
```
% SYMBOLIC EXPRESSIONS AND NUMERICAL INTEGRATION IN MATLAB

%1)
help syms;

%2)
syms t;
func=sin(2*pi*t);

%3)
%{
Two variables are are stored in workspace with the name
func:- with value 1*1 sym
and
t:- with 1*1 sym
%}

%4)
help subs;

%5)
t=-1:0.01:1;
y=subs(func,t);
disp(y);

%6)
help int;
h1=int(func);
h2=int(func*func);
y1=subs(h1,1)-subs(h1,0);
y2=subs(h2,1)-subs(h2,0);
disp(y1);
disp(y2);

%FOURIER SERIES ANALYSIS
%1)
syms t;
w0=100*pi;
T0=2*pi/w0;
K=-5:5;

%2)
x1=cos(w0*t);
[Ak1,w1]=FourierAnalysis(x1,T0,K);

x2=sin(w0*t);
[Ak2,w2]=FourierAnalysis(x2,T0,K);

disp(Ak1);
disp(Ak2);

%3)
```

```

syms t;
t=-5:0.01:5;
xs=(abs(mod(t,1))<=0.25)+(mod(t,1)~=0).*(abs(mod(-t,1))<=0.25);
y=subs(xs);
plot(t,y);

%4)
syms t;
T0=1;
K=-10:10;
Xs=1;
[Ak,W]=FourierAnalysis2(Xs,T0,K);
disp(Ak);
disp(W);
%All the Ak's are real.

%5)
stem(W,abs(Ak));

%6)
%{
The output is verified to be correct, but only after some neccesary changes
to the FourierAnalysis() function because otherwise, since the function is
define as a piecewise function it can't be integrated using the int()
function. Hence FourierAnalysis2() is designed.
%}

%FOURIER SERIES SYNTHESIS EQUATION AND GIBB'S PHENOMENON

%1)
t1=-2:0.01:2;
subplot(231);
plot(t1,X(1));
subplot(232);
plot(t1,X(5));
subplot(233);
plot(t1,X(10));
subplot(234);
plot(t1,X(25));
subplot(235);
plot(t1,X(50));
subplot(111);

%2)
%{
Observation:-
a) From the plot we observe that the maximum overshoot is:-

```

	max(xN(t))	Percentage Overshoot
N=1	1.13662	13.662%
N=5	1.09332	9.332%
N=10	1.09116	9.116%
N=25	1.08996	8.996%
N=50	1.08956	8.956%

b) For each value of N we observe that the amplitude of intersection point is 0.5.

c) For each value of N we observe that the time difference is 0.8.

%

%3)

%{

N=1 and N=5 are not in conformity with Gibb's phenomenon as they are highly deviated from a square wave. N=10 is somewhat in conformity as it tends to be a square wave.N=25 and N=50 almost satisfies Gibb's phenomenon as they are almost fully square waves.

%}

%FUNCTION FourierAnalysis()

```

function [Ak,w]=FourierAnalysis(x,T0,K)
Ak=K;
w=K;
syms t;
for i=1:length(K)
    k=K(i);
    w0=k*2*pi/T0;
    w(i)=w0;
    func=int(x*exp(-(1i)*w0*t))/T0;
    Ak(i)=subs(func,T0)-subs(func,0);
end
end

function [Ak,w]=FourierAnalysis2(x,T0,K)
Ak=K;
w=K;
syms t;
for i=1:length(K)
    k=K(i);
    w0=k*2*pi/T0;
    w(i)=w0;
    func=int(x*exp(-(1i)*w0*t))/T0;
    Ak(i)=subs(func,T0/4)-subs(func,-T0/4);
end
end

function x=X(N)
syms t;
xs=1;
K=-N:N;
[Ak,W]=FourierAnalysis2(xs,1,K);
t1=-2:0.01:2;
x=t1*0;
for y=1:length(K)

```

```

ak=Ak(y);
w=W(y);
x=x+ak*exp((li)*w*t1);
end
end

SYMS Short-cut for constructing symbolic variables.
SYMS arg1 arg2 ...
is short-hand notation for creating symbolic variables
arg1 = sym('arg1');
arg2 = sym('arg2'); ...
or, if the argument has the form f(x1,x2,...), for
creating symbolic variables
x1 = sym('x1');
x2 = sym('x2');
...
f = symfun(sym('f(x1,x2,...)'), [x1, x2, ...]);
The outputs are created in the current workspace.

SYMS ... ASSUMPTION
additionally puts an assumption on the variables created.
The ASSUMPTION can be 'real', 'rational', 'integer', or 'positive'.
SYMS ... clear
clears any assumptions on the variables created, including those
made with the ASSUME command.

SYMS ... [nrows,ncols] matrix
declares the variables symbolic matrices

SYMS({symvar1, symfun1, ...})
is equal to the call SYMS 'symvar1' 'symfun1' ...

SYMS({symvar1, symfun1, ...}, ASSUMPTION)
is equal to the call SYMS 'symvar1' 'symfun1' ... ASSUMPTION

SYMS([symvar1, symvar2, ...])
is equal to the call SYMS 'symvar1' 'symvar2' ...

SYMS([symvar1, symvar2, ...], ASSUMPTION)
is equal to the call SYMS 'symvar1' 'symvar2' ... ASSUMPTION

Each input argument must begin with a letter and must contain only
alphanumeric characters.

S = SYMS returns a cell array containing the names of the symbolic
variables in the workspace. Without an output argument, SYMS lists
the symbolic variables in the workspace.

Example 1:
    syms x beta real
is equivalent to:
    x = sym('x','real');
    beta = sym('beta','real');

```

To clear the symbolic objects *x* and *beta* of 'real' or 'positive' status, type
 syms x beta clear

Example 2:

```
    syms x(t) a
is equivalent to:
    a = sym('a');
    t = sym('t');
    x = symfun(sym('x(t)'), [t]);
```

Example 3:

```
    syms({sym('u'), sym('v'), sym('w'))}
is equivalent to:
    syms u v w
```

Example 4:

```
    syms({symfun('u(t)',sym('t')), symfun('v(t)',sym('t')),
symfun('w(t)',sym('t'))})
is equivalent to:
    syms u(t) v(t) w(t)
```

Example 5:

```
    syms({sym('u'), sym('v'), sym('w')}, 'real')
is equivalent to:
    syms u v w real
```

Example 6:

```
    syms([sym('u'), sym('v'), sym('w')])
is equivalent to:
    syms u v w
```

Example 7:

```
Clear all symbolic variables in the workspace:
    syms u v w
S = syms;
cellfun(@clear, S);
```

Example 8:

```
Create a symbolic matrix variable
    syms A [3 4] matrix
is equivalent to:
    A = symmatrix('A', [3 4]);
```

See also *SYM*, *SYMFUN*, *SYMMATRIX*.

Deprecated API:

The 'unreal' keyword can be used instead of 'clear'.

Documentation for *syms*
 doc syms

SUBS Symbolic substitution.

SUBS(S,OLD,NEW) replaces *OLD* with *NEW* in the symbolic expression *S*.

OLD is a symbolic variable, a string representing a variable name, or an expression. *NEW* is a symbolic or numeric variable or expression.

SUBS(S,VALUES), where *VALUES* is a STRUCT, replaces the symbolic variables in *S* which are field names in *VALUES* by the corresponding entries of the struct.

SUBS(S) replaces all the variables in the symbolic expression *S* with values obtained from the calling function, or the MATLAB workspace.

SUBS(S,NEW) replaces the free symbolic variable in *S* with *NEW*.

If *OLD* and *NEW* are vectors or arrays of the same size, each element of *OLD* is replaced by the corresponding element of *NEW*. If *S* and *OLD* are scalars and *NEW* is an array or cell array, the scalars are expanded to produce an array result. If *NEW* is a cell array of numeric matrices, the substitutions are performed elementwise (i.e., *subs(x*y,{x,y},{A,B})* returns *A.*B* when *A* and *B* are numeric).

If *SUBS(S,OLD,NEW)* does not change *S*, then *SUBS(S,NEW,OLD)* is tried. This provides backwards compatibility with previous versions and eliminates the need to remember the order of the arguments.

SUBS(S,OLD,NEW,0) does not switch the arguments if *S* does not change.

Examples:

Single input:

Suppose *a* = 980 and *C1* = 3 exist in the workspace.

The statement

y = *dsolve('Dy = -a*y')*

produces

y = *exp(-a*t)*C1*

Then the statement

subs(y)

produces

ans = 3**exp(-980*t)*

Single Substitution:

subs(a+b,a,4) returns 4+*b*.

Multiple Substitutions:

subs(cos(a)+sin(b),{a,b},[sym('alpha'),2]) or
subs(cos(a)+sin(b),{a,b},{sym('alpha'),2}) returns
cos(alpha)+sin(2)

Scalar Expansion Case:

*subs(exp(a*t),'a',-magic(2))* returns

[*exp(-t)*, *exp(-3*t)*]
[*exp(-4*t)*, *exp(-2*t)*]

Multiple Scalar Expansion:

*subs(x*y,{x,y},{{0 1;-1 0},{1 -1;-2 1}})* returns
[0, -1]

```
[ 2,  0]
```

See also *SYM/SUBEXPR*, *SYM/VPA*, *SYM/DOUBLE*.

Documentation for *subs*
doc *subs*

Other uses of *subs*

```
sym/subs
```

```
[0, sin(pi/50), sin(pi/25), sin((3*pi)/50), sin((2*pi)/25), 5^(1/2)/4
 - 1/4, sin((3*pi)/25), sin((7*pi)/50), sin((4*pi)/25), sin((9*pi)/50),
 (2^(1/2)*(5 - 5^(1/2))^(1/2))/4, sin((11*pi)/50), sin((6*pi)/25),
 sin((13*pi)/50), sin((7*pi)/25), 5^(1/2)/4 + 1/4, sin((8*pi)/25),
 sin((17*pi)/50), sin((9*pi)/25), sin((19*pi)/50), (2^(1/2)*(5^(1/2)
 + 5)^(1/2))/4, sin((21*pi)/50), sin((11*pi)/25), sin((23*pi)/50),
 sin((12*pi)/25), 1, sin((12*pi)/25), sin((23*pi)/50), sin((11*pi)/25),
 sin((21*pi)/50), (2^(1/2)*(5^(1/2) + 5)^(1/2))/4, sin((19*pi)/50),
 sin((9*pi)/25), sin((17*pi)/50), sin((8*pi)/25), 5^(1/2)/4 + 1/4,
 sin((7*pi)/25), sin((13*pi)/50), sin((6*pi)/25), sin((11*pi)/50), (2^(1/2)*(5
 - 5^(1/2))^(1/2))/4, sin((9*pi)/50), sin((4*pi)/25), sin((7*pi)/50),
 sin((3*pi)/25), 5^(1/2)/4 - 1/4, sin((2*pi)/25), sin((3*pi)/50),
 sin(pi/25), sin(pi/50), 0, -sin(pi/50), -sin(pi/25), -sin((3*pi)/50),
 -sin((2*pi)/25), 1/4 - 5^(1/2)/4, -sin((3*pi)/25), -sin((7*pi)/50),
 -sin((4*pi)/25), -sin((9*pi)/50), -(2^(1/2)*(5 - 5^(1/2))^(1/2))/4, -
 sin((11*pi)/50), -sin((6*pi)/25), -sin((13*pi)/50), -sin((7*pi)/25), -
 5^(1/2)/4 - 1/4, -sin((8*pi)/25), -sin((17*pi)/50), -sin((9*pi)/25), -
 sin((19*pi)/50), -(2^(1/2)*(5^(1/2) + 5)^(1/2))/4, -sin((21*pi)/50), -
 sin((11*pi)/25), -sin((23*pi)/50), -sin((12*pi)/25), -1, -sin((12*pi)/25),
 -sin((23*pi)/50), -sin((11*pi)/25), -sin((21*pi)/50), -(2^(1/2)*(5^(1/2)
 + 5)^(1/2))/4, -sin((19*pi)/50), -sin((9*pi)/25), -sin((17*pi)/50), -
 sin((8*pi)/25), -5^(1/2)/4 - 1/4, -sin((7*pi)/25), -sin((13*pi)/50),
 -sin((6*pi)/25), -sin((11*pi)/50), -(2^(1/2)*(5 - 5^(1/2))^(1/2))/4, -
 sin((9*pi)/50), -sin((4*pi)/25), -sin((7*pi)/50), -sin((3*pi)/25), 1/4 -
 5^(1/2)/4, -sin((2*pi)/25), -sin((3*pi)/50), -sin(pi/25), -sin(pi/50),
 0, sin(pi/50), sin(pi/25), sin((3*pi)/50), sin((2*pi)/25), 5^(1/2)/4
 - 1/4, sin((3*pi)/25), sin((7*pi)/50), sin((4*pi)/25), sin((9*pi)/50),
 (2^(1/2)*(5 - 5^(1/2))^(1/2))/4, sin((11*pi)/50), sin((6*pi)/25),
 sin((13*pi)/50), sin((7*pi)/25), 5^(1/2)/4 + 1/4, sin((8*pi)/25),
 sin((17*pi)/50), sin((9*pi)/25), sin((19*pi)/50), (2^(1/2)*(5^(1/2)
 + 5)^(1/2))/4, sin((21*pi)/50), sin((11*pi)/25), sin((23*pi)/50),
 sin((12*pi)/25), 1, sin((12*pi)/25), sin((23*pi)/50), sin((11*pi)/25),
 sin((21*pi)/50), (2^(1/2)*(5^(1/2) + 5)^(1/2))/4, sin((19*pi)/50),
 sin((9*pi)/25), sin((17*pi)/50), sin((8*pi)/25), 5^(1/2)/4 + 1/4,
 sin((7*pi)/25), sin((13*pi)/50), sin((6*pi)/25), sin((11*pi)/50), (2^(1/2)*(5
 - 5^(1/2))^(1/2))/4, sin((9*pi)/50), sin((4*pi)/25), sin((7*pi)/50),
 sin((3*pi)/25), 5^(1/2)/4 - 1/4, sin((2*pi)/25), sin((3*pi)/50), sin(pi/25),
 sin(pi/50), 0, -sin(pi/50), -sin(pi/25), -sin((3*pi)/50), -sin((2*pi)/25),
 1/4 - 5^(1/2)/4, -sin((3*pi)/25), -sin((7*pi)/50), -sin((4*pi)/25), -
 sin((9*pi)/50), -(2^(1/2)*(5 - 5^(1/2))^(1/2))/4, -sin((11*pi)/50), -
 sin((6*pi)/25), -sin((13*pi)/50), -sin((7*pi)/25), -5^(1/2)/4 - 1/4, -
 sin((8*pi)/25), -sin((17*pi)/50), -sin((9*pi)/25), -sin((19*pi)/50), -
 (2^(1/2)*(5^(1/2) + 5)^(1/2))/4, -sin((21*pi)/50), -sin((11*pi)/25), -
```

```
sin((23*pi)/50), -sin((12*pi)/25), -1, -sin((12*pi)/25), -sin((23*pi)/50),
-sin((11*pi)/25), -sin((21*pi)/50), -(2^(1/2)*(5^(1/2) + 5)^(1/2))/4,
-sin((19*pi)/50), -sin((9*pi)/25), -sin((17*pi)/50), -sin((8*pi)/25),
- 5^(1/2)/4 - 1/4, -sin((7*pi)/25), -sin((13*pi)/50), -sin((6*pi)/25),
-sin((11*pi)/50), -(2^(1/2)*(5 - 5^(1/2))^(1/2))/4, -sin((9*pi)/50),
-sin((4*pi)/25), -sin((7*pi)/50), -sin((3*pi)/25), 1/4 - 5^(1/2)/4, -
sin((2*pi)/25), -sin((3*pi)/50), -sin(pi/25), -sin(pi/50), 0]
```

int - States from CIC filter

This MATLAB function returns the states of a CIC filter in matrix form, rather than as the native filtstates object.

Syntax

```
integerstates = int(hm.states)
```

See also filtstates.cic, dsp.CICDecimator, dsp.CICInterpolator

Introduced in DSP System Toolbox in R2011a

Documentation for int

```
doc int
```

Other uses of int

```
filtstates/int      sym/int
```

0

1/2

Columns 1 through 7

0	0	0	0	0.5000	0	0.5000
---	---	---	---	--------	---	--------

Columns 8 through 11

0	0	0	0
---	---	---	---

Columns 1 through 4

0.0000 + 0.0000i	0.0000 + 0.0000i	0.0000 + 0.0000i	0.0000 + 0.0000i
------------------	------------------	------------------	------------------

Columns 5 through 8

0.0000 + 0.5000i	0.0000 + 0.0000i	0.0000 - 0.5000i	0.0000 + 0.0000i
------------------	------------------	------------------	------------------

Columns 9 through 11

0.0000 + 0.0000i	0.0000 + 0.0000i	0.0000 + 0.0000i
------------------	------------------	------------------

Columns 1 through 7

0	0.0354	0	-0.0455	0	0.0637	0
---	--------	---	---------	---	--------	---

Columns 8 through 14

-0.1061 0 0.3183 0.5000 0.3183 0 -0.1061

Columns 15 through 21

0 0.0637 0 -0.0455 0 0.0354 0

Columns 1 through 7

-62.8319 -56.5487 -50.2655 -43.9823 -37.6991 -31.4159 -25.1327

Columns 8 through 14

-18.8496 -12.5664 -6.2832 0 6.2832 12.5664 18.8496

Columns 15 through 21

25.1327 31.4159 37.6991 43.9823 50.2655 56.5487 62.8319

Warning: Imaginary parts of complex X and/or Y arguments ignored.

Warning: Imaginary parts of complex X and/or Y arguments ignored.

Warning: Imaginary parts of complex X and/or Y arguments ignored.

Warning: Imaginary parts of complex X and/or Y arguments ignored.

