## REPORT: HENSEL LIFTING AND NEWTON ITERATION IN VALUTATION RINGS

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## CONTENTS

CHAPTER 1	Introduction	Page 2
CHAPTER 2	Hensel Lifting	PAGE 3
2.1		3
2.2	2 Conditions related to Hensel's Lemma	4
2.3	Hensel's Lemma	5
2.4	Hensel's Computation	6
2.5	Proof of Hensel's Lemma	6
CHAPTER 3	Newton Iteration	Page 8
Chapter 4	Solving Differential Equations	Page 9
CHAPTER 5	Finding Short Vectors in Modules	

CHAPTER 6 FACTORIZATION OF POLYNOMIALS PAGE 11

## Introduction

### **Hensel Lifting**

The hensel method described here will lift an approximate factorization of a polynomial over a Hensel Ring R with valuation v where the factors are relatively prime. We will show a linear convergence and a quadratic convergence behavior for the liftings.

#### 2.1 Hensel Ring

#### **Definition 2.1.1: Hensel Ring**

A ring with valuation  $v:R \to \mathbb{R}_{\geq 0}$  is called a Hensel Ring if:

- (i)  $\forall a \in R, v(a) \leq 1$
- (ii)  $\forall a, b \in R, \forall \epsilon > 0, \exists c \in R \text{ such that } (v(a) \le v(b) \implies v(a bc) \le \epsilon)$

In other words R is Hensel iff it is contained and dense in the valuation ring of its quotient field (with respect to the unique extension of v). We sometimes call such v a Hensel Valuation.

In condition (ii) we assume we can compute the c efficiently.

#### Theorem 2.1.1

Condition (i) of Hensel Ring  $\implies v$  is Non-Archimedean.

*Proof.* Let  $a, b \in R$ . Now

$$\begin{split} v(a+b)^k &= v((a+b)^k) \\ &= v\left(\sum_{i=0}^k \binom{k}{i} a^{n-i} b^i\right) \le \sum_{i=0}^k v\left(\binom{k}{i}\right) v(a)^{n-i} v(b)^i \\ &\le \sum_{i=0}^k v(a)^{n-i} v(b)^i \le \sum_{i=0}^k M^{n-i} M^i \\ &= \sum_{i=0}^k M^k = M^k (k+1) \end{split}$$
  $[m = \max v(a), v(b)]$ 

Hence

$$\left(\frac{v(a+b)}{M}\right)^k \le (k+1) \iff \frac{v(a+b)}{M} \le (1+k)^{\frac{1}{k}}$$

As  $k \to \infty$  the RHS approaches 1 so  $v(a+b) \le M$ .

#### **Example 2.1** (p-adic Valuations)

- $\mathbb{Z}$  with p-adic valution  $v_p$  where  $p \in \mathbb{N}$  is prime is a Hensel ring. Here  $v_p(a) = p^{-n}$  where  $n = \max\{k \ge 1\}$  $0 \mid p^k \mid a$
- $\mathbb{F}[y]$  with p-adic valutaion  $v_p$  where  $p \in \mathbb{F}[y]$  is an irreducible polynomial is a Hensel Ring. Here  $v_p(f) =$  $2^{-n \deg p}$  where  $n = \max\{k > 0 \mid p^k \mid f\}$

#### Note:-

From the valuation v over R we naturally get a valuation v over the polynomial ring R[x] by defining

$$\forall f \in R[x], \text{ let } f = \sum_{i=0}^{n} f_i x^i, \text{ then } v\left(\sum_{i=0}^{n} f_i x^i\right) = \max_i \{v(f_i)\}$$

#### Conditions related to Hensel's Lemma 2.2

We will define 5 conditinos. First suppose we have:

- (1)  $f \in R[x]$   $\mathcal{F} = \{f_i : 0 \le i \le m\}$ (2)  $f_0, \dots, f_m \in R[x]$   $\mathcal{F} = \{f_i^* : 0 \le i \le m\}$ (3)  $f_0^*, \dots, f_m^* \in R[x]$   $\mathcal{F}^* = \{f_i^* : 0 \le i \le m\}$ (4)  $s_0, \dots, s_m \in R[x]$   $\mathcal{S} = \{s_i : 0 \le i \le m\}$ (5)  $s_0^*, \dots, s_m^* \in R[x]$   $\mathcal{S}^* = \{s_i^* : 0 \le i \le m\}$

- (7)  $\alpha, \delta, \epsilon \in \mathbb{R}$
- $(8) \quad \delta^* \in \mathbb{R}$
- $\gamma = \max\{\delta, \alpha\epsilon\}$

As you can see the set  $\mathcal{F}^*$  basically represents the lift of  $\mathcal{F}$  but here since we are saying the conditions in more generality we are not assuming any relations among them and we define some conditions involving them.

• 
$$H_1(m, f, \mathcal{F}, \mathcal{S}, \epsilon) := v\left(f - \prod_{i=0}^m f_i\right) \le \epsilon < 1$$

• 
$$H_2(m, f, \mathcal{F}, \mathcal{S}, z, \delta) := v\left(\sum_{i=0}^m s_i \prod_{j \neq i} f_i - z\right) < leq \delta < 1$$

• 
$$H_3(m, f, \mathcal{F}, S, z, \alpha, \delta, \epsilon) := (1)$$
  $f_1, \dots, f_m$  are monic  
(2)  $\deg \left(\prod_{i=0}^m f_i\right) \leq \deg f$   
(3)  $\deg s_i \leq \deg f_i \ \forall \ i \in [m]$   
(4)  $\alpha \delta \leq 1, \alpha \epsilon^2 \leq 1$ 

(2) 
$$\deg\left(\prod_{i=0}^{m} f_i\right) \leq \deg f$$

• 
$$H_4(m, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon) := (1)$$
  $v(f_i^* - f_i) \le \alpha \epsilon$   $\forall 0 \le i \le m$   
(2)  $v(s_i^* - s_i) \le \alpha \epsilon$   $\forall 0 \le i \le m$   
(3)  $\deg f_i^* = \deg f_i$   $\forall i \in [m]$   
(4)  $\deg s_i < \deg f_i \implies \deg s_i^* < \deg f_i^*$   $\forall i \in [m]$ 

(3) 
$$\operatorname{deg} f^* = \operatorname{deg} f$$
:  $\forall i \in [m]$ 

(4) 
$$\deg s_i < \deg f_i \implies \deg s_i^* < \deg f_i^* \quad \forall i \in [m]$$

- $H_5(m, f, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon, \delta^*) := \text{Let } p \in [m]$ . Then suppose
  - $\mathcal{I}_p = \{I_0, I_1, \dots, I_p\}$  be a partition of  $\{0, \dots, m\}$  with  $o \in I_0$ .
  - $\overline{\mathcal{F}}_v^m=\{\overline{f}_i\colon i\in[p]\}\subseteq R[x]$  be a set of monic polynomials

Then define:

$$F_i = \prod_{j \in I_i} f_j, \qquad F_i^* = \prod_{j \in I_i} f_j^*, \qquad \mathfrak{s}_i^* = \sum_{j \in I_i} s_j \frac{F_i^*}{f_i^*}$$

So now we denote:

$$\mathscr{F} = \{F_i : 0 \le i \le p\}, \qquad \mathscr{F}^* = \{F_i : 0 \le i \le p\}, \qquad \mathscr{S} = \{\mathfrak{s}_i^* : 0 \le i \le p\}$$

Assume:

1. 
$$v(\overline{f}_i - F_i) \le \alpha \epsilon \ \forall \ i \in [p]$$

2. 
$$\alpha v(s_i) \leq 1 \ \forall \ 0 \leq i \leq m$$

3. 
$$\alpha \delta < 1, \alpha^2 \delta < 1$$

4. 
$$\alpha^2 \epsilon < 1, \alpha^3 \epsilon < 1$$

Then the following are equivalent:

(i)  $\exists \overline{f}_0, \overline{s}_0, \dots, \overline{s}_p \in R[x]$  denote

$$\overline{\mathcal{F}} = \{\overline{f}_i \colon 0 \le i \le p\}, \qquad \overline{\mathcal{S}} = \{\overline{s}_i \colon 0 \le i \le p\}$$

then the following conditions are true:

- (a)  $H_1(p, f, \overline{\mathcal{F}}, \overline{\mathcal{S}}, \epsilon^*)$
- (b)  $H_2(p, f, \overline{\mathcal{F}}, \overline{\mathcal{S}}, z, \delta^*)$
- (c)  $H_3(p, f, \overline{\mathcal{F}}, \overline{\mathcal{S}}, z, \alpha^*, \delta^*, \epsilon^*)$
- (d)  $H_4(p, f, \mathscr{F}, \overline{\mathcal{F}}, \mathscr{S}, \overline{\mathcal{S}}, z, \alpha^*, \delta^*, \epsilon^*)$

where 
$$\alpha^* = \alpha$$
,  $\epsilon^* = \alpha \epsilon \gamma$ 

- (ii)  $\exists \overline{f}_0 \in R[x]$  such that  $H_1(p, f, \overline{\mathcal{F}}, \overline{\mathcal{S}}, \epsilon^*)$  is true
- (iii)  $\forall i \in [p]$  we have  $v(\overline{f}_i F_i^*) \le \epsilon^*$ .

The first 3 conditions here togather imply that: From  $H_1$  we get that  $f_0 \cdots f_m$  is a good approximation of factorization of f with  $\epsilon$ -precision,  $H_2 \Longrightarrow z$  plays a similar role to the gcd of  $f_0, \ldots, f_m$  and it shows the generalized bezout's identity for gcd for multiple elements. In the usual treatment of Hensel's Lemma  $f_0, \ldots, f_m$  are relatively prime (more precisely their images in the residue class field or R modulo the maximal ideal  $\langle a \in R \mid v(a) < 1 \rangle$  satisfy the assumption then one can find  $s_0, \ldots, s_m, \delta$  satisfying  $H_2$  with z=1. One can set  $\alpha=1$  or in general one can choose  $\alpha=\frac{1}{v(z)}$ . Thus  $H_2$  staes that  $f_0, \ldots, f_m$  are approximately pairwise relatively prime.

 $H_4$  shows the connection between the lifts  $f_i^*$ ,  $s_i^*$  and  $f_i$ ,  $s_i$ .

 $H_5$  basically states that the lifts are unique in the sense that one can group some of the  $f_i's$  to form  $F_0, \ldots, F_p$  and change  $F_i$  to  $\overline{f}_i$  with precision  $\epsilon^*$  and still one will have the factorization of f with precision  $\epsilon^*$ .  $H_5$  is very important for the factorization algorithm in chapter 6.

Now we will state the Hensel's Lemma and will later give the algorithm to obtain the lifts.

#### 2.3 Hensel's Lemma

First we will prove a helping lemma which will be very much usefull in the proof of Hensel's Lemma then we will state the actual theorem.

#### Theorem 2.3.1

- (i) Let  $a,f,p,s\in R[x]$  such that f is monic and s=pf+a with  $\deg a<\deg f$ . Then we have  $v(p)\leq v(s)$  and  $v(a)\leq v(s)$
- (ii) Let  $h_0, \ldots, h_m \in R[x]$  and  $h_0^*, \ldots, h_m^* \in R[x]$  such that we have  $v(h_i^* h_i) \le \epsilon$  for all  $0 \le i \le m$ . Then we have  $v\left(\prod_{i=0}^m h_i \prod_{i=0}^m h_i^*\right) \le \epsilon$

#### Theorem 2.3.2 Hensel's Lemma

Assume that we have  $f \in R[x]$ ,  $\mathcal{F} = \{f_0, \ldots, f_m\} \subseteq R[x]$ ,  $\mathcal{S} = \{s_0, \ldots, s_m\} \subseteq R[x]$ ,  $z \in R$  and  $\alpha, \delta, \epsilon \in \mathbb{R}$  which satisfy:

- 1.  $H_1(m, f, \mathcal{F}, \mathcal{S}, \epsilon)$
- 2.  $H_2(m, f, \mathcal{F}, \mathcal{S}, z, \delta)$
- 3.  $H_3(m, f, \mathcal{F}, S, z, \alpha, \delta, \epsilon)$

Then we can compute efficiently

$$\mathcal{F}^* = \{ f_i^* : 0 \le i \le m \}$$
 and  $T = \{ t_0, \dots, t_m \}$ 

such that

- (i) **Linear Case**:  $S^* = S$  and  $\delta^* = \gamma$ ,  $\epsilon^* = \alpha \gamma \epsilon$ . Then we have the following conditions hold:
  - (a)  $H_1(m, f, \mathcal{F}^*, \mathcal{S}^*, \epsilon^*)$
  - (b)  $H_2(m, f, \mathcal{F}^*, \mathcal{S}^*, z, \delta^*)$
  - (c)  $H_3(m, f, \mathcal{F}^*, \mathcal{S}^*, z, \alpha, \delta^*, \epsilon^*)$
  - (d)  $H_4(m, f, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon)$
  - (e)  $H_5(m, f, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon, \delta^*)$
- (ii) **Quadratic Case**:  $S^* = T$  and  $\delta^* = \alpha \gamma^2$ ,  $\epsilon^* = \alpha \gamma \epsilon$ . Assume that  $\deg s_i > \deg f_i$  for  $0 \le i \le m$ . Then we have the following conditions hold:
  - (a)  $H_1(m, f, \mathcal{F}^*, \mathcal{S}^*, \epsilon^*)$
  - (b)  $H_2(m, f, \mathcal{F}^*, \mathcal{S}^*, z, \delta^*)$
  - (c)  $H_3(m, f, \mathcal{F}^*, \mathcal{S}^*, z, \alpha, \delta^*, \epsilon^*)$
  - (d)  $H_4(m, f, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon)$
  - (e)  $H_5(m, f, \mathcal{F}, \mathcal{F}^*, \mathcal{S}, \mathcal{S}^*, \alpha, \delta, \epsilon, \delta^*)$

#### Hensel's Computation 2.4

```
Algorithm 1: Hensel's Computation
    Input:
         1. f \in R[x], \mathcal{F} = \{f_0, \dots, f_m\} \subseteq R[x], \mathcal{S} = \{s_0, \dots, s_m\} \subseteq R[x]
        z \in R
        3. \alpha, \delta, \epsilon \in \mathbb{R}
    Output: \mathcal{F}^* = \{f_0^*, \dots, f_m^*\}, T = \{t_0, \dots, t_m\}
 1 begin
         Set \gamma = \max\{\delta, \alpha\epsilon\}, \alpha^* = \alpha, \epsilon^* = \alpha\gamma\epsilon \text{ and } e = f - \prod_{i=0}^m f_i
 2
         for 1 \le i \le m do
 3
               Compute a_i, b_i, p_i \in R[x] such that
 4
                                          s_i e = p_i f_i + a_i, v(zb_i - a_i) \le \epsilon \gamma, \deg b_i \le \deg a_i < \deg f_i
         Compute a_0, b_0 \emptyset = inR[x] such that
 5
                                     a_0 = s_0 e + f_0 \sum_{i=1}^m p_i, \qquad v(zb_0 - a_0) \le \epsilon \gamma, \qquad \deg b_0 \le \deg f - f_i
         for 0 \le i \le m do
          f_i^* = f_i + b_i
         for 1 \le i \le m do
 8
               Compute c_i, d_i, g_i^*q_i \in R[x] such that
                      g_i^* = \prod_{i \neq i} f_i^*, s_i(s_i g_i^* - z) = q_i f_i^* + c_i v(z d_i - c_i) \le \gamma^2 \deg d_i \le \deg c_i < \deg f_i^*
         Compute g_0^* = \prod_{i=1}^m f_i^* and c_0, d_0 \in R[x] such that
            c_0 = s_o \left( \sum_{i=0}^m s_i g_i^* - z \right) + f_0^* \sum_{i=1}^m \left[ q_i + s_i \left( \sum_{i \neq i} s_j \frac{g_j^*}{f_i^*} \right) \right], \quad v(zd_0 - c_0) \le \gamma^2, \quad \deg d_0 \le \deg f - \deg g_0
         for 0 \le i \le m do
11
          t_i = s_i - d_i
12
         return \mathcal{F}^* = \{f_i^* : 0 \le i \le m\}, T = \{t_i : 0 \le i \le m\}
```

#### **Proof of Hensel's Lemma** 2.5

13

## **Newton Iteration**

# Chapter 4 Solving Differential Equations

## **Chapter 5 Finding Short Vectors in Modules**

## **Factorization of Polynomials**