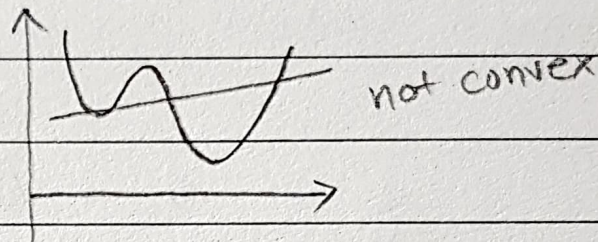
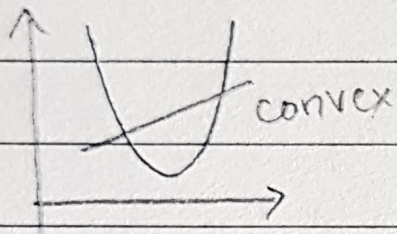


Convex Function

When any line segment drawn between two points on the function lies above or on the function and the min. value occurs at a single point (one global minima)



e.g. $f(x) = \frac{1}{x} \quad x > 0$

$f(x) = -\sqrt{x} \quad x \geq 0$

$y = \theta_0 + \theta_1 x$

x

y

0.80581147

2.27515993

0.38348503

-0.15308204

0.6652413

1.43590601

0.64155897

0.79686399

0.24070017

-0.45275524

0.35429554

2.03862963

0.70827991

1.16148089

0.32378987

2.68814558

0.8708774

0.70110376

0.22902348

0.04881045

$$h_0(x) = Q_0 + Q_1 x$$

$$J(Q_0, Q_1) = \frac{1}{2n} \sum_{i=1}^m (h_0(x_{1i}) - y_i)^2$$

$$m = \text{len}(x)$$

$$m = 10$$

$$J(Q_0, Q_1) = \frac{1}{2m} \left[\begin{aligned} &(Q_0 + 0.805811Q_1 - 2.27515)^2 + (Q_0 + 0.383485Q_1 + 0.15308)^2 \\ &+ (Q_0 + 0.66524Q_1 - 1.43590)^2 + (Q_0 + 0.641559Q_1 - 0.79686)^2 \\ &+ (Q_0 + 0.24070Q_1 + 0.45275)^2 + (Q_0 + 0.35429Q_1 - 2.03863)^2 \\ &+ (Q_0 + 0.70828Q_1 - 1.16148)^2 + (Q_0 + 0.32379Q_1 - 2.68814)^2 \\ &+ (Q_0 + 0.87087Q_1 - 0.701103)^2 + (Q_0 + 0.22902Q_1 - 0.048810)^2 \end{aligned} \right]$$

(convex function)

$$\frac{\partial J}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m - (h_{\theta}(x_{1i}) - y_i)$$

$$\theta_0 = \theta_0 - \alpha \frac{\partial J}{\partial \theta_0}$$

$$\frac{\partial J}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m - x_i (h_{\theta}(x_{1i}) - y_i)$$

$$\theta_1 = \theta_1 - \alpha \frac{\partial J}{\partial \theta_1}$$

$$\frac{\partial}{\partial Q_0} (J) = \frac{1}{10} \left[- (Q_0 + Q_1 (0.805811) - 2.27515) - (Q_0 + 0.38348 Q_1 + 0.15308) \right. \\
- (Q_0 + 0.66524 Q_1 - 1.43590) - (Q_0 + 0.641559 Q_1 - 0.79686) \\
- (Q_0 + 0.24070 Q_1 + 0.45275) - (Q_0 + 0.35429 Q_1 - 2.03863) \\
- (Q_0 + 0.70828 Q_1 - 1.16148) - (Q_0 + 0.32379 Q_1 - 2.68814) \\
\left. - (Q_0 + 0.87087 Q_1 - 0.701103) - (Q_0 + 0.22902 Q_1 - 0.048810) \right]$$

$$\frac{\partial}{\partial Q_1} (J) = \frac{1}{10} \left[- (0.805811 (Q_0 + Q_1 (0.805811) - 2.27515)) - (0.38348 (Q_0 + 0.38348 Q_1 + 0.15308)) \right. \\
- (0.66524 (Q_0 + 0.66524 Q_1 - 1.43590)) - (0.641559 (Q_0 + 0.641559 Q_1 - 0.79682)) \\
- (0.24070 (Q_0 + 0.24070 Q_1 + 0.45275)) - (0.35429 (Q_0 + 0.35429 Q_1 - 2.03863)) \\
- (0.70828 (Q_1 + 0.70828 Q_1 - 1.16148)) - (0.32379 (Q_0 + 0.32379 Q_1 - 2.68814)) \\
\left. - (0.87087 (Q_0 + 0.87087 Q_1 - 0.701103)) - (0.22902 (Q_0 + 0.22902 Q_1 - 0.048810)) \right]$$

#	tetha 0	tetha 1	J
1	0	0	1.066335
2	0.737818	0.431844	0.491165
3	0.801275	0.495645	0.484387
4	0.796986	0.521724	0.483450

First iteration

initially,

$$\theta_0 = 0$$

$$\theta_1 = 0.$$

$$m = \text{len}(x)$$

$$m = 10.$$

$$J(0, 0) = 1.066335.$$

$$\frac{\partial J}{\partial \theta_0} = \frac{1}{m} \sum_{i=1}^m - (h_{\theta}(x_{1i}) - y_i)$$

at $(0, 0)$,

$$\frac{\partial J}{\partial \theta_0} = -1.054026$$

$$\frac{\partial J}{\partial \theta_1} = \frac{1}{m} \sum_{i=1}^m - x_i (h_{\theta}(x_{1i}) - y_i)$$

at $(0, 0)$,

$$\frac{\partial J}{\partial \theta_1} = -0.616920.$$

$$\text{new } \theta_0 = \theta_0 - \alpha * \frac{\partial J}{\partial \theta_0}$$

$$\theta_0 = 0 - 0.7 * -1.054026.$$

$$\theta_0 = 0.737818$$

$$\text{new } \theta_1 = \theta_1 - \alpha * \frac{\partial J}{\partial \theta_1}$$

$$\theta_1 = 0 - 0.7 * -0.616920.$$

$$\theta_1 = 0.431844.$$

$$J(0.737818, 0.431844) = 0.491165.$$

second iteration

initially,

$$\alpha_0 = 0.737818$$

$$\alpha_1 = 0.431844$$

at which the cost is 0.491165

at $(0.737818, 0.431844)$,

$$\frac{\partial J}{\partial \alpha_0} = -0.090652$$

$$\frac{\partial J}{\partial \alpha_1} = -0.091144$$

$$\text{new } \alpha_0 = \alpha_0 - \alpha * \frac{\partial J}{\partial \alpha_0}$$

$$\alpha_0 = 0.737818 - 0.7 * (-0.090652)$$

$$\alpha_0 = 0.801275$$

$$\text{new } \alpha_1 = \alpha_1 - \alpha * \frac{\partial J}{\partial \alpha_1}$$

$$\alpha_1 = 0.431844 - 0.7 * (-0.091144)$$

$$\alpha_1 = 0.495645$$

$$J(0.801275, 0.495645) = 0.484387$$

Third iteration

initially,

$$\theta_0 = 0.801275.$$

$$\theta_1 = 0.495645.$$

at which the cost is 0.484387.

at $(0.801275, 0.495645)$,

$$\frac{\partial J}{\partial \theta_0} = 0.0061279.$$

$$\frac{\partial J}{\partial \theta_1} = -0.037256.$$

$$\text{new } \theta_0 = \theta_0 - \alpha * \frac{\partial J}{\partial \theta_0}$$

$$\theta_0 = 0.801275 - 0.7 * (0.0061279)$$

$$\theta_0 = 0.796985.$$

$$\text{new } \theta_1 = \theta_1 - \alpha \frac{\partial J}{\partial \theta_1}$$

$$\theta_1 = 0.495645 - 0.7 * (-0.037256)$$

$$\theta_1 = 0.521724.$$

$$J(0.796985, 0.521724) = 0.483450.$$