

# Advanced Computer Networks



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## Markov Process



**DSSRG: Decentralized  
Smart Systems Research  
Group**

<https://sites.google.com/iitbbs.ac.in/dssrg>

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# Back to ... Queuing Theory ....

- Stochastic Modeling
- Application of probability theory to understand real-world phenomena
- Many places we have seen Queues - or in a general terms – **Waiting line**
- Queueing theory is the mathematical study of the queues
- **Analysis** of systems that provides **services to some random demand**



# Examples -

- Grocery store
- Airport
- Traffic Signal
  
- Common questions –
- **What is the average time to be spent in the queue**
- [Customer – Cars, Calls, packets]
- **How long the lines are on average**
- How many customers are waiting for **more than two minutes**
- **How many servers are needed?**



# Networks and Queues ...

- Dealing with quantitative models –
- *Probabilistic and Stochastic*
- When ARPANET was being considered – There are many queues it was supposed to deal with.
- Its feasibility was mathematically shown by researchers through Queueing theory – Some people were **Erlang, Kleinrock**

 Similar places we can use the theories -

# Source to read...

- [Web2.uwindor.ca/math/hlynka/queue.html](http://Web2.uwindor.ca/math/hlynka/queue.html)
- [Shortle, Thomson, Gross and Harris](#): Fundamentals of Queueing Theory: Wiley
- **J Medhi: Stochastic Modeling, Academic Press**
- [Kleinrock, Queuing Systems](#), Vol 1, Wiley
- [Cooper, Introduction to Queueing Theory](#), North Holland
- [Nelson: Probability, Stochastic Process and Queuing Theory: The Mathematics of Performance Modeling](#): Springer
- [Gelenbe and Pujolle](#), Introduction to Queuing Networks, Wiley



# Markov processes and Queueing theory:

- **Markov processes**
- A **Markov process (MP)**  $\{ X(t), t \in T \}$  is a process such that:

$$P[ X(t+1) = x_{t+1} \mid X(1) = x_1, X(2) = x_2, \dots, X(t) = x_t ] = P[ X(t+1) = x_{t+1} \mid X(t) = x_t ]$$

- $X(t+1)$  = State at  $t+1$
- $X(1)$  = state at  $x_1$ ,  $X(2)$ , state at  $x_2$ , ...
- In other words: to determine the **next state**  $X(t+1)$ , we only have to look at the **present state**  $X(t)$ .



# Categories of Markov processes

- Markov processes are categorized by the nature of the *time* and *space* domains:

		Space →	
		Discrete	Continuous
← Time	Discrete	Discrete time Markov chain	Discrete time, continuous space Markov process
	Continuous	Continuous time Markov chain	Diffusion processes



# Link with Queuing System -

- $X(t)$  = number of customers in the system
- 

$t \in [0, \infty)$  (all positive time values)

$X(t) \in [0, 1, 2, \dots)$  (# of customers)

$P[ X(t+1) = k-1 \mid X(t) = k ]$  = probab that a customer **departs** in the next time unit

$P[ X(t+1) = k+1 \mid X(t) = k ]$  = probab that a customer **arrives** in the next time unit



# Discrete time Markov chains

- **State Transition –**
- **Recall** that in a **Markov process**, only the *last* state determines the **next state** that the **Markov process** will visit:
- The **state at time  $t$**  is  $X(t)$
- The **state at time  $t+1$**  is  $X(t+1)$
- **Moving** from state  $X(t)$  to the state  $X(t+1)$  is called - **State transition**



# One-step transition probability

- **Given** that the **Markov chain** is in **state i** at **time t**
- The **probability** that the **Markov chain** will be in **state j** at **time t+1** is defined as

$$P_{ij} = \mathbb{P}[ X(t+1) = j \mid X(t) = i ]$$

# One-step transition probability

- Notice that this **relationship** is **valid** for **any value of t**.
- i.e.: This is **time-independent**

$$\begin{aligned} P_{ij} &= P[ X(t+1) = j \mid X(t) = i ] \\ &= P[ X(t+2) = j \mid X(t+1) = i ] \\ &= P[ X(t+3) = j \mid X(t+2) = i ] \end{aligned}$$

- The probability  $P_{ij}$  is called the **one-step (state) transition probability**



# One-step transition probability matrix

- Let **N** denote the **number of states** in the **Markov chain**
- The **collection of *all* one-step transition probabilities** forms a **matrix**: (TPM)

•

$$P = \begin{array}{c} \begin{array}{cc} + & - \end{array} \\ \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} \begin{array}{ccccc} P_{11} & P_{12} & P_{13} & \dots & P_{1N} \\ P_{21} & P_{22} & P_{23} & \dots & P_{2N} \\ \dots & \dots & \dots & & \dots \\ \dots & \dots & \dots & & \dots \\ P_{N1} & P_{N2} & P_{N3} & \dots & P_{NN} \end{array} \begin{array}{c} | \\ | \\ | \\ | \\ | \end{array} \begin{array}{cc} - & + \end{array} \\ \begin{array}{cc} + & - \end{array} \end{array}$$

# Properties of one-step transition probability matrix

## Every row-sum is 1

$$\begin{aligned} P_{11} + P_{12} + P_{13} + \dots + P_{1N} &= 1 \\ P_{21} + P_{22} + P_{23} + \dots + P_{2N} &= 1 \\ \vdots & \\ P_{N1} + P_{N2} + P_{N3} + \dots + P_{NN} &= 1 \end{aligned}$$

## Why?

When a MP is at state  $i$ , at  $t$ , in the next time state, it must need to go to another state which may be  $i$  itself or something different but within the set of states only...



# Stochastic Matrix

- An  $N \times N$  matrix  $P$  is a **stochastic matrix** if
- $\forall i = 1, 2, \dots, N: \sum_{j = 1, 2, \dots, N} P_{ij} = 1$
- (i.e., every **row sum** is equal to **1**)



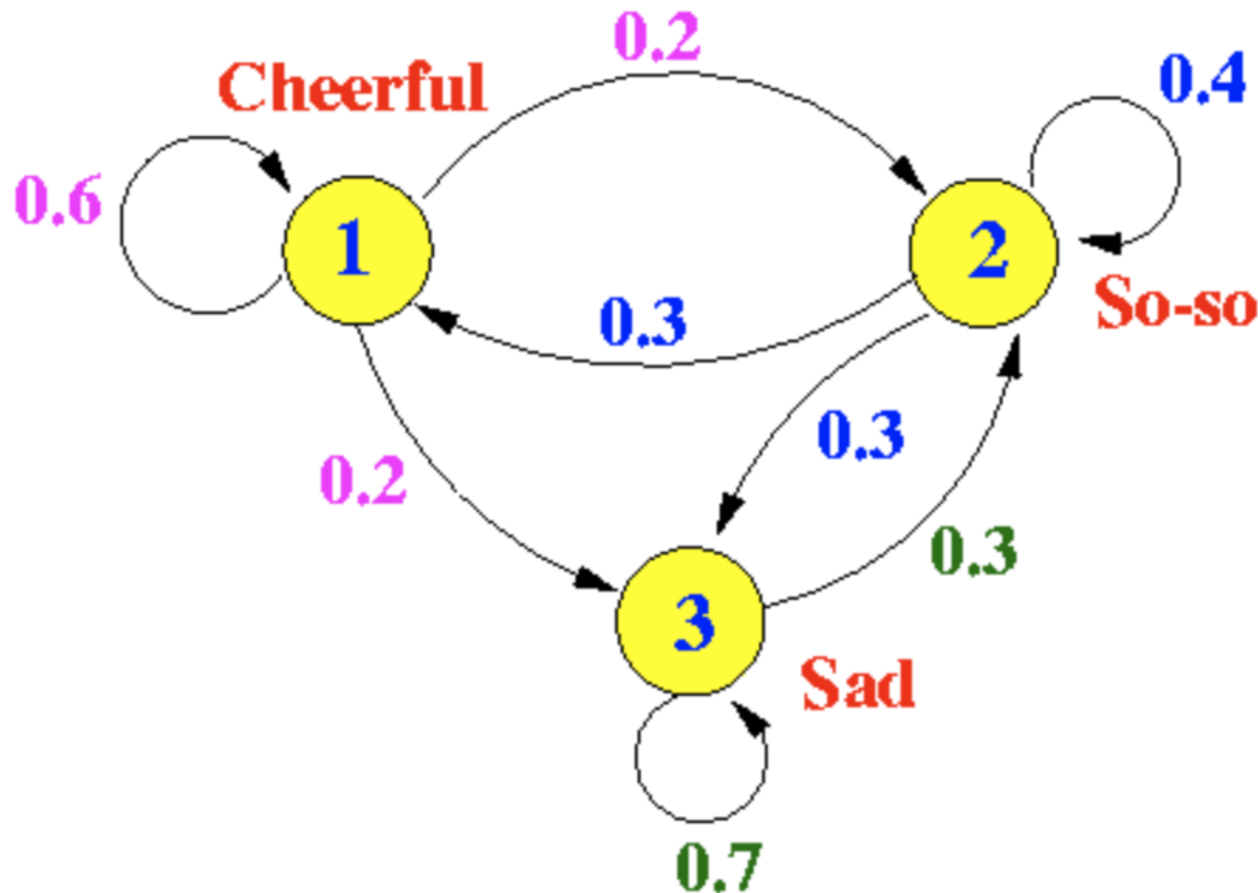
# Double Stochastic Matrix

- An  $N \times N$  matrix  $P$  is a *double stochastic matrix* if
- $\forall i = 1, 2, \dots, N: \sum_{j=1, 2, \dots, N} P_{ij} = 1$
- and:
- $\forall j = 1, 2, \dots, N: \sum_{i=1, 2, \dots, N} P_{ij} = 1$
- (i.e., every **row sum** and every **column sum** are equal to 1)

Can you find some examples ?  
(Stochastic but not double, both double and single etc??)



The following **Markov chain** models the **mode** of a person:





# State transition probabilities

$$\begin{aligned} P[ X(t+1) = \text{Cheerful} \mid X(t) = \text{Cheerful} ] &= P_{11} = 0.6 \\ P[ X(t+1) = \text{So-so} \mid X(t) = \text{Cheerful} ] &= P_{12} = 0.2 \\ P[ X(t+1) = \text{Sad} \mid X(t) = \text{Cheerful} ] &= P_{13} = 0.2 \end{aligned}$$

- One-step transition matrix:

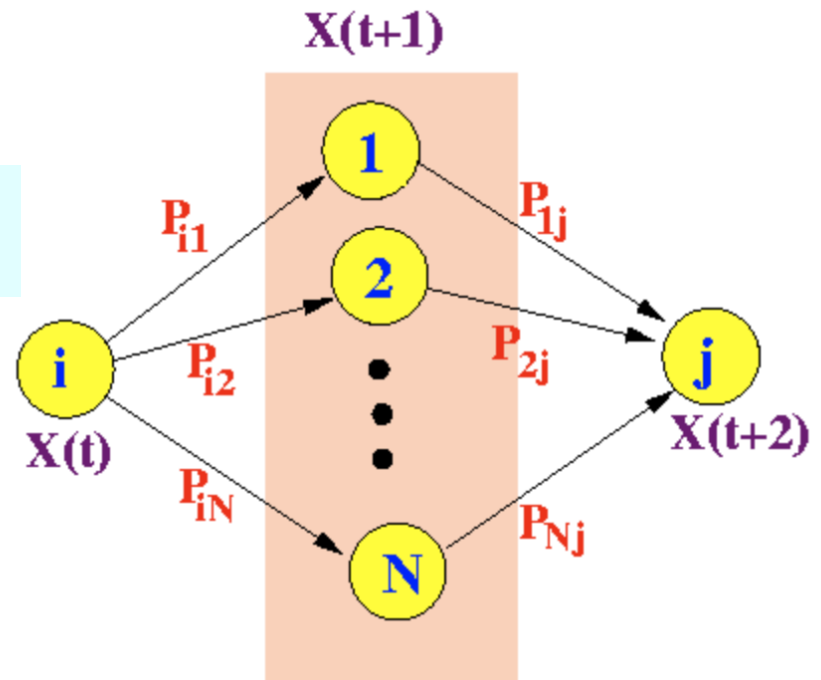
$$P = \begin{array}{c} \begin{array}{cc} + & - \\ | & | \\ 0.6 & 0.2 \\ | & | \\ 0.3 & 0.4 \\ | & | \\ 0.0 & 0.3 \\ + & - \end{array} \end{array}$$

# Two-steps transition probability matrix

- Two steps probability:
- $P^2_{ij} = P[ X(t+2) = j \mid X(t) = i ]$
- Possible ways to arrive in state  $j$  from state  $i$  in 2 steps:

$$P^2_{ij} = P_{i1} \times P_{1j} + P_{i2} \times P_{2j} + \dots + P_{iN} \times P_{Nj}$$

**Note:** this formula is used to multiply 2 matrices !!!



# Thus ...

- Relationship between the *2-steps* and *one-step* transition probability matrices:

- $P^2 = P \times P$

- Example –

$$P = \begin{array}{c|ccc|c} & +- & & & -+ \\ \hline & 0.6 & 0.2 & 0.2 & \\ \hline & 0.3 & 0.4 & 0.3 & \\ \hline & 0.0 & 0.3 & 0.7 & \\ \hline & +- & & & -+ \end{array}$$

$$P^2 = \begin{array}{c|ccc|c} & +- & & & -+ \\ \hline & 0.6 & 0.2 & 0.2 & \\ \hline & 0.3 & 0.4 & 0.3 & \\ \hline & 0.0 & 0.3 & 0.7 & \\ \hline & +- & & & -+ \end{array} \times \begin{array}{c|ccc|c} & +- & & & -+ \\ \hline & 0.6 & 0.2 & 0.2 & \\ \hline & 0.3 & 0.4 & 0.3 & \\ \hline & 0.0 & 0.3 & 0.7 & \\ \hline & +- & & & -+ \end{array}$$
$$= \begin{array}{c|ccc|c} & +- & & & -+ \\ \hline & 0.42 & 0.26 & 0.32 & \\ \hline & 0.30 & 0.31 & 0.39 & \\ \hline & 0.09 & 0.33 & 0.58 & \\ \hline & +- & & & -+ \end{array}$$



# N-step ...

- **N-steps transition probability matrix**
- The **2-steps transition matrix** can be generalized to an **N-steps process**
- It is easy to show that the **N-steps transition matrix**  $P^N$  is equal to:
- $P^N = P \times P \times \dots \times P$



# Example

**P**

[0.6	0.2	0.2]
[		]
[0.3	0.4	0.3]
[		]
[0.	0.3	0.7]

**p2**

[0.42	0.26	0.32]
[		]
[0.30	0.31	0.39]
[		]
[0.09	0.33	0.58]

**p3**

[0.330	0.284	0.386]
[		]
[0.273	0.301	0.426]
[		]
[0.153	0.324	0.523]

**p6**

[0.245490	0.304268	0.450242]
[		]
[0.237441	0.306157	0.456402]
[		]
[0.218961	0.310428	0.470611]

**p10**

[0.2313863532	0.3075488830	0.4610647637]
[		]
[0.2310495033	0.3076271722	0.4613233244]
[		]
[0.2302738212	0.3078074437	0.4619187352]

**It converges !!!**

**p20**

[0.2307712768	0.3076918322	0.4615368910]
[		]
[0.2307701600	0.3076920917	0.4615377482]
[		]
[0.2307675883	0.3076926893	0.4615397223]



# Two issues -

- Markov Process models some real-life process –
- So there are two issues -
- **Initial State of a Markov Process**
  - How the system starts
- **Progress of a Markov process**
  - How it evolves at each time step



# Initial state

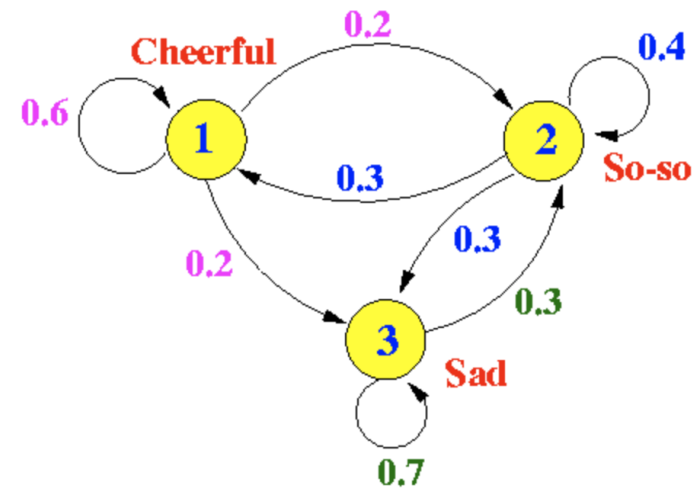
- **Define:**

- $\pi^{(0)} = ( \pi_1^{(0)}, \pi_2^{(0)}, \dots, \pi_N^{(0)} )$

- The **initial state**  $\pi^{(0)}$  is the **vector of probability values** that the **Markov chain** is in state **i** with **probability**  $\pi_i^{(0)}$

- Suppose that **initially** a person **always** starts off in the **"Cheerful"** state

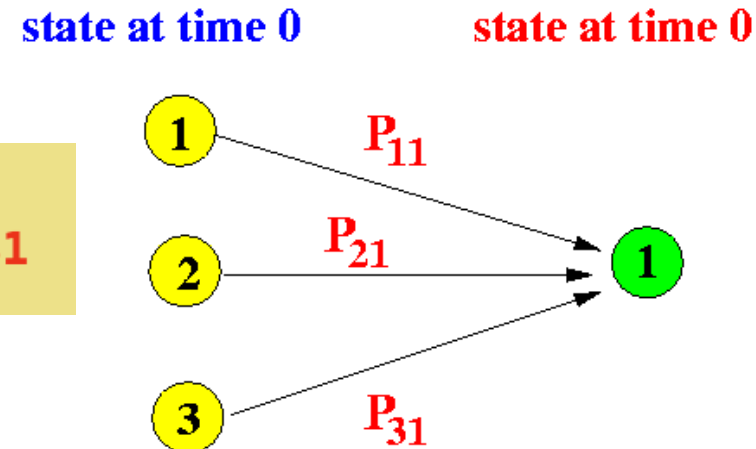
- $\pi^{(0)} = ( 1, 0, 0 )$



# Progress of a Markov Process

- Starting in the **initial state**, a **Markov process (chain)** will make a **state transition** at each time unit.
- The following shows the **possible ways to reach the state 1 after one step**:
- Therefore, the **probability** that the **Markov chain** is in **state 1** is equal to:

$$\pi_1^{(1)} = \pi_1^{(0)}P_{11} + \pi_2^{(0)}P_{21} + \pi_3^{(0)}P_{31}$$





# State Probability Vector

$\pi^{(1)} = ( \pi_1^{(1)}, \pi_2^{(1)}, \dots, \pi_N^{(1)} )$  after one step transition can be computed using  $\pi^{(0)}$  as follows:

$$\begin{aligned}\pi_1^{(1)} &= \pi_1^{(0)} P_{11} + \pi_2^{(0)} P_{21} + \pi_3^{(0)} P_{31} \\ \pi_2^{(1)} &= \pi_1^{(0)} P_{12} + \pi_2^{(0)} P_{22} + \pi_3^{(0)} P_{32} \\ \pi_3^{(1)} &= \pi_1^{(0)} P_{13} + \pi_2^{(0)} P_{23} + \pi_3^{(0)} P_{33}\end{aligned}$$

**Notice:** this is a **vector-matrix multiplication** (rather than a **matrix-vector multiplication**)

**in matrix form:**

$$\pi^{(1)} = \pi^{(0)} \times P$$



# State Probability Vector after **k** steps

**2 steps:**

$$\pi_1^{(2)} = \pi_1^{(1)}P_{11} + \pi_2^{(1)}P_{21} + \pi_3^{(1)}P_{31}$$

$$\pi_2^{(2)} = \pi_1^{(1)}P_{12} + \pi_2^{(1)}P_{22} + \pi_3^{(1)}P_{32}$$

$$\pi_3^{(2)} = \pi_1^{(1)}P_{13} + \pi_2^{(1)}P_{23} + \pi_3^{(1)}P_{33}$$

**Or:**

$$\begin{aligned}\pi^{(2)} &= \pi^{(1)} \times P \\ &= (\pi^{(0)} \times P) \times P \\ &= \pi^{(0)} \times (P \times P) \\ &= \pi^{(0)} \times P^2\end{aligned}$$

**In general:**

$$\pi^{(k)} = \pi^{(0)} \times P^k$$



# Example

- Initial State Probability Vector (SPV) = (1,0,0)
- State Transition Probability Matrix (TPM)
- $P = \begin{bmatrix} 0.6, & 0.2, & 0.2 \\ 0.3, & 0.4, & 0.3 \\ 0.0, & 0.3, & 0.7 \end{bmatrix}$

So, SPV after 1<sup>st</sup> time step, after 2 time steps and so on ...

$$\begin{aligned} x^{(1)} &= [0.6, & 0.2, & 0.2 & ] \\ x^{(2)} &= [0.42, & 0.26, & 0.32 & ] \\ x^{(4)} &= [0.2832, & 0.2954, & 0.4214 & ] \\ x^{(8)} &= [0.23490798, & 0.30673034, & 0.45836168 & ] \\ x^{(16)} &= [0.2307693926, & 0.3076922701, & 0.4615383374 & ] \end{aligned}$$

**It Converges!... -**



# Stationary State & Transient State



# Stationary state

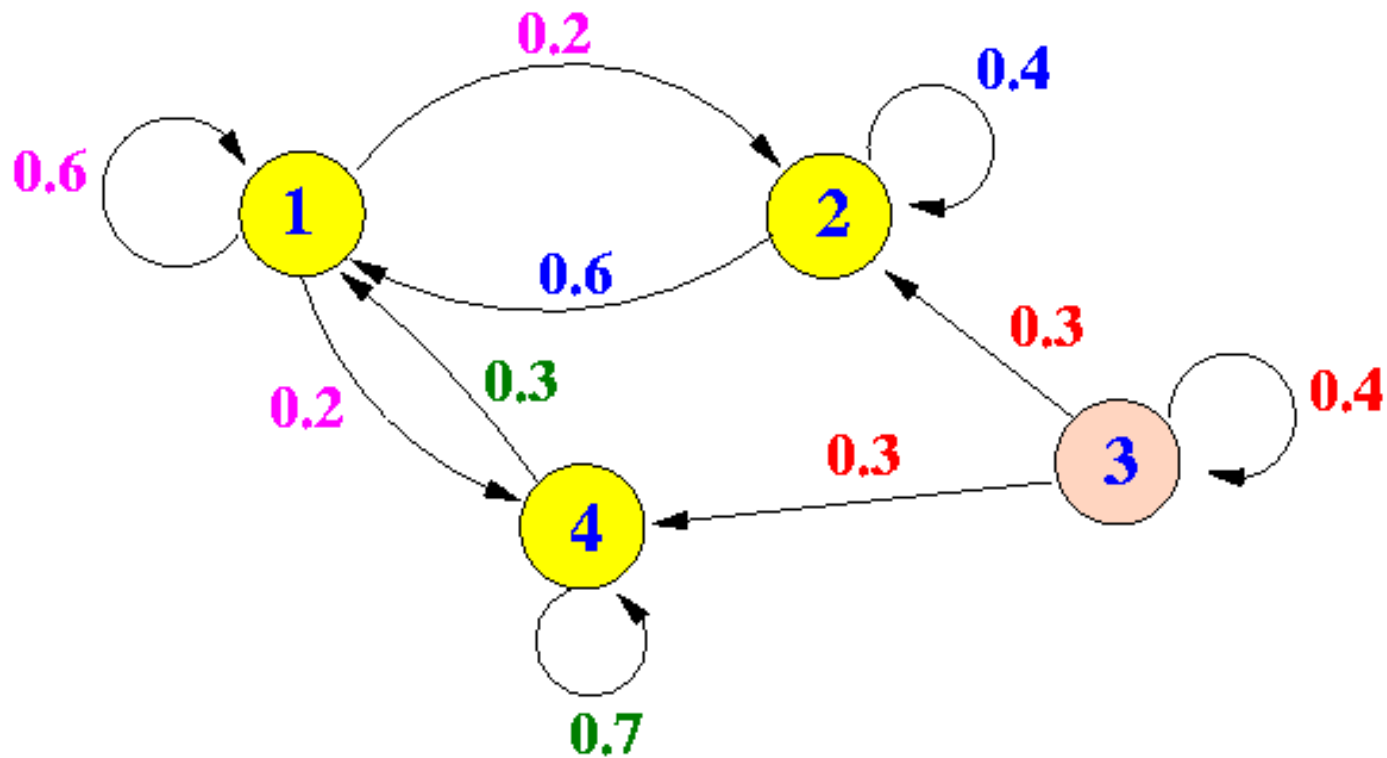
- The **stationary state** is the following **limiting probability**:

$$\pi^{(\infty)} = \lim_{(k \rightarrow \infty)} \pi^{(k)}$$

- The **stationary state** is also called the **steady state**
- (State Probability Vector after long run)

# Transient state:

- Introduced through an example of Markov chain
- Consider the following Markov chain:



# The multi-step probability matrices:

P

0.6	0.2	0.0	0.2
0.6	0.4	0.0	0.0
0.0	0.3	0.4	0.3
0.3	0.0	0.0	0.7

P2

0.54	0.20	0.	0.26
0.60	0.28	0.	0.12
0.27	0.24	0.16	0.33
0.39	0.06	0.	0.55

P3

0.5130	0.1796	0.	0.3074
0.5388	0.2056	0.	0.2556
0.4617	0.1794	0.0256	0.3333
0.4611	0.1278	0.	0.4111

P5

0.5000282111	0.1666948777	0.	0.3332769112
0.5000846332	0.1667513000	0	0.3331640668
0.4999993559	0.1666668815	0.4294967296 10	0.3333333333
0.4999153666	0.1665820333	0.	0.3335025999

P4

0.50167962	0.16834628	0.	0.32997410
0.50503884	0.17170552	0.	0.32325564
0.49901697	0.16699434	0.00065536	0.33333333
0.49496115	0.16162782	0.	0.34341103

The probability that the Markov chain is found in state 3 becomes smaller and smaller with time !!!

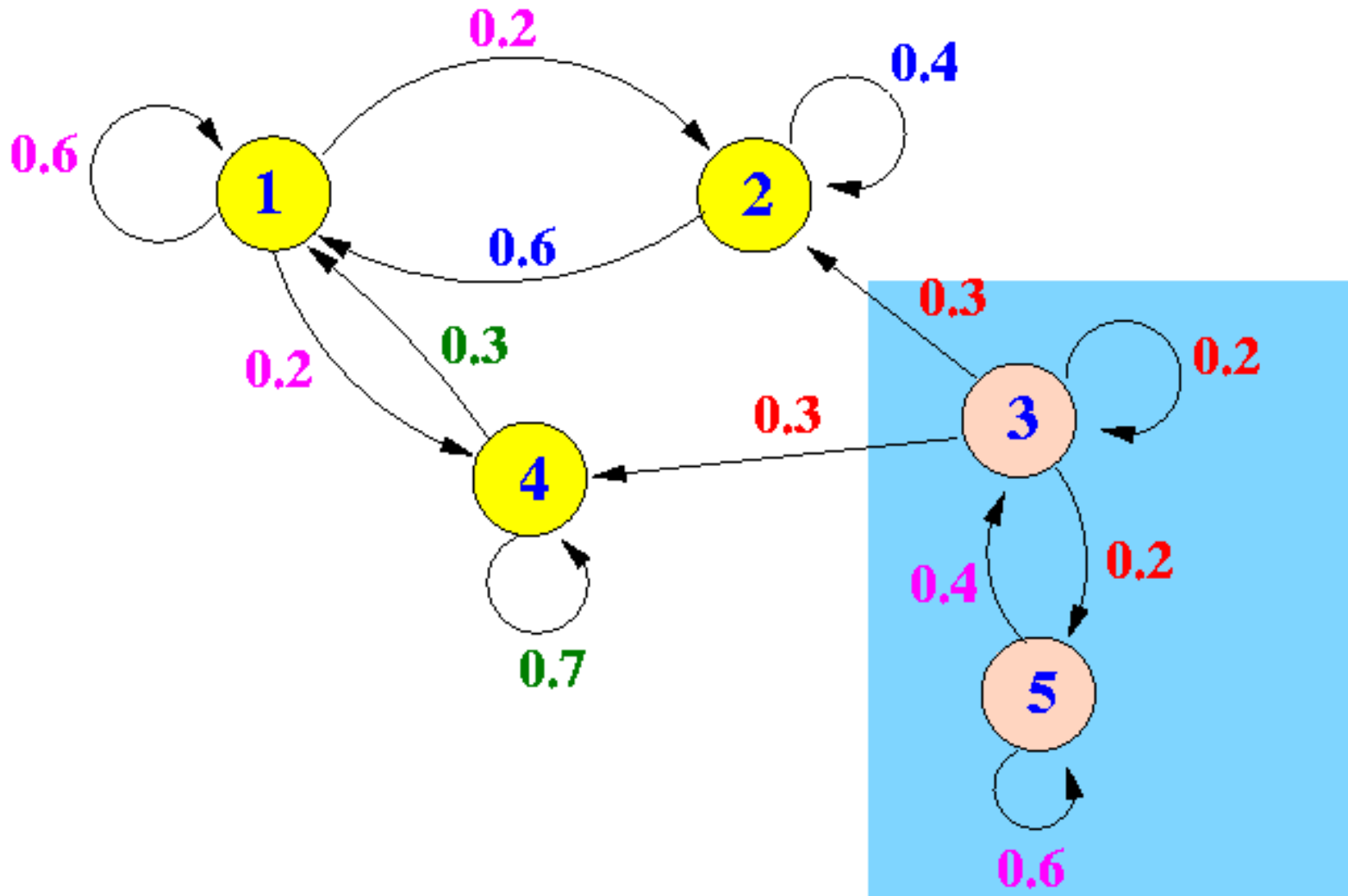
# Transient and Steady State

- **Transient state:**
- A **transient state** of a **Markov chain** is a state where the **stationary probability** is equal to **zero (0)**
- **Recurrent state:**
- A **recurrent state** of a **Markov chain** is a *non-transient* state (stationary probability nonzero)





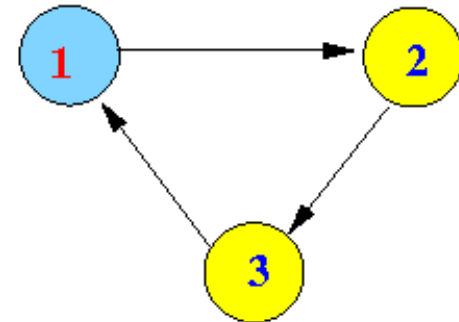
States **3** and **5** are **transient states** because once the **Markov chain** leaves these states, it will **never return back** to them.



# Periodic states:

- A **periodic state** is a special subclass of **recurrent states**
- A periodic state is a **recurrent state** say with a **period d** if it **re-occurs after exactly d steps**
- $p_{ii}^{(1)} = 0$
- $p_{ii}^{(2)} = 0 \dots$
- $p_{ii}^{(d-1)} = 0$
- $p_{ii}^{(d)} = 1$
- $p_{ii}^{(d+1)} = 0 \dots$

Initial state



The **period** of the above **Markov process** is **3**:

$p_{11}^{(1)} = 0$  (Probability that from state 1, in one step, we reach state 1)

$p_{11}^{(2)} = 0$  (Probability that from state 1, in two steps, we reach state 1)

$p_{11}^{(3)} = 1$  (Probability that from state 1, in three steps, we reach state 1)

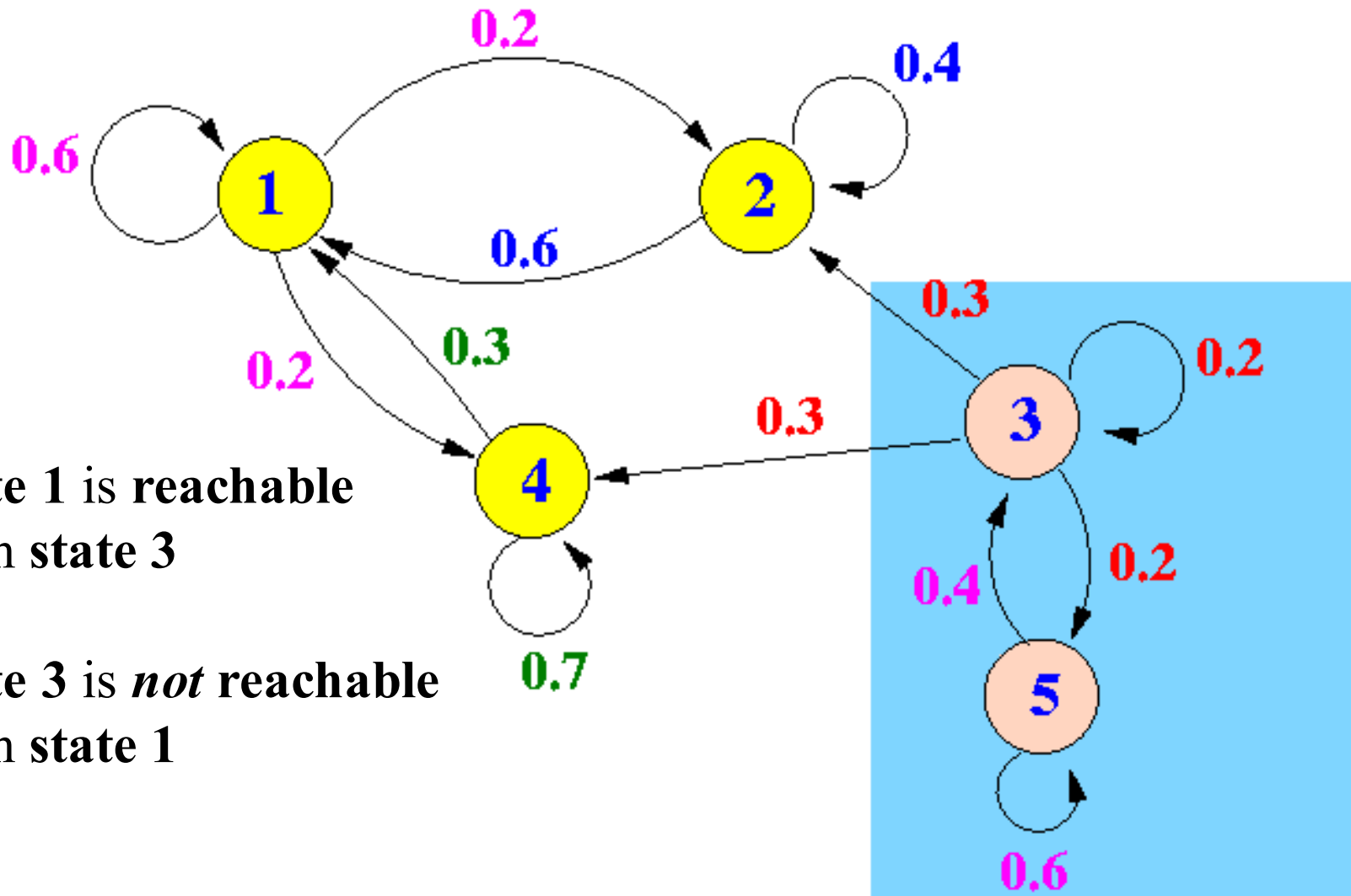
# Reachable state:

- A state **j** is **reachable** from a state **i** iff:
- $p^{(n)}_{ij} > 0$  for some  $n > 0$

i.e., there is a **non-zero probability** that we **end up in state j** starting from state **i** after a **finite number of steps n**



# Example

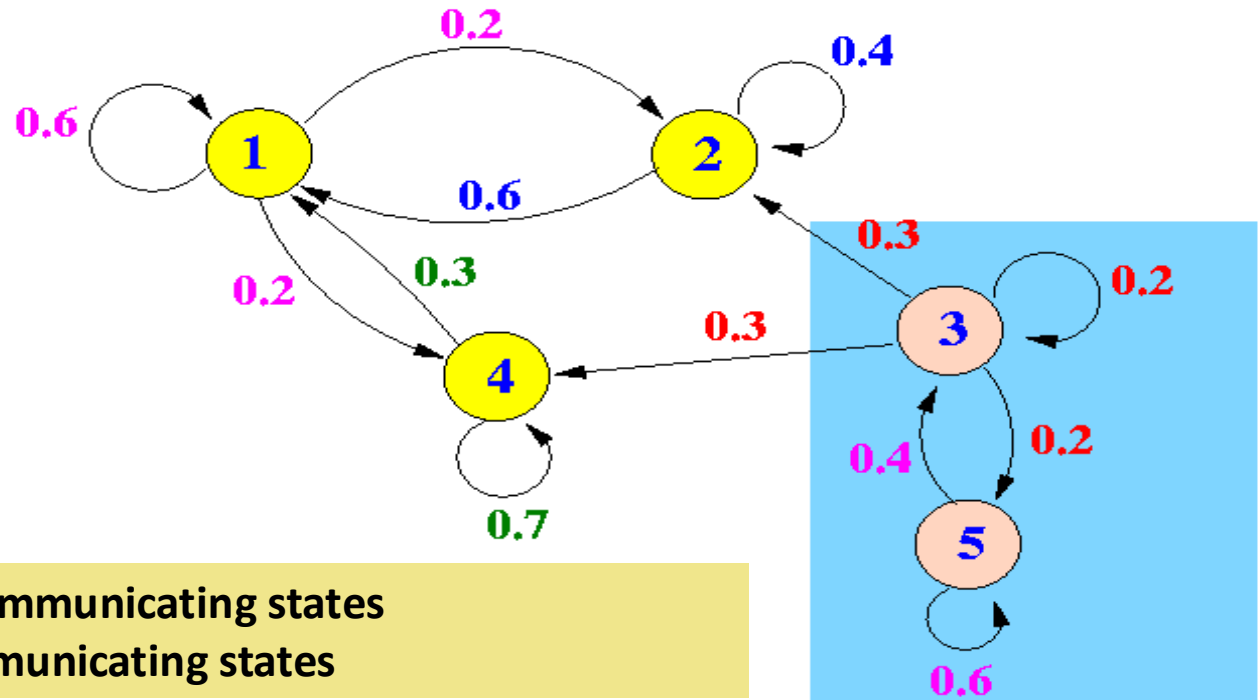


**State 1 is reachable**  
from state 3

**State 3 is *not* reachable**  
from state 1

# Communicating states:

- The states  $i$  and  $j$  are **communicating states** iff:
- **State  $j$  is reachable from state  $i$ , and State  $i$  is reachable from state  $j$**



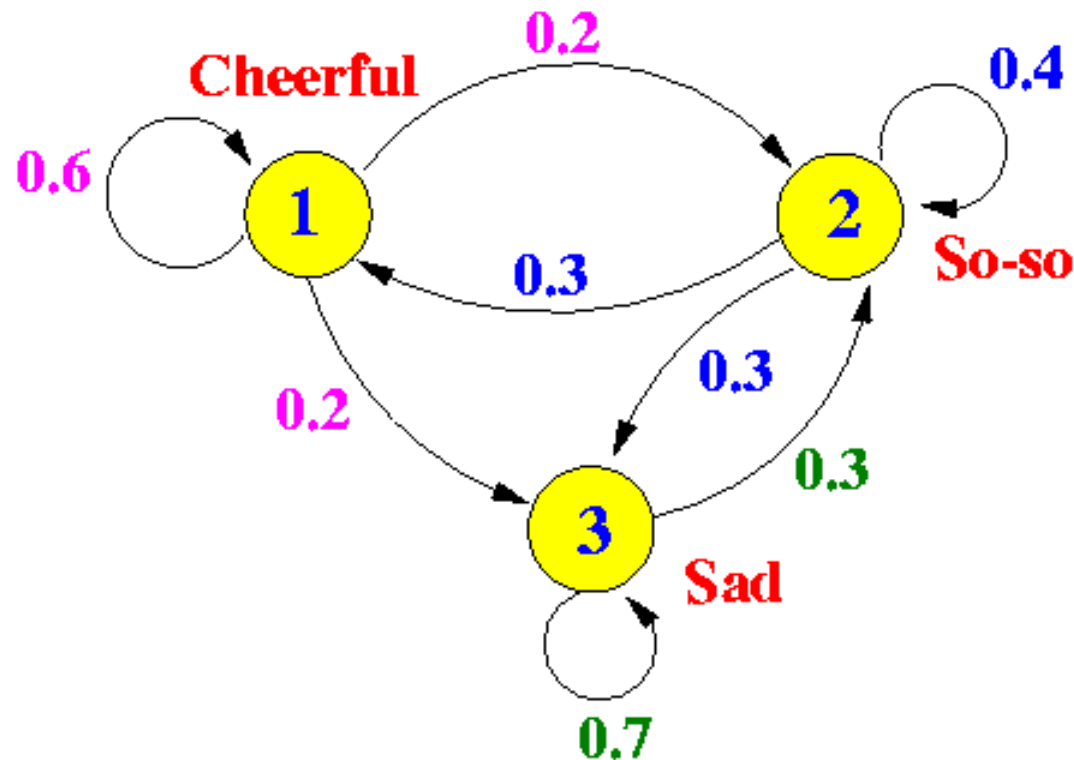
- States 1, 2 and 4 are communicating states
- States 3 and 5 are communicating states

# Chain

- A **chain C** is a **set of states** where **all members are mutually communicating**
- $\forall i, j \in C$ :
- $i$  is reachable from  $j$  and  $j$  is reachable from  $i$

# Single chain Markov process:

- A single chain Markov process is a Markov process that does not have any *transient* states



# Steady-state property of Single Chain Markov processes

- The **steady state probability** (limiting state probability) of a state is the **likelihood** that the **Markov chain** is in that state **after a long period of time**
- **Mathematically speaking:** we must find this **limit**

$$\lim_{\{n \rightarrow \infty\}} \pi^{(n)}_j$$





# Lemma 1:

- If a **Markov Chain** has a **single chain** and **no *periodic* states**, then: the **limiting state probabilities exists** and **independent** from the **initial state**

$$\lim_{\{n \rightarrow \infty\}} \pi^{(n)}_j = \pi$$

( $\pi$  is some constant)

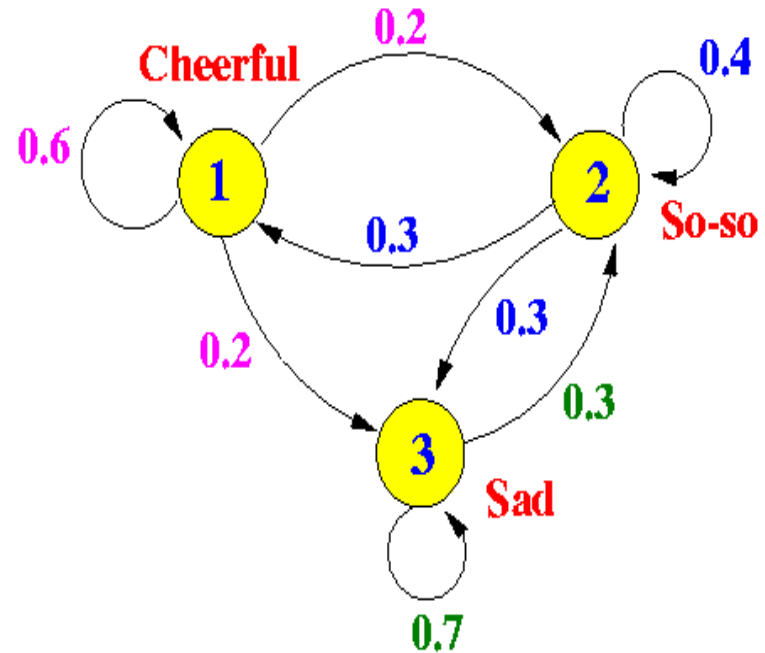
**independent** from the value of  $\pi^{(0)}_j$

# Computing steady-state probabilities (Limiting state probabilities)

One-step probability matrix:

$$P = \begin{array}{c|ccc|c} & + & - & & \\ \hline + & 0.6 & 0.2 & 0.2 & \\ - & 0.3 & 0.4 & 0.3 & \\ & 0.0 & 0.3 & 0.7 & \\ \hline & + & - & & \end{array}$$

The **example Markov chain** has: one  
single chain no recurrent states



According to **Lemma 1**, the **Markov chain** has a **steady state** and  
the **steady state** is reached from **any initial state**

# Finding the steady-state probability $\pi$

- When **Markov chain** starts in **initial state**  $\pi^{(0)}$  and make **1 step**:

$$\pi_1^{(1)} = \pi_1^{(0)}P_{11} + \pi_2^{(0)}P_{21} + \pi_3^{(0)}P_{31}$$

$$\pi_2^{(1)} = \pi_1^{(0)}P_{12} + \pi_2^{(0)}P_{22} + \pi_3^{(0)}P_{32}$$

$$\pi_3^{(1)} = \pi_1^{(0)}P_{13} + \pi_2^{(0)}P_{23} + \pi_3^{(0)}P_{33}$$

Or:

$$\pi^{(1)} = \pi^{(0)} \times P$$

# Forming the equations ...

- If the **Markov chain** is in the **steady state**, and **makes one step**, the **next state** equal to the **steady state**.
- Therefore, in the **steady state**  $\pi = (\pi_1, \pi_2, \pi_3)$ , we have:

$$\pi_1 = \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31}$$

$$\pi_2 = \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32}$$

$$\pi_3 = \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33}$$

Or:

$$\pi = \pi^{\text{Tr}} \times P \quad (\text{Tr} = \text{transpose})$$



# Caveat in solving for $\pi$

- The system of equations obtained from the one step transition probability matrix is a *dependent* system of equations because one of the equation is a linear combination of the *other* two equations:

$$\begin{aligned}\pi_1 &= \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31} \\ \pi_2 &= \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32} \\ + \quad \pi_3 &= \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33}\end{aligned}$$

# Solving equations...

$$\begin{array}{rcl} \pi_1 & = & \pi_1 P_{11} + \pi_2 P_{21} + \pi_3 P_{31} \\ \pi_2 & = & \pi_1 P_{12} + \pi_2 P_{22} + \pi_3 P_{32} \\ + & & \pi_3 = \pi_1 P_{13} + \pi_2 P_{23} + \pi_3 P_{33} \\ \hline \pi_1 + \pi_2 + \pi_3 & = & \end{array}$$

$$\pi_1(P_{11} + P_{12} + P_{13}) + \pi_2(P_{21} + P_{22} + P_{23}) + \pi_3(P_{31} + P_{32} + P_{33})$$

**Facts:**

$$P_{11} + P_{12} + P_{13} = 1$$

$$P_{21} + P_{22} + P_{23} = 1$$

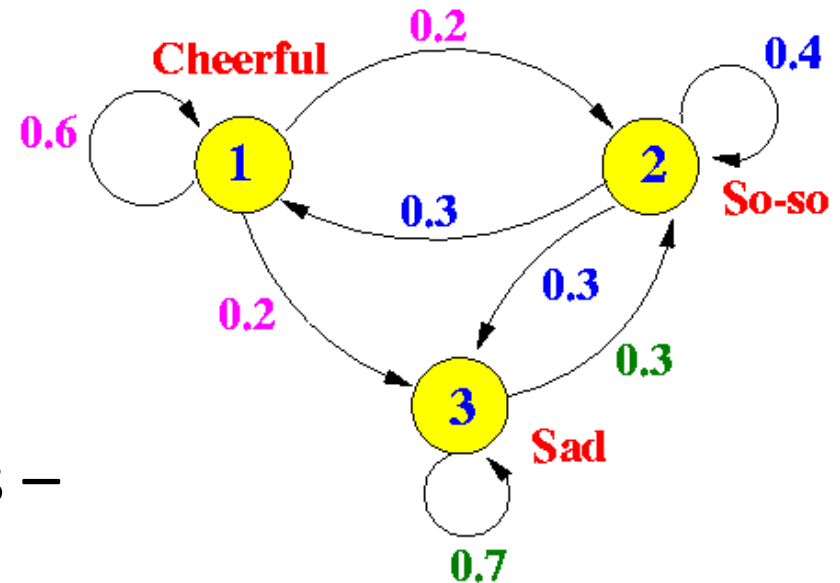
$$P_{31} + P_{32} + P_{33} = 1$$



# Solving...

- In order to **obtain a *non-dependent* system of equations**, you ***must* replace *any* one equation** in the system of equations with this equation:
- So we need to apply  $\pi_1 + \pi_2 + \pi_3 = 1$
- And then solve it...

# Example -



Steady state probability satisfies –

$$\pi_1 = 0.6 \pi_1 + 0.3 \pi_2 + 0.0 \pi_3 \quad \dots (1)$$

$$\pi_2 = 0.2 \pi_1 + 0.4 \pi_2 + 0.3 \pi_3 \quad \dots (2)$$

$$\pi_3 = 0.2 \pi_1 + 0.3 \pi_2 + 0.7 \pi_3 \quad \dots (3)$$

**And:**

$$\pi_1 + \pi_2 + \pi_2 = 1 \quad \dots (4)$$



# Solution...

Drop equation (3) and re-write into canonical form:

$$-0.4 \pi_1 + 0.3 \pi_2 + 0.0 \pi_3 = 0 \quad \dots (1)$$

$$0.2 \pi_1 - 0.6 \pi_2 + 0.3 \pi_3 = 0 \quad \dots (2)$$

$$\pi_1 + \pi_2 + \pi_3 = 1 \quad \dots (4)$$

Solving the equations—

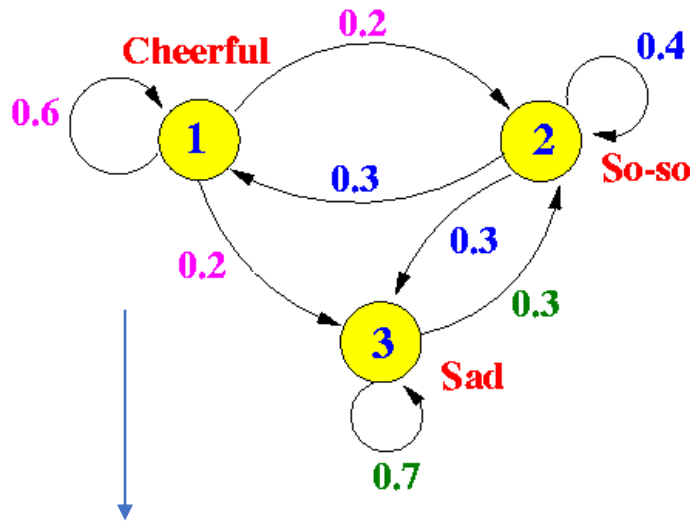
$$\pi_1 = 0.2307692308$$

$$\pi_2 = 0.3076923077$$

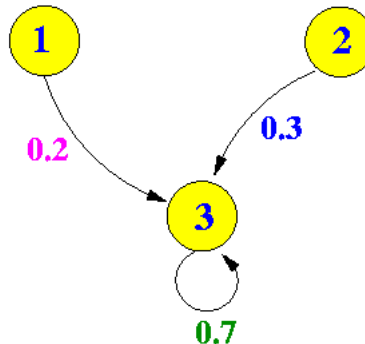
$$\pi_3 = 0.4615384615$$



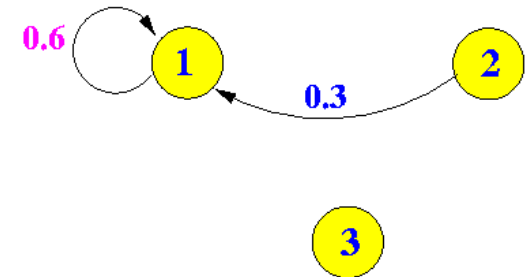
# A common way to find *equilibrium equations* for Markov chains



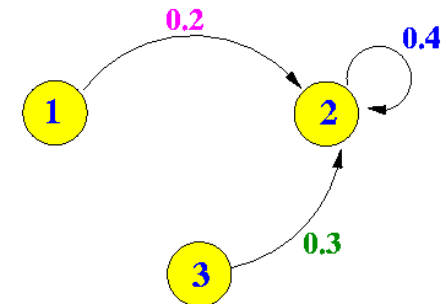
Focussing **only** on the possible ways to *get to* the state 3, we see:



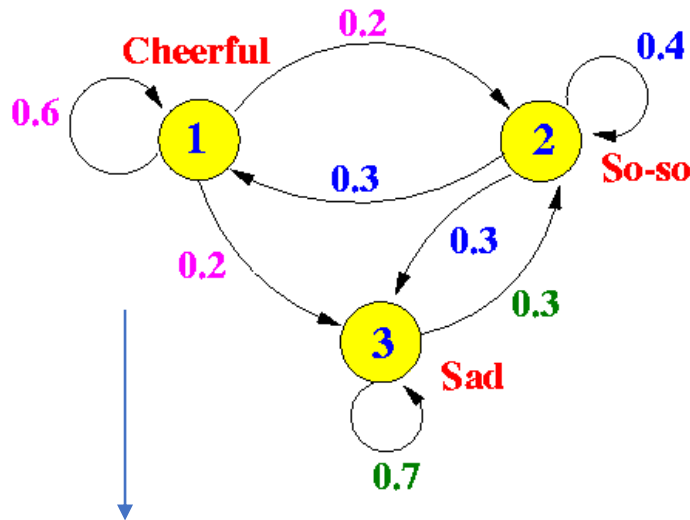
Focussing **only** on the possible ways to *get to* the state 1, we see:



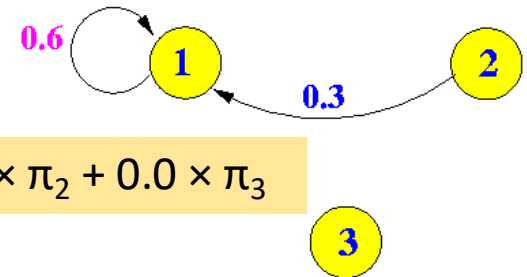
Focussing **only** on the possible ways to *get to* the state 2, we see:



# A common way to find *equilibrium equations* for Markov chains

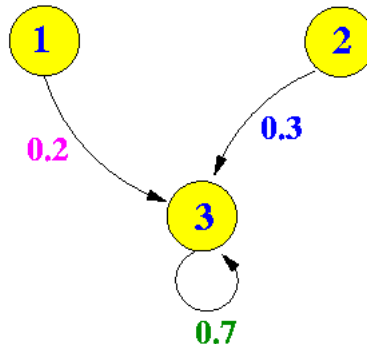


Focussing **only** on the possible ways to *get to* the state 1, we see:

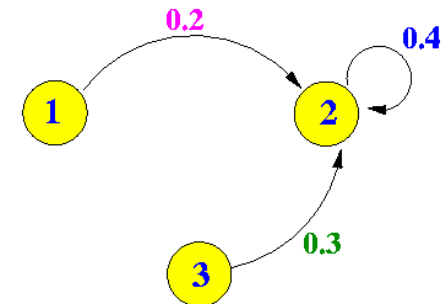


$$\pi_1 = 0.6 \times \pi_1 + 0.3 \times \pi_2 + 0.0 \times \pi_3$$

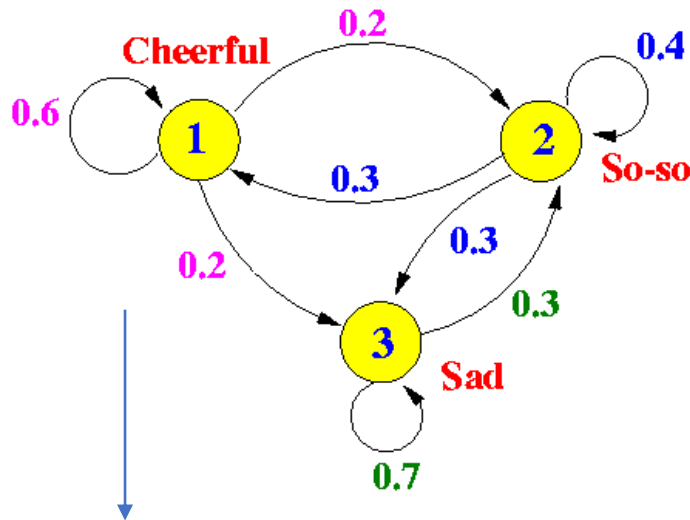
Focussing **only** on the possible ways to *get to* the state 3, we see:



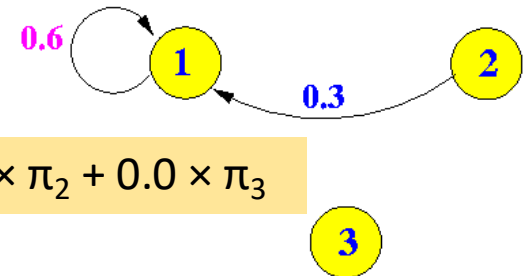
Focussing **only** on the possible ways to *get to* the state 2, we see:



# A common way to find *equilibrium equations* for Markov chains

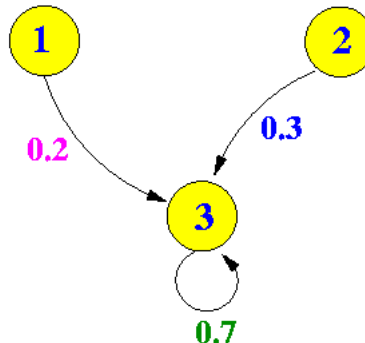


Focussing **only** on the possible ways to *get to* the state 1, we see:

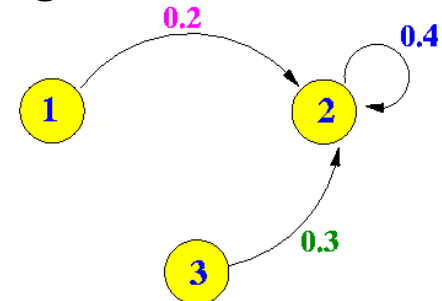


$$\pi_1 = 0.6 \times \pi_1 + 0.3 \times \pi_2 + 0.0 \times \pi_3$$

Focussing **only** on the possible ways to *get to* the state 3, we see:

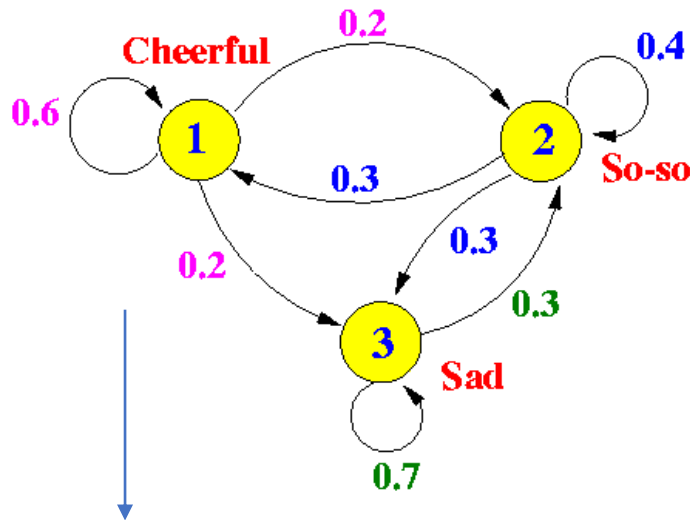


Focussing **only** on the possible ways to *get to* the state 2, we see:

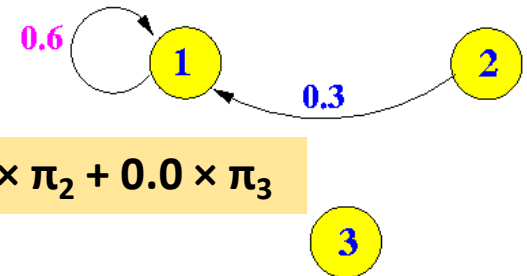


$$\pi_2 = 0.2 \times \pi_1 + 0.4 \times \pi_2 + 0.3 \times \pi_3$$

# A common way to find *equilibrium equations* for Markov chains

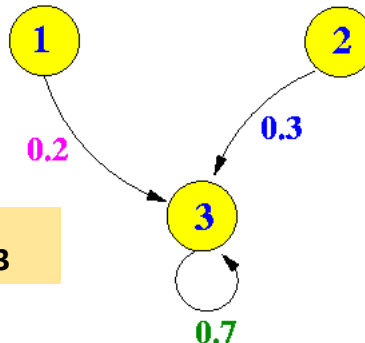


Focussing **only** on the possible ways to *get to* the state 1, we see:



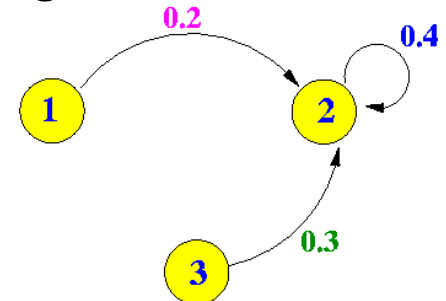
$$\pi_1 = 0.6 \times \pi_1 + 0.3 \times \pi_2 + 0.0 \times \pi_3$$

Focussing **only** on the possible ways to *get to* the state 3, we see:



$$\pi_3 = 0.2 \times \pi_1 + 0.3 \times \pi_2 + 0.7 \times \pi_3$$

Focussing **only** on the possible ways to *get to* the state 2, we see:



$$\pi_2 = 0.2 \times \pi_1 + 0.4 \times \pi_2 + 0.3 \times \pi_3$$

# Complicated situation

- In more complicated Markov chains, we may need to use multiple transitions to establish equilibrium equations