

1 Introduction

- Adhesive Bonding Technology as a Key to Multi-Materialization
- Theoretical Models for Rubber
- Objectives

2 Simulation

- Generation Recipe of Random Networks
- Phantom and KG Chains as Strands
- Simulation Conditions

3 Results

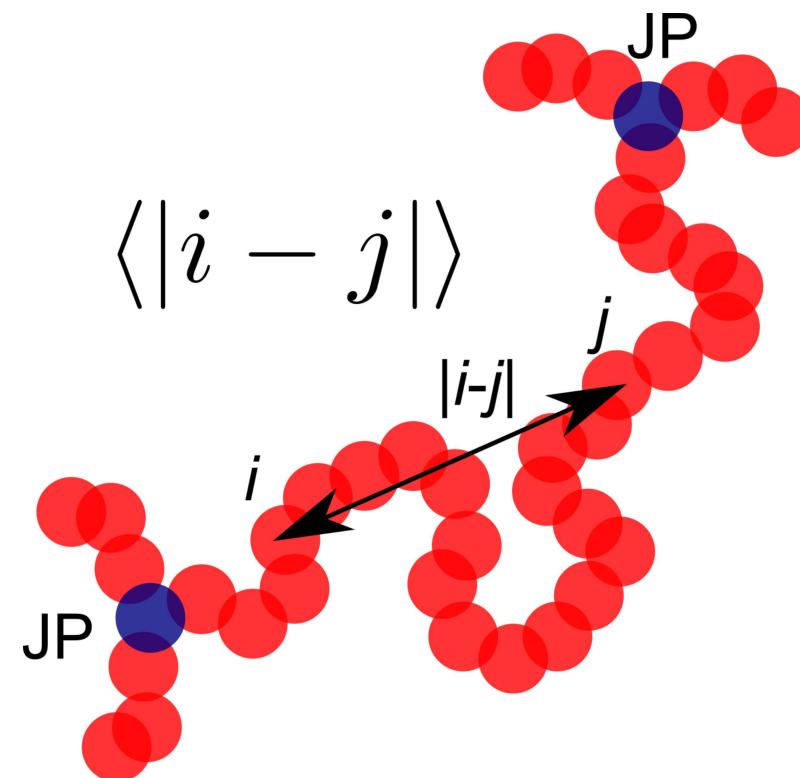
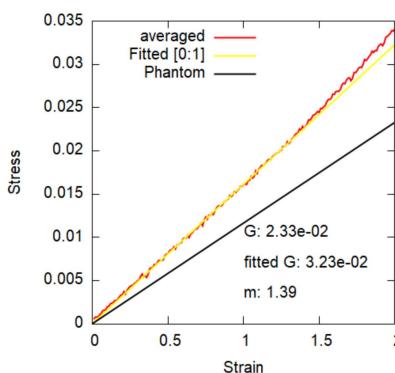
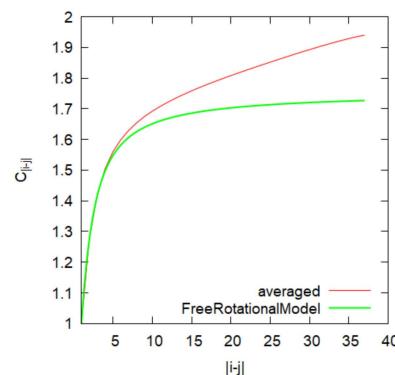
- Networks with Phantom Chains
- KG Chain Networks
- Relaxation in KG Networks

Phantom Chain NW ($f=4$, $N=36$)

- Strand-length is set to Equilibrated length ($N=36$)
- Multiplicity is 3 to keep $\rho = 0.85$

$N = 36$

Shrinkage = 1.0

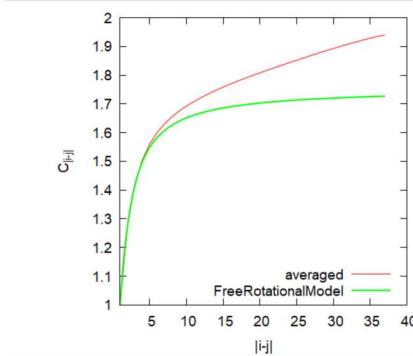


Strand length Effect for Phantom Chain NW

- Strand-length is varied from 36 to 48 for $f=4$
- System size is reduced to keep $\rho = 0.85$

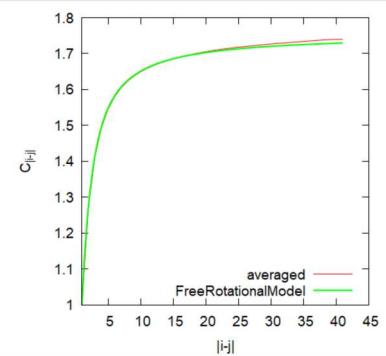
$N = 36$

Shrinkage = 1.0



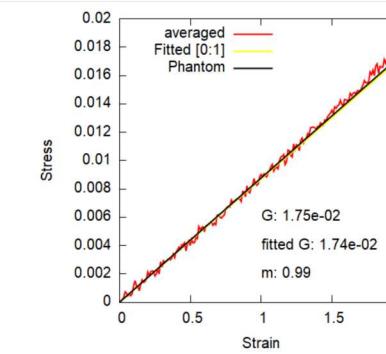
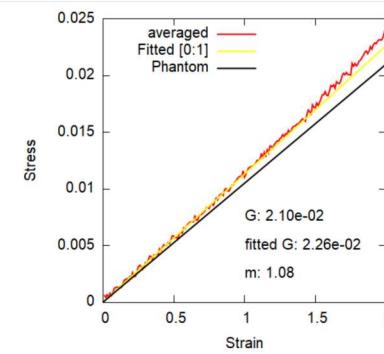
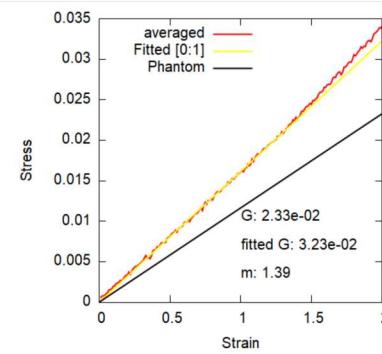
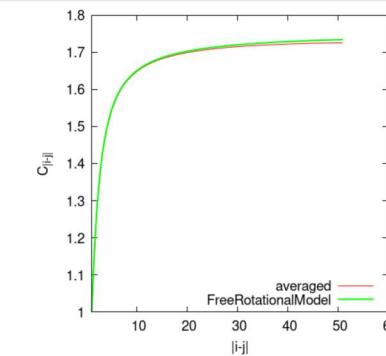
$N = 40$

Shrinkage = 0.89



$N = 48$

Shrinkage = 0.85



Strand Length Comparison for Shear Stress

Comparison of Functionality ($f = 3, 4, 6$)

For Varied Functionalities

- With proper strand length
- Modulus changed according to theory

$f = 3$

$N = 48$

multi = 4

$f = 4$

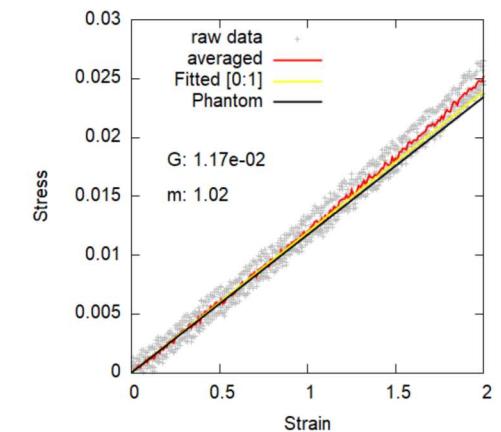
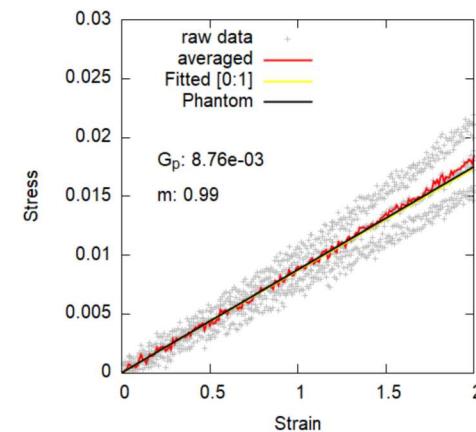
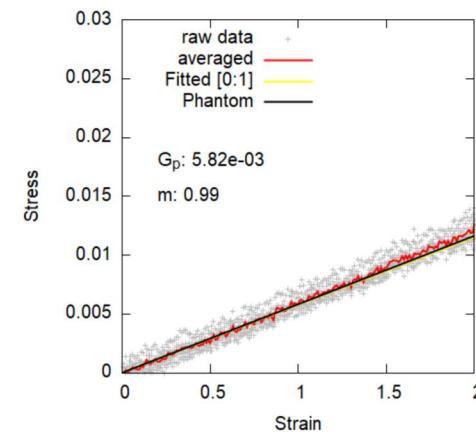
$N = 48$

multi = 3

$f = 6$

$N = 48$

multi = 2

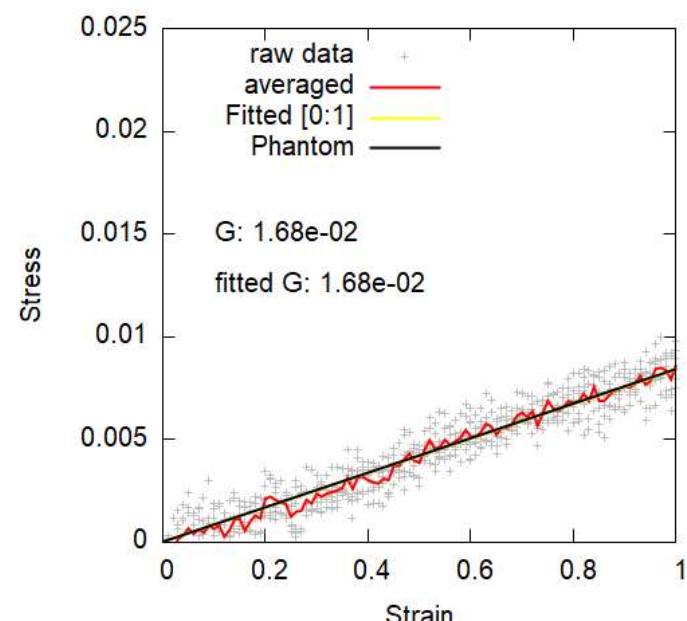


Mechanical Response for KG Chains($f=4$, $N=48$)

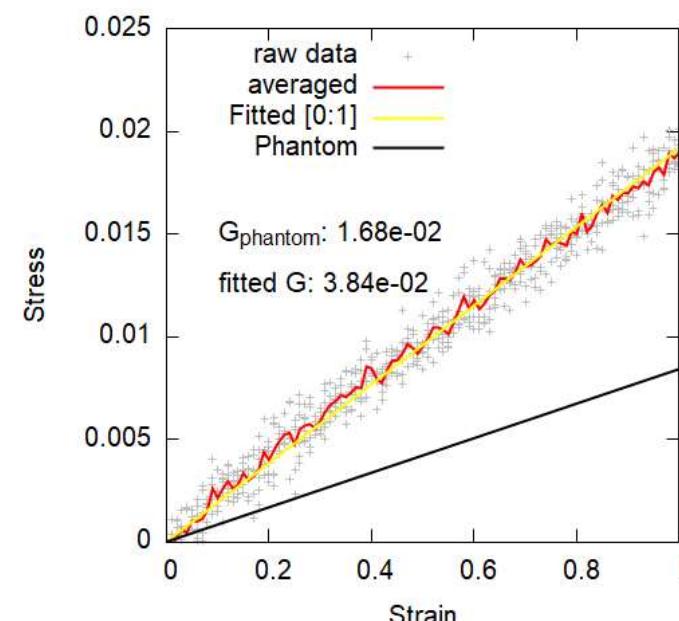
4-Chain Random Network with KG Chain

- Excluded Volume Effect by non-bonding LJ Potential.
- No strands mutual crossing by FENE bond.

Phantom Chain



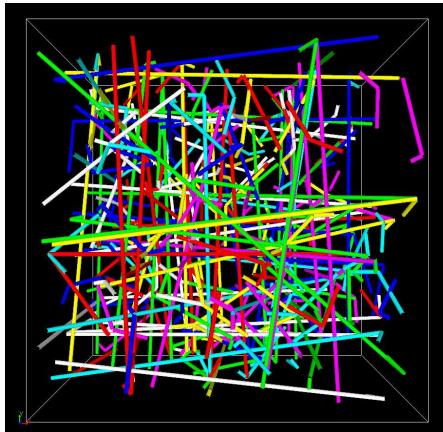
KG Chain



Reduced Entanglements by NPT Model

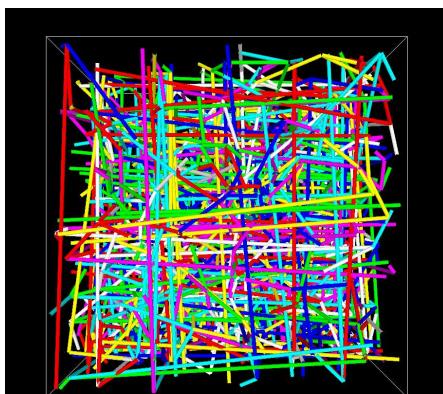
- 4-Chain-NPT

$$\langle Z \rangle_{Z_1} = 0.36$$



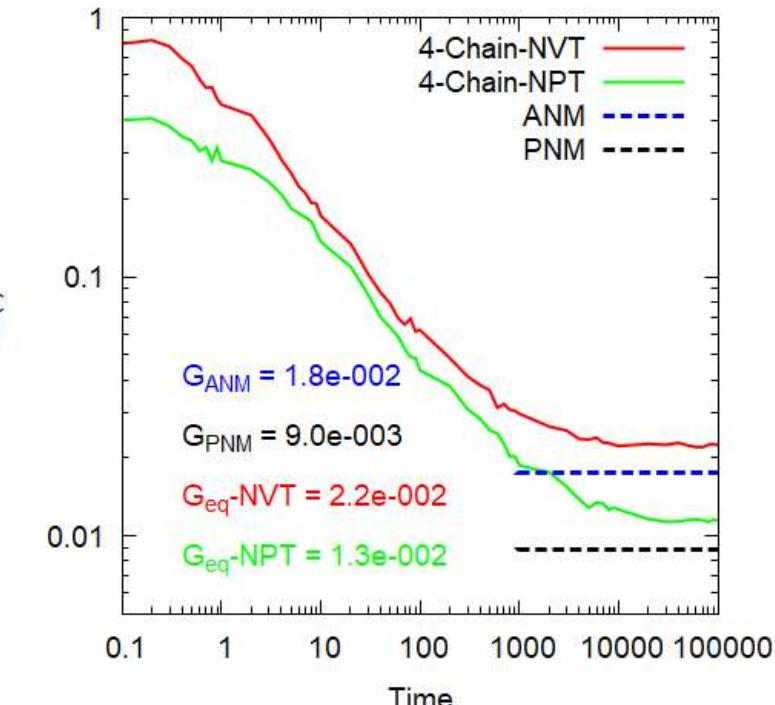
- 4-Chain-NVT

$$\langle Z \rangle_{Z_1} = 1.04$$



$G(t)$

- Step Deformation ($\lambda = 2.0$)
- Reduced Modulus



Entanglement effect in Slip-tube Model

Entanglement in Slip-tube Model

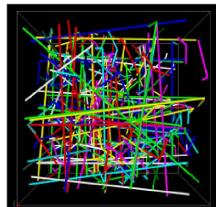
Theoretical model by Rubinstein^a

$$G_c = \nu k_B T \left(1 - \frac{2}{\phi} \right), \quad G_e = \frac{4}{7} \nu k_B T L$$

and L is the number of slip-links per network chain

^aM. Rubinstein, S. Panyukov, Macromolecules, 35, 6670 (2002)

NPT
(less Entglid.)



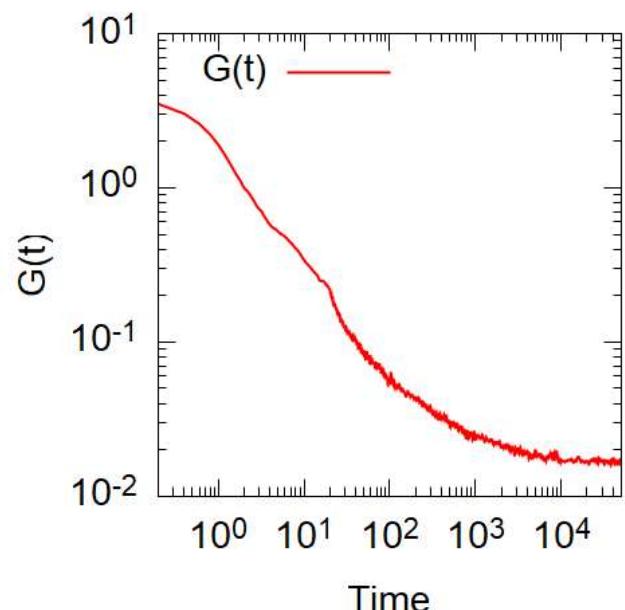
NVT
(well Entglid.)



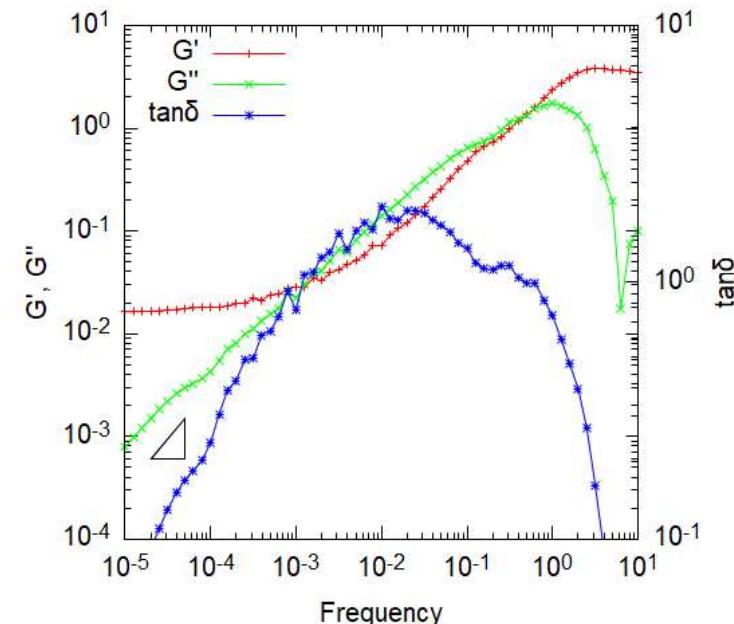
	Ensemble	NPT	NVT
Chains, ν		768, 0.018	
$G_c = \nu \times (1 - 2/4)$		0.009	
Entanglements	278	800	
Entangled Chains	249	557	
L	278/768=0.36	800/768=1.04	
$G_e = 4/7 \times \nu \times L$	0.004	0.011	
$G_{calcd.} = G_c + G_e$	0.013	0.020	
$G_{measd.}$	0.013	0.022	

$G(t)$ for Step Shear and Dynamic Rheo-Spectrum

$G(t)$ for Step Stretch



Dynamic Viscoelastics

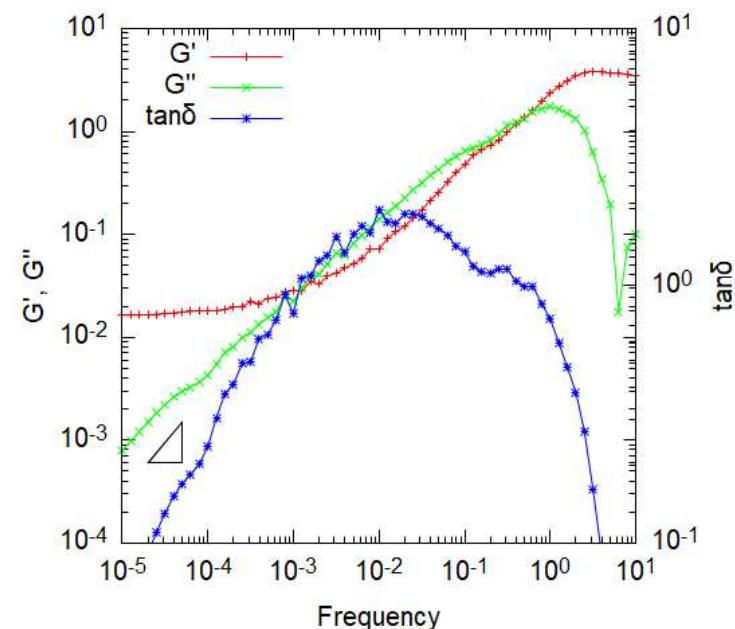


Conditions

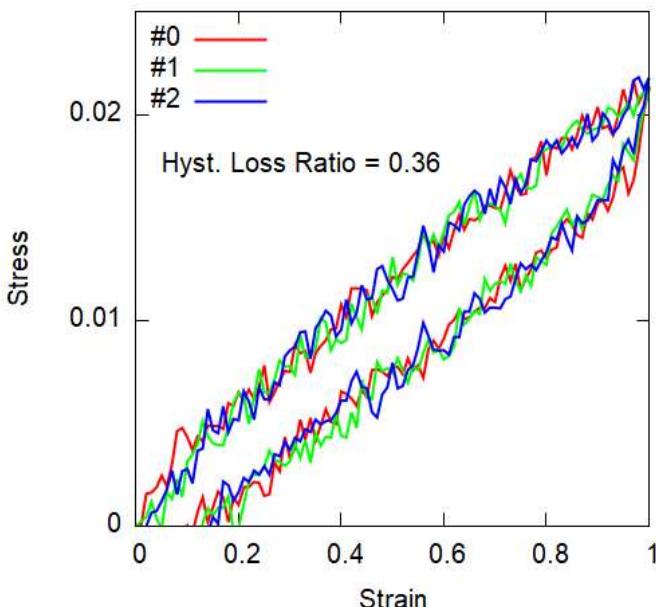
- 4-Chain KG-NW($N=50$)
- Step Stretch: $\lambda = 2$
- $G(t)$ is transformed to Dynamic Viscoelastic Spectrum

Mechanical Hysteresis Loss

Dynamic Viscoelastics



Hysteresis by Cyclic Shear



Conditions

- 4-Chain KG-NW($N=50$)
- Cyclic Shear: $\gamma = 1$, $\dot{\gamma} = 5e^{-5}$

ストランドの最長緩和時間

最長緩和時間 (τ) を評価

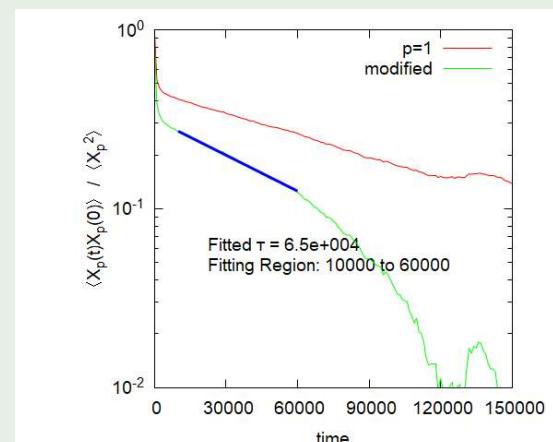
- ストランドのラウスモード ($p=1$) の自己相関関数 $C_p(t)$

$$C_p(t) = \langle X_p(t)X_p(0) \rangle / \langle X_p^2 \rangle$$

- 相関関数の振る舞い
 - 長時間極限で一定値に収束
 - 空間的な拘束のため
 - $C_p(\infty)$ を差し引いて評価

$$\tau \simeq 6.5e^4$$

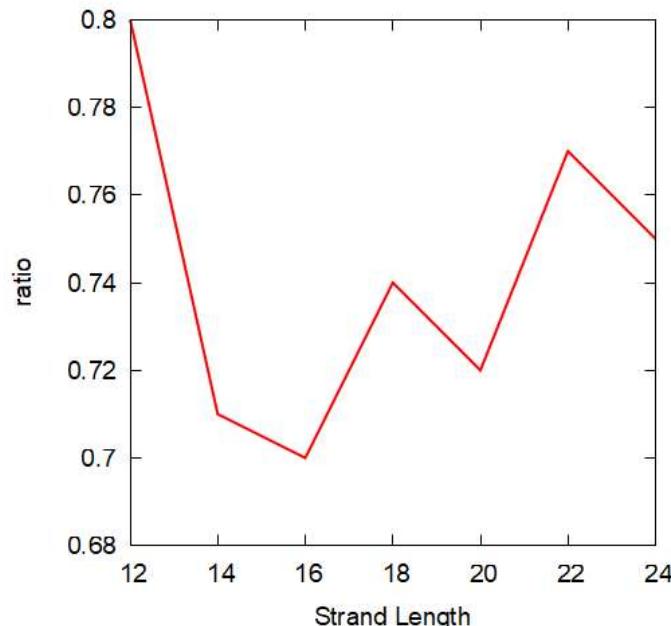
ヒステリシスロスが消失する変形速度 ($\sim 1e^{-5}$) と対応



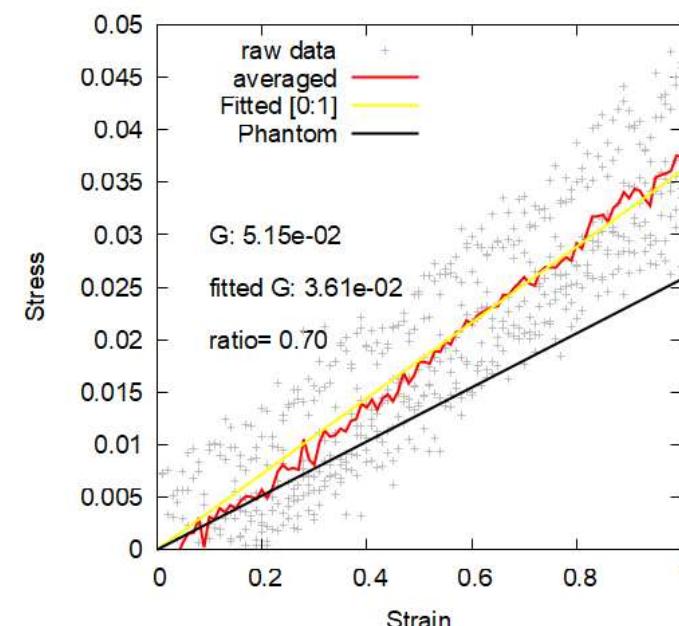
$C_{p1}(t)$ for equilibrated structure

Effect of Strand Length for Shorter KG Chain

- For Phantom Chain
 - Longer Strand resulted in lower Modulus
- KG Chain
 - Proper Length was found for Low Modulus
 - which implies proper restriction for JP



Strand Length vs. Modulei ratio



Shear Stress for $N=16$

Conclusions

- Introducing random connectivity, MD simulation studies were carried out.
- To investigate the criteria for Phantom Network Model, Two model chains are used.
 - Employing phantom chain, basics for PNM is examined.
 - Proper strand length is the key for PNM.
 - Functionality effect was confirmed.
 - Changing the chain to KG Chain, constraints effects are investigated.
 - Trapped Entanglement was explained by Slip-tube Model
 - Hysteresis