```python
# import the opencv library
import cv2
import numpy as np

# define a video capture object
vid = cv2.VideoCapture(0)
params = cv2.SimpleBlobDetector_Params()

params.minThreshold = 100
params.maxThreshold = 255

# Filter by Area.
params.filterByArea = True
params.minArea = 500
params.maxArea = 250000

# Filter by Circularity
params.filterByCircularity = True
params.minCircularity = 0.4

# Filter by Convexity
params.filterByConvexity = True
params.minConvexity = 0.3

# Filter by Inertia
params.filterByInertia = True
params.minInertiaRatio = 0.01

ver = (cv2.__version__).split('.')
if int(ver[0]) < 3 :
  detector = cv2.SimpleBlobDetector(params)
else :
  detector = cv2.SimpleBlobDetector_create(params)

# define range of selected color in HSV
lower_limit = np.array([0,50,50])
upper_limit = np.array([20,255,255])

kernel = np.ones((5, 5), np.uint8)
while(True):

    # Capture the video frame
    # by frame
    _,im = vid.read()
    hsv = cv2.cvtColor(im, cv2.COLOR_BGR2HSV)

    # Threshold the HSV image to get only blue colors
    mask = cv2.inRange(hsv, lower_limit, upper_limit)
    mask = cv2.morphologyEx(mask, cv2.MORPH_CLOSE, kernel)

    # Bitwise-AND mask and original image
    res = cv2.bitwise_and(im,im, mask= mask)

    #cv2.imshow('frame',im)
    #cv2.imshow('mask',mask)
    cv2.imshow('res',res)


    #im3 = cv2.bitwise_not(im3)
    keypoints = detector.detect(cv2.bitwise_not(mask))

    #imcv = cv2.cvtColor(np.array(im),cv2.COLOR_RGB2BGR)
    im_with_keypoints = cv2.drawKeypoints(im, keypoints, np.array([]), (0,0,255), cv2.DRAW_MATCHES_FLAGS_DRAW_RICH_KEYPOINTS)

    #cv2.imshow("Mask", im3)
    cv2.imshow("Detection", im_with_keypoints)

    # the 'q' button is set as the
    # quitting button you may use any
    # desired button of your choice
    if cv2.waitKey(1) & 0xFF == ord('q'):
        break

# After the loop release the cap object
vid.release()
# Destroy all the windows
cv2.destroyAllWindows()
```