

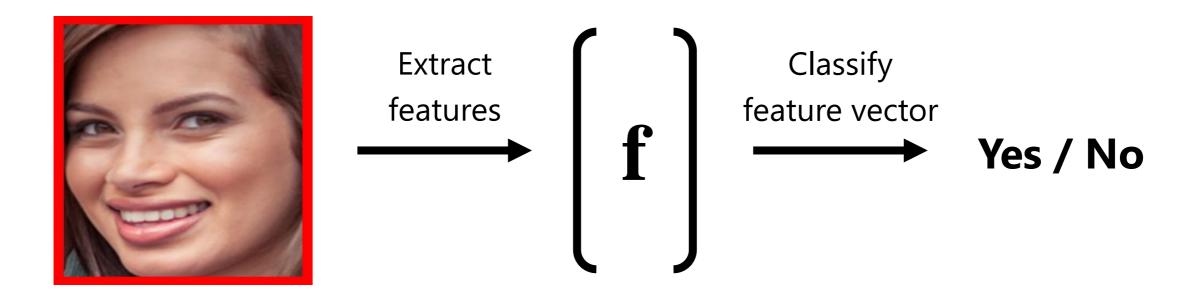
Advanced Computer VisionWeek 11

Nov. 18, 2022 Seokju Lee



Face Detection in the Past: Summary

For each window:



Features: Features to <u>represent</u> faces well.

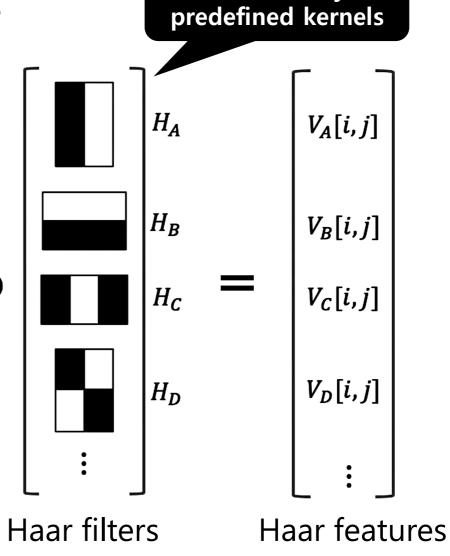
Classifier: Design a face model and efficiently classify features as face or not.

Feature Extractor: Haar Features

Set of correlation responses to **Haar** filters

- Extremely fast by using integral images





Heuristically

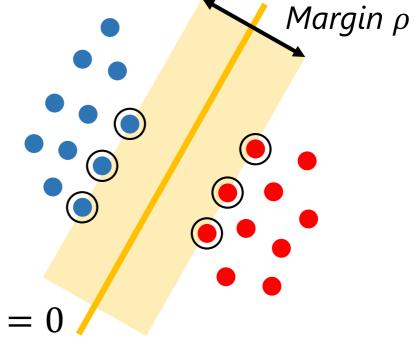
Classifier: Support Vector Machine (SVM)

Given:

- k training images $\{I_1, I_2, ..., I_k\}$ and their Haar features $\{\mathbf{f}_1, \mathbf{f}_2, ..., \mathbf{f}_k\}$.
- k corresponding labels $\{\lambda_1, \lambda_2, ..., \lambda_k\}$, where $\lambda_j = +1$ if I_j is a face and $\lambda_j = -1$ if I_j is a non-face.

Find:

- Decision boundary $\mathbf{w}^T \mathbf{f} + b = 0$
- with maximum margin ρ

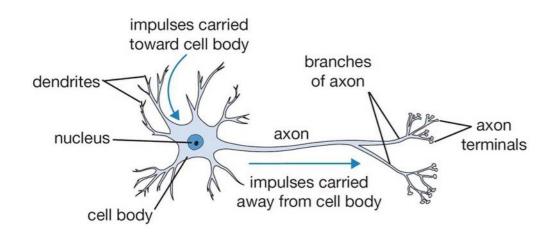




Object Recognition in the Present: Deep Learning

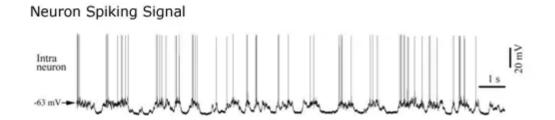
→ Towards Human-like Perception

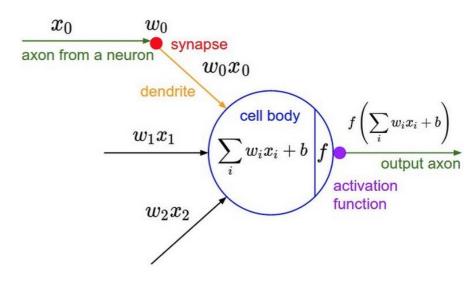
Neuron: Biological Inspiration for Computation



(**Biological**) **neuron:** computational building block for the <u>brain</u> (20W)

- → Analog signals: smooth and continuous
- → Human brain: ~100-1,000 trillion synapses,



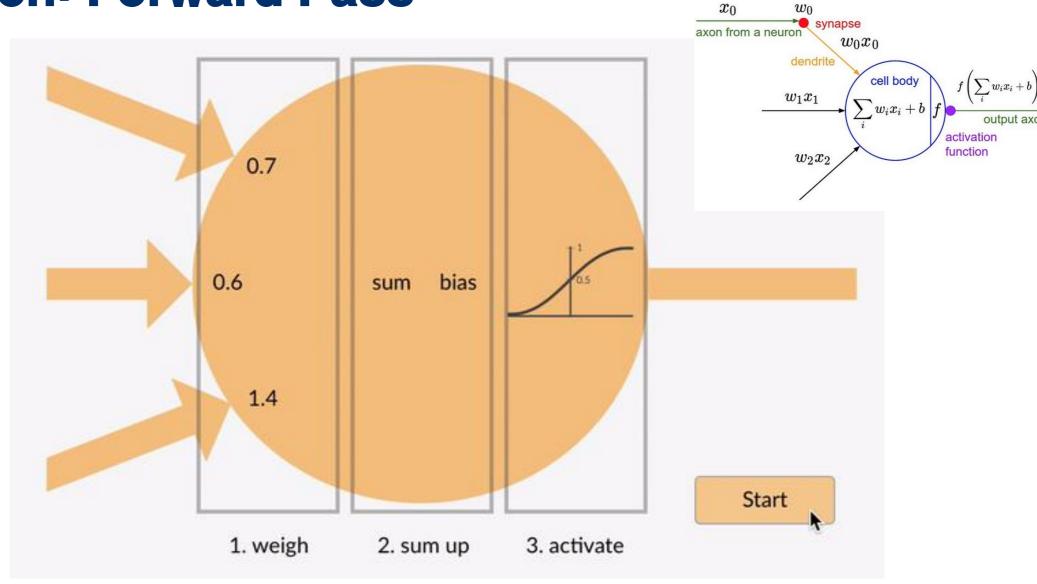


(Artificial) neuron: computational building block for the <u>neural network</u> (20kW)

- → Digital signals: discrete and discontinuous
- → Neural network: ~1-10 billion synapses,

Compared to neural networks, the human brain has ×10k computational power, and consumes only 0.1% of the power.

Perceptron: Forward Pass



Output of activation: $f(input \times weight + bias)$

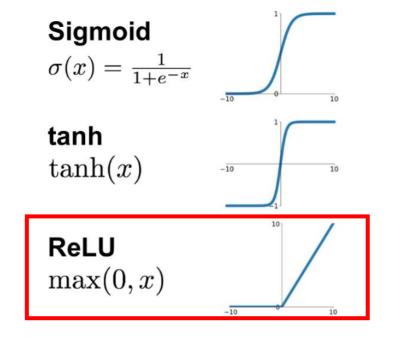
Activation Functions

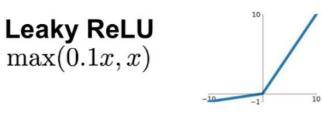
Why does it need activation?

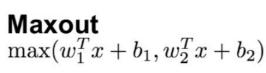
→ Nonlinearity ↑, complexity ↑ to represent high dimensional information

Properties of activation functions

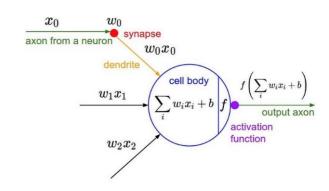
- → Differentiable (for backpropagation)
- → Monotonic (one-to-one correspondence for input & output)









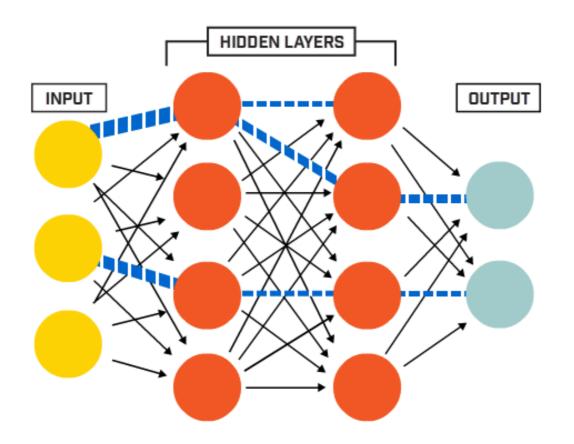


For more details, please check *vanishing gradient problem

Multi-Layer Perceptron (MLP, or Fully-Connected)

<u>Vectorized</u> feature → Fully connected layers → Non-linear activation

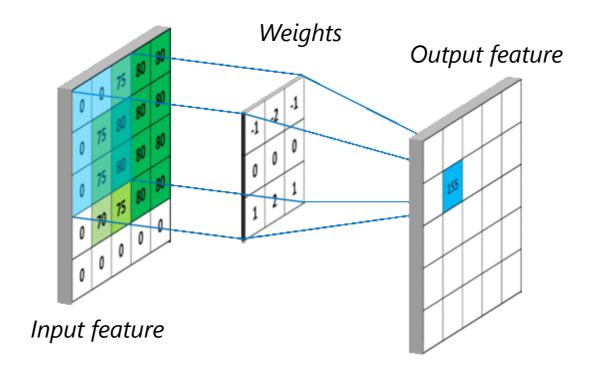
: Number of parameters 1, hard to optimize, number of hidden layers 1



Convolutional Neural Network (CNN)

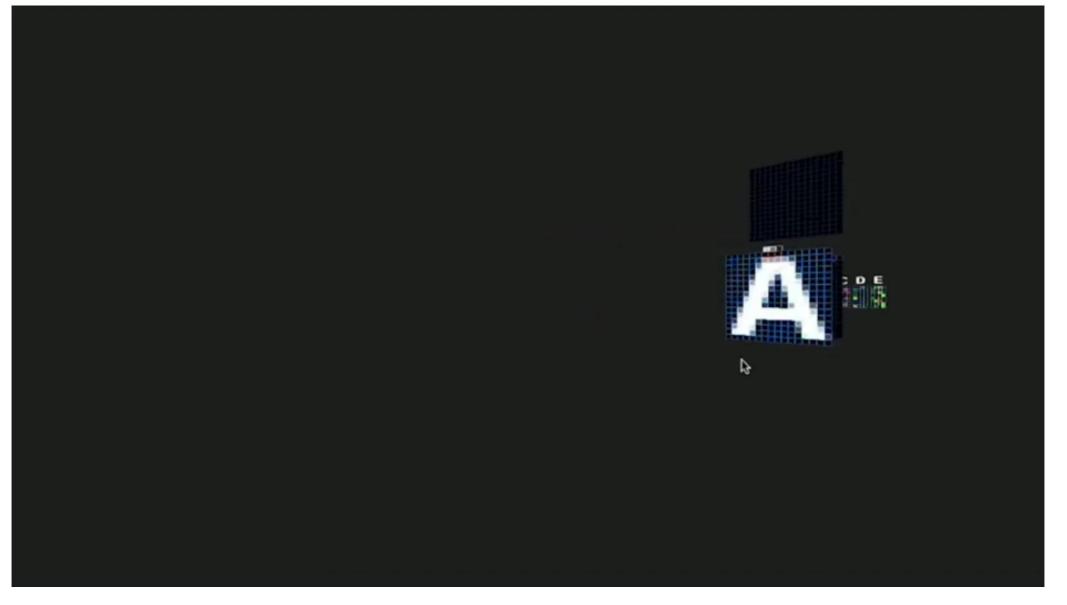
<u>Vectorized</u> feature → Fully connected layers → Non-linear activation

: Number of parameters 1, easier to optimize, number of hidden layers 1



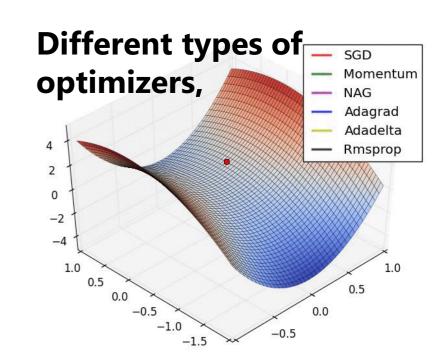
→ Convolution works on spatial & local features!

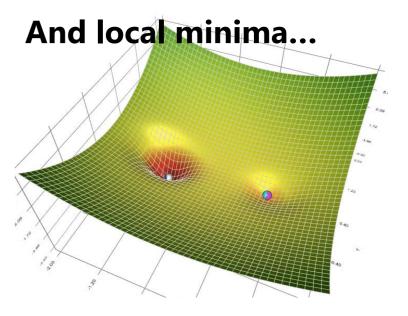
Convolutional Neural Network (CNN)



Drawbacks (including but not limited to)

- Works for specifically defined tasks (weak AI).
- Requires large amount of data (data hungry).
- Requires human annotation for real world data.
- Domain issues (virtual ↔ real, daytime ↔ night)
- Manually select neural architecture.
- Performance is varied over different loss functions.
- Hyperparameter tuning
 - Learning rate, loss function
 - Batch size, number of iteration, number of kernels
 - Optimizer, momentum





Useful Deep Learning Terms (including but not limited to)

- Deep learning = Deep neural network (DNN)
- MLP: Multi-layer perceptron
- **CNN**: Convolutional neural network
- GAN, GNN, RNN, LSTM, autoencoder
- Spiking neural network
- Neural network operations:
 - Convolution, pooling, activation function
 - Feed forward, backpropagation
 - Batch normalization, KL divergence
 - Data augmentation, regularization
- AlexNet, Inception, VGG, ResNet
- Others:
 - ViT, Transformer, attention, cost volume
 - PyTorch, Caffe, TensorFlow

- Supervised learning, self-supervised learning, unsupervised learning, reinforcement Learning
- Few-shot (one-shot) learning, adversarial learning, domain adaptation, meta learning, active learning, multimodal learning, contrastive learning
- Visual learning tasks:
 - Image classification, object detection
 - Semantic/instance/panoptic/video segmentation
 - Optical flow, depth, neural rendering
 - Stereo matching, SfM, MVS
 - Image enhancement, super resolution
 - Stylization, image-to-image, VQA, VLN



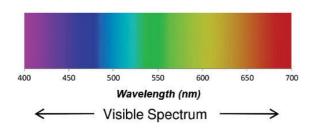
Basic Visual Perception Tasks

Human Visual System: How Do We Perceive the World?

"About **half** of neocortex in humans is devoted to **vision**." [1]



Low-level visual signal



Geometric **(2)** Where is it? perception Two independent visual pathways: **High-level** decision "What-path & Where-path"

00

Semantic perception **(1)**

What is it?

[1] Barton, Robert A. "Visual specialization and brain evolution in primates." Proceedings of the Royal Society of London (1998).

[2] M. A. Goodale, et al., "Separate visual pathways for perception and action." Trends in Neurosciences (1992).

Visual Perception: Semantics & Geometry

"Semantic" perception

: Meaning of an element, syntax, context of scene, or relationship between objects.

Semantic computer vision tasks

- Image classification
- Object detection
- Semantic segmentation
- ...

Video understanding

ex) Video classification



+ "Temporal"

"Geometric" perception

: Distance, shape, structure, size, scale of an element, 3D space where we live, relative position between objects.

Geometric computer vision tasks

- Depth estimation
- Pose estimation
- 3D reconstruction
- ...



Motion understanding

ex) 3D motion estimation

Computer Vision Tasks

*Slide by Kim, et al., "Video Panoptic Segmentation" (CVPR 2020)

Model Complexity 1 Output dimension 1

Image

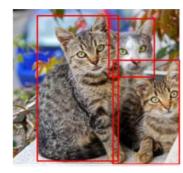


Classification



"Image-level"

Image



Object

Detection

"Box-level"

Faster RCNN NeurIPS 2015 YOLO, CVPR 2016 SSD, ECCV 2016 Cascade RCNN, CVPR 2017 CornerNet, ECCV 2018 HTC. CVPR 2019



Karpathy et.al., Video

Classification

Video Object Detection

Kai et.al.,

CVPR 2016

Semantic Segmentation



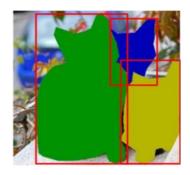
"Pixel-level"

DeepLab, ICLR 2015 PSPNet, CVPR 2016 Deform FCN, ICCV 2017 EncNet, CVPR 2018 DeepLabv2, ECCV 2018 DANet, CVPR 2019 Deformable V2. ICCV 2019



Video Semantic Segmentation

Instance Segmentation



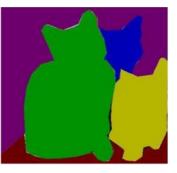
""Pixel-level" MNC, CVPR 2014

"Instance-level" HTC, CVPR2019



Video Instance Segmentation

Panoptic Segmentation



"Unknown pixel"

Kim et.al., CVPR 2020

Video Panoptic Segmentation



Image Classification

- AlexNet, VGG, GoogleNet, ResNet

Image Classification

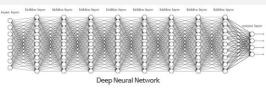
The most fundamental task using deep learning!

→ What's going on inside deep neural networks? Memory ↑ **Probability** Two GPU instances → AlexNet [1] (# cites: **119,000** in Nov. 2022) (sum = 1)**Predicted class** → Dog (0.03) \dense → Car (0.00) dense → Cup (0.01) 128 Max 192 192 → Bus (0.00) 2048 pooling Max Max 128 pooling pooling **Predefined** classes Five convolutional layers Three fully-connected layers

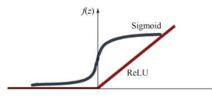
AlexNet: Breakthrough in 2012

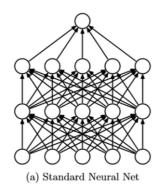
Troublesome of previous neural networks

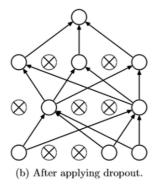
- Local minimum or slow learning
- Overfitting
- Small data •
- Time complexity
- Vanishing gradients

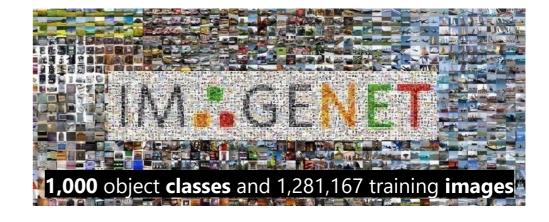








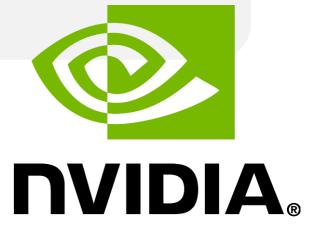




AlexNet

- Big data: ImageNet Challenge
- GPUs
- ReLU (Rectified Linear Unit)
- Dropout
- Deeper network



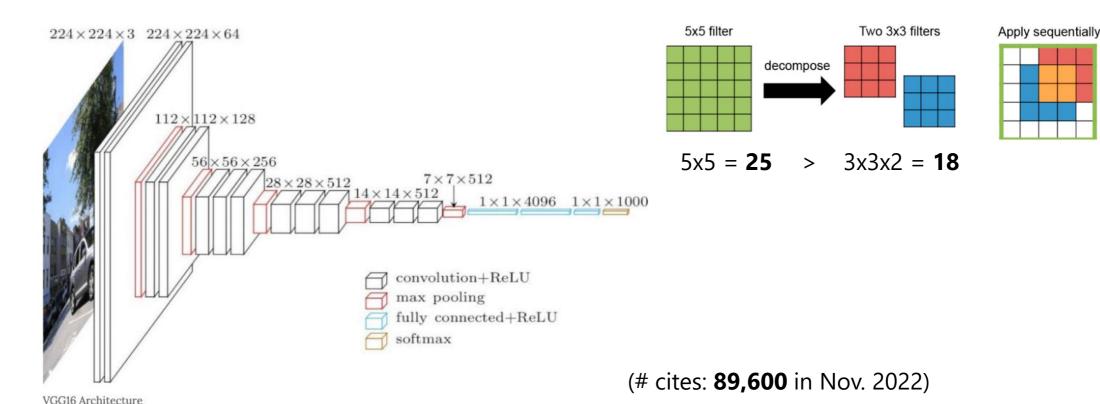


VGG: ImageNet Challenge (2014) 2nd Place

Small filters + Deeper networks + Beautifully uniform design

→ Why use smaller filters?

Number of parameters ↓ (efficiency ↑) + Deeper layer (nonlinearity ↑)

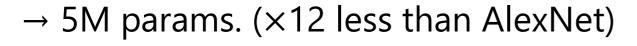


[1] Very Deep Convolutional Networks for Large-Scale Image Recognition; 2015; ICLR 2015

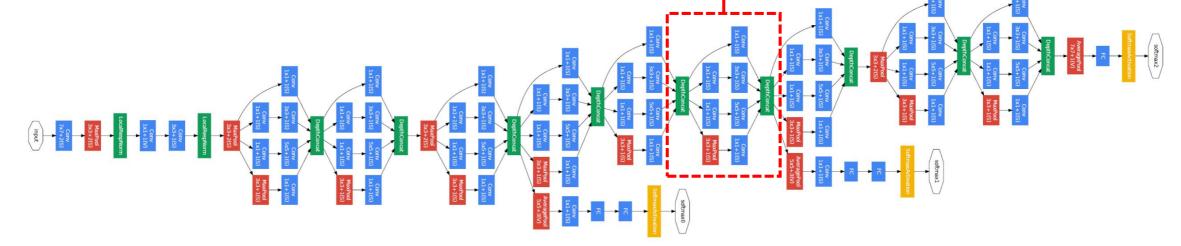
GoogleNet: ImageNet Challenge (2014) Winner

Deeper networks with a computational efficiency

→ **Inception** module: Local network topology (<u>network</u> within a <u>network</u>)



→ Fully convolutional networks



(# cites: **43,600** in Nov. 2022)

[1] Going Deeper with Convolutions, CVPR 2015

 \mathbf{X}

weight layer

weight layer

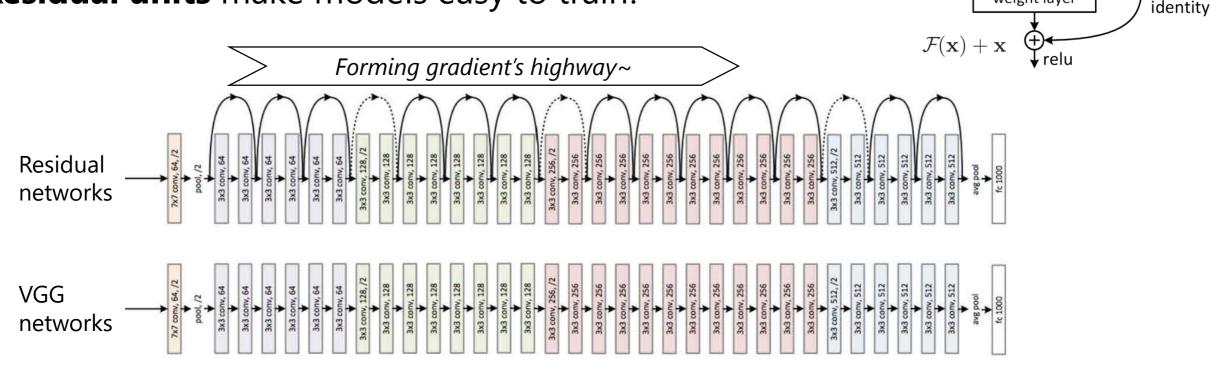
relu

 $\mathcal{F}(\mathbf{x})$

ResNet: ImageNet Challenge (2015) Winner

Major breakthrough in the network architecture

- → Better than "human performance" in ImageNet Challenge
- → **Residual units** make models easy to train!



(# cites: **136,800** in Nov. 2022)

Summary

Basic computer vision tasks inspired by human visual system

- → <u>Semantic</u> and <u>geometric</u> scene understanding
- → Basic visual perception tasks: image classification, detection, segmentation, ...

Basic deep neural networks

- → AlexNet, VGG, GoogleNet, ResNet, ...
- → Take-home message:

"Not all **complex** and **deep** networks are good, but how well you **regularize** (**represent**) **multi-dimensional features** is the key to improve the performance."

Experiments

Image classification

Code is available in https://view.kentech.ac.kr/f088fa7f-874e-44bc-bd6d-6084b42dfdf7

\$ python alexnet.py