Visionary Course

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System and Modeling

System



- What is the definition of system?
 - A system is a group of interacting or interrelated elements that act according to a set of rules to form a unified whole.

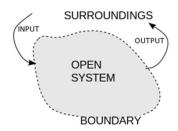
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3

System



- What is the definition of system?
 - A system is a group of interacting or interrelated elements that act according to a set of rules to form a unified whole.



Open systems have input and output flows, representing exchanges of matter, energy or information with their surroundings.

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System Model



- What is the definition of model?
 - A model is an informative representation of an object, person or system.

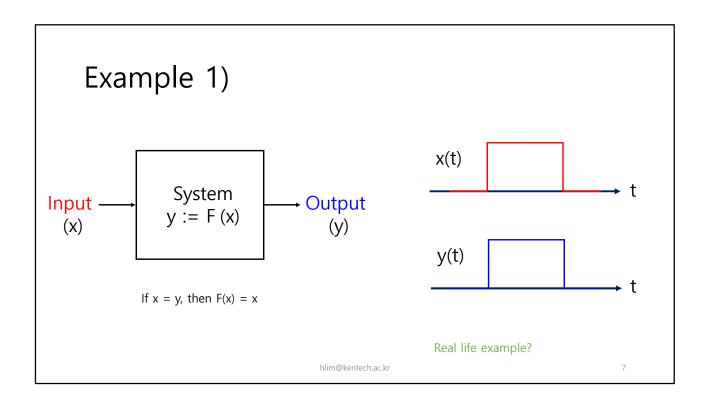
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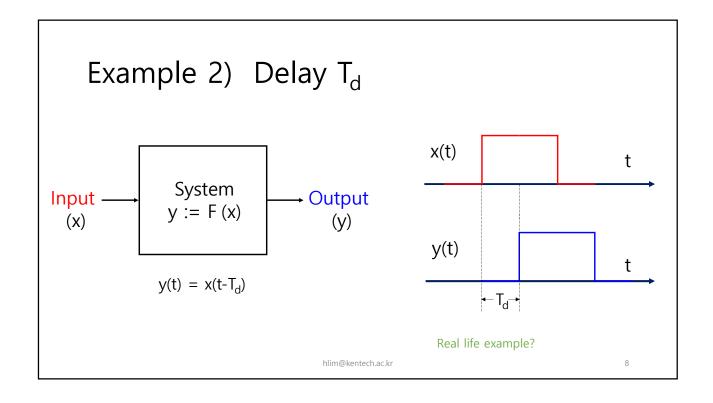
Modeling A System

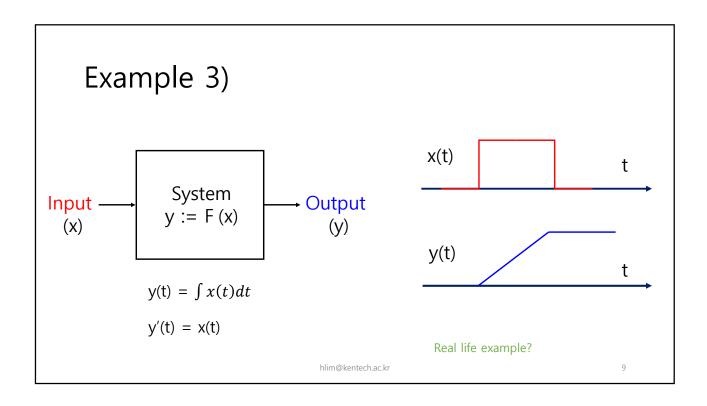


How to define the system?

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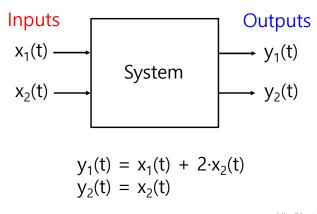






Example 4) MIMO Linear System

• 2x2 MIMO System



$$\begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix} = \begin{bmatrix} 0.5 & 0.5 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

Linear Algebra, Vector, Matrix ...

Real life example?

10

Categories of Systems

- # of inputs and outputs
 - Multiple Inputs and Multiple Output (MIMO)
 - Single Input and Single Output (SISO)
- Input and output types
 - Continuous system
 - Discrete system
- Relationship
 - Linear system
 - Non-linear system

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11

Group Discussion and Presentation

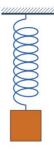
Make a 3-page ppt and give a 3-min presentation!

- Pick a system

 (e.g. mechanical, electrical, biological, economical, communication, automatic control ...)
- Define inputs and outputs of your system
- Describe the behaviors / dynamics / rules for the system (Is it possible to make a mathematical/logical representation?)

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Example 5) Forced Spring Mass System



Dynamics equation: mx''(t) + kx(t) = f(t)

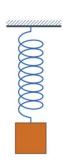
$$x_1(t) = x(t) x_2(t) = x_1'(t)$$

$$x_1'(t) = x_2(t) x_2'(t) = x_1''(t) = -\frac{k}{m}x1(t) + \frac{1}{m}f(t)$$

$$\begin{bmatrix} x_1'(t) \\ x_2'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{m} \end{bmatrix} f(t)$$

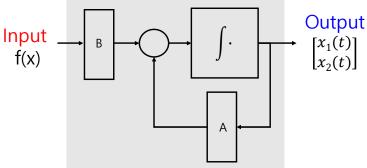
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Example 5) Forced Spring-Mass System

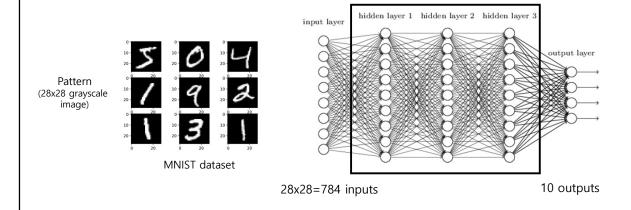


f(x)

$$\begin{bmatrix} x_1'(t) \\ x_2'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{1}{m} \end{bmatrix} f(t)$$



Example 6) Artificial Neural Network



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15

Signals

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Signal

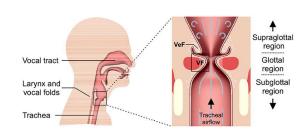


- In signal processing, a signal is a function that conveys **information** about a phenomenon.
- In electronics and telecommunications, it refers to any time varying voltage, current, or electromagnetic wave that carries information.
- A signal may also be defined as an observable change in a quality such as quantity.

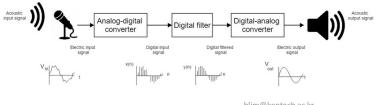
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1) Acoustic Signal

Voice production



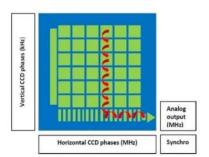
• Capture and signal processing "system"



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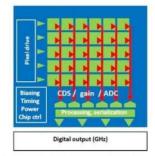
2) Image Signal

Charge Coupled Devices (CCDs)



CCD = Photon-to-electron conversion (analog)

Complementary Metal–Oxide– Semiconductor (CMOS) Sensor



CIS = Photon-to-Voltage conversion (digital)

CMOS Image Sensor Integrated Circuit Architecture
Analog-to-Digital Conversion
Image
Sensor
Die
Bayer
Mossilc
Fillers
Fillers
Active Pixel Sensor
Color Imaging
Active Pixel Sensor
Color Imaging
Control
Pad Ring

https://www.olympus-lifescience.com/ko/microscope-resource/primer/digitalimaging/cmosimagesensors/

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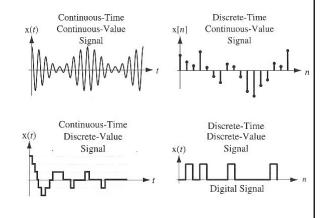
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19

20

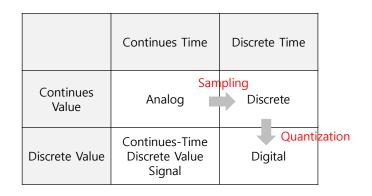
Signal Types

	Continues Time	Discrete Time
Continues Value	Analog	Discrete
Discrete Value	Continues-Time Discrete Value Signal	Digital



Analogy to Digital Conversion

• Sampling and quantization









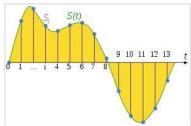
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21

Sampling

- In signal processing, sampling is the reduction of a continuous-time signal to a discrete-time signal.
- A common example is the conversion of a sound wave to a sequence of "samples".
- A sample is a value of the signal at a point in time and/or space.



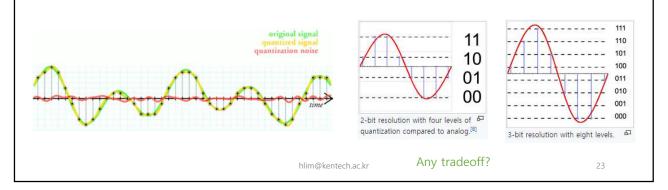


Signal sampling representation. The continuous signal S(t) is represented with a green colored line while the discrete samples are indicated by the blue vertical line.

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Quantization

 Quantization, in mathematics and digital signal processing, is the process of mapping input values from a large set (often a continuous set) to output values in a (countable) smaller set, often with a finite number of elements.



Group Discussion and Presentation

Make a 3-page ppt and give a 3-min presentation!

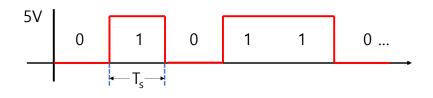
- Pick one of your smartphones
- Investigate its hardware and software including Apps.
- Any signal, sampling, quantization techniques are used?
- What are the specification of ADC/DAC?

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3) Communication Signal

For a given series of binary values, how can we generate a signal (waveform)? → Modulation

010110 ...



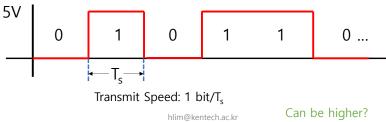
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25

3) Communication Signal

For a given series of binary values, how can we generate a signal (waveform)?

010110 ...

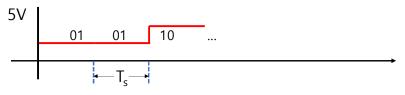


Can be higher?

3) Communication Signal

Change amplitude: $00 \rightarrow 0V$, $01 \rightarrow 1.6V$, $10 \rightarrow 3.3V$, $11 \rightarrow 5V$

010110 → 01/01/10 → 1.6V/1.6V/3.3V



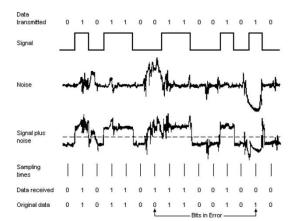
Transmit Speed: 2 bit/T_s

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Can be higher and higher? Any Tradeoff?

27

Noisy Signal

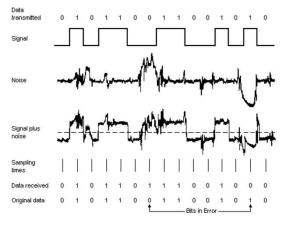


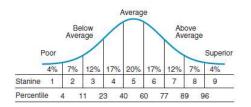
https://www.autodesk.com/products/eagle/blog/top-5-techniques-terminating-transmission-lines/

Calculate bit error rate?

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Noisy Signal





Normal distribution

Statistics, probability, distribution

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Noisy Signal









The original image. Noisy image (noise density 50%). Image denoised with linear interpolation and median filter.

Original Images















Noisy Images

















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Noisy Signal

• How much noisy is the signal?

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31

Noisy Signal

- How much noisy is the signal?
- Signal-to-noise ratio (SNR) Signal-to-interference-plus-noise ratio (SINR)

$$SINR = \frac{S}{I+N}$$

S: signal power, I: interference power, N: noise

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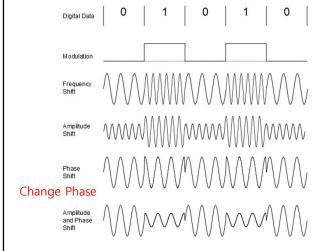
Shannon Limit

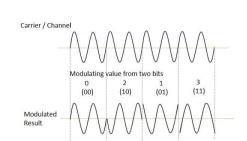
- Shannon-Hartley theorem
 - Proved by Bell Labs research Claude Shannon in 1948.
 - Gives the capacity of a communication channel.
 - Many communication systems in use do not achieve the capacity, however, it provides a useful upper bound.
 - C: max capacity in bits per second W: bandwidth in Hertz

$$C \le W \log_2(1 + \frac{S}{N})$$

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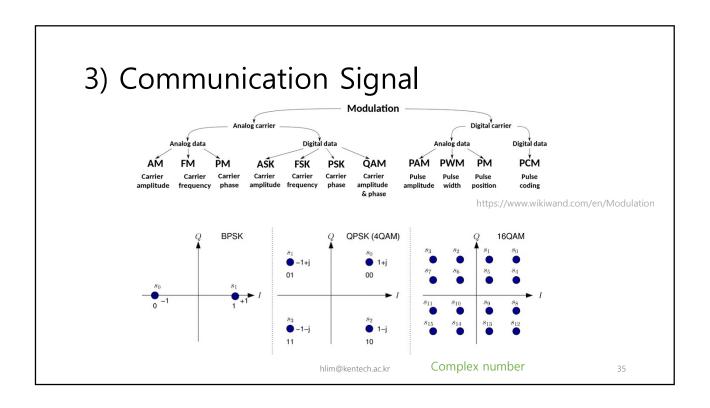
3) Communication Signal





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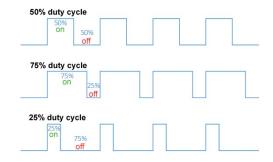
34



4) Pulse-width Modulation (PWM)



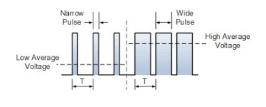
 Pulse-width modulation (PWM), or pulse-duration modulation (PDM), is a method of reducing the average power delivered by an electrical signal, by effectively chopping it up into discrete parts.



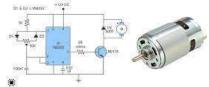
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4) Pulse-width Modulation (PWM)

- The average value of voltage (and current) fed to the load is controlled by turning the switch between supply and load on and off at a fast rate.
- The longer the switch is on compared to the off periods, the higher the total power supplied to the load.
- PWM is particularly suited for running inertial loads such as motors, which are not as easily affected by this discrete switching, because their inertia causes them to react slowly.







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37

Any Questions?

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