

Module 4: Hardware & Location

Repository Pattern, CameraX & Google Maps

Adrián Catalán

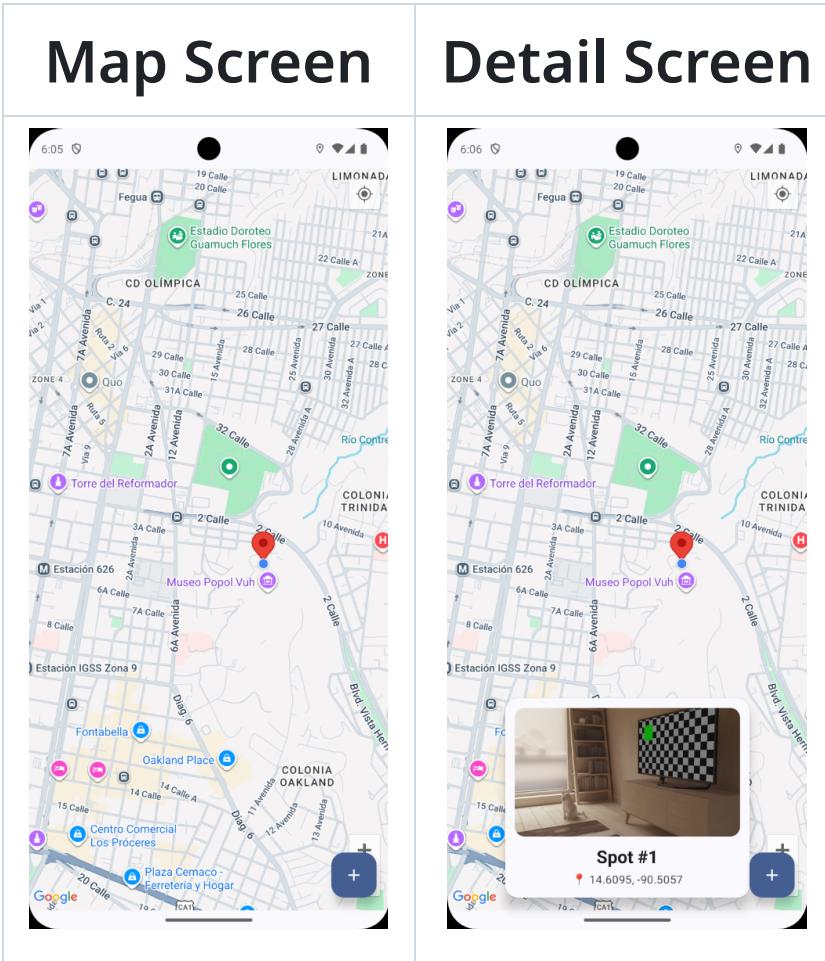
adriancatalan@galileo.edu

Agenda

1. Module App
2. Repository Pattern
3. CameraX
4. Google Maps SDK
5. Deep Dive
6. Challenge Lab

City Spots App

An app that captures geolocated photos and displays them on an interactive map.



What We're Building

Features:

1. **Capture Photos:** Use CameraX to take pictures
2. **Get Location:** FusedLocationProvider for GPS coordinates
3. **Store Locally:** Room database for persistence
4. **Visualize on Map:** Google Maps with custom markers

Architecture Challenge:

How do we coordinate Camera + GPS + Database without creating spaghetti code?

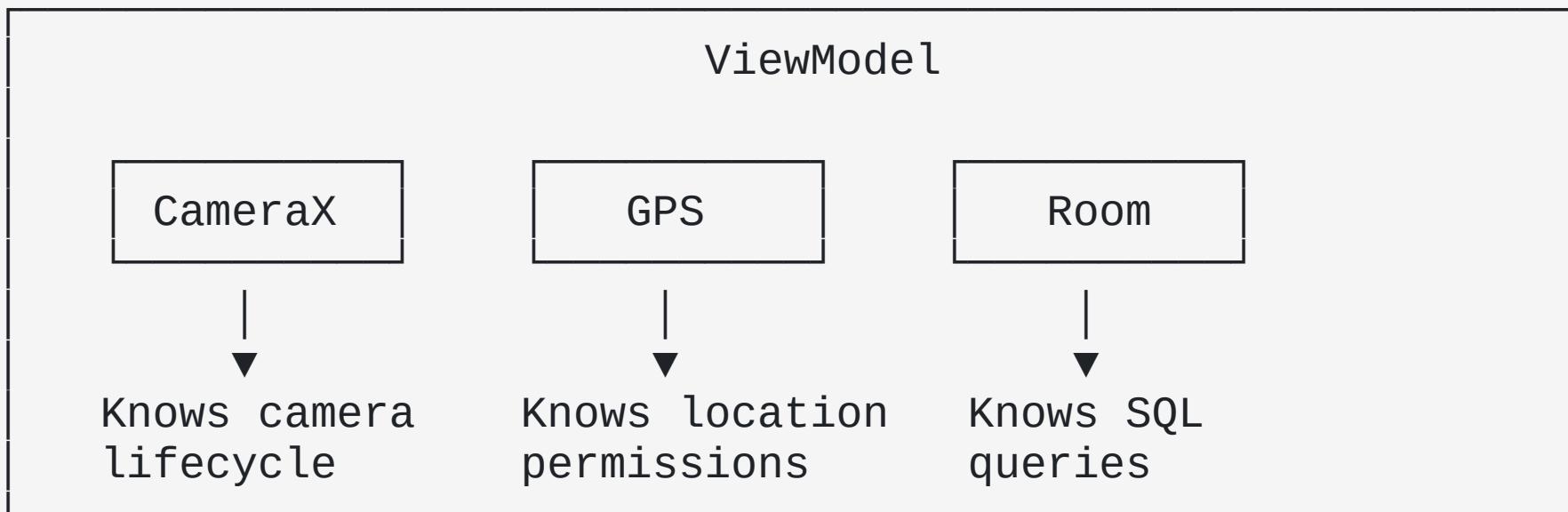
2. Repository Pattern

Unifying Multiple Data Sources

The Problem: Spaghetti Code

Without Repository:

The ViewModel talks to *everything* directly.

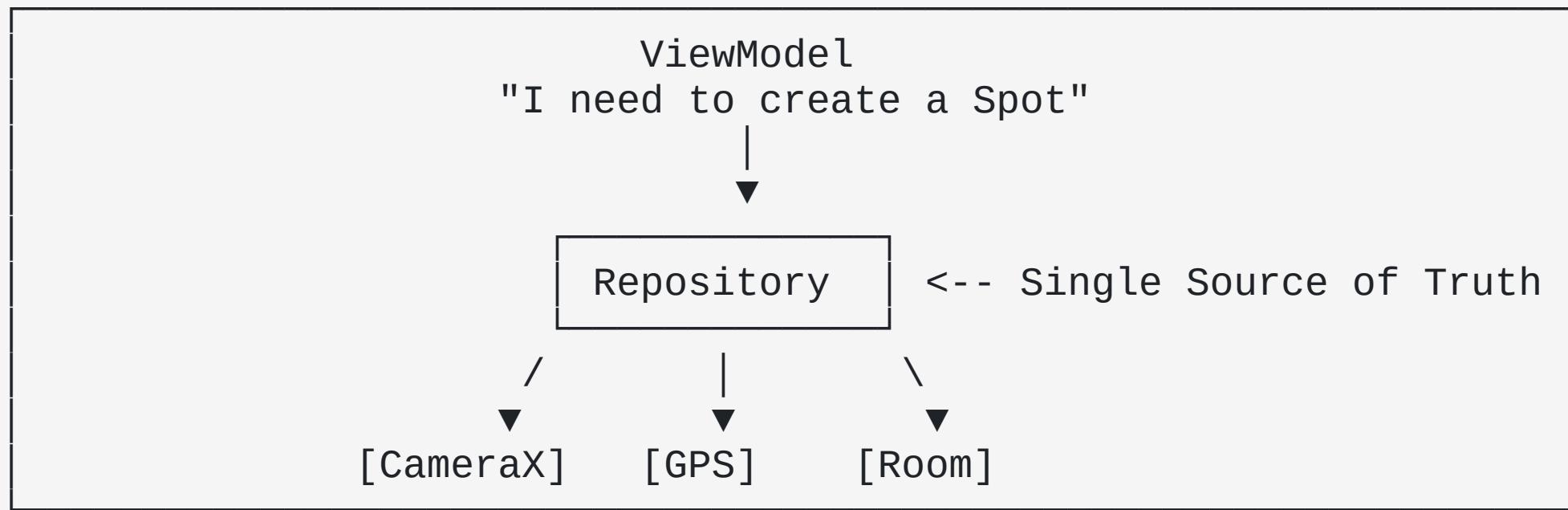


Result: ViewModel becomes a "God Class" with 500+ lines.

The Solution: Single Point of Access

With Repository:

The ViewModel only knows about *one* interface.



Result: ViewModel is simple. Repository handles coordination.

Real World Analogy: The Concierge

Problem (No Repository):

You're a tourist. You need:

- A taxi (Camera)
- A restaurant reservation (GPS)
- A theater ticket (Database)

You call each service separately, handle each error, coordinate timing...

Exhausting.

Real World Analogy: The Solution

Solution (Repository = Hotel Concierge):

You tell the Concierge: "I want dinner and a show tonight."

The Concierge:

1. Calls the restaurant
2. Books the theater
3. Arranges the taxi timing
4. Returns ONE answer: "You're all set for 7pm"

You don't care *how* it was done. The Concierge is your **Single Point of Access**.

Live Code: SpotRepository

```
//repository/SpotRepository.kt
class SpotRepository(
    private val spotDao: SpotDao,           // Database
    private val cameraUtils: CameraUtils,   // Camera hardware
    private val locationUtils: LocationUtils, // GPS
    private val coordinateValidator: CoordinateValidator
) {
    // Database operations
    fun getAllSpots(): Flow<List<SpotEntity>> = spotDao.getAllSpots()

    // Hardware operations
    suspend fun capturePhoto(imageCapture: ImageCapture): Uri =
        cameraUtils.capturePhoto(imageCapture)

    // Location operations
    suspend fun getCurrentLocation(): Location? =
        locationUtils.getCurrentLocation()
}
```

Orchestration: The Real Power

The Repository **coordinates** multiple sources into one operation:

```
suspend fun createSpot(imageCapture: ImageCapture): CreateSpotResult {  
    // 1. Capture photo from camera  
    val photoUri = capturePhoto(imageCapture)  
  
    // 2. Get GPS coordinates  
    val location = getCurrentLocation()  
        ?: return CreateSpotResult.NoLocation  
  
    // 3. Validate coordinates (Null Island check)  
    val validation = coordinateValidator.validate(  
        latitude = location.latitude,  
        longitude = location.longitude  
    )  
    if (validation !is ValidationResult.Valid) {  
        return CreateSpotResult.InvalidCoordinates(validation.message)  
    }  
  
    // 4. Save to database  
    val spot = SpotEntity(imageUri = photoUri.toString(), ...)  
    val id = spotDao.insertSpot(spot)  
  
    return CreateSpotResult.Success(spot.copy(id = id))  
}
```

Result Types: Explicit Error Handling

Instead of throwing exceptions, we return typed results:

```
sealed class CreateSpotResult {  
    data class Success(val spot: SpotEntity) : CreateSpotResult()  
    data object NoLocation : CreateSpotResult()  
    data class InvalidCoordinates(val message: String) : CreateSpotResult()  
}
```

Benefits:

- Compiler forces handling all cases
- UI can show specific error messages
- No try-catch spaghetti in ViewModel

Consuming in ViewModel

```
//ui/viewmodel/MapViewModel.kt
fun captureSpot(imageCapture: ImageCapture) {
    viewModelScope.launch {
        _isLoading.value = true

        when (val result = repository.createSpot(imageCapture)) {
            is CreateSpotResult.Success -> {
                _message.value = "Spot saved: ${result.spot.title}"
            }
            is CreateSpotResult.NoLocation -> {
                _errorMessage.value = "Could not get GPS location"
            }
            is CreateSpotResult.InvalidCoordinates -> {
                _errorMessage.value = result.message
            }
        }
        _isLoading.value = false
    }
}
```

Dependency Injection Setup

```
//di/AppModule.kt
val appModule = module {
    // Singletons for utilities
    single { CameraUtils(androidContext()) }
    single { LocationUtils(androidContext()) }
    singleOf(::CoordinateValidator)

    // Database
    single { SpotDatabase.getInstance(androidContext()) }
    single { get<SpotDatabase>().spotDao() }

    // Repository receives all dependencies
    single {
        SpotRepository(
            spotDao = get(),
            cameraUtils = get(),
            locationUtils = get(),
            coordinateValidator = get()
        )
    }

    viewModelOf(::MapViewModel)
}
```

3. CameraX

Modern Camera API for Android

Why CameraX?

The Old Way (Camera2 API):

- 1000+ lines of boilerplate
- Manual lifecycle management
- Device-specific bugs
- Complex threading model

The New Way (CameraX):

- ~50 lines for basic capture
- Automatic lifecycle binding
- Google handles device quirks
- Coroutines-friendly

CameraX Architecture: Use Cases

CameraX uses a **Use Case** pattern. You declare *what* you want, not *how*.

CameraX Use Cases

Preview

Show
viewfind

ImageCapture

Take still
photos

VideoCapture

Record
videos

ImageAnalysis

Real-time
ML/QR scan

Live Code: ImageCapture Setup

```
//ui/screens/CameraScreen.kt
@Composable
fun CameraScreen(onPhotoTaken: (Uri) -> Unit) {
    val context = LocalContext.current
    val lifecycleOwner = LocalLifecycleOwner.current

    // 1. Create ImageCapture Use Case
    val imageCapture = remember {
        ImageCapture.Builder()
            .setCaptureMode(ImageCapture.CAPTURE_MODE_MAXIMIZE_QUALITY)
            .build()
    }

    // 2. Display Camera Preview
    CameraPreview(
        imageCapture = imageCapture,
        lifecycleOwner = lifecycleOwner
    )

    // 3. Capture Button
    Button(onClick = { /* trigger capture */ }) {
        Text("Take Photo")
    }
}
```

AndroidView: Bridging Compose and Views

CameraX's `PreviewView` is a traditional View. We use `AndroidView` to embed it:

```
@Composable
fun CameraPreview(
    imageCapture: ImageCapture,
    lifecycleOwner: LifecycleOwner
) {
    AndroidView(
        factory = { context ->
            PreviewView(context).apply {
                implementationMode = PreviewView.ImplementationMode.COMPATIBLE
            }
        },
        update = { previewView ->
            val cameraProviderFuture = ProcessCameraProvider.getInstance(context)
            cameraProviderFuture.addListener({
                val cameraProvider = cameraProviderFuture.get()
                bindCameraUseCases(cameraProvider, previewView, imageCapture)
            }, ContextCompat.getMainExecutor(context))
        }
    )
}
```

Binding Use Cases to Lifecycle

```
private fun bindCameraUseCases(
    cameraProvider: ProcessCameraProvider,
    previewView: PreviewView,
    imageCapture: ImageCapture
) {
    // 1. Build Preview Use Case
    val preview = Preview.Builder().build().also {
        it.setSurfaceProvider(previewView.surfaceProvider)
    }

    // 2. Select Camera
    val cameraSelector = CameraSelector.DEFAULT_BACK_CAMERA

    // 3. Unbind previous and bind new
    cameraProvider.unbindAll()
    cameraProvider.bindToLifecycle(
        lifecycleOwner,
        cameraSelector,
        preview,           // Use Case 1: Preview
        imageCapture       // Use Case 2: Capture
    )
}
```

Callback to Coroutine Conversion

CameraX uses callbacks. We convert to coroutines with `suspendCancellableCoroutine`:

```
//utils/CameraUtils.kt
suspend fun capturePhoto(imageCapture: ImageCapture): Uri {
    return suspendCancellableCoroutine { continuation ->
        val photoFile = createImageFile()
        val outputOptions = ImageCapture.OutputFileOptions.Builder(photoFile).build()

        imageCapture.takePicture(
            outputOptions,
            ContextCompat.getMainExecutor(context),
            object : ImageCapture.OnImageSavedCallback {
                override fun onImageSaved(output: OutputFileResults) {
                    continuation.resume(Uri.fromFile(photoFile))
                }
                override fun onError(exception: ImageCaptureException) {
                    photoFile.delete()
                    continuation.resumeWithException(exception)
                }
            }
        )
        continuation.invokeOnCancellation { photoFile.delete() }
    }
}
```

File Storage: Internal vs External

```
fun createImageFile(): File {  
    // Internal storage: Private to app, no permissions needed  
    val storageDir = context.filesDir  
  
    val timeStamp = SimpleDateFormat("yyyyMMdd_HHmmss", Locale.US).format(Date())  
    val fileName = "spot_$timeStamp.jpg"  
  
    return File(storageDir, fileName)  
}
```

Storage Type	Permission	Visible to User	Survives Uninstall
filesDir (Internal)	None	No	No
getExternalFilesDir	None (API 19+)	Yes	No
MediaStore	READ/WRITE	Yes	Yes

Runtime Permissions (Accompanist)

```
@Composable
fun CameraPermissionWrapper(content: @Composable () -> Unit) {
    val cameraPermissionState = rememberPermissionState(
        Manifest.permission.CAMERA
    )

    when {
        cameraPermissionState.status.isGranted -> {
            content() // Show camera
        }
        cameraPermissionState.status.shouldShowRationale -> {
            RationaleDialog(
                onConfirm = { cameraPermissionState.launchPermissionRequest() }
            )
        }
        else -> {
            Button(onClick = { cameraPermissionState.launchPermissionRequest() }) {
                Text("Grant Camera Permission")
            }
        }
    }
}
```

4. Google Maps SDK

Interactive Maps in Compose

Maps Compose: Declarative Mapping

Instead of imperative `googleMap.addMarker(...)`, we declare:

```
GoogleMap(  
    cameraPositionState = cameraPositionState  
) {  
    // Markers are Composables!  
    Marker(  
        state = rememberMarkerState(position = LatLng(14.6, -90.5)),  
        title = "Guatemala City"  
    )  
}
```

Key Concept: The map is *part* of the Compose tree. State changes trigger recomposition, and markers update automatically.

Live Code: MapScreen

```
//ui/screens/MapScreen.kt
@Composable
fun MapScreen(
    viewModel: MapViewModel = koinViewModel(),
    onNavigateToCamera: () -> Unit
) {
    val spots by viewModel.spots.collectAsState()
    val userLocation by viewModel.userLocation.collectAsState()

    val cameraPositionState = rememberCameraPositionState {
        position = userLocation?.let {
            CameraPosition.fromLatLngZoom(it, 15f)
        } ?: CameraPosition.fromLatLngZoom(LatLng(0.0, 0.0), 2f)
    }

    Box(modifier = Modifier.fillMaxSize()) {
        GoogleMap(
            cameraPositionState = cameraPositionState,
            properties = MapProperties(isMyLocationEnabled = true)
        ) {
            spots.forEach { spot -> SpotMarker(spot) }
        }

        // FAB to open camera
        FloatingActionButton(onClick = onNavigateToCamera) {
            Icon(Icons.Filled.Add, "Add Spot")
        }
    }
}
```

Custom Info Windows

```
@Composable
private fun SpotMarker(spot: SpotEntity) {
    MarkerInfoWindowContent(
        state = rememberMarkerState(
            position = LatLng(spot.latitude, spot.longitude)
        ),
        title = spot.title
    ) {
        // Custom Composable as Info Window
        Column(
            modifier = Modifier
                .background(Color.White, RoundedCornerShape(12.dp))
                .padding(8.dp)
        ) {
            AsyncImage(
                model = spot.imageUri.toUri(),
                contentDescription = spot.title,
                modifier = Modifier.size(180.dp, 120.dp)
            )
            Text(text = spot.title, style = MaterialTheme.typography.titleMedium)
            Text(
                text = "📍 ${spot.latitude}, ${spot.longitude}",
                style = MaterialTheme.typography.bodySmall
            )
        }
    }
}
```

FusedLocationProvider: Getting GPS

```
//utils/LocationUtils.kt
class LocationUtils(context: Context) {
    private val fusedLocationClient =
        LocationServices.getFusedLocationProviderClient(context)

    @SuppressLint("MissingPermission")
    suspend fun getCurrentLocation(): Location? {
        return suspendCancellableCoroutine { continuation ->
            val request = CurrentLocationRequest.Builder()
                .setPriority(Priority.PRIORITY_HIGH_ACCURACY)
                .setMaxUpdateAgeMillis(10_000) // Accept 10s old location
                .build()

            fusedLocationClient.getCurrentLocation(request, null)
                .addOnSuccessListener { location ->
                    continuation.resume(location)
                }
                .addOnFailureListener { exception ->
                    continuation.resumeWithException(exception)
                }
        }
    }
}
```

Priority Levels Explained

Priority	Accuracy	Battery	Use Case
HIGH_ACCURACY	~10m	High	Navigation, Photo geotagging
BALANCED_POWER_ACCURACY	~100m	Medium	City-level apps
LOW_POWER	~1km	Low	Background tracking
PASSIVE	Varies	None	Opportunistic updates

```
// For photo geotagging, we want high accuracy  
.setPriority(Priority.PRIORITY_HIGH_ACCURACY)
```

Coordinate Validation: Null Island

Problem: GPS can return (0.0, 0.0) as an error state.

```
//utils/CoordinateValidator.kt
fun validate(latitude: Double, longitude: Double): ValidationResult {
    // Check for NaN/Infinity
    if (latitude.isNaN() || longitude.isNaN()) {
        return ValidationResult.NotANumber
    }

    // Latitude: -90 to +90
    if (latitude < -90.0 || latitude > 90.0) {
        return ValidationResult.InvalidLatitude(latitude)
    }

    // Longitude: -180 to +180
    if (longitude < -180.0 || longitude > 180.0) {
        return ValidationResult.InvalidLongitude(longitude)
    }

    // "Null Island" check (0,0 is suspicious)
    if (latitude == 0.0 && longitude == 0.0) {
        return ValidationResult.SuspiciousNullIsland
    }

    return ValidationResult.Valid
}
```

API Key Configuration

Step 1: local.properties (NEVER commit!)

```
MAPS_API_KEY=AIzaSy...your_key_here
```

Step 2: build.gradle.kts

```
val localProperties = Properties()
localProperties.load(rootProject.file("local.properties").InputStream())

android {
    defaultConfig {
        manifestPlaceholders["MAPS_API_KEY"] =
            localProperties.getProperty("MAPS_API_KEY") ?: ""
    }
}
```

Step 3: AndroidManifest.xml

```
<meta-data  
    android:name="com.google.android.geo.API_KEY"  
    android:value="${MAPS_API_KEY}" />
```

ViewModel: Reactive Map State

```
//ui/viewmodel/MapViewModel.kt
class MapViewModel(private val repository: SpotRepository) : ViewModel() {

    private val _userLocation = MutableStateFlow<LatLng?>(null)
    val userLocation = _userLocation.asStateFlow()

    // Flow from Room, converted to StateFlow
    val spots: StateFlow<List<SpotEntity>> = repository.getAllSpots()
        .stateIn(
            scope = viewModelScope,
            started = SharingStarted.WhileSubscribed(5000),
            initialValue = emptyList()
        )

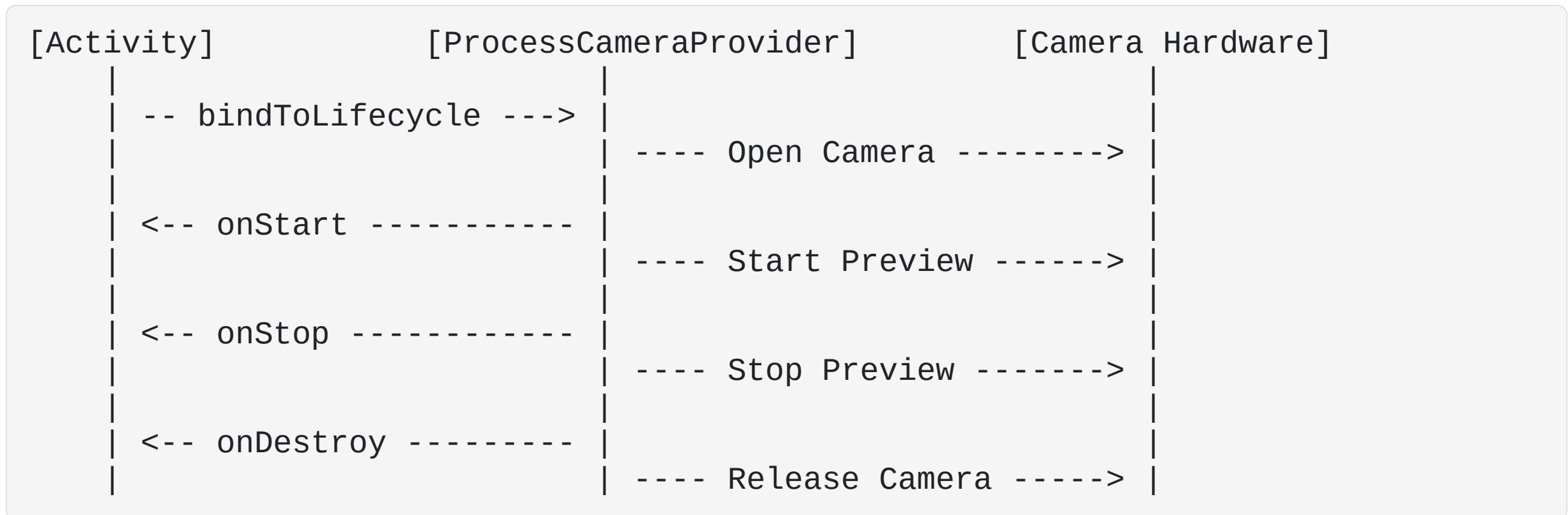
    fun loadUserLocation() {
        viewModelScope.launch {
            repository.getCurrentLocation()?.let { location ->
                _userLocation.value = LatLng(location.latitude, location.longitude)
            }
        }
    }
}
```

5. Deep Dive

Under the Hood

1. CameraX: ProcessCameraProvider Lifecycle

How does CameraX manage camera resources?



CameraX observes the LifecycleOwner and manages camera open/close automatically.

2. suspendCancellableCoroutine Internals

How do we convert callbacks to coroutines?

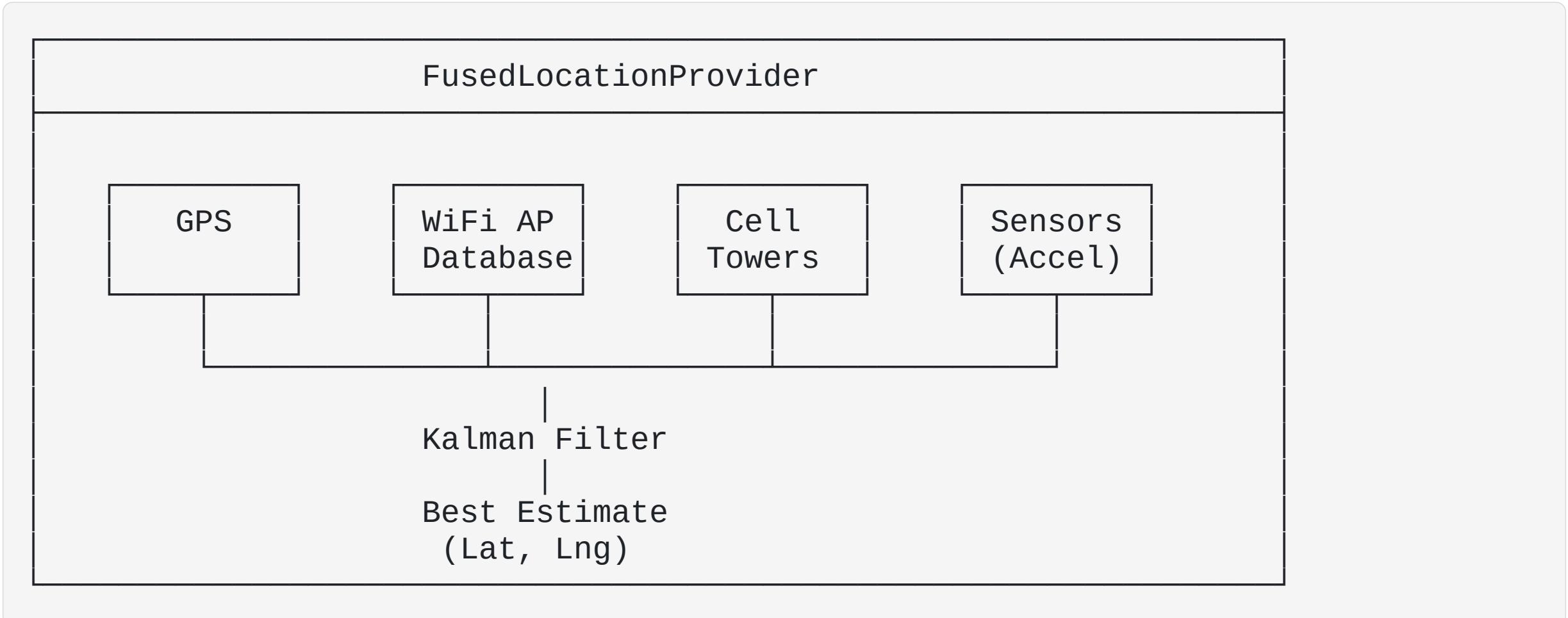
```
suspend fun example(): Result = suspendCancellableCoroutine { continuation ->
    // 1. Coroutine is SUSPENDED here

    asyncOperation(
        onSuccess = { result ->
            // 2. Resume the coroutine with result
            continuation.resume(result)
        },
        onError = { error ->
            // 2b. Or resume with exception
            continuation.resumeWithException(error)
        }
    )

    // 3. Handle cancellation
    continuation.invokeOnCancellation {
        // Clean up resources if coroutine is cancelled
        cancelAsyncOperation()
    }
}
```

3. FusedLocationProvider: Sensor Fusion

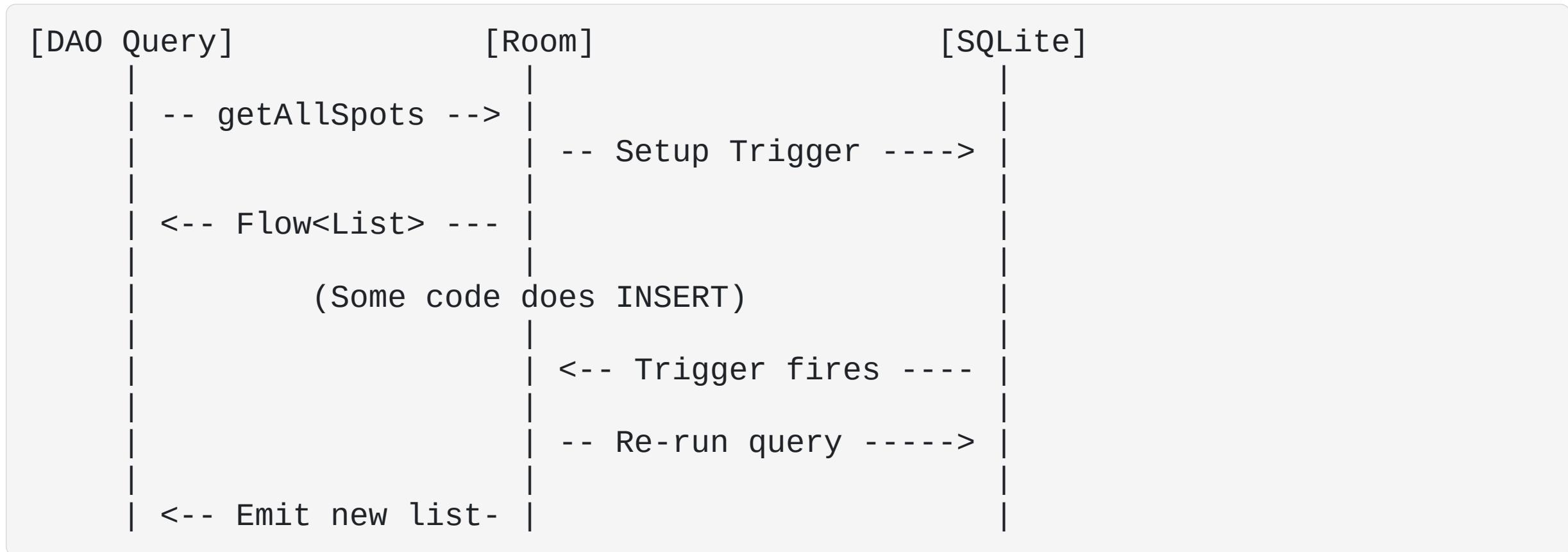
How does "Fused" location work?



It combines multiple signals to get the best accuracy with optimal battery.

4. Room + Flow: Invalidation Tracker

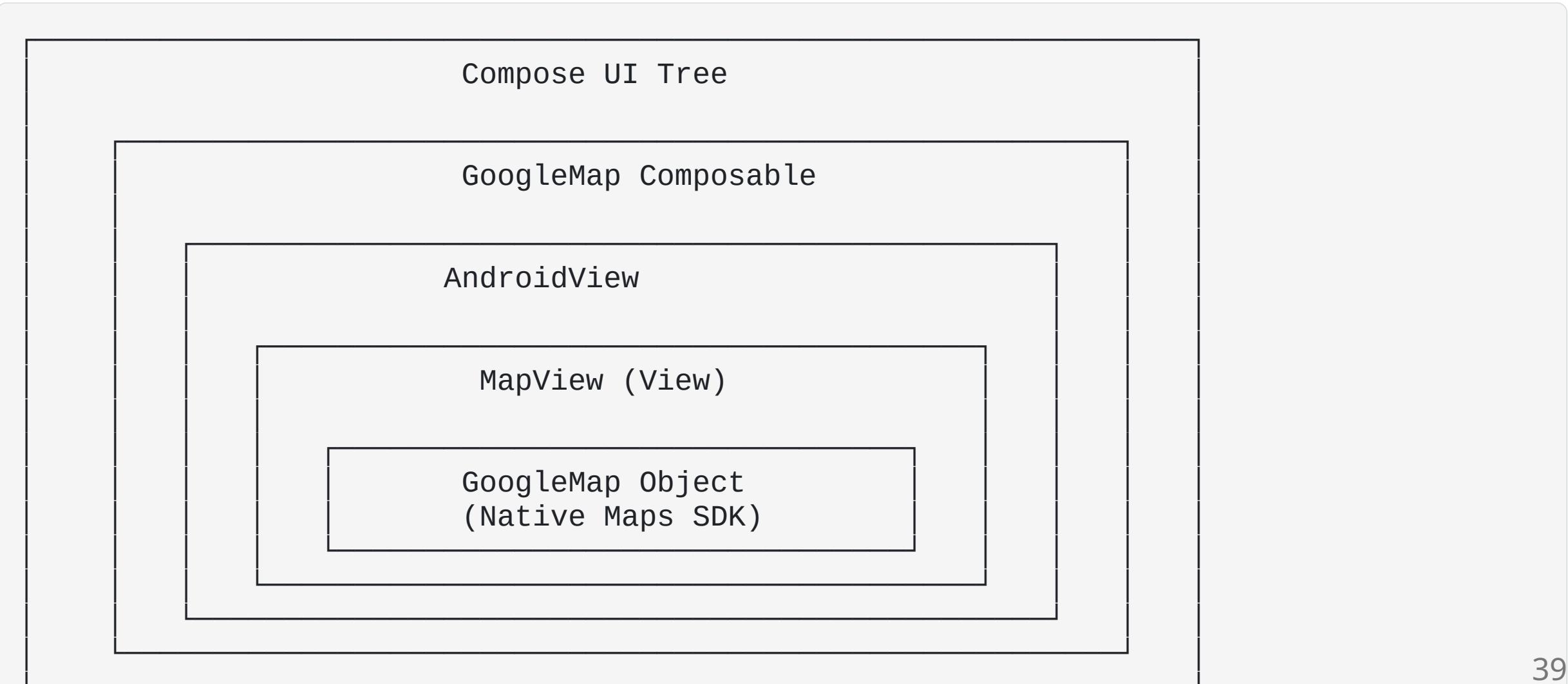
How does `Flow<List<Spot>>` update automatically?



Room's `InvalidationTracker` listens for table changes and re-queries.

5. Maps Compose: Interop Architecture

How does GoogleMap work inside Compose?



6. Challenge Lab

Practice & Application

Part 1: Granular Error Handling

Context:

The app currently shows generic errors when photo capture fails. Users don't know if the problem is the camera, storage, or permissions.

Your Task:

Implement typed error handling for `camerautils.capturePhoto()` that distinguishes between:

- Camera was closed unexpectedly
- Capture failed (hardware issue)
- File I/O error (storage full or permissions)

Files to Modify:

- utils/CameraUtils.kt
- repository/SpotRepository.kt (CreateSpotResult)
- ui/screens/CameraScreen.kt

Part 1: Definition of Done

Criteria	Description
Sealed class exists	<code>CaptureError</code> sealed class with 3+ error types
Errors are mapped	<code>ImageCaptureException.imageCaptureError</code> codes mapped to sealed class
Repository updated	<code>createSpotResult</code> has new <code>PhotoCaptureFailed</code> case
UI shows specific messages	Each error type displays a different user-friendly message
No crashes	App handles all error cases gracefully

Part 2: Spot Deletion Feature

Context:

Users can create spots but cannot delete them. We need to add deletion with proper cleanup.

Your Task:

Implement spot deletion that:

- Triggers on long-press of a map marker
- Shows a confirmation dialog before deleting
- Removes the spot from Room database
- Deletes the associated photo file from internal storage

Files to Modify:

- data/dao/SpotDao.kt
- repository/SpotRepository.kt
- ui/screens/MapScreen.kt
- ui/viewmodel/MapViewModel.kt

Part 2: Definition of Done

Criteria	Description
DAO method exists	<code>deleteSpot(id: Long)</code> query in SpotDao
Repository coordinates	Deletes from DB AND deletes photo file
Long-press triggers dialog	Marker info window responds to long-press
Confirmation dialog	AlertDialog asks "Are you sure?" before deletion
File cleanup	Photo file is deleted from <code>filesDir</code>
UI updates automatically	Map removes marker after deletion (Flow reactivity)
Edge cases handled	Graceful handling if file doesn't exist

Resources & Wrap-up

Resources

Repository Pattern	CameraX	Google Maps SDK
Guide to App Architecture	CameraX Overview	Maps SDK for Android
Data Layer Guide	CameraX Codelab	Maps Compose Library
Repository Pattern in Android	ImageCapture Use Case	FusedLocationProvider
Clean Architecture with MVVM	CameraX Architecture	Location Permissions
Testing Repositories	Camera Permissions Guide	Maps API Key Setup

Recommended Articles

CameraX

- [CameraX: Making Camera Development Easy](#) - Android Developers
- [Building a Camera App with CameraX](#) - ProAndroidDev
- [Migrating from Camera2 to CameraX](#) - Android Developers

Maps & Location

- [Google Maps Compose Under the Hood](#) - Android Developers
- [Best Practices for Location](#) - ProAndroidDev
- [Battery-Efficient Location Updates](#) - Android Developers