



Null Space and Range Space

Comprehensive Course on Linear Algebra

$$N(\tau) = \{ x \in V \mid \tau(x) = 0 \}$$

$N(\tau) \neq \emptyset$ $0 \in N(\tau)$ always.

(c) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$T(x, y, z) = (x+z, y, 0)$$

(a) $N(T)$

(b) Basis of $N(T)$

(c) $\eta(T)$

$$N(T) = \{ (x, y, z) \in \mathbb{R}^3 \mid T(x, y, z) = (0, 0, 0) \}$$

$$T(x, y, z) = (0, 0, 0)$$

\downarrow

$$(x+z, y, 0) = (0, 0, 0)$$

$$y = 0$$

$$x + \textcircled{z} = 0$$

\downarrow free variable.

$$N(T) = \{ (-z, 0, z) \mid z \in \mathbb{R} \}$$

$$N(1) = \{ \underline{(-z, 0, z)} \mid z \in \mathbb{R} \}$$

$$\dim N(1) = n(1) = 1$$

$$\text{Basis} = \{ (-1, 0, 1) \}$$

$$\begin{aligned} y &= 0 \\ x + z &= 0 \end{aligned}$$

$$N(1) = \left\{ \underline{(x, 0, -x)} \mid x \in \mathbb{R} \right\} \quad z = -x$$

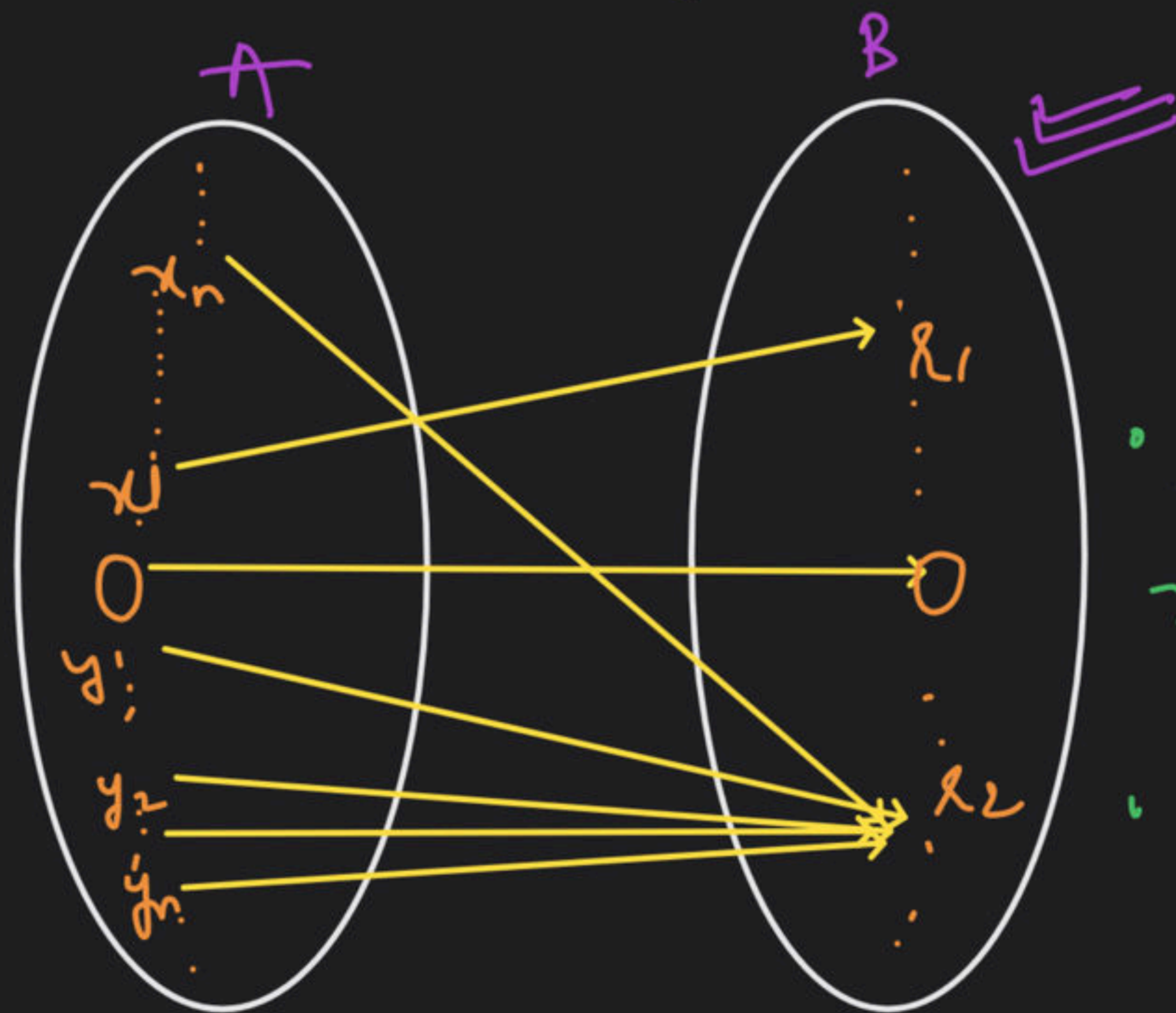
$$\text{Basis} = \{ (1, 0, -1) \}$$

$$\text{dim } \textcircled{1}$$

$$f: A \rightarrow B$$

$$\text{Range}(f) = \{ y \in B \mid \exists x \in A : f(x) = y \}$$

$$\text{R}(f) = \{ r_1, r_2, 0 \}$$



$$f(x_i) = r_1$$

- r_1 is image of x_i under f
- x_i is preimage of r_1 under f

Range space

Let V and W be F.D.V.S. over the same field F . Let $T: V \rightarrow W$ be a

LT. then

$$R(T) = \{ y \in W \mid \exists x \in V, T(x) = y \}$$

↓

range space of T .

$$R(T) \subseteq W$$

$\therefore T$ is a LT

$$T: V \rightarrow W$$

$$\begin{array}{ccc} T(0) & = & 0 \\ \downarrow & & \downarrow \\ \in V & & \in W \end{array}$$

$R(T)$ will always be a non-empty set.

for $0 \in W$ \exists always $0 \in V$ st.
 $0 \in R(T).$

THEOREM : Let V and W are F.D.V.S. over the same field F . Let $T: V \rightarrow W$ be a LT. Then range space of T is a sub-space of W .

Proof : $R(T) = \{ y \in W \mid \exists x \in V : T(x) = y \}$

$$\because T(0) = 0 \Rightarrow 0 \in R(T) \Rightarrow R(T) \neq \phi$$

$$\Rightarrow \forall u, v \in R(T), \forall \alpha, \beta \in F$$

Claim : $\alpha u + \beta v \in R(T)$.

$$\therefore u, v \in R(T) \quad , \quad \exists \quad \underline{x_1, x_2 \in V} \text{ st}$$

$$T(x_1) = u \quad \text{and} \quad T(x_2) = v$$

$$\therefore u, v \in W \text{ and } W \text{ is a V.S.} \quad \Rightarrow \quad \alpha u + \beta v \in W$$

$$\forall \alpha, \beta \in F.$$

$$\begin{aligned} \alpha u + \beta v &= \alpha \cdot T(x_1) + \beta T(x_2) \\ &= T(\alpha x_1) + T(\beta x_2) \quad (\because T \text{ is L}) \\ &= T(\alpha x_1 + \beta x_2) \end{aligned}$$

$$\alpha x_1 + \beta x_2 \in V \quad \therefore \quad \forall \quad \underline{z \in V} \text{ is a V.S.}$$

for $\alpha u + \beta v$, $\exists \alpha x_1 + \beta x_2 \in V$ s.t.

$$T(\alpha x_1 + \beta x_2) = \alpha u + \beta v$$

$$\Rightarrow \alpha u + \beta v \in R(T)$$

$\Rightarrow R(T)$ is a sub-space of W .

$$T: V \rightarrow W$$

$\therefore R(T) \leq W \Rightarrow R(T)$ is a sub-space of W .

$$\dim(R(T)) \leq \dim W$$

dimension of range space of T is called as rank of T , and represented by $\rho(T)$.

(eg)

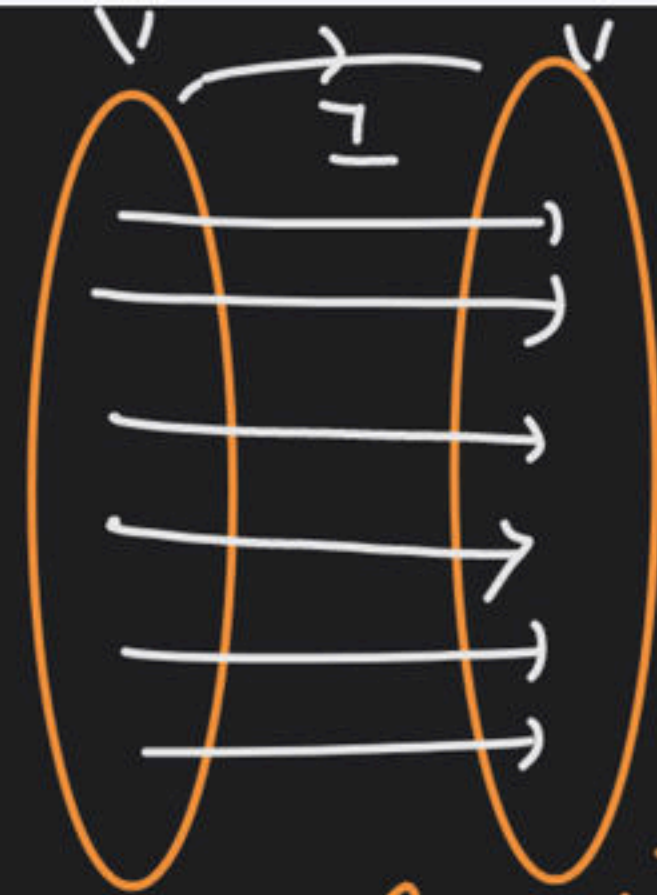
$$I: V \rightarrow V$$

$$I(x) = x$$

$$N(T) = \{0\}$$

$$B \text{ of } N(T) = \emptyset$$

$$R(T) = V$$



$$\eta(T) = 0$$

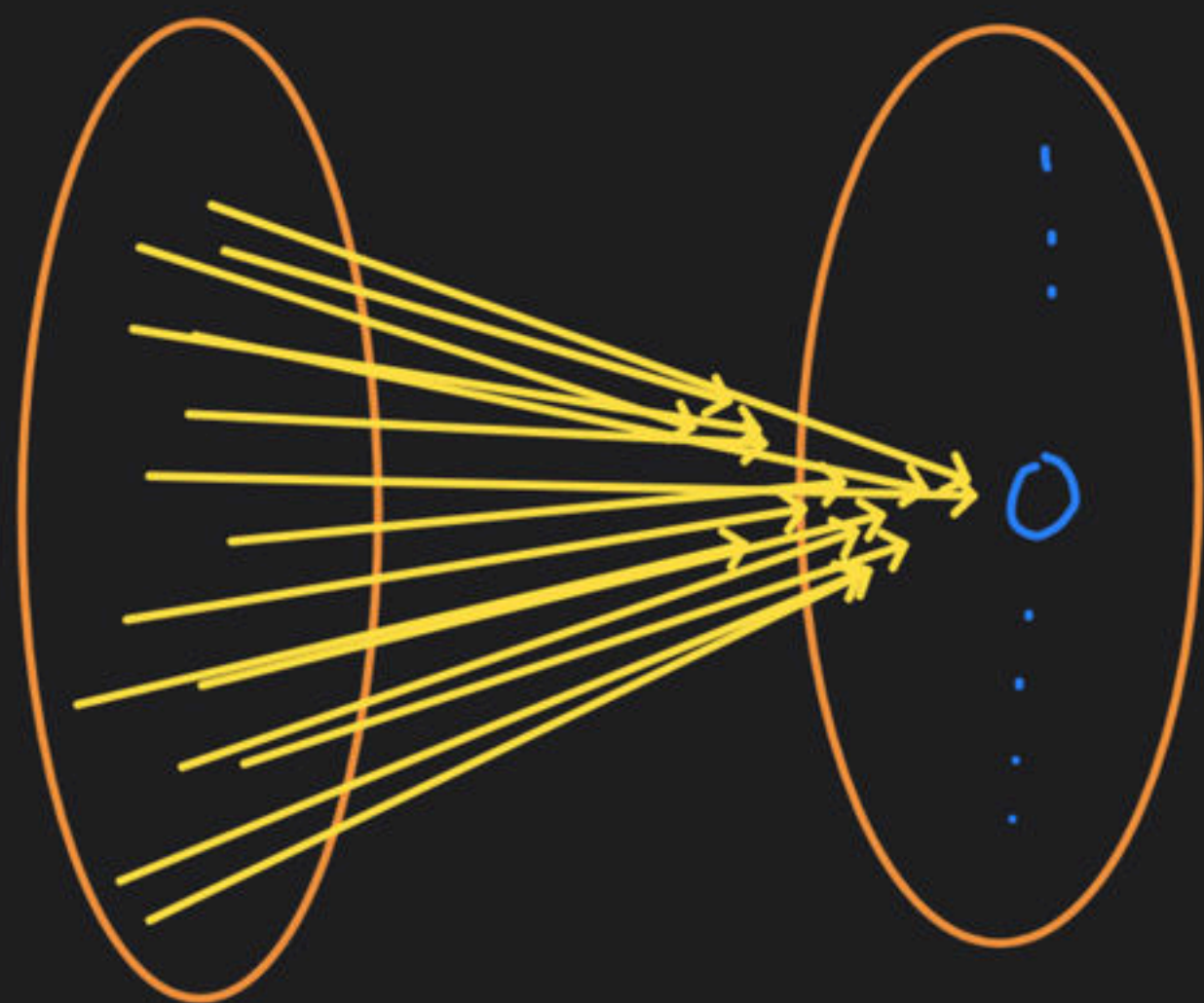
$$B \text{ of } R(T) = \text{Basis of } V$$

$$\dim(R(T)) = \rho(T) = \dim \text{ of } V.$$

(eg) Zero Trans.

$$T: V \rightarrow W$$

$$T(x) = 0$$



$$\underline{N(T) = V}$$

$$R(T) = \{ 0 \}$$

$$\eta(T) = \dim V$$

$$\ell(T) = 0$$

$$(eg) \quad T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$T(x, y, z) = (x + y, y + z)$$

$$\Rightarrow N(T) = \{ (x, y, z) \in \mathbb{R}^3 \mid \underbrace{T(x, y, z)}_{= (0, 0)} = (0, 0) \}$$

$$N(T) = \{ (z, -z, z) \mid z \in \mathbb{R} \}$$

$$\dim N(T) = n(\downarrow) = 1$$

$$B = \{ (1, -1, 1) \}$$

$$(x + y, y + z) = (0, 0)$$

$$x + y = 0$$

$$y + z = 0$$

$$x = -y \quad \text{and} \quad x = z$$

$$y = -z$$

$$T(x, y, z) = (x+y, y+z)$$

$$R(T) = \{ y \in \mathbb{R}^2 \mid \exists x \in \mathbb{R}^3 ; T(x) = y \}$$

$$x_1, x_2, x_3$$

nn.



$$y = (y_1, y_2)$$

s_1

\exists

$$x = (x_1, x_2, x_3) \in \mathbb{R}^3$$

$$T(x_1, x_2, x_3) = (y_1, y_2)$$

$$(x_1 + x_2, x_2 + x_3) = (y_1, y_2)$$

$$x_1 + x_2 = y_1$$

$$x_2 + x_3 = y_2$$

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$B = \{ (1, 0), (0, 1) \}$$

$$T(x, y, z) = (x + y, y + z)$$

$$T(e_1) = T(1, 0, 0) = (1, 0) \quad \sim \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$$

$$T(e_2) = T(0, 1, 0) = (1, 1)$$

$$T(e_3) = T(0, 0, 1) = (0, 1)$$

$$\begin{bmatrix} \boxed{1 \ 0} \\ \boxed{0 \ 1} \\ 0 \ 0 \end{bmatrix} \quad \rho(\underline{T}) = 2$$

$$\sim \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{bmatrix} \sim$$

$$x_1 + x_2 = y_1$$

$$x_2 + x_3 = y_2$$

$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & y_1 \\ 0 & 1 & 1 & y_2 \end{array} \right]$$

$$\rho(A) = 2 = \rho(A|B)$$

soln. exists

(x_1, x_2, x_3) exists

$$\dim R(T) = 2$$

2

$$\begin{array}{r} = 3 - 2 + 1 \\ \hline = 2 \end{array}$$

No sy.

$$= n - r$$

Non no.

$$= n - r + 1$$

