

Advanced Computer Networks



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Markov Process



**DSSRG: Decentralized
Smart Systems Research
Group**

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Back to ... Queuing Theory

- Stochastic Modeling
- Application of probability theory to understand real-world phenomena
- Many places we have seen Queues - or in a general terms – **Waiting line**
- Queueing theory is the mathematical study of the queues
- **Analysis** of systems that provides **services to some random demand**



Examples -

- Grocery store
- Airport
- Traffic Signal

- Common questions –
- **What is the average time to be spent in the queue**
- [Customer – Cars, Calls, packets]
- **How long the lines are on average**
- How many customers are waiting for **more than two minutes**
- **How many servers are needed?**



Networks and Queues ...

- Dealing with quantitative models –
- *Probabilistic and Stochastic*
- When ARPANET was being considered – There are many queues it was supposed to deal with.
- Its feasibility was mathematically shown by researchers through Queueing theory – Some people were **Erlang, Kleinrock**

Similar places we can use the theories -



Source to read...

- Web2.uwindor.ca/math/hlynka/queue.html
- **Shortle, Thomson, Gross and Harris:** Fundamentals of Queueing Theory: Wiley
- **J Medhi: Stochastic Modeling, Academic Press**
- **Kleinrock, Queuing Systems, Vol 1, Wiley**
- **Cooper, Introduction to Queueing Theory, North Holland**
- **Nelson: Probability, Stochastic Process and Queueing Theory: The Mathematics of Performance Modeling: Springer**
- **Gelenbe and Pujolle, Introduction to Queueing Networks, Wiley**



Markov processes and Queueing theory:

- **Markov processes**
- A **Markov process (MP)** { $X(t)$, $t \in T$ } is a process such that:

$$P[X(t+1) = x_{t+1} \mid X(1) = x_1, X(2) = x_2, \dots, X(t) = x_t] = P[X(t+1) = x_{t+1} \mid X(t) = x_t]$$

- $X(t+1)$ = State at $t+1$
- $X(1)$ = state at x_1 , $X(2)$, state at x_2 , ...
- In other words: to determine the **next state $X(t+1)$** , we only have to look at the **present state $X(t)$** .



Categories of Markov processes

- Markov processes are categorized by the nature of the *time* and *space* domains:

		Space →	
		Discrete	Continuous
Time ↓	Discrete	Discrete time Markov chain	Discrete time, continuous space Markov process
	Continuous	Continuous time Markov chain	Diffusion processes

Link with Queuing System -

- $X(t)$ = number of customers in the system
-

$t \in [0, \infty)$ (all positive time values)

$X(t) \in [0, 1, 2, \dots]$ (# of customers)

$P[X(t+1) = k-1 | X(t) = k]$ = probab that a customer departs in the next time unit

$P[X(t+1) = k+1 | X(t) = k]$ = probab that a customer arrives in the next time unit



Discrete time Markov chains

- State Transition –
- Recall that in a **Markov process**, only the *last state* determines the *next state* that the **Markov process** will visit:
- The **state** at **time t** is $X(t)$
- The **state** at **time $t+1$** is $X(t+1)$
- **Moving** from state $X(t)$ to the state $X(t+1)$ is called -
State transition



One-step transition probability

- Given that the **Markov chain** is in state **i** at time **t**
- The **probability** that the **Markov chain** will be in state **j** at time **t+1** is defined as

$$P_{ij} = P[X(t+1) = j \mid X(t) = i]$$



One-step transition probability

- Notice that this **relationship** is valid for any value of t.
- i.e.: This is **time-independent**

$$\begin{aligned} P_{ij} &= P[X(t+1) = j \mid X(t) = i] \\ &= P[X(t+2) = j \mid X(t+1) = i] \\ &= P[X(t+3) = j \mid X(t+2) = i] \end{aligned}$$

- The probability P_{ij} is called the **one-step (state) transition probability**



One-step transition probability matrix

- Let N denote the **number of states** in the **Markov chain**
- The **collection of all one-step transition probabilities** forms a **matrix**: (TPM)
-

$$P = \begin{array}{c|ccccccccc|c} & & & & & & & & & & \\ & & P_{11} & P_{12} & P_{13} & & \dots & & P_{1N} & & \\ & & P_{21} & P_{22} & P_{23} & & \dots & & P_{2N} & & \\ P = & \dots & \dots & \dots & \dots & & \dots & & \dots & & \\ & \dots & \dots & \dots & \dots & & \dots & & \dots & & \\ & P_{N1} & P_{N2} & P_{N3} & & \dots & & & P_{NN} & & \\ & & & & & & & & & & \\ & & & & & & & & & & \end{array}$$



Properties of one-step transition probability matrix

Every row-sum is 1

$$P_{11} + P_{12} + P_{13} + \dots + P_{1N} = 1$$

$$P_{21} + P_{22} + P_{23} + \dots + P_{2N} = 1$$

..

$$P_{N1} + P_{N2} + P_{N3} + \dots + P_{NN} = 1$$

Why?

When a MP is at state i , at t , in the next time state, it must need to go to another state which may be i itself or something different but within the set of states only...



Stochastic Matrix

- An $N \times N$ matrix P is a **stochastic matrix** if
- $\forall i = 1, 2, \dots, N: \sum_{\{j = 1, 2, \dots, N\}} P_{ij} = 1$
- (i.e., every **row sum** is equal to 1)



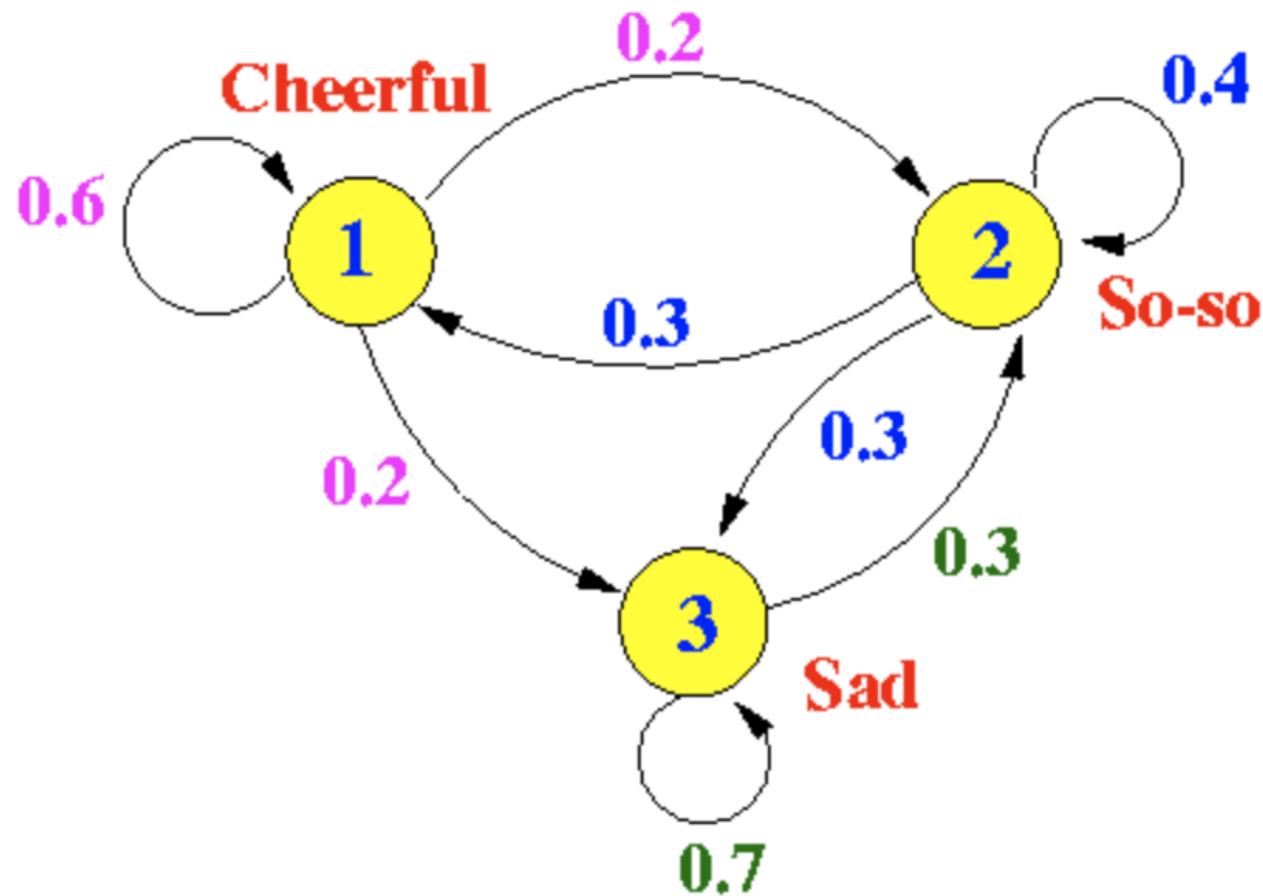
Double Stochastic Matrix

- An $N \times N$ matrix P is a *double stochastic matrix* if
 - $\forall i = 1, 2, \dots, N: \sum_{\{j = 1, 2, \dots, N\}} P_{ij} = 1$
 - and:
 - $\forall j = 1, 2, \dots, N: \sum_{\{i = 1, 2, \dots, N\}} P_{ij} = 1$
- (i.e., every **row sum** and every **column sum** are equal to 1)

**Can you find some examples ?
(Stochastic but not double, both double
and single etc??)**



The following Markov chain models the mode of a person:



State transition probabilities

$$\begin{aligned} P[X(t+1) = \text{Cheerful} | X(t) = \text{Cheerful}] &= P_{11} = 0.6 \\ P[X(t+1) = \text{So-so} | X(t) = \text{Cheerful}] &= P_{12} = 0.2 \\ P[X(t+1) = \text{Sad} | X(t) = \text{Cheerful}] &= P_{13} = 0.2 \end{aligned}$$

- One-step transition matrix:

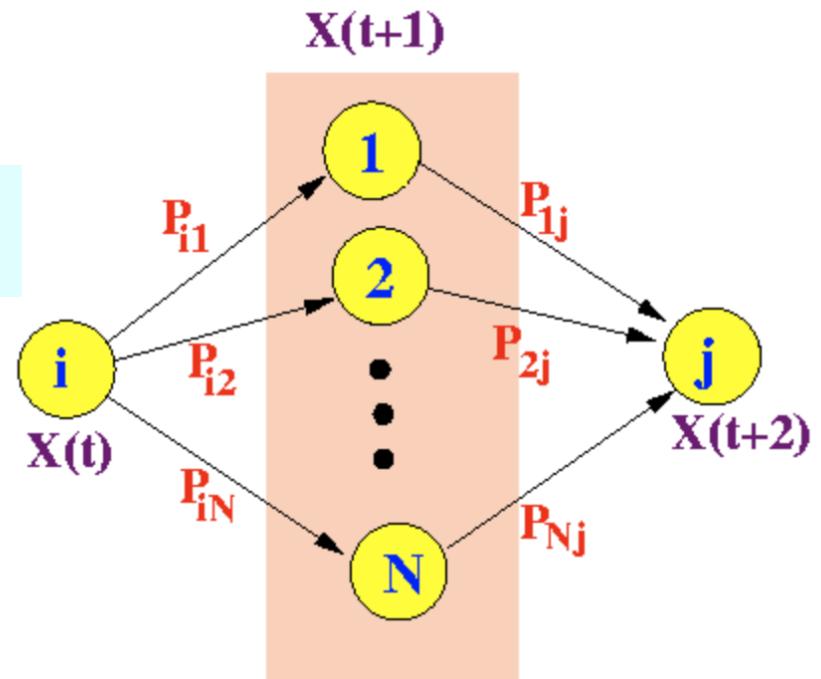
+ -				- +
P =		0.6	0.2	0.2
		0.3	0.4	0.3
		0.0	0.3	0.7
+ -				- +



Two-steps transition probability matrix

- Two steps probability:
- $P_{ij}^2 = P[X(t+2) = j | X(t) = i]$
- Possible ways to arrive in state j from state i in 2 steps:
-

$$P_{ij}^2 = P_{i1} \times P_{1j} + P_{i2} \times P_{2j} + \dots + P_{iN} \times P_{Nj}$$



Note: this formula is used to multiply 2 matrices !!!



Thus . . .

- Relationship between the *2-steps* and *one-step* transition probability matrices:

- $P^2 = P \times P$

- Example –

$$P = \begin{array}{c|ccc|c} & +- & & & +- \\ & | & 0.6 & 0.2 & 0.2 \\ & | & 0.3 & 0.4 & 0.3 \\ & | & 0.0 & 0.3 & 0.7 \\ & +- & & & +- \end{array}$$
$$P^2 = \begin{array}{c|ccc|c} & +- & & & +- \\ & | & 0.6 & 0.2 & 0.2 \\ & | & 0.3 & 0.4 & 0.3 \\ & | & 0.0 & 0.3 & 0.7 \\ & +- & & & +- \end{array} \times \begin{array}{c|ccc|c} & +- & & & +- \\ & | & 0.6 & 0.2 & 0.2 \\ & | & 0.3 & 0.4 & 0.3 \\ & | & 0.0 & 0.3 & 0.7 \\ & +- & & & +- \end{array}$$
$$= \begin{array}{c|ccc|c} & +- & & & +- \\ & | & 0.42 & 0.26 & 0.32 \\ & | & 0.30 & 0.31 & 0.39 \\ & | & 0.09 & 0.33 & 0.58 \\ & +- & & & +- \end{array}$$



N-step ...

- **N-steps transition probability matrix**
- The **2-steps transition matrix** can be generalized to an **N-steps process**
- It is easy to show that the **N-steps transition matrix P^N** is equal to:
$$P^N = P \times P \times \dots \times P$$



Example

P

$$\begin{bmatrix} 0.6 & 0.2 & 0.2 \\ [& &] \\ 0.3 & 0.4 & 0.3 \\ [& &] \\ 0. & 0.3 & 0.7 \end{bmatrix}$$

P^2

$$\begin{bmatrix} 0.42 & 0.26 & 0.32 \\ [& &] \\ 0.30 & 0.31 & 0.39 \\ [& &] \\ 0.09 & 0.33 & 0.58 \end{bmatrix}$$

P^3

$$\begin{bmatrix} 0.330 & 0.284 & 0.386 \\ [& &] \\ 0.273 & 0.301 & 0.426 \\ [& &] \\ 0.153 & 0.324 & 0.523 \end{bmatrix}$$

P^6

$$\begin{bmatrix} 0.245490 & 0.304268 & 0.450242 \\ [& &] \\ 0.237441 & 0.306157 & 0.456402 \\ [& &] \\ 0.218961 & 0.310428 & 0.470611 \end{bmatrix}$$

P^{10}

$$\begin{bmatrix} 0.2313863532 & 0.3075488830 & 0.4610647637 \\ [& &] \\ 0.2310495033 & 0.3076271722 & 0.4613233244 \\ [& &] \\ 0.2302738212 & 0.3078074437 & 0.4619187352 \end{bmatrix}$$

It converges !!!

P^{20}

$$\begin{bmatrix} 0.2307712768 & 0.3076918322 & 0.4615368910 \\ [& &] \\ 0.2307701600 & 0.3076920917 & 0.4615377482 \\ [& &] \\ 0.2307675883 & 0.3076926893 & 0.4615397223 \end{bmatrix}$$



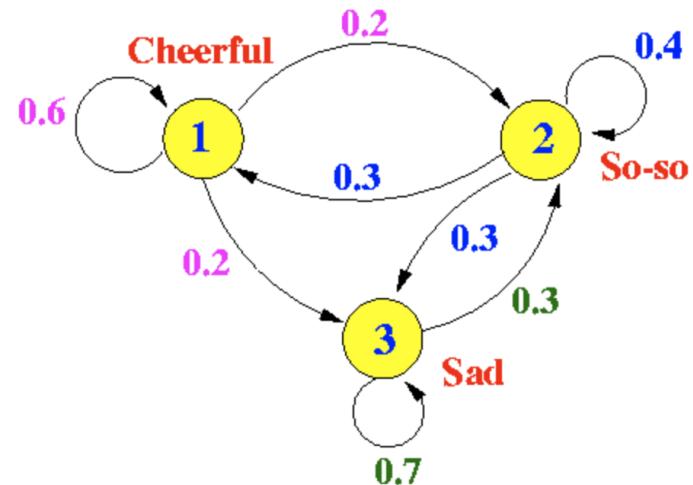
Two issues -

- Markov Process models some real-life process –
- So there are two issues -
- **Initial State of a Markov Process**
 - How the system starts
- **Progress of a Markov process**
 - How it evolves at each time step



Initial state

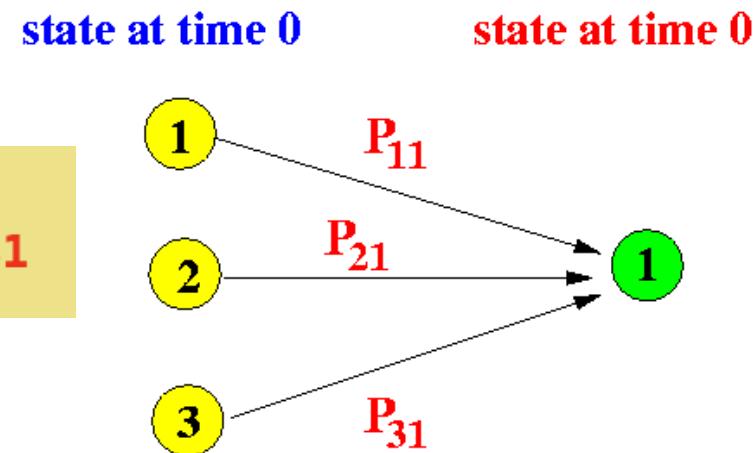
- Define:
- $\pi^{(0)} = (\pi_1^{(0)}, \pi_2^{(0)}, \dots, \pi_N^{(0)})$
- The **initial state $\pi^{(0)}$** is the **vector of probability values** that the **Markov chain** is in state **i** with **probability $\pi_i^{(0)}$**
- Suppose that **initially** a person **always** starts off in the "**Cheerful**" state
- $\pi^{(0)} = (1, 0, 0)$



Progress of a Markov Process

- Starting in the **initial state**, a **Markov process (chain)** will make a **state transition** at each time unit.
- The following shows the **possible ways** to reach the **state 1** after **one step**:
- Therefore, the **probability** that the **Markov chain** is in **state 1** is equal to:

$$\pi_1^{(1)} = \pi_1^{(0)}P_{11} + \pi_2^{(0)}P_{21} + \pi_3^{(0)}P_{31}$$



State Probability Vector

$\pi^{(1)} = (\pi_1^{(1)}, \pi_2^{(1)}, \dots, \pi_N^{(1)})$ after one step transition can be computed using $\pi^{(0)}$ as follows:

$$\begin{aligned}\pi_1^{(1)} &= \pi_1^{(0)}P_{11} + \pi_2^{(0)}P_{21} + \pi_3^{(0)}P_{31} \\ \pi_2^{(1)} &= \pi_1^{(0)}P_{12} + \pi_2^{(0)}P_{22} + \pi_3^{(0)}P_{32} \\ \pi_3^{(1)} &= \pi_1^{(0)}P_{13} + \pi_2^{(0)}P_{23} + \pi_3^{(0)}P_{33}\end{aligned}$$

Notice: this is a vector-matrix multiplication (rather than a matrix-vector multiplication)

in matrix form:

$$\pi^{(1)} = \pi^{(0)} \times P$$



State Probability Vector after **k** steps

2 steps:

$$\pi_1^{(2)} = \pi_1^{(1)}P_{11} + \pi_2^{(1)}P_{21} + \pi_3^{(1)}P_{31}$$

$$\pi_2^{(2)} = \pi_1^{(1)}P_{12} + \pi_2^{(1)}P_{22} + \pi_3^{(1)}P_{32}$$

$$\pi_3^{(2)} = \pi_1^{(1)}P_{13} + \pi_2^{(1)}P_{23} + \pi_3^{(1)}P_{33}$$

Or: $\pi^{(2)} = \pi^{(1)} \times P$

$$= (\pi^{(0)} \times P) \times P$$

$$= \pi^{(0)} \times (P \times P)$$

$$= \pi^{(0)} \times P^2$$

In general:

$$\pi^{(k)} = \pi^{(0)} \times P^k$$



Example

- Initial State Probability Vector (SPV) = (1,0,0)
- State Transition Probability Matrix (TPM)
- $P = \begin{bmatrix} 0.6, 0.2, 0.2 \\ 0.3, 0.4, 0.3 \\ 0.0, 0.3, 0.7 \end{bmatrix}$

So, SPV after 1st time step, after 2 time steps and so on ...

$$\begin{aligned}x^{(1)} &= [0.6, 0.2, 0.2] \\x^{(2)} &= [0.42, 0.26, 0.32] \\x^{(4)} &= [0.2832, 0.2954, 0.4214] \\x^{(8)} &= [0.23490798, 0.30673034, 0.45836168] \\x^{(16)} &= [0.2307693926, 0.3076922701, 0.4615383374]\end{aligned}$$

It Converges!... -



Stationary State & Transient State



Stationary state

- The **stationary state** is the following **limiting probability**:

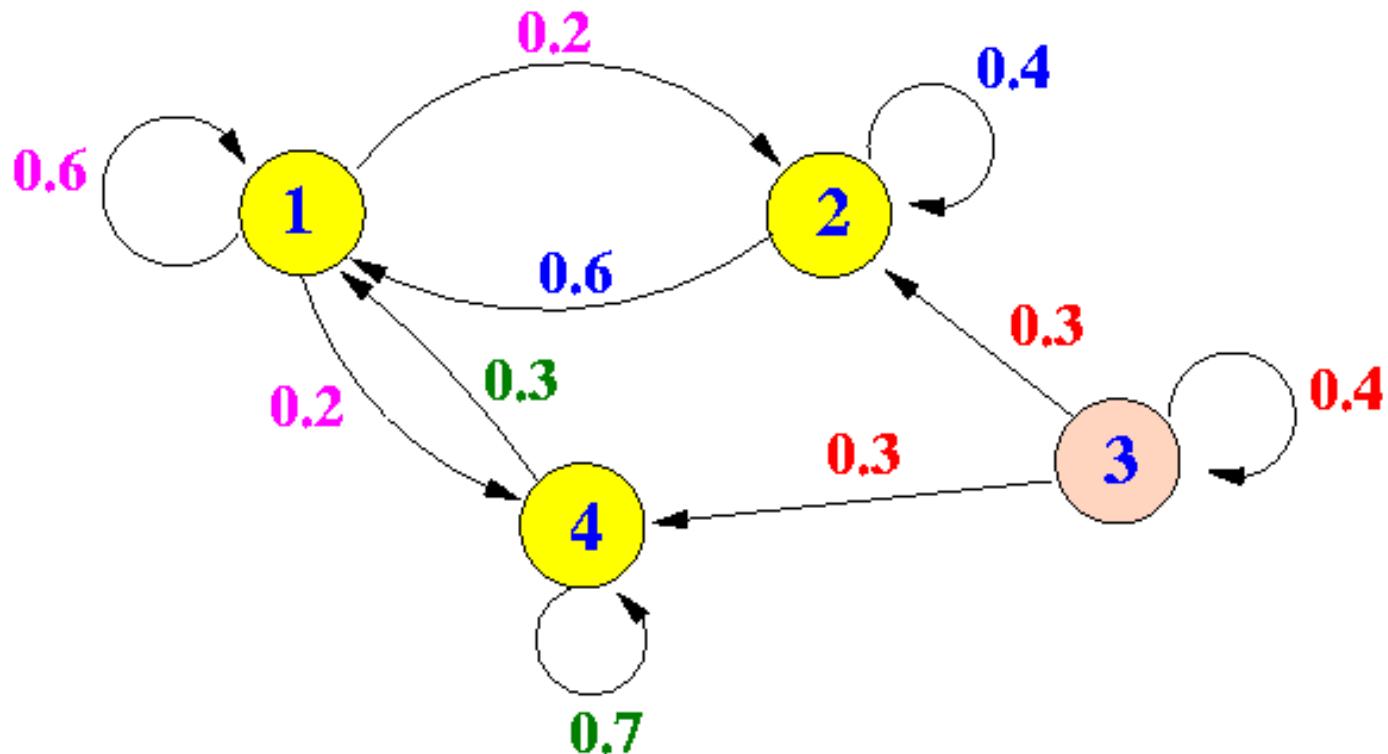
$$\pi^{(\infty)} = \lim_{(k \rightarrow \infty)} \pi^{(k)}$$

- The **stationary state** is also called the **steady state**
- (State Probability Vector after long run)



Transient state:

- Introduced through an example of Markov chain
- Consider the following Markov chain:



The multi-step probability matrices:

P

$$[\begin{matrix} 0.6, & 0.2, & 0.0, & 0.2, \\ 0.6, & 0.4, & 0.0, & 0.0, \\ 0.0, & 0.3, & 0.4, & 0.3, \\ 0.3, & 0.0, & 0.0, & 0.7 \end{matrix}]$$

P2

$$[\begin{matrix} 0.54 & 0.20 & 0. & 0.26 \\ 0.60 & 0.28 & 0. & 0.12 \\ 0.27 & 0.24 & 0.16 & 0.33 \\ 0.39 & 0.06 & 0. & 0.55 \end{matrix}]$$

P3

$$[\begin{matrix} 0.5130 & 0.1796 & 0. & 0.3074 \\ 0.5388 & 0.2056 & 0. & 0.2556 \\ 0.4617 & 0.1794 & 0.0256 & 0.3333 \\ 0.4611 & 0.1278 & 0. & 0.4111 \end{matrix}]$$

P5

$$[\begin{matrix} 0.5000282111 & 0.1666948777 & 0. & 0.3332769112 \\ 0.5000846332 & 0.1667513000 & 0 & 0.3331640668 \\ 0.4999993559 & 0.1666668815 & 0.4294967296 & 10^{-6} \\ 0.4999153666 & 0.1665820333 & 0. & 0.3333333333 \end{matrix}]$$

P4

$$[\begin{matrix} 0.50167962 & 0.16834628 & 0. & 0.32997410 \\ 0.50503884 & 0.17170552 & 0. & 0.32325564 \\ 0.49901697 & 0.16699434 & 0.00065536 & 0.33333333 \\ 0.49496115 & 0.16162782 & 0. & 0.34341103 \end{matrix}]$$

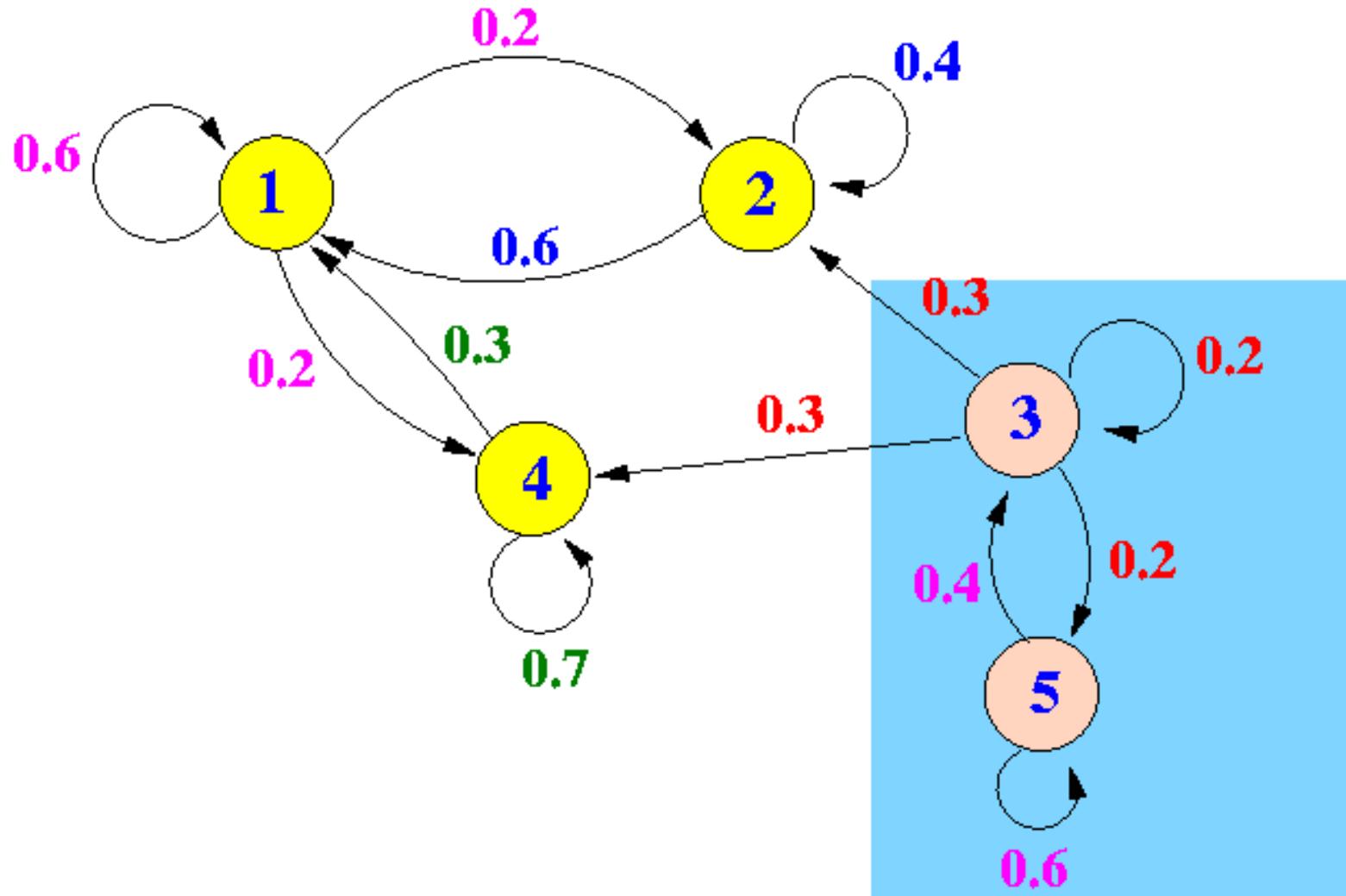
The probability that the Markov chain is found in state 3 becomes smaller and smaller with time !!!

Transient and Steady State

- **Transient state:**
- A transient state of a **Markov chain** is a state where the **stationary probability** is equal to zero (0)
- **Recurrent state:**
- A recurrent state of a **Markov chain** is a ***non-transient*** state (**stationary probability nonzero**)

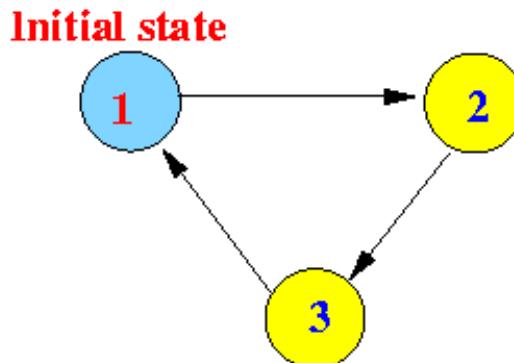


States 3 and 5 are transient states because once the Markov chain leaves these states, it will never return back to them.



Periodic states:

- A periodic state is a special subclass of recurrent states
- A periodic state is a recurrent state say with a period **d** if it re-occurs after exactly **d** steps
- $p^{(1)}_{ii} = 0$
- $p^{(2)}_{ii} = 0 \dots$
- $p^{(d-1)}_{ii} = 0$
- $p^{(d)}_{ii} = 1$
- $p^{(d+1)}_{ii} = 0 \dots$



The **period** of the above **Markov process** is 3:

$$p^{(1)}_{11} = 0 \text{ (Probability that from state 1, in one step, we reach state 1)}$$
$$p^{(2)}_{11} = 0 \text{ (Probability that from state 1, in two steps, we reach state 1)}$$
$$p^{(3)}_{11} = 1 \text{ (Probability that from state 1, in three steps, we reach state 1)}$$

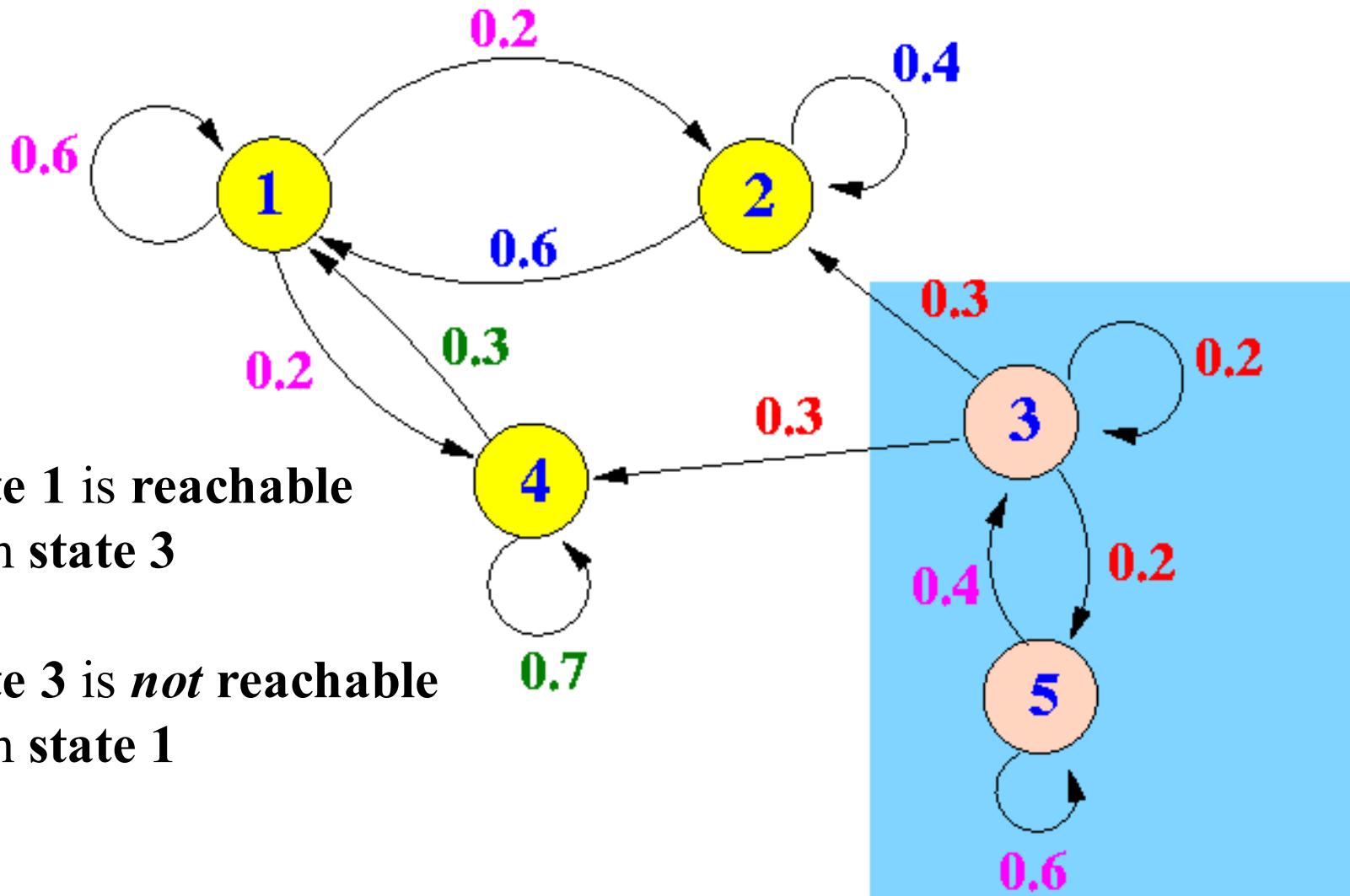
Reachable state:

- A state **j** is **reachable** from a state **i** iff:
- $p_{ij}^{(n)} > 0$ for some $n > 0$

i.e., there is a **non-zero probability** that we **end up in state j** starting from state **i** after a **finite number of steps n**

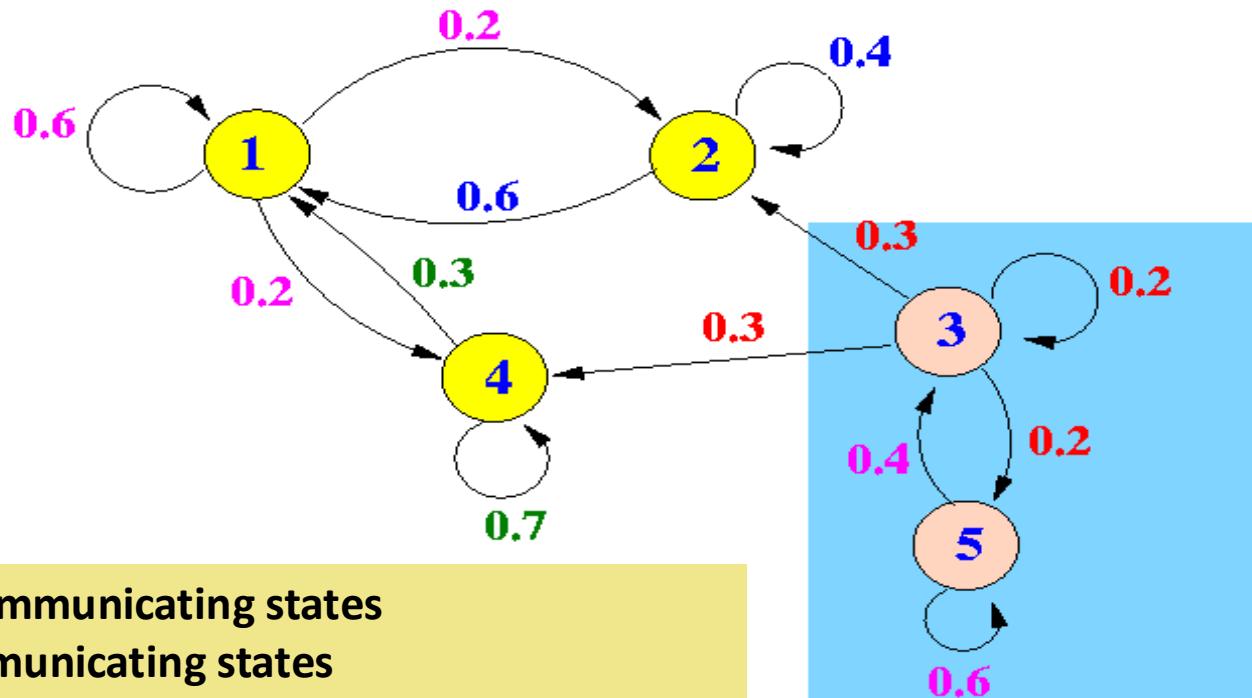


Example



Communicating states:

- The states i and j are **communicating states** iff:
- State j is **reachable** from state i , and State i is **reachable** from state j



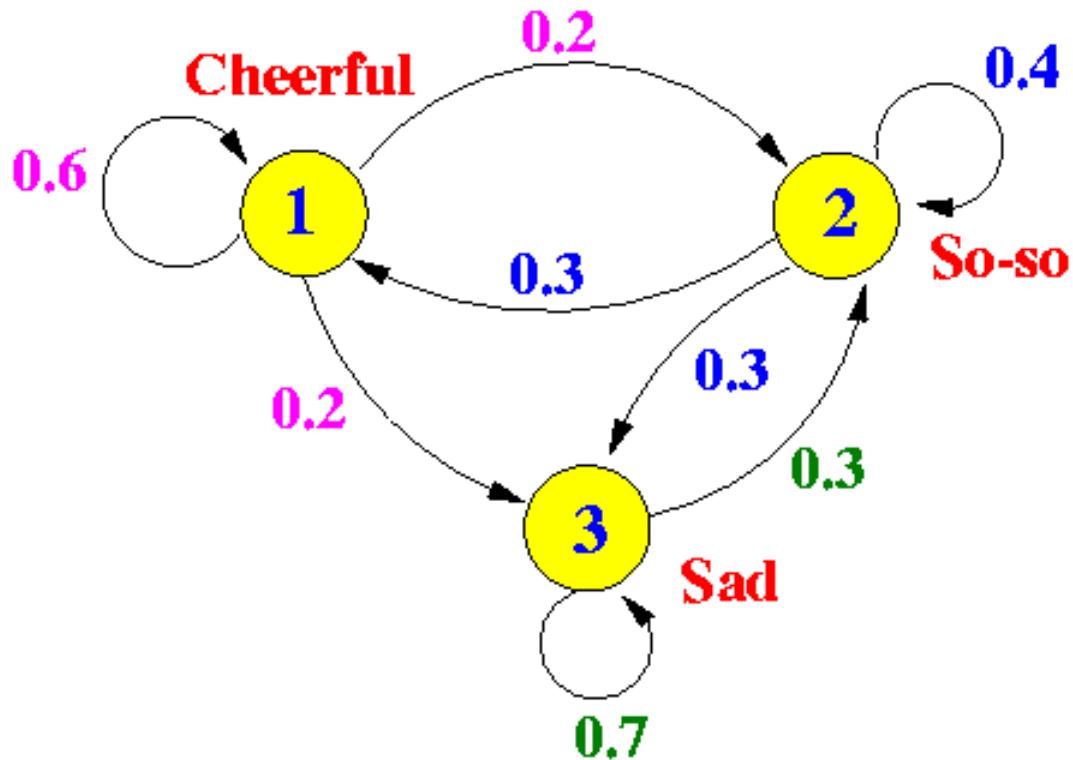
Chain

- A **chain C** is a set of states where **all members are mutually communicating**
- $\forall i, j \in C$:
- i is reachable from j and j is reachable from i



Single chain Markov process:

- A single chain Markov process is a Markov process that does not have any *transient* states



Steady-state property of Single Chain Markov processes

- The **steady state probability** (limiting state probability) of a state is the **likelihood** that the **Markov chain** is in that state **after a long period of time**
- **Mathematically speaking:** we must find this **limit**

$$\lim_{\{n \rightarrow \infty\}} \pi^{(n)}_j$$



Lemma 1:

- If a **Markov Chain** has a **single chain** and **no *periodic* states**, then: the **limiting state probabilities exists and independent from the initial state**

$$\lim_{\{n \rightarrow \infty\}} \pi^{(n)}_j = \pi$$

(π is some constant)

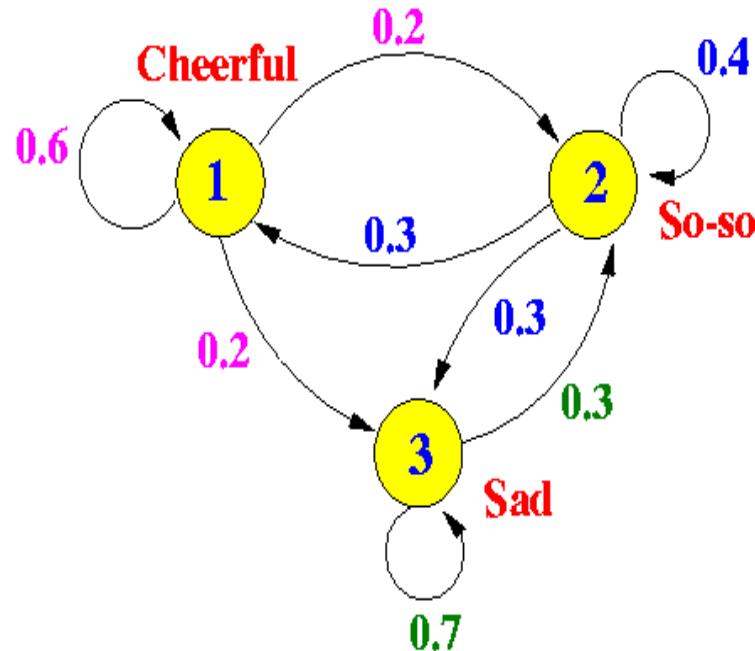
independent from the value of $\pi^{(0)}_j$



Computing steady-state probabilities (Limiting state probabilities)

One-step probability matrix:

$$P = \begin{bmatrix} & \begin{array}{ccc} & + & - \\ 0.6 & 0.2 & 0.2 \\ 0.3 & 0.4 & 0.3 \\ 0.0 & 0.3 & 0.7 \end{array} & - \\ \begin{array}{c} | \\ + \end{array} & & \begin{array}{c} | \\ - \end{array} \end{bmatrix}$$



The example Markov chain has: one single chain no recurrent states

According to Lemma 1, the Markov chain has a steady state and the steady state is reached from any initial state



Finding the steady-state probability π

- When Markov chain starts in initial state $\pi^{(0)}$ and make 1 step:

$$\pi_1^{(1)} = \pi_1^{(0)} P_{11} + \pi_2^{(0)} P_{21} + \pi_3^{(0)} P_{31}$$

$$\pi_2^{(1)} = \pi_1^{(0)} P_{12} + \pi_2^{(0)} P_{22} + \pi_3^{(0)} P_{32}$$

$$\pi_3^{(1)} = \pi_1^{(0)} P_{13} + \pi_2^{(0)} P_{23} + \pi_3^{(0)} P_{33}$$

Or:

$$\pi^{(1)} = \pi^{(0)} \times P$$



Forming the equations ...

- If the **Markov chain** is in the **steady state**, and makes **one step**, the **next state** equal to the **steady state**.
- Therefore, in the **steady state** $\pi = (\pi_1, \pi_2, \pi_3)$, we have:

$$\pi_1 = \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31}$$

$$\pi_2 = \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32}$$

$$\pi_3 = \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33}$$

Or:

$$\pi = \pi^{Tr} \times P \quad (Tr = \text{transpose})$$



Caveat in solving for π

- The system of equations obtained from the **one step transition probability matrix** is a *dependent* system of equations because one of the equation is a linear combination of the *other* two equations:

$$\pi_1 = \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31}$$

$$\pi_2 = \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32}$$

+

$$\pi_3 = \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33}$$



Solving equations...

$$\pi_1 = \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31}$$

$$\pi_2 = \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32}$$

$$+$$
$$\pi_3 = \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33}$$

$$\pi_1 + \pi_2 + \pi_3 =$$

$$\pi_1(P_{11} + P_{12} + P_{13}) + \pi_2(P_{21} + P_{22} + P_{23}) + \pi_3(P_{31} + P_{32} + P_{33})$$

Facts:

$$P_{11} + P_{12} + P_{13} = 1$$

$$P_{21} + P_{22} + P_{23} = 1$$

$$P_{31} + P_{32} + P_{33} = 1$$

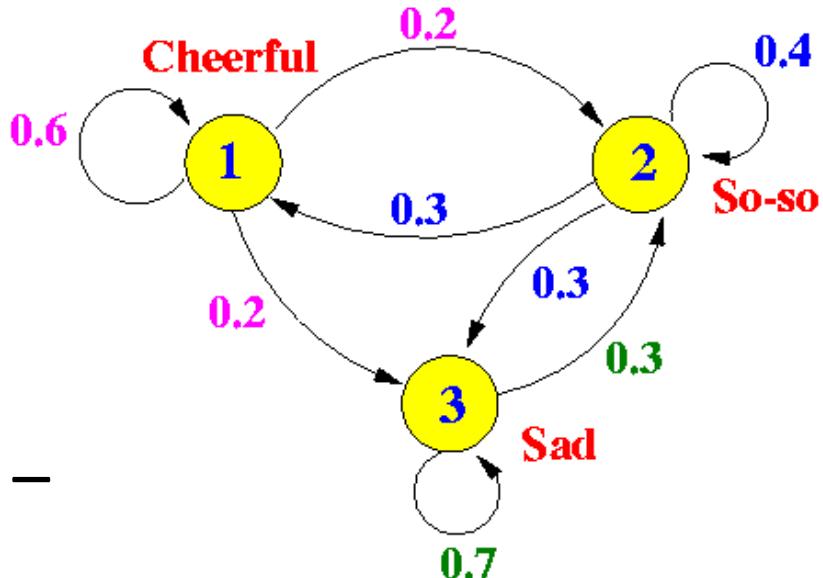


Solving...

- In order to obtain a *non-dependent* system of equations, you *must* replace *any* one equation in the system of equations with this equation:
- So we need to apply $\pi_1 + \pi_2 + \pi_3 = 1$
- And then solve it...



Example -



Steady state probability satisfies –

$$\pi_1 = 0.6 \pi_1 + 0.3 \pi_2 + 0.0 \pi_3 \quad \dots \quad (1)$$

$$\pi_2 = 0.2 \pi_1 + 0.4 \pi_2 + 0.3 \pi_3 \quad \dots \quad (2)$$

$$\pi_3 = 0.2 \pi_1 + 0.3 \pi_2 + 0.7 \pi_3 \quad \dots \quad (3)$$

And :

$$\pi_1 + \pi_2 + \pi_3 = 1 \quad \dots \quad (4)$$

Solution...

Drop equation (3) and re-write into canonical form:

$$-0.4 \pi_1 + 0.3 \pi_2 + 0.0 \pi_3 = 0 \quad \dots \dots \dots (1)$$

$$0.2 \pi_1 - 0.6 \pi_2 + 0.3 \pi_3 = 0 \quad \dots \dots \dots (2)$$

$$\pi_1 + \pi_2 + \pi_3 = 1 \quad \dots \dots \dots (4)$$

Solving the equations—

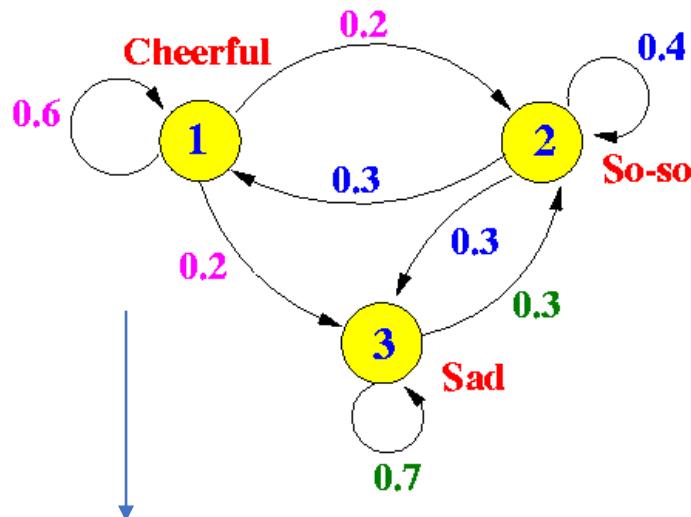
$$\pi_1 = 0.2307692308$$

$$\pi_2 = 0.3076923077$$

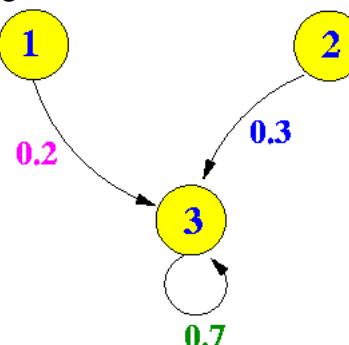
$$\pi_3 = 0.4615384615$$



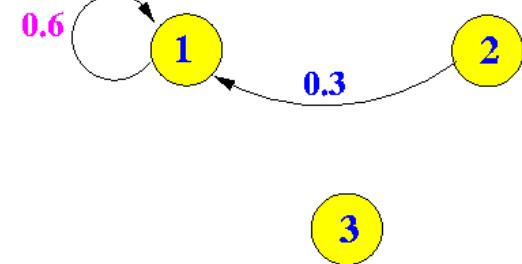
A common way to find *equilibrium equations* for Markov chains



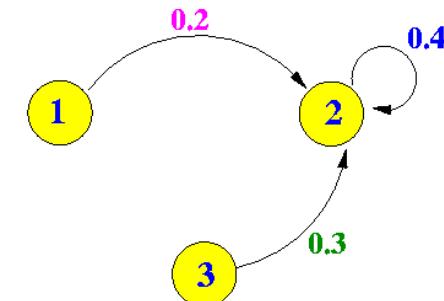
Focussing **only** on the possible ways to *get to* the state 3, we see:



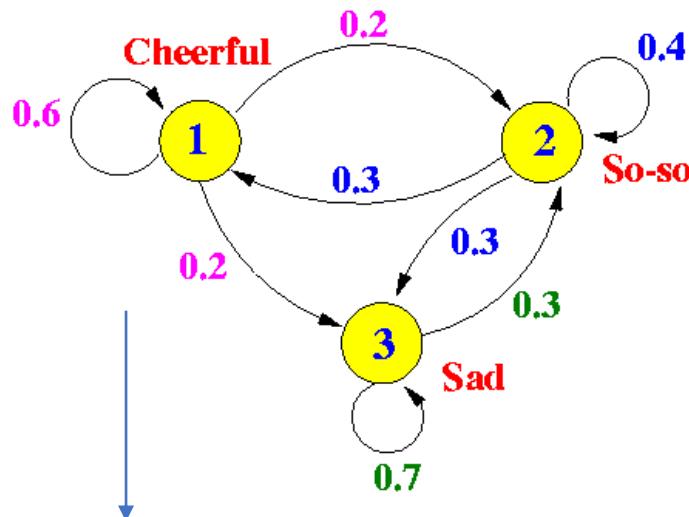
Focussing **only** on the possible ways to *get to* the state 1, we see:



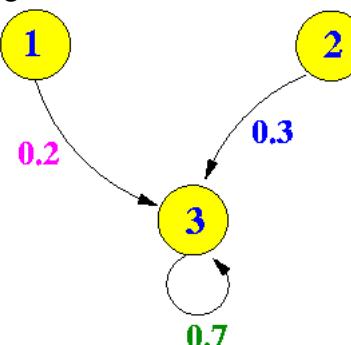
Focussing **only** on the possible ways to *get to* the state 2, we see:



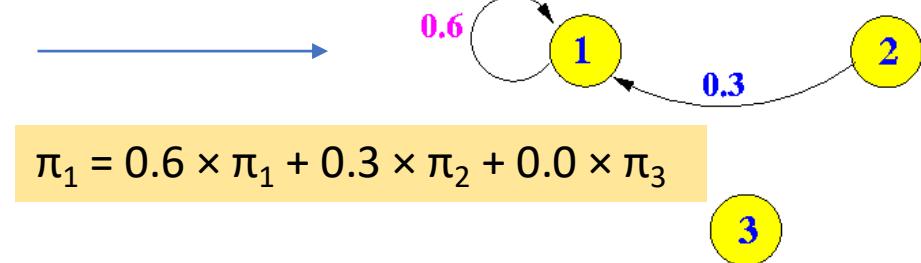
A common way to find *equilibrium equations* for Markov chains



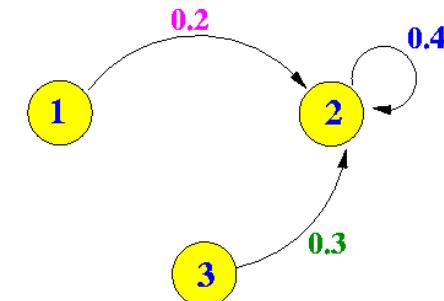
Focussing **only** on the possible ways to *get to* the state 3, we see:



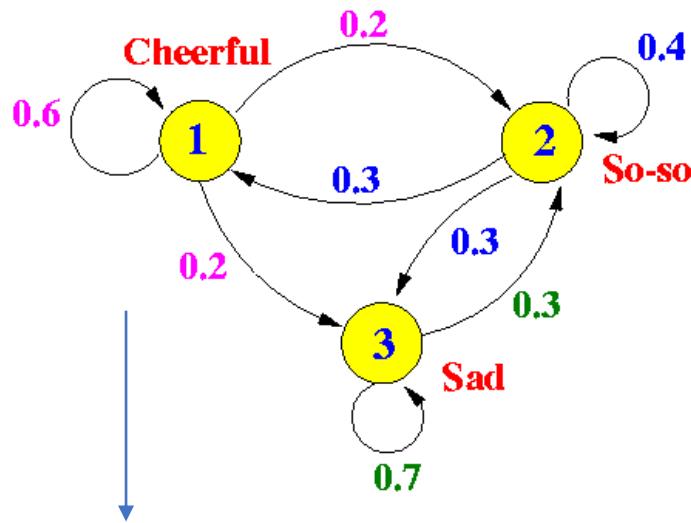
Focussing **only** on the possible ways to *get to* the state 1, we see:



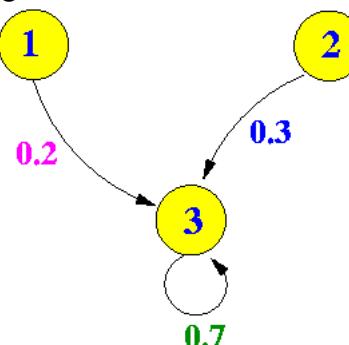
Focussing **only** on the possible ways to *get to* the state 2, we see:



A common way to find *equilibrium equations* for Markov chains

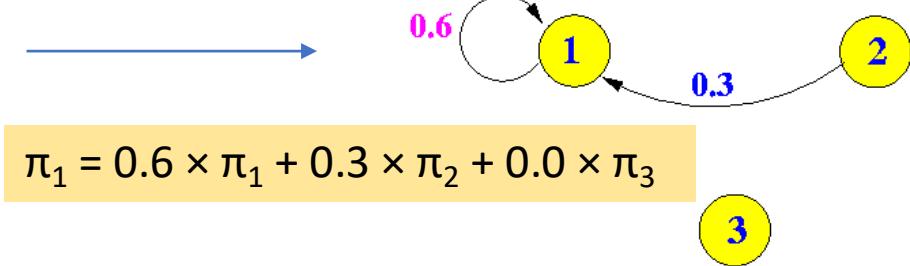


Focussing **only** on the possible ways to *get to* the state 3, we see:

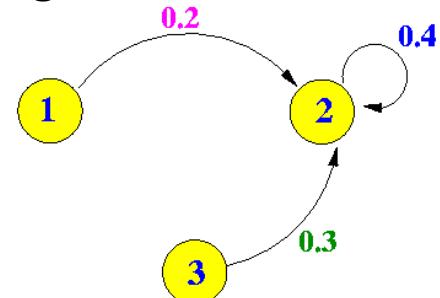


$$\pi_3 = 0.2 \times \pi_1 + 0.3 \times \pi_2 + 0.0 \times \pi_3$$

Focussing **only** on the possible ways to *get to* the state 1, we see:

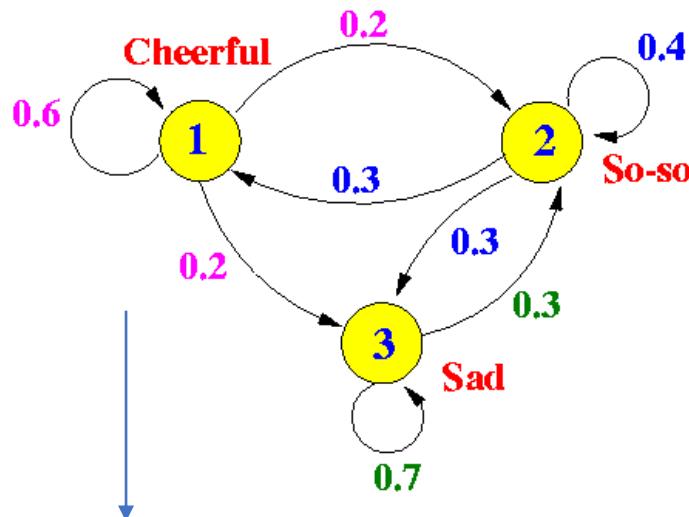


Focussing **only** on the possible ways to *get to* the state 2, we see:



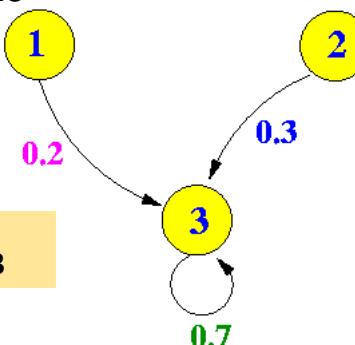
$$\pi_2 = 0.2 \times \pi_1 + 0.4 \times \pi_2 + 0.3 \times \pi_3$$

A common way to find *equilibrium equations* for Markov chains



Focussing **only** on the possible ways to *get to* the state 3, we see:

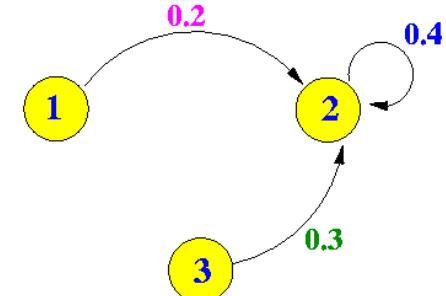
$$\pi_3 = 0.2 \times \pi_1 + 0.3 \times \pi_2 + 0.7 \times \pi_3$$



Focussing **only** on the possible ways to *get to* the state 1, we see:

$$\pi_1 = 0.6 \times \pi_1 + 0.3 \times \pi_2 + 0.0 \times \pi_3$$

Focussing **only** on the possible ways to *get to* the state 2, we see:



$$\pi_2 = 0.2 \times \pi_1 + 0.4 \times \pi_2 + 0.3 \times \pi_3$$

Complicated situation

- In **more complicated Markov chains**, we may need to use **multiple transitions** to establish **equilibrium equations**

