

## HW4

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1,

AR(2)

$$V_t = \phi_0 + \phi_1 v_{t-1} + \phi_2 v_{t-2} + a_t$$

$$\mu_{vt} = \frac{\phi_0}{1 - \phi_1 - \phi_2}$$

1a, The mean of the time series is 0.167.

```
#r = 0 + 0.9 lag_r + at
phi_0 = 0.10
phi_1=0
phi_2=0.4
mean_r = phi_0/ (1-phi_1 - phi_2)
mean_r

## [1] 0.1666667
```

$$V_t = 0.1 + 0.42 v_{t-2} + a_t$$

$$1 - 0B - 0.4B^2 = 0$$

1b, Both absolute roots > 1 , hence the series is STATIONARY

```
# Compute the roots of the characteristic polynomial for v_t= 0.10 + 0.4_vt-2
+at
#
# Its characteristic polynomial is 1 - 0B - .4B^2
polyroot(c(1, 0, -.4)) # Note, two complex roots and they are complex
conjugates!

## [1] 1.581139+0i -1.581139+0i
```

1c,Computing a 1-step and 2-step ahead forecast of AR(2).

1-step = 0.108

2-step = 0.208

$$\hat{V}_t(1) = \phi_0 + \phi_1 v_t + \phi_2 v_{t-1}$$

$$\hat{V}_t(1) = 0.1 + 0_{vt} + 0.42_{vt-1}$$

$$\hat{V}_t(2) = 0.1 + \hat{V}_t(1)$$

```
####1step ahead
phi_0 = 0.10
phi_1=0
phi_2=0.4
vt= -0.01
vt_1= 0.02
one_step = phi_0 + phi_1*vt + phi_2*vt_1
one_step

## [1] 0.108

####1step ahead
two_step = phi_0 + one_step
two_step

## [1] 0.208
```

1d, lag-1 and lag-2 autocorrelations for an AR(2) process.

lag-1 auto correlation = 0

lag2- autp correlation = 0.4

$$\rho_1 = \frac{\phi_1}{1 - \phi_2}$$

$$\rho_2 = \frac{\phi_1^2 + \phi_2(1 - \phi_2)}{1 - \phi_2}$$

```
rho_1= phi_1/(1-phi_2)
rho_1

## [1] 0

rho_2 = phi_1^2+phi_2*(1-phi_2)/(1-phi_2)
rho_2

## [1] 0.4

#####
# Creating an AR(2) process
#####

# Create a series of 1000 white-noise with a sd = .1
set.seed(335)
a = rnorm(1000, 0, .14)
#plot(a, pch=16, cex=.2)
```

```
# Now, we start the array with a starting value, it is the  
# initial "seed" value of the series. Play with this value  
# to see how it affects the series. We also choose a constant  
# "theta" for the model
```

```
p = rep(0, 1000)  
p[1] = 0  
p[2] = 0  
theta_0 = 0.10  
theta_1 = 0  
theta_2 = 0.4
```

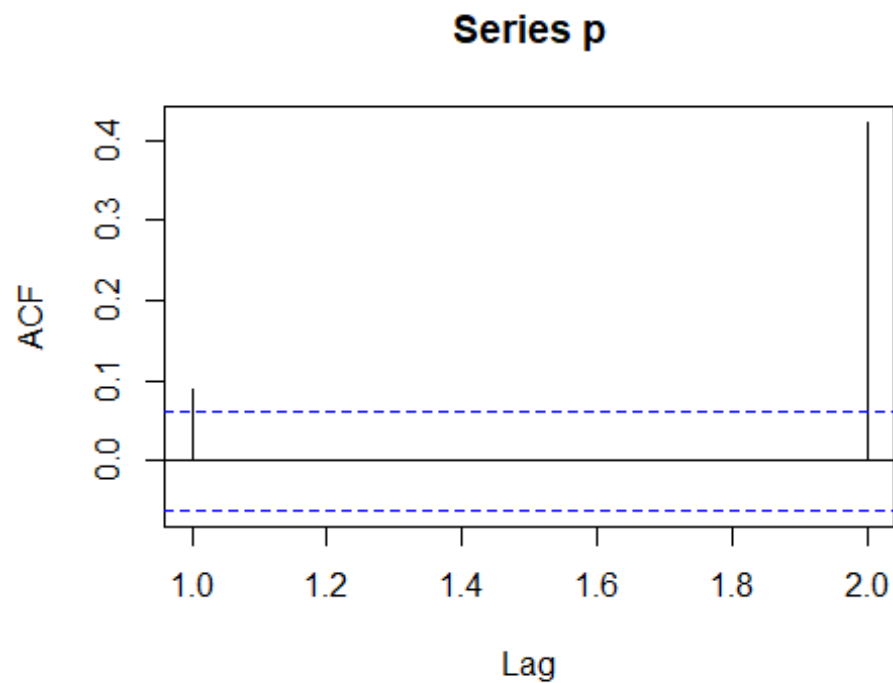
```
# Now, we loop through the elements of p one by one and  
# apply the formula for the AR(2) process.
```

```
#  
#           p_i = p_{i-1} + a_i  
#  
# Our random shocks are in the array "a"
```

```
for (i in 3:1000)  
{  
  p[i] = theta_0 + theta_1 * p[i-1] + theta_2 * p[i-2] + a[i]  
}  
p = ts(p)
```

**Both the mean and lag autocorrelation are equal to the theoretical calculation**

```
## [1] 0.1688576
```



```
##
## Autocorrelations of series 'p', by lag
##
##      1      2
## 0.090 0.422
```

## 2 MA(2) PROCESSES

$$V_t = \theta_0 + a_t + \theta_1 a_{t-1} + \theta_2 a_{t-2}$$

$$\mu_{vt} = \theta_0$$

$$\sigma_v^2 = \sigma_a^2(1 + \theta_1^2 + \theta_2^2)$$

2a,

$$V_t = 5 + a_t - 0.5a_{t-1} + 0.25a_{t-2}$$

The mean of series 9 is 5

The variance of the series is 0.0328

```
b=0.5
var_x= 0.025*(1+b^2+0.25^2)
var_x
## [1] 0.0328125
```

### 2c, Forecast 1,2,3 steps of MA(2) model.

$$\hat{V}_t(1) = 5 - 0.5a_t - 0.25a_{t-1}$$

$$\hat{V}_t(K) = \mu - \text{-----} \text{for } K > 1$$

For multiple step ahead for  $k > 1$  = mean

```
one_step_ma = 5 - 0.5*-0.01 - 0.25*0.02
one_step_ma
```

for MA(2) a non-zero autocorrelation on occurs at lag\_1

$$\rho_1 = \frac{\phi_1 + \phi_1 * \phi_2}{1 + \phi_1^2 + \phi_2^2}$$

$$\rho_k = 0 \text{ --- for } -k > 2$$

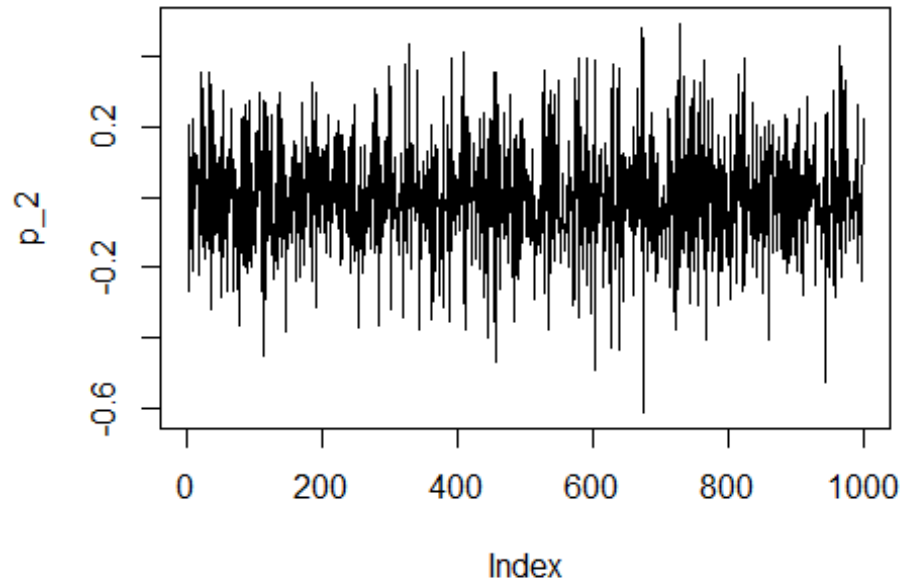
```
ma_rho_1 = -0.5+(-.5*0.25)/(1+(-0.5^2)+0.25^2)
ma_rho_1
```

Since for the simulated result the initial value is zero, this makes the mean different from the theoretical calculation where the initial value is 5 and mean is 5.

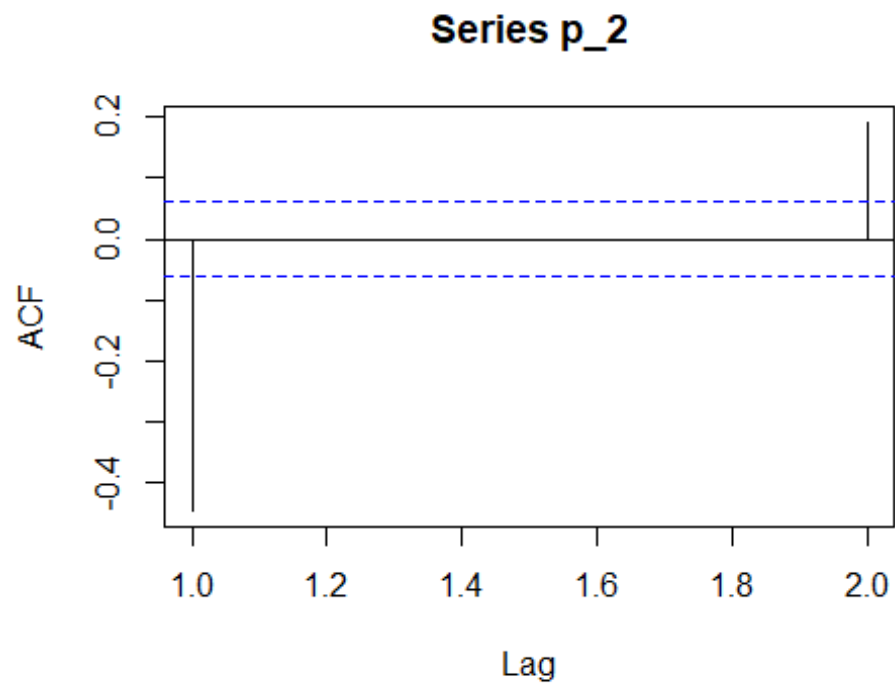
```
# Create a series of 1000 white-noise with a sd = .15
ma_a = rnorm(1001, 0, .15)

rw = ts(cumsum(ma_a))
```

```
# Now, create the MA(2) process  
p_2 = ma_a[1:999] - .5 * ma_a[2:1000] + 0.25 * ma_a[3:1000]  
plot(p_2, type="l")
```



```
ac_f=acf(p_2,lag.max = 2)
```



```
ac_f
##
## Autocorrelations of series 'p_2', by lag
##
##      1      2
## -0.445  0.191

mean(p_2)
## [1] -0.0001731993
```

### 3, EXTRA CREDIT

#### MA(3) AUTOCORRELATION AT LAG 1 & 2

$$\rho_1 = \frac{\phi_1 + \phi_1 * \phi_2 + \phi_2 * \phi_3}{1 + \phi_1^2 + \phi_2^2 + \phi_3^2}$$

$$\rho_2 = \frac{\phi_2 + \phi_1 * \phi_3}{1 + \phi_1^2 + \phi_2^2 + \phi_3^2}$$

#### 3b , Autocorrelation at lag 1 = -0.594518

```
ma_3_phi = (-.5) + (-.5*.25) / (1+ (-.5)^2+ (.25^2) +(-0.1)^2 )
ma_3_phi
```

```
## [1] -0.594518
```

**3c, The autocorrelation at lag 1 are similar to the auto correlation as calculated.**

```
# Create a series of 1000 white-noise with a sd = .15
```

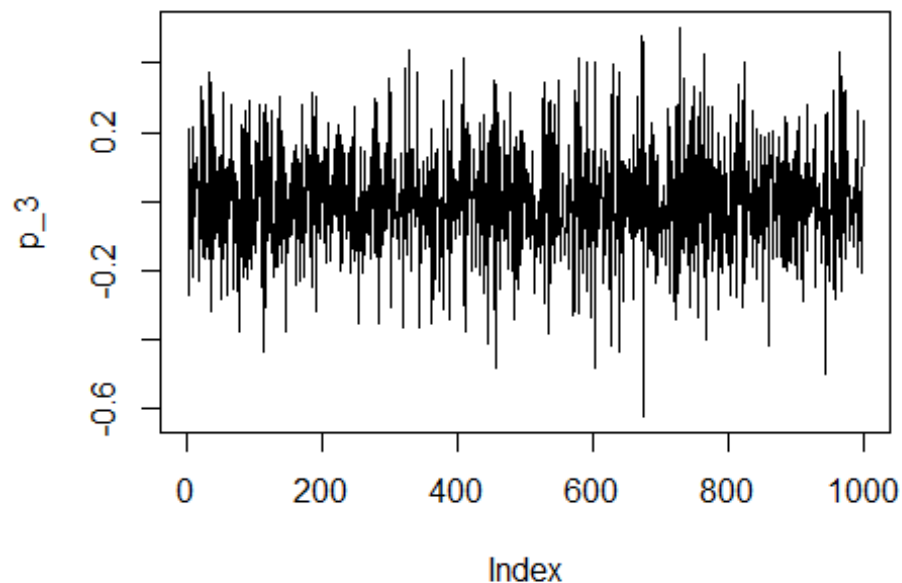
```
ma_3_a = rnorm(1001, 0, .15)
```

```
rw = ts(cumsum(ma_a))
```

```
# Now, create the MA(2) process
```

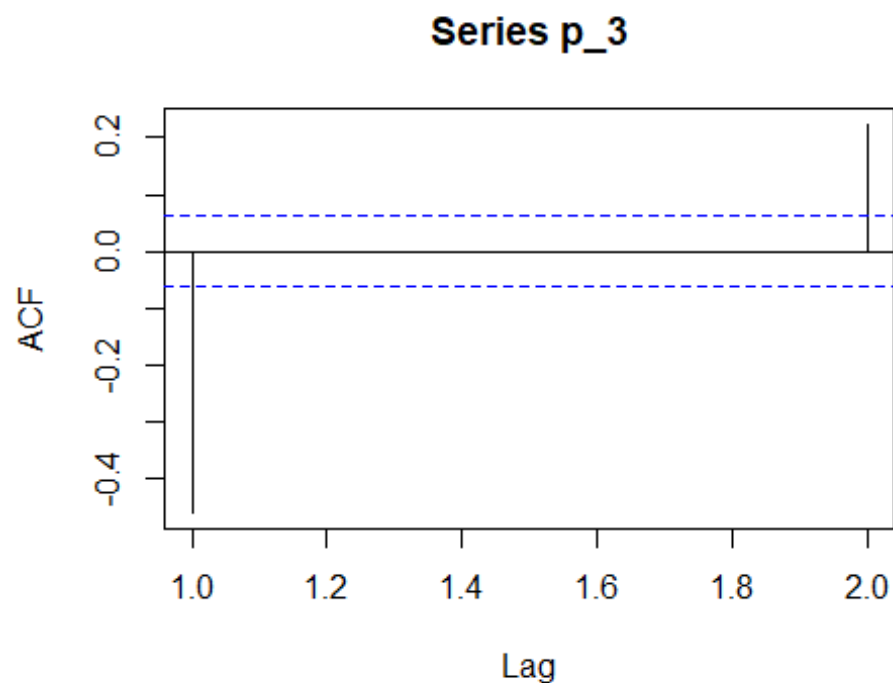
```
p_3 = ma_a[1:999] - .5 * ma_a[2:1000] + 0.25 * ma_a[3:1000] - 0.1  
      *ma_a[4:1000]
```

```
plot(p_3, type="l")
```



```
ac_f3=acf(p_3,lag.max = 2)
```





```
ac_f3
##
## Autocorrelations of series 'p_3', by lag
##
##      1      2
## -0.460  0.223

mean(p_3)
## [1] -0.0001413151
```

## 4

```
library(readxl)

## Warning: package 'readxl' was built under R version 4.0.5

df1<- read.csv("NAPM.csv")
df1$date = as.Date(df1$date,format = "%m/%d/%y")
df1$date =as.character(df1$date)
df1_ts = ts(df1[index,c(2019,01)],frequency=365)
```

4a, Auto arima suggest a Series: df1\_ts ARIMA(3,0,2) all coefficient are highly significant.

```
# Auto.arima
fit2b = auto.arima(df1_ts, seasonal = "F")
fit2b

## Series: df1_ts
## ARIMA(3,0,2) with non-zero mean
##
## Coefficients:
##          ar1      ar2      ar3      ma1      ma2      mean
##          2.1341 -2.0191  0.8263 -1.1207  0.9138  51.2594
## s.e.    0.0520  0.0774  0.0417  0.0334  0.0397  1.3040
##
## sigma^2 = 4.272: log likelihood = -925.1
## AIC=1864.2  AICc=1864.47  BIC=1892.68

coeftest(fit2b)

##
## z test of coefficients:
##
##          Estimate Std. Error z value Pr(>|z|)
## ar1          2.134092    0.051954  41.076 < 2.2e-16 ***
## ar2         -2.019108    0.077396 -26.088 < 2.2e-16 ***
## ar3          0.826309    0.041684  19.823 < 2.2e-16 ***
## ma1         -1.120745    0.033411 -33.544 < 2.2e-16 ***
## ma2          0.913831    0.039679  23.031 < 2.2e-16 ***
## intercept  51.259385    1.303996  39.309 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

4b Auto arima with fit criterion as BIC, using the BIC as a fit criterion gives ARIMA(1,0,2) likewise all coefficient are significant.

Comparing the models we see that MA(2) has the highest  $\sigma^2 = 23.7$ . AR(2)  $\sigma^2 = 4.439$ . Using the autoarima with bic and without bic had both  $\sigma^2$  of 4.284 and 4.272 respectfully. Comparing the models with simplicity we can go with the ARIMA(1,0,2)

```
# Auto.arima
fit3b = auto.arima(df1_ts, seasonal = "F", ic= "bic")
fit3b

## Series: df1_ts
## ARIMA(1,0,2) with non-zero mean
##
## Coefficients:
##          ar1      ma1      ma2      mean
##          0.8786  0.1705  0.2442  51.3660
```

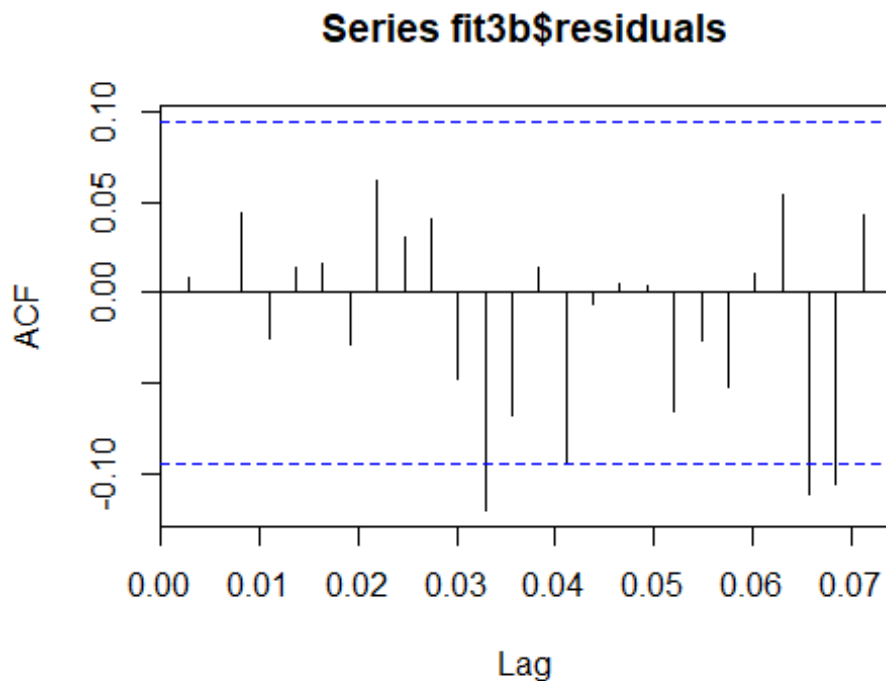
```
## s.e.  0.0259  0.0503  0.0525  1.1358
##
## sigma^2 = 4.284:  log likelihood = -926.33
## AIC=1862.66  AICc=1862.8  BIC=1883

coeftest(fit3b)

##
## z test of coefficients:
##
##          Estimate Std. Error z value Pr(>|z|)
## ar1          0.878615   0.025922 33.8951 < 2.2e-16 ***
## ma1          0.170533   0.050307  3.3898 0.0006993 ***
## ma2          0.244205   0.052464  4.6547 3.244e-06 ***
## intercept 51.366036   1.135791 45.2249 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

**4C, The model I am picking is the ARIMA(1,0,2) this has the highest p-value while analysing the residual. It also has the lowest  $\sigma^2$ .**

```
acf(fit3b$residuals)
```



```
Box.test(fit3b$residuals, lag=10, type="Ljung")
```

```
##
## Box-Ljung test
##
```

```
## data: fit3b$residuals
## X-squared = 4.563, df = 10, p-value = 0.9184
```

**4d, 5-step ahead forecast. From the forecast plot and upward movement seem to exist.**

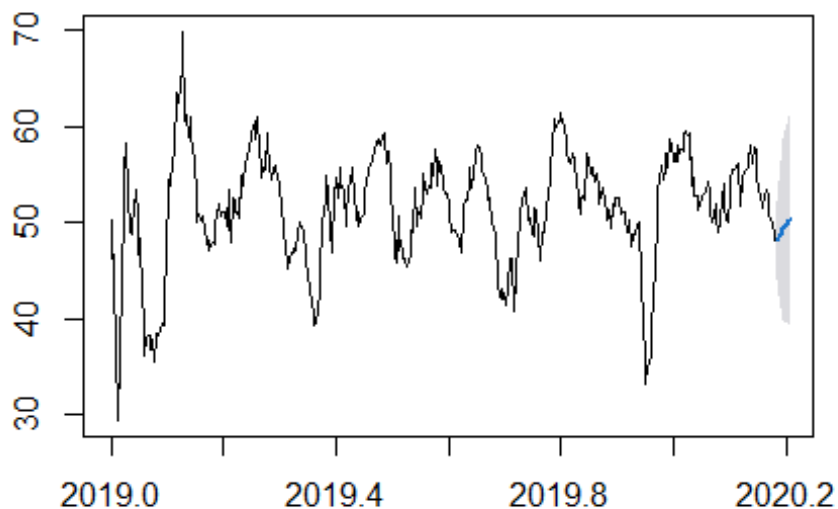
```
fore_arima = forecast::forecast(fit3b, h=5, level = c(95))
df_arima = as.data.frame(fore_arima)
df_arima
```

##		Point Forecast	Lo 95	Hi 95
##	2020.1836	48.11247	44.05576	52.16918
##	2020.1863	48.38277	42.50304	54.26249
##	2020.1890	48.74489	41.19868	56.29110
##	2020.1918	49.06306	40.44810	57.67801
##	2020.1945	49.34260	39.98574	58.69946

**4e, From the forecast plot and upward movement seem to exist towards the mean.**

```
# Now, compute forecasts
plot(forecast(fit3b, h=10, level = c(95)), xlim=c(2019, 2020.2))
```

**Forecasts from ARIMA(1,0,2) with non-zero mean**

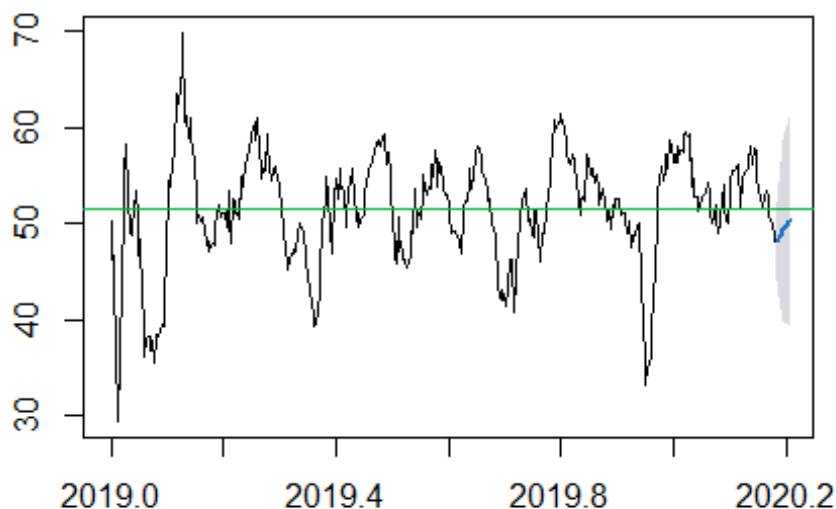


4f, The model predicts suggest a gradual increase as PMI increase toward the mean as seen above. Hence the manufacturing economy is expanding.

4g, Forecast for ARMA model will decay to the current level of the series and remain there. Converges to the mean.

```
b=mean(df1_ts)
# Now, compute forecasts
plot(forecast(fit3b, h=10, level = c(95)), xlim=c(2019, 2020.2))
abline(h=b, col=3)
```

### Forecasts from ARIMA(1,0,2) with non-zero mean



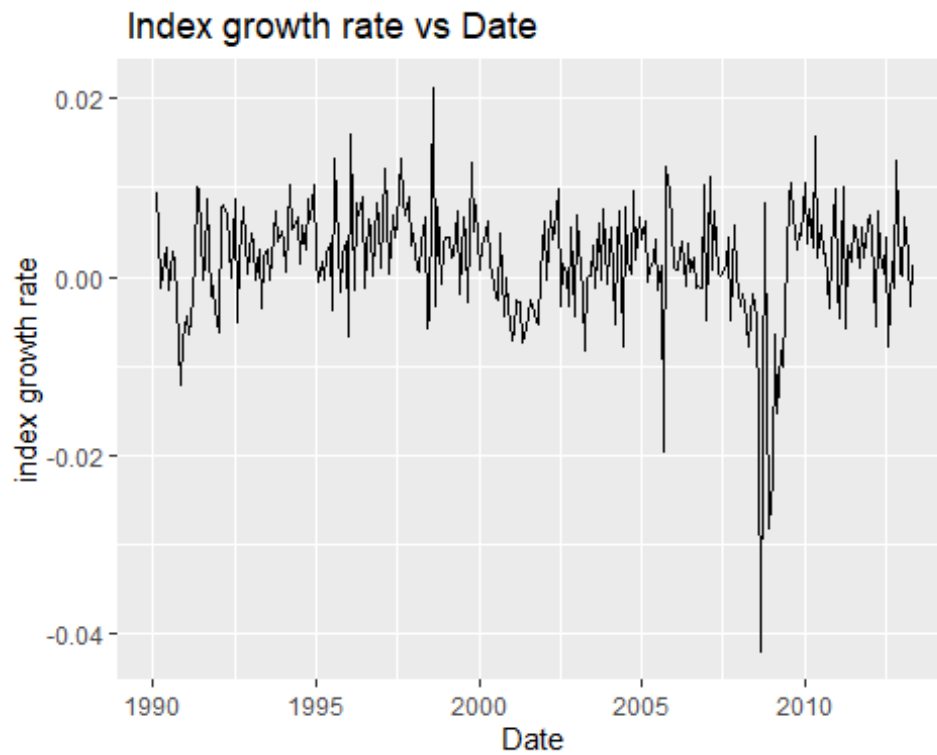
## 5

### 5a Import data

```
library(readxl)
df2<- read.csv("indpro.csv")
df2$date = as.Date(df2$date,format = "%m/%d/%y")
df2$date =as.character(df2$date)
df2_ts = ts(df2$rate,c(1990,02),frequency=12)
```

### 5b, Time plot and analyze series for stationarity, trends and strong seasonality

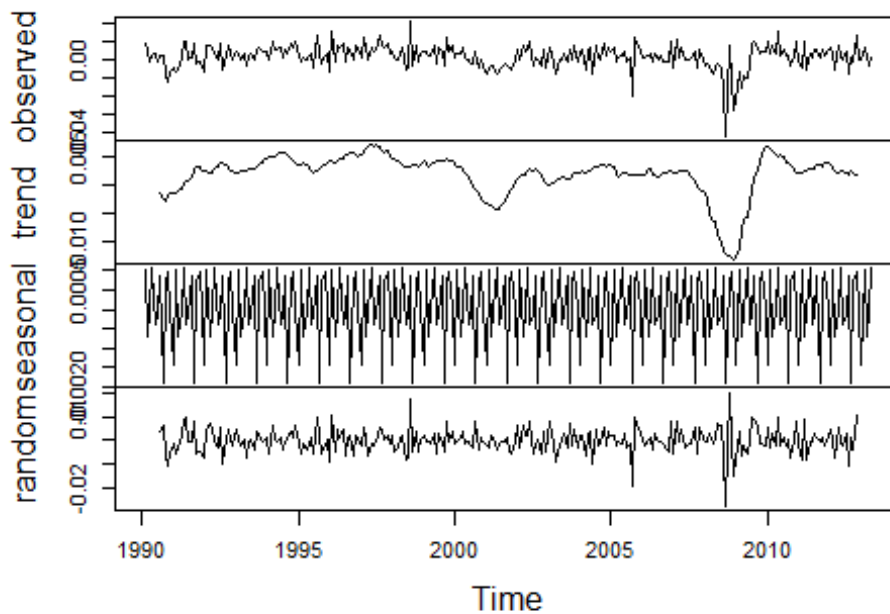
```
ggplot(df2_ts,aes(x= time(df2_ts) ,y= df2_ts
,group=1))+geom_line()+labs(title = " Index growth rate vs
Date")+xlab("Date")+ylab("index growth rate")
```



The series is stationary, there seem to be no distinct trend in the serieies also there is no strong seaoninality in the series beacause the random scale is larger than the seasonal range.

```
plot(decompose(df2_ts))
```

## Decomposition of additive time series



5c Using the Jarque Bera test we reject the null hypothesis , hence index rate is not normally distributed.

```
library(tseries)
jarque.bera.test(df2_ts)
```

```
##
##  Jarque Bera Test
##
## data:  df2_ts
## X-squared = 896.15, df = 2, p-value < 2.2e-16
```

5d Both Dickey-Fuller test rejects non-stationarity and KPSS fail to reject stationarity hence series is stationary and no further transformation is needed.

```
#
#  Dickey-Fuller: The series has a unit root ---> non-stationary
#  KPSS          : The series is stationary
library(TSA)
adf.test(df2_ts)    # What can we conclude?
```

```
##
##  Augmented Dickey-Fuller Test
##
## data:  df2_ts
## Dickey-Fuller = -4.5041, Lag order = 6, p-value = 0.01
## alternative hypothesis: stationary
```

```
kpss.test(df2_ts, null="Level") # What can we conclude?
```

```
##
```

```
## KPSS Test for Level Stationarity
```

```
##
```

```
## data: df2_ts
```

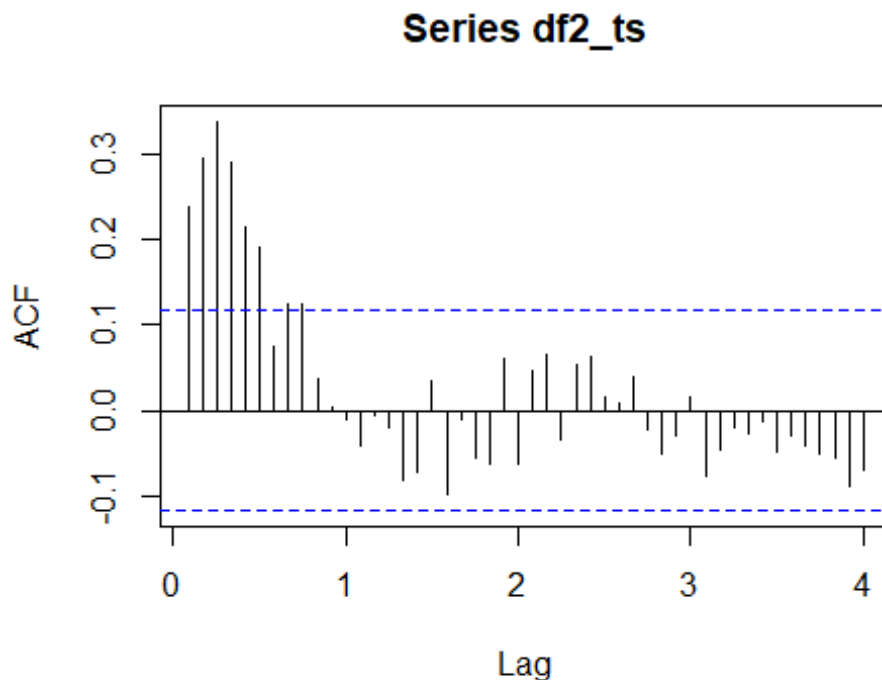
```
## KPSS Level = 0.33824, Truncation lag parameter = 5, p-value = 0.1
```

5e The ACF and PACF do not show any distinct sign of non-stationarity , but the EACF shows sign of stationarity since the top row of the EACF has no strong line of X's.

Model shows a little bit of both AR and MA, the EACF suggest a ARIMA(1,0,1) process, also the ACF and PACF show some MA(1) and AR(1) attribute respectfully.

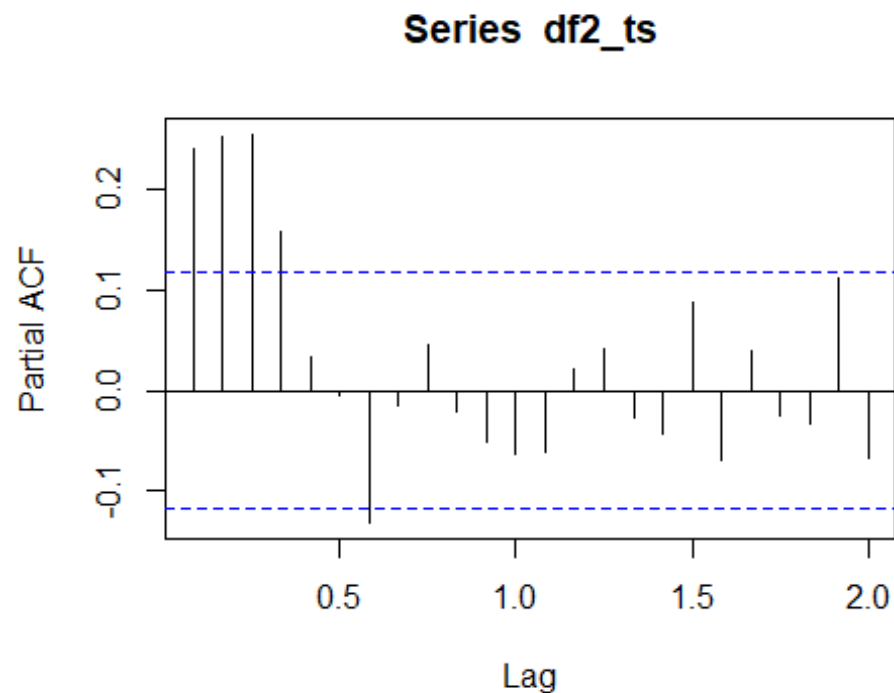
```
# ACF Analysis
```

```
acf(df2_ts, lag.max = 48)
```



```
pacf(df2_ts)
```





```
eacf(df2_ts)
```

```
## AR/MA
##   0 1 2 3 4 5 6 7 8 9 10 11 12 13
## 0 x x x x x x o x x o o  o  o  o
## 1 x o o o o o o o o o o  o  o  o
## 2 x x o o o o x o o o o  o  o  o
## 3 x x x o o o o o o o o  o  o  o
## 4 x o o x o o o o o o o  o  o  o
## 5 x o x x x o o o o o o  o  o  o
## 6 o x x x x x o o o o o  o  o  o
## 7 o x x x x o x o o o o  o  o  o
```

5f, The coefficient of the model are significant but the intercept (mean) is not significant the residual fail to reject the the null hypothesis hence residual has no correlation.

**ARMA (1,1)**

$$V_t = 0.89v_{t-1} - 0.83a_{t-1}$$

```
M1 = Arima(df2_ts, order=c(1, 0, 1))
M1
```

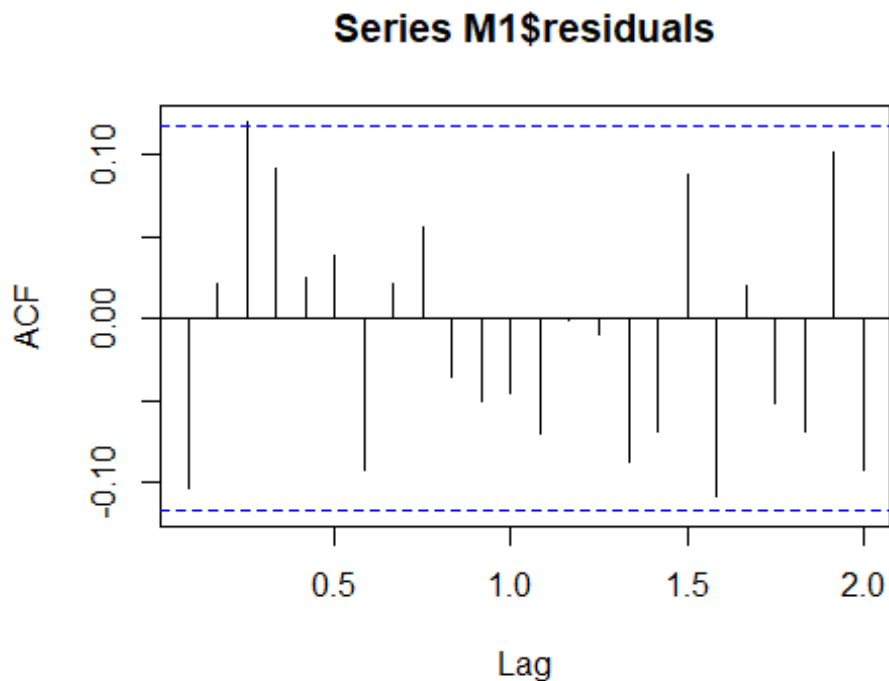
```
## Series: df2_ts
## ARIMA(1,0,1) with non-zero mean
```

```
##
## Coefficients:
##      ar1      ma1      mean
##      0.8919 -0.6967  0.0017
## s.e.  0.0407  0.0583  0.0010
##
## sigma^2 = 3.692e-05: log likelihood = 1032.99
## AIC=-2057.97  AICc=-2057.83  BIC=-2043.43

coeftest(M1)

##
## z test of coefficients:
##
##      Estimate Std. Error z value Pr(>|z|)
## ar1      0.89188598  0.04069736  21.9151 < 2e-16 ***
## ma1     -0.69671463  0.05825331 -11.9601 < 2e-16 ***
## intercept 0.00174898  0.00099419  1.7592  0.07854 .
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

acf(M1$residuals)
```



```
Box.test(M1$residuals, lag=48, type="Ljung")

##
## Box-Ljung test
##
```

```
## data: M1$residuals
## X-squared = 50.153, df = 48, p-value = 0.388
```

5g, Auto ARIMA with BIC suggest a ARIMA(1,0,2) all coefficient are significant in the model but AR(1) and MA(1) are highly significant. The residual fail to reject white noise hence has no correlation

### ARMA (1,2)

$$V_t = 0.89v_{t-1} - 0.83a_{t-1} - 0.21a_{t-2}$$

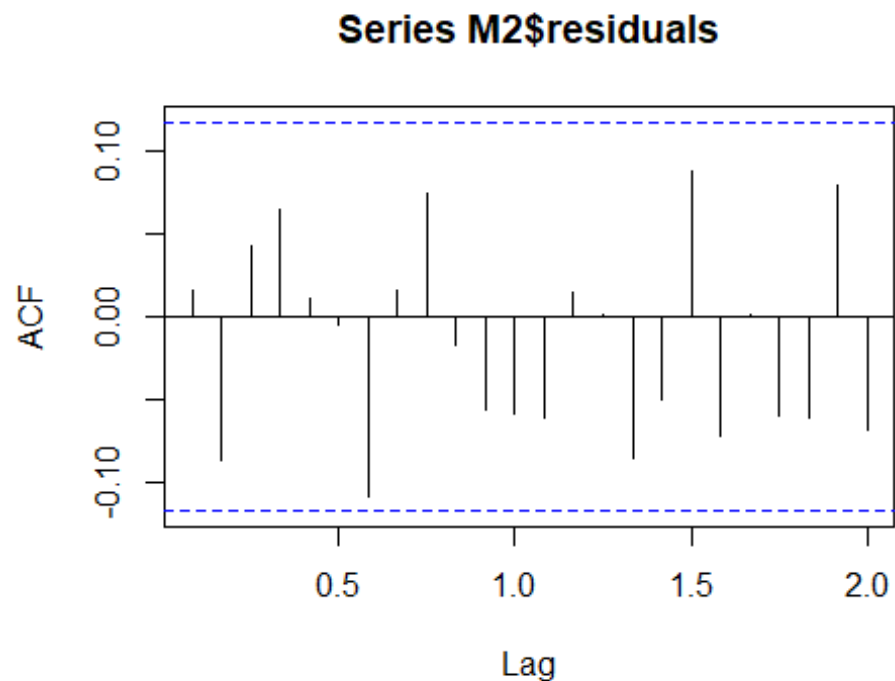
```
# Auto.arima
M2 = auto.arima(df2_ts,ic= "bic")
M2

## Series: df2_ts
## ARIMA(1,0,2) with zero mean
##
## Coefficients:
##          ar1          ma1          ma2
##          0.8813   -0.8302    0.2172
## s.e.    0.0421    0.0716    0.0693
##
## sigma^2 = 3.604e-05: log likelihood = 1036.24
## AIC=-2064.49   AICc=-2064.34   BIC=-2049.95

coeftest(M2)

##
## z test of coefficients:
##
##      Estimate Std. Error  z value  Pr(>|z|)
## ar1  0.881250   0.042066  20.9491 < 2.2e-16 ***
## ma1 -0.830236   0.071645 -11.5882 < 2.2e-16 ***
## ma2  0.217189   0.069277   3.1351  0.001718 **
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

acf(M2$residuals)
```

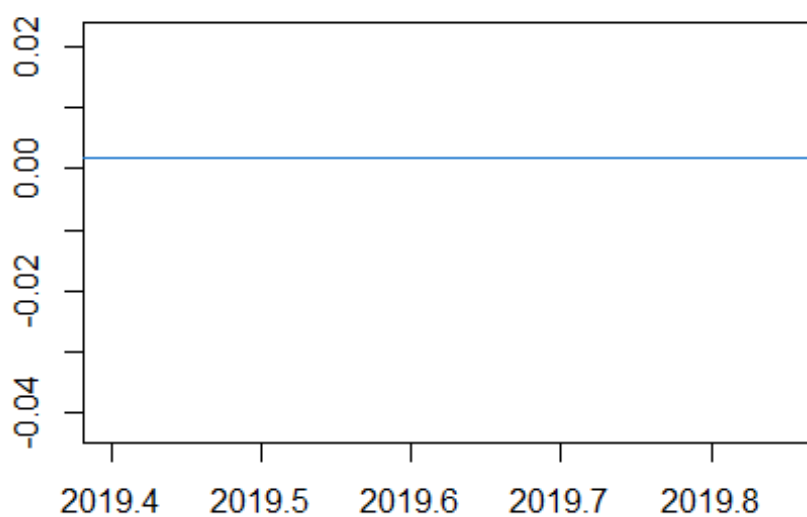


```
Box.test(M2$residuals, lag=10, type="Ljung")  
##  
## Box-Ljung test  
##  
## data: M2$residuals  
## X-squared = 9.1922, df = 10, p-value = 0.514
```

5h Forecast behavior for each series are different, for M1 the forecast somewhat converge to the mean of the series. While the M2 model the forecast somewhat deviates from the mean.

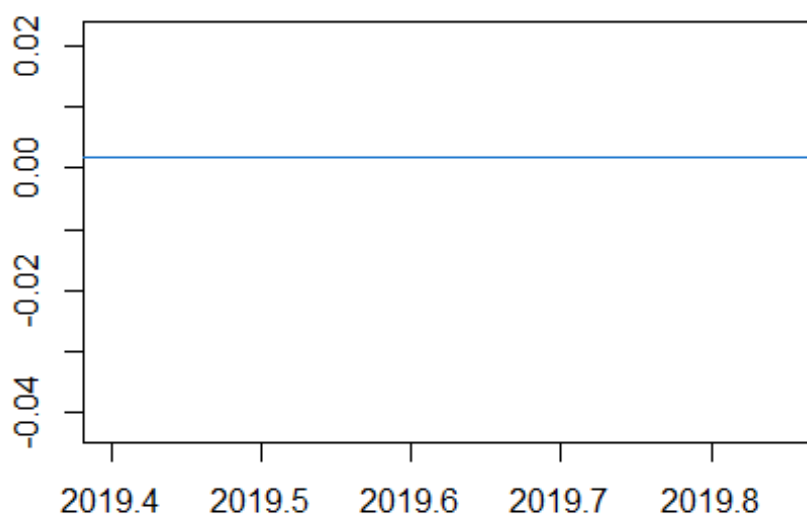
```
# Now, compute forecasts  
plot(forecast(M1, h=10, level = c(95)), xlim=c(2019.4, 2019.85))  
abline(h=mean(df2_ts), col=4)
```

### Forecasts from ARIMA(1,0,1) with non-zero mean



```
plot(forecast(M2, h=10, level = c(95)), xlim=c(2019.4, 2019.85))  
abline(h=mean(df2_ts), col=4)
```

### Forecasts from ARIMA(1,0,2) with zero mean



5i, From the M1 and M2 , I tend to choose M1. The M2 model ARIMA(1,0,2) seem to have a non significant coefficient for M2, the M1 had all coefficient to be significant it also passed the residual test and has a better forecast behaviour compared with M2. I pick M1.

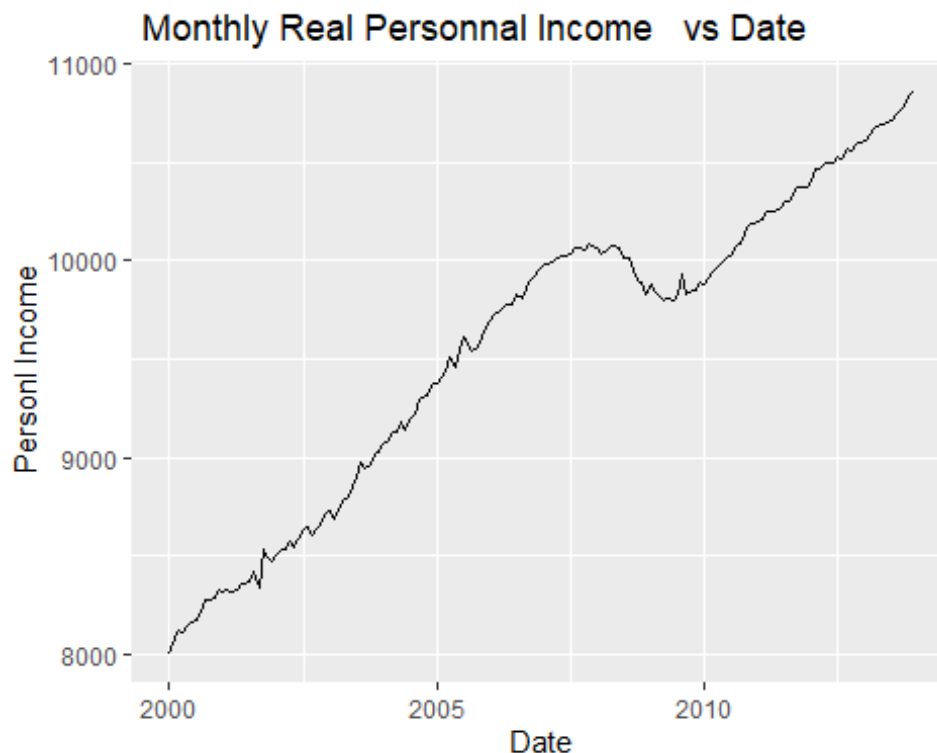
## 6

### 6a Import data

```
library(readxl)
df3<- read.csv("consump.csv")
df3$date = as.Date(df3$date,format = "%m/%d/%Y")
df3$date =as.character(df3$date)
df3_ts = ts(df3$pers_inc,c(2000,01),frequency=12)
```

6b, Personal income show an exponential growth over time, with an up-ward trend , non stationary.

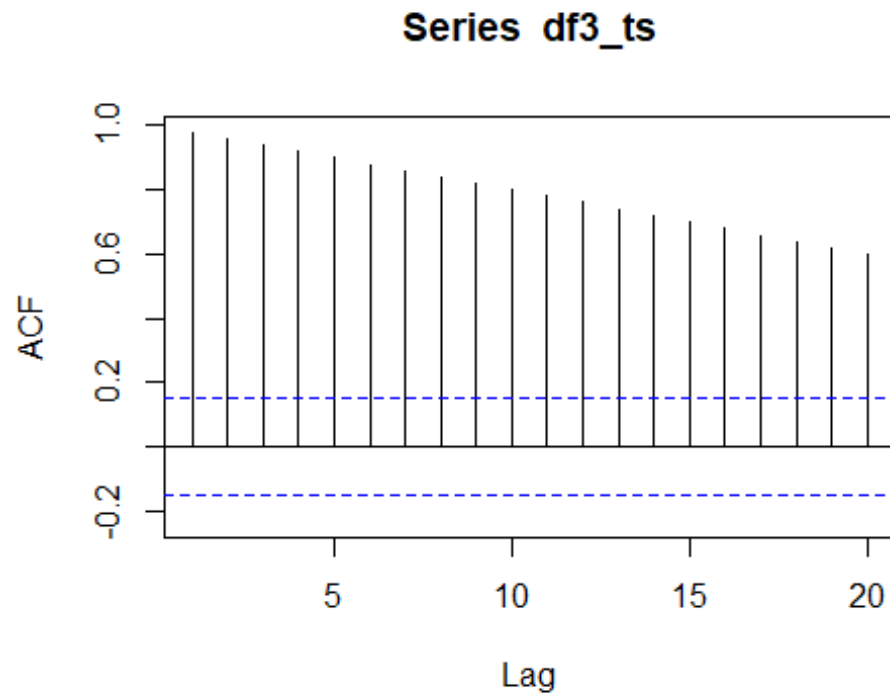
```
ggplot(df3_ts,aes(x= time(df3_ts) ,y= df3_ts
,group=1))+geom_line()+labs(title = " Monthly Real Personnal Income  vs
Date")+xlab("Date")+ylab(" Personl Income")
```



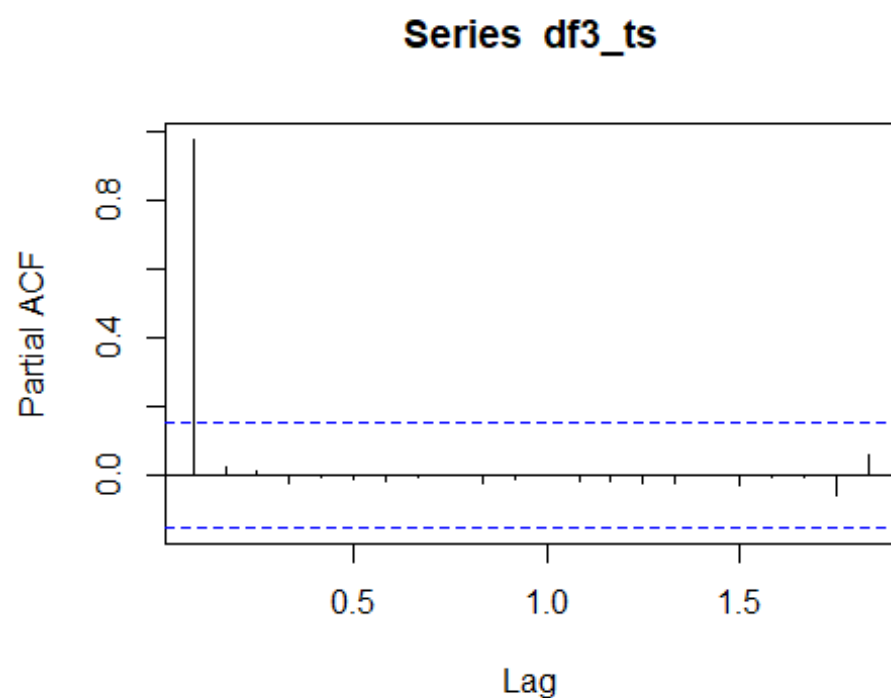
1b, PACF indicates AR(1) ACF shows a sharp fall off but not exponential which indicates non-stationary series. The top row of the EACF has constant line's of X hence series is NON-STATIONARY

```
# ACF Analysis
```

```
Acf(df3_ts, lag.max = 20)
```



```
pacf(df3_ts)
```



```
eacf(df3_ts)
```

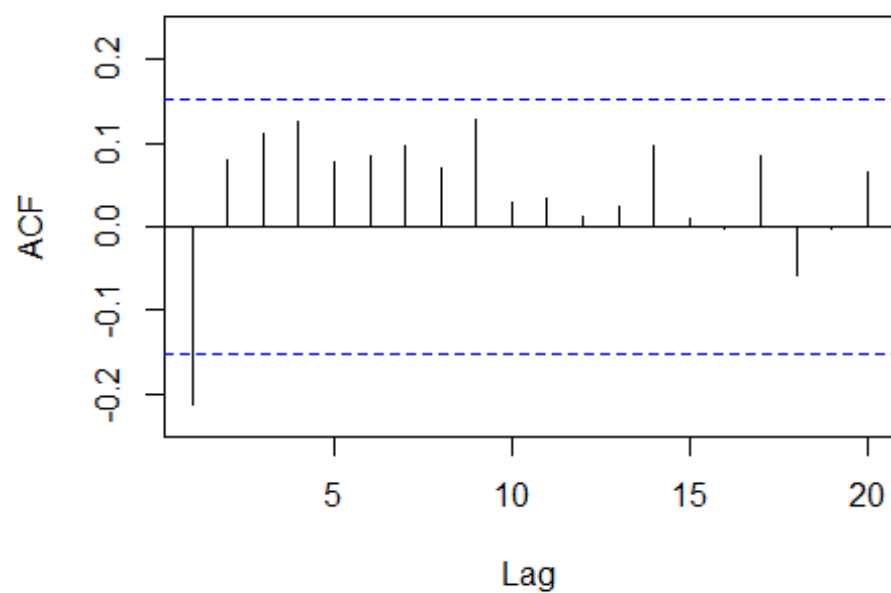
```
## AR/MA
##   0 1 2 3 4 5 6 7 8 9 10 11 12 13
## 0 x x x x x x x x x x x x x
## 1 x o o o o o o o o o o o o
## 2 x o o o o o o o o o o o o
## 3 x o o o o o o o o o o o o
## 4 x x x x o o o o o o o o
## 5 x o o o o o o o o o o o o
## 6 x o o o o o o o o o o o o
## 7 x x o o o x o o o o o o o
```

6c, The difference of the series shows no sign of non-stationary behaviour the acf show some sign of over-differencing which is indicated in the flipping signs in the ACF plot.

```
# ACF Analysis
Acf(diff(df3_ts), lag.max = 20)
```

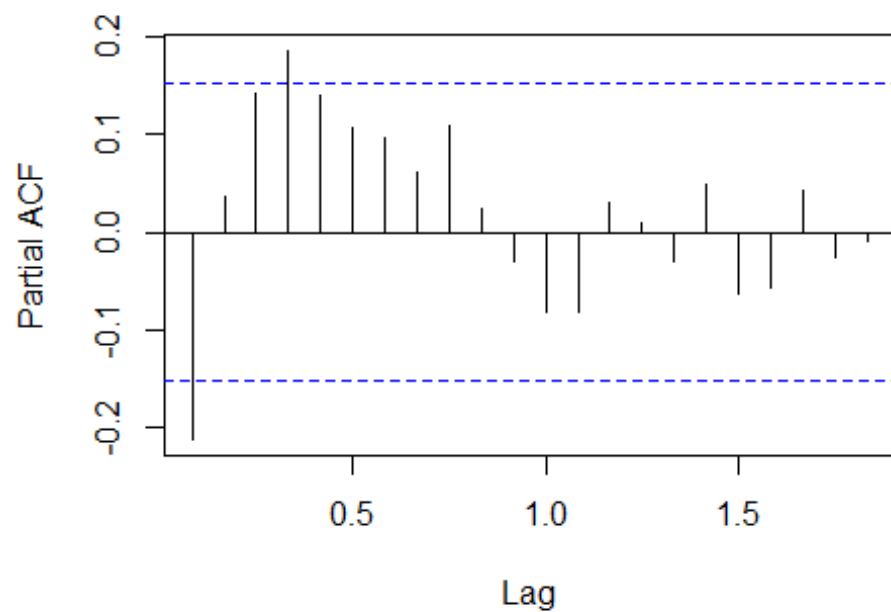


**Series diff(df3\_ts)**



```
pacf(diff(df3_ts))
```

**Series diff(df3\_ts)**



```
eacf(diff(df3_ts))
```

```
## AR/MA
##   0 1 2 3 4 5 6 7 8 9 10 11 12 13
## 0 x o o o o o o o o o o o o o
## 1 x o o o o o o o o o o o o o
## 2 x o o o o o o o o o o o o o
## 3 x x x x o o o o o o o o o
## 4 x o o o o o o o o o o o o o
## 5 x x o o o o o o o o o o o
## 6 x x o o o x o o o o o o o
## 7 x o o o o x o o o o o o o
```

6d, Dickey Fuller can not reject null , hence series is non-stationary. An ARIMA(p,d,q) is appropriate.

```
#
#   Dickey-Fuller: The series has a unit root ---> non-stationary
#   KPSS          : The series is stationary
library(TSA)
adf.test(df3_ts)    # What can we conclude?

##
## Augmented Dickey-Fuller Test
##
## data: df3_ts
## Dickey-Fuller = -1.6612, Lag order = 5, p-value = 0.7177
## alternative hypothesis: stationary

kpss.test(df3_ts, null="Level")    # What can we conclude?

##
## KPSS Test for Level Stationarity
##
## data: df3_ts
## KPSS Level = 3.2373, Truncation lag parameter = 4, p-value = 0.01
```

6e, From the result a differencing is appropriate. From the information gathered from the initial ACF and PACF my initial model was ARIMA(1,1,1) after tuning and observing the residual ACF the final model is ARIMA (1,1,2).

```
M4 = Arima(df3_ts, order=c(1, 1, 2))
M4

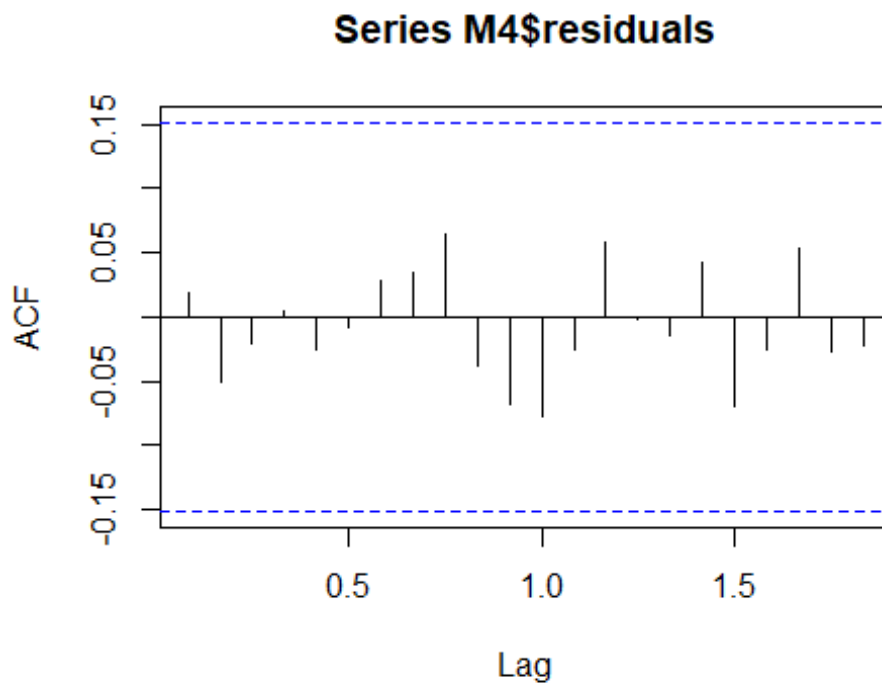
## Series: df3_ts
## ARIMA(1,1,2)
##
## Coefficients:
##          ar1          ma1          ma2
##          0.9804      -1.2851      0.4237
## s.e.    0.0176      0.0765      0.0768
##
## sigma^2 = 1100: log likelihood = -820.93
## AIC=1649.87   AICc=1650.11   BIC=1662.34
```

```
coeftest(M4)
```

```
##
## z test of coefficients:
##
##      Estimate Std. Error  z value  Pr(>|z|)
## ar1  0.980367   0.017559  55.8338 < 2.2e-16 ***
## ma1 -1.285079   0.076545 -16.7887 < 2.2e-16 ***
## ma2  0.423688   0.076823   5.5151 3.485e-08 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

**6f, The model captures all dynamic monthly behaviours.**

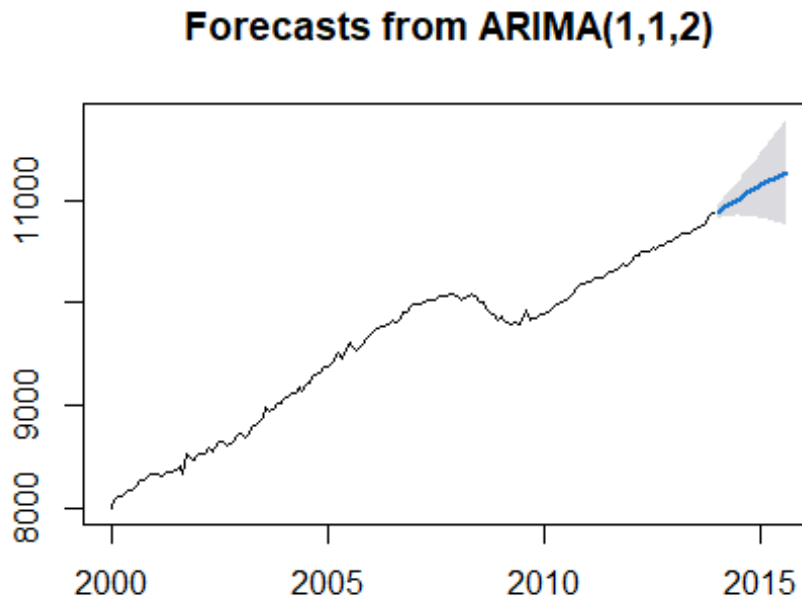
```
acf(M4$residuals)
```



```
Box.test(M4$residuals, lag=20, type="Ljung")
```

```
##
## Box-Ljung test
##
## data:  M4$residuals
## X-squared = 6.6331, df = 20, p-value = 0.9977
```

6g, The 20 step ahead forecast seem to be flow the path of the trend.



6h, Using Auto ARIMA with BIC the model suggest a ARIMA(1,1,0) and includes a drift in the model. The residual ACF seem not to capture all the required monthly information. The ARIMA model fails the Ljung-Box test by rejecting white noise. Hence the hand tuned model performs better than AUTO ARIMA's model.

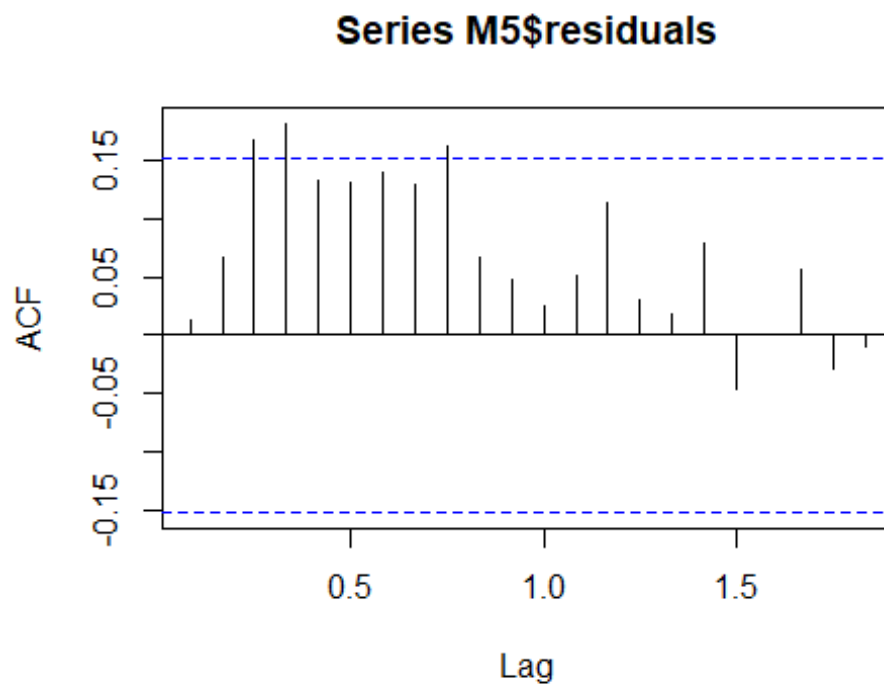
```
# Auto.arima
M5 = auto.arima(df3_ts,ic= "bic")
M5

## Series: df3_ts
## ARIMA(1,1,0) with drift
##
## Coefficients:
##          ar1      drift
##       -0.2147  17.1087
## s.e.    0.0760   2.1843
##
## sigma^2 = 1188: log likelihood = -827.11
## AIC=1660.22   AICc=1660.36   BIC=1669.57

coeftest(M5)
```

```
##
## z test of coefficients:
##
##      Estimate Std. Error z value Pr(>|z|)
## ar1   -0.214674   0.076047 -2.8229  0.004759 **
## drift 17.108730   2.184287  7.8326 4.777e-15 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

acf(M5$residuals)
```



```
Box.test(M5$residuals, lag=20, type="Ljung")

##
## Box-Ljung test
##
## data:  M5$residuals
## X-squared = 35.056, df = 20, p-value = 0.01981
```