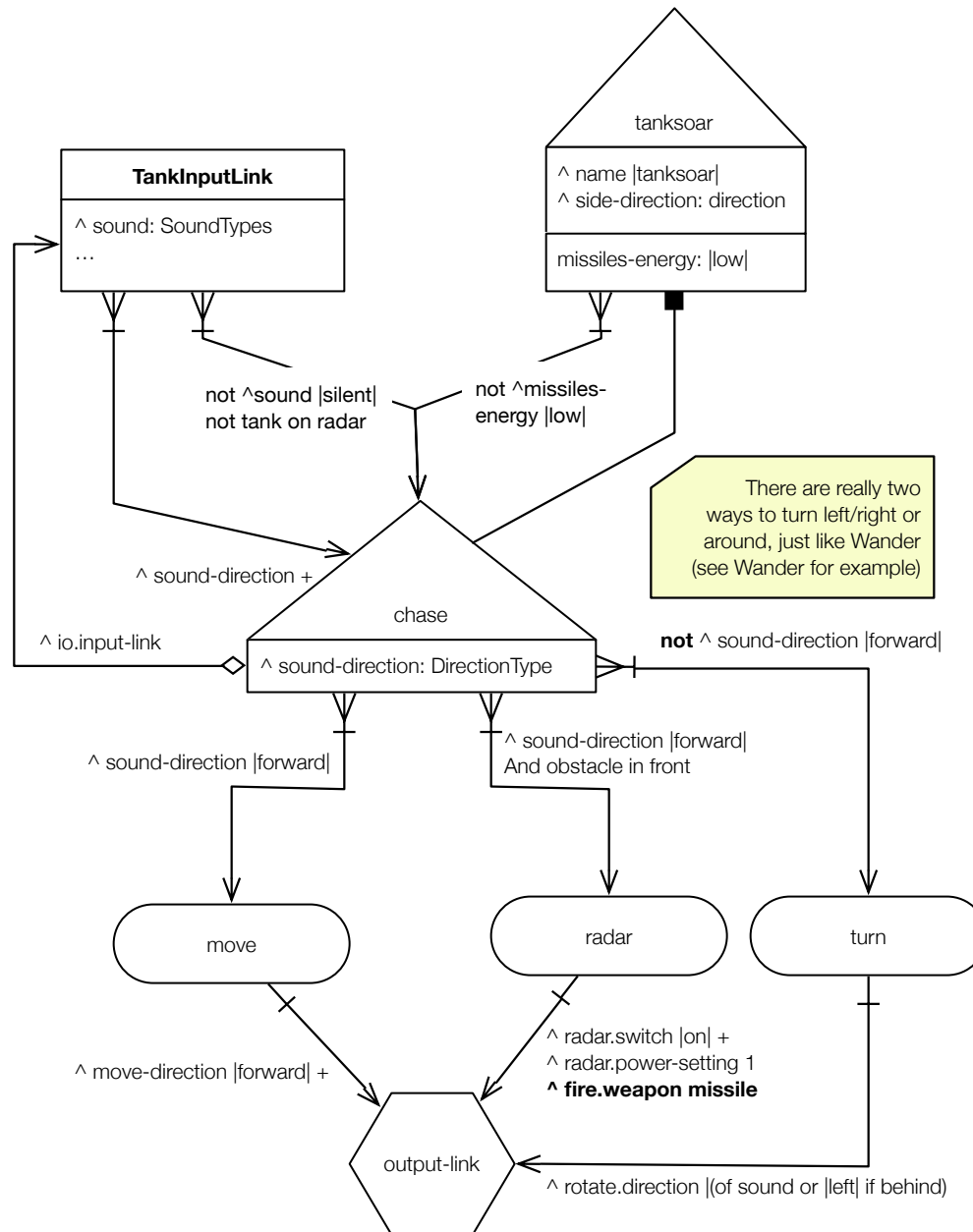
Subgoal: Wander



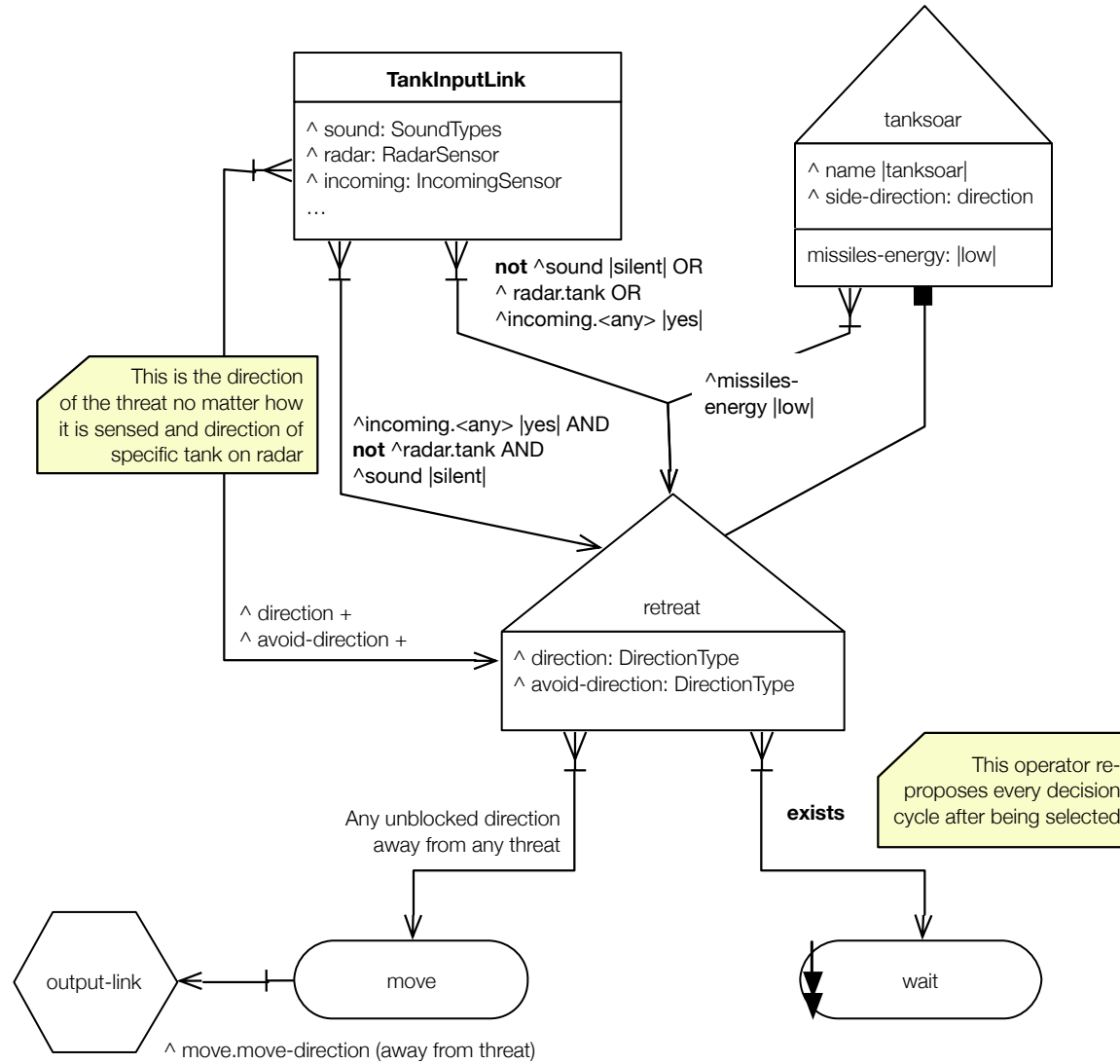
Subgoal: Attack



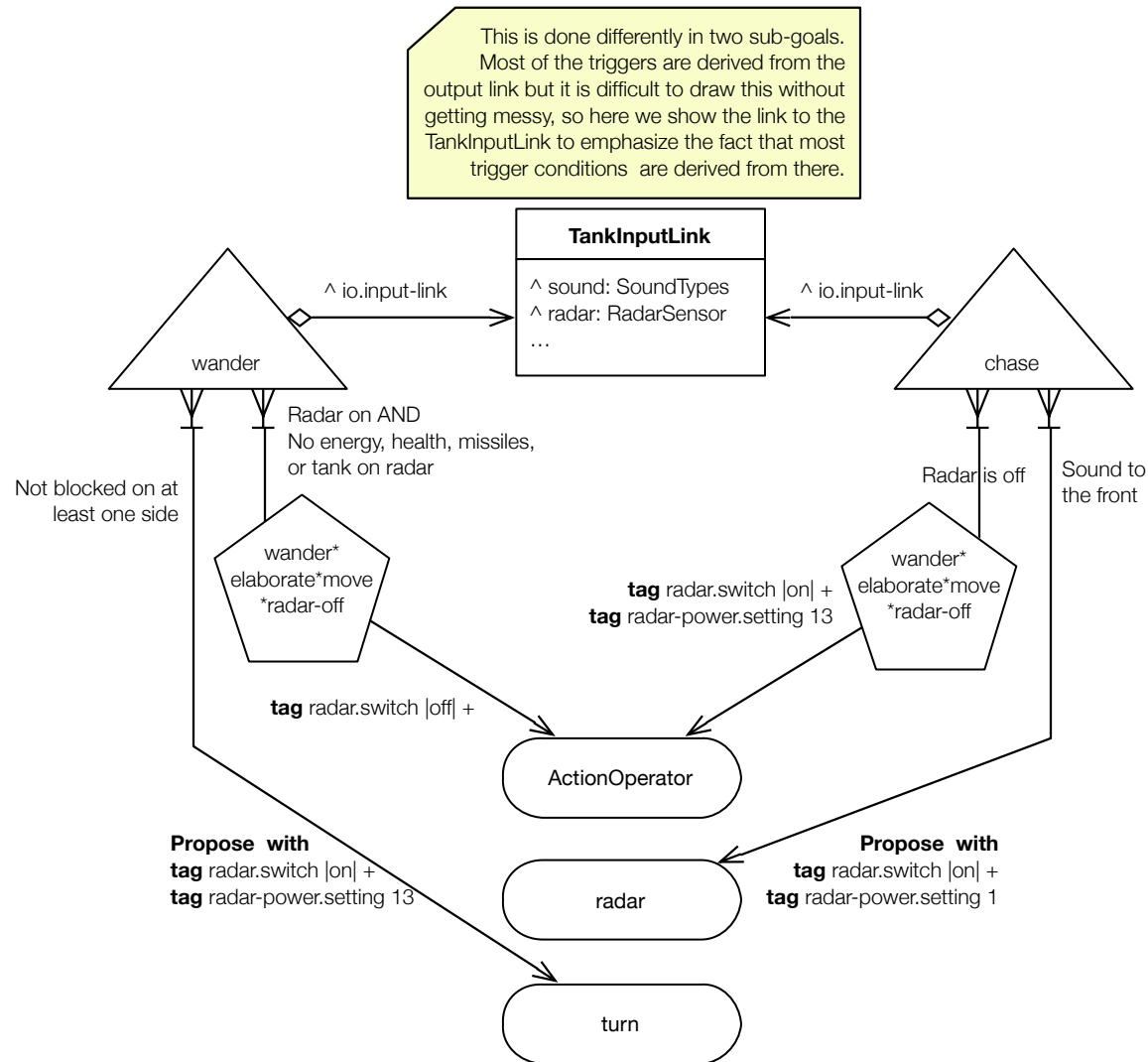
Subgoal: Chase



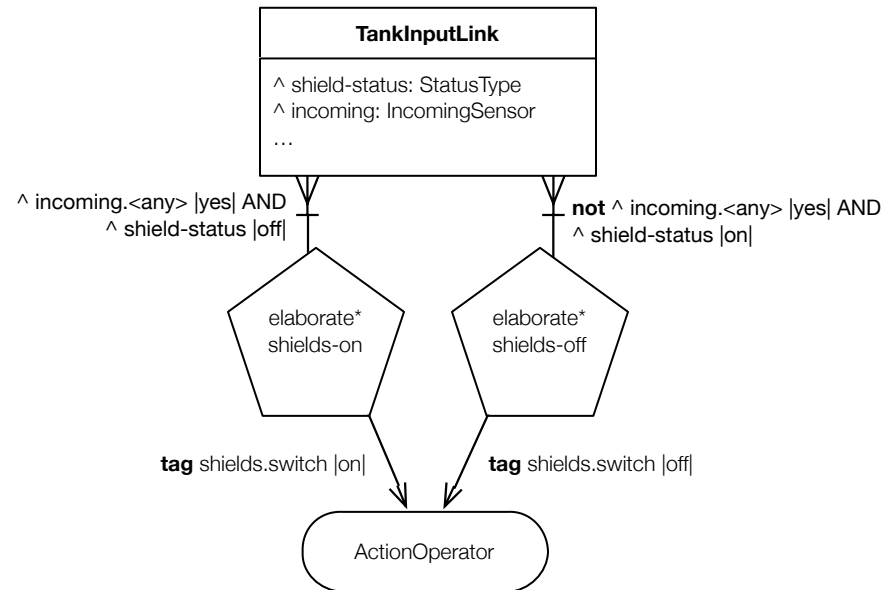
Subgoal: Retreat



Aspect: Radar Control



Aspect: Shield Control



Where to go from here

<https://confluence.soartech.com/display/soartechaie/Soar+ML>

Useful practice activities

- * Documenting existing code
- * Whiteboarding a Soar design
- * Reviewing design or code

Learning

- * Review with Me
- * Also: Glenn and Bob M.

Primitive Design Constructs

OO/Procedural

Objects

Procedures

Functional

Functions & Lists

Operations

Data

Control Flow

Advice

Aspects

Aspect

Operators

Goals

Soar

