### CSS.201.1 Algorithms

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## Finding Closest Pair of Points

**Problem:** Given a set of points find the closest pair of points in  $\mathbb{R}^2$ .

**Input:** Set  $S = \{(x_i, y_i) \mid x_i, y_i \in \mathbb{R}, \forall i \in [n]\}$ . We denote  $P_i = (x_i, y_i)$ .

**Output:**  $P_i, P_j$  that are at minimum  $l_2$  distance i.e. minimize  $\sqrt{(x_i - x_j)^2 + (y_i - y_j)^2}$ .

#### 1.1 Naive Algorithm

Now the naive algorithm for this will be checking all pairs of points and take their distance and output the minimum one. There are total  $\binom{n}{2}$  possible choices of pairs of points. And calculating the distance of each pair takes O(1) time. So it will take  $O(n^2)$  times to find the closest pair of points.

**Idea:**  $\forall P_i, P_j \in S$  find distance  $d(P_i, P_j)$  and return the minimum. Time taken is  $O(n^2)$ .

#### 1.2 Divide and Conquer Algorithm

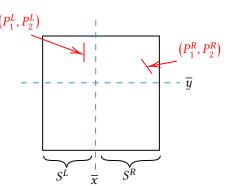
#### **Definition 1.2.1: Divide and Conquer**

- Divide: Divide the problem into two parts (roughly equal)
- Conquer: Solve each part individually recursively. If the subproblem sizes are small enough, however, just solve the subproblems in a straightforward manner.
- Combine: Combine the solutions to the subproblems into the solution.

#### 1.2.1 Divide

So to divide the problem into two roughly equal parts we need to divide the points into two equal sets. That we can do by sorting the points by their x-coordinate. Suppose  $S^x$  denote we get the new sorted array or points. And similarly we obtain  $S^y$  which denotes the array of points after sorting S by their y-coordinate.

# Algorithm 1: Step 1 (Divide) 1 Function Divide: 2 | Sort S by x-coordinate and y-coordinate 3 | $S^x \leftarrow S$ sorted by x-coordinate 4 | $S^y \leftarrow S$ sorted by y-coordinate 5 | $\bar{x} \leftarrow \lfloor \frac{n}{2} \rfloor$ highest x-coordinate 6 | $\bar{y} \leftarrow \lfloor \frac{n}{2} \rfloor$ highest y-coordinate 7 | $S^L \leftarrow \{P_i \mid x_i < \bar{x}, \ \forall \ i \in [n]\}$ 8 | $S^R \leftarrow \{P_i \mid x_i \geq \bar{x}, \ \forall \ i \in [n]\}$



#### 1.2.2 Conquer

Now we will recursively get pair of closest points in  $S_L$  and  $S_R$ . Suppose the  $(P_1^L, P_2^L)$  are the closest pair of points in  $S^L$  and  $(P_1^R, P_2^R)$  are the closest pair of points in  $S^R$ .

#### Algorithm 2: Step 1 (Solve Subproblems)

```
1 Function Conquer:
2 | Solve for S_L, S^R.
3 | (P_1^L, P_2^L) are closest pair of points in S_L.
4 | (P_1^R, P_2^R) are closest pair of points in S_R.
5 | \delta^L = d(P_1^L, P_2^L), \delta^R = d(P_1^R, P_2^R)
6 | \delta_{min} \leftarrow \min\{\delta^L, \delta^R\}
```

#### 1.2.3 Combine

Now we want to combine these two solutions.

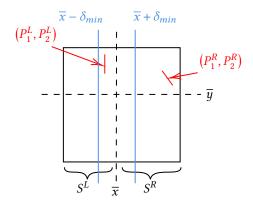
#### Question 1.1: We are not done

Is there a pair of points  $P_i, P_j \in S$  such that  $d(P_i, P_j) < \delta_{min}$ 

If Yes:

- One of them must be in  $S_L$  and the other is in  $S_R$ .
- x-coordinate  $\in [\overline{x} \delta_{min}, \overline{x} + \delta_{min}].$
- $|y_i y_j| \leq \delta_{min}$

So we take the strip of radius  $\delta_{min}$  around  $\overline{x}$ . Define  $T = \{P_i \in S \mid |x_i - \overline{x}| \leq \delta_{min}\}$ 



We now sort all the points in the T by their decreasing y-coordinate. Let  $T_y$  be the array of points. For each  $P_i \in T_y$  define the region

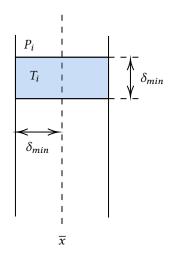
$$T_i = \{ P_j \in T_u \mid 0 \le y_j - y_i \le \delta_{min}, j > i \}$$

#### Lemma 1.2.1

Number of points (other than  $P_i$ ) that lie inside the box is at most 8

**Proof:** Suppose there are more than 8 points that lie inside the box apart from  $P_i$ . The box has a left square part and a right square part. So one of the squares contains at least 5 points. WLOG suppose the left square has at least 5 points. Divide each square into 4 parts by a middle vertical and a middle horizontal line. Now since there are 5 points there is one part which contains 2 points but that is not possible as those two points are in  $S_L$  and their distance will be less than  $\delta_{min}$  which is not possible. Hence contradiction. Therefore there are at most 8 points inside the box.

Hence by the above lemma for each  $P_i \in T_y$  there are at most 8 points in  $T_i$ . So for each  $P_j \in T_i$  we find the  $d(P_i, P_j)$  and if it is less than  $\delta_{min}$  we update the points and the distance



#### 1.2.4 Pseudocode and Time Complexity

```
Algorithm 3: FIND-CLOSEST(S)
```

```
Input: Set of n points, S = \{(x_i, y_i) \mid x_i, y_i \in \mathbb{R}, \forall i \in [n]\}. We denote P_i = (x_i, y_i).
    Output: Closest pair of ponts, (P_i, P_j, \delta) where \delta = d(P_i, P_j)
 1 begin
 2
           if |S| \leq 10 then
                 Solve by Brute Force (Consider every pair of points)
 3
            S^x \leftarrow S sorted by x-coordinate
           S^y \leftarrow S sorted by y-coordinate
 5
           \bar{x} \leftarrow \lfloor \frac{n}{2} \rfloor highest x-coordinate
           \bar{y} \leftarrow \lfloor \frac{n}{2} \rfloor highest y-coordinate S^L \leftarrow \{P_i \mid x_i < \bar{x}, \ \forall \ i \in [n]\}
           S^R \longleftarrow \{P_i \mid x_i \geq \bar{x}, \ \forall \ i \in [n]\}
           (P_1^L, P_2^L, \delta^L) \longleftarrow \text{Find-Closest}(S^L)
(P_1^R, P_2^R, \delta^R) \longleftarrow \text{Find-Closest}(S^R)
10
11
           \delta_{min} \longleftarrow \min{\{\delta^L, \delta^R\}}
12
          if \delta_{min} < \delta^L then
P_1 \longleftarrow P_1^R, P_2 \longleftarrow P_2^R
13
14
15
             16
```

## CHAPTER 2 Median Finding

## CHAPTER 3