Exercise 1-4

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Exercise 1

You can't use 4 "bits" as each dot or dash doesn't represent a number like in binary, which is base 2. The value for a after the loop is 32.

```
#define ledPin
                      250 // ms
  #define unitTime
                      unitTime
  #define dotTime
  #define dashTime unitTime * 3
  #define letterTime unitTime * 3
  #define wordTime
                        unitTime * 7
  void dot() {
     digitalWrite(ledPin, HIGH);
     delay(dotTime);
     digitalWrite(ledPin, LOW);
11
  }
12
13
  void dash() {
14
     digitalWrite(ledPin, HIGH);
15
     delay(dashTime);
     digitalWrite(ledPin, LOW);
17
  }
18
19
  void S() {
20
     dot();
21
     delay(unitTime);
22
     dot();
23
     delay(unitTime);
24
     dot();
25
26
```

```
void 0() {
28
     dash();
29
     delay(unitTime);
     dash();
31
     delay(unitTime);
32
     dash();
33
   }
34
35
   void E() {
36
     dot();
37
     delay(unitTime);
38
   }
39
40
   void R() {
41
     dot();
42
     delay(unitTime);
43
     dash();
44
     delay(unitTime);
45
     dot();
46
   }
47
48
   void N() {
49
     dash();
50
     delay(unitTime);
51
     dot();
52
   }
53
54
   void outputLetter(char letter) {
55
     switch (letter) {
56
        case 'S': case 's':
57
          S();
58
          break;
        case '0': case 'o':
60
          0();
61
          break;
62
        case 'E': case 'e':
63
          E();
64
          break;
65
        case 'R': case 'r':
66
          R();
67
          break;
68
69
        case 'N': case 'n':
          N();
70
```

```
break;
71
       default:
72
          break;
     }
  }
75
76
   void outputWord(char *str) {
77
     for(; *str; str++) { // Just a while-loop in disguise
78
       outputLetter(*str);
       delay(letterTime);
     }
81
82
83
   void setup() {
84
     pinMode(ledPin, OUTPUT);
85
     char name[] = "Soeren";
87
88
     outputWord(name);
89
   }
90
   void loop() {
92
93
  }
94
```

Exercise 2

42%5 = 2.

Traffic Light

```
#define greenLED 8
#define yellowLED 9
#define redLED 10
#define delayTime 2000

void red() {
Serial.println("STOP!");
digitalWrite(redLED, HIGH);
digitalWrite(greenLED, LOW);
digitalWrite(yellowLED, LOW);
```

```
}
11
12
   void redyellow() {
13
     Serial.println("GET READY!");
14
     digitalWrite(redLED, HIGH);
15
     digitalWrite(greenLED, LOW);
16
     digitalWrite(yellowLED, HIGH);
17
18
19
   void green() {
20
     Serial.println("GO!");
21
     digitalWrite(redLED, LOW);
22
     digitalWrite(greenLED, HIGH);
23
     digitalWrite(yellowLED, LOW);
24
   }
26
   void yellow() {
27
     Serial.println("STOP-ISH!");
28
     digitalWrite(redLED, LOW);
29
     digitalWrite(greenLED, LOW);
30
     digitalWrite(yellowLED, HIGH);
31
   }
32
33
   void sequence() {
34
     red();
35
     delay(delayTime);
36
     redyellow();
37
     delay(delayTime);
38
     green();
39
     delay(delayTime);
40
     yellow();
41
     delay(delayTime);
42
   }
43
44
   void setup() {
45
     // put your setup code here, to run once:
46
     pinMode(greenLED, OUTPUT);
47
     pinMode(yellowLED, OUTPUT);
48
     pinMode(redLED, OUTPUT);
49
50
     Serial.begin(115200);
51
     red();
52
  }
53
```

```
void loop() {
   // put your main code here, to run repeatedly:
   sequence();
}
```

Counter

```
#define LEDO 8
  #define LED1 9
  #define LED2 10
  void updateCounter(uint8_t value) {
     Serial.print(value);
6
     Serial.print(", ");
     Serial.println((value >> 2) & 1);
     Serial.print((value >> 1) & 1);
     Serial.print(value & 1);
11
     digitalWrite(LEDO, value & 1);
     digitalWrite(LED1, (value >> 1) & 1);
     digitalWrite(LED2, (value >> 2) & 1);
14
  }
15
16
  uint8_t num;
17
  void setup() {
18
     // put your setup code here, to run once:
19
     pinMode(LEDO, OUTPUT);
20
     pinMode(LED1, OUTPUT);
21
     pinMode(LED2, OUTPUT);
22
23
     Serial.begin(9600);
24
     num = 0;
25
26
27
  void loop() {
28
     // put your main code here, to run repeatedly:
29
     updateCounter(num);
30
31
     num++;
32
     num = num \% 8;
34
```

```
35 delay(1000);
36 }
```

Exercise 3

INPUT is not using an internal pull-up resistor whereas INPUT_PULLUP is. ! is the NOT operator.

Push

Done without code, just connected LED to button through resistor.

Latching

Button press is checked in every loop() call, and a 200ms delay is added for debouncing if pressed.

```
const int ledPin = 9;
                               // Pin for the LED
  const int buttonPin = 7;
                               // Pin for the button
  int ledState = LOW;
                               // Current state of the LED
  int lastButtonState = LOW; // Tracks the last button
     state
6
  void setup() {
7
    pinMode(ledPin, OUTPUT);
                                       // Set LED pin as
       output
    pinMode(buttonPin, INPUT_PULLUP); // Set button pin as
        input with internal pull-up resistor
10
    Serial.begin(9600);
                                     // Initialize serial
       communication
  }
12
13
  void loop() {
14
    // Read the current button state
    int buttonState = digitalRead(buttonPin);
16
    // Check if the button was pressed (from LOW to HIGH
18
       transition)
    if (buttonState == HIGH && lastButtonState == LOW) {
```

```
ledState = !ledState;
                                      // Toggle the LED
20
       digitalWrite(ledPin, ledState); // Update the LED
21
      Serial.print("LED is now: ");
      Serial.println(ledState == HIGH ? "ON" : "OFF"); //
23
          Print LED state to Serial Monitor
       delay(200); // Debounce delay
24
    }
25
26
    lastButtonState = buttonState; // Update the last
27
        button state
28
```

Exercise 4

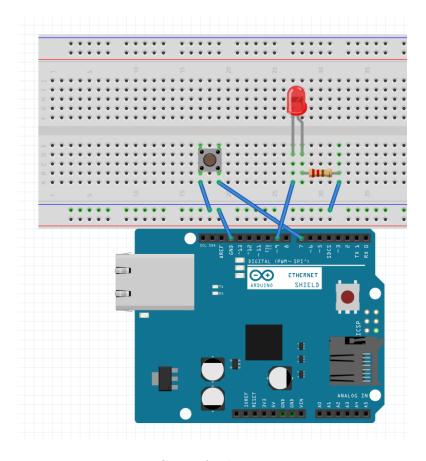


Figure 1: Ciruit for button program