Octoprint on Linux

Change everything in RED to your username. Everything in BOLD copy and run in the terminal, everything in *italics*, copy and paste into config files.

FInd the IP address of the server:
Ifconfig -a

Update your server software to the newest version and reboot:
sudo apt update
sudo apt upgrade

sudo reboot now

cd ~
sudo apt install python-pip python-dev python-setuptools python-virtualenv git libyaml-dev build-essential
mkdir OctoPrint && cd OctoPrint
virtualenv venv
source venv/bin/activate
pip install pip --upgrade
pip install https://get.octoprint.org/latest
sudo usermod -a -G tty chris
sudo usermod -a -G dialout chris
~/OctoPrint/venv/bin/octoprint serve

Now test to make sure you can get to octoprint on the server, use your IP in a browser:
http://192.168.1.5:5000

Now we need to make it so Octoprint starts up after reboot:

wget https://github.com/foosel/OctoPrint/raw/master/scripts/octoprint.init && sudo mv octoprint.init /etc/init.d/octoprint

wget https://github.com/foosel/OctoPrint/raw/master/scripts/octoprint.default && sudo mv octoprint.default /etc/default/octoprint

sudo chmod +x /etc/init.d/octoprint

Edit the user and remove comments in the default file:
sudo nano /etc/default/octoprint

 # Configuration for /etc/init.d/octoprint

 # The init.d script will only run if this variable non-empty.
OCTOPRINT_USER=chris

 # base directory to use
BASEDIR=/home/chris/.octoprint

 # configuration file to use
CONFIGFILE=/home/chris/.octoprint/config.yaml

 # On what port to run daemon, default is 5000
PORT=5000

 # Path to the OctoPrint executable, you need to set this to match your installation!
DAEMON=/home/chris/OctoPrint/venv/bin/octoprint

 # What arguments to pass to octoprint, usually no need to touch this
DAEMON_ARGS="--port=$PORT"

 # Umask of files octoprint generates, Change this to 000 if running octoprint as its own, separate user
UMASK=022

 # Process priority, 0 here will result in a priority 20 process.
 # -2 ensures Octoprint has a slight priority over user processes.
NICELEVEL=-2

 # Should we run at startup?
START=yes

Add default to autostart:
sudo update-rc.d octoprint defaults

Check octoprint service status with:
sudo service octoprint status

Add your users to sudoers file so it can run shutdown commands:
sudo nano /etc/sudoers.d/octoprint-shutdown

chris ALL=NOPASSWD: /sbin/shutdown

Install haproxy:
sudo apt install haproxy

Make a copy of the haproxy config file and remove it:
sudo cp /etc/haproxy/haproxy.cfg /etc/haproxy/haproxy.cfg_old
sudo rm /etc/haproxy/haproxy.cfg

Paste this config into the haproxy file:
sudo nano /etc/haproxy/haproxy.cfg

global
    maxconn 4096

```
    user haproxy
    group haproxy
    daemon
    log 127.0.0.1 local0 debug

defaults
    log     global
    mode    http
    option  httplog
    option  dontlognull
    retries 3
    option redispatch
    option http-server-close
    option forwardfor
    maxconn 2000
    timeout connect 5s
    timeout client  15min
    timeout server  15min

frontend public
    bind :::80 v4v6
    use_backend webcam if { path_beg /webcam/ }
    default_backend octoprint

backend octoprint
    reqrep ^([^\ :]*)\ /(.*)     \1\ /\2
    option forwardfor
    server octoprint1 127.0.0.1:5000

backend webcam
    reqrep ^([^\ :]*)\ /webcam/(.*)     \1\ /\2
    server webcam1  127.0.0.1:8080
```

Enable haproxy:

sudo nano /etc/default/haproxy

 # Defaults file for HAProxy
#
 # This is sourced by both, the initscript and the systemd unit file, so do not
 # treat it as a shell script fragment.

 # Change the config file location if needed
#CONFIG="/etc/haproxy/haproxy.cfg"

 # Add extra flags here, see haproxy(1) for a few options
#EXTRAOPTS="-de -m 16"
ENABLE=1

Check haproxy:
sudo service haproxy status

Restart haproxy just in case:
sudo service haproxy restart

Now we install webcam support:
cd ~
sudo apt install subversion libjpeg8-dev imagemagick ffmpeg libv4l-dev cmake
git clone https://github.com/jacksonliam/mjpg-streamer.git
cd mjpg-streamer/mjpg-streamer-experimental
export LD_LIBRARY_PATH=.
make

Test mjpg streamer:
sudo ./mjpg_streamer -i "./input_uvc.so" -o "./output_http.so"

Create webcam startup scripts don’t use sudo:

cd ~
mkdir scripts
nano /home/chris/scripts/webcam

```
#!/bin/bash
# Start / stop streamer daemon

case "$1" in
    start)
        /home/chris/scripts/webcamDaemon >/dev/null 2>&1 &
        echo "$0: started"
        ;;
    stop)
        pkill -x webcamDaemon
        pkill -x mjpg_streamer
        echo "$0: stopped"
        ;;
    *)
        echo "Usage: $0 {start|stop}" >&2
        ;;
esac
```

Create webcam Daemon script don't use sudo:
nano /home/chris/scripts/webcamDaemon

```
#!/bin/bash

MJPGSTREAMER_HOME=/home/chris/mjpg-streamer/mjpg-streamer-experimental
MJPGSTREAMER_INPUT_USB="input_uvc.so"
MJPGSTREAMER_INPUT_RASPICAM="input_raspicam.so"

# init configuration
camera="auto"
camera_usb_options="-r 640x480 -f 10"
camera_raspi_options="-fps 10"

if [ -e "/boot/octopi.txt" ]; then
    source "/boot/octopi.txt"
fi

# runs MJPG Streamer, using the provided input plugin + configuration
function runMjpgStreamer {
    input=$1
    pushd $MJPGSTREAMER_HOME
    echo Running ./mjpg_streamer -o "output_http.so -w ./www" -i "$input"
    LD_LIBRARY_PATH=. ./mjpg_streamer -o "output_http.so -w ./www" -i "$input"
    popd
}

# starts up the RasPiCam
function startRaspi {
    logger "Starting Raspberry Pi camera"
    runMjpgStreamer "$MJPGSTREAMER_INPUT_RASPICAM $camera_raspi_options"
}

# starts up the USB webcam
function startUsb {
```

```
    logger "Starting USB webcam"
    runMjpgStreamer "$MJPGSTREAMER_INPUT_USB $camera_usb_options"
}

# we need this to prevent the later calls to vcgencmd from blocking
# I have no idea why, but that's how it is...
vcgencmd version

# echo configuration
echo camera: $camera
echo usb options: $camera_usb_options
echo raspi options: $camera_raspi_options

# keep mjpg streamer running if some camera is attached
while true; do
    if [ -e "/dev/video0" ] && { [ "$camera" = "auto" ] || [ "$camera" = "usb" ] ; }; then
        startUsb
    elif [ "`vcgencmd get_camera`" = "supported=1 detected=1" ] && { [ "$camera" = "auto" ] || [ "$camera" = "raspi" ] ; }; then
        startRaspi
    fi

    sleep 120
done
```

Edit webcam file startup permissions:
sudo chmod +x /home/chris/scripts/webcam
sudo chmod +x /home/chris/scripts/webcamDaemon

Add webcams to startup:
sudo nano /etc/rc.local

#!/bin/sh -e
#
 # rc.local
#
 # This script is executed at the end of each multiuser runlevel.
 # Make sure that the script will "" on success or any other
 # value on error.
#
 # In order to enable or disable this script just change the execution
 # bits.
#
 # By default this script does nothing.

/home/chris/scripts/webcam start

exit 0

Start webcam:
sudo /home/chris/scripts/webcam start

Change rc.local permissions:
sudo chmod +x /etc/rc.local

Install avahi:
sudo apt install avahi-daemon

Edit hostname file with server name:
sudo nano /etc/hostname

Edit hosts:
sudo nano /etc/hosts

127.0.0.1 localhost.localdomain localhost
::1 localhost6.localdomain6 localhost6

 # The following lines are desirable for IPv6 capable hosts
::1 localhost ip6-localhost ip6-loopback
fe00::0 ip6-localnet
ff02::1 ip6-allnodes
ff02::2 ip6-allrouters
ff02::3 ip6-allhosts

127.0.1.1 octolinux

Now reboot:
sudo reboot now

Shutdown commands:

Restart OctoPrint: sudo service octoprint restart
Restart system: sudo shutdown -r now
Shutdown system: sudo shutdown -h now

Webcam links:

Stream URL: /webcam/?action=stream
Snapshot URL: http://127.0.0.1:8080/?action=snapshot
Path to FFMPEG: /usr/bin/ffmpeg

Install linux desktop if you would like one:
sudo apt-get install ubuntu-desktop