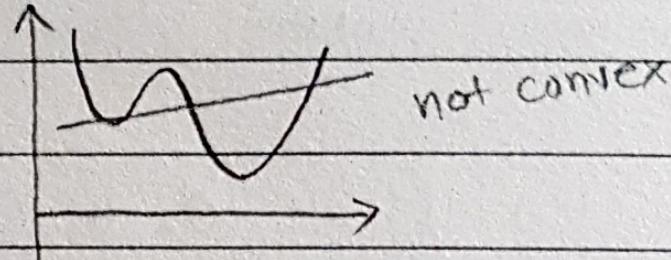
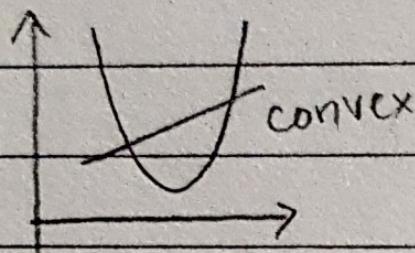


Date

Convex Function

When any line segment drawn between two points on the function lies above or on the function and the min. value occurs at a single point (one global minima)



e.g. $f(x) = \frac{1}{x}$ $x > 0$

$$f(x) = -\sqrt{x} \quad x \geq 0$$

$$y = \theta_0 + \theta_1 x$$

x	y
0.80581147	2.27515993
0.38348503	-0.15308204
0.6652413	1.43590601
0.64155897	0.79686399
0.24070017	-0.45275524
0.35429554	2.03862963
0.70827991	1.16148089
0.32378987	2.68814558
0.8108774	0.70110376
0.22902348	0.04881045

$$h_0(x) = \alpha_0 + \alpha_1 x$$

$$J(\alpha_0, \alpha_1) = \frac{1}{2m} \sum_{i=1}^m (h_0(x_{1i}) - y_i)^2$$

$$m = \text{len}(x)$$

$$m = 10$$

$$J(\alpha_0, \alpha_1) = \frac{1}{2m} \left[(\alpha_0 + 0.805811\alpha_1 - 2.27515)^2 + (\alpha_0 + 0.383485\alpha_1 + 0.15308)^2 + (\alpha_0 + 0.66524\alpha_1 - 1.43590)^2 + (\alpha_0 + 0.641559\alpha_1 - 0.79686)^2 + (\alpha_0 + 0.24070\alpha_1 + 0.45275)^2 + (\alpha_0 + 0.35429\alpha_1 - 2.03863)^2 + (\alpha_0 + 0.70828\alpha_1 - 1.16148)^2 + (\alpha_0 + 0.32379\alpha_1 - 2.68814)^2 + (\alpha_0 + 0.87087\alpha_1 - 0.701103)^2 + (\alpha_0 + 0.22902\alpha_1 - 0.048810)^2 \right]$$

(convex function)

$$\frac{\partial J}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m + (h_\theta(x_{2i}) - y_i) \quad \theta_0 = \theta_0 - \alpha \frac{\partial J}{\partial \theta_0}$$

\sum cuz $\theta_0 = 1$

$$\frac{\partial J}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m + x_i (h_\theta(x_{2i}) - y_i) \quad \theta_1 = \theta_1 - \alpha \frac{\partial J}{\partial \theta_1}$$

$$\begin{aligned} \frac{\partial J}{\partial \theta_0} &= \frac{1}{10} \left[+ (\theta_0 + \theta_1(0.805811) - 2.2775) + (\theta_0 + 0.38348\theta_1 + 0.15308) \right. \\ &\quad + (\theta_0 + 0.66524\theta_1 - 1.43590) + (\theta_0 + 0.641559\theta_1 - 0.79682) \\ &\quad + (\theta_0 + 0.24070\theta_1 + 0.45275) + (\theta_0 + 0.35429\theta_1 - 2.03863) \\ &\quad + (\theta_0 + 0.70828\theta_1 - 1.16148) + (\theta_0 + 0.32379\theta_1 - 2.68814) \\ &\quad \left. + (\theta_0 + 0.87087\theta_1 - 0.701103) + (\theta_0 + 0.22902\theta_1 - 0.048810) \right] \end{aligned}$$

$$\begin{aligned} \frac{\partial J}{\partial \theta_1} &= \frac{1}{10} \left[+ (0.805811(\theta_0 + \theta_1(0.805811) - 2.2775)) + (0.38348(\theta_0 + 0.38348\theta_1 + 0.15308)) \right. \\ &\quad + (0.66524(\theta_0 + 0.66524\theta_1 - 1.43590)) + (0.641559(\theta_0 + 0.641559\theta_1 - 0.79682)) \\ &\quad + (0.24070(\theta_0 + 0.24070\theta_1 + 0.45275)) + (0.35429(\theta_0 + 0.35429\theta_1 - 2.03863)) \\ &\quad + (0.70828(\theta_0 + 0.70828\theta_1 - 1.16148)) + (0.32379(\theta_0 + 0.32379\theta_1 - 2.68814)) \\ &\quad \left. + (0.87087(\theta_0 + 0.87087\theta_1 - 0.701103)) + (0.22902(\theta_0 + 0.22902\theta_1 - 0.048810)) \right] \end{aligned}$$

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	tetha0	tetha1	J	$Q_0 + Q_1 \chi$
1	0	0	1.066335	
2	0.737818	0.431844	0.491165	
3	0.801275	0.495645	0.484387	
4	0.796986	0.521724	0.483450	

First iteration

initially,

$$\theta_0 = 0$$

$$\theta_1 = 0.$$

$$m = \text{len}(x)$$

$$m = 10.$$

$$J(0, 0) = 1.066335.$$

$$\frac{\partial J}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m + (h_\theta(x_i) - y_i)$$

$$\text{at } (0, 0),$$

$$\frac{\partial J}{\partial \theta_0} = -1.054026$$

$$\frac{\partial J}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m + x_i (h_\theta(x_i) - y_i)$$

$$\text{at } (0, 0),$$

$$\frac{\partial J}{\partial \theta_1} = -0.616920.$$

$$\underline{\text{new } \theta_0} = \theta_0 - \alpha * \frac{\partial J}{\partial \theta_0}$$

$$\theta_0 = 0 - 0.7 * -1.054026.$$

$$\theta_0 = 0.737818$$

$$\underline{\text{new } \theta_1} = \theta_1 - \alpha * \frac{\partial J}{\partial \theta_1}$$

$$\underline{\theta_1} = 0 - 0.7 * -0.616920.$$

$$\theta_1 = 0.431844.$$

$$J(0.737818, 0.431844) = 0.491165.$$

Second iteration

initially,

$$\theta_0 = 0.737818$$

$$\theta_1 = 0.431844$$

at which the cost is 0.491165.

at $(0.737818, 0.431844)$,

$$\frac{\partial J}{\partial \theta_0} = -0.090652$$

$$\frac{\partial J}{\partial \theta_1} = -0.091144$$

$$\text{new } \theta_0 = \theta_0 - \alpha * \frac{\partial J}{\partial \theta_0}$$

$$\theta_0 = 0.737818 - 0.7 * (-0.090652)$$

$$\theta_0 = 0.801275$$

$$\text{new } \theta_1 = \theta_1 - \alpha * \frac{\partial J}{\partial \theta_1}$$

$$\theta_1 = 0.431844 - 0.7 * (-0.091144)$$

$$\theta_1 = 0.495645$$

$$J(0.801275, 0.495645) = 0.484387$$

Third iteration

initially,

$$\theta_0 = 0.801275.$$

$$\theta_1 = 0.495645.$$

at which the cost is 0.484387.

at $(0.801275, 0.495645)$,

$$\frac{\partial J}{\partial \theta_0} = 0.0061279.$$

$$\frac{\partial J}{\partial \theta_1} = -0.037256.$$

new $\theta_0 = \theta_0 - \alpha * \frac{\partial J}{\partial \theta_0}$

$$\theta_0 = 0.801275 - 0.7 * (0.0061279)$$

$$\theta_0 = 0.796985$$

new $\theta_1 = \theta_1 - \alpha * \frac{\partial J}{\partial \theta_1}$

$$\theta_1 = 0.495645 - 0.7 * (-0.037256)$$

$$\theta_1 = 0.521724.$$

$$J(0.796985, 0.521724) = 0.483450.$$